

## 24位模数转换器

 查询样品: [ADS1243-HT](#)

### 特性

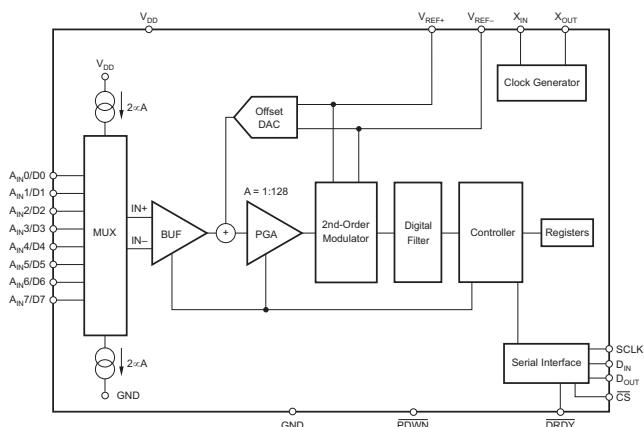
- **24位无丢码**
- 同步**50Hz**和**60Hz**抑制制 (最小**-90 dB**)
- **0.0025%** 积分非线性(INL)
- 可编程增益放大器(PGA)增益从**1**到**128**
- 单循环建立
- 可编程数据输出速率
- **0.1V**至**0.5V**外部差分基准
- 片载校准
- 与**SPI™**兼容
- **2.7V**至**5.25V**电源范围
- **600μW**功率耗散
- 最多**8**个输入通道
- 最多**8**个数据I/O

### 应用范围

- 潜孔打钻
- 高温环境
- 振动/模式分析
- 多通道数据采集
- 声学/动态应变仪
- 压力传感器

### 支持极端温度环境下的应用

- 受控基线
- 一个组装/测试场所
- 一个制造场所
- 可在极端温度范围 (**-55°C/210°C**) 下工作<sup>(1)</sup>
- 延长的产品使用寿命周期
- 延长产品的变更通知周期
- 产品可追溯性
- 德州仪器的高温产品使用高度优化的硅(芯片)解决方案, 此方案提升设计和制造工艺, 以大大提高拓展温度范围内的性能。所有器件可在最大额定温度下连续运行**1000**小时。



(1) 可定制温度范围

### 说明

ADS1243是一款高精度, 宽动态范围,  $\Delta$ - $\Sigma$ , 模数(A/D)转换器, 此转换器的运行电压为2.7V至5.25V并具有24位分辨率。此 $\Delta$ - $\Sigma$ , A/D转换器能提供最高24位的无丢码性能并且其有效分辨率为21位。

此输入通道是复用的。可选择内部缓冲来为到变频器的直接连接或者低水平电压信号提供一个非常高的输入阻抗。提供的熔断电流可用于检测开式或者短接传感器。一个8位模数转换器(DAC)提供一个FSR(满刻度范围)50%的偏差校正。

此可编程增益放大器(PGA)提供1到128间的可选增益(128增益时的有效分辨率为19位)。A/D转换由一个二级 $\Delta$ - $\Sigma$ 调制器和一个可提供同步50Hz和60Hz陷波的可编程有限脉冲响应(FIR)滤波器来完成的。此基准输入是差分的并可被用于比例转换。



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此串口与串行外设接口(SPI)兼容。提供最多8位数据I/O用于输入或者输出。ADS1243设计用于智能发送器，工业过程控制，称量台，套色版和便携式仪器中的高分辨率测量应用。

**ORDERING INFORMATION<sup>(1)</sup>**

T <sub>A</sub>	PACKAGE	ORDERABLE PART NUMBER	TOP-SIDE MARKING
-55°C to 210°C	JD	ADS1243SJD	ADS1243SJD
	KGD	ADS1243SKGD1	NA

(1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI Web site at [www.ti.com](http://www.ti.com).

**ABSOLUTE MAXIMUM RATINGS**

over operating free-air temperature range (unless otherwise noted) <sup>(1)</sup>

	VALUE	UNIT
V <sub>DD</sub> to GND	-0.3 to 6	V
Input Current	100, Momentary	mA
Input Current	10, Continuous	mA
A <sub>IN</sub>	GND - 0.5 to V <sub>DD</sub> + 0.5	V
Digital Input Voltage to GND	-0.3V to V <sub>DD</sub> + 0.3	V
Digital Output Voltage to GND	-0.3V to V <sub>DD</sub> + 0.3	V
Maximum Junction Temperature	215	°C
Operating Temperature Range	-55 to 210	°C
Storage Temperature Range	-65 to 100	°C

(1) Stresses above those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. Exposure to absolute maximum conditions for extended periods may affect device reliability.

**THERMAL CHARACTERISTICS**

over operating free-air temperature range (unless otherwise noted)

PARAMETER		MIN	TYP	MAX	UNIT
θ <sub>JC</sub>	Junction-to-case thermal resistance HKJ package			8.1	°C/W

**DIGITAL CHARACTERISTICS**

V<sub>DD</sub> 2.7 V to 5.25 V

PARAMETER	TEST CONDITIONS	T <sub>A</sub> = -55°C to 125°C			T <sub>A</sub> = 210°C			UNIT	
		MIN	TYP	MAX	MIN	TYP	MAX		
<b>Digital Input/Output</b>									
Logic Family		CMOS			CMOS				
Logic Level	V <sub>IH</sub>	0.8 • V <sub>DD</sub>			0.8 • V <sub>DD</sub>			V	
	V <sub>IL</sub> <sup>(1)</sup>	GND			GND			V	
	V <sub>OH</sub>	I <sub>OH</sub> = 1 mA	V <sub>DD</sub> - 0.4			V <sub>DD</sub> - 0.4			V
	V <sub>OL</sub>	I <sub>OL</sub> = 1 mA	GND			GND + 0.4			V
Input Leakage	I <sub>IH</sub>	V <sub>I</sub> = V <sub>DD</sub>			10			µA	
	I <sub>IL</sub>	V <sub>I</sub> = 0			-10			µA	
Master Clock Rate: f <sub>OSC</sub>		1			5			MHz	
Master Clock Period: t <sub>osc</sub>	1/f <sub>OSC</sub>	200			1000			ns	

(1) V<sub>IL</sub> for X<sub>IN</sub> is GND to GND + 0.05 V.

**ELECTRICAL CHARACTERISTICS:  $V_{DD} = 5\text{ V}$** 

All specifications  $V_{DD} = 5\text{ V}$ ,  $f_{MOD} = 19.2\text{ kHz}$ ,  $PGA = 1$ , Buffer ON,  $f_{DATA} = 15\text{ Hz}$ ,  
 $V_{REF} \equiv (\text{REF IN+}) - (\text{REF IN-}) = 2.5\text{ V}$ , unless otherwise specified.

PARAMETER	TEST CONDITIONS	$T_A = -55^\circ\text{C to } 125^\circ\text{C}$			$T_A = 210^\circ\text{C}$			UNIT
		MIN	TYP	MAX	MIN	TYP	MAX	
<b>ANALOG INPUT (<math>A_{IN0} - A_{IN7}</math>)</b>								
Analog Input Range	Buffer OFF	GND – 0.1		$V_{DD} + 0.1$	GND – 0.1		$V_{DD} + 0.1$	V
	Buffer ON	GND + 0.05		$V_{DD} - 1.5$	GND + 0.05		$V_{DD} - 1.5$	V
Full-Scale Input Range	(In+) – (In–), See Block Diagram, RANGE = 0	$\pm V_{REF}/PGA$			$\pm V_{REF}/PGA$			V
	RANGE = 1	$\pm V_{REF}/(2 \bullet PGA)$			$\pm V_{REF}/(2 \bullet PGA)$			V
Differential Input Impedance	Buffer OFF	5/PGA			12/PGA			M $\Omega$
	Buffer ON	5			8			G $\Omega$
Bandwidth	$f_{DATA} = 3.75\text{ Hz}$	–3 dB		1.65				Hz
	$f_{DATA} = 7.50\text{ Hz}$	–3 dB		3.44				Hz
	$f_{DATA} = 15\text{ Hz}$	–3 dB		14.6				Hz
Programmable Gain Amplifier	User-Selectable Gain Ranges	1		128	1		128	
Input Capacitance		9			25			pF
Input Leakage Current	Modulator OFF, $T = 25^\circ\text{C}$	5			6			pA
Burnout Current Sources		2						$\mu\text{A}$
<b>OFFSET DAC</b>								
Offset DAC Range	RANGE = 0	$\pm V_{REF} / (2 \bullet PGA)$			$\pm V_{REF} / (2 \bullet PGA)$			V
	RANGE = 1	$\pm V_{REF} / (4 \bullet PGA)$			$\pm V_{REF} / (4 \bullet PGA)$			V
Offset DAC Monotonicity		8			8			Bits
Offset DAC Gain Error		$\pm 10$			$\pm 15$			%
Offset DAC Gain Error Drift		1			2.2			ppm/ $^\circ\text{C}$
<b>SYSTEM PERFORMANCE</b>								
Resolution	No Missing Codes	24			24			Bits
Integral Nonlinearity	End Point Fit	$\pm 0.0015$			$\pm 0.0018$			% of FS
Offset Error <sup>(1)</sup>		7.5			15			ppm of FS
Offset Drift <sup>(1)</sup>		0.02			0.04			ppm of FS/ $^\circ\text{C}$
Gain Error <sup>(1)</sup>		0.005			0.100			%
Gain Error Drift <sup>(1)</sup>		0.5			1.118			ppm/ $^\circ\text{C}$
Common-Mode Rejection	at DC	100			94			dB
	$f_{CM} = 60\text{ Hz}$ , $f_{DATA} = 15\text{ Hz}$	130			100			dB
	$f_{CM} = 50\text{ Hz}$ , $f_{DATA} = 15\text{ Hz}$	120			100			dB
Normal-Mode Rejection	$f_{SIG} = 50\text{ Hz}$ , $f_{DATA} = 15\text{ Hz}$	100			95			dB
	$f_{SIG} = 60\text{ Hz}$ , $f_{DATA} = 15\text{ Hz}$	100			95			dB
Output Noise		See Typical Characteristics						
Power-Supply Rejection	at DC, dB = $-20 \log(\Delta V_{OUT}/V_{DD})$ <sup>(2)</sup>	80	95		79	95		dB
<b>VOLTAGE REFERENCE INPUT</b>								
Reference Input Range	REF IN+, REF IN–	0		$V_{DD}$	0		$V_{DD}$	V
$V_{REF}$	$V_{REF} \equiv (\text{REF IN+}) - (\text{REF IN-})$ , RANGE = 0	0.1	2.5	2.6	0.1	2.5	2.6	V
	RANGE = 1	0.1		$V_{DD}$	0.1		$V_{DD}$	V
Common-Mode Rejection	at DC	120			98			dB
Common-Mode Rejection	$f_{VREFCM} = 60\text{ Hz}$ , $f_{DATA} = 15\text{ Hz}$	120			95			dB

(1) Calibration can minimize these errors.

(2)  $\Delta V_{OUT}$  is a change in digital result.

**ELECTRICAL CHARACTERISTICS: V<sub>DD</sub> = 5 V (continued)**

All specifications V<sub>DD</sub> = 5 V, f<sub>MOD</sub> = 19.2 kHz, PGA = 1, Buffer ON, f<sub>DATA</sub> = 15 Hz, V<sub>REF</sub> ≡ (REF IN+) – (REF IN–) = 2.5 V, unless otherwise specified.

PARAMETER	TEST CONDITIONS	T <sub>A</sub> = –55°C to 125°C			T <sub>A</sub> = 210°C			UNIT
		MIN	TYP	MAX	MIN	TYP	MAX	
Bias Current <sup>(3)</sup>	V <sub>REF</sub> = 2.5 V		1.3			10		μA
<b>POWER-SUPPLY REQUIREMENTS</b>								
Power-Supply Voltage	V <sub>DD</sub>	4.75		5.25	4.75		5.25	V
Current	PGA = 1, Buffer OFF		240	375		250	480	μA
	PGA = 128, Buffer OFF		450	800		630	940	μA
	PGA = 1, Buffer ON		290	425		350	585	μA
	PGA = 128, Buffer ON		960	1400		1200	2050	μA
	SLEEP Mode		60			80		μA
	Read Data Continuous Mode		230			350		μA
	$\overline{\text{PDWN}}$		0.5			10		nA
Power Dissipation	PGA = 1, Buffer OFF		1.2	1.9		1.3	2.52	mW

(3) 12-pF switched capacitor at f<sub>SAMP</sub> clock frequency.

**ELECTRICAL CHARACTERISTICS: V<sub>DD</sub> = 3 V**

All specifications V<sub>DD</sub> = 3 V, f<sub>MOD</sub> = 19.2 kHz, PGA = 1, Buffer ON, f<sub>DATA</sub> = 15 Hz, V<sub>REF</sub> ≡ (REF IN+) – (REF IN–) = 1.25 V, unless otherwise specified.

PARAMETER	TEST CONDITIONS	T <sub>A</sub> = –55°C to 125°C			T <sub>A</sub> = 210°C			UNIT
		MIN	TYP	MAX	MIN	TYP	MAX	
<b>ANALOG INPUT (A<sub>IN0</sub> – A<sub>IN7</sub>)</b>								
Analog Input Range	Buffer OFF	GND – 0.1		V <sub>DD</sub> + 0.1	GND – 0.1		V <sub>DD</sub> + 0.1	V
	Buffer ON	GND + 0.05		V <sub>DD</sub> – 1.5	GND + 0.05		V <sub>DD</sub> – 1.5	V
Full-Scale Input Voltage Range	(In+) – (In–), See Block Diagram, RANGE = 0			±V <sub>REF</sub> /PGA			±V <sub>REF</sub> /PGA	V
	RANGE = 1			±V <sub>REF</sub> /(2 • PGA)			±V <sub>REF</sub> /(2 • PGA)	V
Input Impedance	Buffer OFF		5/PGA			10/PGA		MΩ
	Buffer ON		5			8		GΩ
Bandwidth	f <sub>DATA</sub> = 3.75 Hz	–3 dB		1.65				Hz
	f <sub>DATA</sub> = 7.50 Hz	–3 dB		3.44				Hz
	f <sub>DATA</sub> = 15 Hz	–3 dB		14.6				Hz
Programmable Gain Amplifier	User-Selectable Gain Ranges	1		128	1		128	
Input Capacitance			9			25		pF
Input Leakage Current	Modulator OFF, T = 25°C		5			6		pA
Burnout Current Sources			2					μA
<b>OFFSET DAC</b>								
Offset DAC Range	RANGE = 0			±V <sub>REF</sub> /(2 • PGA)			±V <sub>REF</sub> /(2 • PGA)	V
	RANGE = 1			±V <sub>REF</sub> /(4 • PGA)			±V <sub>REF</sub> /(4 • PGA)	V
Offset DAC Monotonicity		8			8			Bits
Offset DAC Gain Error			±10			±12		%
Offset DAC Gain Error Drift			1			2		ppm/°C
<b>SYSTEM PERFORMANCE</b>								
Resolution	No Missing Codes	24			24			Bits
Integral Nonlinearity	End Point Fit			±0.0015			±0.0025	% of FS
Offset Error <sup>(1)</sup>			75			40		ppm of FS

(1) Calibration can minimize these errors.

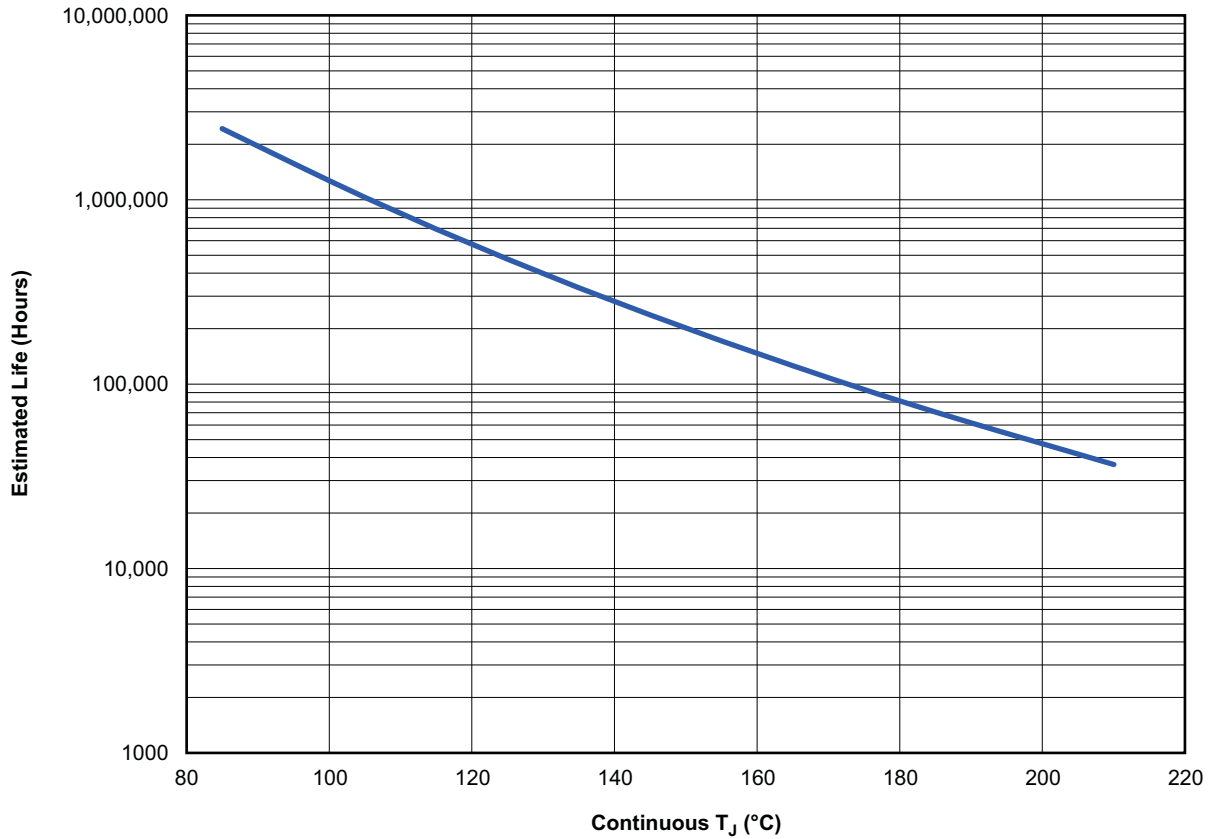
**ELECTRICAL CHARACTERISTICS:  $V_{DD} = 3\text{ V}$  (continued)**

All specifications  $V_{DD} = 3\text{ V}$ ,  $f_{MOD} = 19.2\text{ kHz}$ ,  $PGA = 1$ , Buffer ON,  $f_{DATA} = 15\text{ Hz}$ ,  
 $V_{REF} \equiv (\text{REF IN+}) - (\text{REF IN-}) = 1.25\text{ V}$ , unless otherwise specified.

PARAMETER	TEST CONDITIONS	$T_A = -55^\circ\text{C to } 125^\circ\text{C}$			$T_A = 210^\circ\text{C}$			UNIT		
		MIN	TYP	MAX	MIN	TYP	MAX			
Offset Drift <sup>(1)</sup>			0.02			0.20		ppm of FS/ $^\circ\text{C}$		
Gain Error <sup>(1)</sup>			0.005			0.1		%		
Gain Error Drift <sup>(1)</sup>			0.5			1.118		ppm/ $^\circ\text{C}$		
Common-Mode Rejection	at DC		100			87		dB		
	$f_{CM} = 60\text{ Hz}$ , $f_{DATA} = 15\text{ Hz}$					98		dB		
	$f_{CM} = 50\text{ Hz}$ , $f_{DATA} = 15\text{ Hz}$					95		dB		
Normal-Mode Rejection	$f_{SIG} = 50\text{ Hz}$ , $f_{DATA} = 15\text{ Hz}$					90		dB		
	$f_{SIG} = 60\text{ Hz}$ , $f_{DATA} = 15\text{ Hz}$					90		dB		
Output Noise		See Typical Characteristics								
Power-Supply Rejection	at DC, dB = $-20 \log(\Delta V_{OUT}/V_{DD})$ <sup>(2)</sup>		80	95		75	90	dB		
<b>VOLTAGE REFERENCE INPUT</b>										
Reference Input Range	REF IN+, REF IN-		0	$V_{DD}$		0	$V_{DD}$	V		
$V_{REF}$	$V_{REF} \equiv (\text{REF IN+}) - (\text{REF IN-})$ , RANGE = 0		0.1	1.25	1.30		0.1	1.25	1.30	V
	RANGE = 1		0.1		$V_{DD}$		0.1		2.6	V
Common-Mode Rejection	at DC			120			95		dB	
Common-Mode Rejection	$f_{VREFCM} = 60\text{ Hz}$ , $f_{DATA} = 15\text{ Hz}$			120			93		dB	
Bias Current <sup>(3)</sup>	$V_{REF} = 1.25\text{ V}$			1.3			8		$\mu\text{A}$	
<b>POWER-SUPPLY REQUIREMENTS</b>										
Power-Supply Voltage	$V_{DD}$		2.7		3.3		2.7		3.3	V
Current	PGA = 1, Buffer OFF			190	375		200	480	$\mu\text{A}$	
	PGA = 128, Buffer OFF			460	700		600	940	$\mu\text{A}$	
	PGA = 1, Buffer ON			240	375		350	585	$\mu\text{A}$	
	PGA = 128, Buffer ON			870	1325		1200	1800	$\mu\text{A}$	
	SLEEP Mode			75			110		$\mu\text{A}$	
	Read Data Continuous Mode			113			250		$\mu\text{A}$	
	$\overline{\text{PDWN}} = 0$			0.5			7.5		nA	
Power Dissipation	PGA = 1, Buffer OFF		0.6		1.2		0.66		1.58	mW

(2)  $\Delta V_{OUT}$  is a change in digital result.

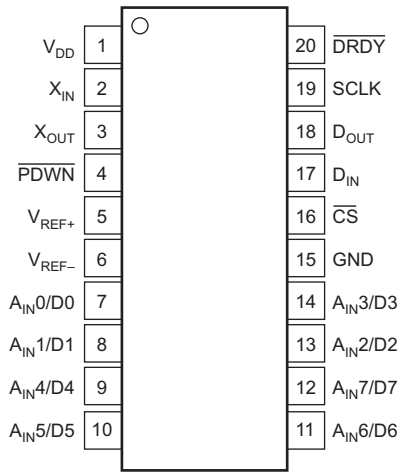
(3) 12-pF switched capacitor at  $f_{SAMP}$  clock frequency.



- (1) See data sheet for absolute maximum and minimum recommended operating conditions.
- (2) Silicon operating life design goal is 10 years at 105°C junction temperature (does not include package interconnect life).
- (3) The predicted operating lifetime vs. junction temperature is based on reliability modeling using electromigration as the dominant failure mechanism affecting device wearout for the specific device process and design characteristics.

**Figure 1. ADS1243-HT Operating Life Derating Chart**

## PIN CONFIGURATION

**CDIP PACKAGE  
(TOP VIEW)**


## PIN ASSIGNMENTS

PIN #	NAME	DESCRIPTION
1	V <sub>DD</sub>	Power Supply
2	X <sub>IN</sub>	Clock Input
3	X <sub>OUT</sub>	Clock Output, used with crystal or ceramic resonator.
4	$\overline{\text{PDWN}}$	Active LOW. Power Down. The power down function shuts down the analog and digital circuits.
5	V <sub>REF+</sub>	Positive Differential Reference Input
6	V <sub>REF-</sub>	Negative Differential Reference Input
7	A <sub>IN</sub> 0/D0	Analog Input 0/Data I/O 0
8	A <sub>IN</sub> 1/D1	Analog Input 1/Data I/O 1
9	A <sub>IN</sub> 4/D4	Analog Input 4/Data I/O 4
10	A <sub>IN</sub> 5/D5	Analog Input 5/Data I/O 5
11	A <sub>IN</sub> 6/D6	Analog Input 6/Data I/O 6
12	A <sub>IN</sub> 7/D7	Analog Input 7/Data I/O 7
13	A <sub>IN</sub> 2/D2	Analog Input 2/Data I/O 2
14	A <sub>IN</sub> 3/D3	Analog Input 3/Data I/O 3
15	GND	Ground
16	$\overline{\text{CS}}$	Active LOW, Chip Select
17	D <sub>IN</sub>	Serial Data Input, Schmitt Trigger
18	D <sub>OUT</sub>	Serial Data Output
19	SCLK	Serial Clock, Schmitt Trigger
20	$\overline{\text{DRDY}}$	Active LOW, Data Ready

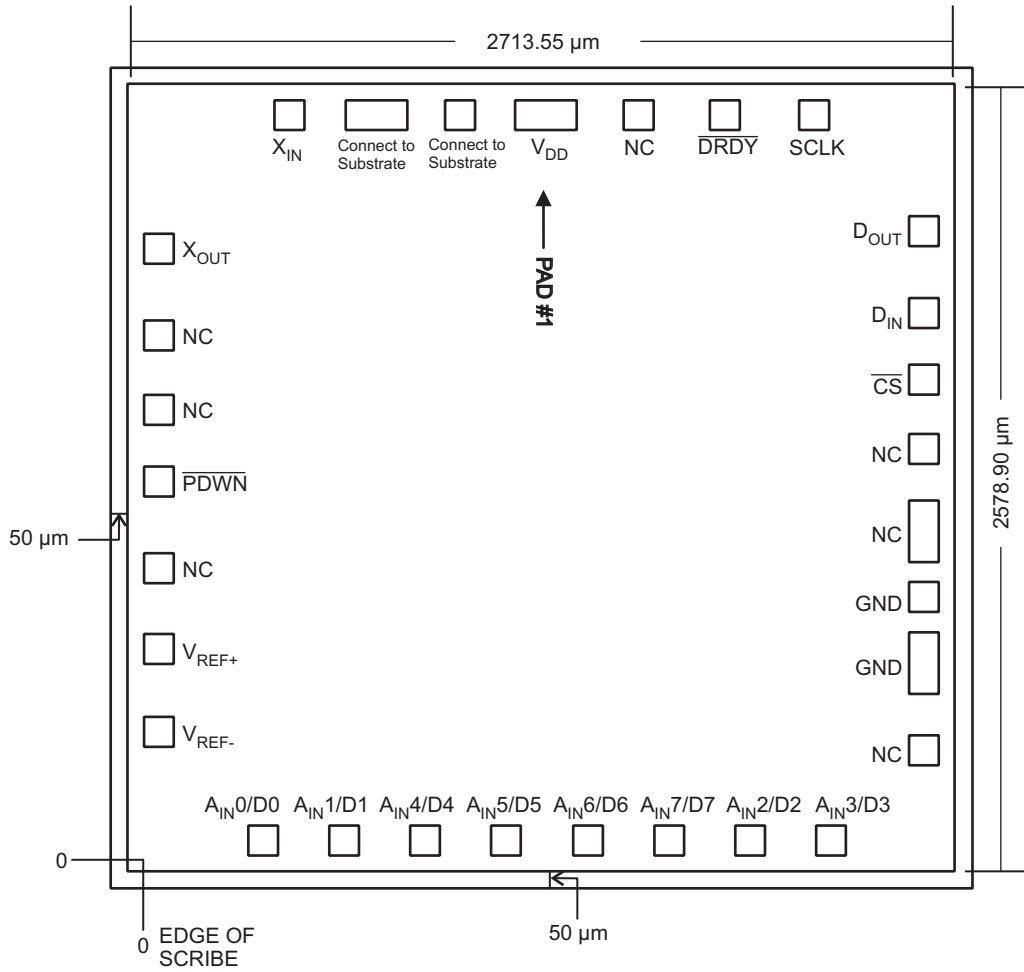
**BARE DIE INFORMATION**

DIE THICKNESS	BACKSIDE FINISH	BACKSIDE POTENTIAL	BOND PAD METALLIZATION COMPOSITION
15 mils	Silicon with backgrind	GND	AlCu

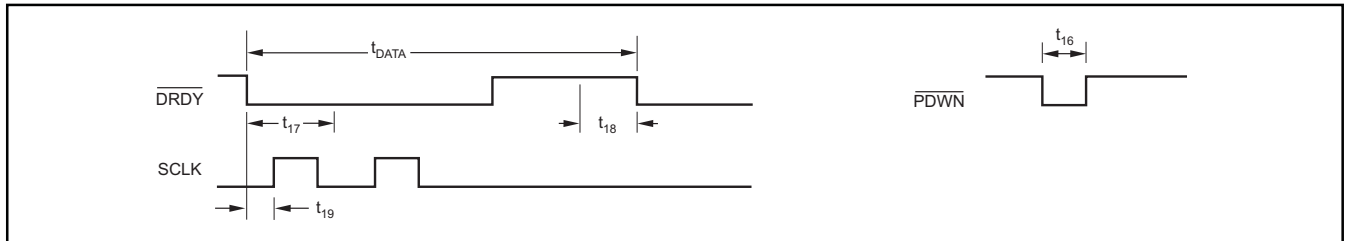
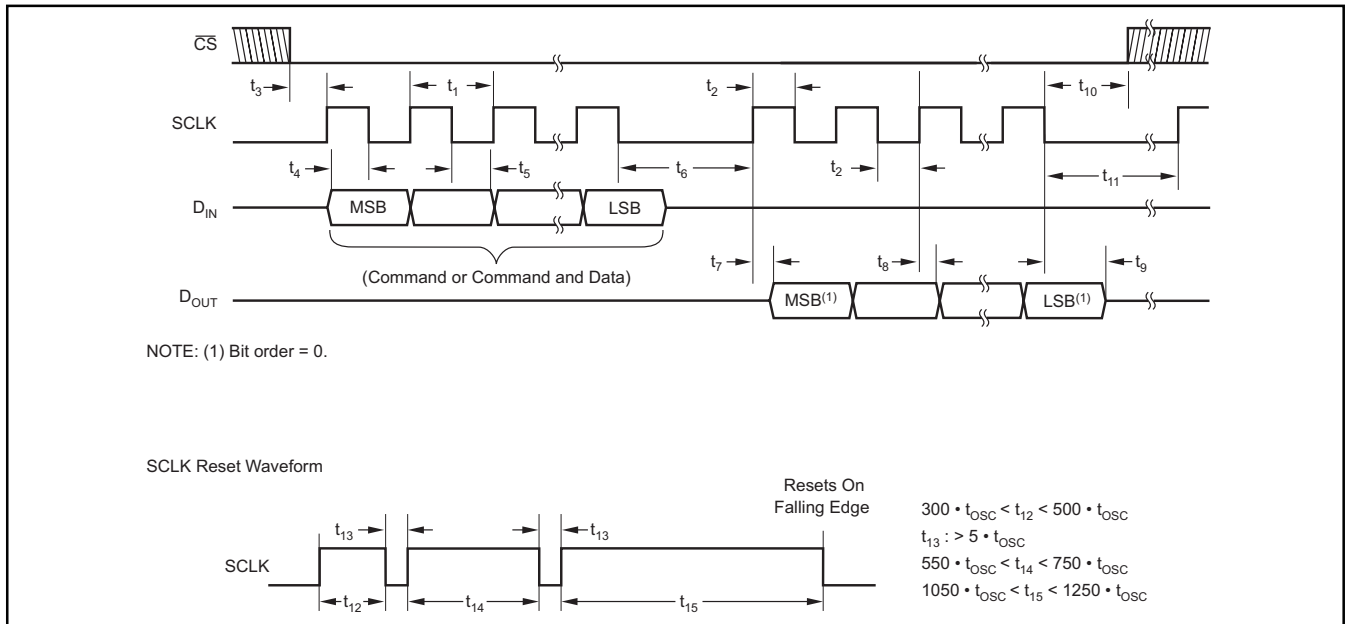
**Table 1. Bond Pad Coordinates in Microns<sup>(1)</sup>**

DISCRIPTION	PAD NUMBER	X MIN	Y MIN	X MAX	Y MAX
V <sub>DD</sub>	1	1268.55	2471.55	1478.15	2572.55
Connect to substrate	2	1030.45	2471.55	1132.45	2572.55
Connect to substrate	3	692.45	2471.55	902.05	2572.55
X <sub>IN</sub>	4	450.05	2471.55	552.05	2572.55
X <sub>OUT</sub>	5	6.45	2016.65	107.45	2118.65
NC	6	6.45	1721.75	107.45	1823.75
NC	7	6.45	1468.60	107.45	1570.60
$\overline{\text{PDWN}}$	8	6.45	1224.80	107.45	1326.80
NC	9	6.45	929.95	107.45	1031.95
V <sub>REF+</sub>	10	6.45	655.20	107.45	757.20
V <sub>REF-</sub>	11	6.45	373.25	107.45	475.25
A <sub>IN</sub> 0/D0	12	361.15	3.55	462.15	105.55
A <sub>IN</sub> 1/D1	13	636.45	3.55	737.45	105.55
A <sub>IN</sub> 4/D4	14	911.70	3.55	1012.70	105.55
A <sub>IN</sub> 5/D5	15	1186.85	3.55	1287.85	105.55
A <sub>IN</sub> 6/D6	16	1466.25	3.55	1567.25	105.55
A <sub>IN</sub> 7/D7	17	1742.50	3.55	1843.50	105.55
A <sub>IN</sub> 2/D2	18	2017.60	3.55	2118.60	105.55
A <sub>IN</sub> 3/D3	19	2292.75	3.55	2393.75	105.55
NC	20	2608.70	310.50	2709.70	412.50
GND	21	2608.75	553.25	2709.75	762.85
GND	22	2608.70	832.20	2709.70	934.20
NC	23	2608.75	1001.60	2709.75	1211.20
NC	24	2608.70	1335.65	2709.70	1437.65
$\overline{\text{CS}}$	25	2608.70	1571.45	2709.70	1673.45
D <sub>IN</sub>	26	2608.70	1797.90	2709.70	1899.90
D <sub>OUT</sub>	27	2608.70	2076.55	2709.70	2178.55
SCLK	28	2234.80	2471.55	2336.80	2572.55
$\overline{\text{DRDY}}$	29	1931.10	2471.55	2033.10	2572.55
NC	30	1637.90	2471.55	1739.90	2572.55

(1) For signal descriptions see the Pin Assignments table.



**TIMING DIAGRAMS**



**TIMING REQUIREMENTS**

PARAMETER	TEST CONDITIONS		MIN	MAX	UNIT
t <sub>1</sub>	SCLK Period		4		t <sub>osc</sub> Periods
				3	$\overline{\text{DRDY}}$ Periods
t <sub>2</sub>	SCLK Pulse Width, HIGH and LOW		200		ns
t <sub>3</sub>	$\overline{\text{CS}}$ low to first SCLK Edge; Setup Time <sup>(1)</sup>		0		ns
t <sub>4</sub>	D <sub>IN</sub> Valid to SCLK Edge; Setup Time		50		ns
t <sub>5</sub>	Valid D <sub>IN</sub> to SCLK Edge; Hold Time		50		ns
t <sub>6</sub>	Delay between last SCLK edge for D <sub>IN</sub> and first SCLK edge for D <sub>OUT</sub> : RDATA, RDATA <sub>C</sub> , RREG, WREG		50		t <sub>osc</sub> Periods
t <sub>7</sub> <sup>(2)</sup>	SCLK Edge to Valid New D <sub>OUT</sub>			50	ns
t <sub>8</sub> <sup>(2)</sup>	SCLK Edge to D <sub>OUT</sub> , Hold Time		0		ns
t <sub>9</sub>	Last SCLK Edge to D <sub>OUT</sub> Tri-State NOTE: D <sub>OUT</sub> goes tri-state immediately when CS goes HIGH.		6	10	t <sub>osc</sub> Periods
t <sub>10</sub>	$\overline{\text{CS}}$ LOW time after final SCLK edge.	Read from the device	0		t <sub>osc</sub> Periods
		Write to the device	8		t <sub>osc</sub> Periods
t <sub>11</sub>	Final SCLK edge of one command until first edge SCLK of next command:	RREG, WREG, DSYNC, SLEEP, RDATA, RDATA <sub>C</sub> , STOPC	4		t <sub>osc</sub> Periods
		SELFGCAL, SELFOCAL, SYSOCAL, SYSGCAL	2		$\overline{\text{DRDY}}$ Periods
		SELFCAL	4		$\overline{\text{DRDY}}$ Periods
		RESET (also SCLK Reset)	16		t <sub>osc</sub> Periods
t <sub>16</sub>	Pulse Width		4		t <sub>osc</sub> Periods
t <sub>17</sub>	Allowed analog input change for next valid conversion.			5000	t <sub>osc</sub> Periods
t <sub>18</sub>	DOR update, DOR data not valid.		4		t <sub>osc</sub> Periods
t <sub>19</sub>	First SCLK after DRDY goes LOW:	RDATA <sub>C</sub> Mode	10		t <sub>osc</sub> Periods
		Any other mode	0		t <sub>osc</sub> Periods

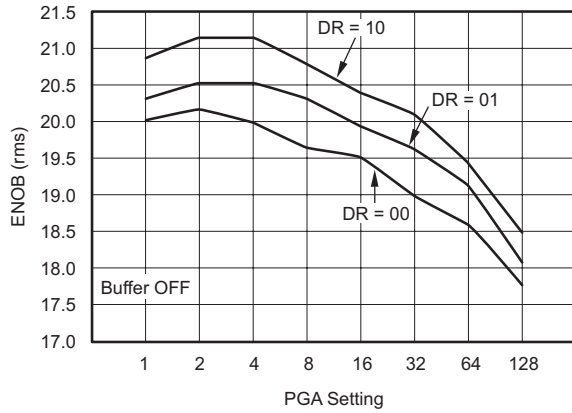
(1)  $\overline{\text{CS}}$  may be tied LOW.

(2) Load = 20 pF || 10 kΩ to GND.

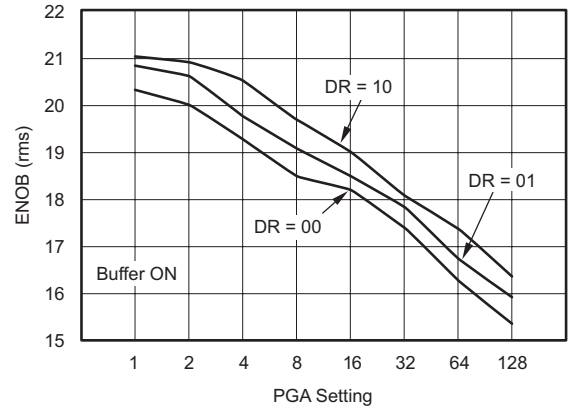
**TYPICAL CHARACTERISTICS**

All specifications  $V_{DD} = 5\text{ V}$ ,  $f_{OSC} = 2.4576\text{ MHz}$ ,  $PGA = 1$ ,  $f_{DATA} = 15\text{ Hz}$ , and  $V_{REF} \equiv (\text{REF IN+}) - (\text{REF IN-}) = 2.5\text{ V}$ , unless otherwise specified.

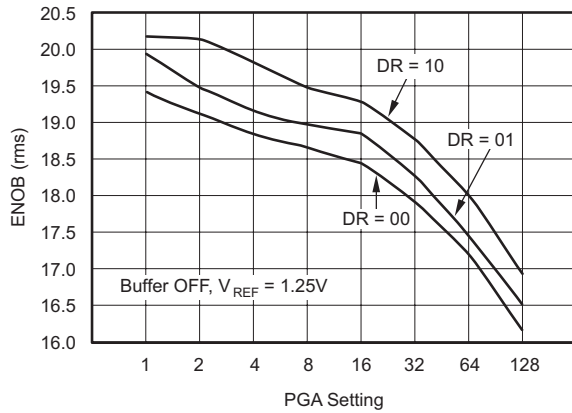
**EFFECTIVE NUMBER OF BITS  
vs  
PGA SETTING**



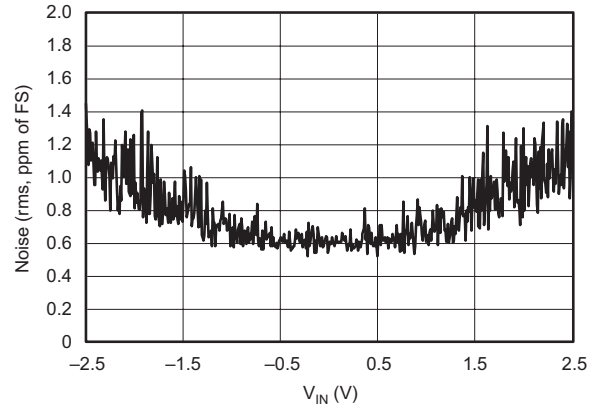
**EFFECTIVE NUMBER OF BITS  
vs  
PGA SETTING**



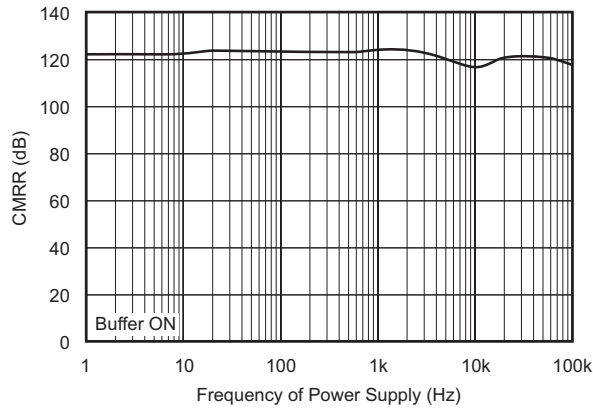
**EFFECTIVE NUMBER OF BITS  
vs  
PGA SETTING**



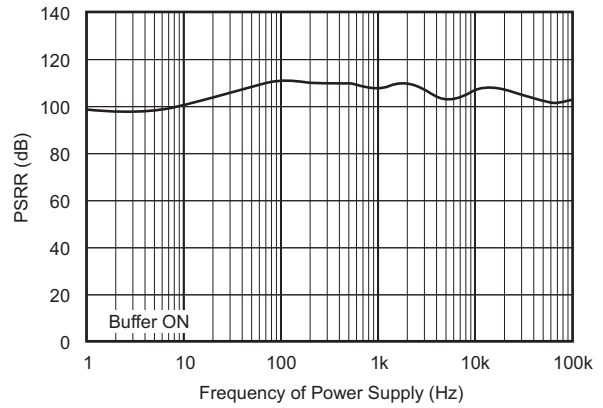
**NOISE  
vs  
INPUT SIGNAL**



**COMMON-MODE REJECTION RATIO  
vs  
FREQUENCY**

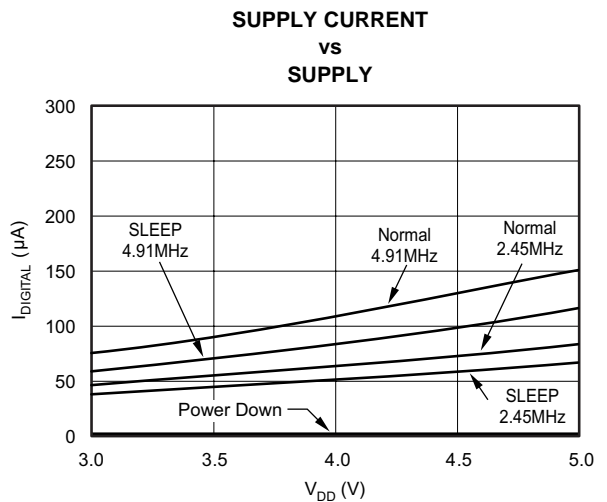
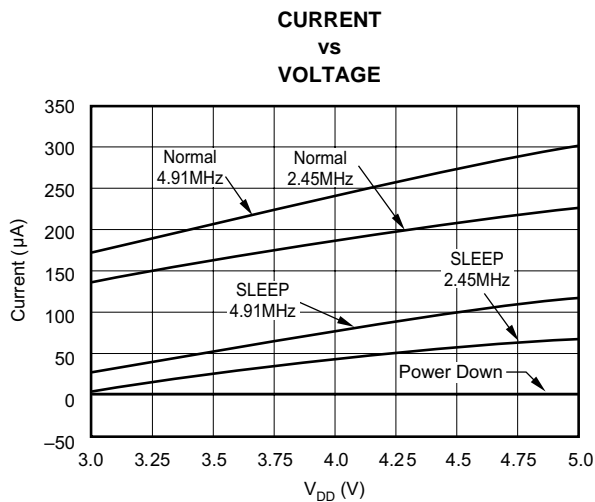
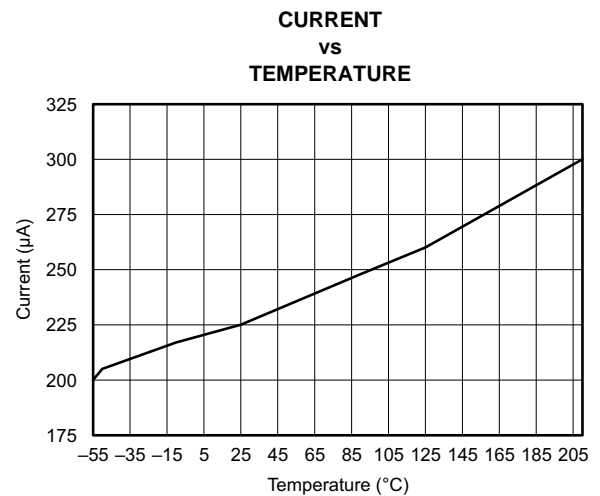
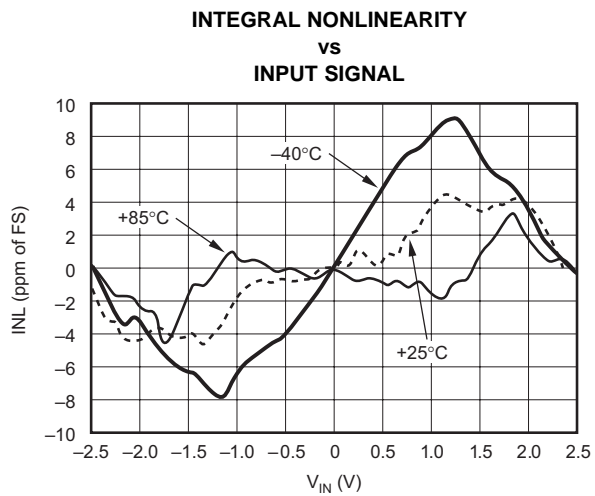
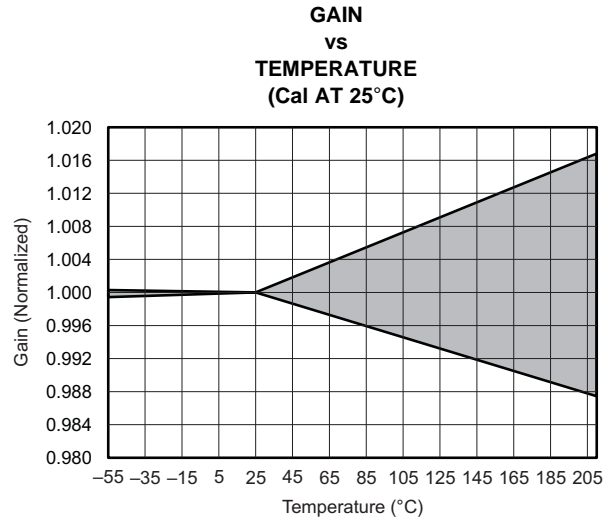
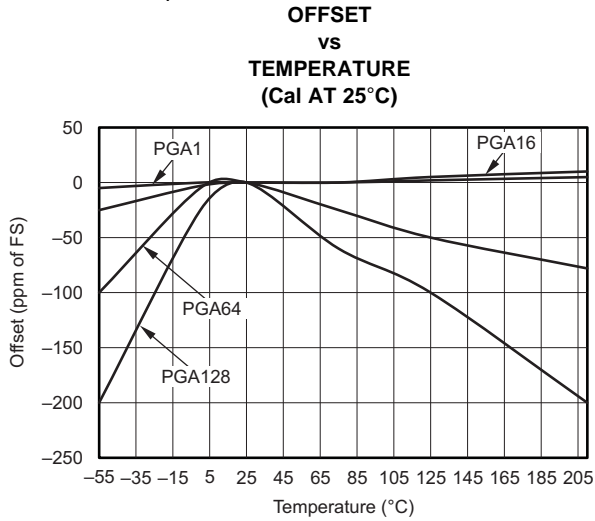


**POWER SUPPLY REJECTION RATIO  
vs  
FREQUENCY**



**TYPICAL CHARACTERISTICS (continued)**

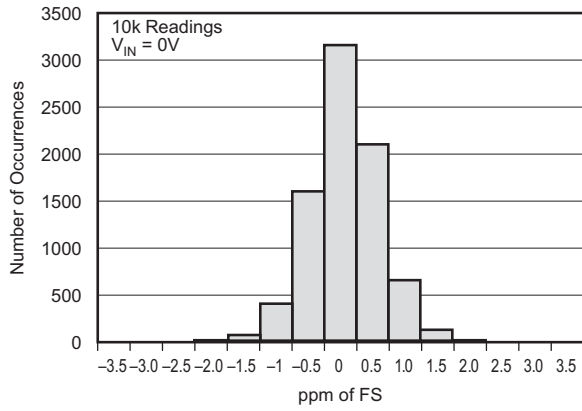
All specifications  $V_{DD} = 5\text{ V}$ ,  $f_{OSC} = 2.4576\text{ MHz}$ ,  $PGA = 1$ ,  $f_{DATA} = 15\text{ Hz}$ , and  $V_{REF} \equiv (\text{REF IN+}) - (\text{REF IN-}) = 2.5\text{ V}$ , unless otherwise specified.



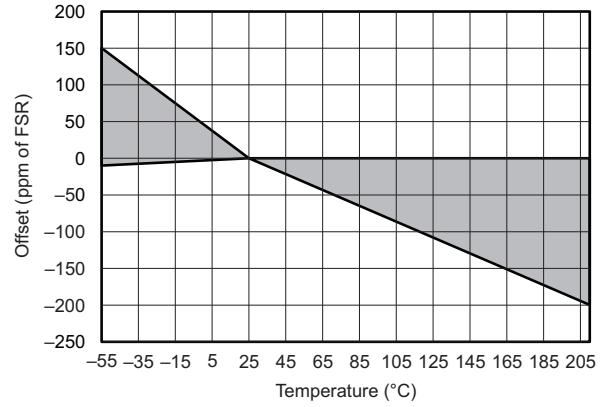
**TYPICAL CHARACTERISTICS (continued)**

All specifications  $V_{DD} = 5\text{ V}$ ,  $f_{OSC} = 2.4576\text{ MHz}$ ,  $PGA = 1$ ,  $f_{DATA} = 15\text{ Hz}$ , and  $V_{REF} \equiv (\text{REF IN+}) - (\text{REF IN-}) = 2.5\text{ V}$ , unless otherwise specified.

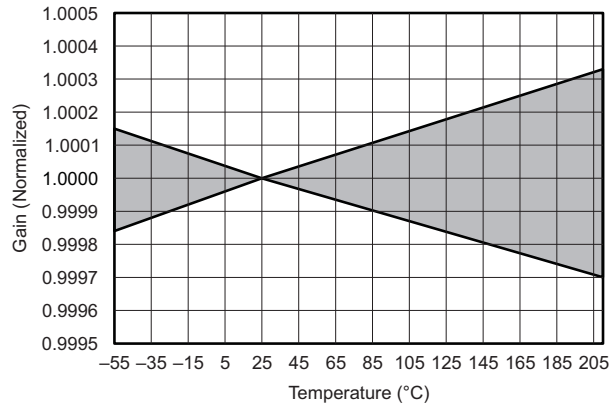
**NOISE HISTOGRAM**



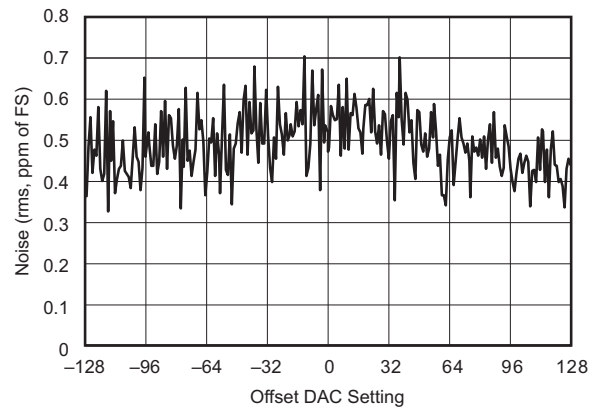
**OFFSET DAC OFFSET  
vs  
TEMPERATURE  
(Cal AT 25°C)**



**OFFSET DAC GAIN  
vs  
TEMPERATURE  
(Cal AT 25°C)**



**OFFSET DAC NOISE  
vs  
SETTING**



## OVERVIEW

### INPUT MULTIPLEXER

The input multiplexer provides for any combination of differential inputs to be selected on any of the input channels, as shown in Figure 2. For example, if  $A_{IN0}$  is selected as the positive differential input channel, any other channel can be selected as the negative terminal for the differential input channel. With this method, it is possible to have up to seven single-ended input channels or four independent differential input channels for the ADS1243.

The ADS1243 features a single-cycle settling digital filter that provides valid data on the first conversion after a new channel selection. In order to minimize the settling error, synchronize MUX changes to the conversion beginning, which is indicated by the falling edge of  $\overline{DRDY}$ . In other words, issuing a MUX change through the WREG command immediately after  $\overline{DRDY}$  goes LOW minimizes the settling error. Increasing the time between the conversion beginning ( $\overline{DRDY}$  goes LOW) and the MUX change command ( $t_{DELAY}$ ) results in a settling error in the conversion data, as shown in Figure 3.

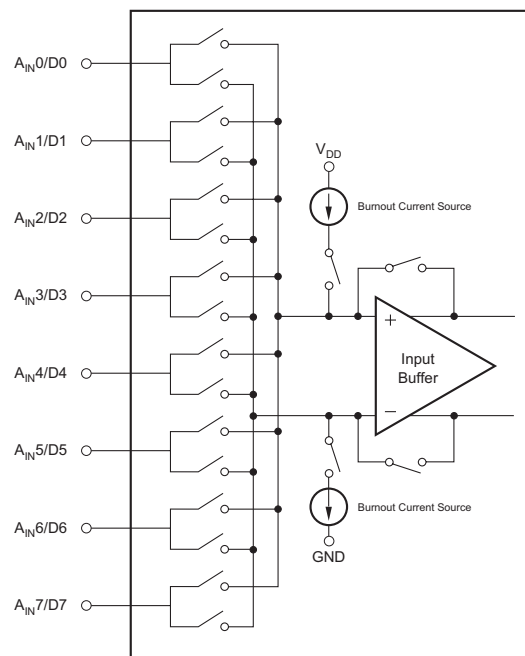


Figure 2. Input Multiplexer Configuration

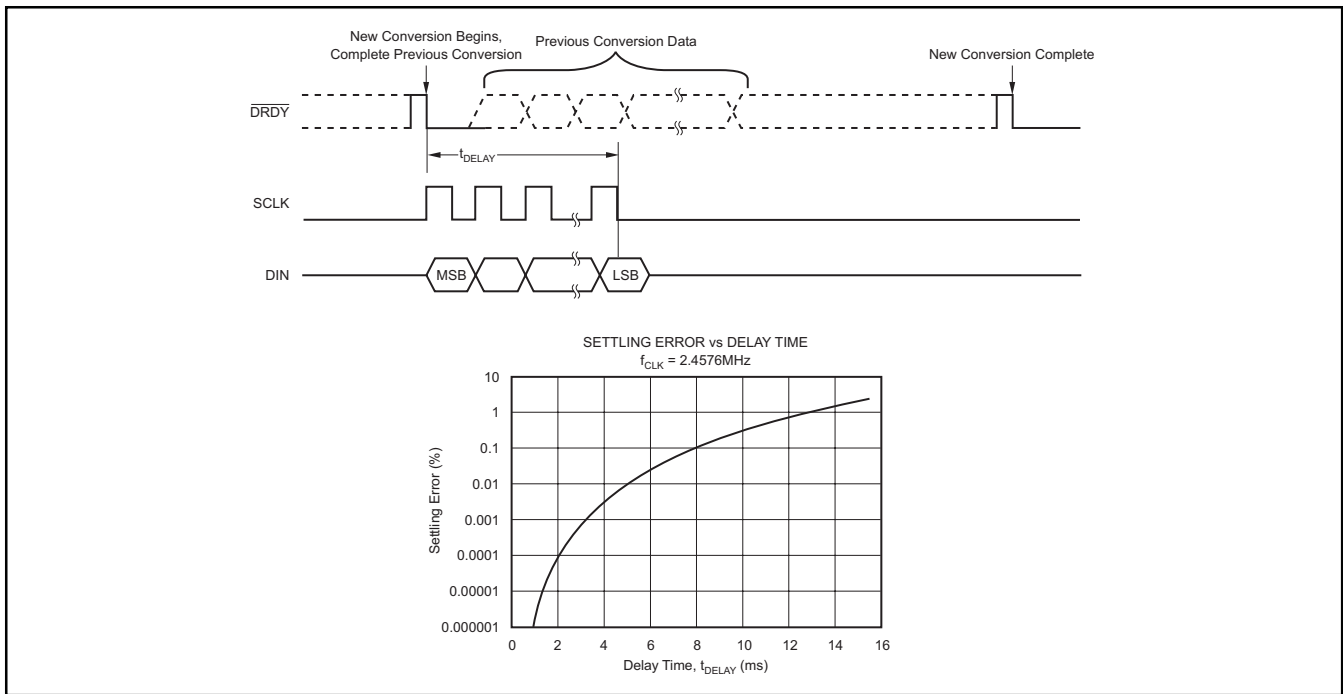


Figure 3. Input Multiplexer Configuration

**BURNOUT CURRENT SOURCES**

The Burnout Current Sources can be used to detect sensor short-circuit or open-circuit conditions. Setting the Burnout Current Sources (BOCS) bit in the SETUP register activates two 2µA current sources called burnout current sources. One of the current sources is connected to the converter’s negative input and the other is connected to the converter’s positive input.

Figure 4 shows the situation for an open-circuit sensor. This is a potential failure mode for many kinds of remotely connected sensors. The current source on the positive input acts as a pull-up, causing the positive input to go to the positive analog supply, and the current source on the negative input acts as a pull-down, causing the negative input to go to ground. The ADS1243 therefore outputs full-scale (7FFFFFF Hex).

Figure 5 shows a short-circuited sensor. Since the inputs are shorted and at the same potential, the ADS1243 signal outputs are approximately zero. (Note that the code for shorted inputs is not exactly zero due to internal series resistance, low-level noise and other error sources.)

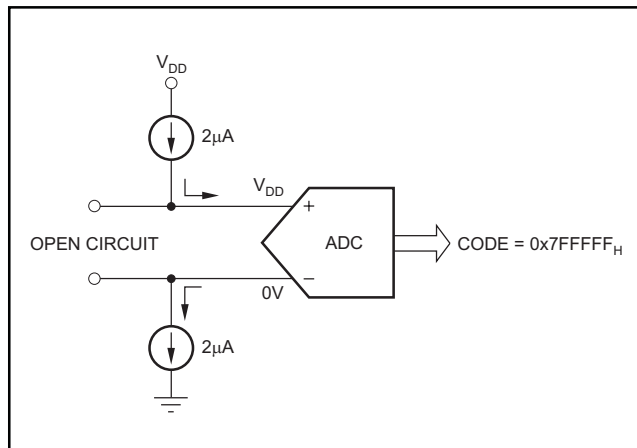


Figure 4. Burnout Detection While Sensor is Open-Circuited.

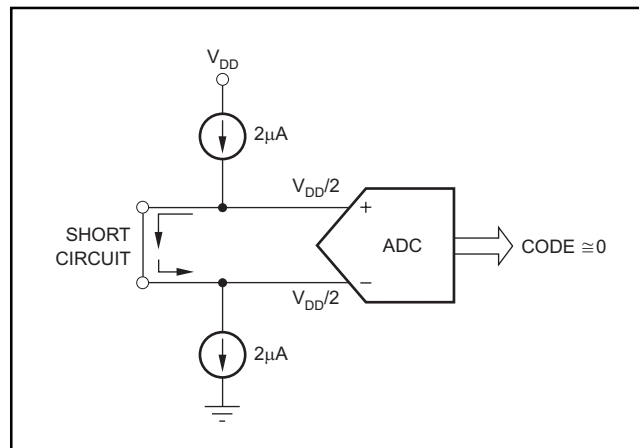


Figure 5. Burnout Detection While Sensor is Short-Circuited.

## INPUT BUFFER

The input impedance of ADS1243 without the buffer enabled is approximately  $5\text{M}\Omega/\text{PGA}$ . For systems requiring very high input impedance, the ADS1243 provides a chopper-stabilized differential FET-input voltage buffer. When activated, the buffer raises the ADS1243 input impedance to approximately  $5\text{G}\Omega$ .

The buffer's input range is approximately  $50\text{mV}$  to  $V_{\text{DD}} - 1.5\text{V}$ . The buffer's linearity will degrade beyond this range. Differential signals should be adjusted so that both signals are within the buffer's input range.

The buffer can be enabled using the BUFEN pin or the BUFEN bit in the ACR register. The buffer is on when the BUFEN pin is high and the BUFEN bit is set to one. If the BUFEN pin is low, the buffer is disabled. If the BUFEN bit is set to zero, the buffer is also disabled.

The buffer draws additional current when activated. The current required by the buffer depends on the PGA setting. When the PGA is set to 1, the buffer uses approximately  $50\text{ }\mu\text{A}$ ; when the PGA is set to 128, the buffer uses approximately  $500\text{ }\mu\text{A}$ .

## PGA

The Programmable Gain Amplifier (PGA) can be set to gains of 1, 2, 4, 8, 16, 32, 64, or 128. Using the PGA can improve the effective resolution of the A/D converter. For instance, with a PGA of 1 on a 5-V full-scale signal, the A/D converter can resolve down to  $1\text{ }\mu\text{V}$ . With a PGA of 128 and a full-scale signal of  $39\text{ mV}$ , the A/D converter can resolve down to  $75\text{ nV}$ .  $V_{\text{DD}}$  current increases with PGA settings higher than 4.

## OFFSET DAC

The input to the PGA can be shifted by half the full-scale input range of the PGA using the Offset DAC (ODAC) register. The ODAC register is an 8-bit value; the MSB is the sign and the seven LSBs provide the magnitude of the offset. Using the offset DAC does not reduce the performance of the A/D converter. For more details on the ODAC in the ADS1243, please refer to TI application report SBAA077 (available through the TI website).

## MODULATOR

The modulator is a single-loop second-order system. The modulator runs at a clock speed ( $f_{\text{MOD}}$ ) that is derived from the external clock ( $f_{\text{OSC}}$ ). The frequency division is determined by the SPEED bit in the SETUP register, as shown in [Table 2](#).

**Table 2. Output Configuration**

f <sub>osc</sub>	SPEED BIT	f <sub>MOD</sub>	DR BITS			1st NOTCH FREQUENCY
			00	01	10	
2.4576 MHz	0	19,200 Hz	15 Hz	7.5 Hz	3.75 Hz	50/60 Hz
	1	9,600 Hz	7.5 Hz	3.75 Hz	1.875 Hz	25/30 Hz
4.9152 MHz	0	38,400 Hz	30 Hz	15 Hz	7.5 Hz	100/120 Hz
	1	19,200 Hz	15 Hz	7.5 Hz	3.75 Hz	50/60 Hz

## CALIBRATION

The offset and gain errors can be minimized with calibration. The ADS1243 supports both self and system calibration.

Self-calibration of the ADS1243 corrects internal offset and gain errors and is handled by three commands: SELFCAL, SELFGAL, and SELFOCAL. The SELFCAL command performs both an offset and gain calibration. SELFGAL performs a gain calibration and SELFOCAL performs an offset calibration, each of which takes two t<sub>DATA</sub> periods to complete. During self-calibration, the ADC inputs are disconnected internally from the input pins. The PGA must be set to 1 prior to issuing a SELFCAL or SELFGAL command. Any PGA is allowed when issuing a SELFOCAL command. For example, if using PGA = 64, first set PGA = 1 and issue SELFGAL. Afterwards, set PGA = 64 and issue SELFOCAL. For operation with a reference voltage greater than (V<sub>DD</sub> – 1.5) volts, the buffer must also be turned off during gain self-calibration to avoid exceeding the buffer input range.

System calibration corrects both internal and external offset and gain errors. While performing system calibration, the appropriate signal must be applied to the inputs. The system offset calibration command (SYSOCAL) requires a zero input differential signal (see Table 5). It then computes the offset that nullifies the offset in the system. The system gain calibration command (SYSGCAL) requires a positive full-scale input signal. It then computes a value to nullify the gain error in the system. Each of these calibrations takes two t<sub>DATA</sub> periods to complete. System gain calibration is recommended for the best gain calibration at higher PGAs.

Calibration should be performed after power on, a change in temperature, or a change of the PGA. The RANGE bit (ACR bit 2) must be zero during calibration.

Calibration removes the effects of the ODAC; therefore, disable the ODAC during calibration, and enable again after calibration is complete.

At the completion of calibration, the  $\overline{\text{DRDY}}$  signal goes low, indicating the calibration is finished. The first data after calibration should be discarded since it may be corrupt from calibration data remaining in the filter. The second data is always valid.

## EXTERNAL VOLTAGE REFERENCE

The ADS1243 requires an external voltage reference. The selection for the voltage reference value is made through the ACR register.

The external voltage reference is differential and is represented by the voltage difference between the pins: +V<sub>REF</sub> and –V<sub>REF</sub>. The absolute voltage on either pin, +V<sub>REF</sub> or –V<sub>REF</sub>, can range from GND to V<sub>DD</sub>. However, the following limitations apply:

- For V<sub>DD</sub> = 5 V and RANGE = 0 in the ACR, the differential V<sub>REF</sub> must not exceed 2.5 V.
- For V<sub>DD</sub> = 5 V and RANGE = 1 in the ACR, the differential V<sub>REF</sub> must not exceed 5 V.
- For V<sub>DD</sub> = 3 V and RANGE = 0 in the ACR, the differential V<sub>REF</sub> must not exceed 1.25 V.
- For V<sub>DD</sub> = 3 V and RANGE = 1 in the ACR, the differential V<sub>REF</sub> must not exceed 2.5 V.

## CLOCK GENERATOR

The clock source for ADS1243 can be provided from a crystal, oscillator, or external clock. When the clock source is a crystal, external capacitors must be provided to ensure start-up and stable clock frequency. This is shown in both Figure 6 and Table 3. X<sub>OUT</sub> is only for use with external crystals and it should not be used as a clock driver for external circuitry.

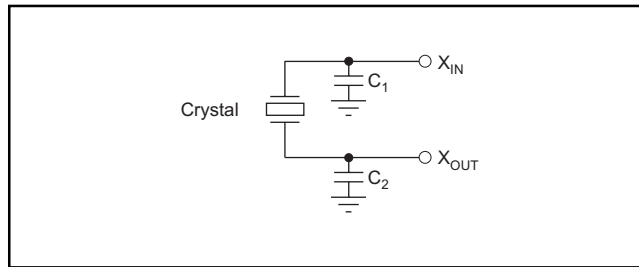


Figure 6. Crystal Connection.

Table 3. Recommended Crystals

CLOCK SOURCE	FREQUENCY	C <sub>1</sub>	C <sub>2</sub>	PART NUMBER
Crystal	2.4576	0-20 pF	0-20 pF	ECS, ECSD 2.45 – 32
Crystal	4.9152	0-20 pF	0-20 pF	ECS, ECSD 4.91
Crystal	4.9152	0-20 pF	0-20 pF	ECS, ECSD 4.91
Crystal	4.9152	0-20 pF	0-20 pF	CTS, MP 042 4M9182

## DIGITAL FILTER

The ADS1243 has a 1279 tap linear phase Finite Impulse Response (FIR) digital filter that a user can configure for various output data rates. When a 2.4576-MHz crystal is used, the device can be programmed for an output data rate of 15 Hz, 7.5 Hz, or 3.75 Hz. Under these conditions, the digital filter rejects both 50Hz and 60Hz interference. Figure 7 shows the digital filter frequency response for data output rates of 15 Hz, 7.5 Hz, and 3.75 Hz.

If a different data output rate is desired, a different crystal frequency can be used. However, the rejection frequencies shift accordingly. For example, a 3.6864-MHz master clock with the default register condition has:

$$(3.6864 \text{ MHz} / 2.4576 \text{ MHz}) \bullet 15 \text{ Hz} = 22.5 \text{ Hz data output rate}$$

and the first and second notch is:

$$1.5 \bullet (50 \text{ Hz and } 60 \text{ Hz}) = 75 \text{ Hz and } 90 \text{ Hz}$$

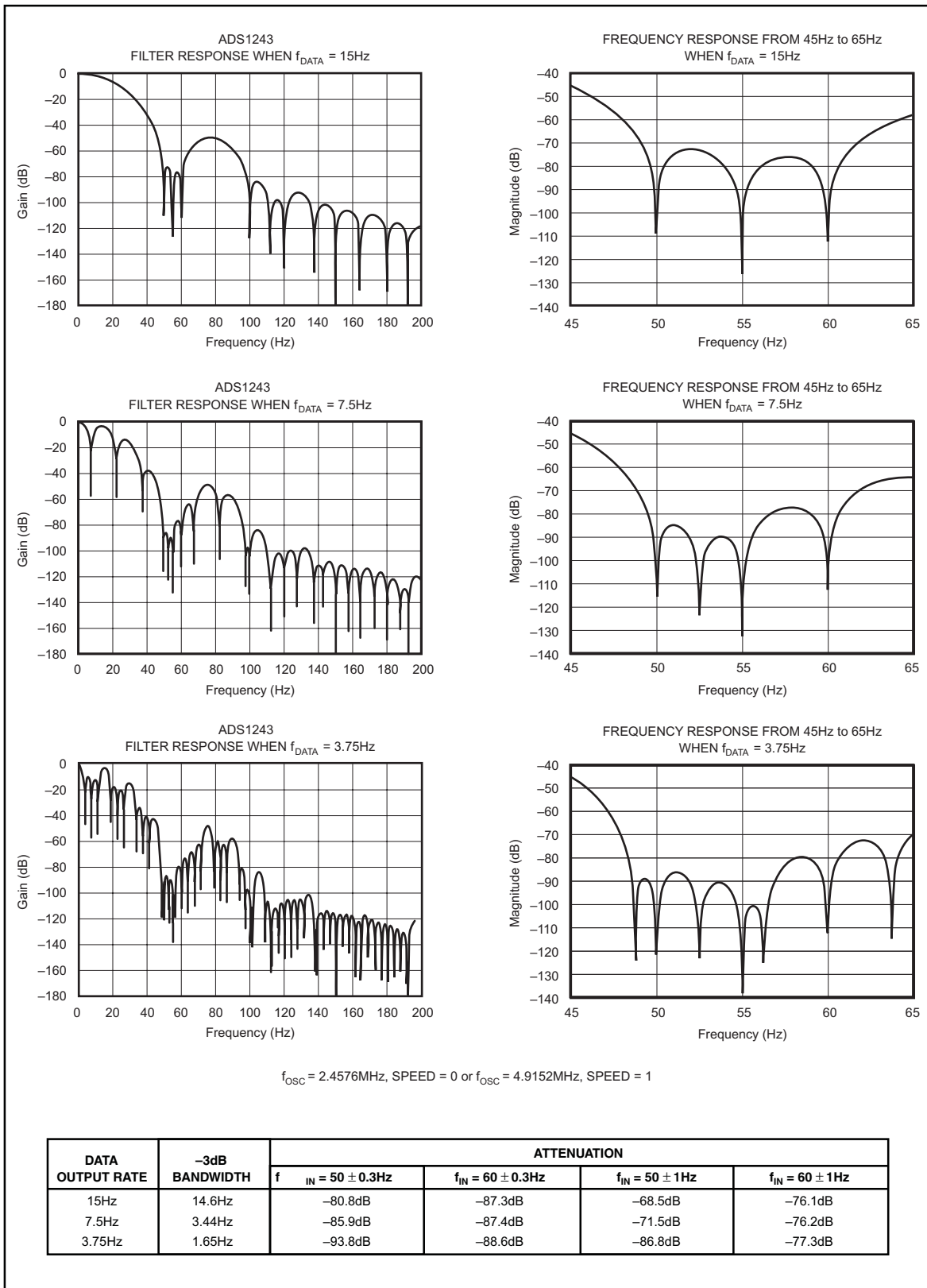


Figure 7. Filter Frequency Responses

## DATA I/O INTERFACE

The ADS1243 has eight pins that serve a dual purpose as both analog inputs and data I/O. These pins are configured through the IOCON, DIR, and DIO registers and can be individually configured as either analog inputs or data I/O. See Figure 8 for the equivalent schematic of an Analog/Data I/O pin.

The IOCON register defines the pin as either an analog input or data I/O. The power-up state is an analog input. If the pin is configured as an analog input in the IOCON register, the DIR and DIO registers have no effect on the state of the pin.

If the pin is configured as data I/O in the IOCON register, then DIR and DIO are used to control the state of the pin. The DIR register controls the direction of the data pin, either as an input or output. If the pin is configured as an input in the DIR register, then the corresponding DIO register bit reflects the state of the pin. Make sure the pin is driven to a logic one or zero when configured as an input to prevent excess current dissipation. If the pin is configured as an output in the DIR register, then the corresponding DIO register bit value determines the state of the output pin (0 = GND, 1 =  $V_{DD}$ ).

It is still possible to perform A/D conversions on a pin configured as data I/O. This may be useful as a test mode, where the data I/O pin is driven and an A/D conversion is done on the pin.

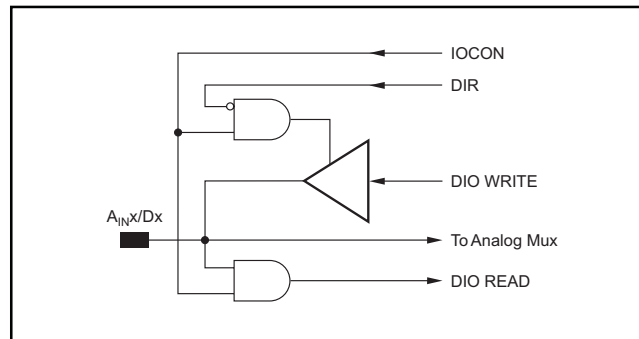


Figure 8. Analog/Data Interface Pin

## SERIAL PERIPHERAL INTERFACE

The Serial Peripheral Interface (SPI) allows a controller to communicate synchronously with the ADS1243. The ADS1243 operates in slave-only mode. The serial interface is a standard four-wire SPI ( $\overline{CS}$ , SCLK,  $D_{IN}$  and  $D_{OUT}$ ) interface.

### Chip Select ( $\overline{CS}$ )

The chip select ( $\overline{CS}$ ) input must be externally asserted before communicating with the ADS1243.  $\overline{CS}$  must stay LOW for the duration of the communication. Whenever  $\overline{CS}$  goes HIGH, the serial interface is reset.  $\overline{CS}$  may be hard-wired LOW.

### Serial Clock (SCLK)

The serial clock (SCLK) features a Schmitt-triggered input and is used to clock  $D_{IN}$  and  $D_{OUT}$  data. Make sure to have a clean SCLK to prevent accidental double-shifting of the data. If SCLK is not toggled within three  $\overline{DRDY}$  pulses, the serial interface resets on the next SCLK pulse and starts a new communication cycle. A special pattern on SCLK resets the entire chip; see the RESET section for additional information.

### Data Input ( $D_{IN}$ ) and Data Output ( $D_{OUT}$ )

The data input ( $D_{IN}$ ) and data output ( $D_{OUT}$ ) receive and send data from the ADS1243.  $D_{OUT}$  is high impedance when not in use to allow  $D_{IN}$  and  $D_{OUT}$  to be connected together and driven by a bidirectional bus. Note: the Read Data Continuous Mode (RDATAC) command should not be issued when  $D_{IN}$  and  $D_{OUT}$  are connected. While in RDATAC mode,  $D_{IN}$  looks for the STOPC or RESET command. If either of these 8-bit bytes appear on  $D_{OUT}$  (which is connected to  $D_{IN}$ ), the RDATAC mode ends.

## DATA READY ( $\overline{\text{DRDY}}$ ) PIN

The  $\overline{\text{DRDY}}$  line is used as a status signal to indicate when data is ready to be read from the internal data register.  $\overline{\text{DRDY}}$  goes LOW when a new data word is available in the DOR register. It is reset HIGH when a read operation from the data register is complete. It also goes HIGH prior to the updating of the output register to indicate when not to read from the device to ensure that a data read is not attempted while the register is being updated.

The status of  $\overline{\text{DRDY}}$  can also be obtained by interrogating bit 7 of the ACR register (address  $2_{\text{H}}$ ). The serial interface can operate in 3-wire mode by tying the  $\overline{\text{CS}}$  input LOW. In this case, the SCLK,  $\text{D}_{\text{IN}}$ , and  $\text{D}_{\text{OUT}}$  lines are used to communicate with the ADS1243. This scheme is suitable for interfacing to microcontrollers. If  $\overline{\text{CS}}$  is required as a decoding signal, it can be generated from a port bit of the microcontroller.

## DSYNC OPERATION

Synchronization can be achieved through the DSYNC command. When the DSYNC command is sent, the digital filter is reset on the edge of the last SCLK of the DSYNC command. The modulator is held in RESET until the next edge of SCLK is detected. Synchronization occurs on the next rising edge of the system clock after the first SCLK following the DSYNC command.

## POWER-UP—SUPPLY VOLTAGE RAMP RATE

The power-on reset circuitry was designed to accommodate digital supply ramp rates as slow as 1 V/10 ms. To ensure proper operation, the power supply should ramp monotonically.

## ADS1243 REGISTERS

The operation of the device is set up through individual registers. Collectively, the registers contain all the information needed to configure the part, such as data format, multiplexer settings, calibration settings, data rate, etc. The 16 registers are shown in [Table 4](#).

**Table 4. Registers**

ADDRESS	REGISTER	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
00 <sub>H</sub>	SETUP	ID	ID	ID	ID	BOCS	PGA2	PGA1	PGA0
01 <sub>H</sub>	MUX	PSEL3	PSEL2	PSEL1	PSEL0	NSEL3	NSEL2	NSEL1	NSEL0
02 <sub>H</sub>	ACR	$\overline{\text{DRDY}}$	$\text{U}/\overline{\text{B}}$	SPEED	BUFEN	BIT ORDER	RANGE	DR1	DR0
03 <sub>H</sub>	ODAC	SIGN	OSET6	OSET5	OSET4	OSET3	OSET2	OSET1	OSET0
04 <sub>H</sub>	DIO	DIO_7	DIO_6	DIO_5	DIO_4	DIO_3	DIO_2	DIO_1	DIO_0
05 <sub>H</sub>	DIR	DIR_7	DIR_6	DIR_5	DIR_4	DIR_3	DIR_2	DIR_1	DIR_0
06 <sub>H</sub>	IOCON	IO7	IO6	IO5	IO4	IO3	IO2	IO1	IO0
07 <sub>H</sub>	OCR0	OCR07	OCR06	OCR05	OCR04	OCR03	OCR02	OCR01	OCR00
08 <sub>H</sub>	OCR1	OCR15	OCR14	OCR13	OCR12	OCR11	OCR10	OCR09	OCR08
09 <sub>H</sub>	OCR2	OCR23	OCR22	OCR21	OCR20	OCR19	OCR18	OCR17	OCR16
0A <sub>H</sub>	FSR0	FSR07	FSR06	FSR05	FSR04	FSR03	FSR02	FSR01	FSR00
0B <sub>H</sub>	FSR1	FSR15	FSR14	FSR13	FSR12	FSR11	FSR10	FSR09	FSR08
0C <sub>H</sub>	FSR2	FSR23	FSR22	FSR21	FSR20	FSR19	FSR18	FSR17	FSR16
0D <sub>H</sub>	DOR2	DOR23	DOR22	DOR21	DOR20	DOR19	DOR18	DOR17	DOR16
0E <sub>H</sub>	DOR1	DOR15	DOR14	DOR13	DOR12	DOR11	DOR10	DOR09	DOR08
0F <sub>H</sub>	DOR0	DOR07	DOR16	FSR21	DOR04	DOR03	DOR02	DOR01	DOR00

## DETAILED REGISTER DEFINITIONS

### Setup

(Address 00<sub>H</sub>) Setup Register

Reset Value = iiiii0000

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
ID	ID	ID	ID	BOCS	PGA2	PGA1	PGA0

bit 7–4 Factory Programmed Bits

bit 3 BOCS: Burnout Current Source

0 = Disabled (default)

1 = Enabled

bit 2–0 PGA2: PGA1: PGA0: Programmable Gain Amplifier

Gain Selection

000 = 1 (default)

001 = 2

010 = 4

011 = 8

100 = 16

101 = 32

110 = 64

111 = 128

**MUX**

(Address 01<sub>H</sub>) Multiplexer Control Register

Reset Value = 01<sub>H</sub>

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
PSEL3	PSEL2	PSEL1	PSEL0	NSEL3	NSEL2	NSEL1	NSEL0

bit 7–4 PSEL3: PSEL2: PSEL1: PSEL0: Positive Channel

Select

- 0000 = A<sub>IN</sub>0 (default)
- 0001 = A<sub>IN</sub>1
- 0010 = A<sub>IN</sub>2
- 0011 = A<sub>IN</sub>3
- 0100 = A<sub>IN</sub>4
- 0101 = A<sub>IN</sub>5
- 0110 = A<sub>IN</sub>6
- 0111 = A<sub>IN</sub>7
- 1111 = Reserved

bit 3–0 NSEL3: NSEL2: NSEL1: NSEL0: Negative Channel

Select

- 0000 = A<sub>IN</sub>0
- 0001 = A<sub>IN</sub>1 (default)
- 0010 = A<sub>IN</sub>2
- 0011 = A<sub>IN</sub>3
- 0100 = A<sub>IN</sub>4
- 0101 = A<sub>IN</sub>5
- 0110 = A<sub>IN</sub>6
- 0111 = A<sub>IN</sub>7
- 1111 = Reserved

**ACR**

(Address 02<sub>H</sub>) Analog Control Register

Reset Value = X0<sub>H</sub>

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
$\overline{\text{DRDY}}$	U/B	SPEED	BUFEN	BIT ORDER	RANGE	DR1	DR0

bit 7  $\overline{\text{DRDY}}$ : Data Ready (Read Only)  
This bit duplicates the state of the  $\overline{\text{DRDY}}$  pin.

bit 6 U/B: Data Format  
0 = Bipolar (default)  
1 = Unipolar

U/B	ANALOG INPUT	DIGITAL OUTPUT (Hex)
0	+FSR	0x7FFFFFFF
	Zero	0x000000
	–FSR	0x800000
1	+FSR	0xFFFFFFFF
	Zero	0x000000
	–FSR	0x000000

- bit 5      **SPEED:** Modulator Clock Speed  
 0 =  $f_{MOD} = f_{OSC}/128$  (default)  
 1 =  $f_{MOD} = f_{OSC}/256$
- bit 4      **BUFEN:** Buffer Enable  
 0 = Buffer Disabled (default)  
 1 = Buffer Enabled
- bit 3      **BIT ORDER:** Data Output Bit Order  
 0 = Most Significant Bit Transmitted First (default)  
 1 = Least Significant Bit Transmitted First  
 Data is always shifted in or out MSB first.
- bit 2      **RANGE:** Range Select  
 0 = Full-Scale Input Range equal to  $\pm V_{REF}$  (default).  
 1 = Full-Scale Input Range equal to  $\pm 1/2 V_{REF}$   
**NOTE:** This allows reference voltages as high as  $V_{DD}$ , but even with a 5V reference voltage the calibration must be performed with this bit set to 0.
- bit 1–0    **DR1: DR0:** Data Rate  
 ( $f_{OSC} = 2.4576\text{MHz}$ ,  $SPEED = 0$ )  
 00 = 15 Hz (default)  
 01 = 7.5 Hz  
 10 = 3.75 Hz  
 11 = Reserved

## ODAC

(Address 03) Offset DAC

Reset Value = 00<sub>H</sub>

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
SIGN	OSET6	OSET5	OSET4	OSET3	OSET2	OSET1	OSET0

- bit 7      **Sign**  
 0 = Positive  
 1 = Negative

$$\text{Offset} = \frac{V_{REF}}{2 \cdot \text{PGA}} \cdot \left( \frac{\text{OSET}[6:0]}{127} \right) \text{ RANGE} = 0$$

$$\text{Offset} = \frac{V_{REF}}{4 \cdot \text{PGA}} \cdot \left( \frac{\text{OSET}[6:0]}{127} \right) \text{ RANGE} = 1$$

**NOTE:** The offset DAC must be enabled after calibration or the calibration nullifies the effects.

## DIO

(Address 04<sub>H</sub>) Data I/O

Reset Value = 00<sub>H</sub>

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
DIO 7	DIO 6	DIO 5	DIO 4	DIO 3	DIO 2	DIO 1	DIO 0

If the IOCON register is configured for data, a value written to this register appears on the data I/O pins if the pin is configured as an output in the DIR register. Reading this register returns the value of the data I/O pins.

**DIR**

(Address 05<sub>H</sub>) Direction Control for Data I/O

Reset Value = FF<sub>H</sub>

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
DIR7	DIR6	DIR5	DIR4	DIR3	DIR2	DIR1	DIR0

Each bit controls whether the corresponding data I/O pin is an output (= 0) or input (= 1). The default power-up state is as inputs.

**IOCON**

(Address 06<sub>H</sub>) I/O Configuration Register

Reset Value = 00<sub>H</sub>

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
IO7	IO6	IO5	IO4	IO3	IO2	IO1	IO0

bit 7-0 IO7: IO0: Data I/O Configuration

0 = Analog (default)

1 = Data

Configuring the pin as a data I/O pin allows it to be controlled through the DIO and DIR registers.

**ORC0**

(Address 07<sub>H</sub>) Offset Calibration Coefficient

(Least Significant Byte)

Reset Value = 00<sub>H</sub>

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
OCR07	OCR06	OCR05	OCR04	OCR03	OCR02	OCR01	OCR00

**OCR1**

(Address 08<sub>H</sub>) Offset Calibration Coefficient

(Middle Byte)

Reset Value = 00<sub>H</sub>

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
OCR15	OCR14	OCR13	OCR12	OCR11	OCR10	OCR09	OCR08

**OCR2**

(Address 09<sub>H</sub>) Offset Calibration Coefficient

(Most Significant Byte)

Reset Value = 00<sub>H</sub>

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
OCR23	OCR22	OCR21	OCR20	OCR19	OCR18	OCR17	OCR16

**FSR0**

(Address 0A<sub>H</sub>) Full-Scale Register

(Least Significant Byte)

Reset Value = 59<sub>H</sub>

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
FSR07	FSR06	FSR05	FSR04	FSR03	FSR02	FSR01	FSR00

**FSR1**

 (Address 0B<sub>H</sub>) Full-Scale Register

(Middle Byte)

 Reset Value = 55<sub>H</sub>

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
FSR15	FSR14	FSR13	FSR12	FSR11	FSR10	FSR09	FSR08

**FSR2**

 (Address 0C<sub>H</sub>) Full-Scale Register

(Most Significant Byte)

 Reset Value = 55<sub>H</sub>

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
FSR23	FSR22	FSR21	FSR20	FSR19	FSR18	FSR17	FSR16

**DOR2**

 (Address 0D<sub>H</sub>) Data Output Register

(Most Significant Byte) (Read Only)

 Reset Value = 00<sub>H</sub>

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
DOR23	DOR22	DOR21	DOR20	DOR19	DOR18	DOR17	DOR16

**DOR1**

 (Address 0E<sub>H</sub>) Data Output Register

(Middle Byte) (Read Only)

 Reset Value = 00<sub>H</sub>

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
DOR15	DOR14	DOR13	DOR12	DOR11	DOR10	DOR09	DOR08

**DOR0**

 (Address 0F<sub>H</sub>) Data Output Register

(Least Significant Byte) (Read Only)

 Reset Value = 00<sub>H</sub>

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
DOR07	DOR06	DOR05	DOR04	DOR03	DOR02	DOR01	DOR00

**ADS1243 CONTROL COMMAND DEFINITIONS**

The commands listed in Table IV control the operations of ADS1243. Some of the commands are stand-alone commands (for example, RESET) while others require additional bytes (for example, WREG requires the count and data bytes).

Operands:

- n = count (0 to 127)
- r = register (0 to 15)
- x = don't care

**Table 5. Command Summary**

COMMANDS	DESCRIPTION	OP CODE	2nd COMMAND BYTE
	Read Data	0000 0001 (01 <sub>H</sub> )	—
	Read Data Continuously	0000 0011 (03 <sub>H</sub> )	—
	Stop Read Data Continuously	0000 1111 (0F <sub>H</sub> )	—
RDATA RDATAc	Read from REG “rrrr”	0001 r r r r (1x <sub>H</sub> )	xxxx_nnnn (# of regs-1)
STOPC RREG	Write to REG “rrrr”	0101 r r r r (5x <sub>H</sub> )	xxxx_nnnn (# of regs-1)
WREG SELFCAL	Offset and Gain Self Cal	1111 0000 (F0 <sub>H</sub> )	—
SELFOCAL	Self Offset Cal	1111 0001 (F1 <sub>H</sub> )	—
SELFGCAL	Self Gain Cal	1111 0010 (F2 <sub>H</sub> )	—
SYSOCAL	Sys Offset Cal	1111 0011 (F3 <sub>H</sub> )	—
SYSGCAL	Sys Gain Cal	1111 0100 (F4 <sub>H</sub> )	—
WAKEUP	Wakeup from SLEEP Mode	1111 1011 (FB <sub>H</sub> )	—
DSYNC SLEEP	Sync $\overline{\text{DRDY}}$	1111 1100 (FC <sub>H</sub> )	—
RESET	Put in SLEEP Mode	1111 1101 (FD <sub>H</sub> )	—
	Reset to Power-Up Values	1111 1110 (FE <sub>H</sub> )	—

NOTE: The received data format is always MSB first; the data out format is set by the BIT ORDER bit in the ACR register.

**RDATA–Read Data**

**Description:** Read the most recent conversion result from the Data Output Register (DOR). This is a 24-bit value.

**Operands:** None

**Bytes:** 1

**Encoding:** 0000 0001

**Data Transfer Sequence:**



(1) For wait time, refer to timing specification.

**RDATAc–Read Data Continuous**

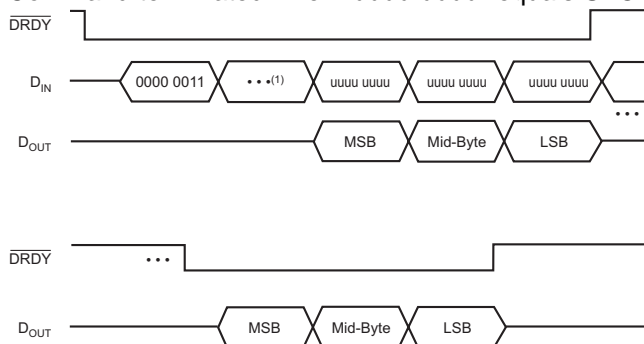
**Description:** Read Data Continuous mode enables the continuous output of new data on each  $\overline{\text{DRDY}}$ . This command eliminates the need to send the Read Data Command on each  $\overline{\text{DRDY}}$ . This mode may be terminated by either the STOPC command or the RESET command. Wait at least 10 f<sub>OSC</sub> after  $\overline{\text{DRDY}}$  falls before reading.

**Operands:** None

**Bytes:** 1

**Encoding:** 0000 0011

**Data Transfer Sequence:** Command terminated when “uuuu uuuu” equals STOPC or RESET.



(1)For wait time, refer to timing specification.

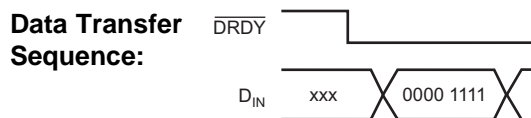
### STOPC–Stop Continuous

**Description:** Ends the continuous data output mode. Issue after  $\overline{DRDY}$  goes LOW.

**Operands:** None

**Bytes:** 1

**Encoding:** 0000 1111



### RREG–Read from Registers

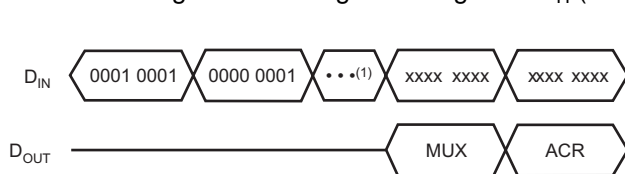
**Description:** Output the data from up to 16 registers starting with the register address specified as part of the instruction. The number of registers read will be one plus the second byte count. If the count exceeds the remaining registers, the addresses wrap back to the beginning.

**Operands:** r, n

**Bytes:** 2

**Encoding:** 0001 rrrr xxxx nnnn

**Data Transfer Sequence:** Read Two Registers Starting from Register 01<sub>H</sub> (MUX)



(1)For wait time, refer to timing specification.

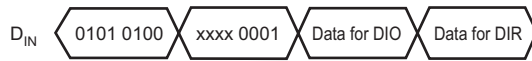
### WREG–Write to Registers

**Description:** Write to the registers starting with the register address specified as part of the instruction. The number of registers that will be written is one plus the value of the second byte.

**Operands:** r, n

**Bytes:** 2

**Encoding:** 0101 rrrr xxxx nnnn  
**Data Transfer Sequence:** Write Two Registers Starting from 04<sub>H</sub> (DIO)



**SELCAL–Offset and Gain Self Calibration**

**Description:** Starts the process of self calibration. The Offset Calibration Register (OCR) and the Full-Scale Register (FSR) are updated with new values after this operation.

**Operands:** None

**Bytes:** 1

**Encoding:** 1111 0000

**Data Transfer Sequence:** 


**SELFOCAL–Offset Self Calibration**

**Description:** Starts the process of self-calibration for offset. The Offset Calibration Register (OCR) is updated after this operation.

**Operands:** None

**Bytes:** 1

**Encoding:** 1111 0001

**Data Transfer Sequence:** 

**SELFGCAL–Gain Self Calibration**

**Description:** Starts the process of self-calibration for gain. The Full-Scale Register (FSR) is updated with new values after this operation.

**Operands:** None

**Bytes:** 1

**Encoding:** 1111 0010

**Data Transfer Sequence:** 

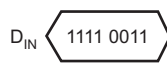
**SYSOCAL–System Offset Calibration**

**Description:** Initiates a system offset calibration. The input should be set to 0V, and the ADS1243 computes the OCR value that compensates for offset errors. The Offset Calibration Register (OCR) is updated after this operation. The user must apply a zero input signal to the appropriate analog inputs. The OCR register is automatically updated afterwards.

**Operands:** None

**Bytes:** 1

**Encoding:** 1111 0011

**Data Transfer Sequence:** 

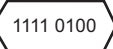
## SYSGCAL–System Gain Calibration

**Description:** Starts the system gain calibration process. For a system gain calibration, the input should be set to the reference voltage and the ADS1243 computes the FSR value that will compensate for gain errors. The FSR is updated after this operation. To initiate a system gain calibration, the user must apply a full-scale input signal to the appropriate analog inputs. FCR register is updated automatically.

**Operands:** None

**Bytes:** 1

**Encoding:** 1111 0100

**Data Transfer Sequence:**  $D_{IN}$  

## WAKEUP

**Description:** Wakes the ADS1243 from SLEEP mode.

**Operands:** None

**Bytes:** 1

**Encoding:** 1111 1011

**Data Transfer Sequence:**  $D_{IN}$  

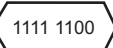
## DSYNC–Sync $\overline{DRDY}$

**Description:** Synchronizes the ADS1243 to an external event.

**Operands:** None

**Bytes:** 1

**Encoding:** 1111 1100

**Data Transfer Sequence:**  $D_{IN}$  

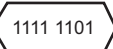
## SLEEP–Sleep Mode

**Description:** Puts the ADS1243 into a low power sleep mode. To exit sleep mode, issue the WAKEUP command.

**Operands:** None

**Bytes:** 1

**Encoding:** 1111 1101

**Data Transfer Sequence:**  $D_{IN}$  

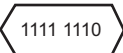
## RESET–Reset to Default Values

**Description:** Restore the registers to their power-up values. This command stops the Read Continuous mode.

**Operands:** None

**Bytes:** 1

**Encoding:** 1111 1110

**Data Transfer Sequence:**  $D_{IN}$  A diagram showing a data transfer sequence. It consists of the label 'D<sub>IN</sub>' followed by a hexagonal shape containing the binary sequence '1111 1110'.

## APPLICATION INFORMATION

### GENERAL-PURPOSE WEIGHT SCALE

Figure 9 shows a typical schematic of a general-purpose weight scale application using the ADS1243. In this example, the internal PGA is set to either 64 or 128 (depending on the maximum output voltage of the load cell) so that the load cell output can be directly applied to the differential inputs of ADS1243.

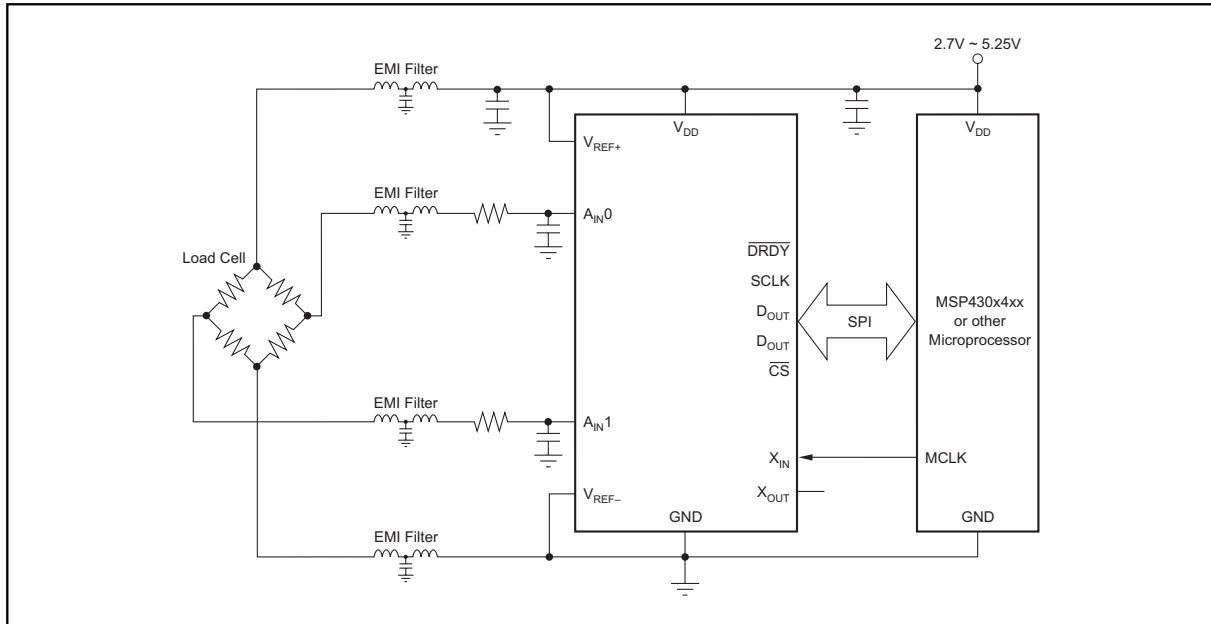


Figure 9. Schematic of a General-Purpose Weight Scale.

### HIGH PRECISION WEIGHT SCALE

Figure 10 shows the typical schematic of a high-precision weight scale application using the ADS1243. The front-end differential amplifier helps maximize the dynamic range.

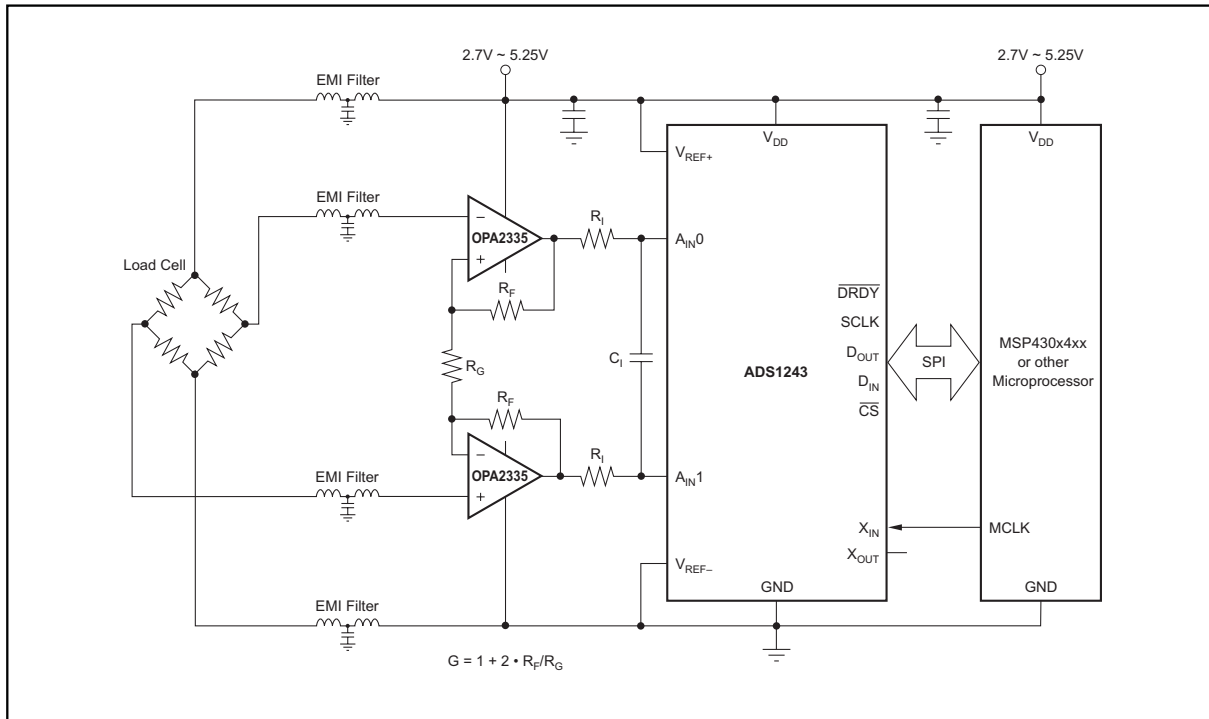


Figure 10. Block Diagram for a High-Precision Weight Scale.

## DEFINITION OF TERMS

An attempt has been made to be consistent with the terminology used in this data sheet. In that regard, the definition of each term is given as follows:

**Analog Input Voltage** – the voltage at any one analog input relative to GND.

**Analog Input Differential Voltage** – given by the following equation: (IN+) – (IN–). Thus, a positive digital output is produced whenever the analog input differential voltage is positive, while a negative digital output is produced whenever the differential is negative.

For example, when the converter is configured with a 2.5-V reference and placed in a gain setting of 1, the positive full-scale output is produced when the analog input differential is 2.5 V. The negative full-scale output is produced when the differential is –2.5 V. In each case, the actual input voltages must remain within the GND to V<sub>DD</sub> range.

**Conversion Cycle** – the term conversion cycle usually refers to a discrete A/D conversion operation, such as that performed by a successive approximation converter. As used here, a conversion cycle refers to the t<sub>DATA</sub> time period.

**Data Rate** – The rate at which conversions are completed. See definition for f<sub>DATA</sub>.

$$f_{\text{DATA}} = \frac{f_{\text{OSC}}}{128 \cdot 2^{\text{SPEED}} \cdot 1280 \cdot 2^{\text{DR}}}$$

SPEED = 0, 1  
DR = 0, 1, 2

f<sub>OSC</sub> – the frequency of the crystal oscillator or CMOS compatible input signal at the X<sub>IN</sub> input of the ADS1243.

f<sub>MOD</sub> – the frequency or speed at which the modulator of the ADS1243 is running. This depends on the SPEED bit as given by the following equation:

	SPEED = 0	SPEED = 1
mfactor	128	256

$$f_{\text{MOD}} = \frac{f_{\text{OSC}}}{\text{mfactor}} = \frac{f_{\text{OSC}}}{128 \cdot 2^{\text{SPEED}}}$$

PGA SETTING	SAMPLING FREQUENCY
1, 2, 4, 8	$f_{\text{SAMP}} = \frac{f_{\text{OSC}}}{\text{mfactor}}$
16	$f_{\text{SAMP}} = \frac{f_{\text{OSC}} \cdot 2}{\text{mfactor}}$
32	$f_{\text{SAMP}} = \frac{f_{\text{OSC}} \cdot 4}{\text{mfactor}}$
64, 128	$f_{\text{SAMP}} = \frac{f_{\text{OSC}} \cdot 8}{\text{mfactor}}$

f<sub>SAMP</sub> – the frequency, or switching speed, of the input sampling capacitor. The value is given by one of the following equations:

f<sub>DATA</sub> – the frequency of the digital output data produced by the ADS1243, f<sub>DATA</sub> is also referred to as the Data Rate.

**Full-Scale Range (FSR)** – as with most A/D converters, the full-scale range of the ADS1243 is defined as the input, that produces the positive full-scale digital output minus the input, that produces the negative full-scale digital output.

For example, when the converter is configured with a 2.5-V reference and is placed in a gain setting of 2, the full-scale range is: [1.25 V (positive full-scale) minus –1.25 V (negative full-scale)] = 2.5 V.

**Least Significant Bit (LSB) Weight** – this is the theoretical amount of voltage that the differential voltage at the analog input has to change in order to observe a change in the output data of one least significant bit. It is computed as follows:

$$\text{LSBWeight} = \frac{\text{Full-Scale Range}}{2^N - 1}$$

where N is the number of bits in the digital output.

t<sub>DATA</sub> – the inverse of f<sub>DATA</sub>, or the period between each data output.

**Table 6. Full-Scale Range versus PGA Setting**

GAIN SETTING	5V SUPPLY ANALOG INPUT <sup>(1)</sup>			GENERAL EQUATIONS		
	FULL-SCALE RANGE	DIFFERENTIAL INPUT VOLTAGES <sup>(2)</sup>	PGA OFFSET RANGE	FULL-SCALE RANGE	DIFFERENTIAL INPUT VOLTAGES <sup>(2)</sup>	PGA SHIFT RANGE
1	5 V	±2.5 V	±1.25 V	RANGE = 0		
2	2.5 V	±1.25 V	±0.625 V	$\frac{V_{REF}}{PGA}$	$\frac{\pm V_{REF}}{2 \cdot PGA}$	$\frac{\pm V_{REF}}{4 \cdot PGA}$
4	1.25 V	±0.625 V	±312.5 mV			
8	0.625 V	±312.5 mV	±156.25 mV	RANGE = 1		
16	312.5 mV	±156.25 mV	±78.125 mV			
32	156.25 mV	±78.125 mV	±39.0625 mV			
64	78.125 mV	±39.0625 mV	±19.531 mV			
128	39.0625 mV	±19.531 mV	±9.766 mV			

(1) With a 2.5-V reference.

(2) Refer to electrical specification for analog input voltage range.

**PACKAGING INFORMATION**

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
ADS1243SJD	Last Time Buy	Production	CDIP SB (JD)   20	19   TUBE	Yes	AU	N/A for Pkg Type	-55 to 210	ADS1243SJD
ADS1243SKGD1	Last Time Buy	Production	XCEPT (KGD)   0	121   TUBE	Yes	Call TI	N/A for Pkg Type	-55 to 210	

(1) **Status:** For more details on status, see our [product life cycle](#).

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "-" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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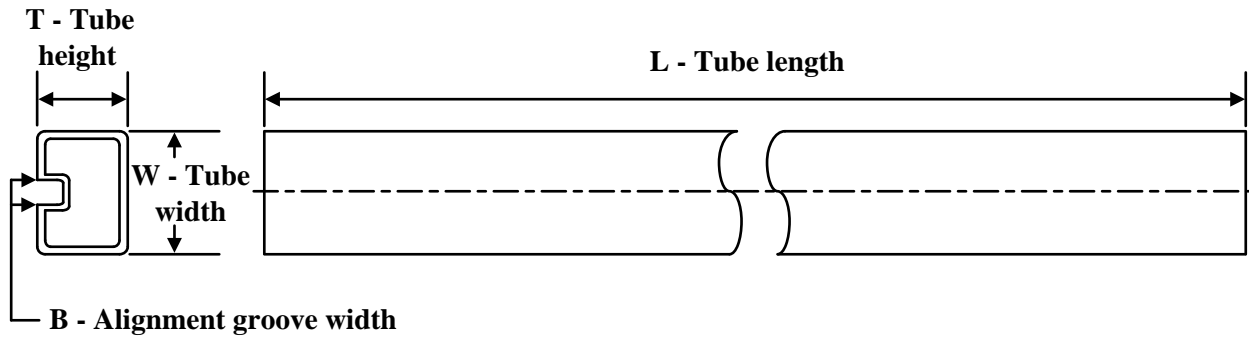
In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

**OTHER QUALIFIED VERSIONS OF ADS1243-HT :**

- Catalog : [ADS1243](#)

NOTE: Qualified Version Definitions:

- Catalog - TI's standard catalog product

**TUBE**


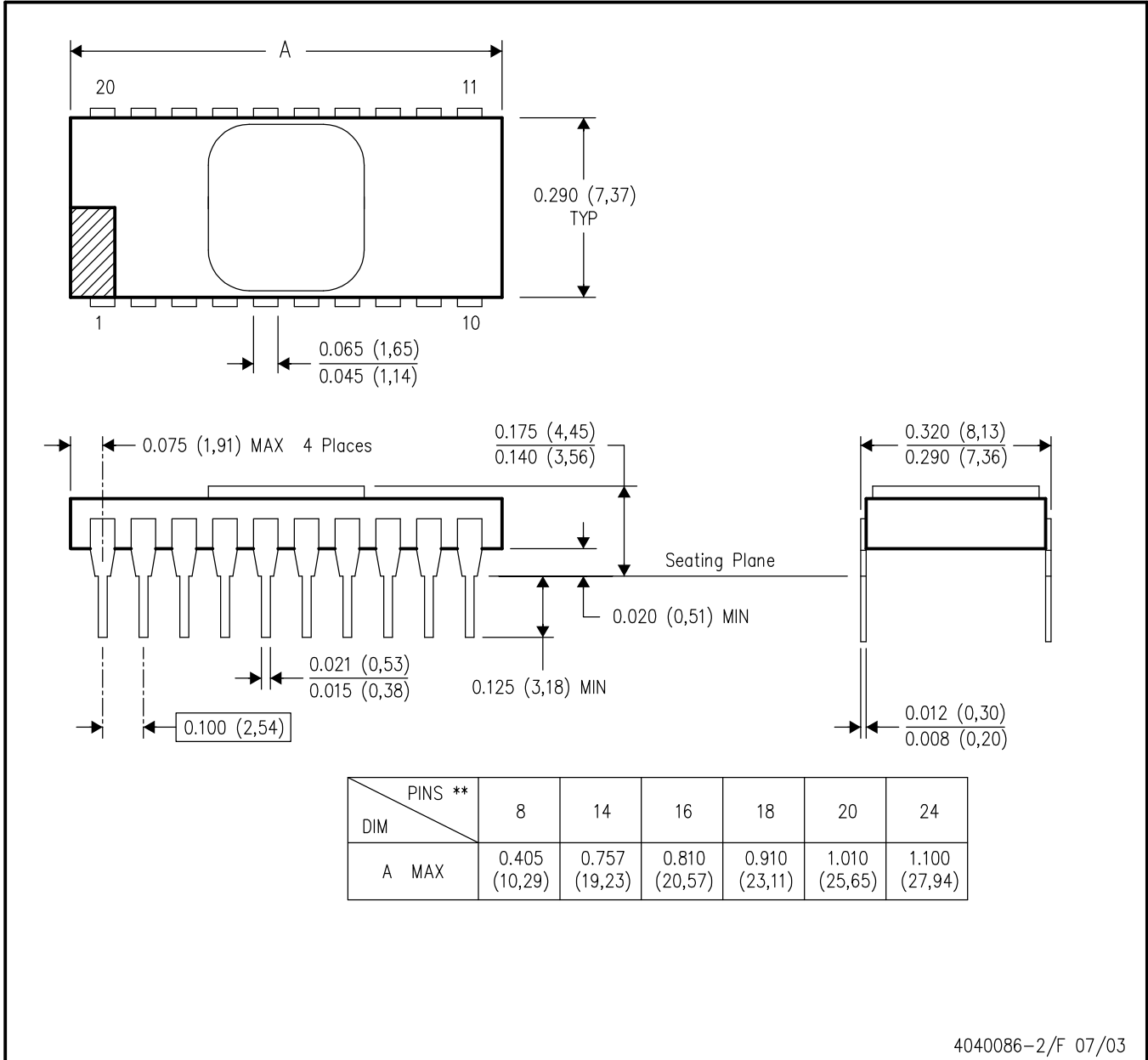
\*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (μm)	B (mm)
ADS1243SJD	JD	CDIP SB	20	19	506.98	15.24	12290	NA

JD (R-CDIP-T\*\*)

CERAMIC SIDE-BRAZE DUAL-IN-LINE PACKAGE

20 PINS SHOWN



4040086-2/F 07/03

- NOTES:
- A. All linear dimensions are in inches (millimeters).
  - B. This drawing is subject to change without notice.
  - C. This package is hermetically sealed with a metal lid.
  - D. The terminals are gold plated.
  - E. Falls within MIL STD 1835 CDIP2 - T8, T14, T16, T18, T20 and T24 respectively.

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