

# ADS7052 14 位, 1 MSPS, 单端输入, 小型低功耗 SAR ADC

## 1 特性

- 1 MSPS 吞吐量
- 封装尺寸小:
  - X2QFN-8 封装 (1.5mm × 1.5mm)
- 单极输入范围: 0V 至 AVDD
- 宽工作电压范围:
  - AVDD: 1.65V 至 3.6V
  - DVDD: 1.65V 至 3.6V (与 AVDD 无关)
  - 温度范围: -40°C 至 +125°C
- 性能优异:
  - 14 位 NMC DNL,  $\pm 2$ -LSB INL
  - 74.5dB SINAD (2kHz 时)
  - 72.5dB SINAD (200kHz 时)
- 低功耗:
  - 1.5mW (1 MSPS, 3.3V AVDD 时)
  - 160 $\mu$ W (100kSPS, 3.3V AVDD 时)
  - 40 $\mu$ W (100kSPS, 1.8V AVDD 时)
- 集成失调电压校准
- 与 SPI 兼容的串行接口: 24MHz
- 符合 JESD8-7A 标准的数字 I/O

## 2 应用

- 光学编码器
- 声纳接收器
- 探鱼器
- I/Q 解调器
- 光线路卡和模块
- 热成像摄像机
- 超声波流量计
- 手持无线电

## 3 说明

ADS7052 器件属于引脚对引脚兼容的高速低功耗、单通道逐次逼近型寄存器 (SAR) 类型的模数转换器 (ADC) 系列。该器件系列包含多个分辨率、吞吐量和模拟输入型号 (有关器件列表, 请参阅 [表格1](#))。

ADS7052 是一款 14 位 1 MSPS SAR ADC, 支持 0V 到 AVDD 范围内的单端输入, AVDD 的范围为 1.65V 至 3.6V。

内部失调电压校准功能在整个 AVDD 和工作温度范围内可保持优异的失调电压规格。

该器件支持由  $\overline{CS}$  和 SCLK 信号控制的兼容 SPI 的串行接口。输入信号通过  $\overline{CS}$  下降沿进行采样, 而 SCLK 用于转换和串行数据输出。该器件支持宽数字电源范围 (1.65V 至 3.6V), 可直接连接到各种主机控制器。

ADS7052 的标称 DVDD 范围 (1.65V 至 1.95V) 符合 JESD8-7A 标准。

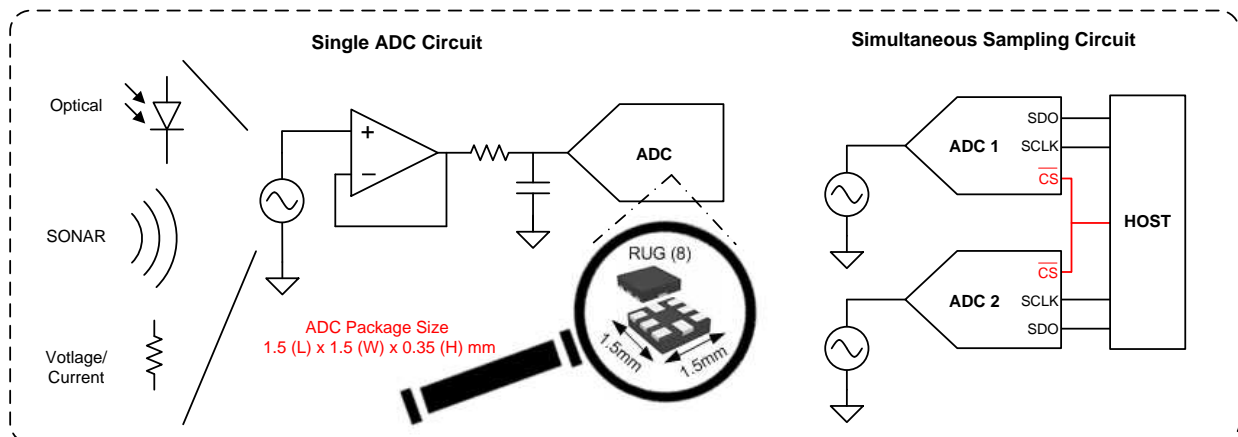
ADS7052 采用 8 引脚小型 X2QFN 封装, 可以在广泛的工业温度范围 (-40°C 至 +125°C) 内正常工作。该器件体积小, 功耗极低, 非常适合需要高速高分辨率数据采集的空间受限型 电池供电 应用。

器件信息<sup>(1)</sup>

部件名称	封装	封装尺寸 (标称值)
ADS7052	X2QFN (8)	1.50mm x 1.50mm

(1) 如需了解所有可用封装, 请参阅数据表末尾的可订购产品附录。

## 典型应用



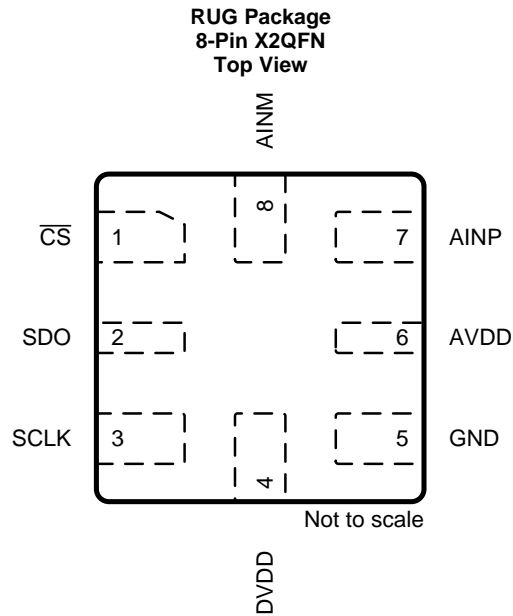
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## 4 修订历史记录

日期	修订版本	说明
2017 年 12 月	*	初始发行版

## 5 Pin Configuration and Functions



### Pin Functions

PIN		I/O	DESCRIPTION
NO.	NAME		
1	$\overline{\text{CS}}$	Digital input	Chip-select signal, active low
2	SDO	Digital output	Serial data out
3	SCLK	Digital input	Serial clock
4	DVDD	Supply	Digital I/O supply voltage
5	GND	Supply	Ground for power supply, all analog and digital signals are referred to this pin
6	AVDD	Supply	Analog power-supply input, also provides the reference voltage to the ADC
7	AINP	Analog input	Analog signal input, positive
8	AINM	Analog input	Analog signal input, negative

## 6 Specifications

### 6.1 Absolute Maximum Ratings<sup>(1)</sup>

	MIN	MAX	UNIT
AVDD to GND	−0.3	3.9	V
DVDD to GND	−0.3	3.9	V
AINP to GND	−0.3	AVDD + 0.3	V
AINM to GND	−0.3	0.3	V
Input current to any pin except supply pins	−10	10	mA
Digital input voltage to GND	−0.3	DVDD + 0.3	V
Storage temperature, T <sub>stg</sub>	−60	150	°C

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### 6.2 ESD Ratings

		VALUE	UNIT
V <sub>(ESD)</sub>	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±2000
		Charged device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±1000
			V

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
AVDD	Analog supply voltage range	1.65	3.3	3.6	V
DVDD	Digital supply voltage range	1.65	1.8	3.6	V
T <sub>A</sub>	Operating free-air temperature	−40	25	125	°C

### 6.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		ADS7052	UNIT
		RUG (X2QFN)	
		8 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	177.5	°C/W
R <sub>θJC(top)</sub>	Junction-to-case (top) thermal resistance	51.5	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	76.7	°C/W
Ψ <sub>JT</sub>	Junction-to-top characterization parameter	1	°C/W
Ψ <sub>JB</sub>	Junction-to-board characterization parameter	76.7	°C/W
R <sub>θJC(bot)</sub>	Junction-to-case (bottom) thermal resistance	N/A	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

## 6.5 Electrical Characteristics

at  $V_{DD} = 3.3\text{ V}$ ,  $DVDD = 1.65\text{ V to }3.6\text{ V}$ ,  $f_{\text{sample}} = 1\text{ MSPS}$ , and  $V_{\text{AINM}} = 0\text{ V}$  (unless otherwise noted); minimum and maximum values for  $T_A = -40^\circ\text{C to }+125^\circ\text{C}$ ; typical values at  $T_A = 25^\circ\text{C}$

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT		
<b>ANALOG INPUT</b>							
Full-scale input voltage span <sup>(1)</sup>		0		AVDD	V		
Absolute input voltage range	AINP to GND	-0.1		AVDD + 0.1	V		
	AINM to GND	-0.1		0.1			
$C_S$	Sampling capacitance		16		pF		
<b>SYSTEM PERFORMANCE</b>							
Resolution			14		Bits		
NMC	No missing codes	14			Bits		
INL <sup>(2)</sup>	Integral nonlinearity	-3.75	±2	3.75	LSB <sup>(3)</sup>		
DNL	Differential nonlinearity	-0.99	±0.5	1	LSB		
$E_O$ <sup>(2)</sup>	Offset error	After calibration <sup>(4)</sup>		-6	±1	6	LSB
$dV_{OS}/dT$	Offset error drift with temperature		1.75			ppm/°C	
$E_G$ <sup>(2)</sup>	Gain error	-0.1	±0.01	0.1		%FS	
	Gain error drift with temperature		0.5			ppm/°C	
<b>SAMPLING DYNAMICS</b>							
$t_{\text{CONV}}$	Conversion time		$18 \times t_{\text{SCLK}}$			ns	
$t_{\text{ACQ}}$	Acquisition time	230				ns	
$f_{\text{SAMPLE}}$	Maximum throughput rate	24-MHz SCLK, AVDD = 1.65 V to 3.6 V			1	MHz	
	Aperture delay		3			ns	
	Aperture jitter, RMS		12			ps	
<b>DYNAMIC CHARACTERISTICS</b>							
SNR	Signal-to-noise ratio <sup>(5)</sup>	AVDD = 3.3 V, $f_{\text{IN}} = 2\text{ kHz}$	71.5	74.9		dB	
		AVDD = 2.5 V, $f_{\text{IN}} = 2\text{ kHz}$		73.7			
THD	Total harmonic distortion <sup>(5)(6)</sup>	$f_{\text{IN}} = 2\text{ kHz}$		-92		dB	
		$f_{\text{IN}} = 100\text{ kHz}$		-90			
		$f_{\text{IN}} = 200\text{ kHz}$		-87			
SINAD	Signal-to-noise and distortion <sup>(5)</sup>	$f_{\text{IN}} = 2\text{ kHz}$	71.5	74.8		dB	
		$f_{\text{IN}} = 100\text{ kHz}$		74.7			
		$f_{\text{IN}} = 200\text{ kHz}$		74.5			
SFDR	Spurious-free dynamic range <sup>(5)</sup>	$f_{\text{IN}} = 2\text{ kHz}$		89.8		dB	
		$f_{\text{IN}} = 100\text{ kHz}$		91			
		$f_{\text{IN}} = 200\text{ kHz}$		87			
$BW_{(fp)}$	Full-power bandwidth	At -3 dB		200		MHz	

(1) Ideal input span; does not include gain or offset error.

(2) See Figure 31, Figure 29, and Figure 30 for statistical distribution data for INL, offset error, and gain error.

(3) LSB means least significant bit.

(4) See the *OFFCAL State* section for details.

(5) All specifications expressed in decibels (dB) refer to the full-scale input (FSR) and are tested with an input signal 0.5 dB below full-scale, unless otherwise noted.

(6) Calculated on the first nine harmonics of the input frequency.

## Electrical Characteristics (continued)

at AVDD = 3.3 V, DVDD = 1.65 V to 3.6 V,  $f_{\text{sample}} = 1$  MSPS, and  $V_{\text{AINM}} = 0$  V (unless otherwise noted); minimum and maximum values for  $T_A = -40^\circ\text{C}$  to  $+125^\circ\text{C}$ ; typical values at  $T_A = 25^\circ\text{C}$

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>DIGITAL INPUT/OUTPUT (CMOS Logic Family)</b>						
$V_{\text{IH}}$	High-level input voltage <sup>(7)</sup>		0.65 DVDD		DVDD + 0.3	V
$V_{\text{IL}}$	Low-level input voltage <sup>(7)</sup>		-0.3		0.35 DVDD	V
$V_{\text{OH}}$	High-level output voltage <sup>(7)</sup>	At $I_{\text{source}} = 500 \mu\text{A}$		0.8 DVDD	DVDD	V
		At $I_{\text{source}} = 2 \text{ mA}$		DVDD - 0.45	DVDD	
$V_{\text{OL}}$	Low-level output voltage <sup>(7)</sup>	At $I_{\text{sink}} = 500 \mu\text{A}$		0	0.2 DVDD	V
		At $I_{\text{sink}} = 2 \text{ mA}$		0	0.45	
<b>POWER-SUPPLY REQUIREMENTS</b>						
AVDD	Analog supply voltage		1.65	3	3.6	V
DVDD	Digital I/O supply voltage		1.65	3	3.6	V
$I_{\text{AVDD}}$	Analog supply current	AVDD = 3.3 V, $f_{\text{SAMPLE}} = 1$ MSPS		450	500	$\mu\text{A}$
		AVDD = 3.3 V, $f_{\text{SAMPLE}} = 100$ kSPS		46	50	
		AVDD = 3.3 V, $f_{\text{SAMPLE}} = 10$ kSPS		5		
		AVDD = 1.8 V, $f_{\text{SAMPLE}} = 1$ MSPS		230		
		Static current with $\overline{\text{CS}}$ and SCLK high		0.02		
$I_{\text{DVDD}}$	Digital supply current	DVDD = 1.8 V, CS $\overline{\text{DO}} = 20$ pF, output code = 2AAAh <sup>(8)</sup>		250		$\mu\text{A}$
		DVDD = 1.8 V, static current with $\overline{\text{CS}}$ and SCLK high		0.01		

(7) Digital voltage levels comply with the JESD8-7A standard for DVDD from 1.65 V to 1.95 V; see the [Parameter Measurement Information](#) section for details.

(8) See the [Estimating Digital Power Consumption](#) section for details.

## 6.6 Timing Requirements

all specifications are at AVDD = 1.65 V to 3.6 V, DVDD = 1.65 V to 3.6 V, and C<sub>LOAD-SDO</sub> = 20 pF (unless otherwise noted); minimum and maximum values for T<sub>A</sub> = -40°C to +125°C; typical values at T<sub>A</sub> = 25°C

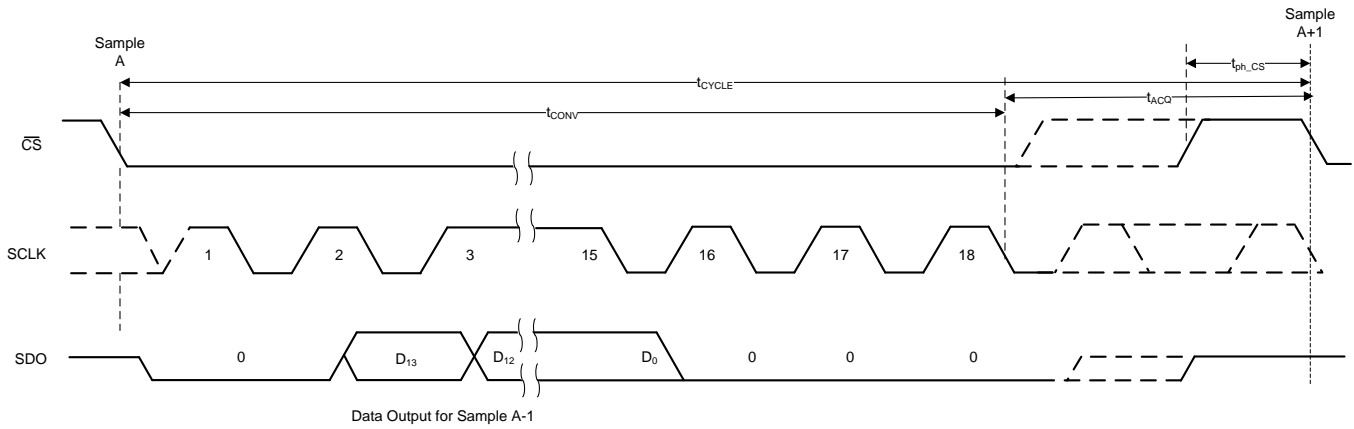
		MIN	TYP	MAX	UNIT
t <sub>CLK</sub>	Time period of SCLK	41.66			ns
t <sub>su_CSCK</sub>	Setup time: $\overline{CS}$ falling edge to SCLK falling edge	7			ns
t <sub>ht_CKCS</sub>	Hold time: SCLK rising edge to $\overline{CS}$ rising edge	8			ns
t <sub>ph_CK</sub>	SCLK high time	0.45		0.55	t <sub>SCLK</sub>
t <sub>pl_CK</sub>	SCLK low time	0.45		0.55	t <sub>SCLK</sub>
t <sub>ph_CS</sub>	$\overline{CS}$ high time	15			ns

## 6.7 Switching Characteristics

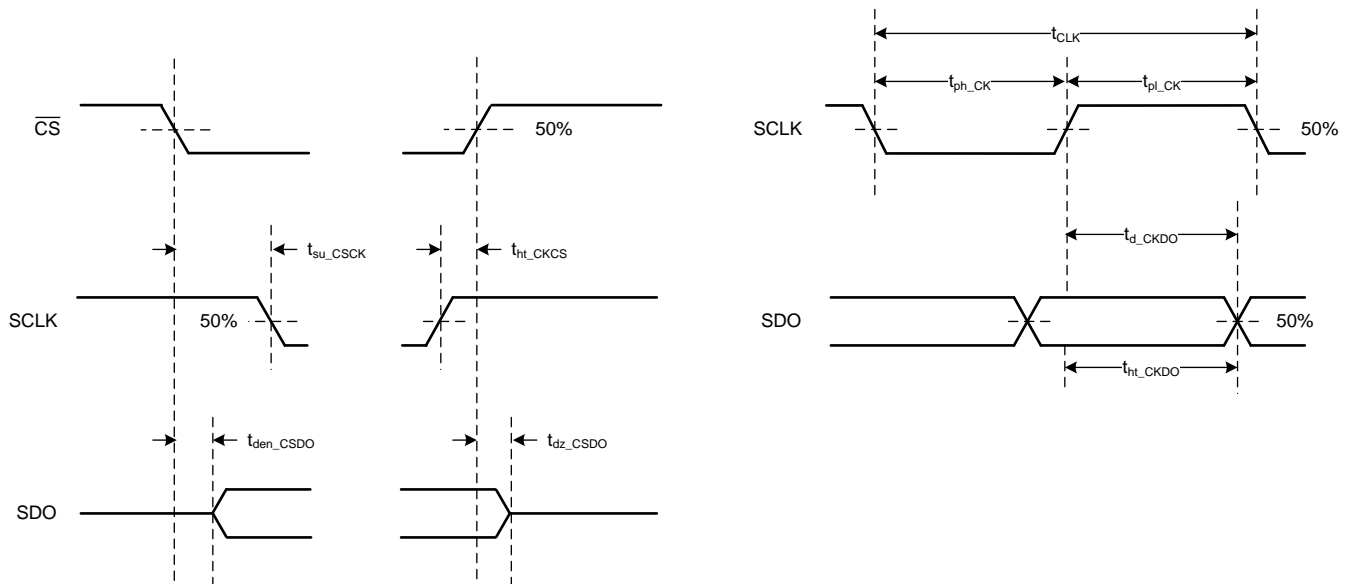
all specifications are at AVDD = 1.65 V to 3.6 V, DVDD = 1.65 V to 3.6 V, and C<sub>LOAD-SDO</sub> = 20 pF (unless otherwise noted); minimum and maximum values for T<sub>A</sub> = -40°C to +125°C; typical values at T<sub>A</sub> = 25°C

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t <sub>CYCLE</sub> <sup>(1)</sup>	Cycle time	1000			ns
t <sub>CONV</sub>	Conversion time		18 × t <sub>SCLK</sub>		ns
t <sub>den_CSDO</sub>	Delay time: $\overline{CS}$ falling edge to data enable			6.5	ns
t <sub>d_CKDO</sub>	Delay time: SCLK rising edge to (next) data valid on SDO			10	ns
t <sub>ht_CKDO</sub>	SCLK rising edge to current data invalid	2.5			ns
t <sub>dz_CSDO</sub>	Delay time: $\overline{CS}$ rising edge to SDO going to tri-state	5.5			ns

(1) t<sub>CYCLE</sub> = 1 / f<sub>SAMPLE</sub>.



**Figure 1. Serial Transfer Frame**



**Figure 2. Timing Specifications**



### 6.8 Typical Characteristics

at  $T_A = 25^\circ\text{C}$ ,  $AVDD = 3.3\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $f_{IN} = 2\text{ kHz}$ , and  $f_{\text{sample}} = 1\text{ MSPS}$  (unless otherwise noted)

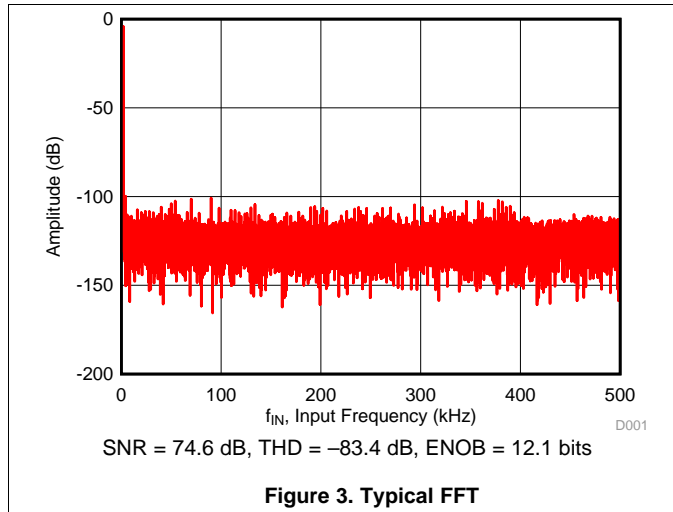


Figure 3. Typical FFT

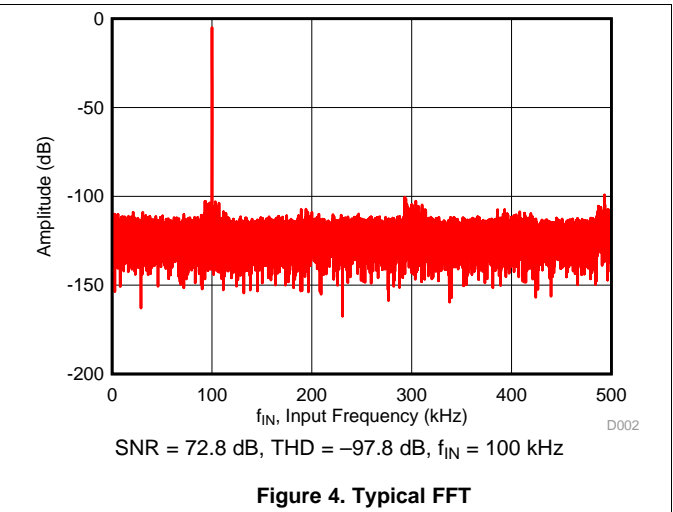


Figure 4. Typical FFT

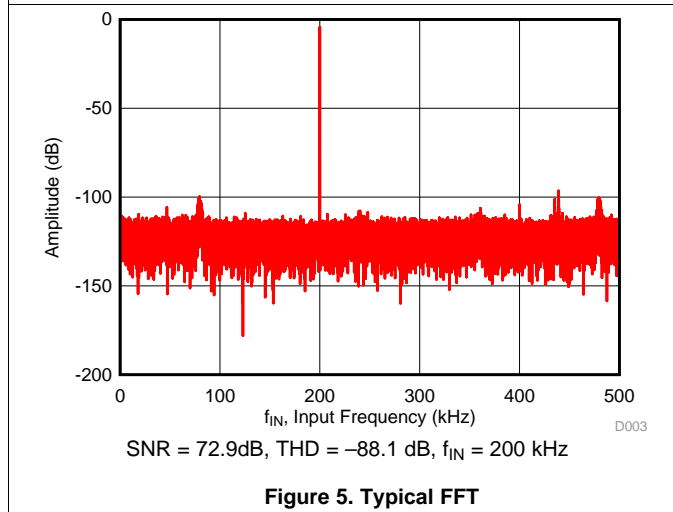


Figure 5. Typical FFT

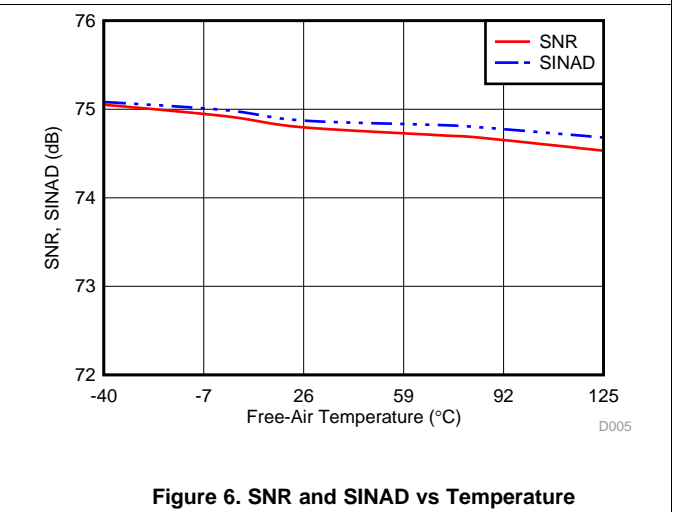


Figure 6. SNR and SINAD vs Temperature

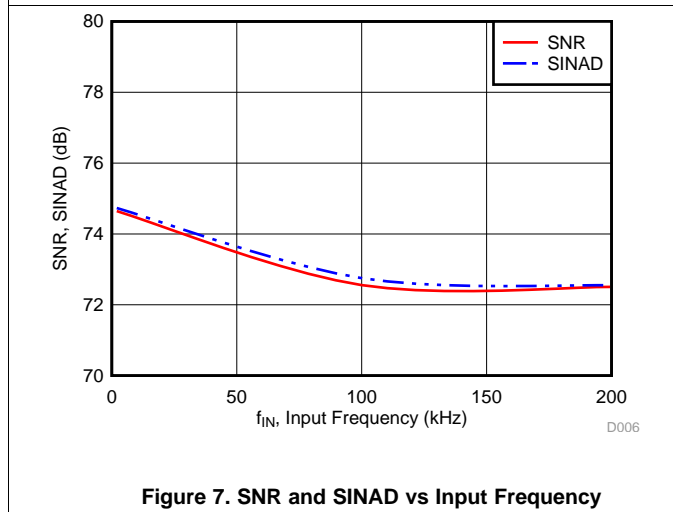


Figure 7. SNR and SINAD vs Input Frequency

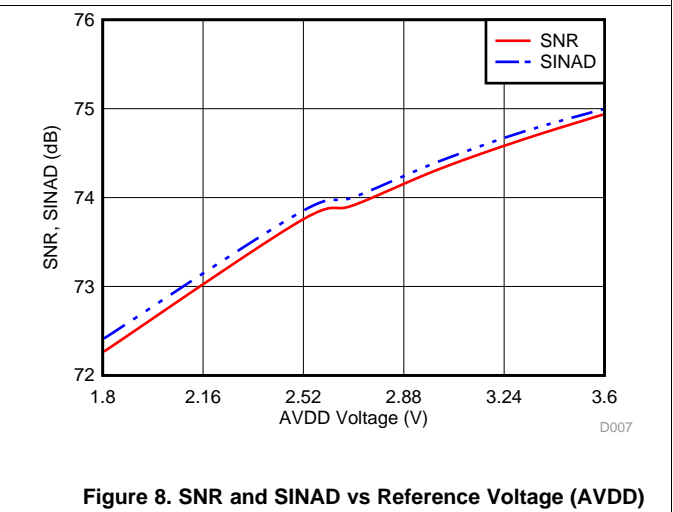


Figure 8. SNR and SINAD vs Reference Voltage (AVDD)

Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $AVDD = 3.3\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $f_{IN} = 2\text{ kHz}$ , and  $f_{\text{sample}} = 1\text{ MSPS}$  (unless otherwise noted)

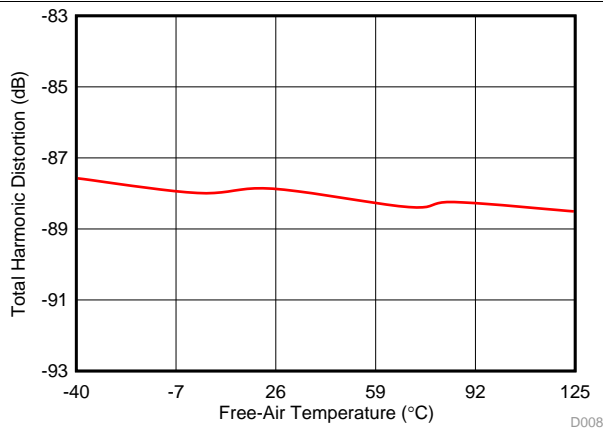


Figure 9. THD vs Temperature

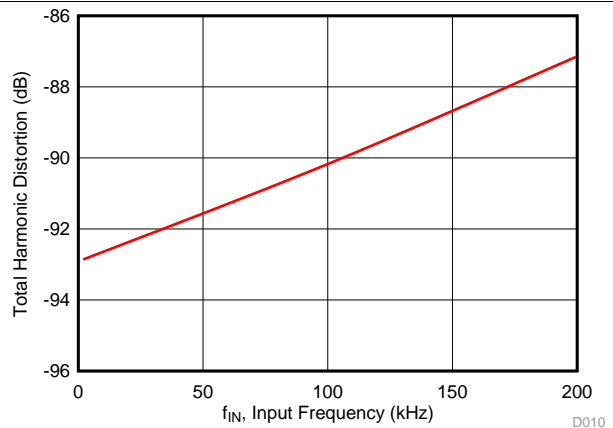


Figure 10. THD vs Input Frequency

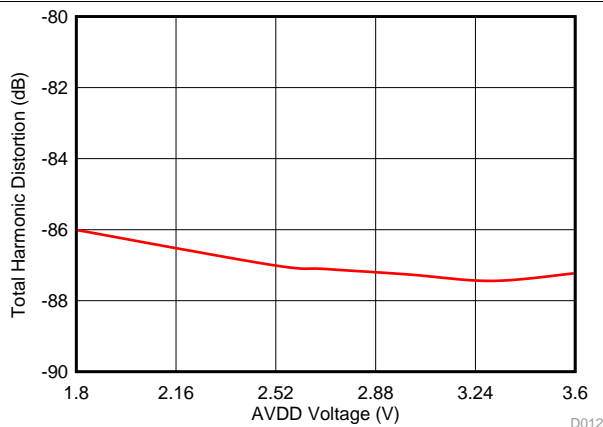


Figure 11. THD vs Reference Voltage (AVDD)

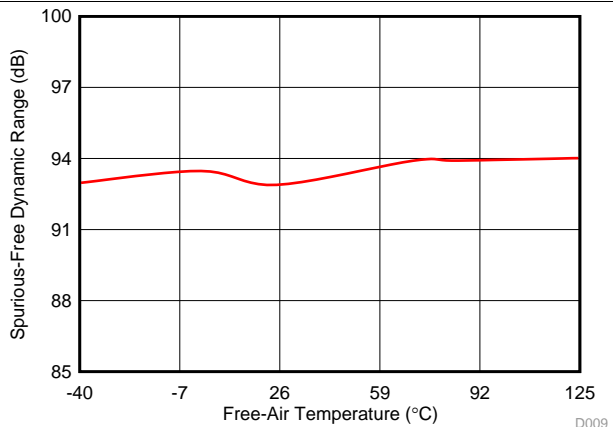


Figure 12. SFDR vs Temperature

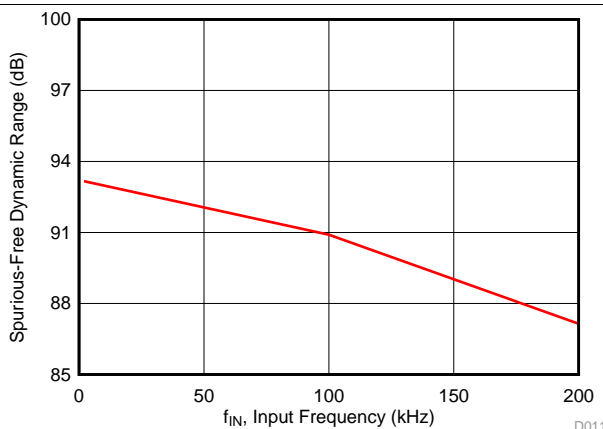


Figure 13. SFDR vs Input Frequency

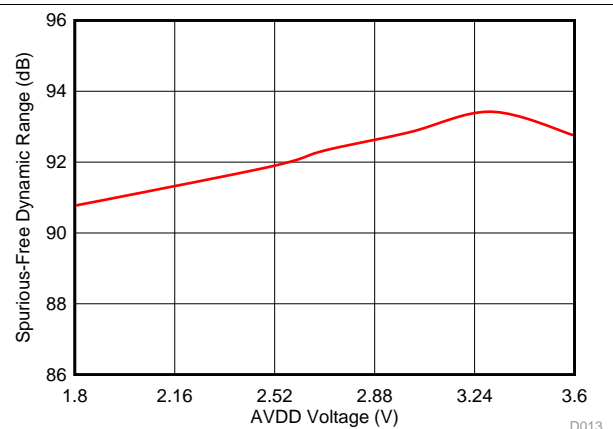
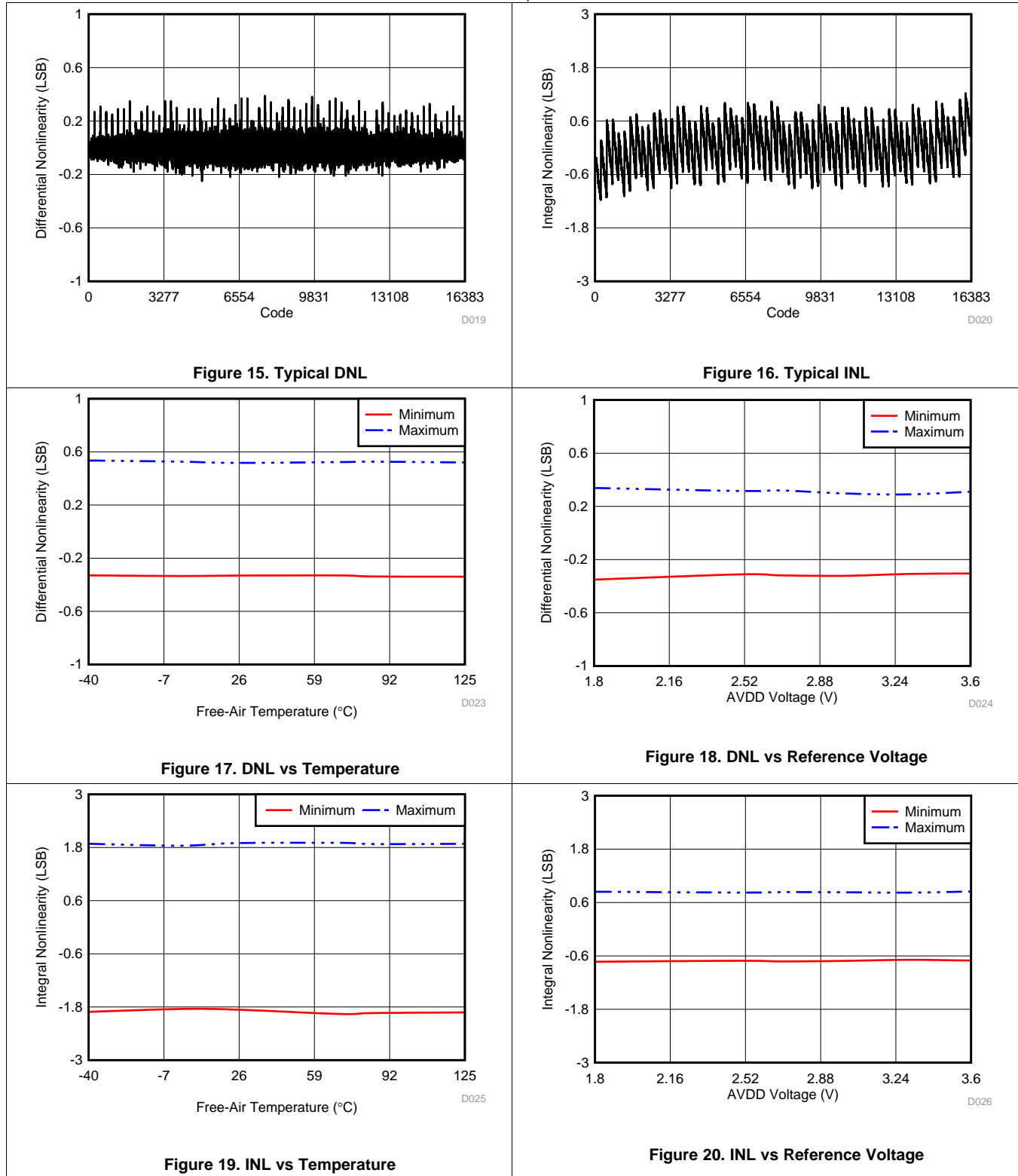


Figure 14. SFDR vs Reference Voltage (AVDD)

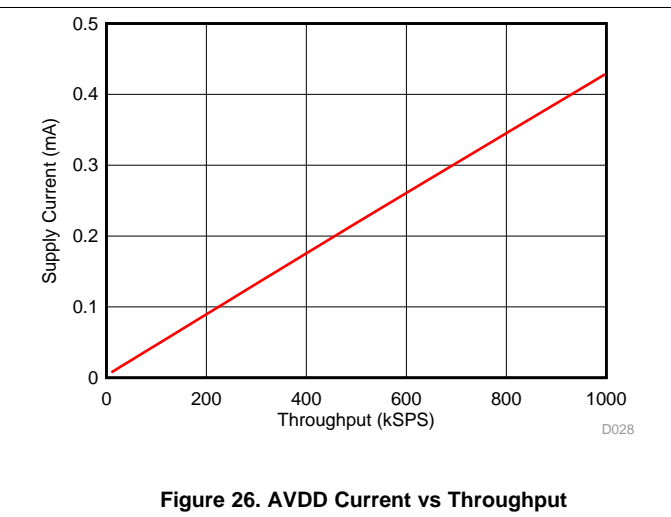
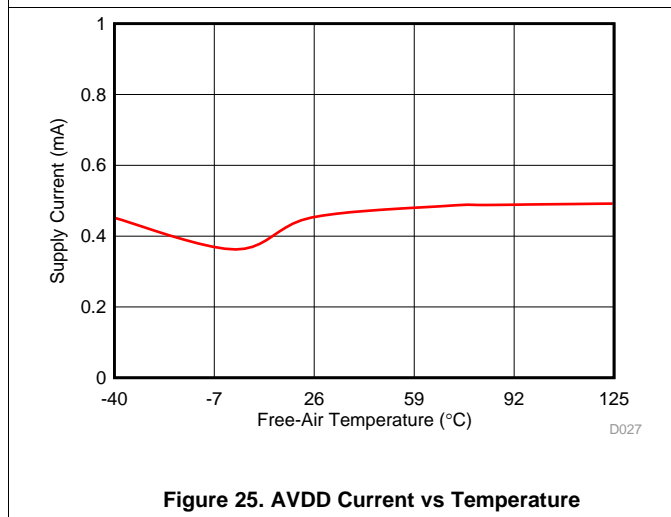
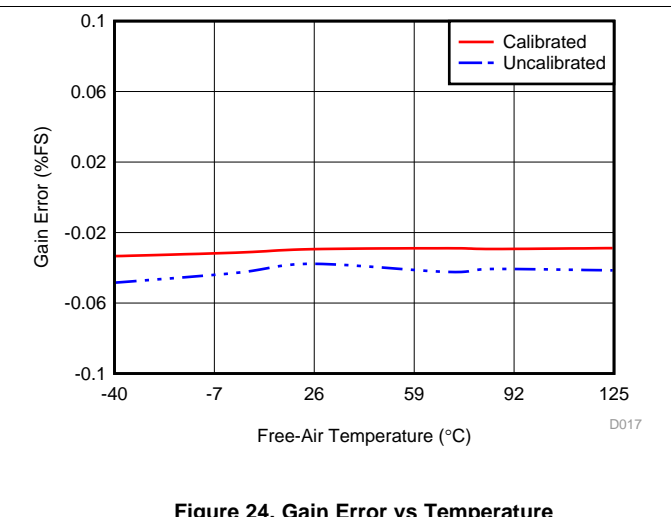
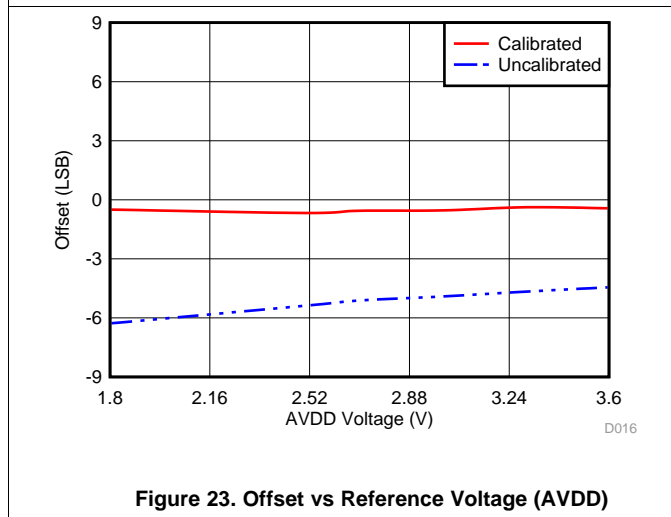
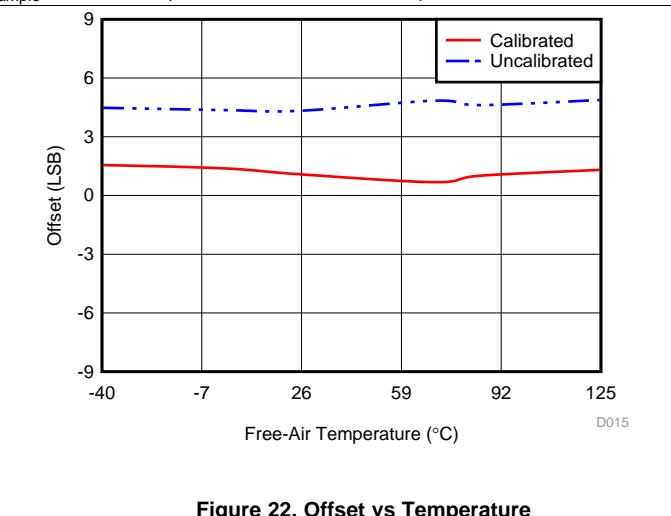
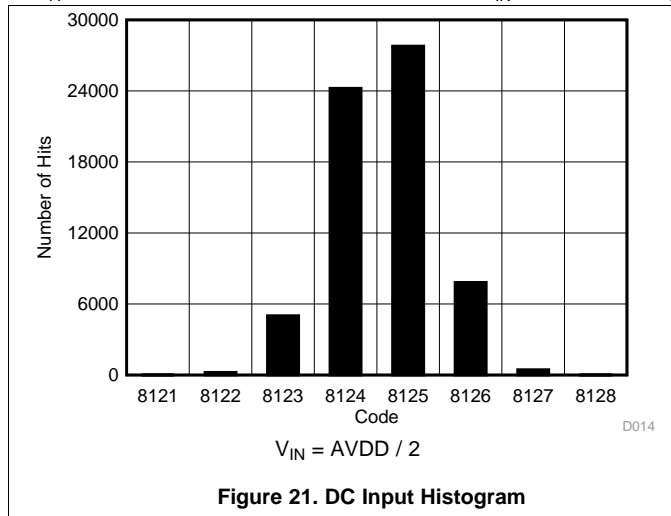
Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $AVDD = 3.3\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $f_{IN} = 2\text{ kHz}$ , and  $f_{sample} = 1\text{ MSPS}$  (unless otherwise noted)



Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $AVDD = 3.3\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $f_{IN} = 2\text{ kHz}$ , and  $f_{sample} = 1\text{ MSPS}$  (unless otherwise noted)



Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $AVDD = 3.3\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $f_{IN} = 2\text{ kHz}$ , and  $f_{sample} = 1\text{ MSPS}$  (unless otherwise noted)

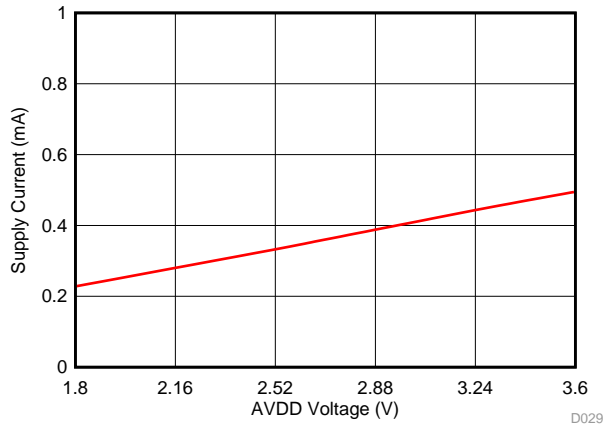


Figure 27. AVDD Current vs AVDD Voltage

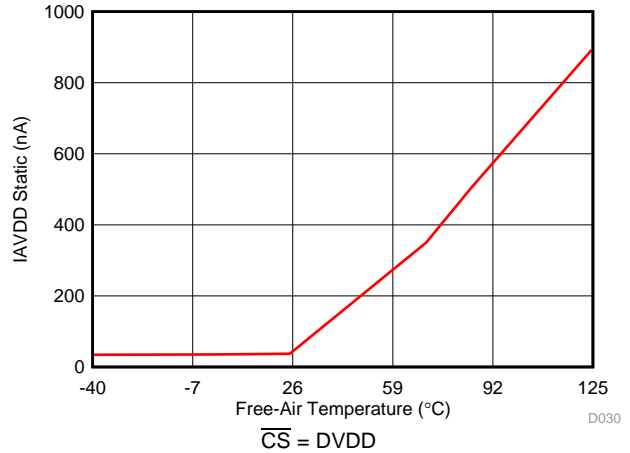


Figure 28. Static AVDD Current vs Temperature

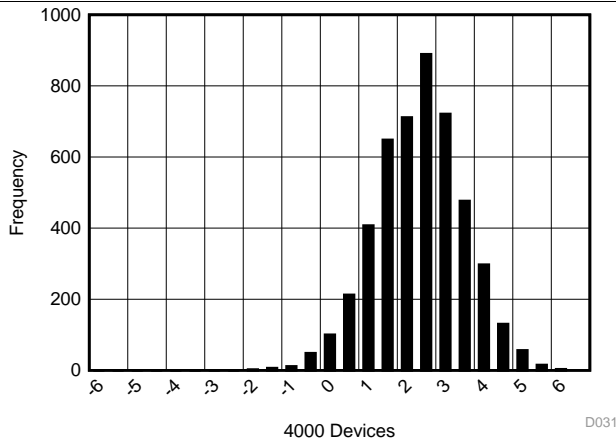


Figure 29. Typical Offset Error Distribution

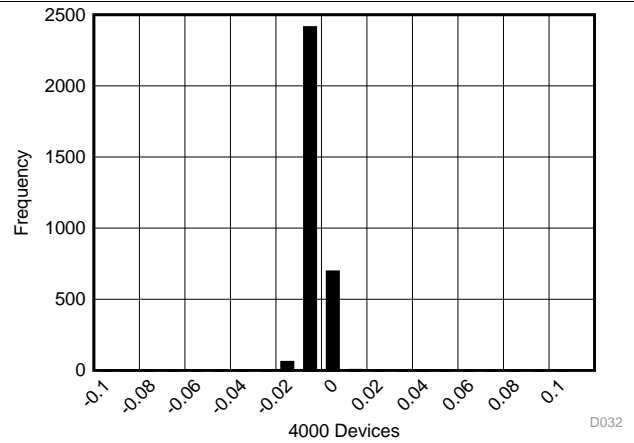


Figure 30. Typical Gain Error Distribution

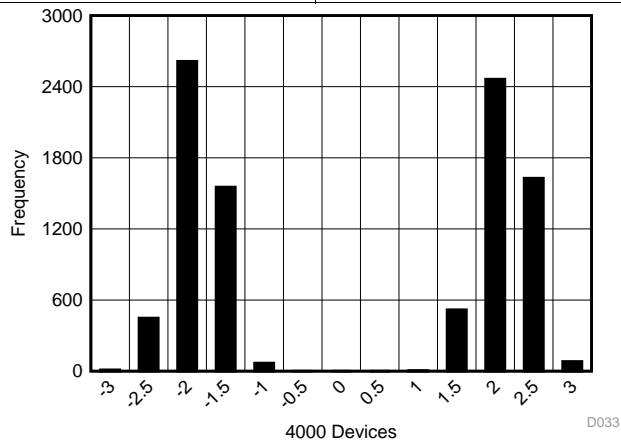
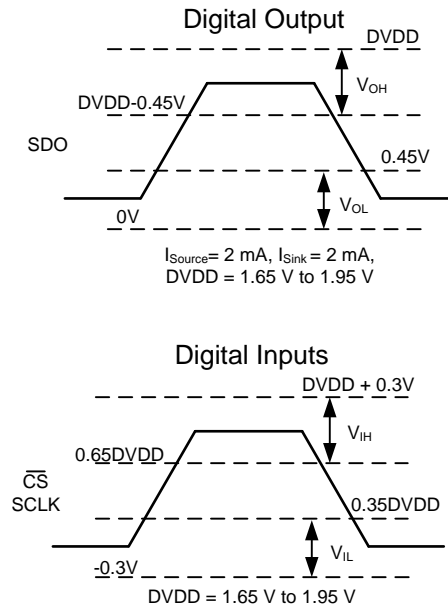


Figure 31. Typical INL Distribution

## 7 Parameter Measurement Information

### 7.1 Digital Voltage Levels

The device complies with the JESD8-7A standard for DVDD from 1.65 V to 1.95 V. Figure 32 shows voltage levels for the digital input and output pins.



**Figure 32. Digital Voltage Levels as per the JESD8-7A Standard**

## 8 Detailed Description

### 8.1 Overview

The ADS7052 device belongs to a family of pin-to-pin compatible, high-speed, low-power, single-channel successive-approximation register (SAR) type analog-to-digital converters (ADCs). The device family includes multiple resolutions, throughputs, and analog input variants (see [Table 1](#) for a list of devices).

The ADS7052 is a 14-bit, 1-MSPS SAR ADC that supports a single-ended input in the range of 0 V to AVDD, for AVDD in the range of 1.65 V to 3.6 V (see the [Analog Input](#) section for details on the analog input pins).

The internal offset calibration feature (see the [OFFCAL State](#) section) maintains excellent offset specifications over the entire AVDD and temperature operating range.

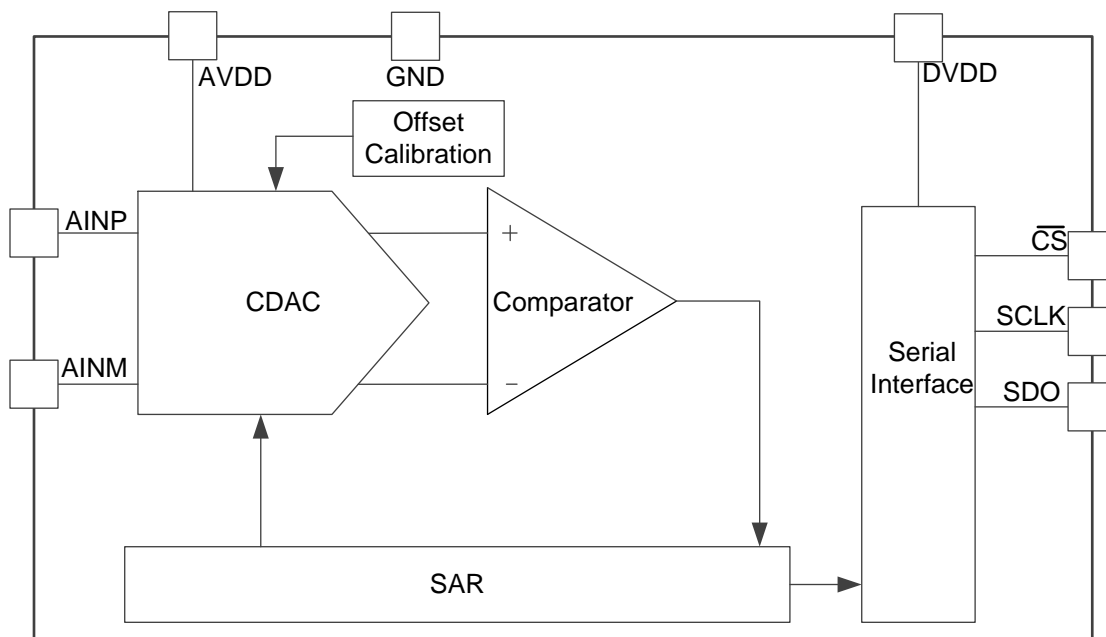
The device supports an SPI-compatible serial interface that is controlled by the  $\overline{CS}$  and SCLK signals. The input signal is sampled with the  $\overline{CS}$  falling edge and SCLK is used for both, conversion and serial data output (see the [Device Functional Modes](#) section, [Timing Requirements](#) table, and [Switching Characteristics](#) table).

The device supports a wide digital supply range (1.65 V to 3.6 V), enabling direct interfacing to a variety of host controllers. The ADS7052 complies with the JESD8-7A standard (see the [Digital Voltage Levels](#) section) for a normal DVDD range (1.65 V to 1.95 V).

The ADS7052 is available in an 8-pin, small, X2QFN package (see the [机械、封装和可订购信息](#) section for more details) and is specified over the extended industrial temperature range (–40°C to +125°C).

The small form-factor and extremely-low power consumption make this device suitable for space-constrained and battery-powered applications that require high-speed, high-resolution data acquisition (see the [Application Information](#) section).

### 8.2 Functional Block Diagram



## 8.3 Feature Description

### 8.3.1 Product Family

The devices listed in [Table 1](#) are all part of the same pin-to-pin compatible, high-speed, low-power, single-channel SAR ADC family. This device family includes multiple different ADC resolutions, throughputs, and analog input types to allow for greater flexibility in the end system. Devices in the same package are pin-compatible to offer a scalable family of devices for varying levels of end-system performance. The ADCs with device numbers ending in -Q1 are also AEC-Q100 qualified for automotive applications.

**Table 1. Device Family Comparison**

DEVICE NUMBER	RESOLUTION (Bits)	THROUGHPUT (MSPS)	INPUT TYPE	PACKAGES <sup>(1)</sup>
<a href="#">ADS7040</a>	8	1	Single-ended	X2QFN (8): 1.5 mm × 1.5 mm VSSOP (8): 2.0 mm × 3.1 mm
<a href="#">ADS7041</a>	10	1	Single-ended	X2QFN (8): 1.5 mm × 1.5 mm VSSOP (8): 2.0 mm × 3.1 mm
<a href="#">ADS7042</a>	12	1	Single-ended	X2QFN (8): 1.5 mm × 1.5 mm VSSOP (8): 2.0 mm × 3.1 mm
<a href="#">ADS7043</a>	12	1	Pseudo-differential	X2QFN (8): 1.5 mm × 1.5 mm VSSOP (8): 2.0 mm × 3.1 mm
<a href="#">ADS7044</a>	12	1	Fully-differential	X2QFN (8): 1.5 mm × 1.5 mm VSSOP (8): 2.0 mm × 3.1 mm
<a href="#">ADS7029-Q1</a>	8	2	Single-ended	VSSOP (8): 2.0 mm × 3.1 mm
<a href="#">ADS7039-Q1</a>	10	2	Single-ended	VSSOP (8): 2.0 mm × 3.1 mm
<a href="#">ADS7049-Q1</a>	12	2	Single-ended	VSSOP (8): 2.0 mm × 3.1 mm
<a href="#">ADS7046</a>	12	3	Single-ended	X2QFN (8): 1.5 mm × 1.5 mm
<a href="#">ADS7047</a>	12	3	Fully-differential	X2QFN (8): 1.5 mm × 1.5 mm
<a href="#">ADS7052</a>	14	1	Single-ended	X2QFN (8): 1.5 mm × 1.5 mm
<a href="#">ADS7054</a>	14	1	Fully-differential	X2QFN (8): 1.5 mm × 1.5 mm
<a href="#">ADS7056</a>	14	2.5	Single-ended	X2QFN (8): 1.5 mm × 1.5 mm
<a href="#">ADS7057</a>	14	2.5	Fully-differential	X2QFN (8): 1.5 mm × 1.5 mm

(1) Devices listed in the same package are pin-compatible.



### 8.3.2 Analog Input

The device supports a unipolar, single-ended analog input signal. Figure 33 shows a small-signal equivalent circuit of the sample-and-hold circuit. The sampling is represented by a resistance ( $R_{S1}$  and  $R_{S2}$ , typically  $50\ \Omega$ ) in series with an ideal switch ( $SW_1$  and  $SW_2$ ). The sampling capacitors,  $C_{S1}$  and  $C_{S2}$ , are typically  $16\ \text{pF}$ .

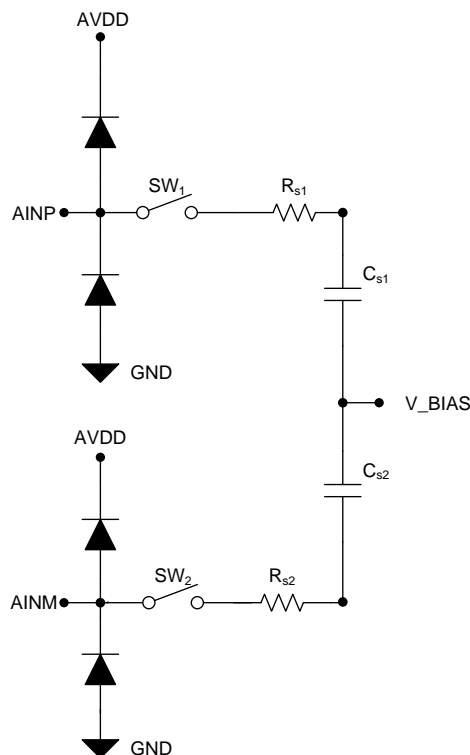


Figure 33. Equivalent Input Circuit for the Sampling Stage

During the acquisition process, both positive and negative inputs are individually sampled on  $C_{S1}$  and  $C_{S2}$ , respectively. During the conversion process, the device converts for the voltage difference between the two sampled values:  $V_{AINP} - V_{AINM}$ .

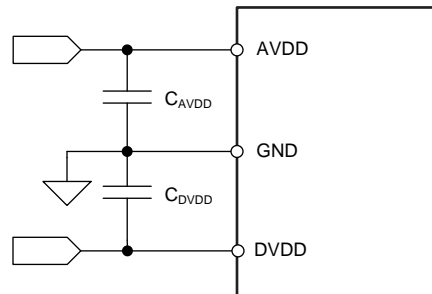
Each analog input pin has electrostatic discharge (ESD) protection diodes to AVDD and GND. Keep the analog inputs within the specified range to avoid turning the diodes on.

The full-scale analog input range (FSR) is 0 V to AVDD.

### 8.3.3 Reference

The device uses the analog supply voltage (AVDD) as the reference voltage for the analog to digital conversion. During the conversion process, the internal capacitors are switched to the AVDD pin as per the successive approximation algorithm. A voltage reference must be selected with low temperature drift, high output current drive and low output impedance. TI recommends a 3.3- $\mu\text{F}$  ( $C_{\text{AVDD}}$ ), low equivalent series resistance (ESR) ceramic capacitor between the AVDD and GND pins. This decoupling capacitor provides the instantaneous charge required by the internal circuit during the conversion process and maintains a stable dc voltage on the AVDD pin.

See the [Power Supply Recommendations](#) and [Layout Example](#) sections for component recommendations and layout guidelines.



**Figure 34. Reference for the Device**

### 8.3.4 ADC Transfer Function

The device supports a unipolar, single-ended analog input signal. The output is in straight binary format. Figure 35 and Table 2 show the ideal transfer characteristics for the device.

The least significant bit for the device is given by:

$$1 \text{ LSB} = V_{\text{REF}} / 2^N$$

where:

- $V_{\text{REF}}$  = Voltage applied between the AVDD and GND pins
- $N = 14$

(1)

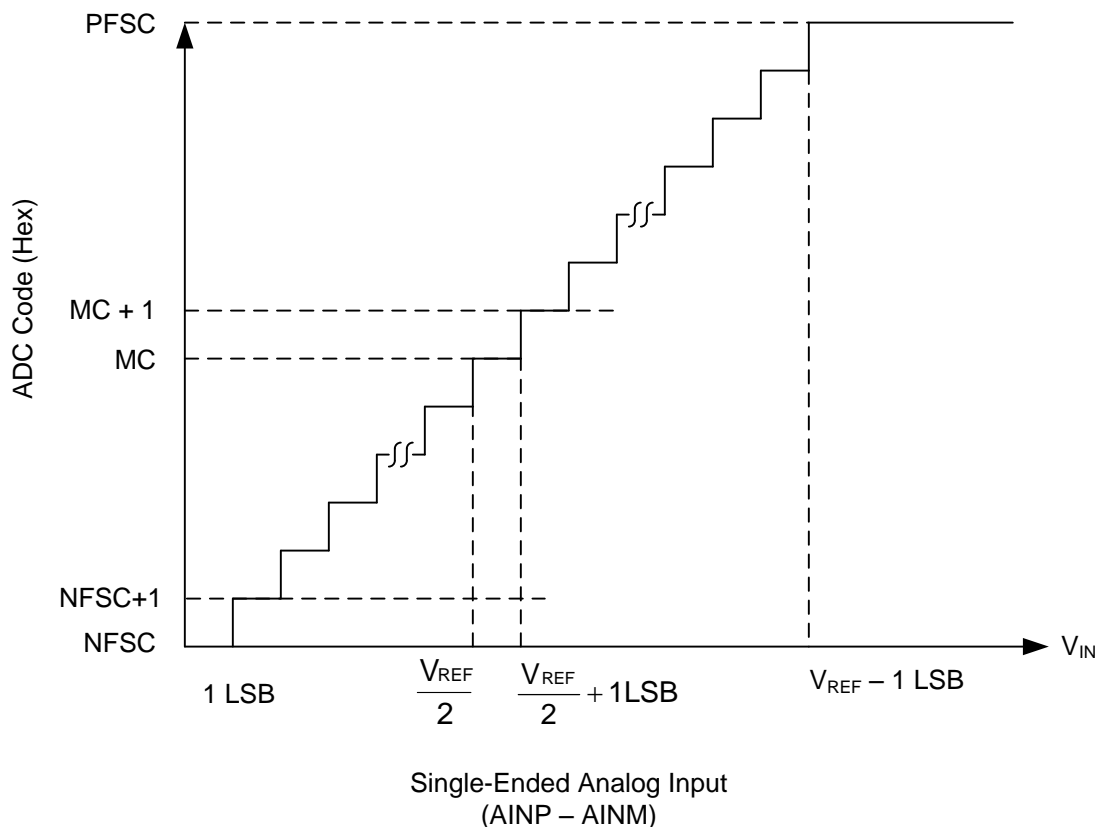


Figure 35. Ideal Transfer Characteristics

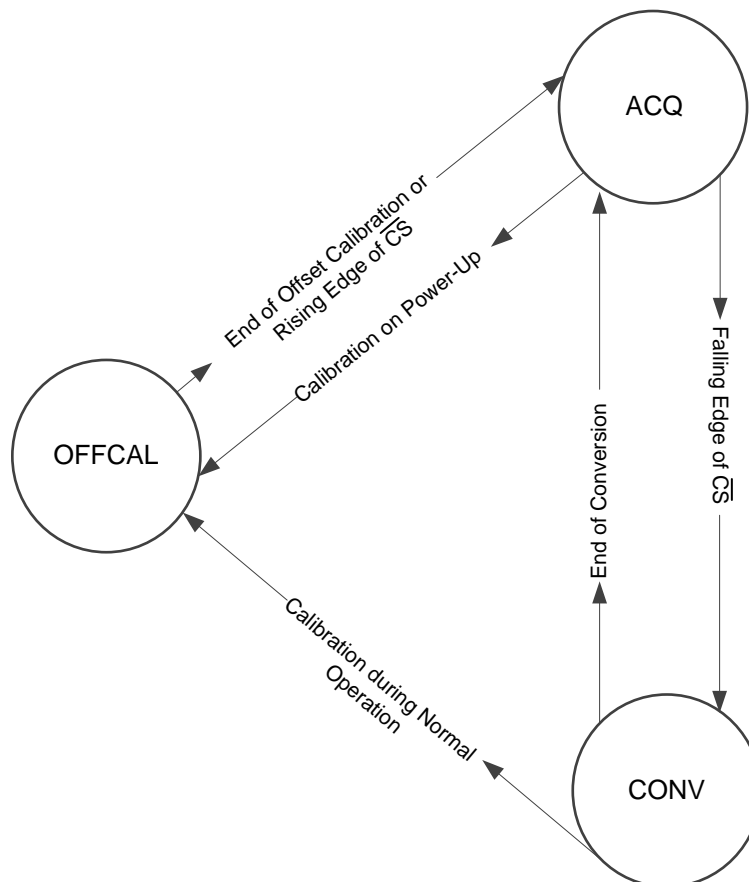
Table 2. Transfer Characteristics

INPUT VOLTAGE (AINP – AINM)	CODE	DESCRIPTION	IDEAL OUTPUT CODE (Hex)
$\leq 1 \text{ LSB}$	NFSC	Negative full-scale code	0000
1 LSB to 2 LSBs	NFSC + 1	—	0001
$V_{\text{REF}} / 2$ to $V_{\text{REF}} / 2 + 1 \text{ LSB}$	MC	Mid code	1FFF
$V_{\text{REF}} / 2 + 1 \text{ LSB}$ to $V_{\text{REF}} / 2 + 2 \text{ LSB}$	MC + 1	—	2000
$\geq V_{\text{REF}} - 1 \text{ LSB}$	PFSC	Positive full-scale code	3FFF

## 8.4 Device Functional Modes

The device supports a simple, SPI-compatible interface to the external host. On power-up, the device is in the ACQ state. The  $\overline{CS}$  signal defines one conversion and serial data transfer frame. A frame starts with a  $\overline{CS}$  falling edge and ends with a  $\overline{CS}$  rising edge. The SDO pin is tri-stated when  $\overline{CS}$  is high. With  $\overline{CS}$  low, the clock provided on the SCLK pin is used for conversion and data transfer. Output data are available on the SDO pin.

As shown in Figure 36, the device supports three functional states: acquisition (ACQ), conversion (CNV), and offset calibration (OFFCAL). The device status depends on the  $\overline{CS}$  and SCLK signals provided by the host controller.



**Figure 36. Functional State Diagram**

### 8.4.1 ACQ State

In the ACQ state, switches  $SW_1$  and  $SW_2$  connected to the analog input pins close and the device acquires the analog input signal on  $C_{S1}$  and  $C_{S2}$ . The device enters ACQ state at power-up, at the end of every conversion, and after completing the offset calibration. A  $\overline{CS}$  falling edge takes the device from the ACQ state to the CNV state.

The device consumes extremely low power from the AVDD and DVDD power supplies when in ACQ state.

## Device Functional Modes (continued)

### 8.4.2 CNV State

In the CNV state, the device uses the external clock to convert the sampled analog input signal to an equivalent digital code as per the transfer function illustrated in Figure 35. The conversion process requires a minimum of 18 SCLK falling edges to be provided within the frame. After the end of conversion process, the device automatically moves from the CNV state to the ACQ state. For acquisition of the next sample, a minimum time of  $t_{ACQ}$  must be provided.

Figure 37 shows a detailed timing diagram for the serial interface. In the first serial transfer frame after power-up, the device provides the first data as all zeros. In any frame, the clocks provided on the SCLK pin are also used to transfer the output data for the previous conversion. A leading 0 is output on the SDO pin on the  $\overline{CS}$  falling edge. The most significant bit (MSB) of the output data is launched on the SDO pin on the rising edge after the first SCLK falling edge. Subsequent output bits are launched on the subsequent rising edges provided on SCLK. When all 14 output bits are shifted out, the device outputs 0's on the subsequent SCLK rising edges. The device enters the ACQ state after 18 clocks and a minimum time of  $t_{ACQ}$  must be provided for acquiring the next sample. If the device is provided with less than 18 SCLK falling edges in the present serial transfer frame, the device provides an invalid conversion result in the next serial transfer frame.

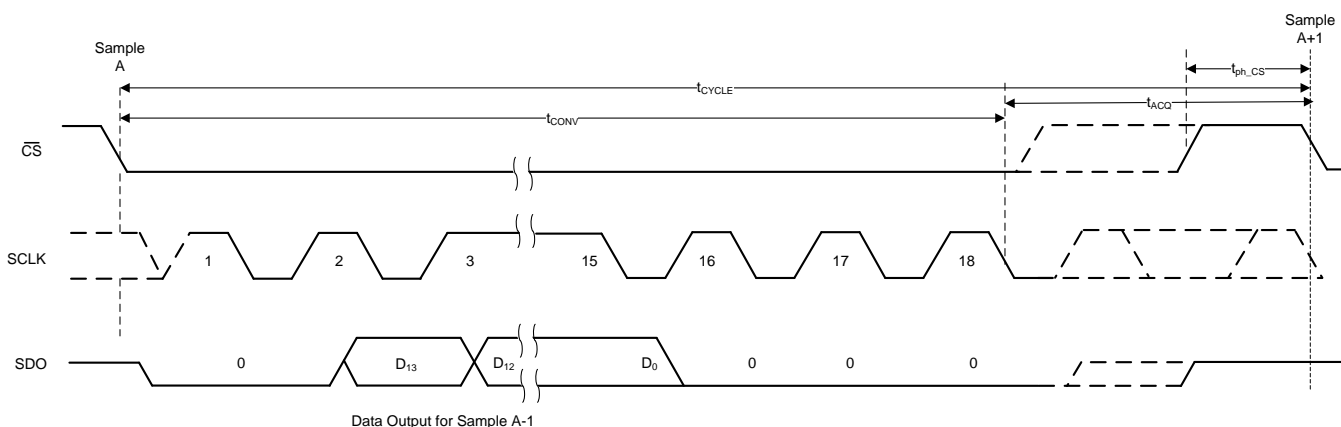


Figure 37. Serial Interface Timing Diagram

## Device Functional Modes (continued)

### 8.4.3 OFFCAL State

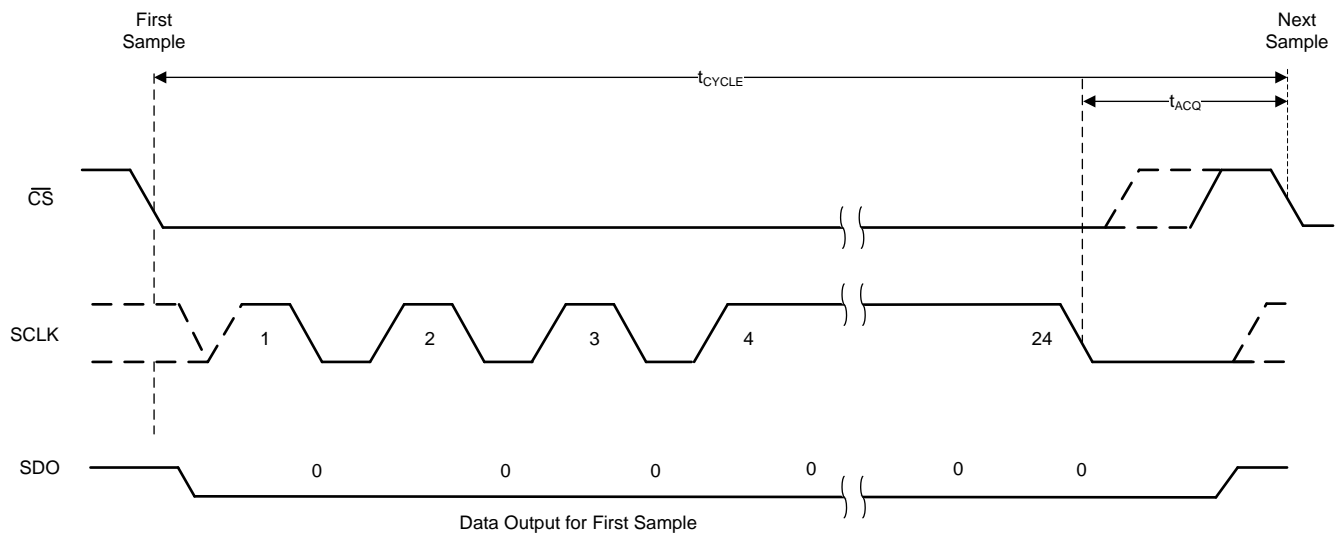
In the offset calibration (OFFCAL) state, the sampling capacitors are disconnected from the analog input pins (AINP and AINM) and the device calibrates and corrects for any internal offset errors. The offset calibration is effective for all subsequent conversions until the device is powered off. An offset calibration cycle is recommended at power-up and whenever there is a significant change in the operating conditions for the device (such as in the AVDD voltage and operating temperature).

The host controller must provide a serial transfer frame as described in [Figure 38](#) or in [Figure 39](#) to enter the OFFCAL state.

#### 8.4.3.1 Offset Calibration on Power-Up

On power-up, the host must provide 24 SCLKs in the first serial transfer to enter the OFFCAL state. The device provides 0's on SDO during offset calibration. For acquisition of the next sample, a minimum time of  $t_{ACQ}$  must be provided.

If the host controller starts the offset calibration process but then pulls the  $\overline{CS}$  pin high before providing 24 SCLKs, then the offset calibration process is aborted and the device enters the ACQ state. [Figure 38](#) and [Table 3](#) provide the timing for offset calibration on power-up.



**Figure 38. Timing for Offset Calibration on Power-Up**

**Table 3. Timing Specifications for Offset Calibration on Power-Up<sup>(1)</sup>**

		MIN	TYP	MAX	UNIT
$t_{cycle}$	Cycle time for offset calibration on power-up	$24 \times t_{CLK} + t_{ACQ}$			ns
$t_{ACQ}$	Acquisition time	230			ns
$f_{SCLK}$	Frequency of SCLK	24			MHz

(1) In addition to the timing specifications of [Figure 38](#) and [Table 3](#), the timing specifications described in [Figure 2](#) and the [Timing Requirements](#) table are also applicable for offset calibration on power-up.

### 8.4.3.2 Offset Calibration During Normal Operation

During normal operation, the host must provide 64 SCLKs in the serial transfer frame to enter the OFFCAL state. The device provides the conversion result for the previous sample during the first 18 SCLKs and 0's on SDO for the rest of the SCLKs in the serial transfer frame. For acquisition of the next sample, a minimum time of  $t_{ACQ}$  must be provided.

If the host controller provides more than 18 SCLKs but pulls the  $\overline{CS}$  high before providing 64 SCLKs, then the offset calibration process is aborted and the device enters the ACQ state. Figure 39 and Table 4 provide the timing for offset calibration during normal operation.

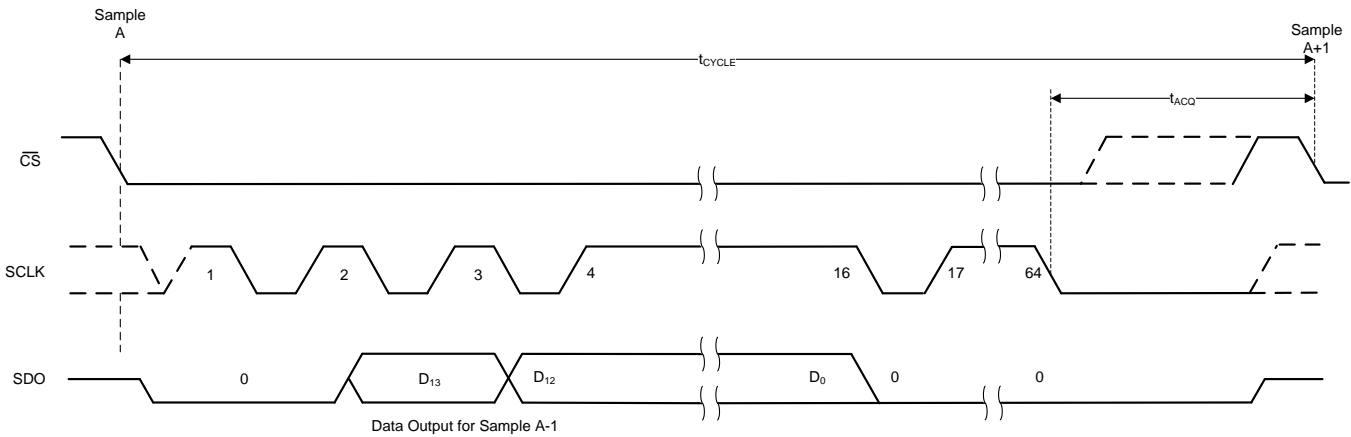


Figure 39. Timing for Offset Calibration During Normal Operation

Table 4. Timing Specifications for Offset Calibration During Normal Operation<sup>(1)</sup>

		MIN	TYP	MAX	UNIT
$t_{cycle}$	Cycle time for offset calibration on power-up	$64 \times t_{CLK} + t_{ACQ}$			ns
$t_{ACQ}$	Acquisition time	230			ns
$f_{SCLK}$	Frequency of SCLK	24			MHz

(1) In addition to the timing specifications of Figure 39 and Table 4, the timing specifications described in Figure 2 and the [Timing Requirements](#) table are also applicable for offset calibration during normal operation.

## 9 Application and Implementation

### NOTE

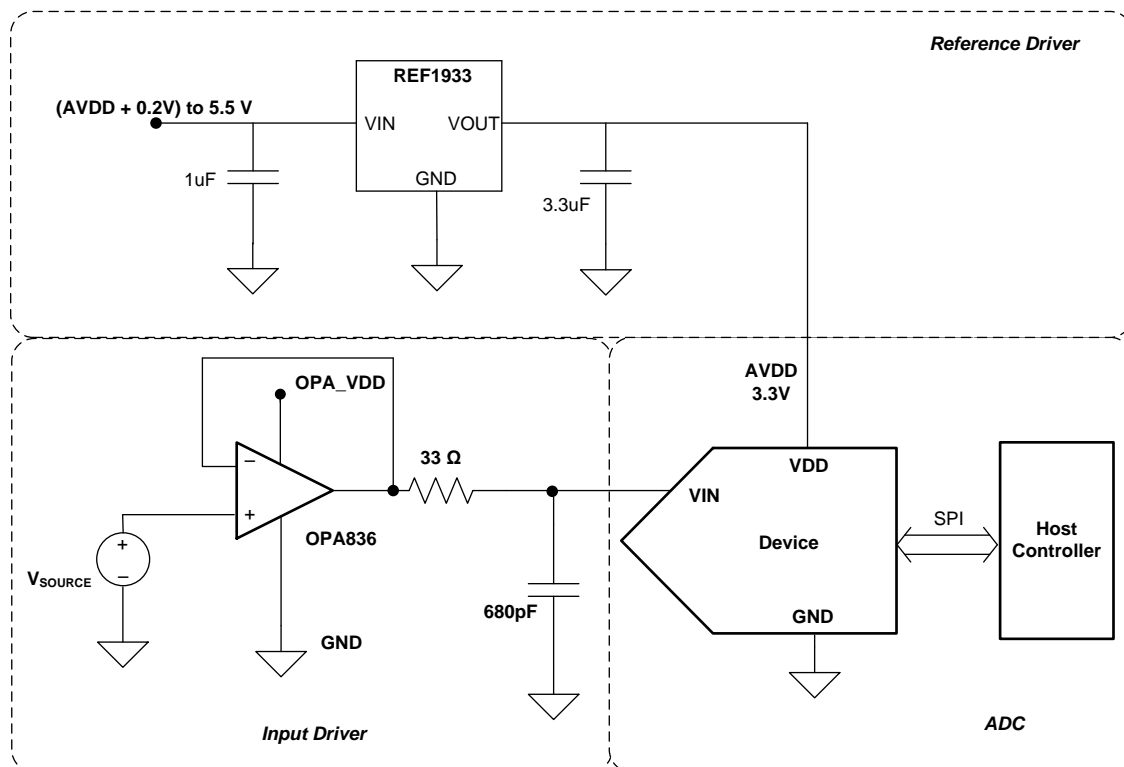
Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 9.1 Application Information

The two primary supporting circuits required to maximize the performance of a high-precision, successive approximation register (SAR) analog-to-digital converter (ADC) are the input driver and the reference driver circuits. This section details some general principles for designing the input driver circuit, reference driver circuit, and provides typical application circuits designed for the device.

### 9.2 Typical Applications

#### 9.2.1 Single-Supply Data Acquisition With the ADS7052



**Figure 40. DAQ Circuit: Single-Supply DAQ**

#### 9.2.1.1 Design Requirements

The goal of the circuit shown in [Figure 40](#) is to design a single-supply data acquisition (DAQ) circuit based on the ADS7052 with SNR greater than 74 dB and THD less than  $-85$  dB for input frequencies of 2 kHz at a throughput of 1 MSPS for applications such as low power data acquisition systems, sensor monitoring, and environmental sensing.



## Typical Applications (continued)

### 9.2.1.2 Detailed Design Procedure

The input driver circuit for a high-precision ADC mainly consists of two parts: a driving amplifier and charge kickback filter. Careful design of the front-end circuit is critical to meet the linearity and noise performance of a high-precision ADC.

#### 9.2.1.2.1 Low Distortion Charge Kickback Filter Design

Figure 41 shows the input circuit of a typical SAR ADC. During the acquisition phase, the SW switch closes and connects the sampling capacitor ( $C_{SH}$ ) to the input driver circuit. This action introduces a transient on the input pins of the SAR ADC. An ideal amplifier with  $0\ \Omega$  of output impedance and infinite current drive can settle this transient in zero time. For a real amplifier with non-zero output impedance and finite drive strength, this switched capacitor load can create stability issues.

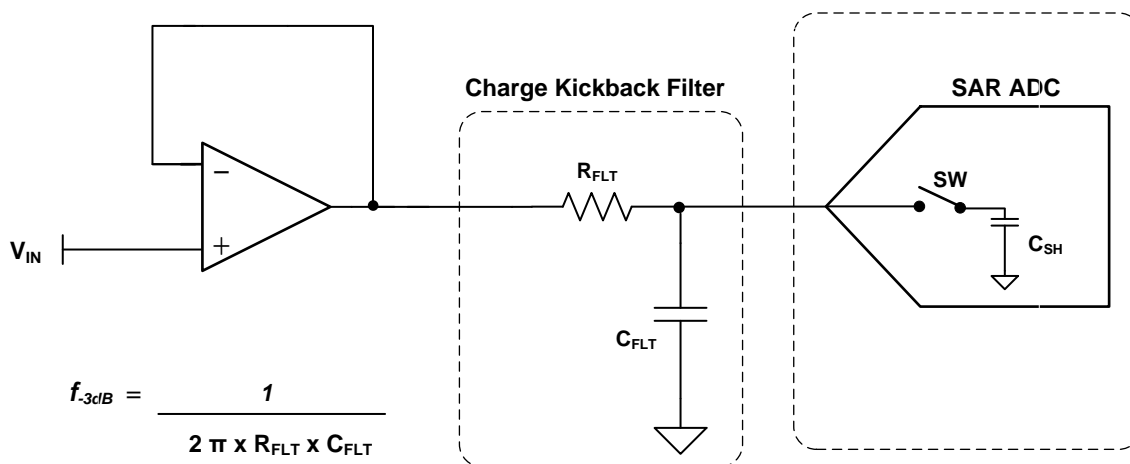


Figure 41. Input Sample-and-Hold Circuit for a Typical SAR ADC

For ac signals, the filter bandwidth must be kept low to band-limit the noise fed into the ADC input, thereby increasing the signal-to-noise ratio (SNR) of the system. Besides filtering the noise from the front-end drive circuitry, the RC filter also helps attenuate the sampling charge injection from the switched-capacitor input stage of the ADC. A filter capacitor,  $C_{FLT}$ , is connected across the ADC inputs. This capacitor helps reduce the sampling charge injection and provides a charge bucket to quickly charge the internal sample-and-hold capacitors during the acquisition process. As a rule of thumb, the value of this capacitor is at least 20 times the specified value of the ADC sampling capacitance. For this device, the input sampling capacitance is equal to 16 pF. Thus, the value of  $C_{FLT}$  is greater than 320 pF. Select a COG- or NPO-type capacitor because these capacitor types have a high-Q, low-temperature coefficient, and stable electrical characteristics under varying voltages, frequency, and time.

Driving capacitive loads can degrade the phase margin of the input amplifiers, thus making the amplifier marginally unstable. To avoid amplifier stability issues, series isolation resistors ( $R_{FLT}$ ) are used at the output of the amplifiers. A higher value of  $R_{FLT}$  is helpful from the amplifier stability perspective, but adds distortion as a result of interactions with the nonlinear input impedance of the ADC. Distortion increases with source impedance, input signal frequency, and input signal amplitude. Therefore, the selection of  $R_{FLT}$  requires balancing the stability and distortion of the design.

## Typical Applications (continued)

### 9.2.1.2.2 Input Amplifier Selection

The input amplifier bandwidth is typically much higher than the cutoff frequency of the charge kickback filter. Thus, TI strongly recommends performing a SPICE simulation to confirm that the amplifier has more than 40° phase margin with the selected filter. Simulation is critical because even with high-bandwidth amplifiers, some amplifiers can require more bandwidth than others to drive similar filters. To learn more about the SAR ADC input driver design, see the [TI Precision Labs training video series](#).

For the application circuit of [Figure 40](#), the [OPA836](#) is selected for its high bandwidth (205 MHz), low noise (4.6 nV/√Hz), high output drive capacity (45 mA), and fast settling response (22 ns for 0.1% settling).

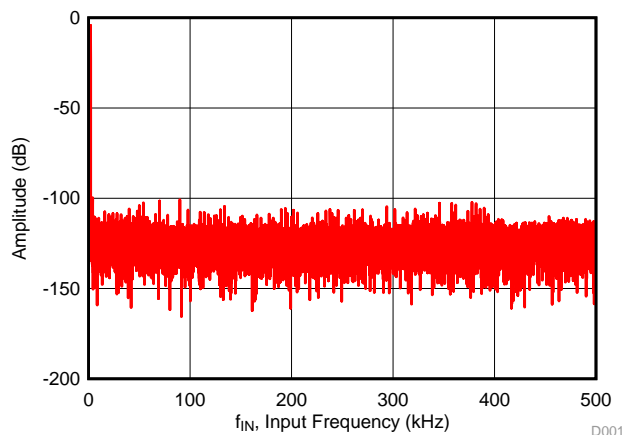
### 9.2.1.2.3 Reference Circuit

The ADS70xx uses the analog supply voltage (AVDD) as the reference voltage for the analog to digital conversion. During the conversion process, the internal capacitors are switched to the level of the AVDD pin as per the successive approximation algorithm. A voltage reference must be selected with low temperature drift, high output current drive and low output impedance. For this application, the [REF1933](#) was selected as the voltage reference and analog power supply for the ADC. The [REF1933](#) has excellent temperature drift performance (25 ppm/°C), good initial accuracy (0.1%), high output drive capability (25 mA), and low quiescent current (360 μA). The [REF1933](#) also provides a bias voltage output of half the reference voltage (VREF/2) which can be used as the common mode input for the amplifier.

TI recommends a 3.3-μF ( $C_{AVDD}$ ), low equivalent series resistance (ESR) ceramic capacitor between the AVDD and GND pins. This decoupling capacitor provides the instantaneous charge required by the internal circuit during the conversion process and maintains a stable dc voltage on the AVDD pin.

### 9.2.1.3 Application Curve

[Figure 42](#) provides the measurement result for the circuit described in [Figure 40](#).



SNR = 75.3 dB, THD = -90.1 dB, SINAD = 75 dB

**Figure 42. Test Results for the ADS7052 and OPA836 for a 2-kHz Input**

## Typical Applications (continued)

### 9.2.2 High Bandwidth (200 kHz) Data Acquisition With the ADS7052

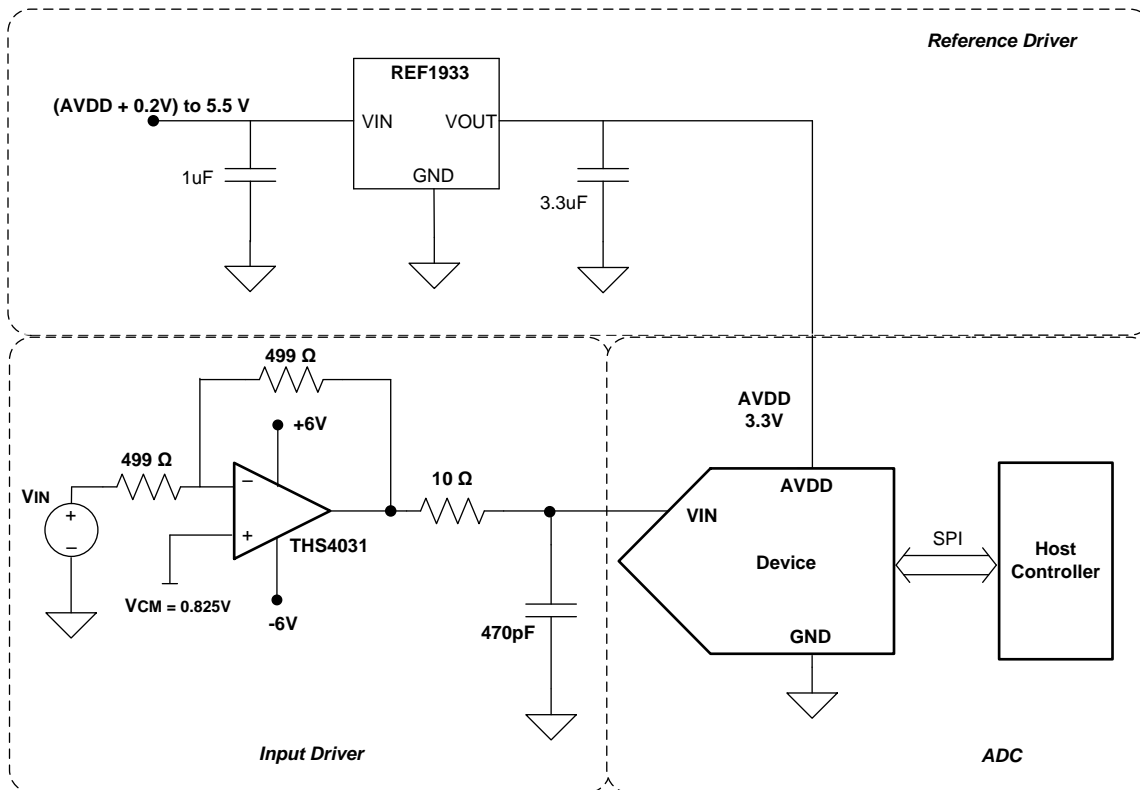


Figure 43. High Bandwidth DAQ Circuit

#### 9.2.2.1 Design Requirements

Applications such as motor control feedback loops, motor encoders, global positioning systems (GPS), and optical modules need analog-to-digital converters that are interfaced to high-frequency sensors (200 kHz to 1 MHz). The goal of the circuit described in Figure 43 is to design a circuit based on the ADS7052 with SNR greater than 73 dB and THD less than  $-85$  dB for input frequencies of 200 kHz at a throughput of 1 MSPS.

#### 9.2.2.2 Detailed Design Procedure

To achieve a SINAD greater than 73 dB and THD less than  $-85$  dB, the operational amplifier must have high bandwidth in order to settle the input signal within the acquisition time of the ADC. The operational amplifier must have low noise to keep the total system noise below 20% of the input-referred noise of the ADC. For the application circuit shown in Figure 43, the THS4031 is selected for its high bandwidth (275 MHz), low total harmonic distortion of  $-90$  dB at 1 MHz, and ultra-low noise of  $1.6 \text{ nV}/\sqrt{\text{Hz}}$ . The THS4031 is powered up from dual power supply ( $V_{DD} = 6 \text{ V}$  and  $V_{SS} = -6 \text{ V}$ ).

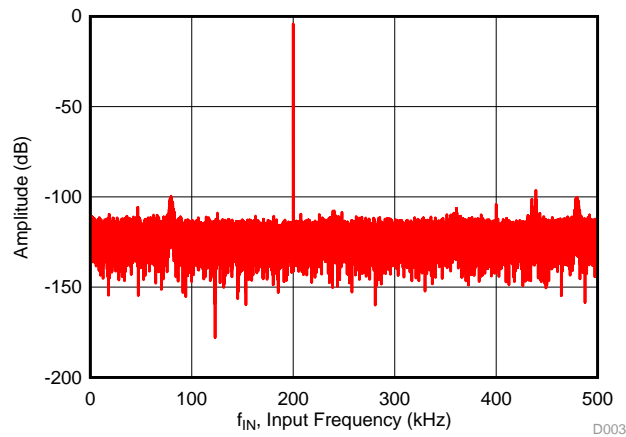
For this application, the REF1933 was selected as the voltage reference and analog power supply for the ADC. The REF1933 has excellent temperature drift performance ( $25 \text{ ppm}/^\circ\text{C}$ ), good initial accuracy (0.1%), high output drive capability (25 mA), and low quiescent current ( $360 \mu\text{A}$ ). The REF1933 also provides a bias voltage output of half the reference voltage ( $V_{REF} / 2$ ) that can be used as the common-mode input for the amplifier.

The SNR performance at higher input frequency is highly dependant on jitter on the sampling signal ( $\overline{CS}$ ). TI recommends selecting a clock source that has very low jitter ( $< 20\text{-ps RMS}$ ).

Typical Applications (continued)

9.2.2.3 Application Curve

Figure 44 shows the FFT plot for the ADS7052 with a 200-kHz input frequency used for the circuit in Figure 43.



SNR = 74.2 dB, THD = -90.4 dB, SINAD = 74 dB

Figure 44. Test Results for the ADS7052 and THS4031 for a 200-kHz Input

## Typical Applications (continued)

### 9.2.3 14-Bit, 10-kSPS DAQ Circuit Optimized for DC Sensor Measurements

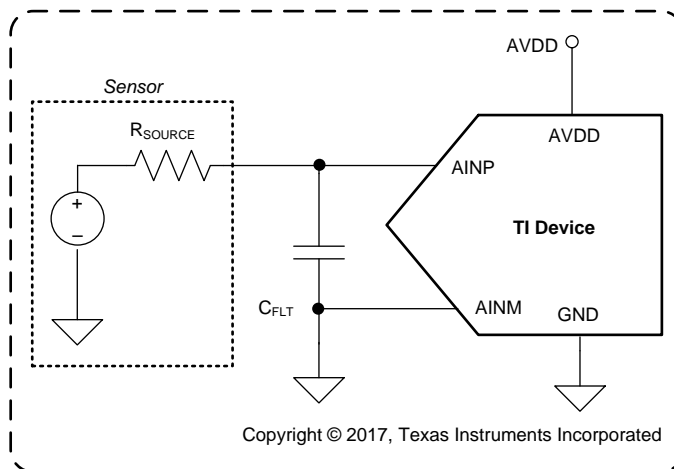


Figure 45. Interfacing the Device Directly With Sensors

In applications where the input is very slow moving and the overall system ENOB is not a critical parameter, a DAQ circuit can be designed without the input driver for the ADC. This type of a use case is of particular interest for applications in which the primary goal is to achieve the absolute lowest power possible. Typical applications that fall into this category are low-power sensor applications (such as temperature, pressure, humidity, gas, and chemical).

#### 9.2.3.1 Design Requirements

For this design example, use the parameters listed in Table 5 as the input parameters.

Table 5. Design Parameters

DESIGN PARAMETER	GOAL VALUE
Throughput	10 kSPS
SNR at 100 Hz	74 dB
THD at 100 Hz	-85 dB
SINAD at 100 Hz	73 dB
ENOB	12 bits
Power	20 $\mu$ W

#### 9.2.3.2 Detailed Design Procedure

The ADS7052 can be directly interfaced with sensors at lower throughput without the need of an amplifier buffer, however, the output impedance of the sensor must be taken into account. The sensor must be capable of driving the switched capacitor load of a SAR ADC and settling the analog input signal within the acquisition time of the SAR ADC. Figure 45 shows the simplified circuit for a sensor as a voltage source with output impedance ( $R_{SOURCE}$ ). As the output impedance of the sensor increases, the device requires more acquisition time to settle the input signal to the desired accuracy.

The acquisition time of a SAR ADC (such as the ADS7052) can be increased by reducing throughput in the following ways:

1. Reducing the SCLK frequency to reduce the throughput or
2. Keeping the SCLK fixed at the highest permissible value (that is, 24 MHz for the device) and increasing the CS high time

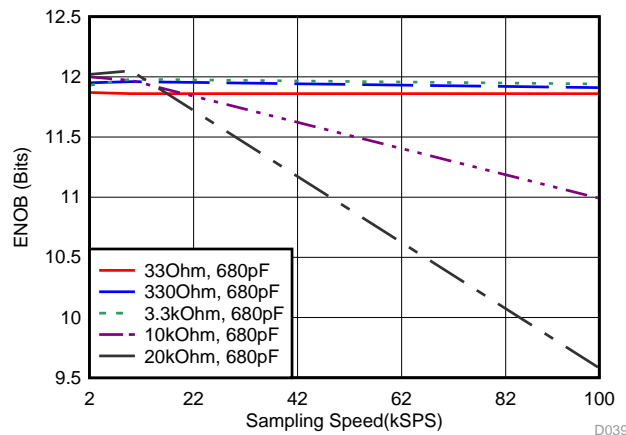
Table 6 lists the acquisition time for the above two cases for a throughput of 10 kSPS. Clearly, case 2 provides more acquisition time for the input signal to settle.

**Table 6. Acquisition Time With Different SCLK Frequencies**

CASE	SCLK	t <sub>cycle</sub>	CONVERSION TIME (= 18 × t <sub>SCLK</sub> )	ACQUISITION TIME (= t <sub>cycle</sub> – t <sub>conv</sub> )
1	0.24 MHz	100 μs	75 μs	25 μs
2	24 MHz	100 μs	0.75 μs	99.25 μs

**9.2.3.3 Application Curve**

Figure 46 provides the results for ENOB achieved from the ADS7052 for case 2 at different throughputs with different values of sensor output impedance.



**Figure 46. Effective Number of Bits (ENOB) Achieved From the ADS7052 at Different Throughputs**

Table 7 shows the results and performance summary for this 14-bit, 10-kSPS DAQ circuit application with a sensor output impedance of 22 kΩ.

**Table 7. Results and Performance Summary for a 14-Bit, 10-kSPS DAQ Circuit for DC Sensor Measurements**

DESIGN PARAMETER	GOAL VALUE	ACHIEVED RESULT
Throughput	10 kSPS	10 kSPS
SNR at 100 Hz	74 dB	75 dB
THD at 100 Hz	–85 dB	–89 dB
SINAD at 100 Hz	73 dB	74.3 dB
ENOB	12 bits	12.05 bits
Power	20 μW	17 μW

## 10 Power Supply Recommendations

### 10.1 AVDD and DVDD Supply Recommendations

The device has two separate power supplies: AVDD and DVDD.

AVDD powers the analog blocks and is also used as the reference voltage for the analog-to-digital conversion. Use a low-noise, low-dropout regulator (LDO) or a discrete reference to supply AVDD (see the [Reference](#) and [Application Information](#) sections). Always set the AVDD supply to be greater than or equal to the maximum input signal to avoid code saturation. Decouple the AVDD pin to the GND pin with a 3.3- $\mu$ F ceramic decoupling capacitor.

DVDD is used for the interface circuits. Decouple the DVDD pin to the GND pin with a 1- $\mu$ F ceramic decoupling capacitor. [图 47](#) shows the decoupling recommendations.

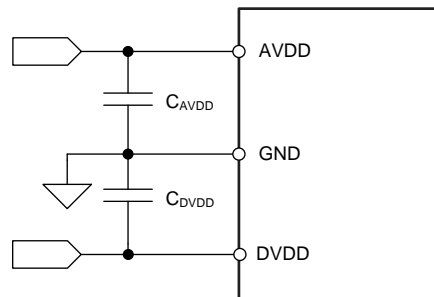


图 47. Power-Supply Decoupling

### 10.2 Optimizing Power Consumed by the Device

In order to best optimize the power consumed by the device, use the following design considerations:

- Keep the analog supply voltage (AVDD) in the specified operating range and equal to the maximum analog input voltage.
- Keep the digital supply voltage (DVDD) in the specified operating range and at the lowest value supported by the host controller.
- Reduce the load capacitance on the SDO output.
- Run the device at the optimum throughput. Power consumption reduces proportionally with the throughput.

#### 10.2.1 Estimating Digital Power Consumption

The current consumption from the DVDD supply depends on the DVDD voltage, the load capacitance on the SDO pin ( $C_{\text{LOAD-SDO}}$ ), and the output code, and can be calculated as:

$$I_{\text{DVDD}} = C_{\text{LOAD-SDO}} \times V \times f$$

where:

- $C_{\text{LOAD-SDO}}$  = Load capacitance on the SDO pin
  - $V$  = DVDD supply voltage
  - $f$  = Frequency of transitions on the SDO output
- (2)

The number of transitions on the SDO output depends on the output code, and thus changes with the analog input. The maximum value of  $f$  occurs when data output on the SDO change on every SCLK (that is, for output codes of 2AAAh or 1555h). With an output code of 2AAAh or 1555h,  $f = 7$  MHz and when  $C_{\text{LOAD-SDO}} = 20$  pF and  $\text{DVDD} = 1.8$  V,  $I_{\text{DVDD}} = 250$   $\mu$ A.

## 11 Layout

### 11.1 Layout Guidelines

图 48 shows a typical connection diagram for the ADS7052.

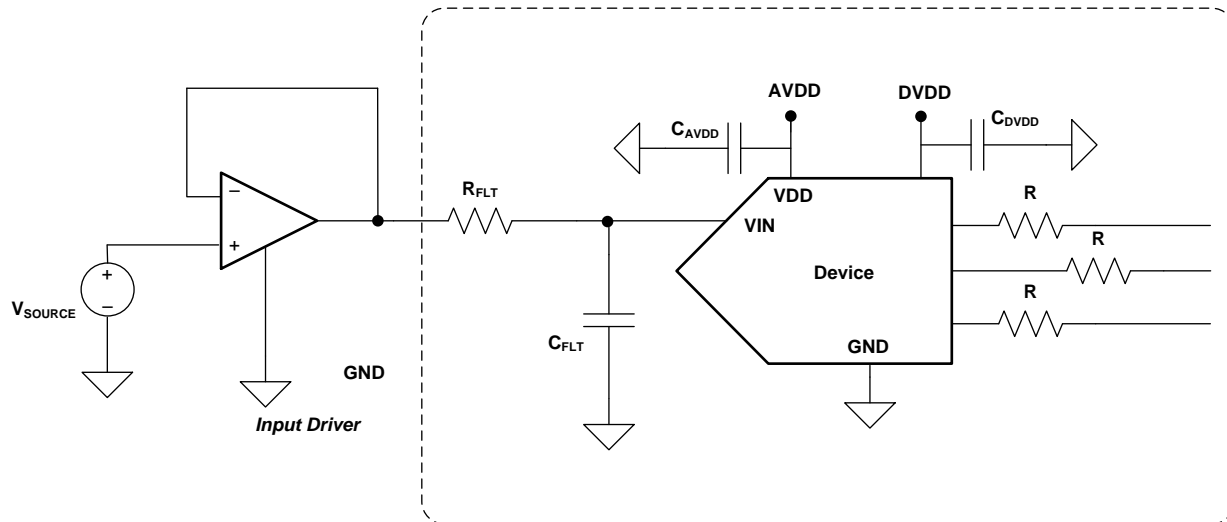


图 48. Typical Connection Diagram

图 49 depicts a board layout example for the device for the typical connection diagram in 图 48. The key considerations for layout are:

- Use a solid ground plane underneath the device and partition the PCB into analog and digital sections
- Avoid crossing digital lines with the analog signal path and keep the analog input signals and the reference input signals away from noise sources.
- The power sources to the device must be clean and well-bypassed. Use  $C_{AVDD}$  decoupling capacitors in close proximity to the analog (AVDD) power-supply pin.
- Use a  $C_{DVDD}$  decoupling capacitor close to the digital (DVDD) power-supply pin.
- Avoid placing vias between the AVDD and DVDD pins and the bypass capacitors.
- Connect the ground pin to the ground plane using a short, low-impedance path.
- Place the charge kickback filter components close to the device.

Among ceramic surface-mount capacitors, COG (NPO) ceramic capacitors are recommended because these components provide the most stable electrical properties over voltage, frequency, and temperature changes.



## 11.2 Layout Example

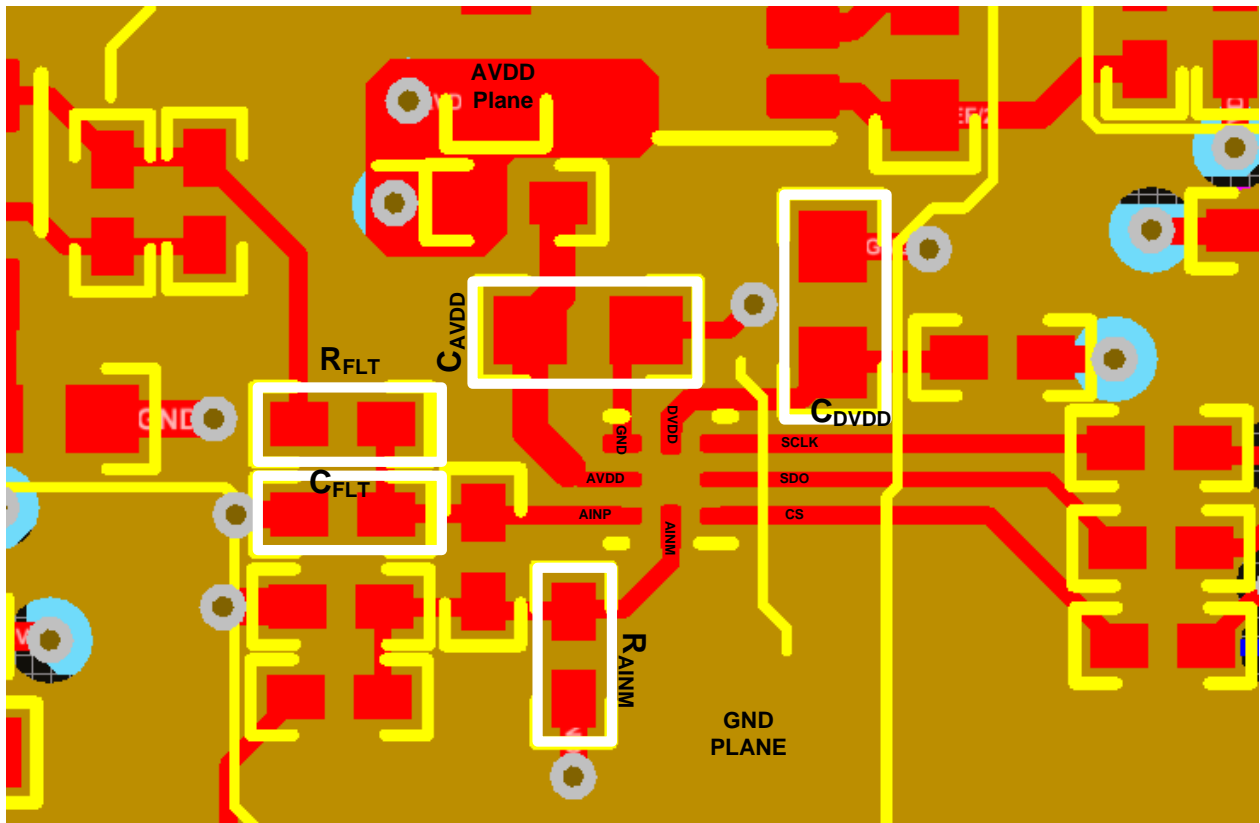


图 49. Example Layout

## 12 器件和文档支持

### 12.1 器件支持

#### 12.1.1 开发支持

[TI 高精度实验室培训视频系列](#)

### 12.2 文档支持

#### 12.2.1 相关文档

请参阅如下相关文档：

输入驱动器放大器（单端输入）：

- [《OPAx836 极低功耗、轨至轨输出、负轨输入、电压反馈运算放大器》](#)
- [THS403x 100MHz 低噪声高速放大器](#)
- [《OPAx365 50MHz、零交叉、低失真、高 CMRR、RRI/O、单电源运算放大器》](#)

输入驱动器放大器（全差分输入）：

- [THS4551 低噪声 150MHz 全差分精密放大器](#)
- [《OPAx836 极低功耗、轨至轨输出、负轨输入、电压反馈运算放大器》](#)

基准驱动器：

- [《REF19xx 低漂移、低功率、双路输出、 \$V\_{REF}\$  和  \$V\_{REF}/2\$  电压基准》](#)
- [《具有集成 ADC 驱动器缓冲器的 REF61xx 高精度电压基准》](#)

类似器件：

- [《ADS7042 超低功耗、超小尺寸、12 位、1MSPS、SAR ADC》](#)
- [《ADS7049-Q1 小型低功耗 12 位、2MSPS SAR ADC》](#)

参考设计：

- [TI 设计：采用 73dB SNR、7.5MSPS 时间交织 SAR ADC 且适用于成像应用的模拟前端参考设计](#)
- [针对双极信号采用运算放大器和 FDA 的单端到差分](#)

### 12.3 接收文档更新通知

要接收文档更新通知，请导航至 [TI.com](http://TI.com) 上的器件产品文件夹。单击右上角的 [通知我](#) 进行注册，即可每周接收产品信息更改摘要。有关更改的详细信息，请查看任何已修订文档中包含的修订历史记录。

### 12.4 社区资源

下列链接提供到 TI 社区资源的连接。链接的内容由各个分销商“按照原样”提供。这些内容并不构成 TI 技术规范，并且不一定反映 TI 的观点；请参阅 TI 的 [《使用条款》](#)。

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**设计支持** [TI 参考设计支持](#) 可帮助您快速查找有帮助的 E2E 论坛、设计支持工具以及技术支持的联系信息。

### 12.5 商标

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### 12.6 静电放电警告



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ESD 的损坏小至导致微小的性能降级，大至整个器件故障。精密的集成电路可能更容易受到损坏，这是因为非常细微的参数更改都可能会导致器件与其发布的规格不相符。

## 12.7 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

### **13 机械、封装和可订购信息**

以下页面包含机械、封装和可订购信息。这些信息是指定器件的最新可用数据。数据如有变更，恕不另行通知和修订此文档。如欲获取此产品说明书的浏览器版本，请参阅左侧的导航。

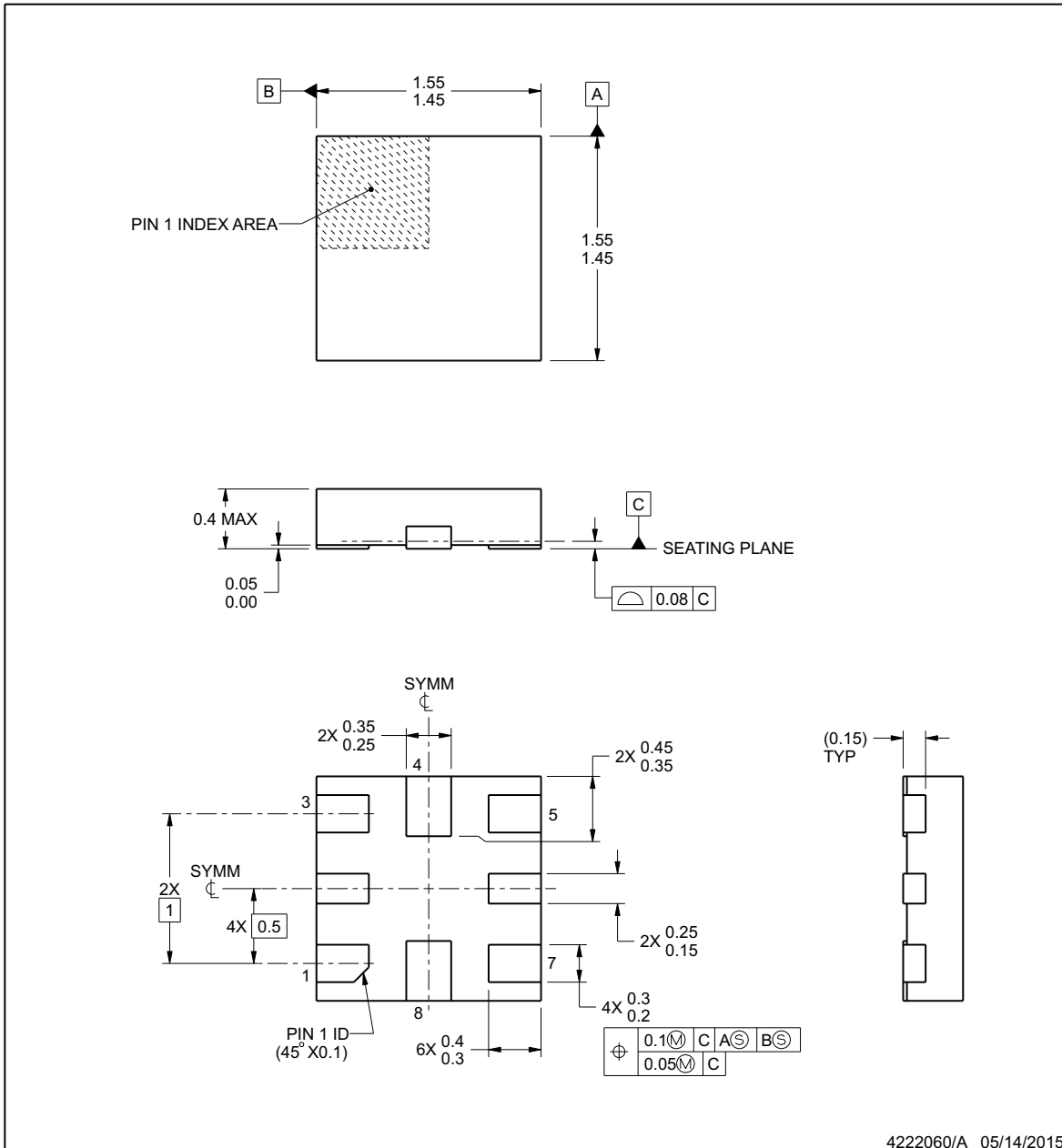


RUG0008A

PACKAGE OUTLINE

X2QFN - 0.4 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES:

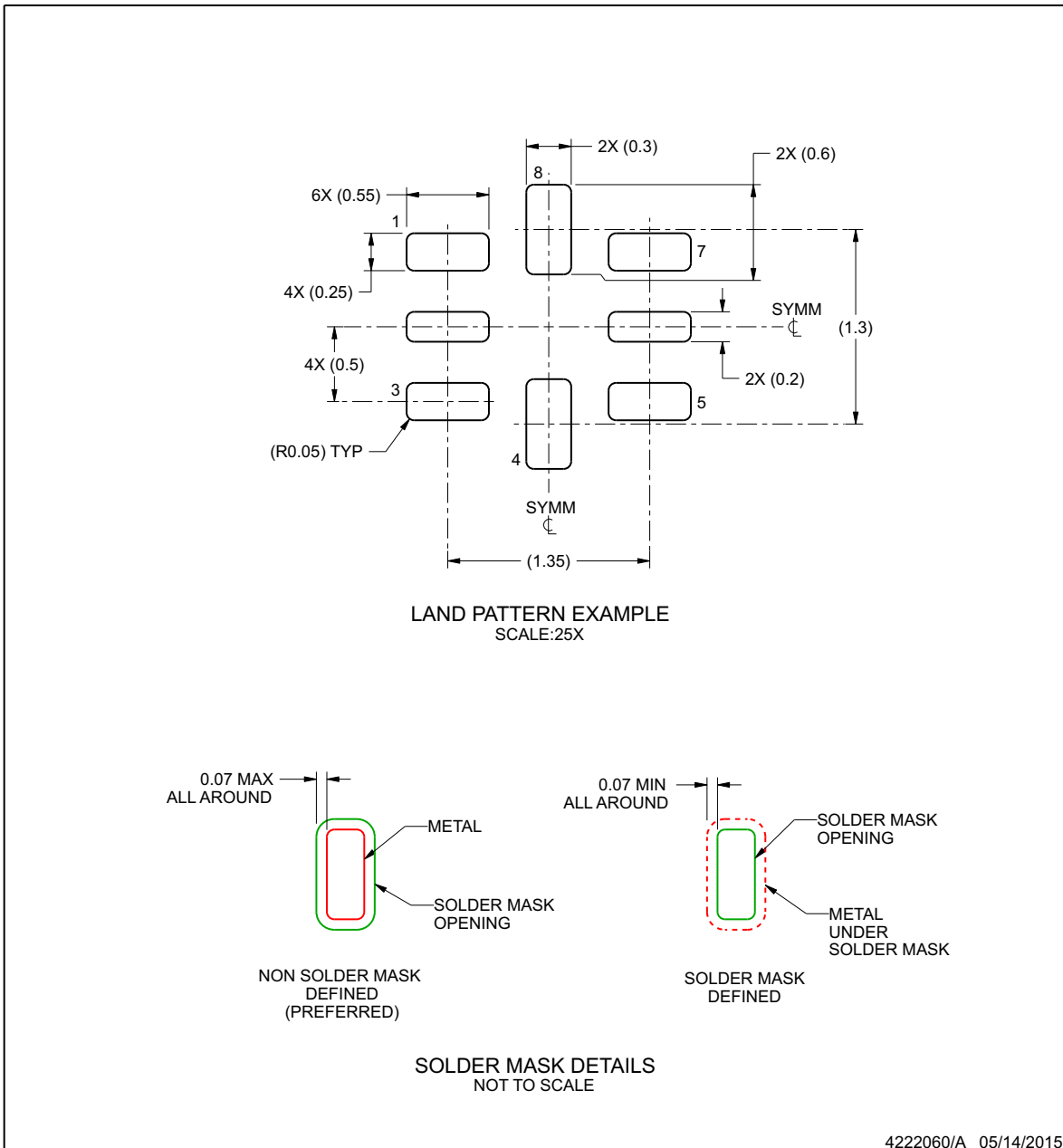
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.

EXAMPLE BOARD LAYOUT

RUG0008A

X2QFN - 0.4 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



4222060/A 05/14/2015

NOTES: (continued)

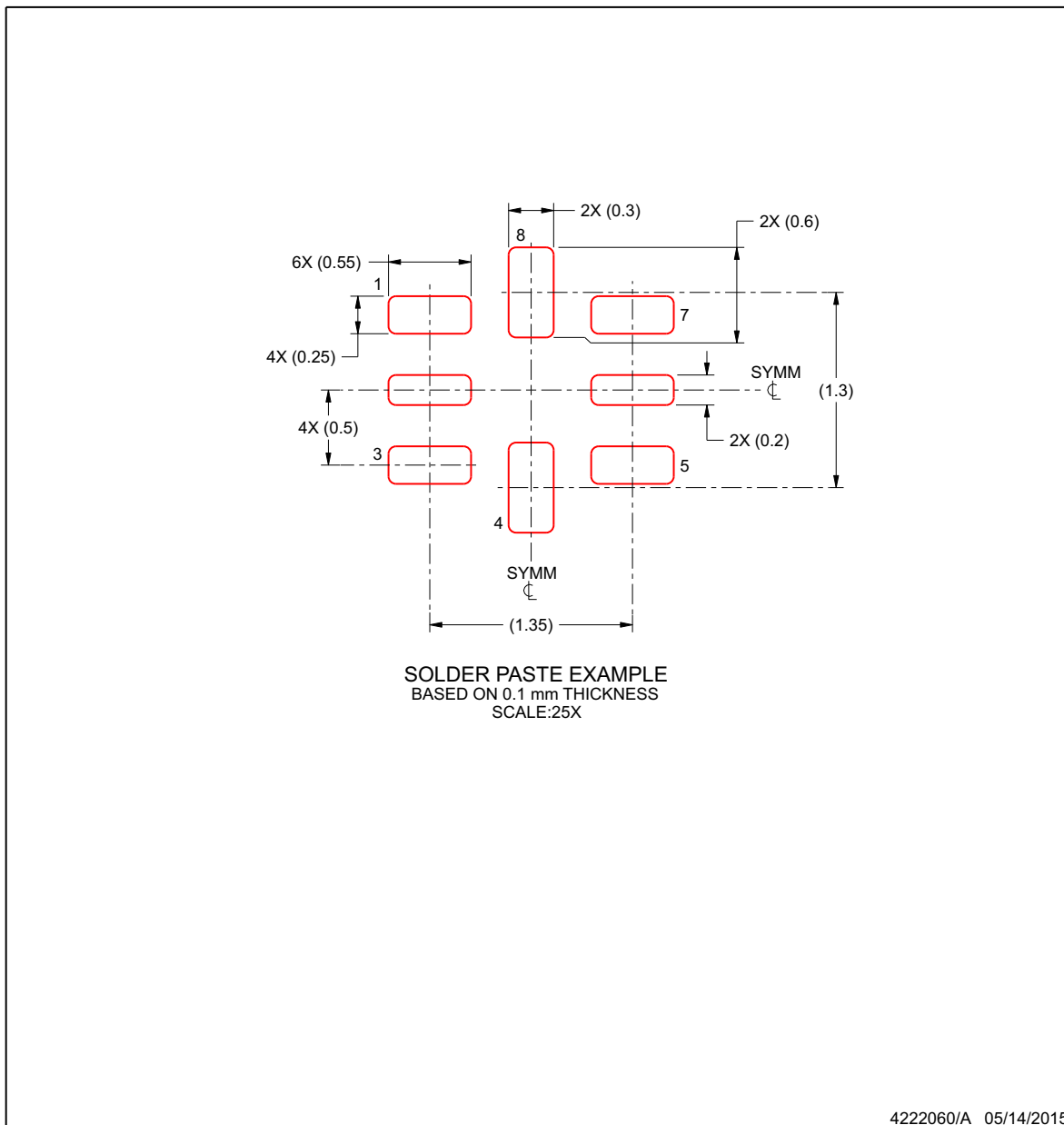
3. For more information, see Texas Instruments literature number SLUA271 ([www.ti.com/lit/slua271](http://www.ti.com/lit/slua271)).

## EXAMPLE STENCIL DESIGN

**RUG0008A**

**X2QFN - 0.4 mm max height**

PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

**PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
ADS7052IRUGR	ACTIVE	X2QFN	RUG	8	3000	RoHS & Green	NIPDAUAG	Level-1-260C-UNLIM	-40 to 125	90	<b>Samples</b>

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "-" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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## TAPE AND REEL INFORMATION



### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
ADS7052IRUGR	X2QFN	RUG	8	3000	180.0	8.4	1.6	1.6	0.66	4.0	8.0	Q2

TAPE AND REEL BOX DIMENSIONS

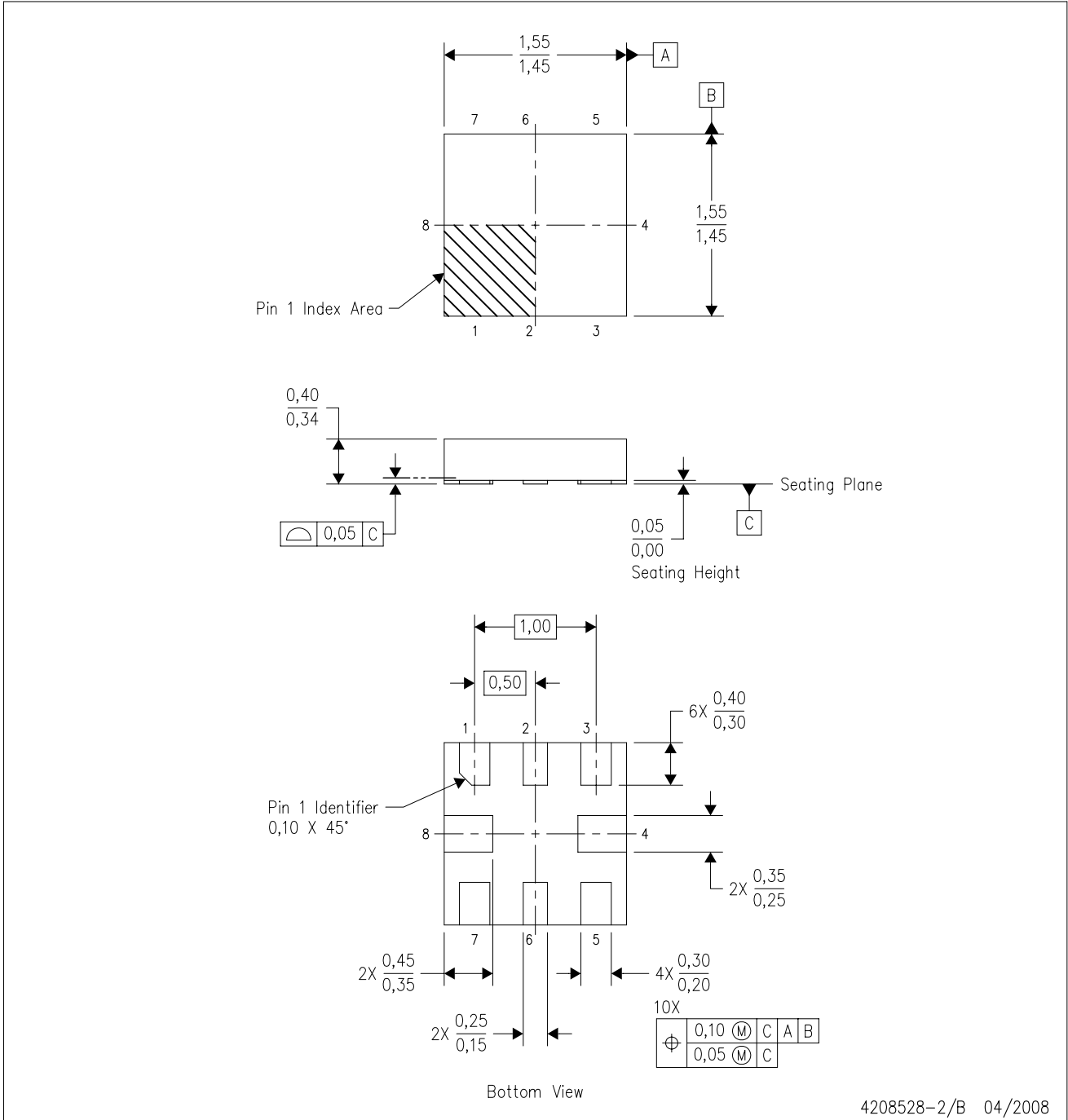


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
ADS7052IRUGR	X2QFN	RUG	8	3000	183.0	183.0	20.0

RUG (S-PQFP-N8)

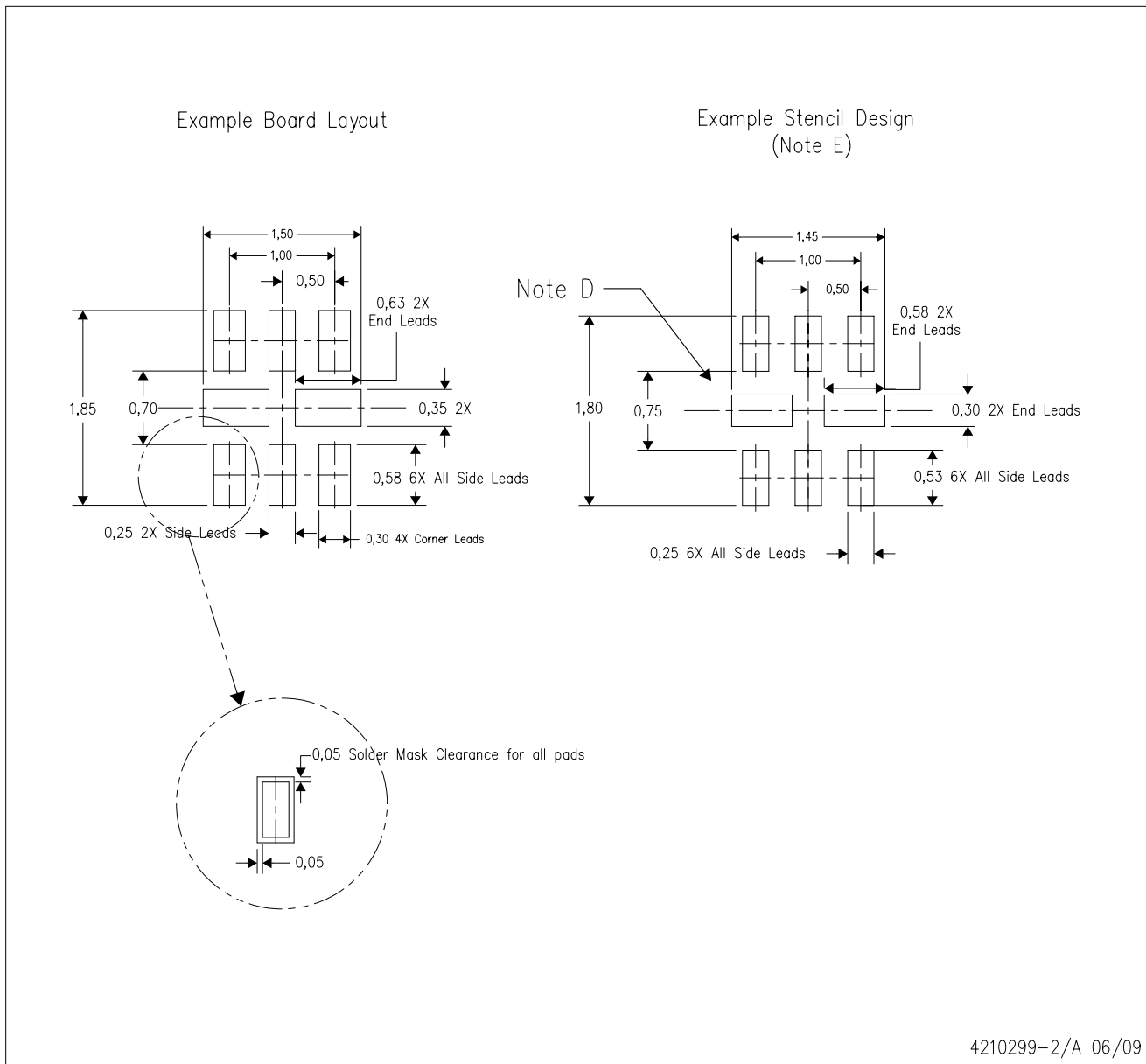
PLASTIC QUAD FLATPACK



4208528-2/B 04/2008

- NOTES:
- A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
  - B. This drawing is subject to change without notice.
  - C. QFN (Quad Flatpack No-Lead) package configuration.
  - D. This package complies to JEDEC MO-288 variation X2ECD.

RUG (R-PQFP-N8)



4210299-2/A 06/09

- NOTES:
- A. All linear dimensions are in millimeters.
  - B. This drawing is subject to change without notice.
  - C. Publication IPC-7351 is recommended for alternate designs.
  - D. Customers should contact their board fabrication site for minimum solder mask web tolerances between signal pads.
  - E. Maximum stencil thickness 0,127 mm (5 mils). All linear dimensions are in millimeters.
  - F. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
  - G. Side aperture dimensions over-print land for acceptable area ratio > 0.66. Customer may reduce side aperture dimensions if stencil manufacturing process allows for sufficient release at smaller opening.

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