









#### **[LMK03806](https://www.ti.com.cn/product/cn/lmk03806?qgpn=lmk03806)**

[ZHCSHU9K](https://www.ti.com.cn/cn/lit/pdf/ZHCSHU9) – SEPTEMBER 2011 – REVISED DECEMBER 2023

# 具有 **14** 个可编程输出的 **LMK03806** 超低抖动时钟发生器

## **1** 特性

高性能、超低抖动时钟发生器

**INSTRUMENTS** 

低抖动:

<span id="page-0-0"></span>**7 TEXAS** 

- 输出频率为 312.5MHz 时抖动小于 50fs (1.875MHz – 20MHz)
- 输出频率为 312.5MHz 时抖动小于 150fs (12kHz – 20MHz)
- 从低成本晶体或外部时钟生成多个时钟
- 14 路可编程输出格式(LVDS、LVPECL、 CMOS)的输出
- 多达 8 个独特输出频率。
- 工业温度范围:–40°C 至 85°C
- 可调 VCO 频率:2.37 GHz 2.6 GHz
- 可编程分频器从低成本晶体生成多个时钟。
- 工作电压范围为 3.15V 至 3.45V

## **2** 应用

- SONET/SDH 中的超高速串行接口
- 千兆位级以太网和光纤通道线卡
- 用于 RAN 应用的基带单元 (BBU)
- GPON OLT/ONU、高速串行接口(如 PCIe、 XAUI、SATA、SAS)
- 时钟 ADC 和 DAC
- 时钟 DSP、微处理器和 FPGA

## **3** 描述

LMK03806 器件是一款高性能、超低抖动、多速率时 钟发生器,能够在频率高达 2.6GHz 的条件下针对 14 路输出合成 8 个不同的频率。每个输出时钟可设定为 LVDS、LVPECL 或 LVCMOS 格式。LMK03806 集成 了高性能的整数 N PLL、低噪声 VCO 和可编程输出分 频器,能够以低成本的晶体为 SONET、以太网、光纤 通道、XAUI、背板、PCIe、SATA 和网络处理器生成 多个参考时钟。

#### 封装信息



(1) 有关所有可用封装,请参阅节 [12](#page-60-0)。

(2) 封装尺寸(长 × 宽)为标称值,并包括引脚(如适用)。



功能方框图





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## **4 Pin Configuration and Functions**











## 表 **4-1. Pin Functions** (续)



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## **5 Specifications**

## **5.1 Absolute Maximum Ratings**

See (1) (3) .



(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) Never to exceed 3.6 V.

(3) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/Distributors for availability and specifications.

## **5.2 ESD Ratings**



(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process. Manufacturing with less than 500-V HBM is possible with the necessary precautions. Pins listed as ±2000 V may actually have higher performance.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process. Manufacturing with less than 250-V CDM is possible with the necessary precautions. Pins listed as ±750 V may actually have higher performance.

### **5.3 Recommended Operating Conditions**





## <span id="page-5-0"></span>**5.4 Thermal Information**



(1) For more information about traditional and new thermal metrics, see the *Semiconductors and IC Package Thermal Metrics* application report ([SPRA953\)](https://www.ti.com/lit/pdf/spra953).

(2) Specification assumes 32 thermal vias connect the die attach pad to the embedded copper plane on the 4-layer JEDEC PCB. These vias play a key role in improving the thermal performance of the WQFN. Note that the JEDEC PCB is a standard thermal measurement PCB and does not represent best performance a PCB can achieve. TI recommends that the maximum number of vias be used in the board layout. R  $_{\theta$  JA is unique for each PCB.

(3) Case is defined as the DAP (die attach pad)

## **5.5 Electrical Characteristics**

3.15 V  $\leqslant$  V<sub>CC</sub>  $\leqslant$  3.45 V,  $\,$  - 40°C  $\leqslant$  T<sub>A</sub>  $\leqslant$  85°C, Junction Temperature T $_{\textrm{J}}$   $\leqslant$  125°C.

Typical values represent most likely parametric norms at V<sub>CC</sub> = 3.3 V, T<sub>A</sub> = 25°C, at *[Recommended Operating Conditions](#page-4-0)* at the time of product characterization and are not ensured.<sup>[\(3\)](#page-12-0)</sup>





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<span id="page-12-0"></span>

3.15 V  $\leq$  V<sub>CC</sub>  $\leq$  3.45 V,  $-$  40°C  $\leq$  T<sub>A</sub>  $\leq$  85°C, Junction Temperature T<sub>J</sub>  $\leq$  125°C.

Typical values represent most likely parametric norms at  $V_{CC}$  = 3.3 V,  $T_A$  = 25°C, at *[Recommended Operating Conditions](#page-4-0)* at the time of product characterization and are not ensured.<sup>(3)</sup>



(1) If emitter resistors are placed on the OSCout1/1\* pins, there will be a DC current to ground which will cause powerdown Icc to increase.

(2) Load conditions for output clocks: LVDS: 100 Ω differential. See *[Current Consumption and Power Dissipation Calculations](#page-36-0)* for Icc for specific part configuration and how to calculate Icc for a specific design.

- (3) In order to meet the jitter performance listed in the subsequent sections of this data sheet, the minimum recommended slew rate for all input clocks is 0.5 V/ns. This is especially true for single-ended clocks. Phase noise performance will begin to degrade as the clock input slew rate is reduced. However, the device will function at slew rates down to the minimum listed. When compared to single-ended clocks, differential clocks (LVDS, LVPECL) will be less susceptible to degradation in phase noise performance at lower slew rates due to their common mode noise rejection. However, it is also recommended to use the highest possible slew rate for differential clocks to achieve optimal phase noise performance at the device outputs.
- (4)  $F_{\text{OSC}}$  maximum frequency guaranteed by characterization. Production tested at 200 MHz.
- (5) A specification in modeling PLL in-band phase noise is the 1/f flicker noise,  $L_{PLL}$  flicker(f), which is dominant close to the carrier. Flicker noise has a 10 dB/decade slope. PN10kHz is normalized to a 10 kHz offset and a 1 GHz carrier frequency. PN10kHz = L<sub>PLL</sub> flicker<sup>(10</sup>) kHz) - 20log(Fout / 1 GHz), where L<sub>PLL</sub> flicker(f) is the single side band phase noise of only the flicker noise's contribution to total noise, L(f). To measure L<sub>PLL\_flicker</sub>(f) it is important to be on the 10 dB/decade slope close to the carrier. A high compare frequency and a clean crystal are important to isolating this noise source from the total phase noise,  $L(f)$ . L<sub>PLL flicker</sub>(f) can be masked by the reference oscillator performance if a low power or noisy source is used. The total PLL in-band phase noise performance is the sum of  $L_{PLL}$  flicker(f) and  $L_{PLL}$  flat(f).
- (6) A specification modeling PLL in-band phase noise. The normalized phase noise contribution of the PLL, L<sub>PLL</sub>  $_{\text{flat}}(f)$ , is defined as: PN1HZ=L<sub>PLL\_flat</sub>(f) - 20log(N) - 10log(f<sub>PD</sub>). L<sub>PLL\_flat</sub>(f) is the single side band phase noise measured at an offset frequency, f, in a 1 Hz bandwidth and f<sub>PD</sub> is the phase detector frequency of the synthesizer. L<sub>PLL</sub> flat(f) contributes to the total noise, L(f).
- (7) Maximum Allowable Temperature Drift for Continuous Lock is how far the temperature can drift in either direction from the value it was at the time that the R30 register was last programmed, and still have the part stay in lock. The action of programming the R30 register, even to the same value, activates a frequency calibration routine. This implies the part will work over the entire frequency range, but if the temperature drifts more than the maximum allowable drift for continuous lock, then it will be necessary to reload the R30 register to ensure it stays in lock. Regardless of what temperature the part was initially programmed at, the temperature can never drift outside the frequency range of -40°C to 85°C without violating specifications.
- (8) Equal loading and identical clock output configuration on each clock output is required for specification to be valid.
- (9) Guaranteed by characterization.
- (10) Jitter and phase noise data for 100 MHz, 156.25, and 312.5 MHz collected using an ECS crystal, part number ECS-200-20-30B-DU. Loop filter values are C1 = 220 pF, C2 = 18 nF, R2 = 820  $\Omega$ , C3 = 10 pF, R3 = 200  $\Omega$ , C4 = 10 pF, R4 = 200  $\Omega$ . Charge pump current = 3.2 mA. LVPECL emitter resistors,  $R_e$  = 240 Ω. Reference doubler disabled. VCO frequency = 2500 MHz using a phase detector frequency = 20 MHz the loop bandwidth =  $62$  kHz and phase margin =  $76^{\circ}$ .
- (11) Jitter and phase noise data for 106.25 MHz collected using an ECS crystal, part number ECS-200-20-30B-DU. Loop filter values are  $C1 = 220$  pF,  $C2 = 18$  nF, R2 = 820  $\Omega$ ,  $C3 = 10$  pF, R3 = 200  $\Omega$ , C4 = 10 pF, R4 = 200  $\Omega$ . Charge pump current = 3.2 mA. LVPECL emitter resistors,  $R_e$  = 240  $\Omega$ . Reference doubler disabled. VCO frequency = 2550 MHz using a phase detector frequency = 10 MHz the loop bandwidth = 32 kHz and phase margin =  $69^{\circ}$ .
- (12) Jitter and phase noise data for 622.08 MHz collected using a Vectron crystal, part number VXB1-1137-15M360. Loop filter values are  $C1 = 100$  pF,  $C2 = 120$  nF, R2 = 470  $\Omega$ ,  $C3 = 10$  pF, R3 = 200  $\Omega$ ,  $C4 = 10$  pF, R4 = 200  $\Omega$ . Charge pump current = 3.2 mA. LVPECL emitter resistors,  $R_e = 240 \Omega$ . Reference doubler enabled. VCO frequency = 2488.32 MHz using a phase detector frequency = 30.72 MHz the loop bandwidth = 54 kHz and phase margin =  $86^{\circ}$ .
- (13) Refer to typical performance charts for output operation performance at higher frequencies than the minimum maximum output frequency.
- (14) Jitter and phase noise data for 100 MHz, 156.25, and 312.5 MHz collected using a Wenzel crystal oscillator, part number 501– 04623G. Loop filter values are C1 = 39 pF, C2 = 3.3 nF, R2 = 680 Ω, C3 = 10 pF, R3 = 200 Ω, C4 = 10 pF, R4 = 200 Ω. Charge pump current = 3.2 mA. LVPECL emitter resistors,  $R_e$  = 240 Ω. Reference doubler disabled. VCO frequency = 2500 MHz using a phase detector frequency = 100 MHz the loop bandwidth = 80 kHz and phase margin =  $60^{\circ}$ .
- (15) Jitter and phase noise data for 106.25 MHz collected using a Wenzel crystal oscillator, part number 501–04623G. Loop filter values are C1 = 39pF, C2 = 3.3 nF, R2 = 820 Ω, C3 = 10 pF, R3 = 200 Ω, C4 = 10 pF, R4 = 200 Ω. Charge pump current = 3.2 mA. LVPECL



<span id="page-13-0"></span>emitter resistors,  $R_e$  = 240  $\Omega$ . Reference doubler disabled. VCO frequency = 2550 MHz using a phase detector frequency = 10 MHz the loop bandwidth = 80 kHz and phase margin =  $60^{\circ}$ .

(16) Jitter and phase noise data for 622.08 MHz collected using a Crystec oscillator, part number CVHD-950. Loop filter values are C1 = 39 pF, C2 = 3.3 nF, R2 = 680 Ω, C3 = 10 pF, R3 = 200 Ω, C4 = 10 pF, R4 = 200 Ω. Charge pump current = 3.2 mA. LVPECL emitter resistors, R<sub>e</sub> = 240 Ω. Reference doubler enabled. VCO frequency = 2488.32 MHz using a phase detector frequency = 30.72 MHz the loop bandwidth = 80 kHz and phase margin =  $60^{\circ}$ .

## **5.6 Timing Requirements**

See *[Programming](#page-21-0)* for additional information





图 **5-1. MICROWIRE Timing Diagram**

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## **5.7 Typical Characteristics**

### **Clock Output AC Characteristics**





## <span id="page-15-0"></span>**6 Parameter Measurement Information**

## **6.1 Differential Voltage Measurement Terminology**

The differential voltage of a differential signal can be described by two different definitions causing confusion when reading data sheets or communicating with other engineers. This section will address the measurement and description of a differential signal so that the reader will be able to understand and discern between the two different definitions when used.

The first definition used to describe a differential signal is the absolute value of the voltage potential between the inverting and noninverting signal. The symbol for this first measurement is typically  $V_{ID}$  or  $V_{OD}$  depending on if an input or output voltage is being described.

The second definition used to describe a differential signal is to measure the potential of the noninverting signal with respect to the inverting signal. The symbol for this second measurement is  $V_{SS}$  and is a calculated parameter. Nowhere in the IC does this signal exist with respect to ground, it only exists in reference to its differential pair.  $V_{SS}$  can be measured directly by oscilloscopes with floating references, otherwise this value can be calculated as twice the value of  $V_{OD}$  as described in the first description.

图 6-1 shows the two different definitions side-by-side for inputs and 图 6-2 shows the two different definitions side-by-side for outputs. The V<sub>ID</sub> and V<sub>OD</sub> definitions show V<sub>A</sub> and V<sub>B</sub> DC levels that the noninverting and inverting signals toggle between with respect to ground.  $V_{SS}$  input and output definitions show that if the inverting signal is considered the voltage potential reference, the noninverting signal voltage potential is now increasing and decreasing above and below the noninverting reference. Thus the peak-to-peak voltage of the differential signal can be measured.

 $V_{\text{ID}}$  and  $V_{\text{OD}}$  are often defined as volts (V) and  $V_{\text{SS}}$  is often defined as volts peak-to-peak (V<sub>PP</sub>).



图 **6-1. Two Different Definitions for Differential Input Signals**



### 图 **6-2. Two Different Definitions for Differential Output Signals**

Refer to application note AN-912, *Common Data Transmission Parameters and their Definitions* ([SNLA036\)](https://www.ti.com/lit/pdf/SNLA036) for more information.

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## **7 Detailed Description**

## **7.1 Overview**

The LMK03806 is an ultra-low-noise clock generator that integrates a high-performance integer-N PLL, lownoise VCO, and flexible output clock division/fan-out with 14 programmable drivers. It operates with a standard off-the-shelf crystal or low noise external clock as the reference oscillator input (OSCin).

The integrated VCO tuning range is from 2370 to 2600 MHz. The VCO clock drives 6 output dividers that support a divide range of 1 to 1045 (even and odd) with 50% output duty cycle. Each output divider feeds 2 output drivers for a total of 12 CLKoutX outputs. Each CLKoutX driver is programmable to LVDS, LVPECL, or 2x LVCMOS 3.3-V output levels and synchronized by means of the SYNC input pin.

The device provides 2 additional outputs (OSCout0 and OSCout1) that are buffered or divided-down copies of the OSCin input. The divide value for the OSCoutX outputs can be set independently by programming the OSC divider. The OSC divider value range is 1 to 8. The OSCout0 driver is programmable to LVDS, LVPECL or 2x LVCMOS 3.3-V output levels. The OSCout1 driver supports LVPECL output levels only.

The LMK03806 has programmable 3rd and 4th order loop filter resistors and capacitors for the internal PLL. The integrated programmable resistors and capacitors compliment external loop filter components mounted near the chip. These integrated components can be disabled through register programming. The device registers are programmable through serial Microwire interface.

### **7.2 Functional Block Diagrams**

图 7-1 shows the complete LMK03806 block diagram.







图 **7-2. 10-Gigabit Ethernet Reference Clocks**



图 **7-3. Fiber Channel Reference Clocks**

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图 **7-4. SONET/SDH Reference Clocks**

## **7.3 Features Description**

### **7.3.1 Serial MICROWIRE Timing Diagram and Terminology**

Register programming information on the DATAuWire pin is clocked into a shift register on each rising edge of the CLKuWire signal. On the rising edge of the LEuWire signal, the register is sent from the shift register to the register addressed. A few programming considerations are listed below:

- A slew rate of at least 30 V/us is recommended for the programming signals
- After the programming is complete, the CLKuWire, DATAuWire, and LEuWire signals should be returned to a low state
- If the CLKuWire or DATAuWire lines are toggled while the VCO is in lock, as is sometimes the case when these lines are shared with other parts, the phase noise may be degraded during this programming.

### **7.3.2 Crystal Support With Buffered Outputs**

The LMK03806 provides 2 dedicated outputs which are a buffered copy of the PLL reference input. This reference input is typically a low noise external clock or Crystal.

The OSCout0 buffer output type is programmable to LVDS, LVPECL, or LVCMOS. The OSCout1 buffer is fixed to LVPECL.

The dedicated output buffers OSCout0 and OSCout1 can output frequency lower than the Input frequency by programming the OSC Divider. The OSC Divider value range is 1 to 8. Each OSCoutX can individually choose to use the OSC Divider output or to bypass the OSC Divider.

Crystal buffered outputs cannot be synchronized to the VCO clock distribution outputs. The assertion of SYNC will still cause these outputs to become low. Since these outputs will turn off and on asynchronously with respect to the VCO sourced clock outputs during a SYNC, it is possible for glitches to occur on the buffered clock outputs when SYNC is asserted and unasserted. If the NO\_SYNC\_CLKoutX\_Y bits are set these outputs will not be affected by the SYNC event except that the phase relationship will change with the other synchronized clocks unless a buffered clock output is used as a qualification clock during SYNC.

#### **7.3.3 Integrated Loop Filter Poles**

The LMK03806 features programmable 3rd and 4th order loop filter poles for PLL. These internal resistors and capacitor values may be selected from a fixed range of values to achieve either a 3rd or 4th order loop filter



<span id="page-19-0"></span>response. The integrated programmable resistors and capacitors compliment external components mounted near the chip.

These integrated components can be effectively disabled by programming the integrated resistors and capacitors to their minimum values.

#### **7.3.4 Integrated VCO**

The output of the internal VCO is routed to the Clock Distribution Path and also fed back to the PLL phase detector through a prescaler and N-divider.

#### **7.3.5 Clock Distribution**

The LMK03806 features a total of 12 outputs driven from the internal VCO.

All VCO driven outputs have programmable output types. They can be programmed to LVPECL, LVDS, or LVCMOS. When all distribution outputs are configured for LVCMOS or single-ended LVPECL a total of 24 outputs are available.

#### *7.3.5.1 CLKout DIvider*

Each clock group, which is a pair of outputs such as CLKout0 and CLKout1, has a single clock output divider. The divider supports a divide range of 1 to 1045 (even and odd) with 50% output duty cycle. When divides of 26 or greater are used, the divider block uses extended mode.

#### *7.3.5.2 Programmable Output Type*

For increased flexibility all LMK03806 clock outputs (CLKoutX) and OSCout0 can be programmed to an LVDS, LVPECL, or LVCMOS output type. OSCout1 is fixed as LVPECL.

Any LVPECL output type can be programmed to 700-, 1200-, 1600-, or 2000-mVpp amplitude levels. The 2000 mVpp LVPECL output type is a Texas Instruments proprietary configuration that produces a 2000-mVpp differential swing for compatibility with many data converters and is also known as 2VPECL.

#### *7.3.5.3 Clock Output Synchronization*

Using the SYNC input causes all active clock outputs to share a rising edge.

By toggling the SYNC\_POL\_INV bit, it is possible to generate a SYNC through uWire eliminating the need for connecting the external SYNC pin to external circuitry.

#### **7.3.6 Default Start-Up Clocks**

Before the LMK03806 is programmed some clocks will operate at default frequencies upon power up. The active output clocks depend upon the reference input type. If a crystal reference is used with OSCin, only CLKout8 will operate at a nominal VCO frequency /25. When an XO or other external reference is used as a reference with OSCin, OSCout0 will buffer the OSCin frequency in addition to CLKout8 operating at a nominal VCO frequency /25. These clocks can be used to clock external devices such as microcontrollers, FPGAs, CPLDs, and so forth, before the LMK03806 is programmed. Refer to  $\mathbb{R}$  [7-5](#page-20-0) or  $\mathbb{R}$  [7-6](#page-20-0) for illustration of start-up clocks.

The nominal VCO frequency of CLKout8 on power up will typically be 98 MHz.

Note during programming CLKout8 may momentarily stop or glitch during the VCO calibration routine.

<span id="page-20-0"></span>



图 **7-5. Start-Up Clock Using Crystal Reference**



图 **7-6. Start-Up Clock Using XO or Other External Reference**

## **7.4 Device Functional Modes**

By using the tunable range of the VCO followed by a programmable divider, the LMK03806 can achieve any of the frequencies in  $\bar{\mathcal{R}}$  7-1.

<b>OUTPUT DIVIDER VALUE</b>	<b>ACHIEVED FREQUENCY (MHZ)</b>
	2370 - 2600
$\overline{2}$	1185 - 1300
3	790 - 866.7
4	$592.5 - 650$
5	474 - 520
6	395.7 - 433
7	338.6 - 371.4
8	296.25 - 325
9	263.3 - 288.9
10	237 - 260
11 to 1045	Any frequency in the range of 2.27 - 236.36

表 **7-1. Achievable Frequencies**

## 表 **7-2. Common Frequency Plans**





## <span id="page-21-0"></span>**7.5 Programming**

### **7.5.1 General Information**

LMK03806 devices are programmed using 32-bit registers. Each register consists of a 5-bit address field and 27 bit data field. The address field is formed by bits 0 through 4 (LSBs) and the data field is formed by bits 5 through 31 (MSBs). The contents of each register is clocked in MSB first (bit 31), and the LSB (bit 0) last. During programming, the LEuWire signal should be held *low*. The serial data is clocked in on the rising edge of the CLKuWire signal. After the LSB (bit 0) is clocked in the LEuWire signal should be toggled *low*-to-*high*-to-*low* to latch the contents into the register selected in the address field. TI recommends to program registers in numeric order, for example R0 to R14, R16, R24, R26, and R28 to R31 to achieve proper device operation. Refer to the *[Timing Requirements](#page-13-0)* for the timing for the programming.

To achieve proper frequency calibration, the OSCin port must be driven with a valid signal before programming register R30. Changes to PLL R divider or the OSCin port frequency require register R30 to be reloaded in order to activate the frequency calibration process.

### *7.5.1.1 Special Programming Case for R0 to R5 for CLKoutX\_Y\_DIV > 25*

When programming register R0 to R5 to change the CLKoutX\_Y\_DIV divide value, the register must be programmed twice if the CLKoutX\_Y\_DIV value is greater than 25.

### *7.5.1.2 Recommended Initial Programming Sequence*

The registers are to be programmed in numeric order with R0 being the first and R31 being the last register programmed as shown below:

- 1. Program R0 with RESET bit = 1. This ensures that the device is configured with default settings. When RESET = 1, all other R0 bits are ignored.
	- If R0 is programmed again during the initial configuration of the device, the RESET bit must be cleared.
- 2. R0 through R5: CLKouts.
	- It is required to program R3 after power up.
	- Program as necessary to configure the clock outputs, CLKout0 to CLKout11 as desired. These registers configure clock output controls such as powerdown, divider value, and clock source select.
- 3. R6 through R8: CLKouts.
	- Program as necessary to configure the clock outputs, CLKout0 to CLKout11 as desired. These registers configure the output format for each clock output.
- 4. R9: Undisclosed bits.
	- Program this register as shown in the register map for proper operation.
- 5. R10: OSCouts.
- 6. R11: SYNC, and XTAL.
- 7. R12: LD pin and SYNC.
- 8. R13: Readback pin & GPout0.
- 9. R14: GPout1.
- 10. R16: Undisclosed bits.
	- Program this register as shown in the register map for proper operation.
- 11. R24: Partially integrated PLL filter values.
- 12. R26, R28, R29, and R30: PLL.
- 13. R31: uWire readback and uWire lock.

<span id="page-22-0"></span>

## *7.5.1.3 READBACK*

At no time should the MICROWIRE registers be programmed to any value other than what is specified in the datasheet.

For debug of the MICROWIRE interface or programming, TI recommends to simply program an LD\_MUX to active low and then toggle the output type register between output and inverting output while observing the output pin for a low to high transition. For example, to verify MICROWIRE programming, set the LD\_MUX = 0 (Low) and then toggle the LD\_TYPE register between 3 (Output, push-pull) and 4 (Output inverted, pushpull). The result will be that the Ftest/LD pin will toggle from low to high.

Readback from the MICROWIRE programming registers is available. The MICROWIRE readback function can be accessed on the Readback pin. The READBACK\_TYPE register can be programmed to *Output (push-pull)*  for active output, or for communication with FPGAs/microcontrollers with lower voltage rails than 3.3 V the READBACK\_TYPE register can be programmed to *Output (Open-Drain)* while connecting an external pull-up resistor to the voltage rail needed.

To perform a readback operation:

- 1. Write the register address to be read back by programming the READBACK\_ADDR register in R31.
- 2. With the LEuWire pin held low continue to clock the CLKuWire pin. On every falling edge of the CLKuWire pin a new data bit is clocked onto the Readback pin.
- 3. Data is clocked out MSB first. After 32 clocks all the data values will have been read and the read operation is complete. The 5 LSB bits which are the address will be undefined during readback.

#### **7.5.1.3.1 Readback Example**

To readback register R3 perform the following steps:

- 1. Write R31 with READBACK\_ADDR = 3. DATAuWire and CLKuWire are toggled as shown in  $\overline{8}$  [5-1](#page-13-0) with new data being clocked in on rising edges of CLKuWire
- 2. Toggle LEuWire high and low as shown in  $\overline{\otimes}$  [5-1.](#page-13-0)
- 3. Toggle CLKuWire high and then low 32 times to read back all 32 bits of register R3. Data is read MSB first. Data is valid on falling edge of CLKuWire.



## <span id="page-23-0"></span>**8 Application and Implementation**

备注

以下应用部分中的信息不属于 TI 器件规格的范围,TI 不担保其准确性和完整性。TI 的客 户应负责确定 器件是否适用于其应用。客户应验证并测试其设计,以确保系统功能。

## **8.1 Application Information**

#### **8.1.1 Crystal Interface**

The LMK03806 has an integrated crystal oscillator circuit on that supports a fundamental mode, AT-cut crystal. The crystal interface is shown in  $\boxed{8}$  8-1.



图 **8-1. Crystal Interface**

The load capacitance  $(C_L)$  is specific to the crystal, but usually on the order of 18 - 20 pF. While  $C_L$  is specified for the crystal, the OSCin input capacitance  $(C_{1N} = 6$  pF typical) of the device and PCB stray capacitance (C<sub>STRAY</sub> approximately 1 pF to 3 pF) can affect the discrete load capacitor values,  $C_1$  and  $C_2$ .

For the parallel resonant circuit, the discrete capacitor values can be calculated as follows:

$$
C_{L} = (C_{1} \times C_{2}) / (C_{1} + C_{2}) + C_{IN} + C_{STRAY}
$$
\n(1)

Typically, C<sub>1</sub> = C<sub>2</sub> for optimum symmetry, so 方程式 1 can be rewritten in terms of C<sub>1</sub> only:

$$
C_{L} = C_{1}^{2} / (2 \times C_{1}) + C_{IN} + C_{STRAY}
$$
 (2)

Finally, solve for  $C_1$ :

$$
C_1 = (C_L - C_{IN} - C_{STRAY}) \times 2 \tag{3}
$$

*[Electrical Characteristics](#page-5-0)* provides crystal interface specifications with conditions that ensure start-up of the crystal, but it does not specify crystal power dissipation. The designer will need to ensure the crystal power dissipation does not exceed the maximum drive level specified by the crystal manufacturer. Overdriving the crystal can cause premature aging, frequency shift, and eventual failure. Drive level should be held at a sufficient level necessary to start-up and maintain steady-state operation.

The power dissipated in the crystal,  $P_{\text{XTAL}}$ , can be computed by:

$$
P_{\text{XTAL}} = I_{\text{RMS}}^2 \times R_{\text{ESR}} \times (1 + C_0/C_L)^2 \tag{4}
$$

where

- $I<sub>RMS</sub>$  is the RMS current through the crystal.
- $R<sub>ESR</sub>$  is the maximum equivalent series resistance specified for the crystal
- $C_L$  is the load capacitance specified for the crystal
- $C_0$  is the minimum shunt capacitance specified for the crystal

<span id="page-24-0"></span>

I<sub>RMS</sub> can be measured using a current probe (for example, Tektronix CT-6 or equivalent) placed on the leg of the crystal connected to OSCin\* with the oscillation circuit active.

As shown in  $\boxtimes$  [8-1](#page-23-0), an external resistor, R<sub>LIM</sub>, can be used to limit the crystal drive level, if necessary. If the power dissipated in the selected crystal is higher than the drive level specified for the crystal with  $R_{LM}$  shorted, then a larger resistor value is mandatory to avoid overdriving the crystal. However, if the power dissipated in the crystal is less than the drive level with  $R_{LIM}$  shorted, then a zero value for  $R_{LIM}$  can be used. As a starting point, a suggested value for R<sub>LIM</sub> is 1.5 kΩ.

#### **8.1.2 Driving OSCin Pins With a Single-Ended Source**

The LMK03806 has an the ability to be driven by an external reference. Typical external reference interfaces are shown in  $\overline{8}$  8-2 and  $\overline{8}$  8-3.

In applications where the external reference amplitude is less than the V<sub>OSCin</sub> specification of 2.4 V<sub>pp</sub>  $\&$  8-2 is an appropriate method of interfacing the reference to the LMK03806.

In applications where the external reference amplitude is greater than the V<sub>OSCin</sub> specification of 2.4 V<sub>pp</sub>  $\boxtimes$  8-3 is an appropriate method of interfacing the reference to the LMK03806.

In both cases C1 and C2 should be present a low impedance at the reference frequency. A typical value for C1 and C2 is 0.1 µF.





图 **8-3. 3.3 Vpp External Reference Interface**

Using an external reference, such as a crystal oscillator (XO), may provide better phase noise than a crystal at offsets below the loop bandwidth. If the jitter integration bandwidth for the application of interest is above the loop filter bandwidth, the added phase noise of a crystal will not be a significant jitter contributor and may be a more cost effective solution than an XO. Also, operating at higher reference frequencies allows higher phase detector frequencies, which also improves in band PLL phase noise performance.

#### **8.1.3 Driving OSCin Pins With a Differential Source**

The OSCin port can be driven by differential signals. The LMK03806 internally biases the input pins so the differential interface should be AC coupled. The recommended circuits for driving the OSCin pins with either LVDS or LVPECL are shown below.



图 **8-4. OSCin/OSCin\* Termination for an LVDS Reference Clock Source**

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<span id="page-25-0"></span>

## 图 **8-5. OSCin/OSCin\* Termination for an LVPECL Reference Clock Source**

### **8.1.4 Frequency Planning With the LMK03806**

Calculating the value of the output dividers is simple due to the architecture of the LMK03806. That is, the clock output dividers allow for even and odd output divide values from 2 to 1045. The procedure for determining the PLL and clock output divider values for a set of clock output frequencies is straightforward.

- 1. Calculate the least common multiple (LCM) of the clock output frequencies.
- 2. Determine which VCO frequency will support the target clock output frequencies given the LCM.
- 3. Determine the clock output divide values based on VCO frequency.
- 4. Determine the PLL divider values VCO\_DIV, PLL\_P, PLL\_N, and PLL\_R to allow the VCO frequency to lock to the OSCin frequency. For best in-band PLL noise, try to maximize the PLL phase detector frequency by using the smallest PLL divider values and enabling the PLL doubler.

For example, given the following target output frequencies: 156.25 MHz, 125 MHz, 100 MHz, and 25 MHz with a OSCin frequency of 20 MHz:

- 1. Determine the LCM of the three frequencies. LCM(156.25, 125, 100, 25) = 2500 MHz. The LCM frequency is the lowest frequency for which all of the target output frequencies are integer divisors of the LCM. Note: if there is one frequency which causes the LCM to be very large, greater than 2.6 GHz for example, determine if there is a single frequency requirement which causes this. It may be possible to select the crystal frequency to satisfy this frequency requirement through OSCout or CLKout6/7/8/9 driven by OSCin. In this way it is possible to get non-integer related frequencies at the outputs.
- 2. Multiply the LCM frequency by an integer value that causes the product (LCM × X) to fall into the valid VCO frequency range from 2370 to 2600 MHz. In this case, the LCM frequency of 2500 MHz is already within the VCO frequency.
- 3. Continuing the example by using a VCO frequency of 2500 MHz, the CLKout dividers can be calculated by simply dividing the VCO frequency by the output frequency. To output 156.25 MHz, 125 MHz, 100 MHz, and 25 MHz, the output dividers will be 16, 20, 25, and 100, respectively.
	- a. 2500 MHz / 156.25 MHz = 16
	- b. 2500 MHz / 125 MHz = 20
	- c. 2500 MHz / 100 MHz = 25
	- d. 2500 MHz / 25 MHz = 100
- 4. The PLL must be locked to its input reference. Refer to *Configuring the PLL* for more information on this topic. By programming the clock output dividers and the PLL dividers, the VCO can be locked to 2500 MHz and the clock outputs dividers can each divide-down the VCO frequency to the achieve the target output frequencies.

Refer to Application Note AN-1865, Frequency Synthesis and Planning for PLL Architectures (SNAA061) for more information on this topic and LCM calculations.

### **8.1.5 Configuring the PLL**

For the PLL to operate in closed-loop mode, the following relationships in Equations 5 and 6 must be satisfied to ensure the PLL phase detector input frequencies for the reference and feedback paths are equal.

 $F_{pd} = F_{osc} \times PLL_D / PLL_R$  (PLL reference path) (5)

$$
F_{\text{pd}} = F_{\text{vco}} / (PLL_P \times PL_N) (PL feedback path)
$$
 (6)

where

- $F_{pd}$  = PLL phase detector frequency ( $F_{pd} \le 155$  MHz)
- $F_{\text{oscin}}$  = OSCin reference frequency ( $F_{\text{osc}} \le 500$  MHz)
- $\cdot$  F<sub>vco</sub> = VCO frequency (VCO tuning range = 2370 to 2600 MHz)
- PLL  $D = PLL$  reference doubler mode (Disabled = 1, Enabled = 2)
- PLL  $R = PLL$  reference divider (values = 1 to 4095)
- PLL\_P = PLL N prescaler divider (values =  $2$  to  $8$ )
- PLL  $N = PLL N$  divider (values = 1 to 262143)

## 备注

When  $F_{\text{OSC}_{in}}$  and  $F_{\text{pd}}$  are equal, the best PLL in-band noise can be achieved with the PLL reference doubler enabled (EN\_PLL\_REF\_2X=1) and the PLL reference divider is 2 (PLL\_R =2), rather than with the doubler disabled (EN\_PLL\_REF\_2X=0) and PLL reference divider of 1 (PLL\_R=1).

The output frequency is related to  $F_{\text{vco}}$  as follows.

$$
F_{CLKout} = F_{vco} / OUT\_DIV
$$
 (7)

### where

• OUT DIV: Output channel divider (value = 1 to 1045)

## *8.1.5.1 Example PLL Configuration*

Continuing the example above, we are given the target output frequencies of 156.25 MHz, 125 MHz, 100 MHz, and 25 MHz with an OSCin frequency of 20 MHz. As previously calculated, the LCM and  $F_{vco}$  is 2500 MHz.

First, we will consider the PLL reference path. For lowest possible in-band PLL flat noise, we will try to maximize phase detector frequency. In this case, the highest  $F_{pd}$  possible from the reference path is 40 MHz (with the reference doubler enabled, doubling the 20 MHz OSCin). However, since 40 MHz does not divide into 2500 MHz by an integer value (and thus is unable to be reproduced by the PLL feedback path), we are required to use an  $F_{pd}$  of 20 MHz instead, which does divide into 2500 by an integer value of 125. As noted above, when  $F_{OSCin}$ and  $F_{pd}$  are equal, the best PLL in-band noise can be achieved with the PLL reference doubler enabled (EN\_PLL\_REF\_2X=1) and the PLL reference divider is 2 (PLL\_R =2).

Next, we will consider the PLL feedback path. As determined earlier,  $F_{vco}$  is 2500 MHz and  $F_{pd}$  is 20 MHz, which is 2500 MHz divided by 125. The prescaler and N divider settings together must divide  $F_{\text{vco}}$  by 125. Given that the prescaler can be set between 2 to 8 and the N divider can be set between 1 to 262,143, the only setting that would work in this case is a prescaler value of 5 and an N divider value of 25. Note that in a case where multiple configurations are possible, increasing the N divider value will reduce loop filter component sizes.



## <span id="page-27-0"></span>**8.1.6 Digital Lock Detect**

The digital lock detect circuit is used to determine the lock status of the PLL. The flowchart in  $\boxtimes$  8-6 shows the general way this circuit works.



For a digital lock detect event to occur there must be a number of PLL phase detector cycles during which the time/phase error of the PLL\_R reference and PLL\_N feedback signal edges are within the 3.7 ns window size of the LMK03806. *Lock count* is the term which is used to specify how many PLL phase detector cycles have been within the window size of 3.7 ns at any given time. Since there must be a specified number phase detector events before a lock event occurs, a minimum digital lock event time can be calculated as *lock count* / F<sub>pd</sub>.



图 **8-6. Digital Lock Detect Flow Diagram**



A user specified ppm accuracy for lock detect is programmable using a lock count register. By using 方程式 8, values for a *lock count* and *window size* can be chosen to set the frequency accuracy required by the system in ppm before the digital lock detect event occurs. Units of  $F_{pd}$  are Hertz:

$$
ppm = \frac{2e6 \times 3.7 \text{ ns} \times f_{PD}}{PLL\_DLD\_CNT}
$$

(8)

The effect of the *lock count* value is that it shortens the effective lock window size by dividing the *window size* by *lock count*.

If at any time the PLL\_R reference and PLL\_N feedback signals are outside the time window set by *window size*, then the *lock count* value is reset to 0.

For example, we will calculate the minimum PLL digital lock time given a PLL  $F_{\text{pd}}$  of 40 MHz and PLL\_DLD\_CNT  $= 10,000$ . The minimum lock time of PLL will be 10,000 / 40 MHz = 250 µs.



## <span id="page-29-0"></span>**8.2 Typical Application**

Normal use case of the LMK03806 device is as a clock generator. This section will discuss a design example to show the various functional aspects of the LMK03806 device.



图 **8-7. Simplified Functional Block Diagram**

#### **8.2.1 Design Requirements**

A networking line card type application needs a clocking solution for an ASIC, FPGA, CPU, PCIe 3.0 interface, and a 10G PHY. The input clock will be a crystal oscillator. A summary of clock input and output requirements are as follows:

Clock Input:

• 20 MHz oscillator

Clock Outputs:

- 2x 156.25-MHz LVPECL clock for ASIC
- 2x 156.25-MHz LVPECL clock for 10G PHY
- 4x 100-MHz HCSL for PCIe 3.0
- 2x 100-MHz LVDS for FPGA
- 2x 50-MHz LVCMOS for CPU

The following information reviews the steps to produce this design.

#### **8.2.2 Detailed Design Procedure**

Design of all aspects of the LMK03806 is quite involved and software has been written to assist in part selection, part programming, loop filter design, and simulation. This design procedure will give a quick outline of the process.

### 备注

This information is current as of the date of the release of this data sheet. Design tools receive continuous enhancements to add features and improve model accuracy. Refer to software instructions or training for latest features.

- 1. Device Selection
	- The key to device selection is the required  $F_{\text{vco}}$  given the required output frequencies. The device must be able to produce a  $F_{\text{vco}}$  that can be divided down to required output frequencies.
	- The software design tools will take into account the  $F_{\text{vco}}$  range for specific devices based on the application's required output frequencies.
- 2. Device Configuration
	- There are many possible permutations of dividers and other registers to get same output frequencies from a device. However there are some optimizations and trade-offs to be considered.



- If more than one divider is in series, for instance PLL prescaler followed by PLL N divider, it is possible although not assured that some crosstalk/mixing could be created when using some divides.
- The design software normally attempts to maximize  $F_{\text{pd}}$ , use smallest dividers, and maximize PLL charge pump current.
- Refer to *[Configuring the PLL](#page-25-0)* for divider equations to ensure the PLL is locked. The design software is able to configure the device for most cases.
- These guidelines may be followed when configuring PLL related dividers or other related registers:
	- For lowest possible in-band PLL flat noise, maximize  $F_{\text{pd}}$  to minimize N divide value.
	- For lowest possible in-band PLL flat noise, maximize charge pump current. Higher value charge pump currents often yield similar performance.
	- To reduce loop filter component sizes, increase the total feedback divide value (PLL\_P  $\times$  PLL\_N) and/or reduce charge pump current.
	- As rule of thumb, keep  $F_{\text{pd}}$  approximately between 10 × PLL loop bandwidth and 100 × PLL loop bandwidth. An F<sub>pd</sub> value less than 5  $\times$  PLL bandwidth may be unstable and a F<sub>pd</sub> > 100  $\times$  loop bandwidth may experience increased lock time due to cycle slipping.
- 3. PLL Loop Filter Design
	- TI recommends to use Clock Design Tool or Clock Architect to design your loop filter.
	- The Clock Design Tool will return solutions with high reference/phase detector frequencies by default. In the Clock Design Tool the user may choose to increase the reference divider to reduce the  $F_{\text{od}}$  to achieve a narrow loop bandwidth, so it is possible to reduce loop filter capacitor to a practical value.
	- While designing the loop filter, adjusting the charge pump current and/or the total feedback divide value (PLL  $P \times$  PLL N) can help with loop filter component selection. Lower charge pump currents and larger N values result in smaller loop filter capacitor values but at the expense of increased in-band PLL phase noise.
	- More detailed understanding of PLL loop filter design can found in *PLL Performance, Simulation, and Design* ([www.ti.com/tool/pll\\_book](http://www.ti.com/tool/pll_book)).
- 4. Clock Output Assignment
	- At this point of time, the design software does not take into account frequency assignment to specific outputs except to ensure that the output frequencies can be achieved. It is best to consider proximity of each clock output to each other and other PLL circuitry when choosing final clock output locations. Here are some guidelines to help achieve best performance when assigning outputs to specific CLKout/ OSCout pins.
		- Group common frequencies together.
		- PLL charge pump circuitry can cause crosstalk at charge pump frequency. Place outputs sharing charge pump frequency or lower priority outputs that are not sensitive to charge pump frequency spurs together.
- 5. Other device specific configuration. For LMK03806 consider the following:
	- PLL digital lock detect based on programming:
		- There is a digital lock detect circuit which is used to determine the lock status of the PLL. It can also be used to ensure a specific frequency accuracy. A user specified frequency accuracy required to trigger a lock detect event is programmable using a lock count register. Refer to *[Digital Lock Detect](#page-27-0)* for more information.
- 6. Device Programming
	- The software tool CodeLoader for EVM programming can be used to set up the device in the desired configuration, then export a hex register map suitable for use in application. Some additional information on each part of the design procedure for the example is outlined below.

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## *8.2.2.1 Device Selection*

WEBENCH Clock Architect Tool or Clock Design Tool can be used as aids in device selection. Enter the required frequencies and formats into the tools. To find this device, select a solution based on LMK03806B (referring to the evaluation board).

#### **8.2.2.1.1 Clock Architect**

When generating solutions, it is possible to narrow the parts used in the solution by setting the appropriate part filter.

#### **8.2.2.1.2 Clock Design Tool**

In wizard-mode, select Single PLL and fill in the input frequency and desired output frequencies to generate a list of solutions. If the example values are used, the LMK03806 should be listed as the first result.

#### **8.2.2.1.3 Calculation Using LCM**

In this example, the LCM of 156.25 MHz, 100 MHz, and 50 MHz = 2500 MHz. This value is a valid  $F_{vco}$  for the LMK03806. Therefore, it may be used to produce these output frequencies.

#### *8.2.2.2 Device Configuration*

The tools listed above automatically configure the clock solution to meet the input and output frequency requirements given and make assumptions about certain parameters to give default simulation results. The assumptions made are to maximize input frequencies,  $F_{pd}$ , and charge pump currents while minimizing  $F_{vco}$  and divider values. We will also outline the steps for manually configuring the device below for greater flexibility. Note that this procedure is the same as the one outlined in the *[Frequency Planning With the LMK03806](#page-25-0)* and *[Configuring the PLL](#page-25-0)* sections, which can be referenced for a more detailed explanation.

We are given the target output frequencies of 156.25 MHz, 125 MHz, 100 MHz, and 25 MHz with an  $F_{\rm OSCin}$  of 20 MHz. As previously calculated, the LCM and  $F_{\text{vco}}$  is 2500 MHz.

First, we will consider the PLL reference path. For lowest possible in-band PLL flat noise, we will try to maximize  $F_{\text{nd}}$ . 20 MHz is the highest frequency which divides into 2500 MHz by an integer value and which can also be synthesized from  $F_{\rm OSCin}$ . As noted earlier, when  $F_{\rm OSCin}$  and  $f_{\rm od}$  are equal, the best PLL in-band noise can be achieved with the PLL reference doubler enabled (EN\_PLL\_REF\_2X=1) and the PLL reference divider is 2 (PLL  $R = 2$ ).

Next, we will consider the PLL feedback path. As determined earlier,  $F_{vco}$  is 2500 MHz and the  $F_{\text{nd}}$  is 20 MHz, which is 2500 MHz divided by 125. The prescaler and N divider settings together must divide  $F_{\rm vco}$  by 125. The only setting that works in this case is a prescaler value of 5 and an N divider value of 25.

At this point the design meets all input and output frequency requirements and it is possible to design a loop filter for the application and simulate phase noise of the output clocks.

### *8.2.2.3 PLL Loop Filter Design*

At this time, the user may choose to use the simulation tools for more accurate simulations. For example:

- Clock Design Tool allows loading a custom phase noise profile for various blocks. Typically, a custom phase noise plot is entered for OSCin to match the reference phase noise to the device. For improved accuracy in simulation and optimum loop filter design, be sure to load these custom noise profiles for use in application. After loading a phase noise plot, user should recalculate the recommended loop filter design.
- The Clock Design Tool will return solutions with high reference/phase detector frequencies by default. In the Clock Design Tool the user may increase the reference divider to reduce the frequency if desired. For example, if a narrow loop bandwidth is desired, it is possible to reduce  $F_{\text{pd}}$  by increasing the PLL R divider.

Note: Clock Design Tool provides some recommended loop filters upon first loading the simulation. These values are not re-calculated any time PLL related values are changed (for example, input phase noise, charge pump current, divider values, etc.), so it is recommended to re-design the PLL loop filter, either by manually entering desired values, or by using the 'Design a Loop Filter' button in the LOOPFILTER box.



#### **8.2.2.3.1 Example Loop Filter Design**

In the LOOPFILTER box, there are options for displaying a bode plot, simulating phase noise, and re-calculating loop filter values. Selecting the 'Design a Loop Filter' button brings up a window where a target bandwidth and phase margin can be entered and the tool will re-design the loop filter component values to converge to the specified targets. Component values can also be manually entered and the tool will calculate the resulting loop filter parameters.

For this example, a custom phase noise plot was uploaded based on measured data for the reference oscillator input. F<sub>pd</sub> was set to 20 MHz and loop filter was optimized to achieve a loop bandwidth of 62 kHz and phase margin of 76°. The loop filter values used were C1 = 220 pF, C2 = 18 nF, R2 = 820  $\Omega$ , C3 = 10 pF, R3 = 200  $\Omega$ , C4 = 10 pF, and R4 = 200  $\Omega$ . The charge pump current was set to 3.2 mA.

#### *8.2.2.4 Other Device Specific Configuration*

#### **8.2.2.4.1 Digital Lock Detect**

Digital lock time for the PLL will ultimately depend upon the programming of the PLL\_DLD\_CNT register as discussed in *[Digital Lock Detect](#page-27-0)*. Since the PLL F<sub>pd</sub> in this example is 20 MHz, the lock time will = PLL\_DLD\_CNT / 20 MHz. If PLL\_DLD\_CNT is set to 10,000, the lock time will be 0.5 ms. The ppm accuracy required to indicate lock will be (2e6  $\times$  3.7 ns  $\times$   $f_{\text{nd}}$ ) / PLL\_DLD\_CNT, or 14.8 ppm. Refer to *[Digital Lock Detect](#page-27-0)* for more detail on calculating lock times.

#### *8.2.2.5 Device Programming*

The CodeLoader software is used to program the LMK03806B evaluation board using the LMK03806B profile. It also allows the exporting of a register map which can be used to program the device to the user's desired configuration. Once a configuration of dividers has been achieved using the Clock Design Tool to meet the requested input/output frequencies with the desired performance, the CodeLoader software needs to be manually updated with this configuration to meet the required application. At this time no automatic import between the two tools exists.



## **8.2.3 Application Curves**

The following jitter and phase noise data was captured from an LMK03806 evaluation board.  $F_{vco}$  was set to 2500 MHz and F<sub>pd</sub> was set to 20 MHz. In order to obtain a loop bandwidth of 62 kHz and a phase margin of 76°, the loop filter values used were C1 = 220 pF, C2 = 18 nF, R2 = 820 Ω, C3 = 10 pF, R3 = 200 Ω, C4 = 10 pF, and R4 = 200  $\Omega$ . The charge pump current was set to 3.2 mA.





The following PCIe 3.0 phase jitter results were obtained using the Intel Clock Jitter Tool using waveform data captured with an Agilent DSA90804A. The RMS jitter result of 0.107 ps easily meets the PCIe 3.0 jitter requirement of 1ps with significant margin.





## <span id="page-35-0"></span>**8.3 System Examples**

## **8.3.1 System Level Diagram**

 $\boxtimes$  8-13 shows a detailed system level diagram of the example above to serve as a guideline for good practices when designing with the LMK03806.





<span id="page-36-0"></span>

## **8.4 Best Design Practices**

#### **8.4.1 LVCMOS Complementary vs. Non-Complementary Operation**

- TI recommends to use a complementary LVCMOS output format such as LVCMOS (Norm/Inv) to reduce switching noise and crosstalk when using LVCMOS.
- If only a single LVCMOS output is required, the complementary LVCMOS output format can still be used by leaving the unused LVCMOS output floating.
- A non-complimentary format such as LVCMOS (Norm/Norm) is not recommended as increased switching noise is present.

#### **8.4.2 LVPECL Outputs**

When using an LVPECL output it is not recommended to place a capacitor to ground on the output as might be done when using a capacitor input LC lowpass filter. The capacitor will appear as a short to the LVPECL output drivers which are able to supply large amounts of switching current. The effect of the LVPECL sourcing large switching currents can result in the following:

- 1. Large switching currents through the Vcc pin of the LVPECL power supply resulting in more Vcc noise and possible Vcc spikes.
- 2. Large switching currents injected into the ground plane through the capacitor which could couple onto other Vcc pins with bypass capacitors to ground resulting in more Vcc noise and possible Vcc spikes.

#### **8.4.3 Sharing MICROWIRE (SPI) Lines**

When CLKuWire and DATAuWire toggle and an internal VCO mode is used, there may some spurious content on the phase noise plot related to the frequency of the CLKuWire and DATAuWire pins.

#### **8.4.4 SYNC Pin**

If the SYNC pin is connected to a host device (for example, FPGA, CPLD, CPU) with noisy I/O power rails, use small series resistor and shunt capacitor ( $C_{NR}$ ) as shown in  $\&$  [8-13](#page-35-0). An external low-pass filter can prevent noise on the SYNC input from coupling unwanted spurious content to nearby internal analog circuitry.

#### **8.4.5 CLKout Vcc Pins**

Place 0.1-μF capacitors after the ferrite beads and as close as possible to each CLKout Vcc pin (Vcc2, Vcc3, Vcc10, Vcc11, Vcc12, Vcc13) for optimal output performance.

### **8.5 Power Supply Recommendations**

#### **8.5.1 Current Consumption and Power Dissipation Calculations**

From  $\frac{1}{\sqrt{6}}$  [8-1](#page-37-0) the current consumption can be calculated for any configuration.

For example, the current for the entire device with 1 LVDS (CLKout0) and 1 LVPECL 1.6 Vpp with 240-Ω emitter resistors (CLKout1) output active with a clock output divide = 1, and no other features enabled can be calculated by adding up the following blocks: core current, base clock distribution, clock output group, clock divider, one LVDS output buffer current, and one LVPECL output buffer current. There will also be one LVPECL output drawing emitter current, which means some of the power from the current draw of the device is dissipated in the external emitter resistors which doesn't add to the thermal power dissipation budget for the device. In addition to emitter resistor power, power dissipated in the load for LVDS/LVPECL do not contribute to the thermal power dissipation budget for the device.

For total current consumption of the device, add up the significant functional blocks. In this example, 212.9 mA =

- 122 mA (core current)
- 17.3 mA (base clock distribution)
- 2.8 mA (CLKout group for two outputs)
- 25.5 mA (CLKout0 ans CLKout1 divider)
- 14.3 mA (LVDS buffer)
- 31 mA (LVPECL 1.6 Vpp buffer with a 240- $\Omega$  emitter resistors)



<span id="page-37-0"></span>Once total current consumption has been calculated, power dissipated by the device can be calculated. The power dissipation of the device is equation to the total current entering the device multiplied by the voltage at the device minus the power dissipated in any emitter resistors connected to any of the LVPECL outputs or any other external load power dissipation. Continuing the above example which has 212.9 mA total Icc and one output with 240- $\Omega$  emitter resistors and one LVDS output. Total IC power = 666 mW = 3.3 V × 212.9 mA - 35 mW - 1.5 mW.



## 表 **8-1. Typical Current Consumption for Selected Functional Blocks**  $(T_A = 25^{\circ}C, V_{CC} = 3.3 V)$

(1) Power is dissipated externally in LVPECL emitter resistors. The externally dissipated power is calculated as twice the DC voltage level of one LVPECL clock output pin squared over the emitter resistance. That is to say power dissipated in emitter resistors =  $2 \times \text{V} \text{em}^2$  / Rem.

(2) Assuming  $\theta_{JA} = 15^{\circ}$ C/W, the total power dissipated on chip must be less than (125°C – 85°C) / 16°C/W = 2.5 W to guarantee a junction temperature is less than 125°C.

(3) Worst case power dissipation can be estimated by multiplying typical power dissipation with a factor of 1.15.

## **8.6 Layout**

### **8.6.1 Layout Guidelines**

Power consumption of the LMK03806 can be high enough to require attention to thermal management. For reliability and performance reasons the die temperature should be limited to a maximum of 125°C. That is, as an estimate,  $T_A$  (ambient temperature) plus device power consumption times  $\theta_{JA}$  should not exceed 125°C.



The package of the device has an exposed pad that provides the primary heat removal path as well as excellent electrical grounding to a printed-circuit-board. To maximize the removal of heat from the package a thermal land pattern including multiple vias to a ground plane must be incorporated on the PCB within the footprint of the package. The exposed pad must be soldered down to ensure adequate heat conduction out of the package.

A recommended land and via pattern is shown in  $\&$  8-14. More information on soldering WQFN packages and gerber footprints can be obtained: [http://www.ti.com/packaging.](http://www.ti.com/packaging)

A recommended footprint including recommended solder mask and solder paste layers can be found at: [http://](http://www.ti.com/packaging) [www.ti.com/packaging](http://www.ti.com/packaging) for the NKD0064A package.





To minimize junction temperature, TI recommends that a simple heat sink be built into the PCB (if the ground plane layer is not exposed). This is done by including a copper area of about 2 square inches on the opposite side of the PCB from the device. This copper area may be plated or solder coated to prevent corrosion but should not have conformal coating (if possible), which could provide thermal insulation. The vias shown in  $\boxtimes$ 8-14 should connect these top and bottom copper layers and to the ground layer. These vias act as *heat pipes* to carry the thermal energy away from the device side of the board to where it can be more effectively dissipated.



### **8.6.2 Layout Example**



图 **8-15. LMK03806 Layout Example**

Crystal input to OSCin pins (purple circle):

- Place crystal with associated load capacitors (C6 and C9) as close as possible to the chip, and use short/ direct routing to the OSCin pins.
- If possible, cut out both ground plane and power plane under the area where the crystal and the routing to the device are placed. In this area, avoid using vias in the crystal signal path and routing other signals below the crystal paths, as these could be potential areas for noise coupling.

Clock outputs (blue circles):

- Differential signals should be routed tightly coupled to minimize PCB crosstalk. Trace impedance and loading/ terminations should be designed according to output type being used (that is, LVDS, LVPECL...).
- Unused output pins should be left open without connection to a trace. Unused outputs should be powered down through registers to reduce power and switching noise.

Power pins (green rectangles):

• Place ferrite beads and bypass caps as close as possible to the Vcc pins as possible. Design a low impedance power distribution network over a wide frequency range using multiple decoupling and bypass caps with different values/sizes. Use ferrite beads to isolate the device supply pins from board noise sources.

Loop filter (orange oval):

• Place loop filter resistor and capacitors nearby the chip, and route loop filter nodes from digital traces or noisy power traces/planes to avoid noise coupling.

<span id="page-40-0"></span>

## **9 Device and Documentation Support**

#### **9.1 Device Support**

#### **9.1.1 Development Support**

For additional support, see the following:

- Clock Design Tool:<http://www.ti.com/tool/clockdesigntool>
- Clock Architect: [http://www.ti.com/lsds/ti/analog/webench/clock-architect.page](http://www.ti.com/clockarchitect)
- Loop Filter Design: *PLL Performance, Simulation, and Design* ([www.ti.com/tool/pll\\_book](http://www.ti.com/tool/pll_book))

#### **9.2 Documentation Support**

#### **9.2.1 Related Documentation**

For additional information, see the following:

- Texas Instruments, *[Common Data Transmission Parameters and their Definitions](https://www.ti.com/lit/pdf/SNLA036)* application note
- Texas Instruments, *[Crystal Based Oscillator Design with the LMK04000 Family](https://www.ti.com/lit/pdf/SNAA065)* application note
- Texas Instruments, *[Frequency Synthesis and Planning for PLL Architectures](https://www.ti.com/lit/pdf/SNAA061)* application note

### **9.3** 接收文档更新通知

要接收文档更新通知,请导航至 [ti.com](https://www.ti.com) 上的器件产品文件夹。点击*通知* 进行注册,即可每周接收产品信息更改摘 要。有关更改的详细信息,请查看任何已修订文档中包含的修订历史记录。

### **9.4** 支持资源

TI E2E™ [中文支持论坛](https://e2e.ti.com)是工程师的重要参考资料,可直接从专家处获得快速、经过验证的解答和设计帮助。搜索 现有解答或提出自己的问题,获得所需的快速设计帮助。

链接的内容由各个贡献者"按原样"提供。这些内容并不构成 TI 技术规范,并且不一定反映 TI 的观点;请参阅 TI [的使用条款](https://www.ti.com/corp/docs/legal/termsofuse.shtml)。

#### **9.5 Trademarks**

TI E2E™ is a trademark of Texas Instruments. 所有商标均为其各自所有者的财产。

#### **9.6** 静电放电警告



静电放电 (ESD) 会损坏这个集成电路。德州仪器 (TI) 建议通过适当的预防措施处理所有集成电路。如果不遵守正确的处理 和安装程序,可能会损坏集成电路。

ESD 的损坏小至导致微小的性能降级,大至整个器件故障。精密的集成电路可能更容易受到损坏,这是因为非常细微的参 数更改都可能会导致器件与其发布的规格不相符。

### **9.7** 术语表

TI [术语表](https://www.ti.com/lit/pdf/SLYZ022) 本术语表列出并解释了术语、首字母缩略词和定义。



## <span id="page-41-0"></span>**10 Register Maps**

 $\bar{\textbf{x}}$  10-1 Provides the register map for device programming. At no time should registers be programmed to undefined values. Only valid register values should be written.



表 **10-1. Register Map**

<span id="page-42-0"></span>

#### 表 **10-1. Register Map** (续)



## **10.1 Default Device Register Settings After Power On Reset**

 $\bar{\ddot{\mathcal{R}}}$  10-2 shows the default register settings programmed in silicon for the LMK03806 after power on or asserting the reset bit. Capital X and Y represent numeric values.



#### 表 **10-2. Default Device Register Settings After Power On/Reset**



#### 表 **10-2. Default Device Register Settings After Power On/Reset** (续)



<span id="page-44-0"></span>

## 表 **10-2. Default Device Register Settings After Power On/Reset** (续)



(1) On POR, any output from CLKout6 cannot be used. R3 must be programmed per data sheet specifications before CLKout6 can be used.



## <span id="page-45-0"></span>**10.2 Register R0 TO R5**

Registers R0 through R5 control the 12 clock outputs CLKout0 to CLKout11. Register R0 controls CLKout0 and CLKout1, Register R1 controls CLKout2 and CLKout3, and so on. The X and Y in CLKoutX\_Y\_PD, CLKoutX Y DIV denote the actual clock output which may be from 0 to 11 where X is even and Y is odd. Two clock outputs CLKoutX and CLKoutY form a clock output group and are often run together in bit names as CLKoutX\_Y.

Two additional bits within the R0 to R5 register range are:

- The RESET bit, which is only in register R0.
- The POWERDOWN bit, which is only in register R1.

备注

R3 must be programmed after POR.

## **10.2.1 CLKoutX\_Y\_PD, Powerdown CLKoutX\_Y Output Path**

This bit powers down the clock group as specified by CLKoutX and CLKoutY. This includes the divider and output buffers.





#### **10.2.2 RESET**

The RESET bit is located in register R0 only. Setting this bit will cause the silicon default values to be loaded. When programming register R0 with the RESET bit set, all other programmed values are ignored. After resetting the device, the register R0 must be programmed again (with RESET = 0) to set non-default values in register R0.

The reset occurs on the falling edge of the LEuWire pin which loaded R0 with RESET = 1.

The RESET bit is automatically cleared upon writing any other register. For instance, when R0 is written to again with default values.



#### **10.2.3 POWERDOWN**

The POWERDOWN bit is located in register R1 only. Setting the bit causes the device to enter powerdown mode. Normal operation is resumed by clearing this bit with MICROWIRE.



#### **10.2.4 CLKoutX\_Y\_DIV, Clock Output Divide**

CLKoutX\_Y\_DIV sets the divide value for the clock group. The divide may be even or odd. Both even and odd divides output a 50% duty cycle clock.

Using a divide value of 26 or greater will cause the clock group to operate in extended mode.

Programming CLKoutX\_Y\_DIV can require special attention.



表 **10-6. CLKoutX\_Y\_DIV, 11 bits**

(1) After programming PLL\_N value, a SYNC must occur on channels using this divide value. Programming PLL\_N does generate a SYNC event automatically which satisfies this requirement, but NO\_SYNC\_CLKoutX\_Y must be set to 0 for these clock groups.



## <span id="page-47-0"></span>**10.3 Registers R6 TO R8**

#### **10.3.1 CLKoutX\_TYPE**

The clock output types of the LMK03806 are individually programmable. The CLKoutX\_TYPE registers set the output type of an individual clock output to LVDS, LVPECL, LVCMOS, or powers down the output buffer. Note that LVPECL supports four different amplitude levels and LVCMOS supports single LVCMOS outputs, inverted, and normal polarity of each output pin for maximum flexibility.

The programming addresses table shows at what register and address the specified clock output CLKoutX\_TYPE register is located.

The CLKoutX\_TYPE table shows the programming definition for these registers.



#### 表 **10-7. CLKoutX\_TYPE Programming Addresses**

#### 表 **10-8. CLKoutX\_TYPE, 4 Bits**



(1) TI recommends to use one of the complementary LVCMOS modes. Best noise performance is achieved using LVCMOS (Norm/Inv) or LVCMOS (Inv/Norm) due to the differential switching of the outputs. The next best performance is achieved using an LVCMOS mode with only one output on. Finally, LVCMOS (Norm/Norm) or LVCMOS (Inv/Inv) have the create the most switching noise.

<span id="page-48-0"></span>

### **10.4 REGISTER R9**

Register 9 contains no user programmable bits, but must be programmed as described in the register map.

#### **10.5 REGISTER R10**

#### **10.5.1 OSCout1\_TYPE, LVPECL Output Amplitude Control**

The OSCout1 clock output can only be used as an LVPECL output type. OSCout1\_TYPE sets the LVPECL output amplitude of the OSCout1 clock output.



#### 表 **10-9. OSCout1\_TYPE, 2 Bits**

#### **10.5.2 OSCout0\_TYPE**

The OSCout0 clock output has a programmable output type. The OSCout0\_TYPE register sets the output type to LVDS, LVPECL, LVCMOS, or powers down the output buffer. Note that LVPECL supports four different amplitude levels and LVCMOS supports dual and single LVCMOS outputs with inverted, and normal polarity of each output pin for maximum flexibility.

To turn on the output, the OSCout0 TYPE must be set to a non-power down setting and enabled with *[EN\\_OSCoutX, OSCout Output Enable](#page-49-0)*.



#### 表 **10-10. OSCout0\_TYPE, 4 Bits**

(1) TI recommends to use one of the complementary LVCMOS modes. Best noise performance is achieved using LVCMOS (Norm/Inv) or LVCMOS (Inv/Norm) due to the differential switching of the outputs. The next best performance is achieved using an LVCMOS mode with only one output on. Finally, LVCMOS (Norm/Norm) or LVCMOS (Inv/Inv) have the create the most switching noise.



### <span id="page-49-0"></span>**10.5.3 EN\_OSCoutX, OSCout Output Enable**

EN\_OSCoutX is used to enable an oscillator buffered output.

#### 表 **10-11. EN\_OSCout1**



#### 表 **10-12. EN\_OSCout0**



OSCout0 note: In addition to enabling the output with EN\_OSCout0. The OSCout0\_TYPE must be programmed to a non-power down value for the output buffer to power up.

#### **10.5.4 OSCoutX\_MUX, Clock Output Mux**

Sets OSCoutX buffer to output a divided or bypassed OSCin signal.

#### 表 **10-13. OSCout1\_MUX**



#### 表 **10-14. OSCout0\_MUX**



#### **10.5.5 OSCout\_DIV, Oscillator Output Divide**

The OSCout divider can be programmed from 2 to 8. Divide by 1 is achieved by bypassing the divider with *OSCoutX\_MUX, Clock Output Mux*.

#### 表 **10-15. OSCout\_DIV, 3 Bits**



## <span id="page-50-0"></span>**10.6 REGISTER R11**

## **10.6.1 NO\_SYNC\_CLKoutX\_Y**

The NO\_SYNC\_CLKoutX\_Y bits prevent individual clock groups from becoming synchronized during a SYNC event. A reason to prevent individual clock groups from becoming synchronized is that during synchronization, the clock output is in a fixed low state or can have a glitch pulse.

By disabling SYNC on a clock group, it will continue to operate normally during a SYNC event.

Setting the NO\_SYNC\_CLKoutX\_Y bit has no effect on clocks already synchronized together.

## 表 **10-16. NO\_SYNC\_CLKoutX\_Y Programming Addresses**



#### 表 **10-17. NO\_SYNC\_CLKoutX\_Y**



#### **10.6.2 SYNC\_POL\_INV**

Sets the polarity of the SYNC pin when input. When SYNC is asserted the clock outputs will transition to a low state.

#### 表 **10-18. SYNC\_POL\_INV**



## **10.6.3 SYNC\_TYPE**

Sets the IO type of the SYNC pin.

#### 表 **10-19. SYNC\_TYPE, 2 Bits**



#### **10.6.4 EN\_PLL\_XTAL**

If an external crystal is being used to implement a discrete VCXO, the internal feedback amplifier must be enabled with this bit in order to complete the oscillator circuit.

#### 表 **10-20. EN\_PLL\_XTAL**





## <span id="page-51-0"></span>**10.7 REGISTER R12**

### **10.7.1 LD\_MUX**

LD\_MUX sets the output value of the Ftest/LD pin.

All the outputs logic is active high when LD\_TYPE = 3 (Output). All the outputs logic is active low when LD TYPE = 4 (Output Inverted). For example, when LD\_MUX = 0 (Logic Low) and LD\_TYPE = 3 (Output) then Ftest/LD pin outputs a logic low. When LD\_MUX = 0 (Logic Low) and LD\_TYPE = 4 (Output Inverted) then Ftest/LD pin outputs a logic high.



 $\#$  **10-21. LD\_MUY, 5 Bits** 

(1) Only valid when LD\_MUX is not set to 2 (PLL\_DLD).

### **10.7.2 LD\_TYPE**

Sets the IO type of the LD pin.





### **10.7.3 SYNC\_PLL\_DLD**

By setting SYNC\_PLL\_DLD a SYNC mode will be engaged (asserted SYNC) until the PLL locks.

### 表 **10-23. SYNC\_PLL\_DLD**



<span id="page-52-0"></span>

## **10.8 REGISTER R13**

## **10.8.1 READBACK\_TYPE**

Sets the IO format of the readback pin. The open drain output type can be used to interface the LMK03806 with low voltage IO rails.

## 表 **10-24. READBACK\_TYPE, 3 Bits**



#### **10.8.2 GPout0**

Sets the output state of the GPout0 pin.

表 **10-25. GPout0, 3 Bits**

R13[18:16]	<b>OUTPUT STATE</b>
0(0x00)	Reserved
1(0x01)	Reserved
2(0x02)	Weak pull-down
3(0x03)	Low $(0 V)$
4(0x04)	High (3.3 V)

## **10.9 REGISTER 14**

#### **10.9.1 GPout1**

Sets the output state of the GPout1 pin.

表 **10-26. GPout1, 3 Bits**

R14[26:24]	<b>OUTPUT STATE</b>
0(0x00)	Reserved
1(0x01)	Reserved
2(0x02)	Weak pull-down
3(0x03)	Low $(0 V)$
4(0x04)	High (3.3 V)



## <span id="page-53-0"></span>**10.10 REGISTER 16**

Register 16 contains no user programmable bits, but must be programmed as described in the register map.

## **10.11 REGISTER 24**

#### **10.11.1 PLL\_C4\_LF, PLL Integrated Loop Filter Component**

Internal loop filter components are available for the PLL, enabling either 3rd or 4th order loop filters without requiring external components.

Internal loop filter capacitor C4 can be set according to the values listed in  $\bar{\mathcal{R}}$  10-27.



#### 丰**40.27. PLL\_C4\_LE 4 Bits**



#### **10.11.2 PLL\_C3\_LF, PLL Integrated Loop Filter Component**

Internal loop filter components are available for the PLL, enabling either 3rd or 4th order loop filters without requiring external components.

Internal loop filter capacitor C3 can be set according to the values listed in  $\bar{\mathcal{R}}$  10-28.



#### 丰 10-28 **PLL C3 LE** *A* **Bits**

### **10.11.3 PLL\_R4\_LF, PLL Integrated Loop Filter Component**

Internal loop filter components are available for the PLL, enabling either 3rd or 4th order loop filters without requiring external components.

Internal loop filter resistor R4 can be set according to the values listed in  $\bar{\mathcal{R}}$  10-29.





## **10.11.4 PLL\_R3\_LF, PLL Integrated Loop Filter Component**

Internal loop filter components are available for the PLL, enabling either 3rd or 4th order loop filters without requiring external components.

Internal loop filter resistor R3 can be set according to the values listed in  $\frac{1}{\mathcal{R}}$  10-30.



<span id="page-56-0"></span>

## **10.12 REGISTER 26**

#### **10.12.1 EN\_PLL\_REF\_2X, PLL Reference Frequency Doubler**

Enabling the PLL reference frequency doubler allows for higher phase detector frequencies on the PLL than would normally be allowed with the given VCXO or Crystal frequency.

Higher phase detector frequencies reduces the PLL N values which makes the design of wider loop bandwidth filters possible.





#### **10.12.2 PLL\_CP\_GAIN, PLL Charge Pump Current**

This bit programs the PLL charge pump output current level.





#### **10.12.3 PLL\_DLD\_CNT**

The reference and feedback of the PLL must be within the window of acceptable phase error for **PLL\_DLD\_CNT**  cycles before PLL digital lock detect is asserted.







## <span id="page-57-0"></span>**10.13 REGISTER 28**

#### **10.13.1 PLL\_R, PLL R Divider**

The reference path into the PLL phase detector includes the PLL R divider.

#### $\overline{\mathcal{R}}$  10-34 lists the valid values for PLL R.



#### 表 **10-34. PLL\_R, 12 Bits**

#### **10.14 REGISTER 29**

#### **10.14.1 OSCin\_FREQ, PLL Oscillator Input Frequency Register**

The frequency of the PLL reference input to the PLL Phase Detector (OSCin/OSCin\* port) must be programmed in order to support proper operation of the frequency calibration routine which locks the internal VCO to the target frequency.

#### 表 **10-35. OSCin\_FREQ, 3 Bits**



## **10.14.2 PLL\_N\_CAL, PLL N Calibration Divider**

During the frequency calibration routine, the PLL uses the divide value of the PLL\_N\_CAL register instead of the divide value of the PLL\_N register to lock the VCO to the target frequency.

#### 表 **10-36. PLL\_N\_CAL, 18 Bits**



<span id="page-58-0"></span>

## **10.15 REGISTER 30**

Programming Register 30 triggers the frequency calibration routine. This calibration routine will also generate a SYNC event.

#### **10.15.1 PLL\_P, PLL N Prescaler Divider**

The PLL N Prescaler divides the output of the VCO and is connected to the PLL N divider.



#### 表 **10-37. PLL\_P, 3 Bits**

#### **10.15.2 PLL\_N, PLL N Divider**

The feedback path into the PLL phase detector includes the PLL N divider.

Each time register 30 is updated through the MICROWIRE interface, a frequency calibration routine runs to lock the VCO to the target frequency. During this calibration PLL\_N is substituted with PLL\_N\_CAL.

 $\bar{\text{\#}}$  10-38 lists the valid values for PLL\_N.

#### 表 **10-38. PLL\_N, 18 Bits**





## <span id="page-59-0"></span>**10.16 REGISTER 31**

## **10.16.1 READBACK\_ADDR**



## 表 **10-39. READBACK\_ADDR**

### **10.16.2 uWire\_LOCK**

Setting uWire\_LOCK will prevent any changes to uWire registers R0 to R30. Only by clearing the uWire\_LOCK bit in R31 can the uWire registers be unlocked and written to once more.

It is not necessary to lock the registers to perform a readback operation.

#### 表 **10-40. uWire\_LOCK**



<span id="page-60-0"></span>

## **11 Revision History**

注:以前版本的页码可能与当前版本的页码不同





## **12 Mechanical, Packaging, and Orderable Information**

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



## **PACKAGING INFORMATION**



**(1)** The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

**(3)** MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

**(4)** There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

**(5)** Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

**(6)** Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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# **PACKAGE OPTION ADDENDUM**

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.



**TEXAS** 

## **TAPE AND REEL INFORMATION**

**ISTRUMENTS** 





#### **QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**







# **PACKAGE MATERIALS INFORMATION**

www.ti.com 31-Oct-2024



\*All dimensions are nominal



# **GENERIC PACKAGE VIEW**

# **NKD 64 WQFN - 0.8 mm max height**

**9 x 9, 0.5 mm pitch** PLASTIC QUAD FLATPACK - NO LEAD

This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.





# PACKAGE OUTLINE



# NKD0064A WQFN - 0.8 mm max height

WQFN



NOTES:

- 1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.

3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.



# EXAMPLE BOARD LAYOUT

NKD0064A WQFN - 0.8 mm max height

WQFN



NOTES: (continued)

4. This package is designed to be soldered to a thermal pad on the board. For more information, refer to QFN/SON PCB application note in literature No. [SLUA271](http://www.ti.com/lit/slua271) (www.ti.com/lit/slua271).



# EXAMPLE STENCIL DESIGN

# NKD0064A WQFN - 0.8 mm max height

WQFN



NOTES: (continued)

5. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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