

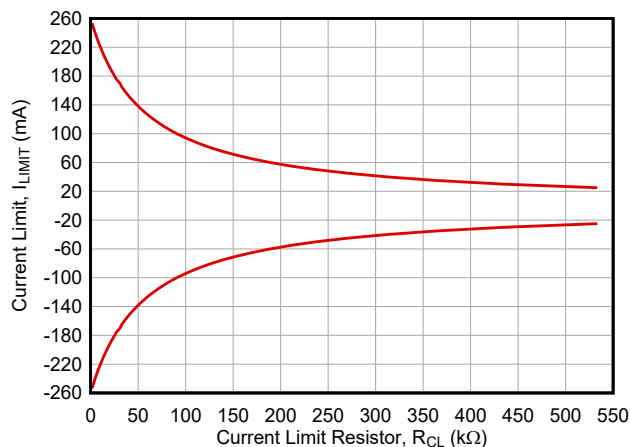
# OPA593 85V、250mA 输出电流、精密、功率运算放大器

## 1 特性

- 宽电源范围：
  - 8V ( $\pm 4V$ ) 至 85V ( $\pm 42.5V$ )
- 低失调电压： $\pm 20\mu V$
- 低失调电压漂移： $\pm 0.4\mu V/^\circ C$
- 高输出电流：250mA
- 宽增益带宽：10MHz
- 高压摆率：45V/ $\mu s$ ，上升
- 低噪声：10 kHz 时为  $7nV/\sqrt{Hz}$
- 多路复用器友好型输入
- 轨到轨输出
- 静态电流：
  - 启用：3.25mA
  - 禁用：250  $\mu A$
- 额定电流限制精度
- 过热和过流标志
- 温度范围： $-40^\circ C$  至  $+125^\circ C$
- 封装：12 引脚 WSON

## 2 应用

- 半导体测试
- 半导体制造
- 可编程直流电源
- LCD 测试
- CT 和 PET 扫描仪



输出电流与电流限制电阻器配置

## 3 说明

OPA593 是一款高压 (85V)、高精度、宽带宽 (10MHz)、高输出电流 (250mA)、单位增益稳定功率运算放大器。

OPA593 采用激光修整技术来改善失调电压 (20 $\mu V$ ，典型值) 和失调电压温漂 (0.4 $\mu V/^\circ C$ ，典型值)，因此无需校准。该器件具有多路复用器友好型输入，可实现电源轨的差分输入电压范围，并有助于提高多通道系统的稳定性。

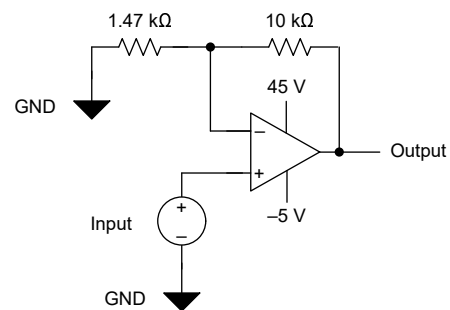
可以使用一个外部电阻器来限制具有指定精度的电流，从而提供更为精确的测量。在过流或过热条件下，该器件会通过状态标志来指示错误操作。所含的禁用功能用于关断该器件，从而实现省电并将输出置于高阻抗状态。

该器件具有单位增益稳定特性，可用作高阻抗缓冲器。宽带宽和高压摆率可实现高信号增益。由于具有高输出电流和容性驱动，该器件能够驱动用于提供更高系统电流的外部场效应晶体管 (FET)，例如在数字电源中。

### 封装信息

器件型号	封装 <sup>(1)</sup>	封装尺寸 (标称值)
OPA593	DNT (WSON, 12)	4.00mm × 4.00mm

(1) 如需了解所有可用封装，请参阅数据表末尾的封装选项附录。



配置为增益 8 的输出驱动器



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## 4 Revision History

注：以前版本的页码可能与当前版本的页码不同

<b>Changes from Revision B (August 2022) to Revision C (November 2022)</b>	<b>Page</b>
• 从预告信息 ( 预发布 ) 更改为量产数据 ( 正在供货 ) .....	<b>1</b>

## 5 Pin Configuration and Functions

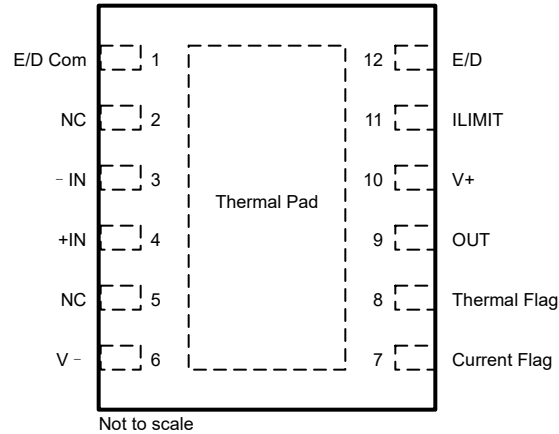


图 5-1. DNT (12-Pin WSON) Package, Top View

表 5-1. Pin Functions

PIN		TYPE	DESCRIPTION
NAME	NO.		
Current Flag	7	Output	Overcurrent status flag
E/D	12	Input	Enable and disable
E/D Com	1	Input	Enable and disable common
ILIMIT	11	Input	Current limit
+IN	4	Input	Noninverting input
- IN	3	Input	Inverting input
NC	2, 5	—	No internal connection
OUT	9	Output	Output
Thermal Flag	8	Output	Overtemperature status flag
Thermal Pad	Thermal pad	—	The thermal pad is internally connected to V <sub>-</sub> . The thermal pad must be soldered to a printed-circuit board (PCB) connected to V <sub>-</sub> , even with applications that have low power dissipation.
V+	10	Power	Positive (highest) power supply
V-	6	Power	Negative (lowest) power supply

## 6 Specifications

### 6.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
V <sub>S</sub>	Supply voltage, V <sub>S</sub> = (V+) - (V-)		93	V
	Signal input pin voltage <sup>(2)</sup>	(V-) - 0.3	(V+) + 0.3	V
	Status flag and E/D pin voltage <sup>(3)</sup>		E/D Com + 7	V
	ILIMIT pin voltage	V-	(V-) + 3.35	V
	Status flag pins current <sup>(3)</sup>		3	mA
	Input current, all pins <sup>(2)</sup>		±10	mA
	Output short circuit current <sup>(4)</sup>		Continuous	
T <sub>J</sub>	Junction temperature	- 55	150	°C
T <sub>STG</sub>	Storage temperature	- 65	150	°C

- (1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.
- (2) Input, E/D Com, and output pins are diode-clamped to the power-supply rails. Input signals that can swing more than 0.3 V beyond the supply rails must be current-limited to less than 10 mA.
- (3) Status flag and E/D pins are diode clamped to E/D Com - 0.3 V and E/D Com + 7 V. Pullup signals must be current-limited to < 3 mA.
- (4) Short-circuit to ground.

### 6.2 ESD Ratings

			VALUE	UNIT
V <sub>(ESD)</sub>	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±1500	V
		Charged-device model (CDM), per ANSI/ESDA/JEDEC JS-002 <sup>(2)</sup>	±500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Conditions

Over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V <sub>S</sub>	Supply voltage, V <sub>S</sub> = (V+) - (V-)	Single supply voltage	8	85	V
		Dual supply voltage	±4	±42.5	
V <sub>E/D</sub>	E/D pin voltage <sup>(1)</sup>			5.5	V
	Status flag pin voltage <sup>(1)</sup>			5.5	V
I <sub>LIMIT</sub>	Current limit set	±25		±250	mA
T <sub>A</sub>	Operating temperature	- 40		125	°C

- (1) Recommended voltage must be current limited to below the listed value in the *Absolute Maximum Ratings*.

### 6.4 Thermal Information

	THERMAL METRIC <sup>(1)</sup>	OPA593	UNIT
		DNT (WSON)	
		12 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	40.8	°C/W
R <sub>θJC(top)</sub>	Junction-to-case (top) thermal resistance	30.2	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	17.8	°C/W
ψ <sub>JT</sub>	Junction-to-top characterization parameter	0.3	°C/W
ψ <sub>JB</sub>	Junction-to-board characterization parameter	17.7	°C/W

THERMAL METRIC <sup>(1)</sup>		OPA593	UNIT
		DNT (WSON)	
		12 PINS	
R <sub>θJC(bot)</sub>	Junction-to-case (bottom) thermal resistance	4.3	°C/W

(1) For information on traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

## 6.5 Electrical Characteristics

at  $V_S = 85\text{ V}$ ,  $T_A = 25^\circ\text{C}$ ,  $R_L = 10\text{ k}\Omega$  to mid-supply,  $I_{OUT}$  limit set to 100 mA, and  $V_{CM} = V_{OUT} = \text{mid-supply}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>OFFSET VOLTAGE</b>						
$V_{OS}$	Input offset voltage			$\pm 20$	$\pm 100$	$\mu\text{V}$
$dV_{OS}/dT$	Input offset voltage drift	$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$		$\pm 0.4$	$\pm 2$	$\mu\text{V}/^\circ\text{C}$
PSRR	Power supply rejection ratio	$V_S = \pm 4\text{ V}$ to $\pm 42.5\text{ V}$		0.1	1	$\mu\text{V}/\text{V}$
<b>INPUT BIAS CURRENT</b>						
$I_B$	Input bias current			$\pm 1$	$\pm 10$	$\text{pA}$
		$T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$			$\pm 350$	
		$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$				$\pm 5$
$I_{OS}$	Input offset current			$\pm 1$	$\pm 5$	$\text{pA}$
		$T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$				
		$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$				$\pm 1$
<b>NOISE</b>						
	Input voltage noise	$f = 0.1\text{ Hz}$ to $10\text{ Hz}$		2.9		$\mu\text{V}_{PP}$
$e_n$	Input voltage noise density	$f = 10\text{ Hz}$		75		$\text{nV}/\sqrt{\text{Hz}}$
		$f = 1\text{ kHz}$		10		
		$f = 10\text{ kHz}$		7		
$i_n$	Current noise density	$f = 1\text{ kHz}$		12		$\text{fA}/\sqrt{\text{Hz}}$
<b>INPUT VOLTAGE</b>						
$V_{CM}$	Common-mode voltage	Linear operation	$(V_-) - 0.1$		$(V_+) - 3.5$	V
CMRR	Common-mode rejection	$(V_-) \leq V_{CM} \leq (V_+) - 3.5\text{ V}$		124	140	dB
			$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$	108	124	
<b>INPUT IMPEDANCE</b>						
	Differential			$10^{13} \parallel 0.3$		$\Omega \parallel \text{pF}$
	Common-mode			$10^{13} \parallel 9.4$		$\Omega \parallel \text{pF}$
<b>OPEN-LOOP GAIN</b>						
$A_{OL}$	Open-loop voltage gain	$(V_-) + 0.3\text{ V} < V_O < (V_+) - 0.3\text{ V}$ , $R_L = 10\text{ k}\Omega$		134	140	dB
			$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$	130	140	
		$(V_-) + 1\text{ V} < V_O < (V_+) - 1\text{ V}$ , $R_L = 2\text{ k}\Omega$		132	140	
			$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$	130	135	
		$(V_-) + 2.5\text{ V} < V_O < (V_+) - 2.5\text{ V}$ , $R_L = 600\ \Omega$		130	135	
			$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$	125	130	
<b>FREQUENCY RESPONSE</b>						
GBW	Gain-bandwidth product			10		MHz
SR	Slew rate	Gain = $\pm 1$ , $V_{OUT} = 70\text{-V}$ step	Rising		45	$\text{V}/\mu\text{s}$
			Falling		35	
$t_s$	Settling time	To $\pm 0.01\%$ , gain = $-1$ , $V_{OUT} = 70\text{-V}$ step, $C_L = 100\text{ pF}$		2.9		$\mu\text{s}$
THD+N	Total harmonic distortion + noise	Gain = $+1$ , $V_{OUT} = 70\text{ V}_{PP}$ , $f = 1\text{ kHz}$	$R_L = 600\ \Omega$		-105	dB
			$R_L = 2\text{ k}\Omega$		-110	
<b>OUTPUT</b>						

## 6.5 Electrical Characteristics (continued)

at  $V_S = 85\text{ V}$ ,  $T_A = 25^\circ\text{C}$ ,  $R_L = 10\text{ k}\Omega$  to mid-supply,  $I_{OUT}$  limit set to 100 mA, and  $V_{CM} = V_{OUT} = \text{mid-supply}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
$V_O$	Voltage output swing from rail	$R_{CL} = 0\ \Omega$ connected to $V^-$	No load		10	25	mV
			$I_{OUT} = 50\text{ mA}$		50	125	
			$I_{OUT} = 100\text{ mA}$		400	750	
			$I_{OUT} = 250\text{ mA}$		1.2	2	V
	Continuous output current, dc	$V_S = 85\text{ V}$ , $R_{CL} = 2.29\text{ k}\Omega$ , $I_{LIMIT} = 250\text{ mA}$		$\pm 250$			mA
$C_{LOAD}$	Capacitive load drive			See typical curves			pF
$Z_O$	Open-loop output impedance			See typical curves			$\Omega$
	Output impedance	Output disabled, $V^- < V_{OUT} < V^+$		100			M $\Omega$
	Output capacitance	Output disabled		56			pF
<b>CURRENT LIMIT</b>							
$I_{LIMIT}$	Current limit			$\pm 25$		$\pm 250$	mA
	Current limit accuracy <sup>(3)</sup>	Sourcing, $R_L = 10\ \Omega$ to mid-supply	$I_{LIMIT} = 25\text{ mA}$ , $V_{LIMIT} = 3.33\text{ V}$	17		29	mA
			$I_{LIMIT} = 50\text{ mA}$ , $V_{LIMIT} = 2.98\text{ V}$	42		55	
			$I_{LIMIT} = 100\text{ mA}$ , $V_{LIMIT} = 2.27\text{ V}$	94		107	
			$I_{LIMIT} = 250\text{ mA}$ , $V_{LIMIT} = 0.14\text{ V}$	237		263	
		Sinking, $R_L = 10\ \Omega$ to mid-supply	$I_{LIMIT} = 25\text{ mA}$ , $V_{LIMIT} = 3.33\text{ V}$	10		45	
			$I_{LIMIT} = 50\text{ mA}$ , $V_{LIMIT} = 2.98\text{ V}$	35		68	
			$I_{LIMIT} = 100\text{ mA}$ , $V_{LIMIT} = 2.27\text{ V}$	85		115	
			$I_{LIMIT} = 250\text{ mA}$ , $V_{LIMIT} = 0.14\text{ V}$	235		275	
	Current limit equation	Resistor set, $R_{CL}$ connected between $I_{LIMIT}$ pin and $V^-$		$(3.687\text{ V} \times 4000) / (56.7\text{ k}\Omega + R_{CL})$		mA	
		Voltage set, $V_{LIMIT}$ connected to $I_{LIMIT}$ pin and referenced to $V^-$		$4000 \times (3.687\text{ V} - V_{LIMIT}) / 56.7\text{ k}\Omega$			
<b>STATUS FLAG PIN (Referenced to E/D Com)</b>							
	Status flag delay	Overcurrent delay		10			$\mu\text{s}$
		Overcurrent recovery delay		10			
	Thermal shutdown	Alarm (status flag high)		170			$^\circ\text{C}$
		Return to normal operation (status flag low)		150			
	Status flag output voltage	Normal operation		See typical curves			
<b>E/D PIN</b>							
$V_{E/D}$	E/D voltage <sup>(1)</sup>	Enable, pin open or forced high <sup>(2)</sup>		E/D Com + 1.5		E/D Com + 5.5	V
		Disable, pin forced low <sup>(2)</sup>		E/D Com		E/D Com + 0.5	
$I_{E/D}$	E/D input current			50			$\mu\text{A}$
	Output disable time			12			$\mu\text{s}$
	Output enable time			18			$\mu\text{s}$
<b>E/D COM PIN</b>							
	E/D Com voltage			$(V^-)$		$(V^+) - 6$	V
<b>POWER SUPPLY</b>							

## 6.5 Electrical Characteristics (continued)

at  $V_S = 85\text{ V}$ ,  $T_A = 25^\circ\text{C}$ ,  $R_L = 10\text{ k}\Omega$  to mid-supply,  $I_{OUT}$  limit set to 100 mA, and  $V_{CM} = V_{OUT} = \text{mid-supply}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_Q$	Quiescent current			3.25	3.75	mA
		$T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$			4	
		Output disabled		0.25		

- (1) For information on the output enable and disable feature see [节 7.3.4](#).
- (2) Enable and disable voltage thresholds can vary near the maximum temperature range; see [图 6-67](#).
- (3) Proper output swing headroom is necessary to maintain current limit accuracy; see [图 6-19](#) to [图 6-34](#).



## 6.6 Typical Characteristics

at  $T_A = 25^\circ\text{C}$ ,  $V_S = (V+) - (V-) = 85\text{ V}$ ,  $I_{\text{LIMIT}} = 100\text{ mA}$ ,  $V_{\text{CM}} = V_{\text{OUT}} = V_S/2$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_S/2$  (unless otherwise noted)

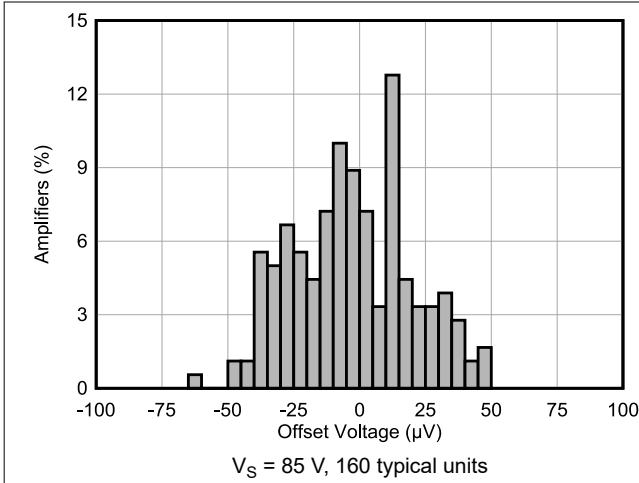


图 6-1. Input Offset Production Distribution

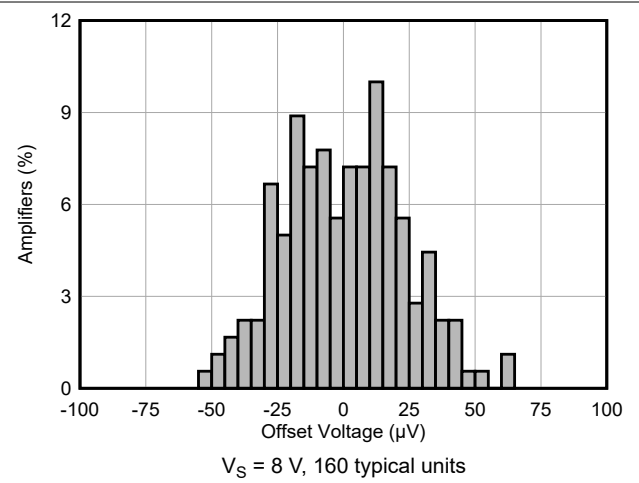


图 6-2. Input Offset Production Distribution

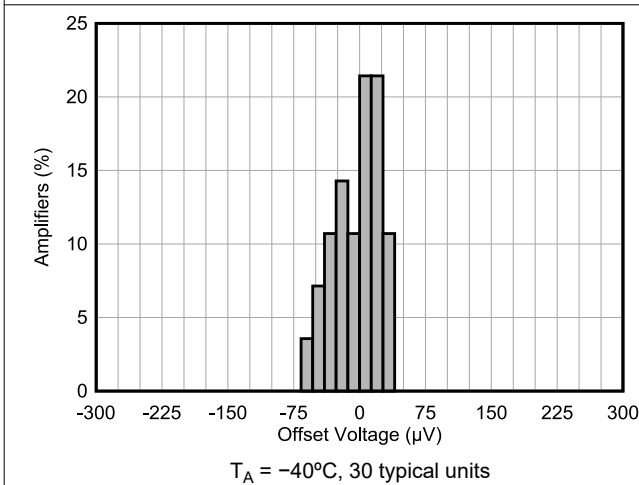


图 6-3. Input Offset Production Distribution

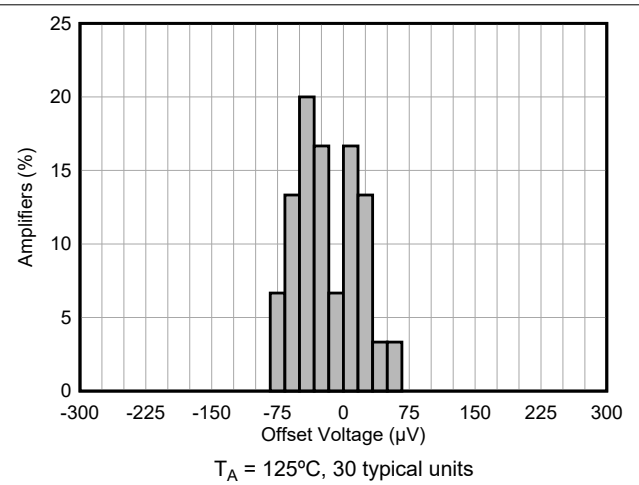


图 6-4. Input Offset Production Distribution

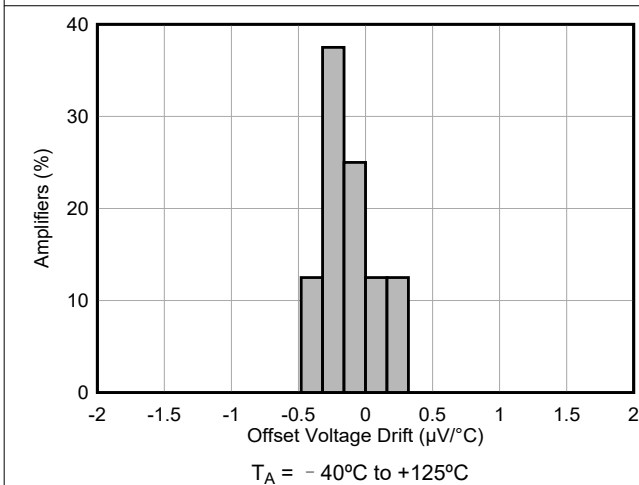


图 6-5. Input Offset Voltage Drift Distribution

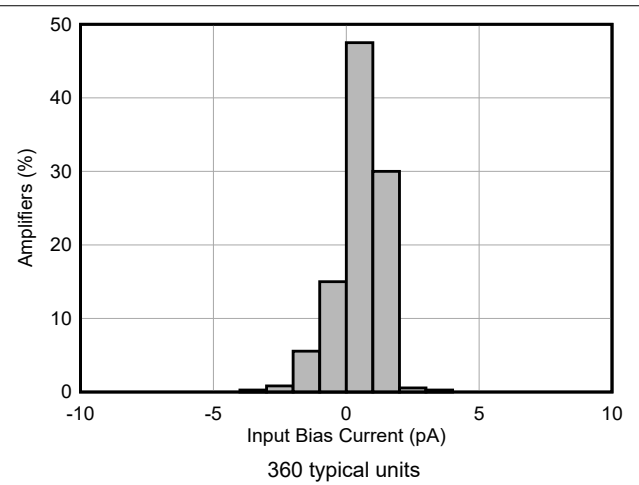


图 6-6. Input Bias Current Production Distribution

### 6.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = (V+) - (V-) = 85\text{ V}$ ,  $I_{\text{LIMIT}} = 100\text{ mA}$ ,  $V_{\text{CM}} = V_{\text{OUT}} = V_S/2$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_S/2$  (unless otherwise noted)

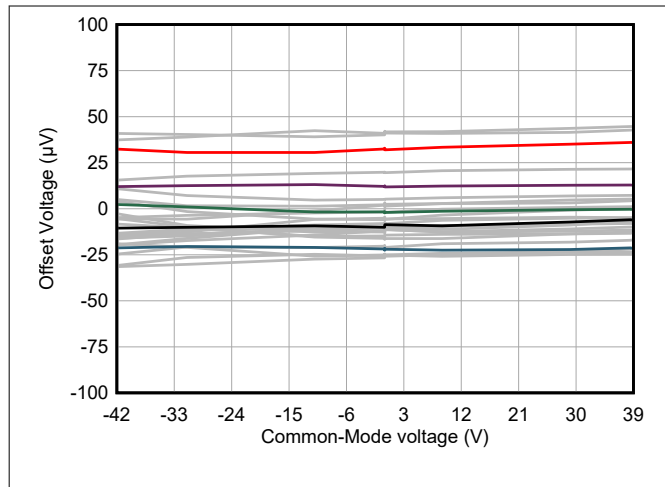


图 6-7. Input Offset Voltage vs Common-Mode Voltage

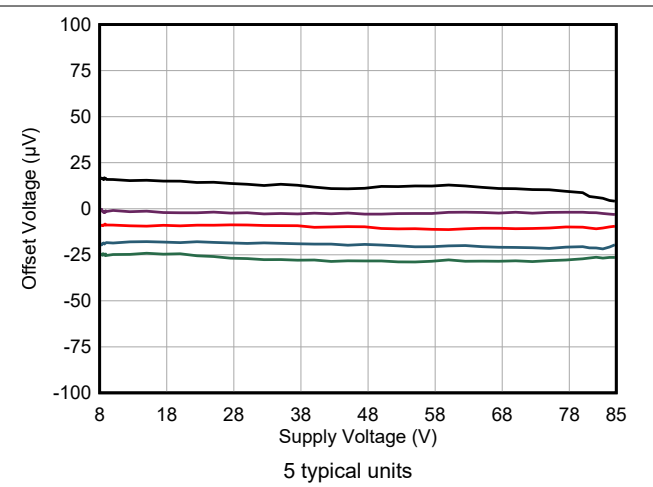


图 6-8. Input Offset Voltage vs Supply Voltage

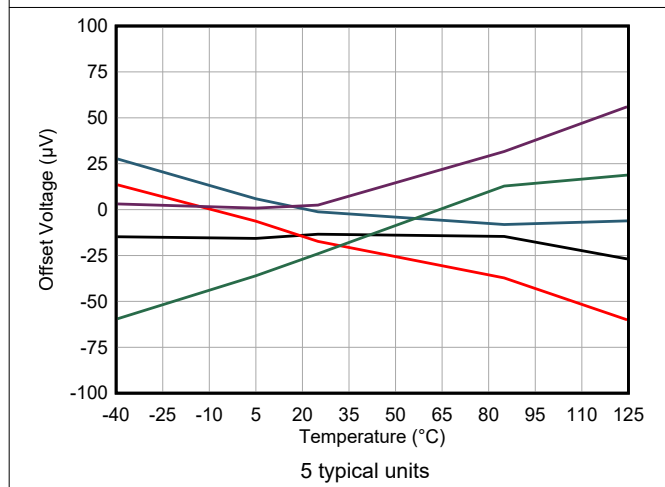


图 6-9. Input Offset Voltage vs Temperature

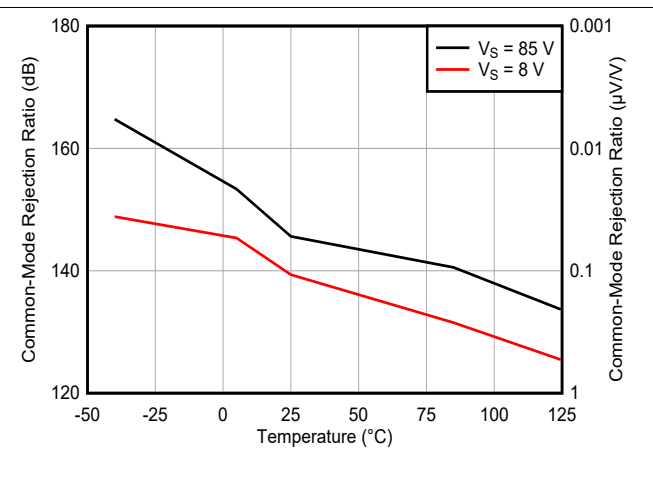


图 6-10. CMRR vs Temperature

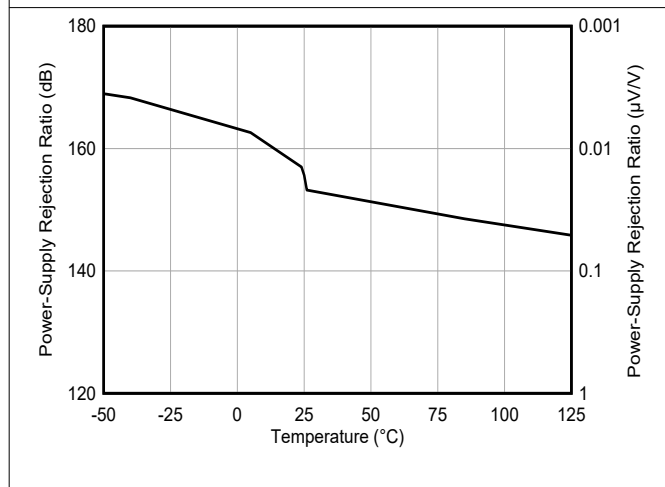


图 6-11. PSRR vs Temperature

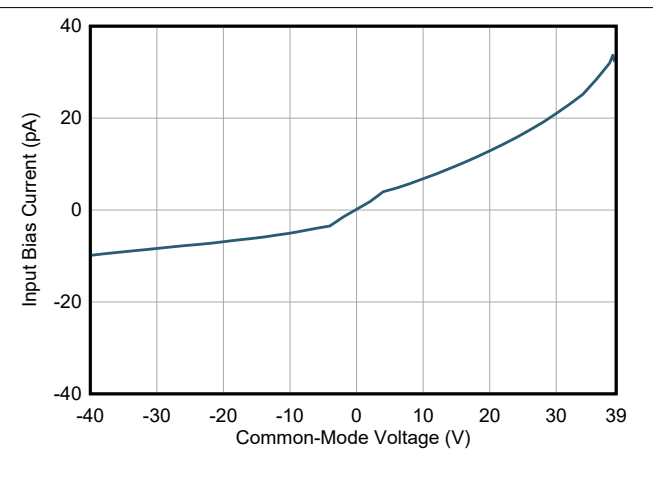


图 6-12. Input Bias Current vs Common-Mode Voltage

### 6.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = (V+) - (V-) = 85\text{ V}$ ,  $I_{\text{LIMIT}} = 100\text{ mA}$ ,  $V_{\text{CM}} = V_{\text{OUT}} = V_S/2$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_S/2$  (unless otherwise noted)

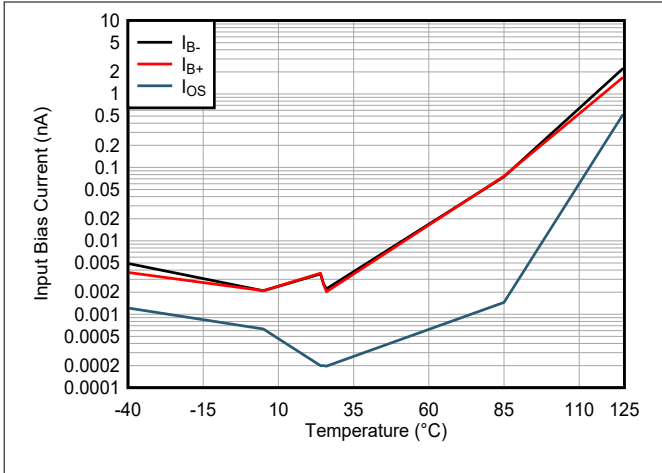


图 6-13. Input Bias Current and Current Offset vs Temperature

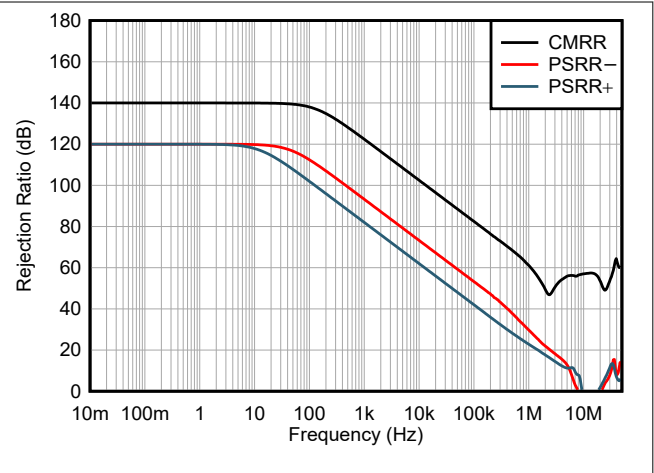


图 6-14. PSRR and CMRR vs Frequency

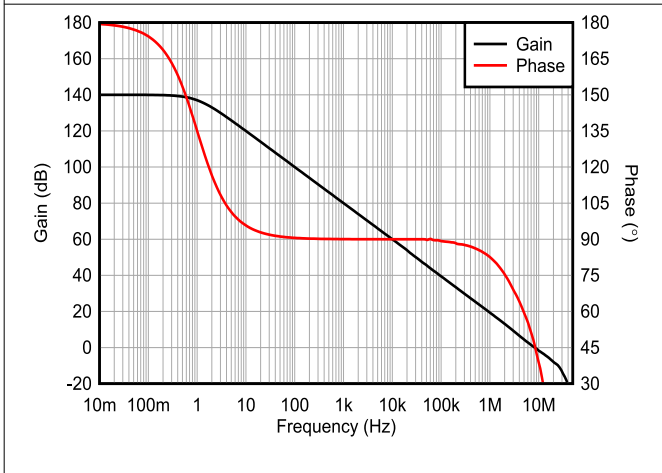


图 6-15. Open-Loop Gain and Phase vs Frequency

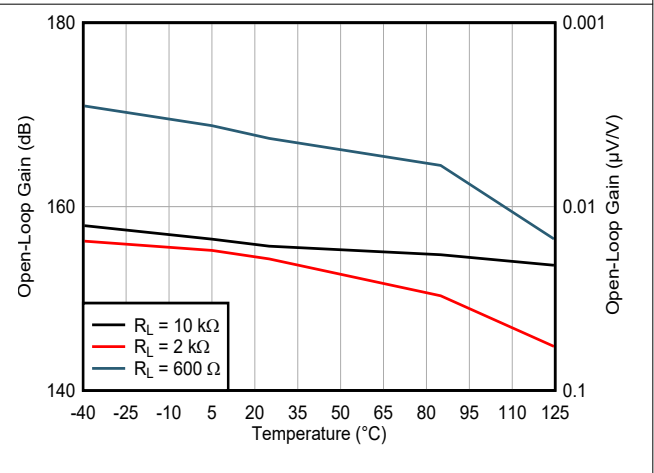


图 6-16. Open Loop Gain vs Temperature

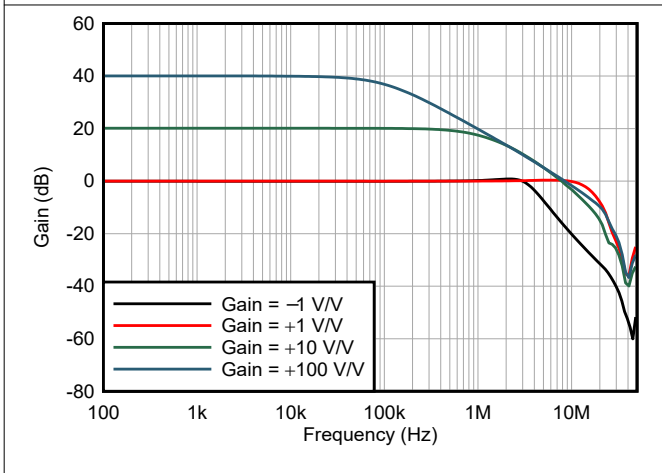


图 6-17. Closed-Loop Gain vs Frequency

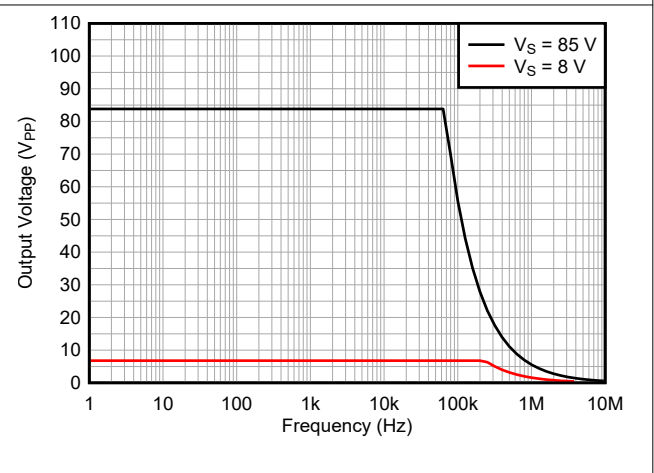


图 6-18. Maximum Output Voltage vs Frequency

### 6.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = (V+) - (V-) = 85\text{ V}$ ,  $I_{\text{LIMIT}} = 100\text{ mA}$ ,  $V_{\text{CM}} = V_{\text{OUT}} = V_S/2$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_S/2$  (unless otherwise noted)

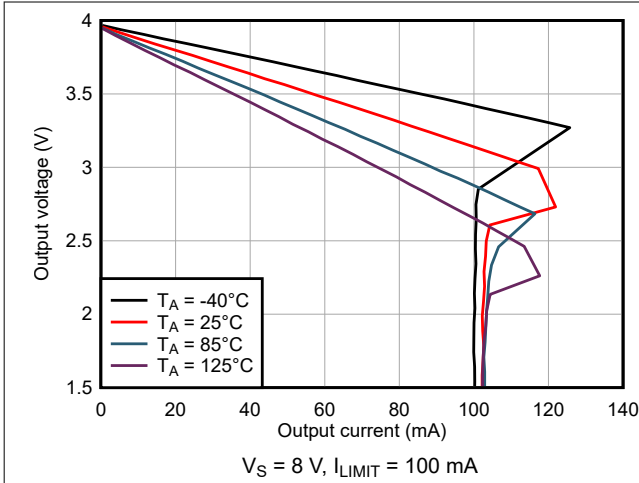


图 6-19. Output Voltage vs Output Sourcing Current

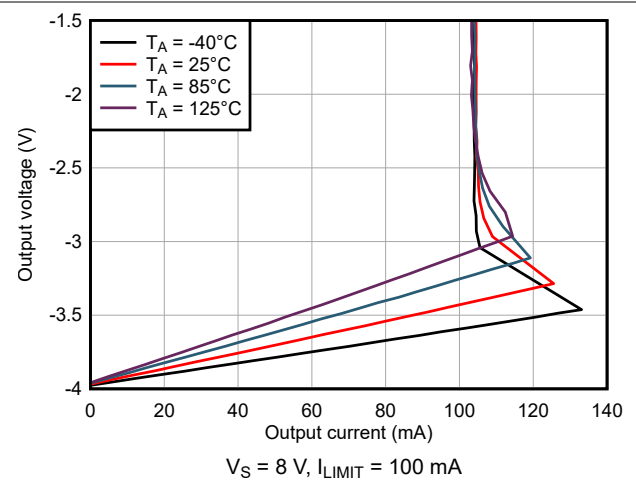


图 6-20. Output Voltage vs Output Sinking Current

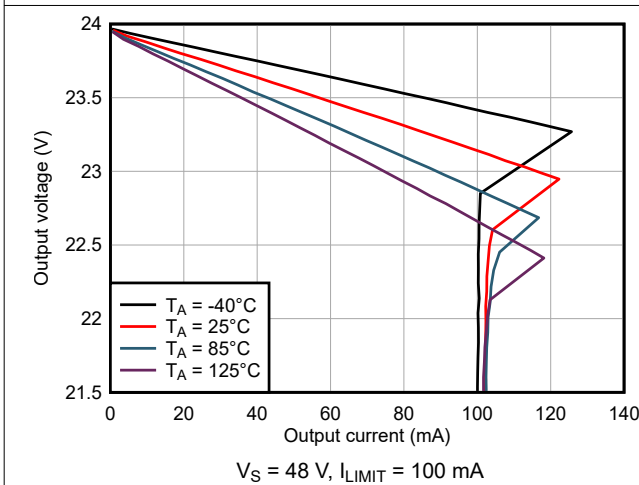


图 6-21. Output Voltage vs Output Sourcing Current

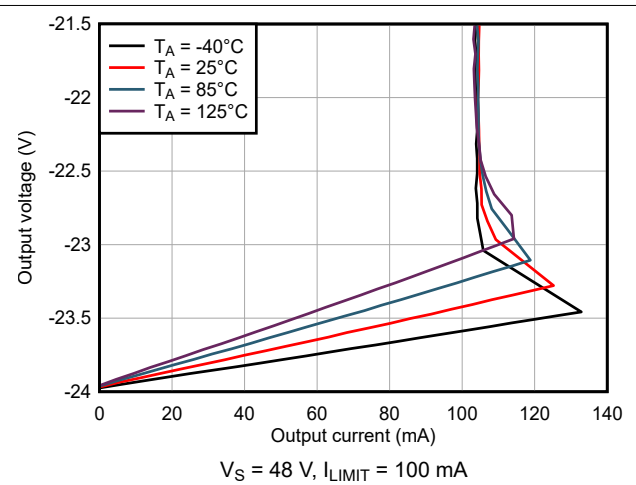


图 6-22. Output Voltage vs Output Sinking Current

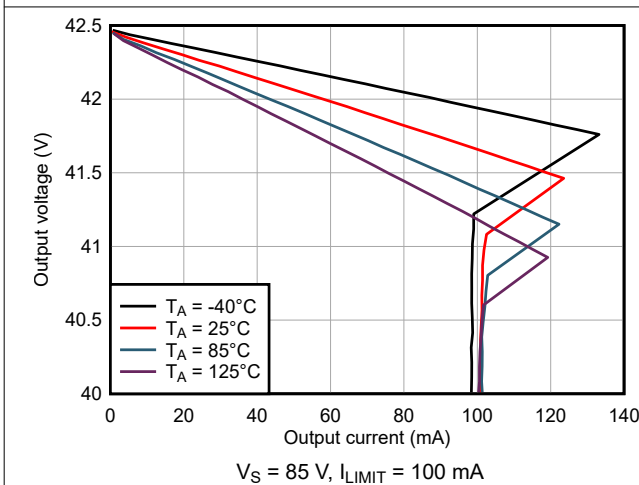


图 6-23. Output Voltage vs Output Sourcing Current

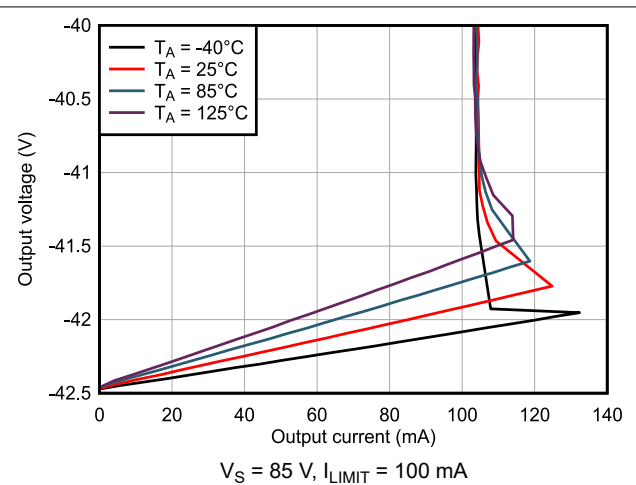


图 6-24. Output Voltage vs Output Sinking Current

## 6.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = (V+) - (V-) = 85\text{ V}$ ,  $I_{\text{LIMIT}} = 100\text{ mA}$ ,  $V_{\text{CM}} = V_{\text{OUT}} = V_S/2$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_S/2$  (unless otherwise noted)

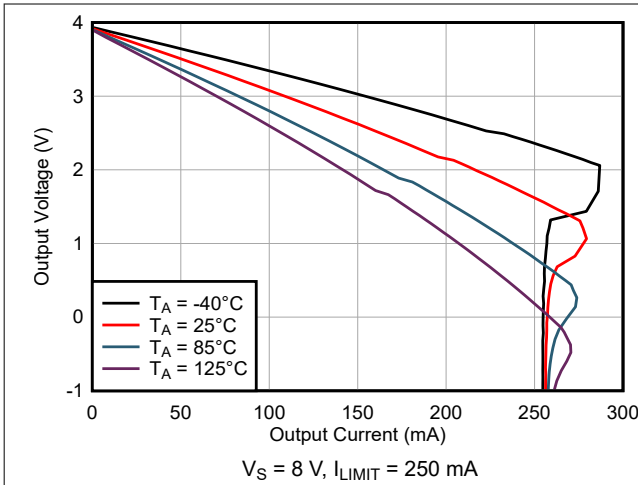


图 6-25. Output Voltage vs Output Sourcing Current

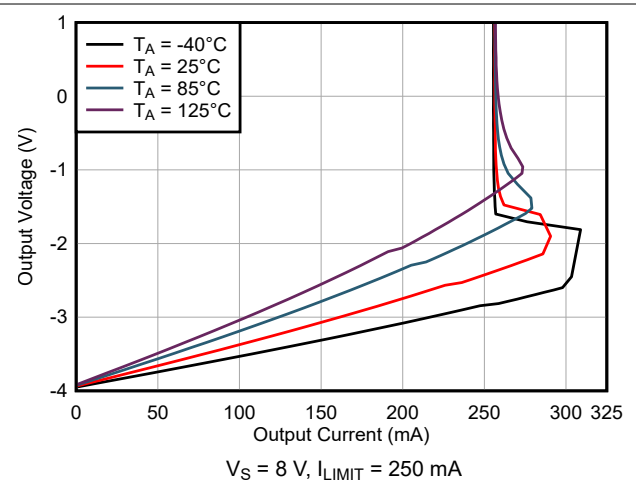


图 6-26. Output Voltage vs Output Sinking Current

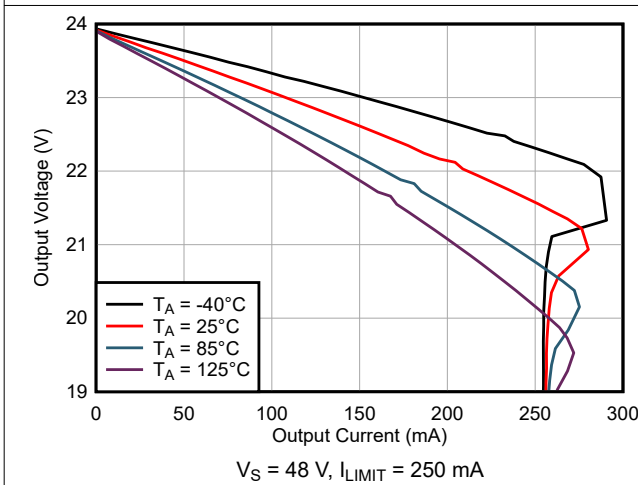


图 6-27. Output Voltage vs Output Sourcing Current

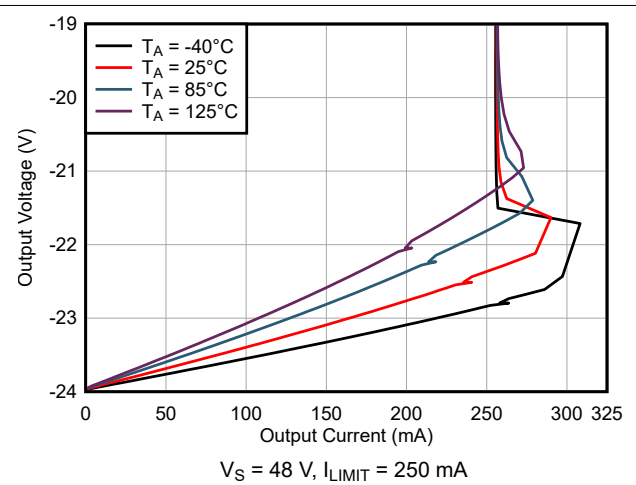


图 6-28. Output Voltage vs Output Sinking Current

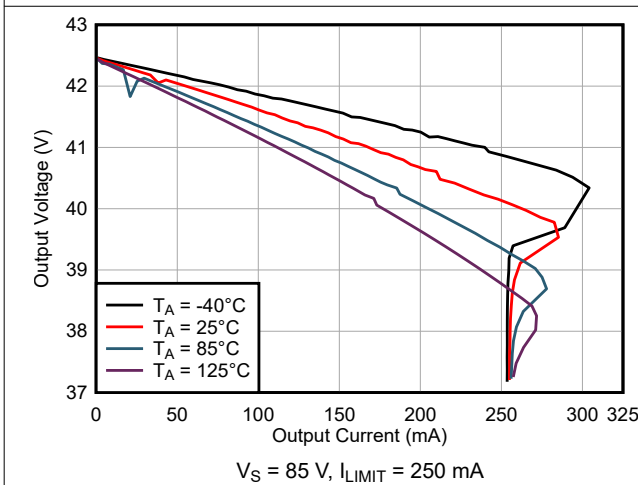


图 6-29. Output Voltage vs Output Sourcing Current

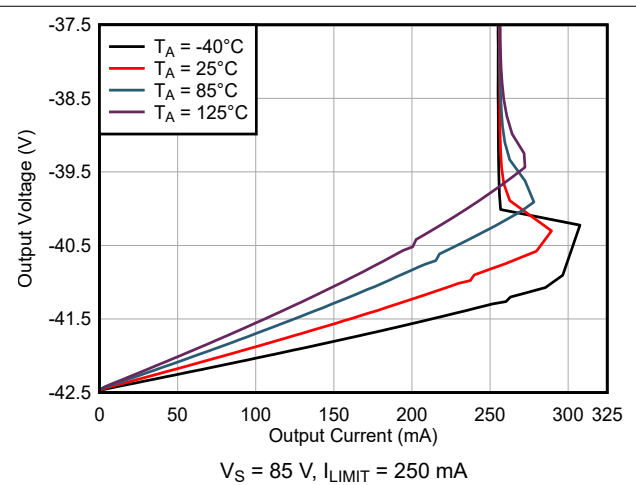


图 6-30. Output Voltage vs Output Sinking Current

### 6.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = (V+) - (V-) = 85\text{ V}$ ,  $I_{LIMIT} = 100\text{ mA}$ ,  $V_{CM} = V_{OUT} = V_S/2$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_S/2$  (unless otherwise noted)

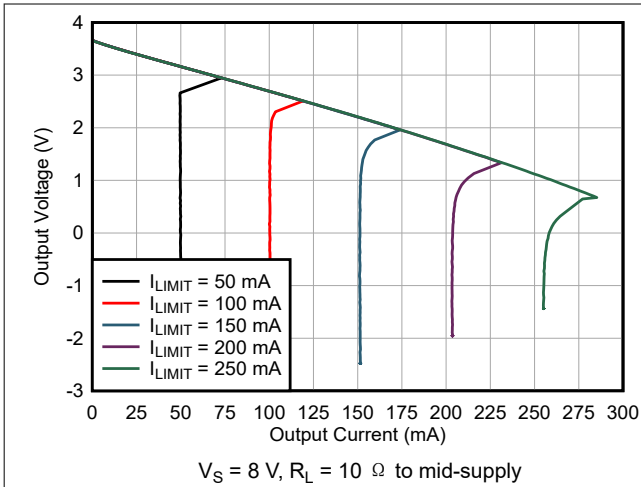


图 6-31. Output Voltage vs Current Limit Set

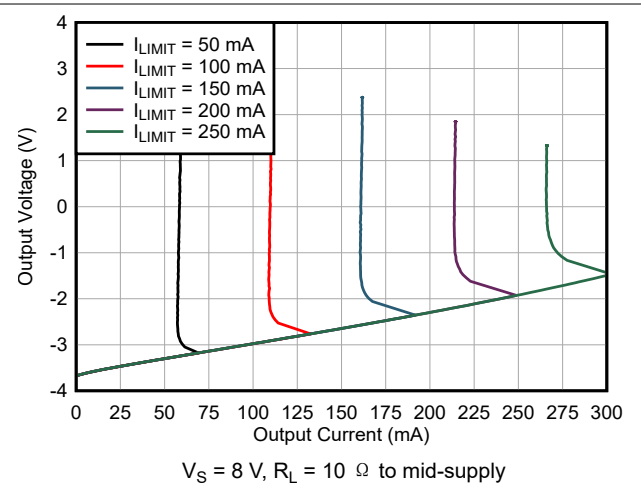


图 6-32. Output Voltage vs Current Limit Set

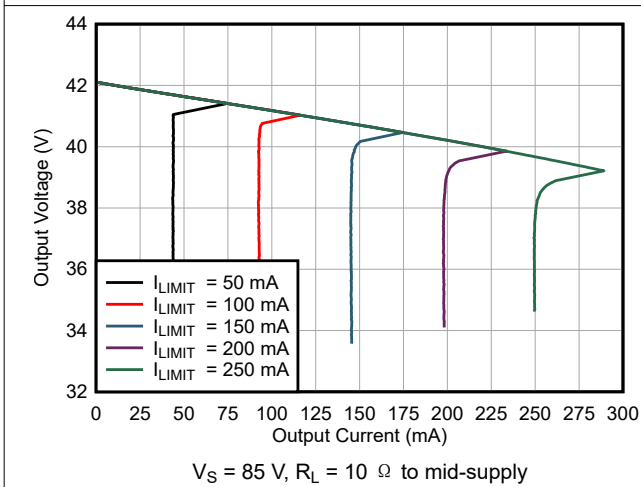


图 6-33. Output Voltage vs Output Sourcing Current

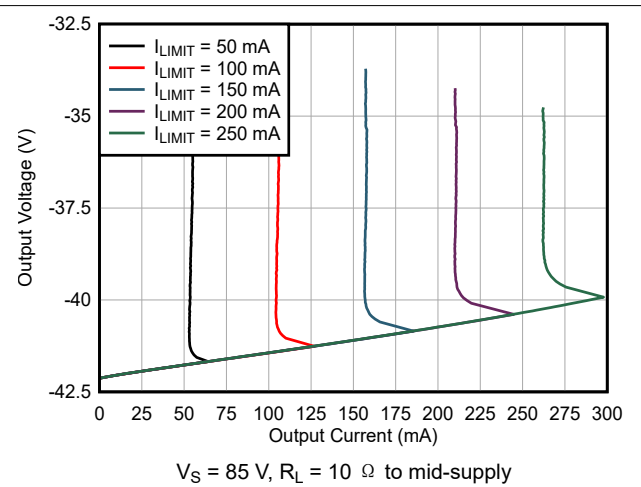


图 6-34. Output Voltage vs Output Sinking Current

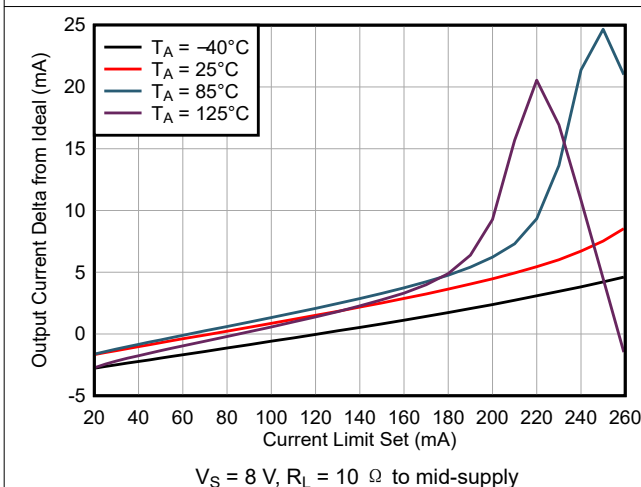


图 6-35. Output Sourcing Current Error vs Current Limit Set

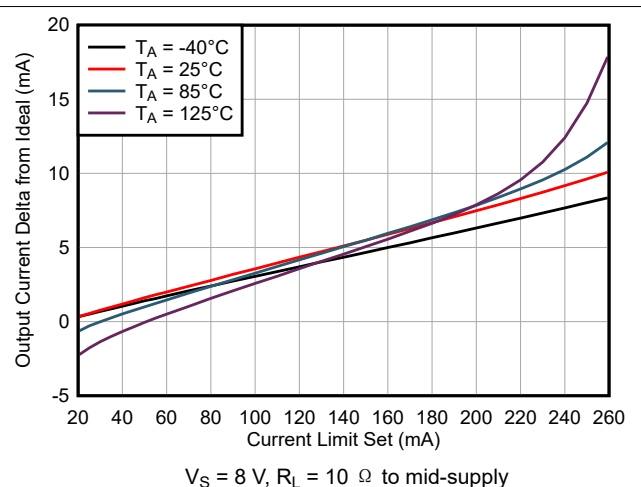


图 6-36. Output Sinking Current Error vs Current Limit Set

### 6.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = (V+) - (V-) = 85\text{ V}$ ,  $I_{\text{LIMIT}} = 100\text{ mA}$ ,  $V_{\text{CM}} = V_{\text{OUT}} = V_S/2$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_S/2$  (unless otherwise noted)

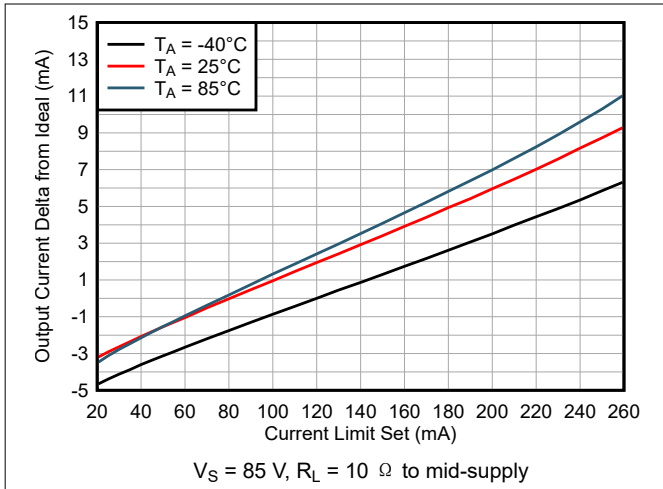


图 6-37. Output Sourcing Current Error vs Current Limit Set

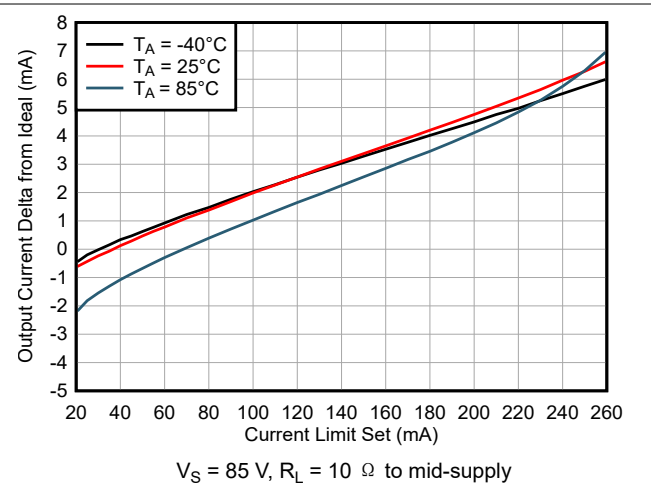


图 6-38. Output Sinking Current Error vs Current Limit Set

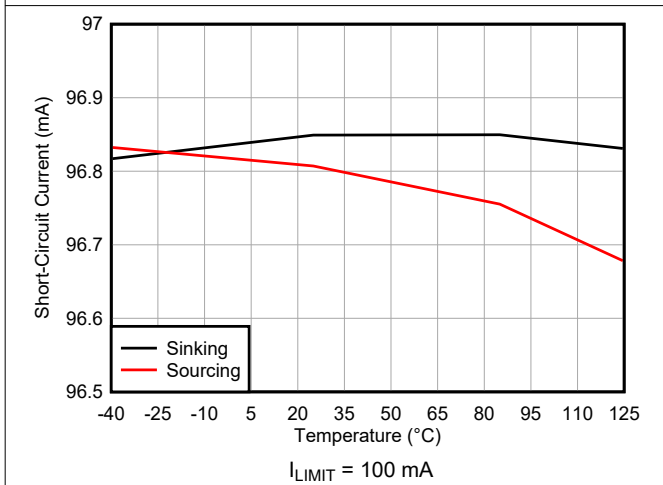


图 6-39. Short Circuit Current vs Temperature

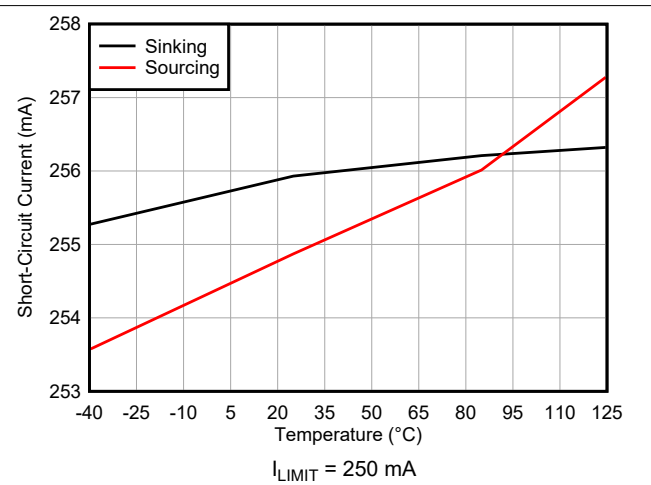


图 6-40. Short Circuit Current vs Temperature

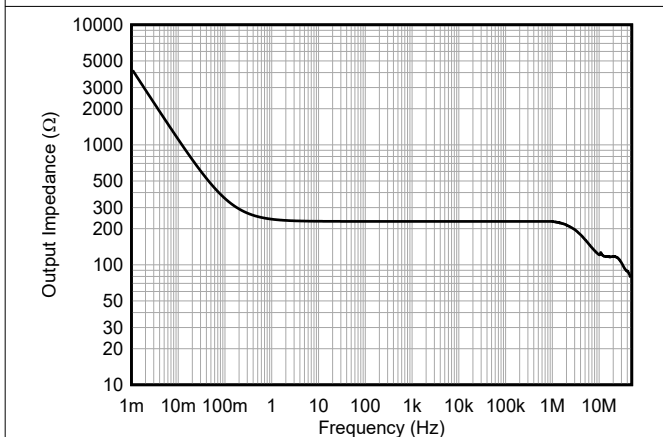


图 6-41. Open-Loop Output Impedance vs Frequency

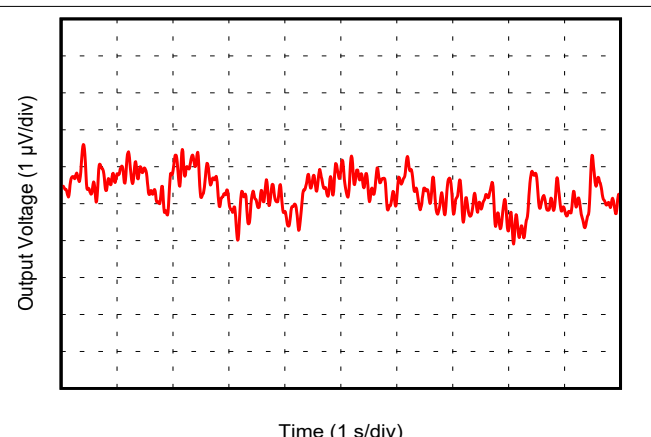


图 6-42. 0.1-Hz to 10-Hz Noise

### 6.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = (V+) - (V-) = 85\text{ V}$ ,  $I_{\text{LIMIT}} = 100\text{ mA}$ ,  $V_{\text{CM}} = V_{\text{OUT}} = V_S/2$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_S/2$  (unless otherwise noted)

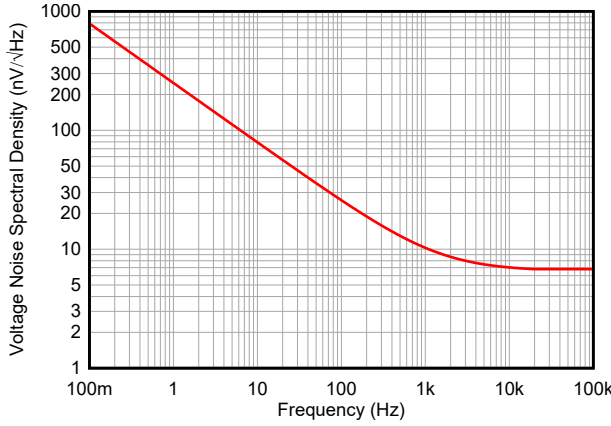


图 6-43. Input Voltage Noise Spectral Density

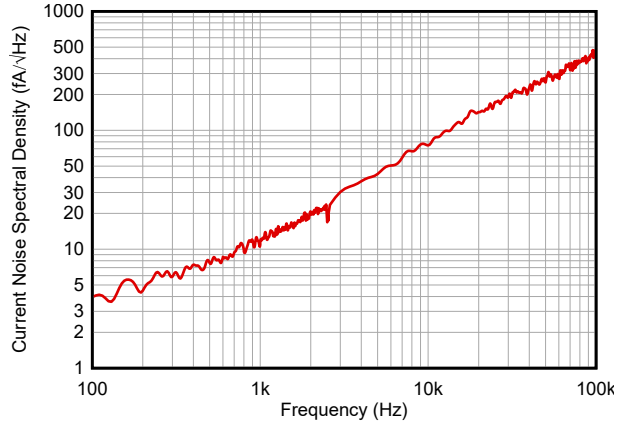


图 6-44. Input Current Noise Spectral Density

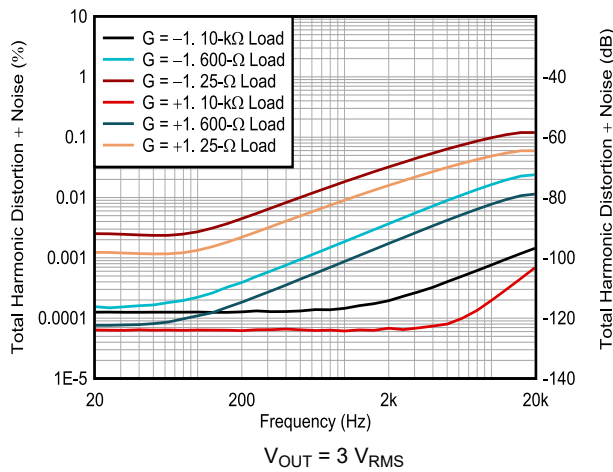


图 6-45. Total Harmonic Distortion + Noise vs Frequency

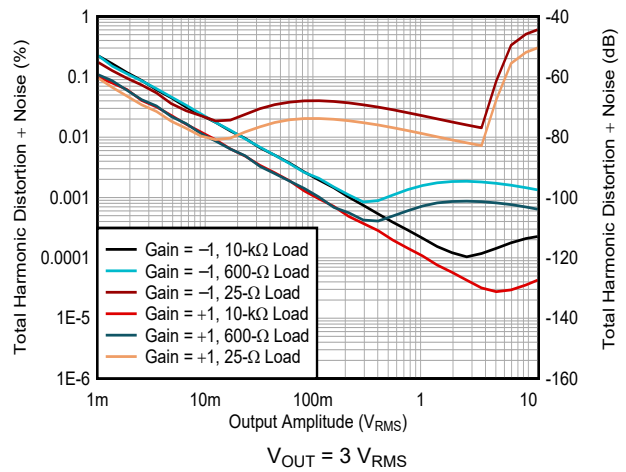


图 6-46. Total Harmonic Distortion + Noise vs Amplitude

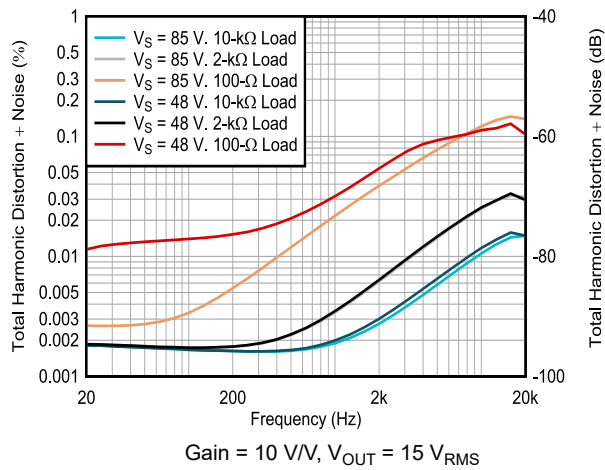


图 6-47. Total Harmonic Distortion + Noise vs Frequency

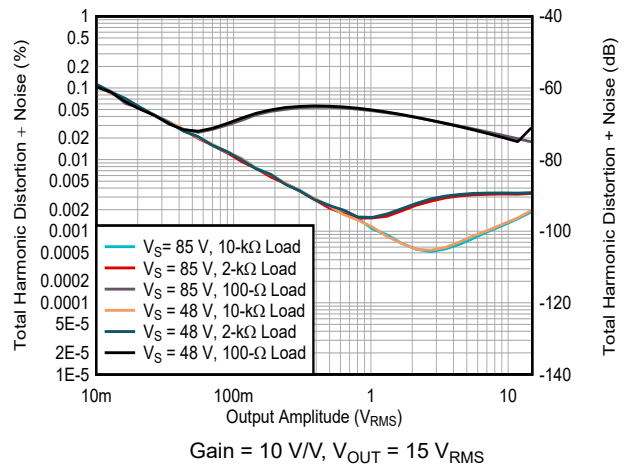


图 6-48. Total Harmonic Distortion + Noise vs Amplitude



### 6.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = (V+) - (V-) = 85\text{ V}$ ,  $I_{\text{LIMIT}} = 100\text{ mA}$ ,  $V_{\text{CM}} = V_{\text{OUT}} = V_S/2$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_S/2$  (unless otherwise noted)

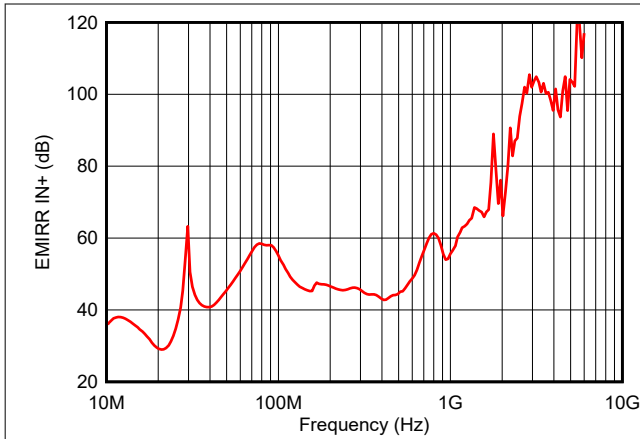


图 6-49. EMIRR vs Frequency

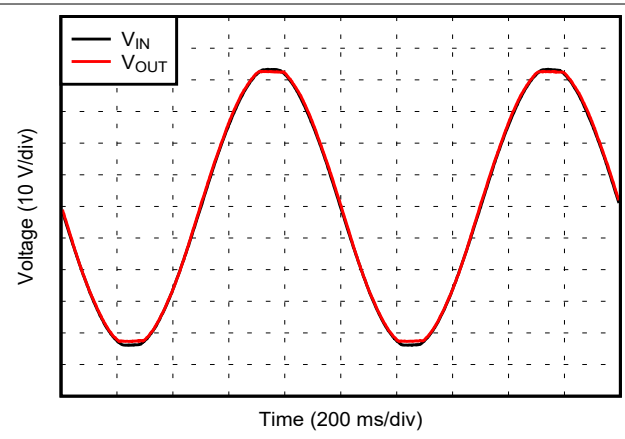


图 6-50. No Phase Reversal

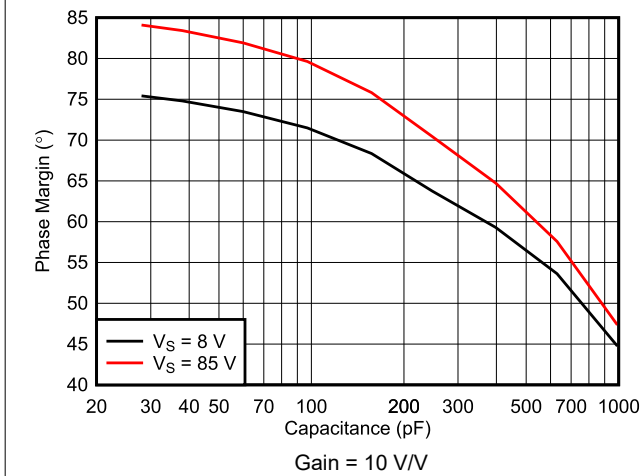


图 6-51. Phase Margin vs Capacitive Load

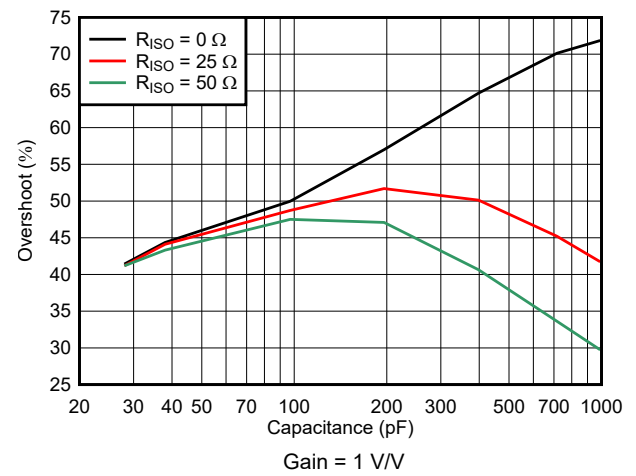


图 6-52. Small-Signal Overshoot vs Capacitive Load

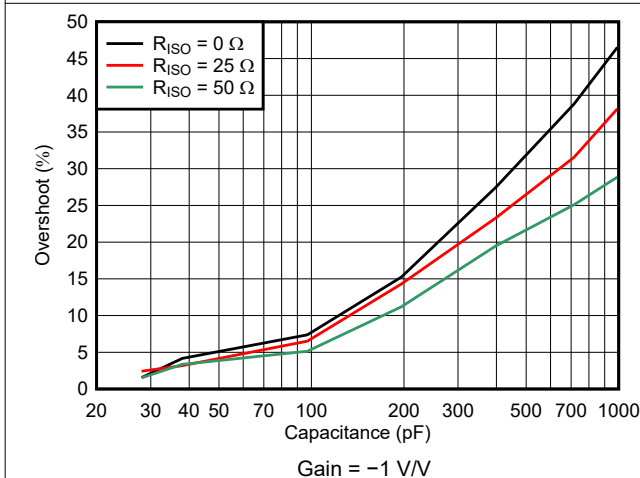


图 6-53. Small-Signal Overshoot vs Capacitive Load

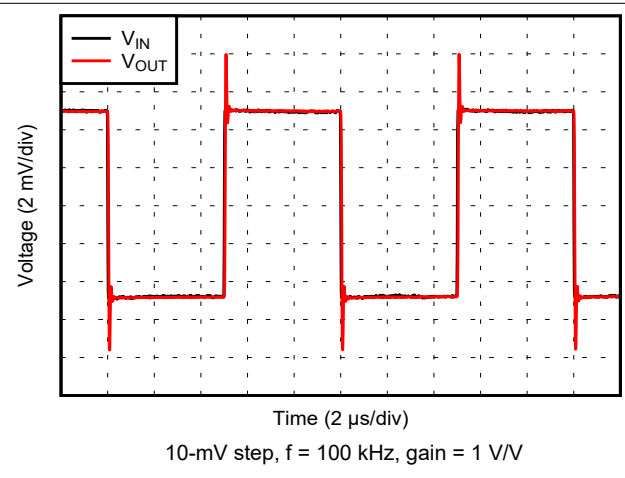
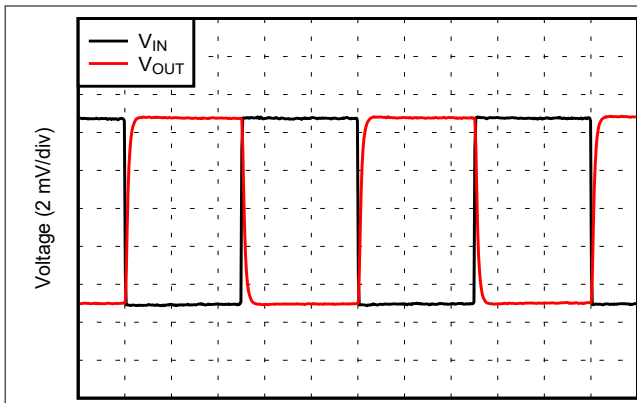


图 6-54. Small-Signal Step Response

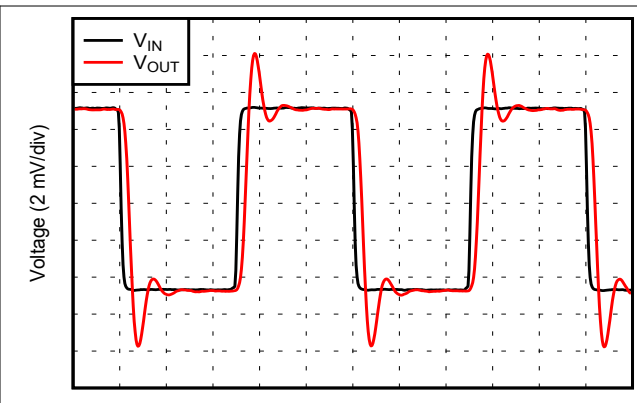
### 6.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = (V+) - (V-) = 85\text{ V}$ ,  $I_{\text{LIMIT}} = 100\text{ mA}$ ,  $V_{\text{CM}} = V_{\text{OUT}} = V_S/2$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_S/2$  (unless otherwise noted)



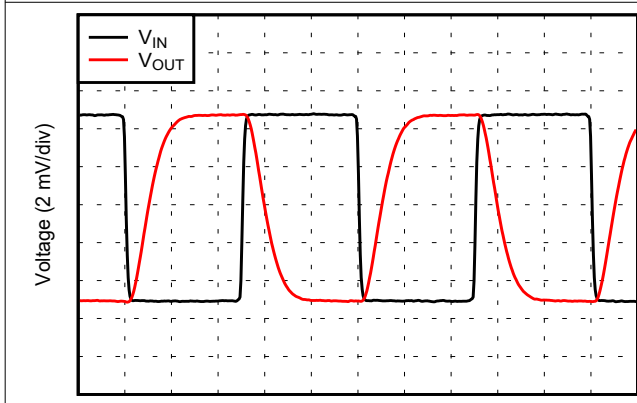
Time (2  $\mu\text{s}/\text{div}$ )  
10-mV step,  $f = 100\text{ kHz}$ , gain = -1 V/V

图 6-55. Small-Signal Step Response



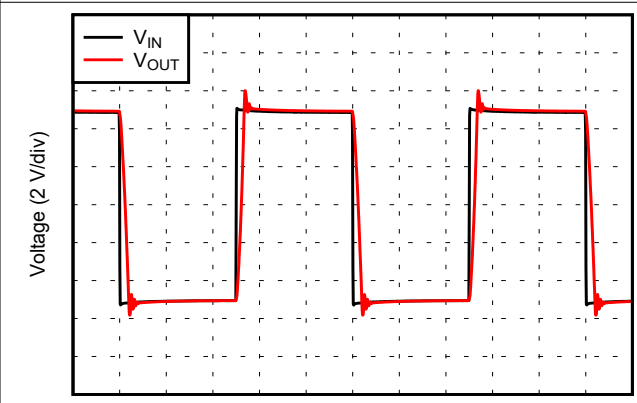
Time (200 ns/div)  
10-mV step,  $f = 1\text{ MHz}$ , gain = 1 V/V

图 6-56. Small-Signal Step Response



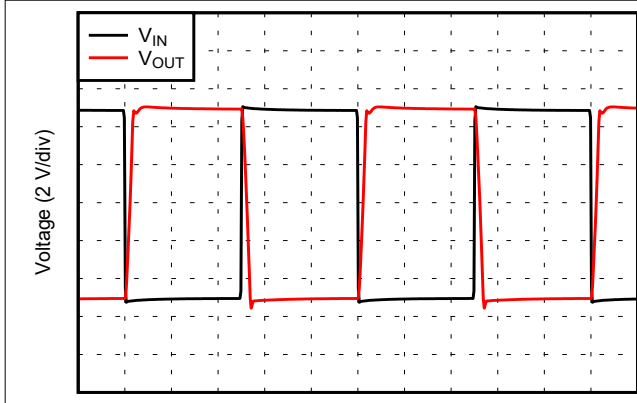
Time (200 ns/div)  
10-mV step,  $f = 1\text{ MHz}$ , gain = -1 V/V

图 6-57. Small-Signal Step Response



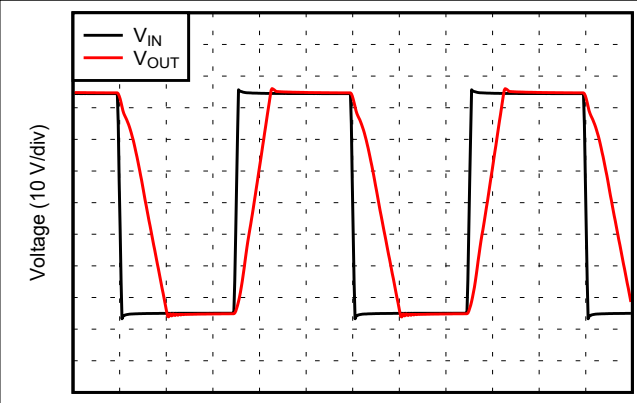
Time (2  $\mu\text{s}/\text{div}$ )  
10-V step,  $f = 100\text{ kHz}$ , gain = 1 V/V

图 6-58. Large-Signal Step Response



Time (2  $\mu\text{s}/\text{div}$ )  
10-V step,  $f = 100\text{ kHz}$ , gain = -1 V/V

图 6-59. Large-Signal Step Response



Time (2  $\mu\text{s}/\text{div}$ )  
70-V step,  $f = 100\text{ kHz}$ , gain = 1 V/V

图 6-60. Large-Signal Step Response

## 6.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = (V+) - (V-) = 85\text{ V}$ ,  $I_{\text{LIMIT}} = 100\text{ mA}$ ,  $V_{\text{CM}} = V_{\text{OUT}} = V_S/2$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_S/2$  (unless otherwise noted)

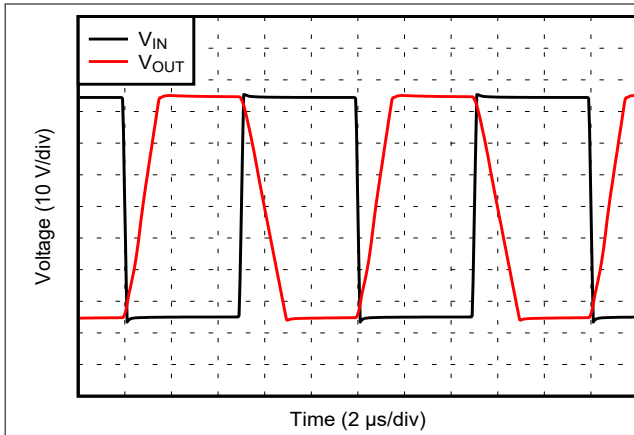


图 6-61. Large-Signal Step Response

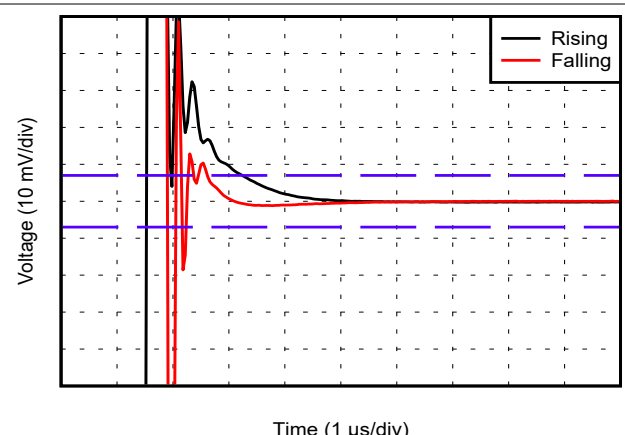


图 6-62. Settling Time

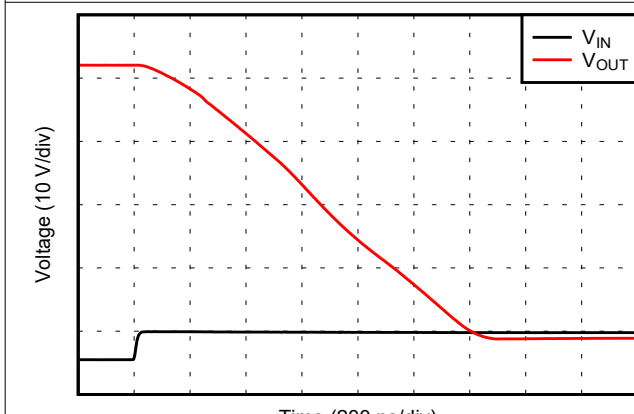


图 6-63. Positive Overload Recovery

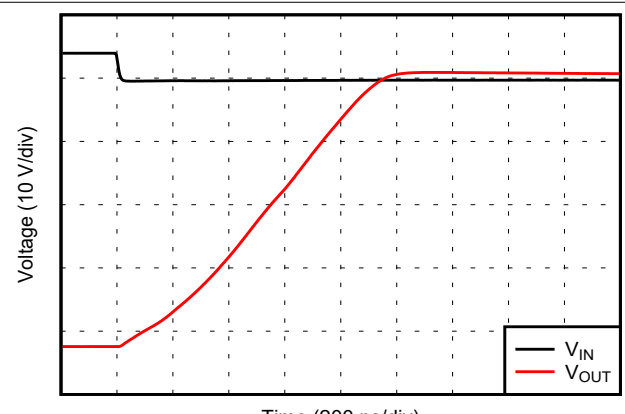


图 6-64. Negative Overload Recovery

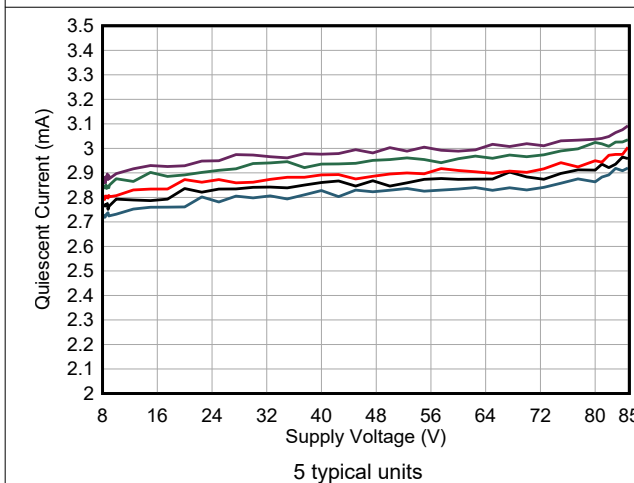


图 6-65. Quiescent Current vs Supply Voltage

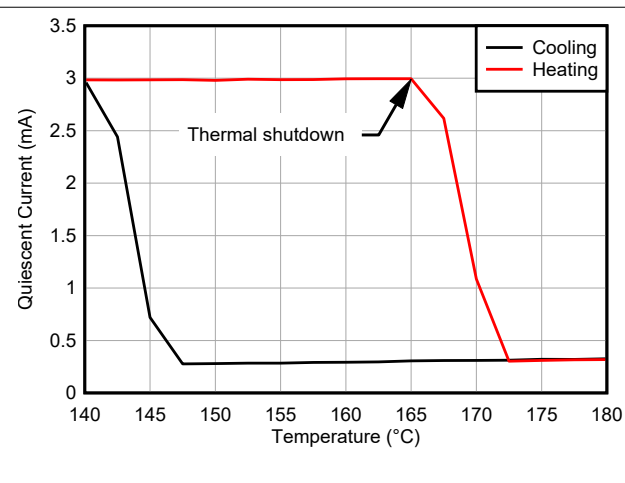


图 6-66. Quiescent Current Temperature Response

### 6.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = (V+) - (V-) = 85\text{ V}$ ,  $I_{\text{LIMIT}} = 100\text{ mA}$ ,  $V_{\text{CM}} = V_{\text{OUT}} = V_S/2$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_S/2$  (unless otherwise noted)

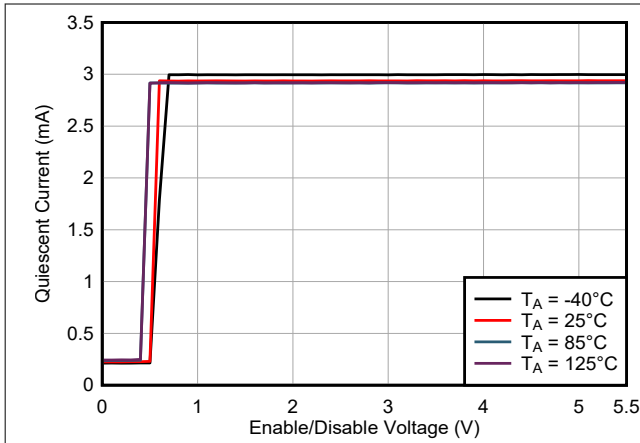


图 6-67. Quiescent Current vs Enable Voltage

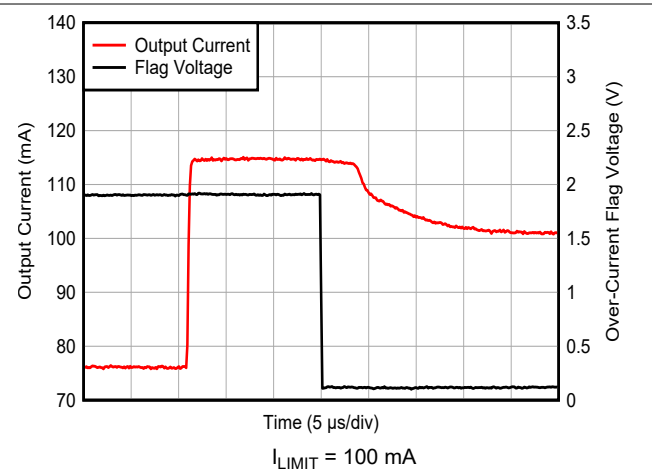


图 6-68. Current Limit Response

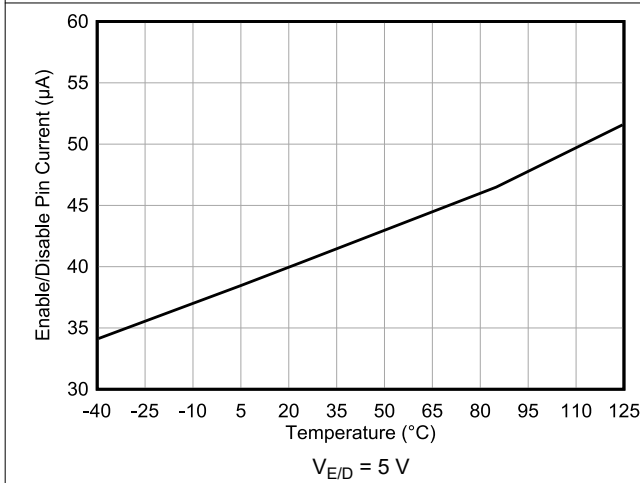


图 6-69. Enable/Disable Pin Current vs Temperature

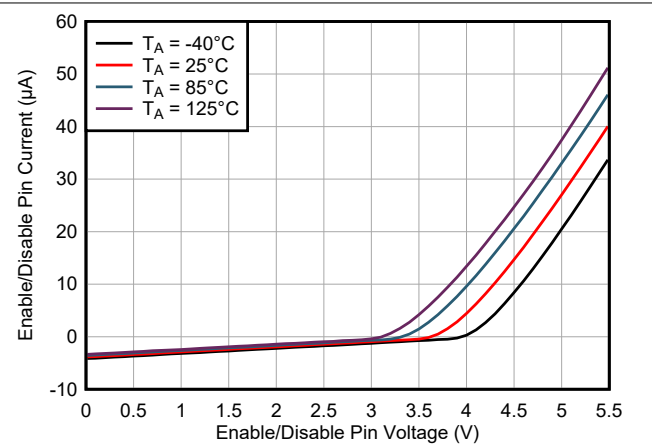


图 6-70. Enable Pin Current vs Enable Pin Voltage

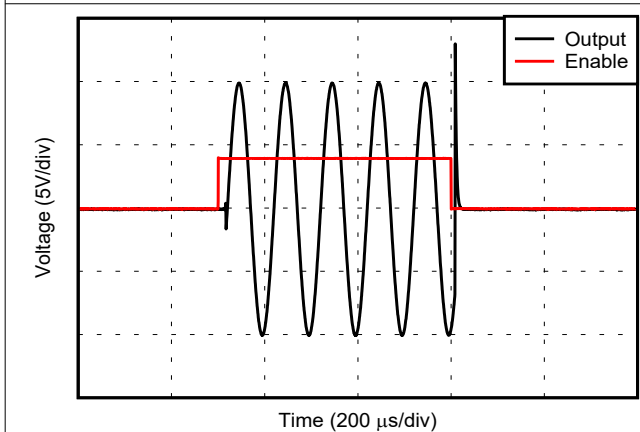


图 6-71. Enable Response

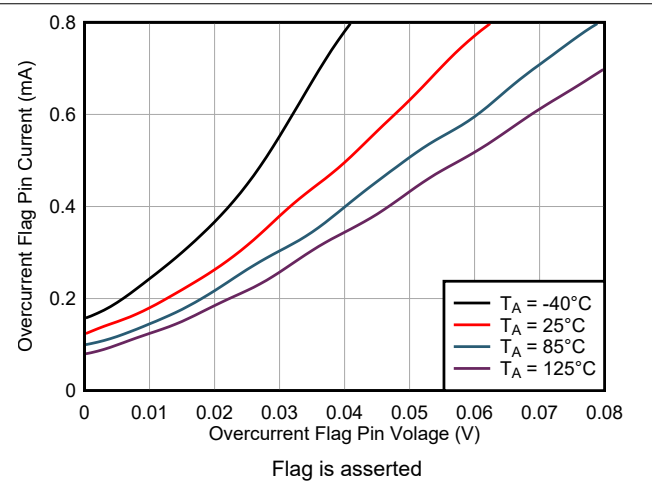


图 6-72. Current-Limit Flag Pin vs Current-Limit Flag Pin Voltage

### 6.6 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_S = (V+) - (V-) = 85\text{ V}$ ,  $I_{\text{LIMIT}} = 100\text{ mA}$ ,  $V_{\text{CM}} = V_{\text{OUT}} = V_S/2$ , and  $R_L = 10\text{ k}\Omega$  connected to  $V_S/2$  (unless otherwise noted)

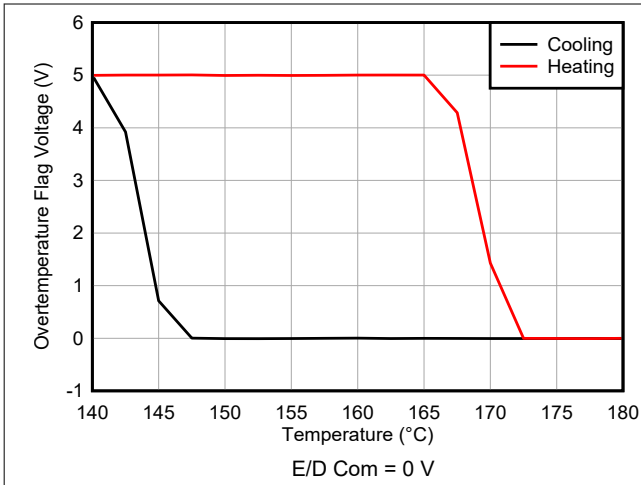


图 6-73. Overtemperature Flag Pin Voltage vs Temperature

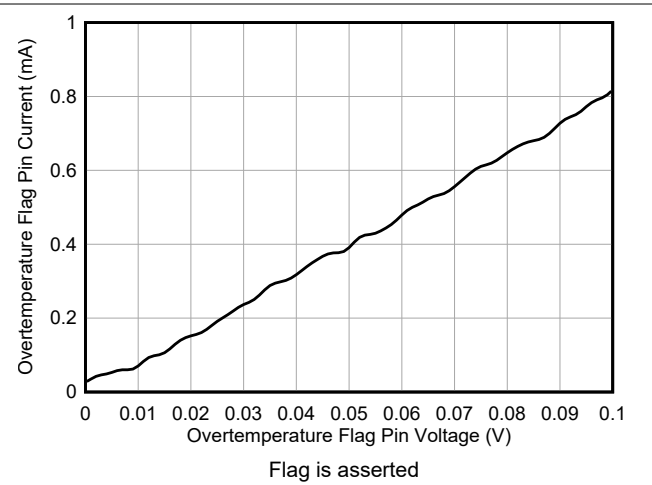


图 6-74. Overtemperature Flag Pin Current vs Overtemperature Flag Pin Voltage

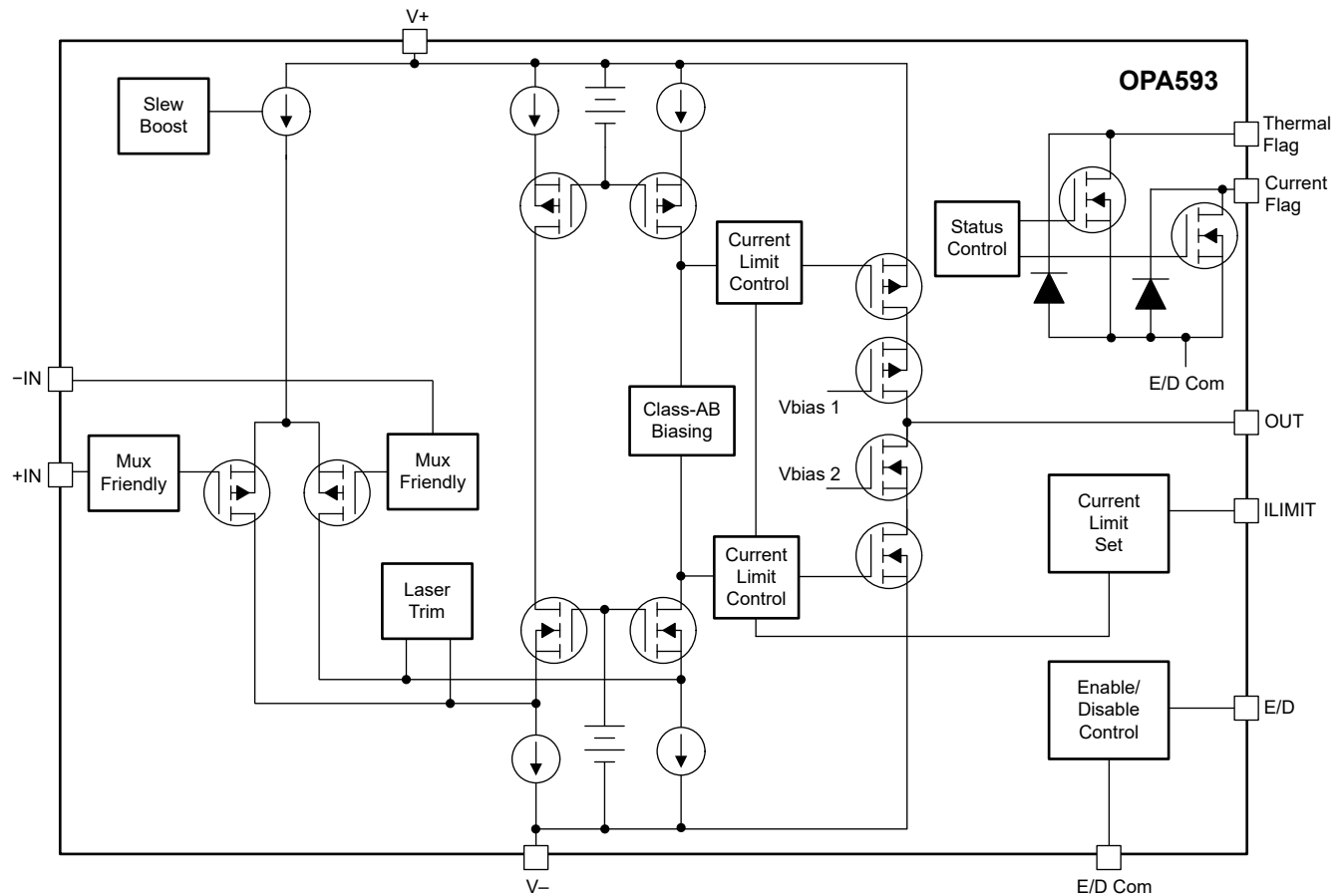
## 7 Detailed Description

### 7.1 Overview

The OPA593 is a precision, high-voltage (85 V), wide bandwidth (10 MHz), power operational amplifier (op amp) with a high output current drive of  $\pm 250$  mA. The device features a current limit that helps protect the system in the event of an output short to ground. Unlike other power op amps, the current limit is specified for specific current ranges from  $\pm 25$  mA to  $\pm 250$  mA. Additionally, the device has two flags that indicate an overcurrent fault condition (beyond the configured limit) and an overtemperature fault condition (when the output stage shuts down to protect the device from overheating). Lastly, the output can be disabled to save system power and reduce thermal dissipation.

The unity-gain stable OPA593 has no phase inversion, a common-mode voltage range that includes the negative rail, a wide output swing range, and high dc precision. All these features make the OPA593 an excellent choice as an output driver for a device under test (DUT) in automated test equipment (ATE) systems, or for signal processing in industrial systems using signals greater than 36 V.

### 7.2 Functional Block Diagram



## 7.3 Feature Description

### 7.3.1 Current Limit

The OPA593 current limit is set through the I<sub>LIMIT</sub> pin and is programmable from ±25 mA to ±250 mA, typical. The device is specified and tested for current limits of ±25 mA, ±50 mA, ±100 mA, ±250 mA. A resistor can be used to limit the current to a fixed value or a digital-to-analog converter (DAC) can be used to vary the current limit during operation. 图 7-1 shows a simplified diagram of the current-limit mirror configurations, as well as common resistor or DAC settings and the respective output current limit.

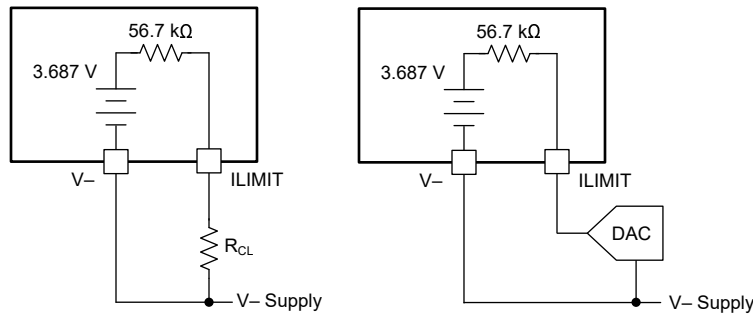


图 7-1. OPA593 Internal Current Limit Configurations

The most common configuration is to set the current limit using a resistor ( $R_{CL}$ ) connected between the I<sub>LIMIT</sub> pin and the negative supply ( $V^-$ ). With this configuration, 方程式 1 and 方程式 2 are used to calculate the current limit based on the external resistor value or the resistor needed given the desired current limit value:

$$I_{LIMIT} = \frac{3.687 V \times 4000}{56.7 k\Omega + R_{CL}} \quad (1)$$

$$R_{CL} = \frac{3.687 V \times 4000}{I_{LIMIT}} - 56.7 k\Omega \quad (2)$$

An alternative to fixing the current limit to a single value using an external resistor is to use a source measure unit (SMU) or digital-to-analog converter (DAC), which enables a variable current limit.

#### CAUTION

With this configuration, the output of the SMU or DAC must not exceed the  $I_{LIMIT}$  specification in 节 6.1 to avoid reverse biasing the internal current limit circuitry and potentially damaging the device.

Use 方程式 3 to set the current limit when a DAC is used ( $V_{LIMIT} = \text{DAC output voltage}$ ):

$$V_{LIMIT} = 3.687 V - \frac{I_{LIMIT} \times 56.7 k\Omega}{4000} \quad (3)$$

Be aware that the SMU or DAC output voltage must be referenced to the negative supply of the OPA593. Several nominal current-limit values along with the respective external resistor values and DAC output voltages are listed in 表 7-1.

表 7-1. Nominal Current-Limit Values

CURRENT LIMIT, $I_{LIMIT}$ (mA)	RESISTOR, $R_{CL}$ (k $\Omega$ )	DAC VOLTAGE, $V_{LIMIT}$ (V) <sup>(1)</sup>
25	536	3.33
50	237	2.98
100	90.9	2.27
200	16.9	0.85
250	2.29	0.14

(1) Voltages are referenced to the negative supply,  $V^-$

While the current limit tolerance of the OPA593 is specified for specific current limit levels, any resistor, SMU, or DAC inaccuracies add to the listed tolerance. To achieve the desired system level accuracy, take care when selecting these external components. 图 7-2 shows a correlation between the ideal or calculated output current limit and the actual current limit as measured on the OPA593.

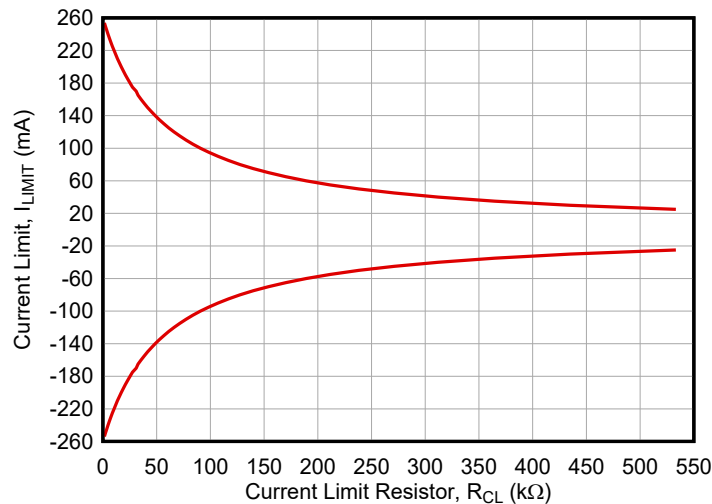


图 7-2. Typical Output Current vs Current-Limit Resistor Value

### 7.3.2 Overcurrent Flag

The OPA593 features an overcurrent flag (Current Flag pin) that indicates a condition where the output current exceeds the limit established by the ILIMIT pin. For example, in an output short-to-ground fault condition, the overcurrent flag asserts, which pulls the flag pin low to E/D Com, and the output current is limited to the value set by ILIMIT. This flag is an open-drain output compatible with standard low-voltage logic circuitry, such as a microcontroller (MCU). Use a 5-k $\Omega$  to 10-k $\Omega$  pullup resistor to limit the input current when the flag is asserted. If this feature is not used, leave this pin floating.

### 7.3.3 Overtemperature Flag

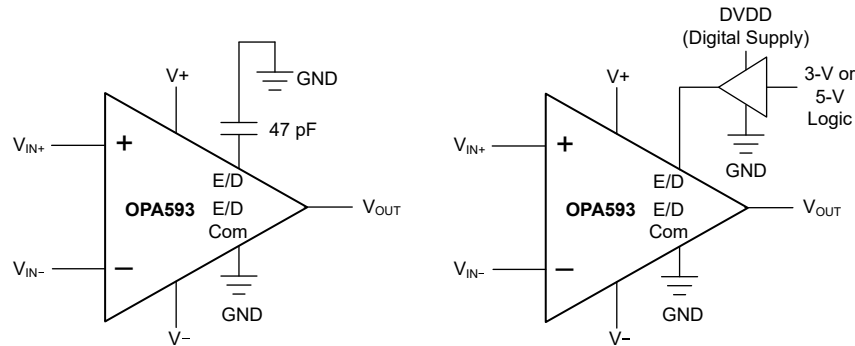
The OPA593 has internal thermal protection. When the junction temperature reaches approximately 170°C, the op amp output stage disables and the overtemperature flag (Thermal Flag pin) is asserted, which pulls the flag pin low to E/D Com. When the junction temperature cools to a safe operating temperature, approximately 150°C, the output stage is enabled, and the op amp resumes normal operation. This flag is an open-drain output compatible with standard low-voltage logic circuitry, such as an MCU. Use a 5-k $\Omega$  to 10-k $\Omega$  pullup resistor to limit the input current when the flag is asserted. If this feature is not used, leave this pin floating.



### 7.3.4 Output Enable and Disable

The OPA593 incorporates an enable and disable feature that uses the E/D pin to disable the output stage of the amplifier, which reduces the power consumption of the op amp and switches the output to a high-impedance state.

The E/D pin is referenced to the E/D Com pin. If left floating, the E/D pin is internally pulled up to enable the device. If externally controlled, the E/D pin must be supplied with a voltage between 1.5 V and 5.5 V greater than the E/D Com pin voltage. Even though the OPA593 output is enabled with a floating E/D pin, a moderately fast, negative-going signal capacitively coupled to the E/D pin can overpower the internal pullup and cause device shutdown. If the enable function is not used, a conservative and recommended approach is to connect E/D through a 47-pF capacitor to E/D Com. [图 7-3](#) shows different ways to connect the E/D and E/D Com pins.

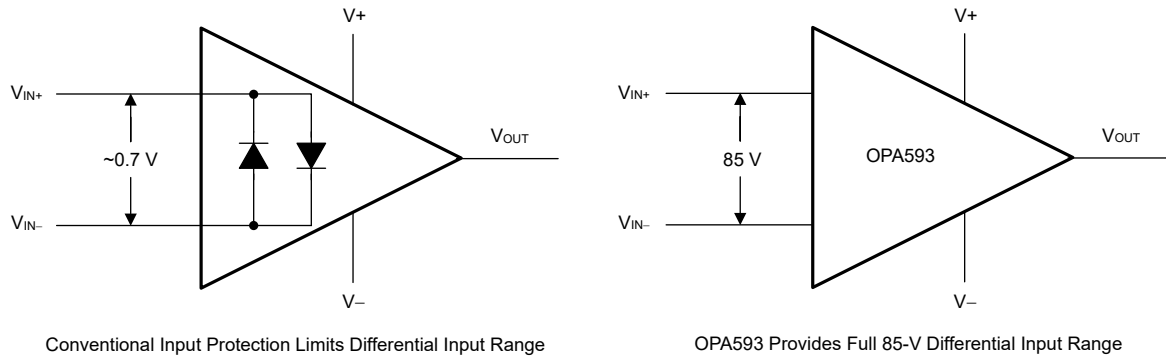


**图 7-3. E/D and E/D Com Pin Connections**

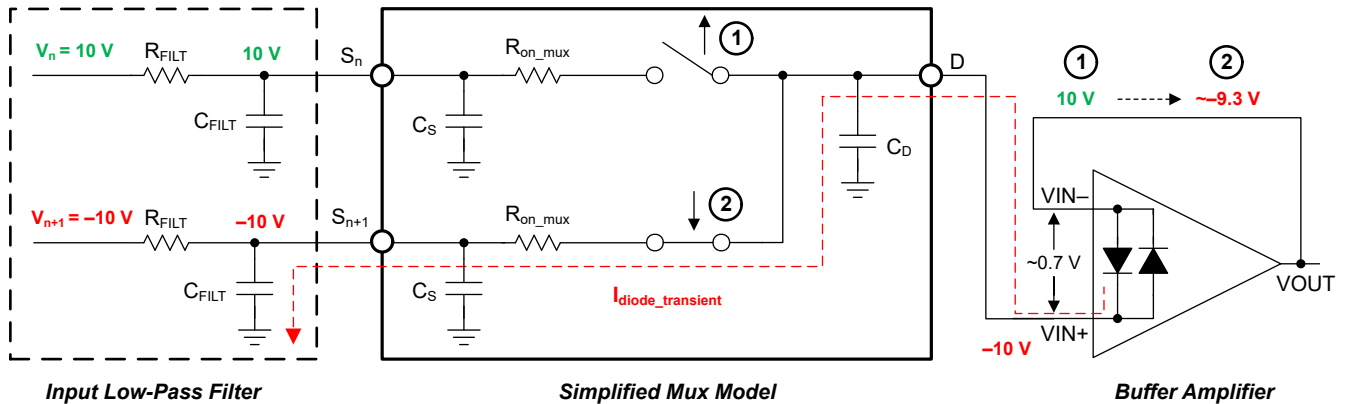
When the E/D pin is dropped to a voltage between 0 V and 0.5 V greater than the E/D Com pin voltage, the output of the OPA593 is disabled. When disabled, the output of the OPA593 is set to a high-impedance state.

### 7.3.5 Mux-Friendly Inputs

The OPA593 uses a unique input architecture to eliminate the need for input protection diodes but still provides robust input protection under transient conditions. Conventional input diode protection schemes shown in [图 7-4](#) can be activated by fast transient step responses and can introduce signal distortion and settling time delays because of alternate current paths, as shown in [图 7-5](#). For low-gain circuits, these fast-ramping input signals forward-bias back-to-back diodes that cause an increase in input current, resulting in extended settling time.



**图 7-4. OPA593 Input Protection Does Not Limit Differential Input Capability**



**图 7-5. Back-to-Back Diodes Create Settling Issues**

The OPA593 a true high-impedance differential input capability for high-voltage applications. This patented input protection architecture does not introduce additional signal distortion or delayed settling time, making this device an excellent choice for multichannel, high-switched, input applications. The OPA593 tolerates a maximum differential swing (voltage between inverting and noninverting pins of the op amp) of up to 85 V, making this device a great choice for use as a comparator or in applications with fast-ramping or switched input signals.

### 7.4 Device Functional Modes

The OPA593 has two modes of operation. The first mode is normal operation where the amplifier is enabled, either by supplying a voltage to the enable-disable (E/D) pin that is between 2.5 V and 5 V greater than the E/D Com pin or by leaving the E/D pin floating. The second mode of operation is a low-power, disabled state where the E/D pin is driven between 0 V and 0.65 V greater than the E/D Com pin. In this state, the amplifier output is disabled and enters a high-output-impedance state.

## 8 Application and Implementation

### 备注

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

### 8.1 Application Information

The OPA593 is a precision, high-voltage, high-output-current op amp. The device is capable of operating with supplies as low as  $\pm 4$  V (8 V) and as high as  $\pm 42.5$  V (85 V). The current limit feature limits the output current, up to  $\pm 250$  mA, to a specified accuracy. With a small size, high operating voltage range, output current, and high dc precision, the device is designed to operate as a high-gain stage, capable of driving heavy loads and condition large signals. The additional features of the OPA593, including the current limit, overcurrent and overtemperature flags, thermal protection, output disable, and mux-friendly inputs, help protect both the op amp and the system from potential damage due to various fault conditions.

### 8.2 Typical Application

#### 8.2.1 Output Driver

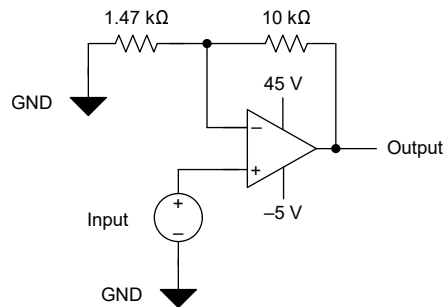


图 8-1. Output Driver Configured With a Gain of 8

#### 8.2.1.1 Design Requirements

The OPA593 is designed for use as an output driver stage with gain and provides a wide supply voltage and high output current with programmable current limit. Combined with the small size of the 4-mm  $\times$  4-mm WSON package, these features make this device a great choice for high-channel density systems, such as semiconductor test and manufacturing platforms where many channels are present. In this design example, the OPA593 is configured for a gain of 8 V/V. A small negative supply is provided if the application requires a small output voltage. For example, in the case of a device under test (DUT) continuity check, the amplifier is able to provide the output without being limited by the negative rail (that is, saturating the output).

表 8-1. Design Parameters

PARAMETER	VALUE
Supply voltage	+45 V, - 5 V
Input voltage	0 V to 5 V
Output voltage	0 V to 40 V
System gain	8
Output current	Up to 250 mA

### 8.2.1.2 Detailed Design Procedure

In this design example, the OPA593 is configured as both a gain stage and output driver. The input signal to the amplifier is 0 V to 5 V, and the device is configured with a positive gain of 8. This configuration results in an output voltage of 0 V to 40 V. Select supply voltages that provide adequate headroom so that the amplifier can sink or source up to 250 mA without *slamming* the output into the rail. Minimize the swing from the supply to the output to minimize the thermal dissipation of the device.

This simple design example is common in many systems that use a DAC to provide the input signal and require a wide output signal with high output current. Such systems include test and measurement platforms and power supplies.

图 8-2 shows the input and output signal of this OPA593 circuit.

### 8.2.1.3 Application Curve

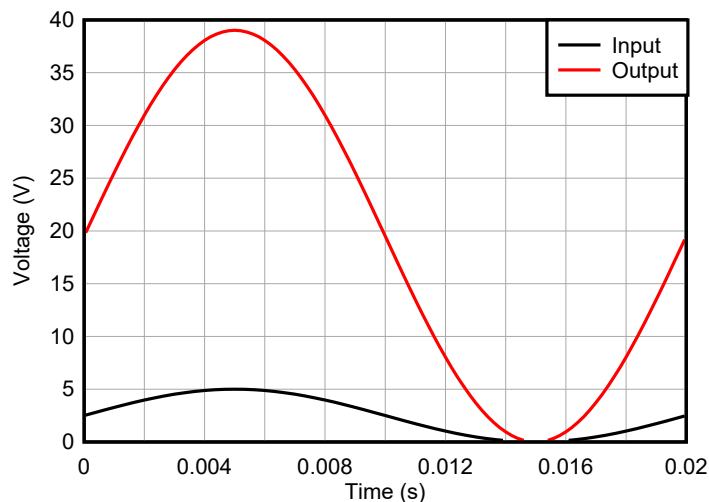


图 8-2. OPA593 Output Driver Circuit, Input and Output Signals

## 8.2.2 High Voltage 2:1 Multiplexer With Unity Gain

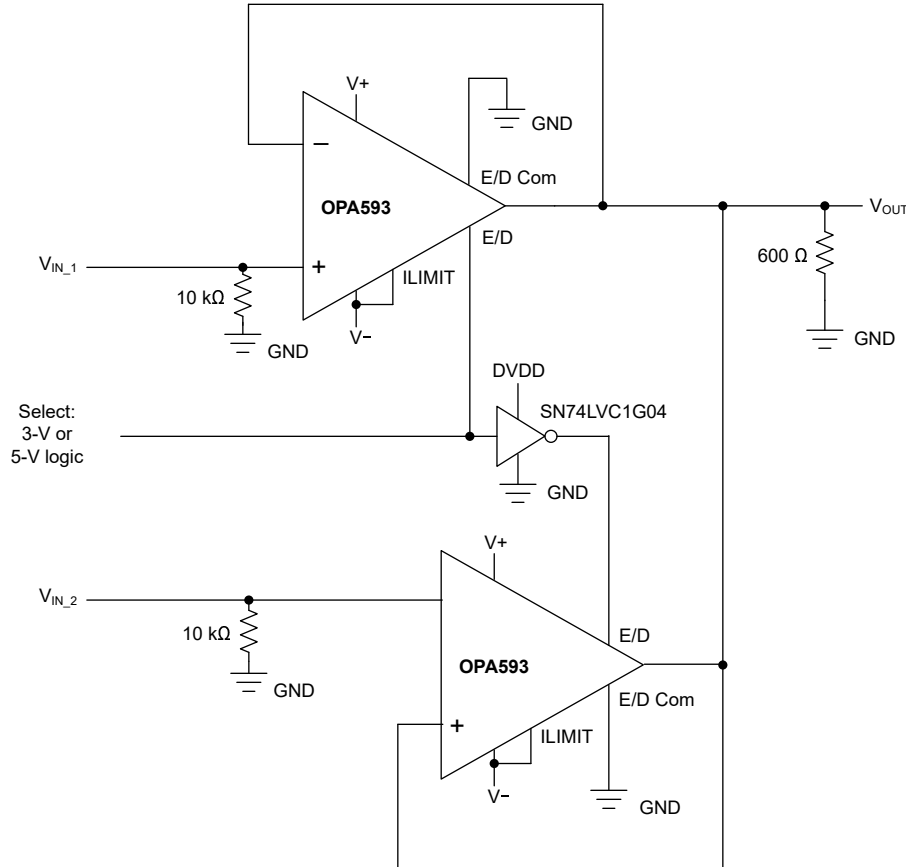


图 8-3. High Voltage 2:1 Multiplexer With Unity Gain

### 8.2.2.1 Design Requirements

The OPA593 operates on high-voltage supplies up to 85 V and is used to create a high voltage multiplexer (MUX) with a gain of 1 or higher. This design example uses two OPA593 op amps and makes use of the disable function. The high-impedance state of the output while the amplifier is disabled allows for the outputs of two OPA593 op amps to be connected together.

### 8.2.2.2 Detailed Design Procedure

In this design example, two OPA593 precision op amps are configured as a unity gain buffers powered with a  $\pm 42.5\text{-V}$  dual supply. The input signal to either amplifier can range from  $-40\text{ V}$  to  $+39\text{ V}$  to remain in linear operation. The output of the amplifiers are connected together and a 3-V or 5-V logic signal, serving as the output select, is used to toggle between the enable and disable modes of operation. The logic control signal is directly applied to one OPA593 E/D pin, and an inverter gate is used to drive the other OPA593 E/D pin. 图 8-3 shows a simplified representation of this circuit.

A clear benefit of this design is the high-voltage capability, along with the thermal protection, overcurrent protection, and current-limit features. The *mux-friendly* input of the OPA593 provides a full input differential range, avoiding the pitfalls of other amplifiers with traditional back-to-back diodes in this configuration. This design can also be reconfigured to include signal gain, but careful selection of the input and feedback resistors is required to minimize current leakage paths.

## 8.3 Power Supply Recommendations

The OPA593 operates from power supplies up to  $\pm 42.5$  V, or a total of 85 V, with excellent performance. Most behavior remains unchanged throughout the full operating voltage range. A power-supply bypass capacitor of at least 0.1  $\mu$ F is required for proper operation. Make sure that the capacitor voltage is rated for high voltage across the full operating temperature range. Parameters that vary significantly with operating voltage are shown in [节 6.6](#).

Some applications do not require an equal positive and negative output voltage swing. Power-supply voltages do not have to be equal. The OPA593 operates with as little as 8 V between the supplies, and with up to 85 V between the supplies.

## 8.4 Layout

### 8.4.1 Layout Guidelines

During the surface-mount solder operation (when the pins are being soldered), the thermal pad must be soldered to a copper area underneath the package. Through the use of thermal paths within this copper area, heat is conducted away from the package into a V- plane. Always solder the thermal pad to the PCB, even with applications that have low power dissipation. Follow these steps to attach the device to the PCB:

1. Connect the thermal pad to the most negative supply voltage on the device, V - .
2. Prepare the PCB with a top-side pattern. There must be patterning for the pins and thermal pad.
3. Thermal vias improve heat dissipation, but are not required.
4. Place recommended vias in the area of the thermal pad. Recommended thermal land size and thermal via patterns for the SON-12 DNT package are shown in the thermal land pattern mechanical drawing appended at the end of this document. Keep the vias small, so that solder wicking through the vias is not a problem during reflow. Use a 0.2-mm size via with a minimum of five connected directly below the thermal pad.
5. Additional vias can be placed anywhere along the thermal plane outside of the thermal pad area. These vias help dissipate the heat generated by the OPA593 device. These additional vias can be larger than the vias directly under the thermal pad because the additional vias are not in the thermal pad area to be soldered; thus, wicking is not a problem.
6. Connect all vias to the internal power plane of the correct voltage potential, V - .
7. When connecting these vias to the plane, do not use the typical web or spoke via connection methodology. Web connections have a high thermal resistance connection that is useful for slowing the heat transfer during soldering operations, making the soldering of vias that have plane connections easier. In this application, however, low thermal resistance is desired for the most efficient heat transfer. Therefore, the vias under the OPA593 WSON package must make the connections to the internal plane with a complete connection around the entire circumference of the plated-through hole.
8. The top-side solder mask must leave the pins of the package and the thermal pad area exposed. The bottom-side solder mask must cover the vias of the thermal pad area. This masking prevents solder from being pulled away from the thermal pad area during the reflow process.
9. Apply solder paste to the exposed thermal pad area and all of the device pins.
10. With these preparatory steps in place, simply place the device in position, and run through the solder reflow operation as with any standard surface-mount component.

### 8.4.1.1 Thermal Considerations

Through normal operation, the OPA593 self-heats. Self-heating is a natural increase in the die junction temperature that occurs in every amplifier. The maximum allowed junction temperature sets the maximum allowed internal power dissipation ( $P_D$ ) as described in the following paragraph. Design efforts should be made to prevent  $T_J$  from exceeding the maximum temperature listed in the *Absolute Maximum Ratings* table.

Operating junction temperature ( $T_J$ ) is determined by the ambient temperature ( $T_A$ ), the internal  $P_D$  under the operating conditions, and the junction-to-ambient thermal resistance ( $R_{\theta JA}$ ). This relationship is given by  $T_A + (P_D \times R_{\theta JA})$ .  $P_D$  is the sum of quiescent power ( $P_{DQ}$ ) and additional power dissipated in the output stage ( $P_{DL}$ ) when delivering power to the load.  $P_{DQ}$  is the specified no-load supply current times the total supply voltage across the part.  $P_{DL}$  depends on the required output signal and load, but for a grounded resistive load the  $P_{DL}$  is at a maximum when the output is fixed at a voltage equal to 1/2 of either supply voltage (for balanced bipolar supplies,  $V+$  and  $V-$ ). Under this condition  $P_{DL} = (V+)^2 / (4 \times R_L)$ , where  $R_L$  includes feedback network loading.

The power in the output stage and not into the load determines internal power dissipation.

As a worst-case example, compute the maximum  $T_J$  using the OPA593 in the circuit of [图 8-1](#) operating at a maximum specified temperature of 125°C and driving a grounded 600- $\Omega$  load.

$$P_D = P_{DQ} + P_{DL} \quad (4)$$

$$P_D = (50 V \times 4 mA) + \frac{22.5^2 V}{(4 \times 600 \Omega \parallel 11.47 k\Omega)} \quad (5)$$

$$T_J(max) = 125^\circ C + (0.422 W \times 40.8^\circ C/W) = 142.2^\circ C \quad (6)$$

To enhance semiconductor long-term operating life, minimize  $T_J$ . Take proper measures to provide maximum heat removal through both heat conduction and radiation to help keep  $T_J$  to the lowest possible level. These proper measures include maximizing the PCB copper area to which the package thermal pad is soldered. The copper area serves as the traditional heat sink. The top layer copper is often easiest to route and is most often exposed to open air. PCB internal planes and the exposed bottom plane can also be used as heat sinks, but the connections are made with vias having higher thermal resistance. The [OPA593EVM](#) uses a board design that provides a highly effective thermal layout. The board design encompasses a large top-side copper area, and has heat conduction paths to other planes on the board. Additionally, other higher power-dissipating components are kept physically distant from the OPA593 to better accommodate heat removal by radiation.

### 8.4.2 Layout Example

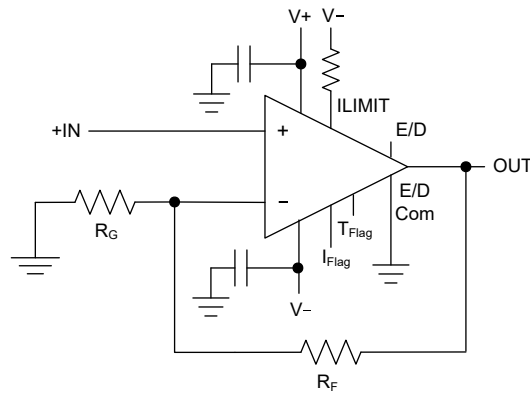


图 8-4. Schematic Representation

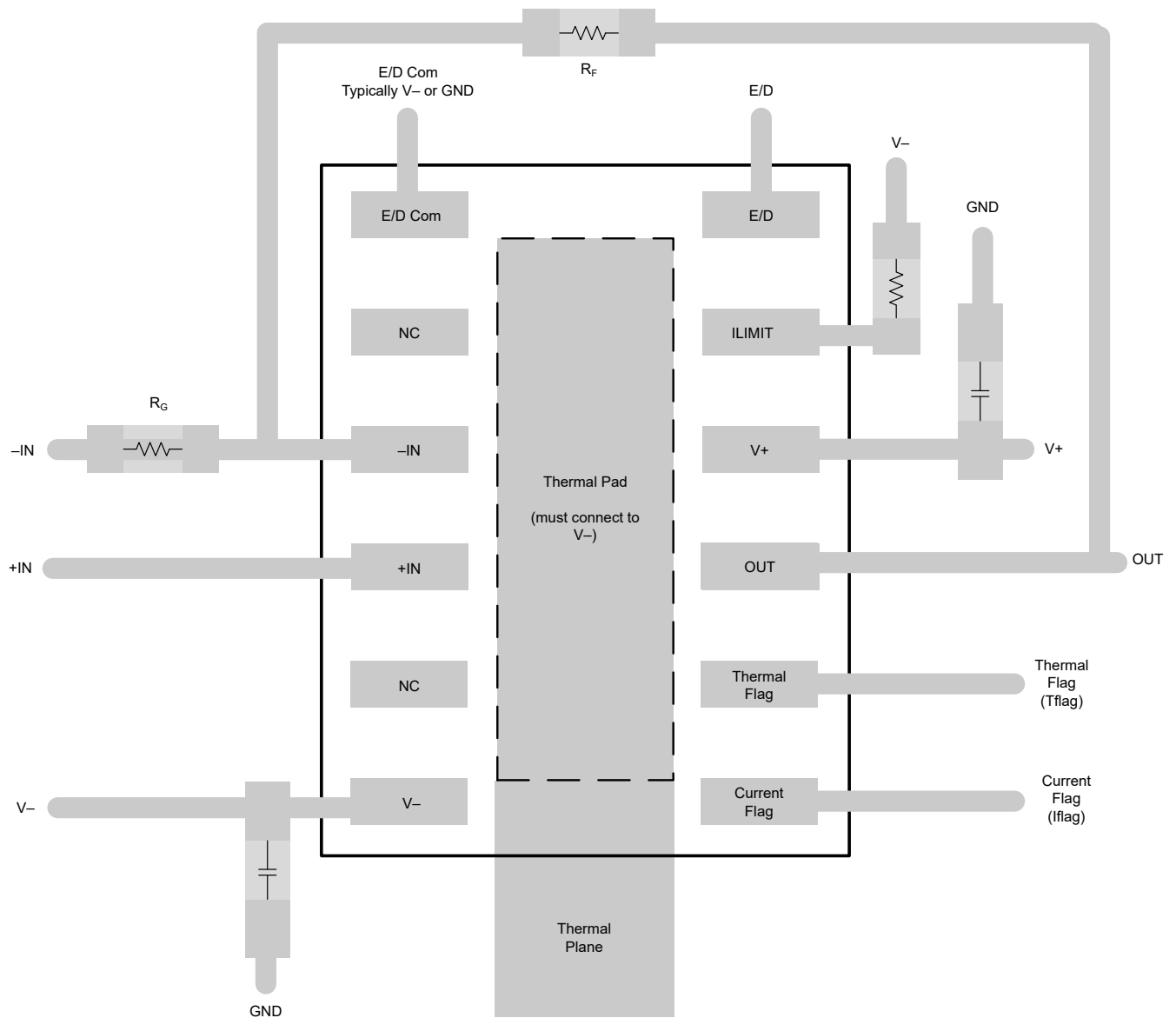


图 8-5. OPA593 Board Layout for Noninverting Configuration



## 9 Device and Documentation Support

### 9.1 Device Support

#### 9.1.1 Development Support

##### 9.1.1.1 PSpice® for TI

PSpice® for TI 是可帮助评估模拟电路性能的设计和仿真环境。在进行布局和制造之前创建子系统设计和原型解决方案，可降低开发成本并缩短上市时间。

##### 9.1.1.2 TINA-TI™ 仿真软件 (免费下载)

TINA-TI™ 仿真软件是一款简单易用、功能强大且基于 SPICE 引擎的电路仿真程序。TINA-TI 仿真软件是 TINA™ 软件的一款免费全功能版本，除了一系列无源和有源模型外，此版本软件还预先载入了一个宏模型库。TINA-TI 仿真软件提供所有传统的 SPICE 直流、瞬态和频域分析，以及其他设计功能。

TINA-TI 仿真软件提供全面的后处理能力，便于用户以多种方式获得结果，用户可从 [设计工具和仿真网页](#) 免费下载。虚拟仪器提供选择输入波形和探测电路节点、电压以及波形的能力，从而构建一个动态的快速启动工具。

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#### 备注

必须安装 TINA 软件或者 TINA-TI 软件后才能使用这些文件。请从 [TINA-TI™ 软件文件夹](#) 中下载免费的 TINA-TI 仿真软件。

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### 9.2 接收文档更新通知

要接收文档更新通知，请导航至 [ti.com](#) 上的器件产品文件夹。点击 [订阅更新](#) 进行注册，即可每周接收产品信息更改摘要。有关更改的详细信息，请查看任何已修订文档中包含的修订历史记录。

### 9.3 支持资源

TI E2E™ 支持论坛是工程师的重要参考资料，可直接从专家获得快速、经过验证的解答和设计帮助。搜索现有解答或提出自己的问题可获得所需的快速设计帮助。

链接的内容由各个贡献者“按原样”提供。这些内容并不构成 TI 技术规范，并且不一定反映 TI 的观点；请参阅 TI 的《使用条款》。

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PSpice® is a registered trademark of Cadence Design Systems, Inc.

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### 9.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 9.6 术语表

TI 术语表 本术语表列出并解释了术语、首字母缩略词和定义。

## 10 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

**PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
OPA593DNTR	ACTIVE	WSON	DNT	12	5000	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 125	OPA593	<a href="#">Samples</a>
OPA593DNTT	ACTIVE	WSON	DNT	12	250	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 125	OPA593	<a href="#">Samples</a>

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

**Important Information and Disclaimer:**The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.



**TAPE AND REEL INFORMATION**

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
OPA593DNTR	WSO	DNT	12	5000	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
OPA593DNTR	WSO	DNT	12	250	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2

**TAPE AND REEL BOX DIMENSIONS**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
OPA593DNTR	WSON	DNT	12	5000	367.0	367.0	35.0
OPA593DNTR	WSON	DNT	12	250	210.0	185.0	35.0

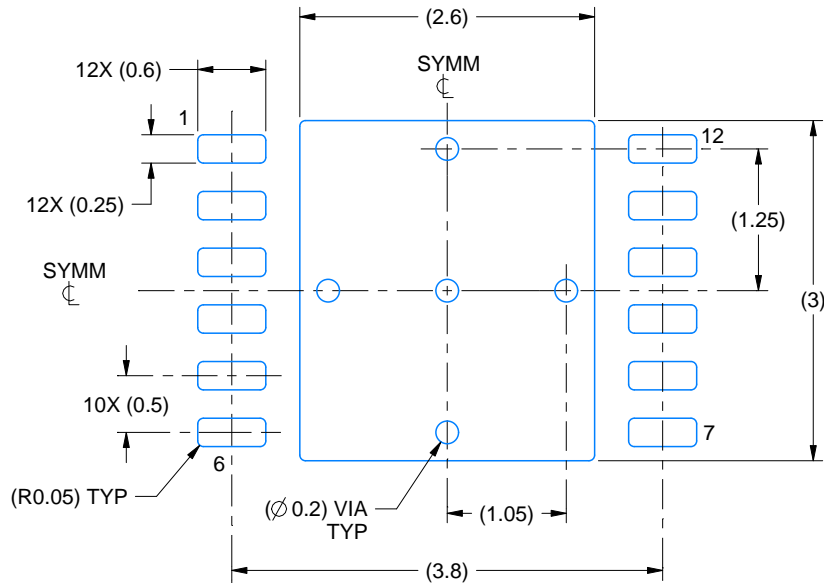


# EXAMPLE BOARD LAYOUT

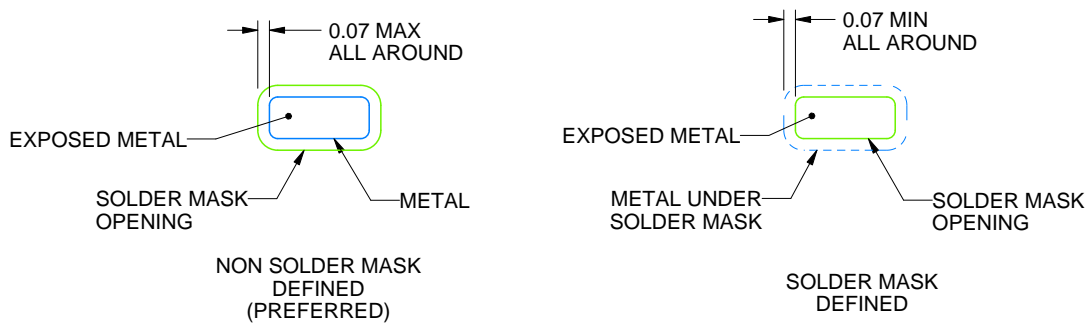
DNT0012B

WSON - 0.8 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:15X



SOLDER MASK DETAILS

4214928/C 10/2021

NOTES: (continued)

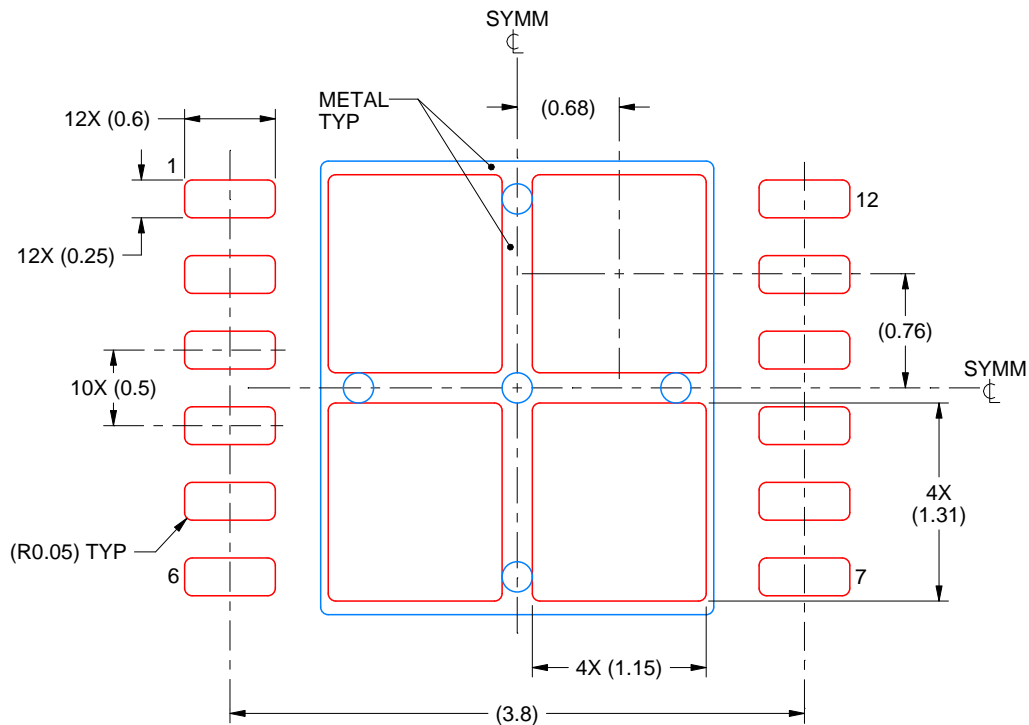
4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 ([www.ti.com/lit/slua271](http://www.ti.com/lit/slua271)).

# EXAMPLE STENCIL DESIGN

DNT0012B

WSON - 0.8 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



SOLDER PASTE EXAMPLE  
BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD  
77% PRINTED SOLDER COVERAGE BY AREA  
SCALE:20X

4214928/C 10/2021

NOTES: (continued)

5. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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