



## ABSTRACT

This document describes the known exceptions to the functional specifications (advisories).

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## 1 Functional Advisories

Advisories that affect the device's operation, function, or parametrics.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev B	Rev A
ADC18	✓	✓
ADC25	✓	✓
BCL5	✓	✓
CPU41	✓	✓
DAC4		✓
I2C7	✓	✓
I2C8	✓	✓
I2C9	✓	✓
I2C10	✓	✓
I2C11	✓	✓
I2C12	✓	✓
I2C13	✓	✓
I2C14	✓	✓
I2C15	✓	✓
I2C16	✓	✓
MPY2	✓	✓
TA12	✓	✓
TA16	✓	✓
TA21	✓	✓
TAB22	✓	✓
TB2	✓	✓
TB16	✓	✓
TB24	✓	✓
US14		✓
US15	✓	✓
WDG2	✓	✓

## 2 Preprogrammed Software Advisories

Advisories that affect factory-programmed software.

✓ The check mark indicates that the issue is present in the specified revision.

The device does not have any errata for this category.

## 3 Debug Only Advisories

Advisories that affect only debug operation.

✓ The check mark indicates that the issue is present in the specified revision.

The device does not have any errata for this category.

## 4 Fixed by Compiler Advisories

Advisories that are resolved by compiler workaround. Refer to each advisory for the IDE and compiler versions with a workaround.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev B	Rev A
<a href="#">CPU4</a>	✓	✓

Refer to the following MSP430 compiler documentation for more details about the CPU bugs workarounds.

#### **TI MSP430 Compiler Tools (Code Composer Studio IDE)**

- [MSP430 Optimizing C/C++ Compiler](#): Check the --silicon\_errata option
- [MSP430 Assembly Language Tools](#)

#### **MSP430 GNU Compiler (MSP430-GCC)**

- [MSP430 GCC Options](#): Check -msilicon-errata= and -msilicon-errata-warn= options
- [MSP430 GCC User's Guide](#)

#### **IAR Embedded Workbench**

- [IAR workarounds for msp430 hardware issues](#)

## 5 Nomenclature, Package Symbolization, and Revision Identification

The revision of the device can be identified by the revision letter on the [Package Markings](#) or by the [HW\\_ID](#) located inside the TLV structure of the device.

### 5.1 Device Nomenclature

To designate the stages in the product development cycle, TI assigns prefixes to the part numbers of all MSP MCU devices. Each MSP MCU commercial family member has one of two prefixes: MSP or XMS. These prefixes represent evolutionary stages of product development from engineering prototypes (XMS) through fully qualified production devices (MSP).

**XMS** – Experimental device that is not necessarily representative of the final device's electrical specifications

**MSP** – Fully qualified production device

Support tool naming prefixes:

**X**: Development-support product that has not yet completed Texas Instruments internal qualification testing.

**null**: Fully-qualified development-support product.

XMS devices and X development-support tools are shipped against the following disclaimer:

"Developmental product is intended for internal evaluation purposes."

MSP devices have been characterized fully, and the quality and reliability of the device have been demonstrated fully. TI's standard warranty applies.

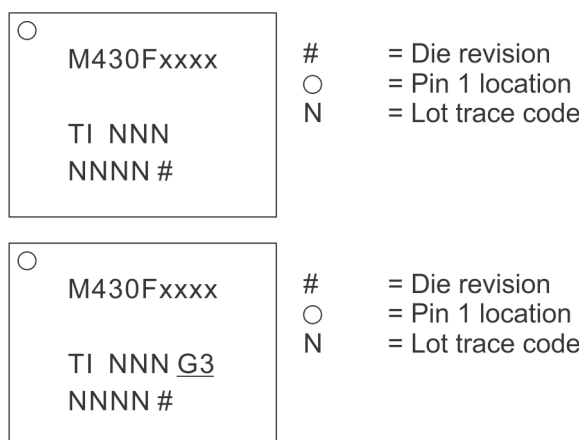
Predictions show that prototype devices (XMS) have a greater failure rate than the standard production devices. TI recommends that these devices not be used in any production system because their expected end-use failure rate still is undefined. Only qualified production devices are to be used.

TI device nomenclature also includes a suffix with the device family name. This suffix indicates the temperature range, package type, and distribution format.

### 5.2 Package Markings

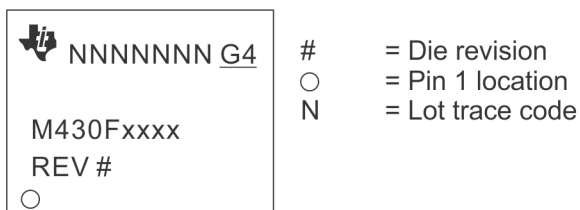
**RTD64**

**QFN (RTD), 64 Pin**



**PM64**

**LQFP (PM), 64 Pin**



### 5.3 Memory-Mapped Hardware Revision (TLV Structure)

This device does not support reading the hardware revision from memory.

Further guidance on how to locate the TLV structure and read out the HW\_ID can be found in the device User's Guide.

## 6 Advisory Descriptions

<b>ADC18</b>	<b>ADC Module</b>
<b>Category</b>	Functional
<b>Function</b>	Incorrect conversion result in extended sample mode
<b>Description</b>	<p>The ADC12 conversion result can be incorrect if the extended sample mode is selected (SHP = 0), the conversion clock is not the internal ADC12 oscillator (ADC12SSEL &gt; 0), and one of the following two conditions is true:</p> <ul style="list-style-type: none"> <li>- The extended sample input signal SHI is asynchronous to the clock source used for ADC12CLK and the undivided ADC12 input clock frequency exceeds 3.15 MHz.</li> </ul> <p>or</p> <ul style="list-style-type: none"> <li>- The extended sample input signal SHI is synchronous to the clock source used for ADC12CLK and the undivided ADC12 input clock frequency exceeds 6.3 MHz.</li> </ul>
<b>Workaround</b>	<ul style="list-style-type: none"> <li>- Use the pulse sample mode (SHP = 1).</li> </ul> <p>or</p> <ul style="list-style-type: none"> <li>- Use the ADC12 internal oscillator as the ADC12 clock source.</li> </ul> <p>or</p> <ul style="list-style-type: none"> <li>- Limit the undivided ADC12 input clock frequency to 3.15 MHz.</li> </ul> <p>or</p> <ul style="list-style-type: none"> <li>- Use the same clock source (such as ACLK or SMCLK) to derive both SHI and ADC12CLK, to achieve synchronous operation, and also limit the undivided ADC12 input clock frequency to 6.3 MHz.</li> </ul>
<b>ADC25</b>	<b>ADC Module</b>
<b>Category</b>	Functional
<b>Function</b>	Write to ADC12CTL0 triggers ADC12 when CONSEQ = 00
<b>Description</b>	If ADC conversions are triggered by the Timer_B module and the ADC12 is in single-channel single-conversion mode (CONSEQ = 00), ADC sampling is enabled by write access to any bit(s) in the ADC12CTL0 register. This is contrary to the expected behavior that only the ADC12 enable conversion bit (ADC12ENC) triggers a new ADC12 sample.
<b>Workaround</b>	When operating the ADC12 in CONSEQ=00 and a Timer_B output is selected as the sample and hold source, temporarily clear the ADC12ENC bit before writing to other bits in the ADC12CTL0 register. The following capture trigger can then be re-enabled by setting ADC12ENC = 1.
<b>BCL5</b>	<b>BCL Module</b>
<b>Category</b>	Functional
<b>Function</b>	RSELx bit modifications can generate high frequency spikes on MCLK
<b>Description</b>	When DIVMx = 00 or 01 the RSELx bits of the Basic Clock Module are incremented or decremented in steps of 2 or greater, the DCO output may momentarily generate high frequency spikes on MCLK, which may corrupt CPU operation. This is not an issue when DIVMx = 10 or 11.

**Workaround** Set DIVMx = 10 or 11 to divide the MCLK input prior to modifying RSELx. After the RSELx bits are configured as desired, the DIVMx setting can be changed back to the original selection.

**CPU4**

**CPU Module**

**Category**

Compiler-Fixed

**Function**

PUSH #4, PUSH #8

**Description**

The single operand instruction PUSH cannot use the internal constants (CG) 4 and 8. The other internal constants (0, 1, 2, -1) can be used. The number of clock cycles is different:

PUSH #CG uses address mode 00, requiring 3 cycles, 1 word instruction  
 PUSH #4/#8 uses address mode 11, requiring 5 cycles, 2 word instruction

**Workaround**

Refer to the table below for compiler-specific fix implementation information.

IDE/Compiler	Version Number	Notes
IAR Embedded Workbench	IAR EW430 v2.x until v6.20	User is required to add the compiler flag option below. --hw_workaround=CPU4
IAR Embedded Workbench	IAR EW430 v6.20 or later	Workaround is automatically enabled
TI MSP430 Compiler Tools (Code Composer Studio)	v1.1 or later	
MSP430 GNU Compiler (MSP430-GCC)	MSP430-GCC 4.9 build 167 or later	

**CPU41**

**CPU Module**

**Category**

Functional

**Function**

Incorrect address fetching during interrupt priority decoding

**Description**

The CPU might fetch a random address if the system clock is greater than 6 MHz and two general maskable interrupts (GMI) with large priority difference are triggered within a time frame of 8 system clock cycles. In fail case, a race condition of the internal interrupt priority chain is corrupting the address bus.

The issue can potentially occur if the priority delta between the two occurring interrupts is greater than 8.

GMI	Address	Priority
TimerB	0FFFA	13
TimerB	0FFF8	12
CompA	0FFF6	11
WDT	0FFF4	10
USART0 RX	0FFF2	9
USART0 TX	0FFF0	8
ADC12	0FFEE	7
TimerA	0FFEC	6
TimerA	0FFEA	5
P1	0FFE8	4
USART1 RX	0FFE6	3
USART1 TX	0FFE4	2
P2	0FFE2	1
DMA/DAC	0FFE0	0

Priority Delta<sup>(1)</sup> = 8

(1) Priority Delta = High Priority – Low Priority

NOTE: This erratum supersedes the DMA9 erratum.

#### Workaround

1. Reduce the system frequency below 6MHz.  
OR
2. Disable affected interrupts and poll the IFGs.

#### DAC4

##### **DAC Module**

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#### Category

Functional

#### Function

DAC1 overwrites an input of the SVS comparator

#### Description

DAC1, when enabled (DAC12\_1CTL.DAC12AMPx > 0), overrides the input of the SVS comparator if SVSCTL.VLDx = 1111 (comparing external input voltage SVSIN to 1.25 V.) This is caused by a conflict between SVS and DAC1 at Port 6.7. This behavior only affects DAC output pins shared with SVSIN function.

#### Workaround

- 1) Do not enable DAC1 when SVS is used with VLDx = 1111  
  
OR
- 2) Use DAC output pin not shared with SVSIN function

#### I2C7

##### **I2C Module**

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#### Category

Functional

#### Function

ARDYIFG Interrupt flag generation can fail in I2C slave mode.

#### Description

When the USART is configured for I2C mode (U0CTL.I2C, SYNC, and I2CEN are set) and the module is configured as an I2C slave (U0CTL.MST=0), the ARDYIFG interrupt flag generation can fail, even when both the I2C stop condition is received and the receive buffer is empty.

This condition occurs when the I2C clock source selected by I2CSSSELx is disabled by the Status Register (SR) control signals OSCOFF or SCG1.

In this configuration, the hardware clock activation is enabled by the I2C module.

However, if RXRDYIFG is polled to determine data reception, the I2C hardware clock activation may be disabled before the ARDYIFG is generated.



**Workaround** (1)Use interrupt service routines using the I2C interrupt vector generator feature (I2CIV) to handle all I2C interrupts.  
OR  
(2)After detection of I2C Own Address (OAIFG), the selected I2C clock source is enabled by clearing the OSCOFF or SCG1 Status Register (SR) bits. When the ARDYIFG is detected, the OSCOFF or SCG1 in the Status Register (SR) can be set to disable the clock source and return to the desired low power mode operation.  
OR  
(3)For slave only devices, it is normally not necessary to use ARDYIFG.

## I2C8

### *I2C Module*

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**Category**

Functional

**Function**

Master Transmitter transmits 0FFh continuously.

**Description**

When the USART is configured for I2C mode (U0CTL.I2C, SYNC, and I2CEN are set) and the module is configured as an I2C master (U0CTL.MST=1) and I2CNDAT is used to control the number of bytes to transmit, the possibility exists that the master state-machine can become corrupted and start sending 0FFh as data on the I2C bus. Specifically, this error can occur when a long delay occurs between the set of the I2CTXRDY interrupt flag and the loading of I2CDRB (I2CDRW).

**Workaround**

After detection of the I2CTXRDY interrupt flag, verify that the I2CTXUDF bit in I2CDCTL is set before loading I2CDRB (I2CDRW).

## I2C9

### *I2C Module*

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**Category**

Functional

**Function**

Master Transmitter Repeat Mode I2CSTP setting error.

**Description**

When the USART is configured for I2C mode (U0CTL.I2C, SYNC, and I2CEN are set) and the module is configured as an I2C master (U0CTL.MST=1) and repeat mode operation is selected (I2CTCTL.I2CRM=1), the timing of the I2CSTP bit can result in lost data or extra requested transmitted bytes.

Specifically, if interrupts are active during the following two cases:

1) During the time between the setting of the I2CSTP bit and loading of I2CDRB (I2CDRW).

2) For transmitting slave address only, during the time between checking for I2CSTT cleared and setting I2CSTP.

Note: In the second case, the SCL line will be held low until the I2CDRB (I2CDRW) is loaded and then shifted out.

**Workaround**

Solution for case #1: disable all interrupts (DINT) before setting I2CSTP then re-enabling after loading of I2CDRB.

Solution for case #2: disable all interrupts (DINT) before setting I2CSTT bit then re-enabling after setting I2CSTP bit.

## I2C10

### *I2C Module*

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**Category**

Functional

**Function**

Master stop bit SCL low phase does not match I2CSCLL setting.

**Description**

When the USART is configured for I2C mode (U0CTL.I2C, SYNC, and I2CEN are set) and the module is configured as an I2C master (U0CTL.MST=1), the hardware control

of the SCL low phase before stop generation is equal to a single I2CCLK period. This is particularly noticeable with large I2CSCLL settings or large I2CPCSC settings.

**Workaround**

None.

**I2C11*****I2C Module*****Category**

Functional

**Function**

Master state machine requires reset before new sequence can proceed.

**Description**

When the USART is configured for I2C mode (U0CTL.I2C, SYNC, and I2CEN are set) and the module is configured as an I2C master (U0CTL.MST=1), the master state-machine does not properly reset between execution cycles.

**Workaround**

Before starting the new master sequence, clear and then re-set the I2CEN bit in the U0CTL register.

```
bic.b #I2CEN,&U0CTL
```

```
bis.b #I2CEN,&U0CTL
```

**I2C12*****I2C Module*****Category**

Functional

**Function**

Master/Slave loses data on reception (lost RXRDYIFG).

**Description**

If the I2C data register I2CDRB (I2CDRW) is read at the same time that data is loaded from the internal I2C shift register into I2CDRB (I2CDRW), then the received data is lost and no corresponding receive ready interrupt (RXRDYIFG) is generated. Following RXRDYIFG interrupts are processed but the missing byte cannot be recovered.

**Workaround**

Do not read the I2CDRB(I2CDRW) register while data is being loaded into it. This can be ensured by reading this register in a timely manner using any one of the following methods:

- 1) Handle RXRDYIFG events with all other interrupt sources disabled.
- 2) Use the DMA for receiving incoming I2C data. The DMA interrupt or ARDYIFG interrupt can be used to initiate further processing of received data.
- 3) Enable nested interrupts to allow immediate processing of RXRDYIFG interrupts. (Care must be taken to avoid stack overflows).

**I2C13*****I2C Module*****Category**

Functional

**Function**

Glitch on SCL between I2C communication cycles can corrupt the state machine in I2C master mode.

**Description**

When the USART is configured for I2C communication (U0CTL.I2C, SYNC, and I2CEN are set) and the module is configured as an I2C master (U0CTL.MST=1), the I2C module is automatically switched to slave mode following the I2C master's generation of a stop condition. If SCL is then pulled low and released again, the following device behavior can be observed:

- 1) When SCL is pulled low after the stop condition is generated and while ARDYIFG is not yet set, then ARDYIFG is not set as expected and ALIFG is set. SCL is released. See workaround 1 for details on how to handle this condition.
- 2) When SCL is pulled low at the same time as ARDYIFG is being set, ALIFG is set and SCL is released. Subsequent communication can result in an immediate ALIFG

generation. See workaround 2 for details on how to handle this condition.

3) When SCL is pulled low after ARDYIFG is set but before ARDYIFG is cleared, ALIFG is not set, but SCL is held low by the master. An SCL hang-up condition occurs. See workaround 3 for details on how to handle this condition.

4) When SCL is pulled low after ARDYIFG is cleared, the module operates as intended. The ALIFG flag is not set and SCL is released.

<b>Workaround</b>	<ol style="list-style-type: none"> <li>1. ALIFG must be processed. Data bytes are not affected.</li> <li>2. ALIFG must be processed. Data bytes are not affected. To avoid a second ALIFG, clear I2CEN and re-set I2CEN before new communication begins.</li> <li>3. Clear I2CEN and re-set I2CEN before new communication begins to clear the SCL hang-up.</li> </ol>
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## **I2C14** *I2C Module*

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**Category** Functional

**Function** Master SCL phases do not match I2CSCLx settings.

**Description** When the USART is configured for I2C mode (U0CTL.I2C, SYNC, and I2CEN are set) and the module is used as an I2C master (U0CTL.MST=1), the generated I2C shift clock (SCL) high and low phases may be one or more I2CIN clock periods longer than defined by I2CSCLH and I2CSCLL. High I2CIN frequencies, large external pull-up resistors, and a large capacitive bus loading on SCL increase the likelihood for this to occur.

**Workaround** If possible, use an I2CIN input frequency of 1MHz or less. Additionally, use low-impedance I2C pull-up resistors, preferably in the lower single-digit k-Ohm range, and minimize capacitive load on SCL.

## **I2C15** *I2C Module*

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**Category** Functional

**Function** I2CBUSY flag may clear before stop condition

**Description** The I2CBUSY flag may already be cleared before the Stop condition on the bus is seen.

**Workaround** Use the I2CBB flag instead of the I2CBUSY flag.

## **I2C16** *I2C Module*

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**Category** Functional

**Function** I2C Slave may not detect own address correctly

**Description** When an interrupt occurs between ACK and stop conditions of a slave transmission, the slave may not acknowledge the slave address byte if all below conditions are fulfilled:

- STT interrupt is enabled
- Device is in LPMx during start condition.

If the failure occurs, the I2C state machine switches into IDLE state.

**Workaround** (1) Do not use the STT interrupt for slave transmission.  
Or  
(2) Disable all interrupts between ACK and stop condition on I2C

## **MPY2** *MPY Module*

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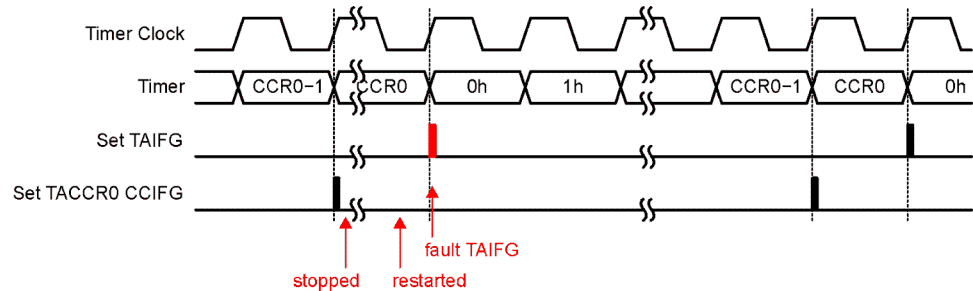
<b>Category</b>	Functional
<b>Function</b>	Multiplier Result register corruption
<b>Description</b>	Depending on the address of the write instruction, writing to the multiplier result registers (RESHI, RESLO, or SUMEXT) may corrupt the result registers. The address dependency varies between a 2-word and a 3-word instructions.
<b>Workaround</b>	Ensure that a write instruction to an MPY result register (for example, mov.w #200, &RESHI) is not located at an address with the four least significant bits shown in Table 1:

Table 1. Sensitive Addresses for Write Access to MPY Result Registers MAB[3:0]

RESLOW 013Ah		RESHI 013Ch		SUMEXT 013Eh	
3 Word	2 Word	3 Word	2 Word	3 Word	2 Word
2	4	2	4	2	4
6	8	4	6	6	8
A	C	A	C	A	C
E	0	C	E	-	-

<b>TA12</b>	<b>TA Module</b>
<hr/>	
<b>Category</b>	Functional
<b>Function</b>	Interrupt is lost (slow ACLK)
<b>Description</b>	Timer_A counter is running with slow clock (external TACLK or ACLK) compared to MCLK. The compare mode is selected for the capture/compare channel and the CCRx register is incremented by one with the occurring compare interrupt (if TAR = CCRx). Due to the fast MCLK the CCRx register increment (CCRx = CCRx+1) happens before the Timer_A counter has incremented again. Therefore the next compare interrupt should happen at once with the next Timer_A counter increment (if TAR = CCRx + 1). This interrupt gets lost.
<b>Workaround</b>	Switch capture/compare mode to capture mode before the CCRx register increment. Switch back to compare mode afterwards.
<b>TA16</b>	<b>TA Module</b>
<hr/>	
<b>Category</b>	Functional
<b>Function</b>	First increment of TAR erroneous when IDx > 00
<b>Description</b>	The first increment of TAR after any timer clear event (POR/TACLK) happens immediately following the first positive edge of the selected clock source (INCLK, SMCLK, ACLK or TACLK). This is independent of the clock input divider settings (ID0, ID1). All following TAR increments are performed correctly with the selected IDx settings.
<b>Workaround</b>	None
<b>TA21</b>	<b>TA Module</b>
<hr/>	
<b>Category</b>	Functional
<b>Function</b>	TAIFG Flag is erroneously set after Timer A restarts in Up Mode
<b>Description</b>	In Up Mode, the TAIFG flag should only be set when the timer counts from TACCR0 to zero. However, if the Timer A is stopped at TAR = TACCR0, then cleared (TAR=0) by

setting the TACLK bit, and finally restarted in Up Mode, the next rising edge of the TACLK will erroneously set the TAIFG flag.



**Workaround** None.

## TAB22 *TAB Module*

**Category** Functional

**Function** Timer\_A/Timer\_B register modification after Watchdog Timer PUC

**Description** Unwanted modification of the Timer\_A/Timer\_B registers TACTL/TBCTL and TAIV/TBIV can occur when a PUC is generated by the Watchdog Timer(WDT) in Watchdog mode and any Timer\_A/Timer\_B counter register TACCRx/TBCCRx is incremented/decremented (Timer\_A/Timer\_B does not need to be running).

**Workaround** Initialize TACTL/TBCTL register after the reset occurs using a MOV instruction (BIS/BIC may not fully initialize the register). TAIV/TBIV is automatically cleared following this initialization.

Example code:

```
MOV.W #VAL, &TACTL
or
MOV.W #VAL, &TBCTL
```

Where, VAL=0, if Timer is not used in application otherwise, user defined per desired function.

## TB2 *TB Module*

**Category** Functional

**Function** Interrupt is lost (slow ACLK)

**Description** Timer\_B counter is running with slow clock (external TBCLK or ACLK) compared to MCLK. The compare mode is selected for the capture/compare channel and the CCRx register is incremented by 1 with the occurring compare interrupt (if TBR = CCRx). Due to the fast MCLK, the CCRx register increment (CCRx = CCRx + 1) happens before the Timer\_B counter has incremented again. Therefore, the next compare interrupt should happen at once with the next Timer\_B counter increment (if TBR = CCRx + 1). This interrupt is lost.

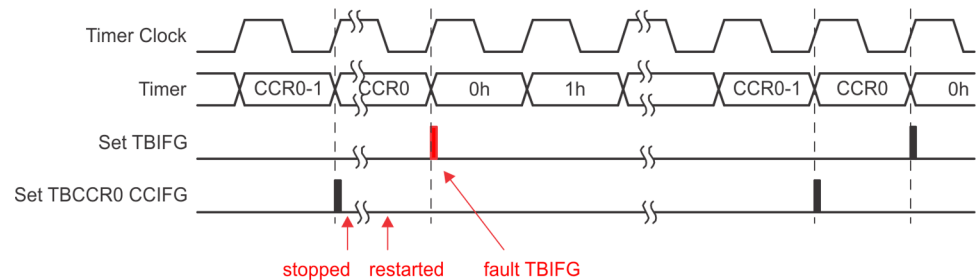
**Workaround** Switch capture/compare mode to capture mode before the CCRx register increment. Switch back to compare mode afterward.

## TB16 *TB Module*

<b>Category</b>	Functional
<b>Function</b>	First increment of TBR erroneous when IDx > 00
<b>Description</b>	The first increment of TBR after any timer clear event (POR/TBCLR) happens immediately following the first positive edge of the selected clock source (INCLK, SMCLK, ACLK, or TBCLK). This is independent of the clock input divider settings (ID0, ID1). All following TBR increments are performed correctly with the selected IDx settings.
<b>Workaround</b>	None

## TB24 *TB Module*

<b>Category</b>	Functional
<b>Function</b>	TBIFG Flag is erroneously set after Timer B restarts in Up Mode
<b>Description</b>	In Up Mode, the TBIFG flag should only be set when the timer resets from TBCCR0 to zero. However, if the Timer B is stopped at TBR = TBCCR0, then cleared (TBR=0) by setting the TBCLR bit, and finally restarted in Up Mode, the next rising edge of the TBCLK will erroneously set the TBIFG flag.



<b>Workaround</b>	None.
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## US14 *USART Module*

<b>Category</b>	Functional
<b>Function</b>	Start edge of received characters may be ignored
<b>Description</b>	When using the USART in UART mode with UxBR0 = 0x03 and UxBR1 = 0x00, the start edge of received characters may be ignored due to internal timing conflicts within the UART state machine. This condition does not apply when UxBR0 is > 0x03.
<b>Workaround</b>	None

## US15 *USART Module*

<b>Category</b>	Functional
<b>Function</b>	UART receive with two stop bits
<b>Description</b>	USART hardware does not detect a missing second stop bit when SPB = 1. The Framing Error Flag (FE) will not be set under this condition and erroneous data reception may occur.
<b>Workaround</b>	None (Configure USART for a single stop bit, SPB = 0)

<b>WDG2</b>	<b><i>WDG Module</i></b>
<b>Category</b>	Functional
<b>Function</b>	Incorrectly accessing a flash control register
<b>Description</b>	If a key violation is caused by incorrectly accessing a flash control register, the watchdog interrupt flag is set in addition to the expected PUC.
<b>Workaround</b>	None

## 7 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

<b>Changes from October 9, 2019 to May 17, 2021</b>	<b>Page</b>
<ul style="list-style-type: none"><li>Changed the document format and structure; updated the numbering format for tables, figures, and cross references throughout the document.....</li></ul>	<a href="#">6</a>

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