LM36010EVM User Guide

The Texas Instruments LM36010EVM evaluation module (EVM) helps designers evaluate the operation and performance of the LM36010 Synchronous-Boost Single-LED Driver with 1.5-A High-Side Current Source. The device offers configurability via I²C-compatible interface. It can be enabled in flash or torch mode via the I²C interface or externally using the STROBE pin. The module utilizes one LED (D1) mounted on the EVM.

The EVM contains one synchronous boost, single-LED flash driver (see Table 1).

Table 1. Device and Package Configurations

FLASH LED DRIVER	DEVICE	PACKAGE
U1	LM36010	0.35-mm pitch 8-pin DSBGA

Contents

List of Figures

List of Tables

Trademarks

LaunchPad is a trademark of Texas Instruments.
All other trademarks are the property of their respective owners.

1 Setup

This section describes the jumpers and connectors on the EVM as well as how to properly connect, set up, and use the LM36010EVM.

1.1 Input/Output Connector Description

VINL, GND (Banana Connectors) – These are the power input terminals for the driver and provide a power (VINL) and ground (GND) connection to allow the user to attach the EVM to a cable harness.

TP1 (Test Point) – This pin can be used to measure the input voltage VIN.

VINL, VIN (Jumper J2) – The user can monitor the inductor current and input current waveforms by omitting this jumper and using separate wires from the power supply to the VINL and VIN pins. This will remove the input capacitors from the inductor and eliminate their filtering effect to the inductor current.

STROBE (Jumper J3) – STROBE is an active high hardware flash enable. This pin can be used to monitor the STROBE signal.

PWM, STROBE, GND (Jumper J4) – This jumper provides an external method for initiating a flash event. The STROBE pin is connected to ground via a 300-kΩ resistor internal to the LM36010EVM. To externally drive this pin, either connect a control signal directly to the STROBE pin of the connector or place a jumper between the pins STROBE (J4<2>) and PWM (J4<1>). PWM can be configured as a time-adjustable voltage pulse via the General User Interface (GUI) software provided or can be driven externally using a function generator.

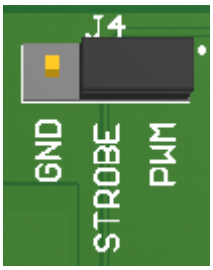

Figure 1. STROBE Jumper Settings

VOUT (Jumper J5) – This pin can be used to measure the output voltage.

VOUT, VLED (Jumper J6) – This jumper provides access to the regulated output of the driver and the output of the LED current sources. The user can measure VOUT with reference to GND, VLED with reference to GND, and current source headroom directly between VOUT and VLED.

GND (Jumpers J8, J9, and J10) – These are additional pins to connect to ground (GND).

VLED, D1A (Jumper J11) – Connect VLED (J11<1>) and D1A (J11<2>) to light the LED as it connects the LED output of the driver to the on-board anode of the flash LED.

VIO (Jumper J12) – This pin can be used to measure the VIO.

3.3V, VIO, VIN (Jumper J13) – This jumper provides pullup for the I^2C lines (clock and data). VIO (J13<2>) can be connected to the 3.3-V pin (J13<1>) of the TI LaunchPad™. Communication via the I^2C interface may not be possible if the supply voltage to the LED driver is below approximately 3 V.

Figure 2. VIO Jumper Setting

LED Current Measurements, D1F, D1S, GNDS (Jumper J14) – The LM36010EVM provides a way to accurately measure the LED current through the LED on board. Resistor R4 (0.1 Ω) is placed between the cathode of LED (D1F) and ground. The user can first measure the resistor value accurately by first applying a known current through force pin (D1F) and ground and measuring the voltage between sense pin (D1S) and GNDS. Then, during normal flash or torch operation, the voltage measured across the resistor divided by the resistor value will equal the current through the resistor (or the LED).

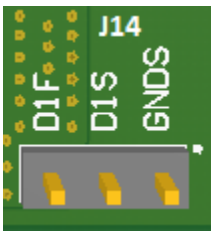

Figure 3. LED Current Measurements Jumper

SDA / SDK (Pins 9 and 10 on Launchpad) – These connections allow the user to externally control the I^2C lines.

1.2 EVM Configuration

Configuration of LM36010EVM jumpers is as shown in Figure 4.

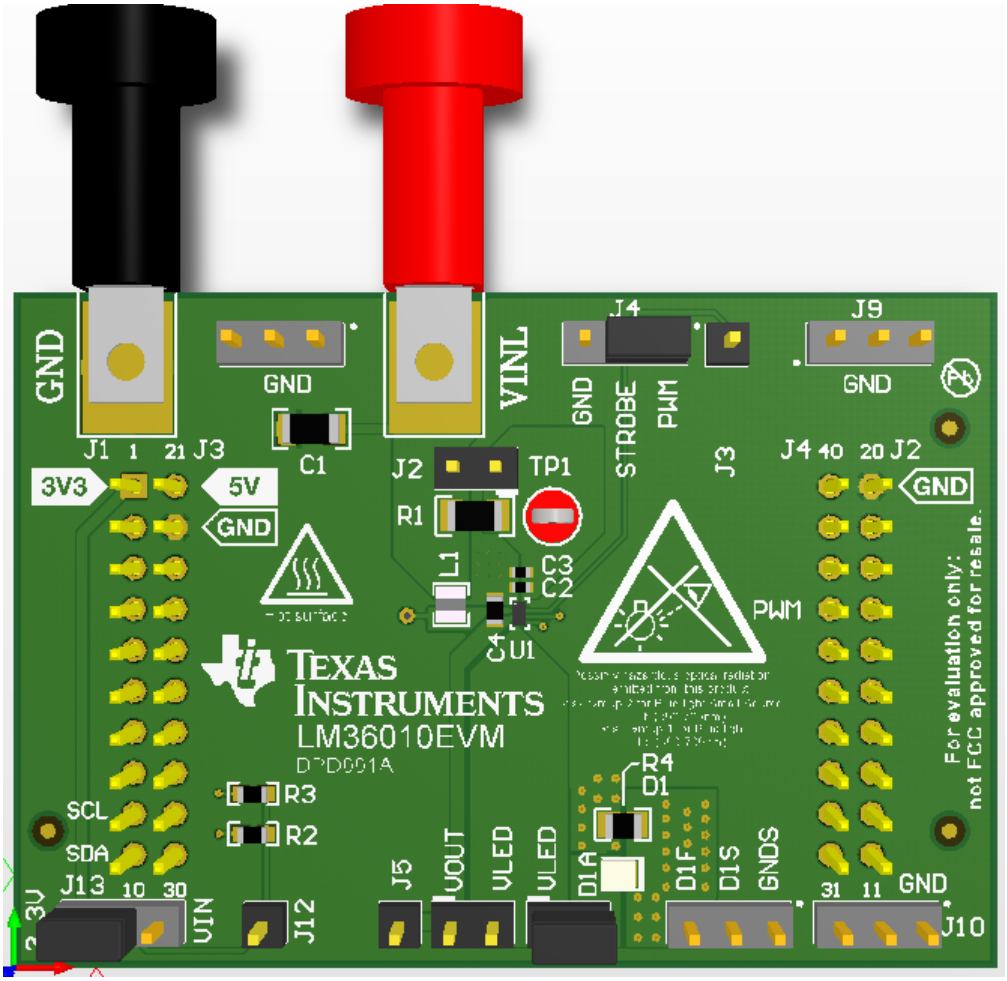

Figure 4. LM36010EVM Jumper Configuration

The input voltage range for the flash driver is 2.5 V to 5.5 V. The on-board LED or an LED module should be connected for proper operation.

The LM36010EVM dissipates power, especially during high current and long duration flash events. Power will also be dissipated on the flash LEDs. TI recommends that in order to prevent overheating, repeated flash events in very short time intervals is avoided. Special care must be taken with regards to thermal management when using time-out values greater than 500 ms.

The EVM layout is designed to minimize temperature rise during operation. Depending on the PCB layout, input voltage, and output current, it is possible to have the internal thermal shutdown circuit trip prior to reaching the desired flash time-out value. A warning is also placed on the EVM as a safety measure.

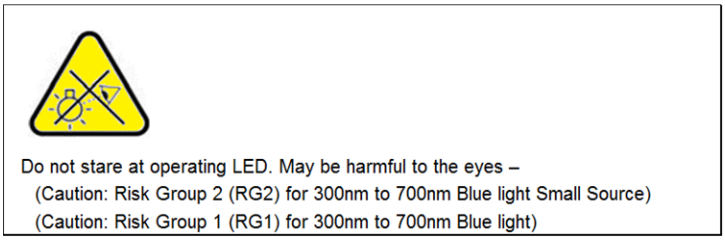

Figure 5. LED Warning

For proper operation of the LM36010EVM, the jumpers should be properly configured. The recommended setting using shorting blocks is:

- VIO (J13<2>) to 3.3 V (J13<1>) if TI Launchpad is used
- STROBE (J4<2>) to PWM (J4<1>) or external signal
- VLED (J11<1>) to D1A (J11<2>)

Texas Instruments has created LaunchPad (MSP432) and an I^2C-compatible graphical user interface (GUI) that can help exercise the part in a simple way. A description of how to install and use the LaunchPad and the GUI is contained in Section 2 and Section 3.

The LM36010EVM has the means to “plug into” the LaunchPad BoosterPack connectors, which provide the control signals for the simple interface. Power to the part needs to be provided externally. A USB cable provided in LaunchPad MSP432 kit should be connected to the LaunchPad board from a PC as shown in Figure 6.

Figure 6. LM36010EVM Test Setup

2 Software

2.1 Setup Overview

1. Verify jumper configuration on the MSP-EXP432P401R LaunchPad and the LM36010EVM as in Figure 7 and Figure 4, respectively.
2. Connect the LM36010EVM to the MSP-EXP432P401R LaunchPad.
3. If using the MSP432 for the first time, install XDS110 drivers as in Section 2.2.
4. If the LM3601x GUI is not installed, refer to section Section 2.3.
5. Run the EVM software and select LM36010 button in the EVM selection pop-up window.
6. If the LaunchPad is new or was used for another purpose, EVM software asks to update firmware, which can be done by clicking "FW Update" in the File menu on the top. EVM software restarts after updating firmware.
7. For LM36010EVM operation with the GUI, refer to Section 3.

2.2 MSP432 LaunchPad Installation

Configuration of MSP432 LaunchPad jumpers is as shown in Figure 7.

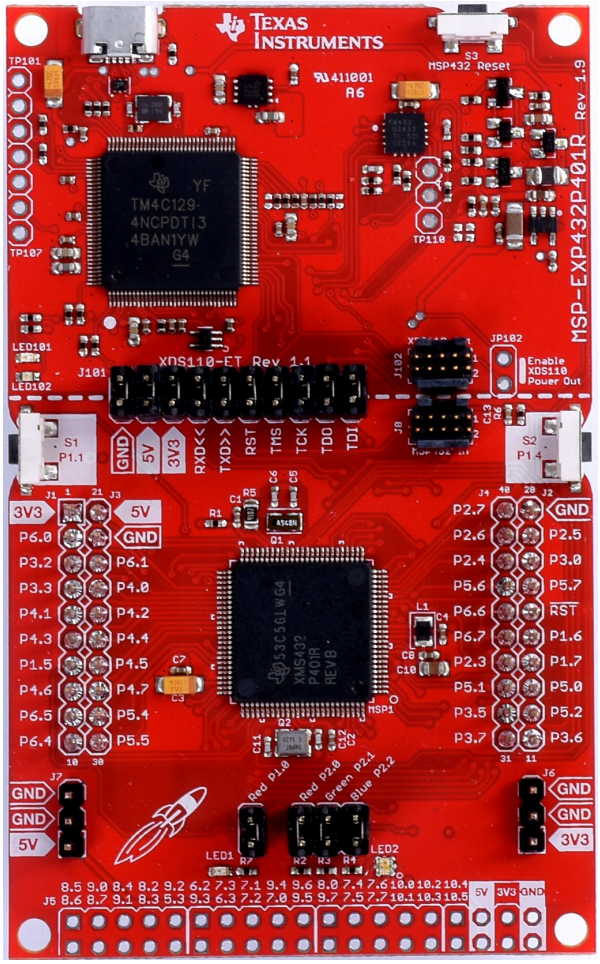

Figure 7. MSP432 LaunchPad Jumper Configuration

Driver XDS110 of the MSP432 LaunchPad must be installed to use the Texas Instruments LM36010 GUI. Go to *XDS Emulation Software Package* to download the driver. On the driver download website, click “3 XDS110 Reset Download” under Contents.

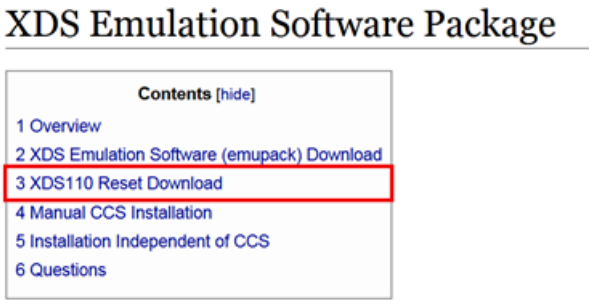

Figure 8. Driver Download Website (Part 1)

There are several versions to install depending on the computer’s operating system. Choose the appropriate version for the computer.

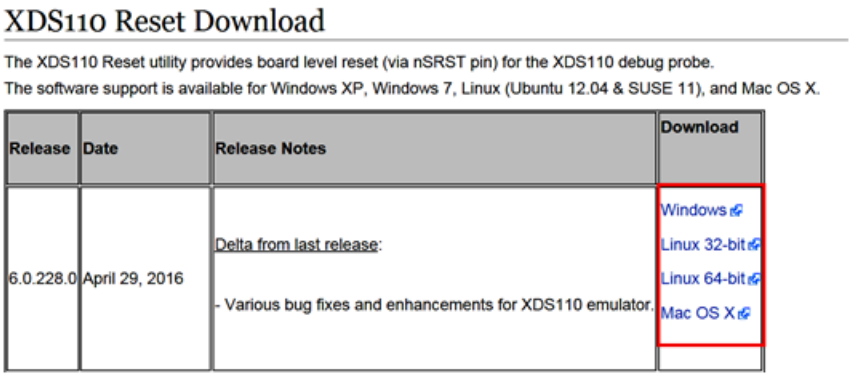

Figure 9. Driver Download Website (Part 2)

Fill out the form for U.S government export approval.

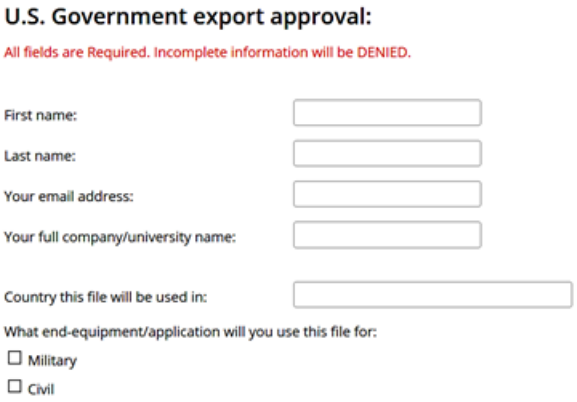

Figure 10. U.S. Government Export Approval (Part 1)

At the end of the form, check “Yes” next to the statement “I CERTIFY ALL THE ABOVE IS TRUE”. Then, click “Submit”.

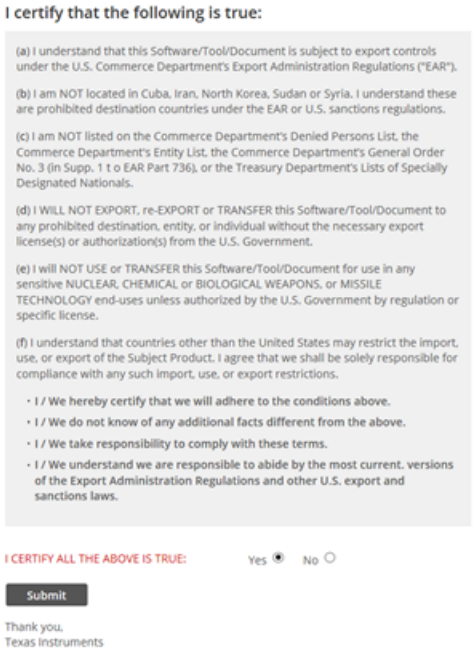

Figure 11. U.S. Government Export Approval (Part 2)

If everything is filled out properly, the user can gain access to the file. The zip file can be downloaded by clicking on “Download” or by going to the user’s email.

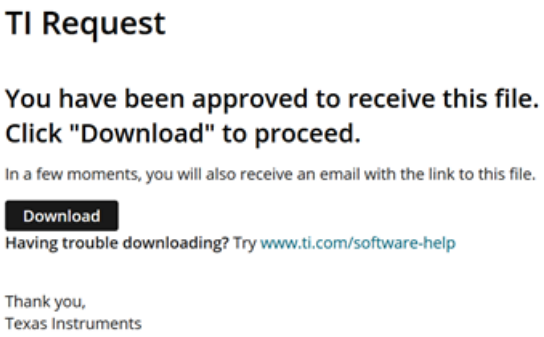

Figure 12. Driver Download (Part 1)

Save the driver zip file to any folder on the computer.

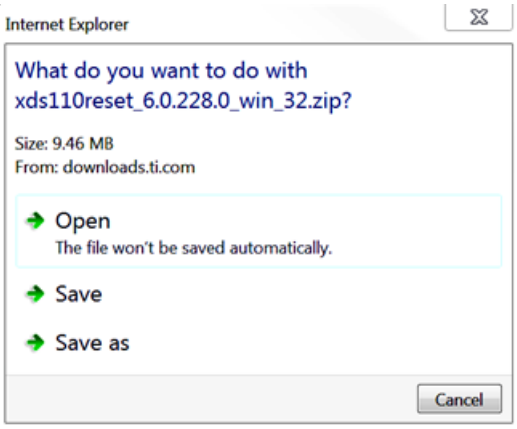

Figure 13. Driver Download (Part 2)

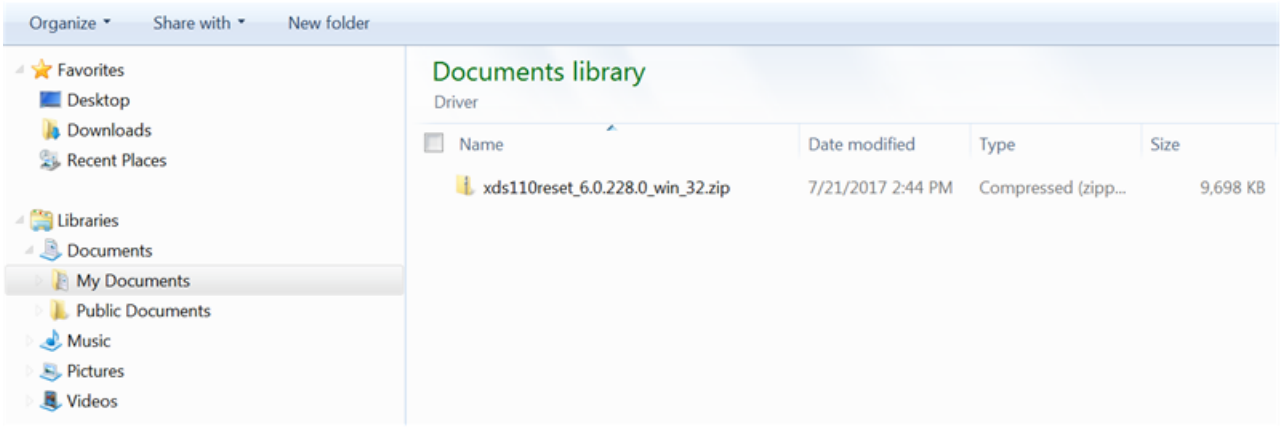

Figure 14. Driver Zip Folder

The zip file can then be extracted to any folder.

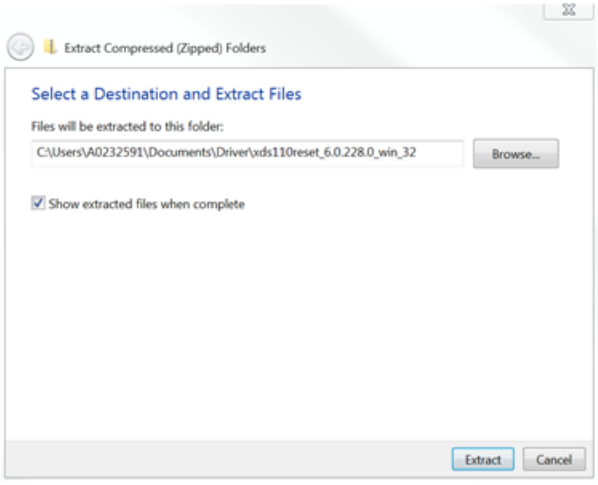

Figure 15. Extract Files

Click the folder to access the driver installation. In the folder, click “xdsdrivers-1.7.0.0-windows-installer.exe”.

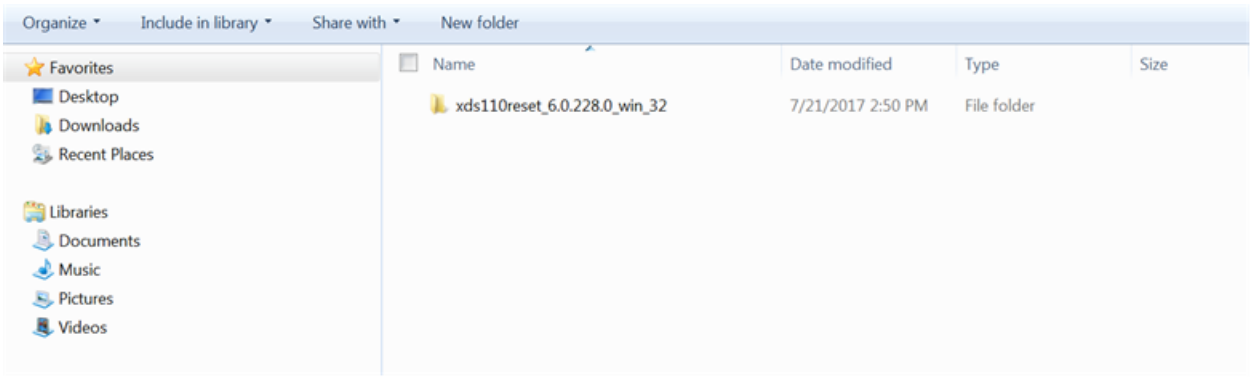

Figure 16. Driver Folder

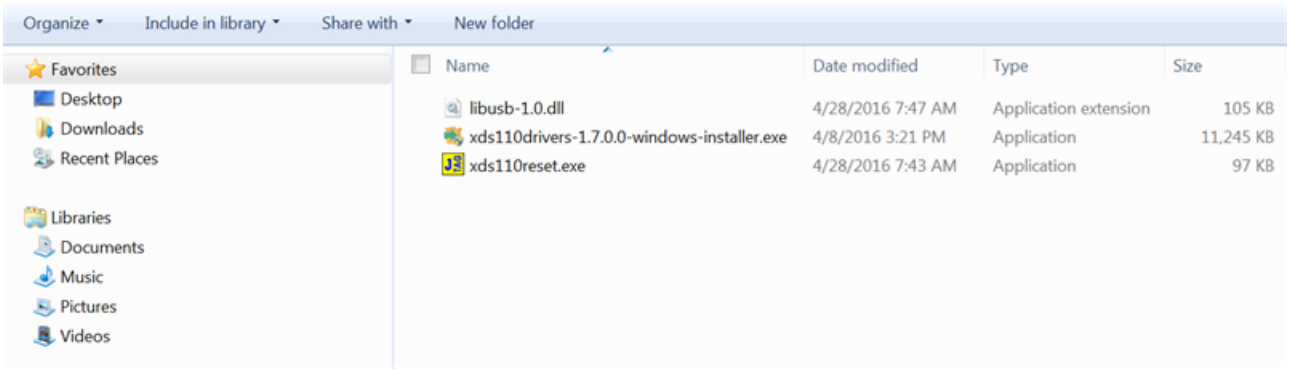

Figure 17. Driver Folder (Inside)

Once the driver setup is selected, a window appears as shown below. Click “Next” to proceed.

Figure 18. Driver Setup

Check “I accept the agreement” and click “Next” to proceed.

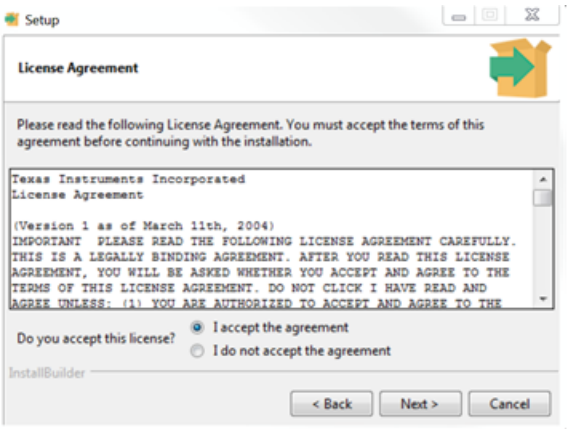

Figure 19. Driver License Agreement

A default installation directory is already filled in the box, but it can be changed to the user's preferred location. When ready, click “Next”.

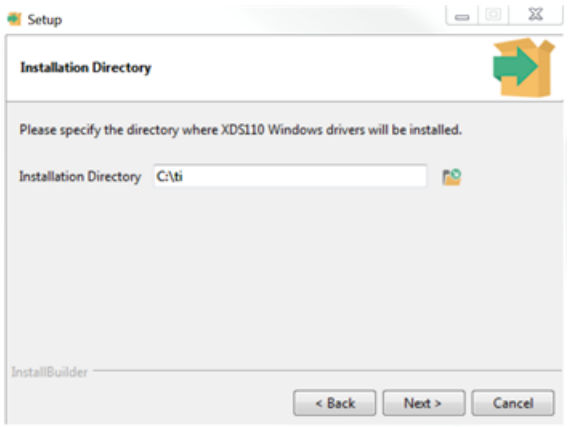

Figure 20. Driver Installation Directory

Click “Next” again to begin the installation. However, a series of security windows appears to confirm the installation. Click “Install” for each window.

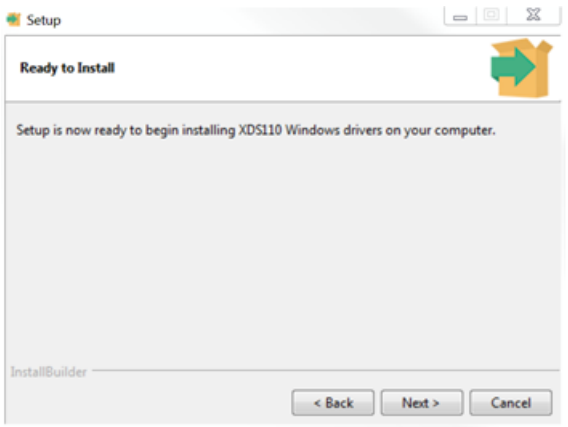

Figure 21. Device Driver Installation (Part 1)

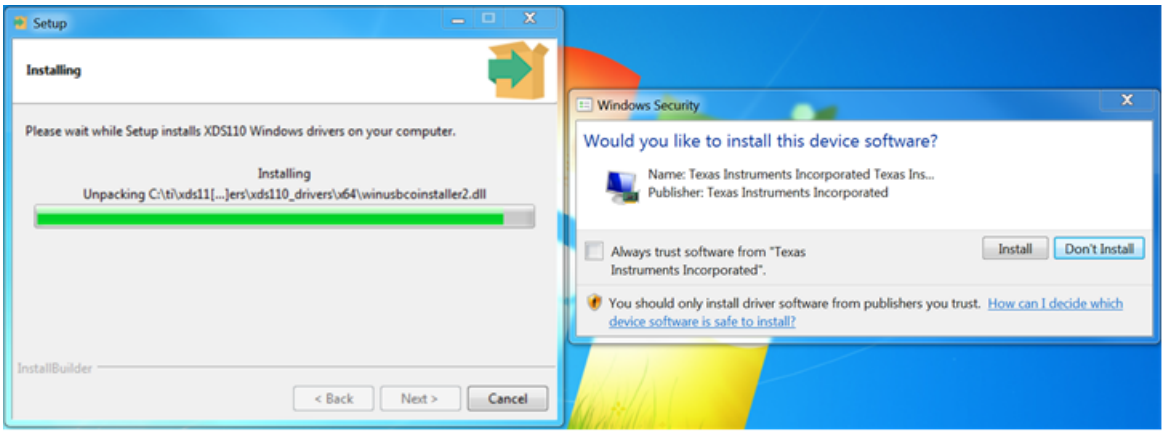

Figure 22. Device Driver Installation (Part 2)

In the end, a final window shows that the installation has completed. Click “Finish” to complete the installation process.

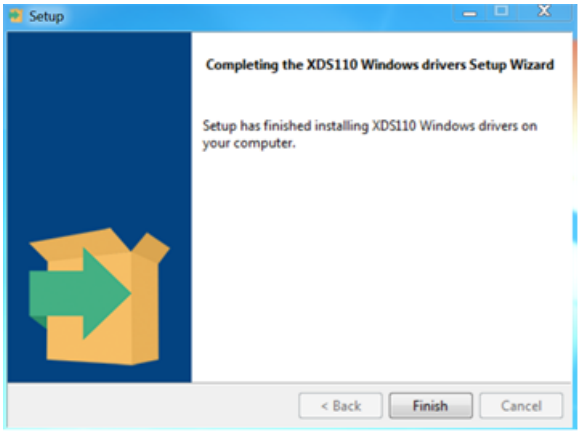

Figure 23. Device Driver Installation (Part 3)

2.3 EVM GUI Installation

LM36010 GUI is available to download from the TI website: LM3601xEVM GUI.

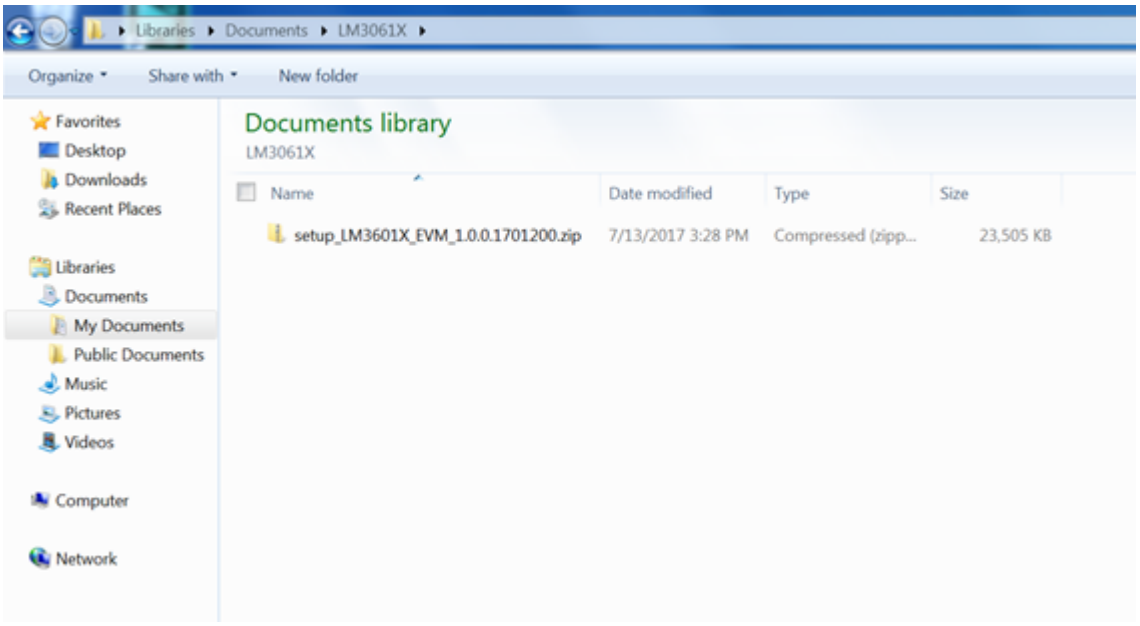

Figure 24. EVM Software Zip File

The zip file to install the GUI can be downloaded into any folder.

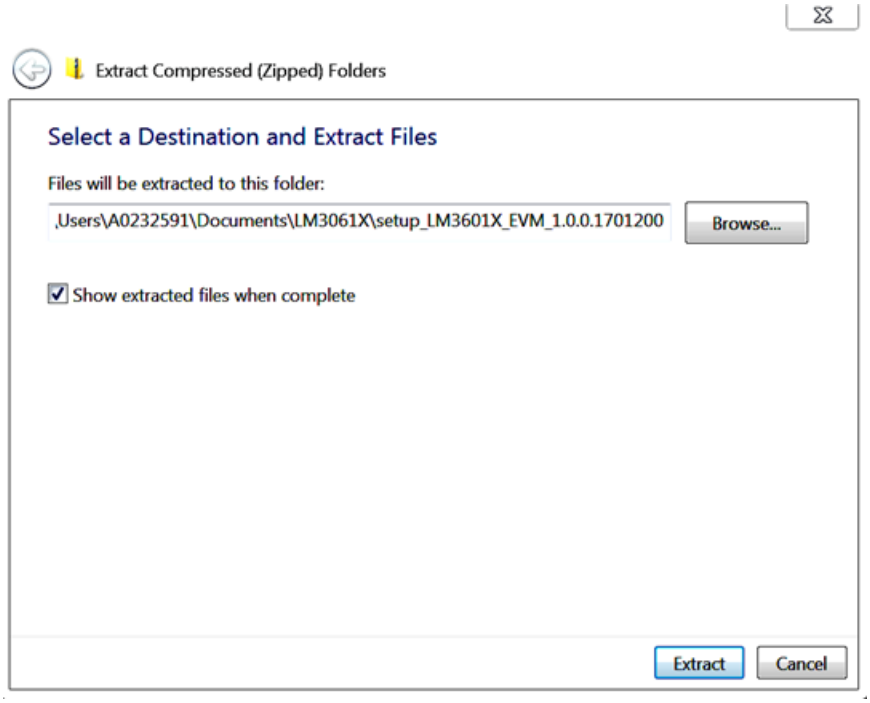

Figure 25. EVM Software Extract Files

Click the extracted file to access the EVM software installation. If there are any security programs, allow the file to be added to the computer.

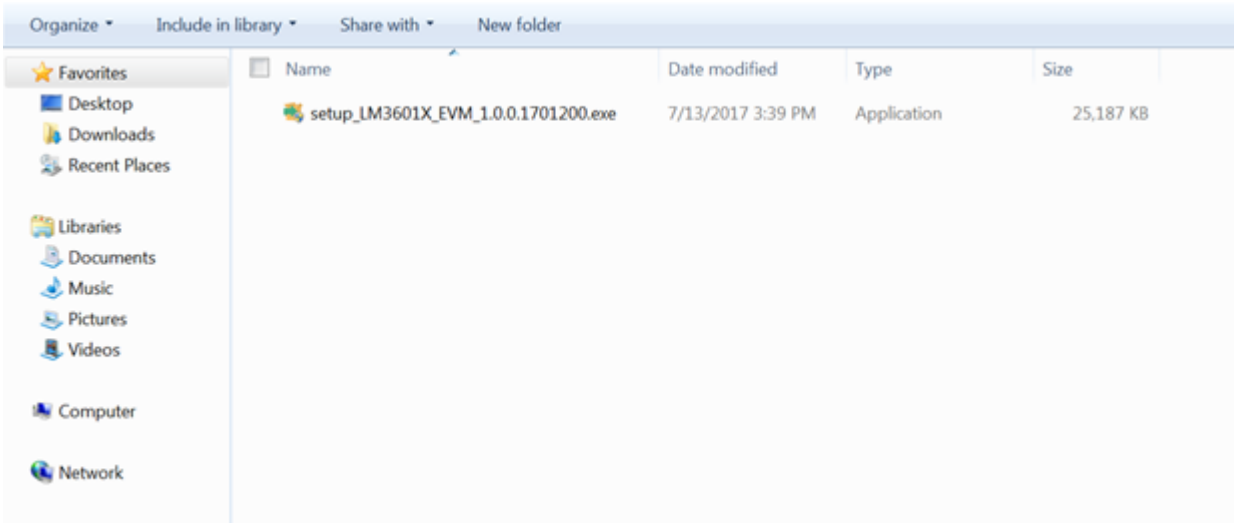

Figure 26. EVM Software Setup File

Once the file has been clicked, a window opens to install the EVM software. Click “Next” to proceed.

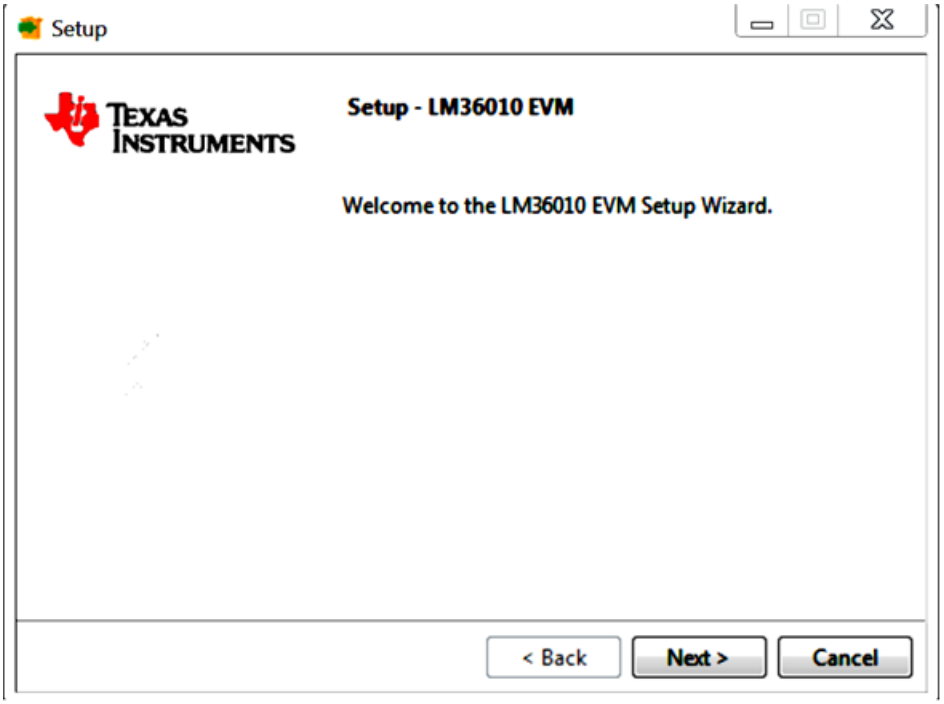

Figure 27. EVM Software Setup Wizard

Check “I accept the agreement” and click “Next” to proceed.

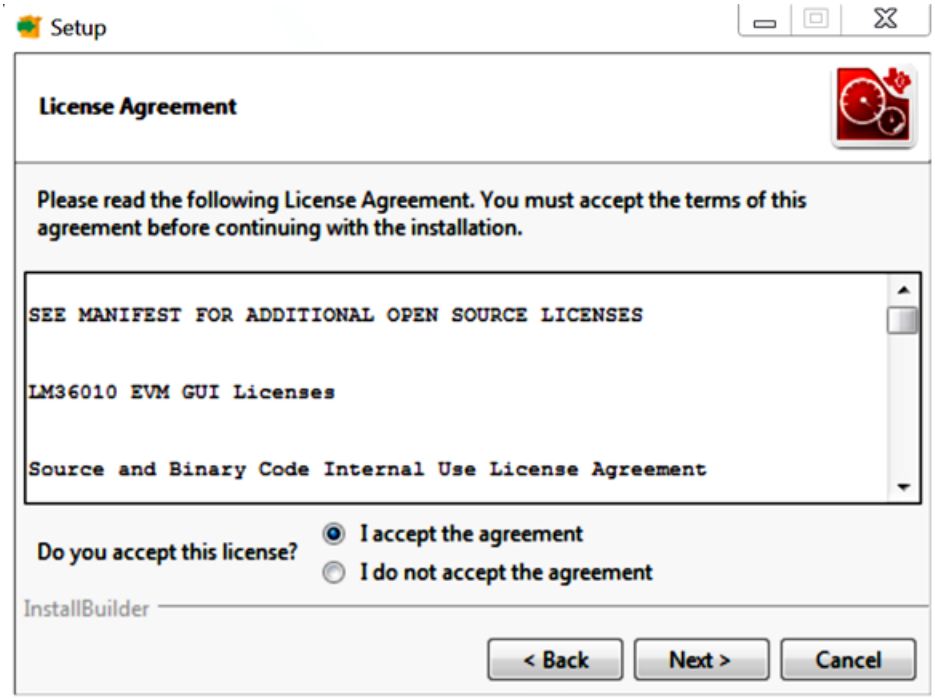

Figure 28. EVM Software License Agreement

A default installation directory is already filled in the box, but it can be changed to the user's preferred location. When ready, click “Next”.

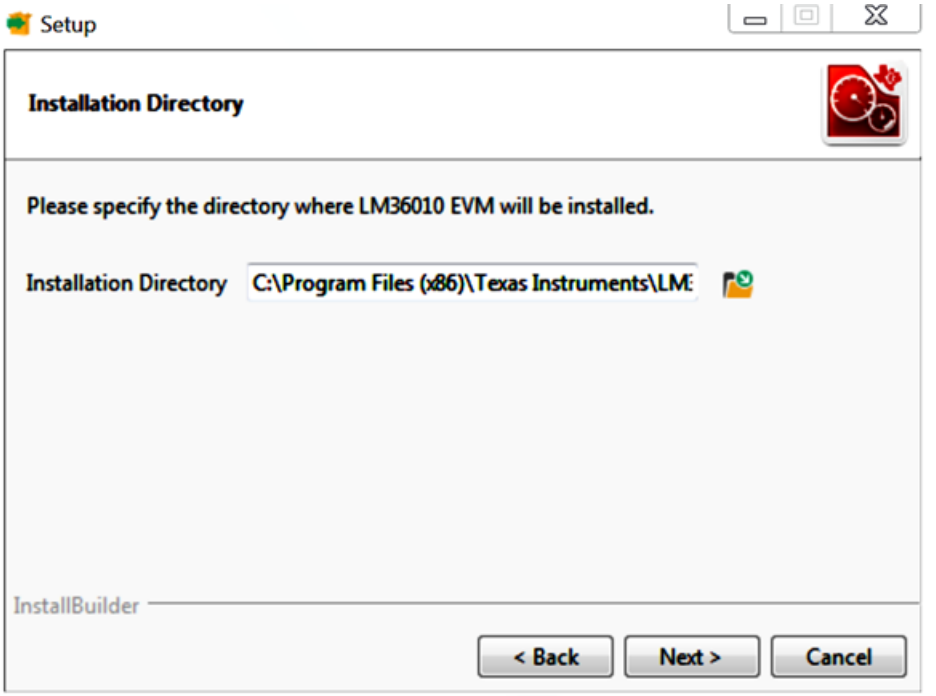

Figure 29. EVM Software Installation Directory

Click “Next” again to begin the installation. The window then shows the progress of the installation.

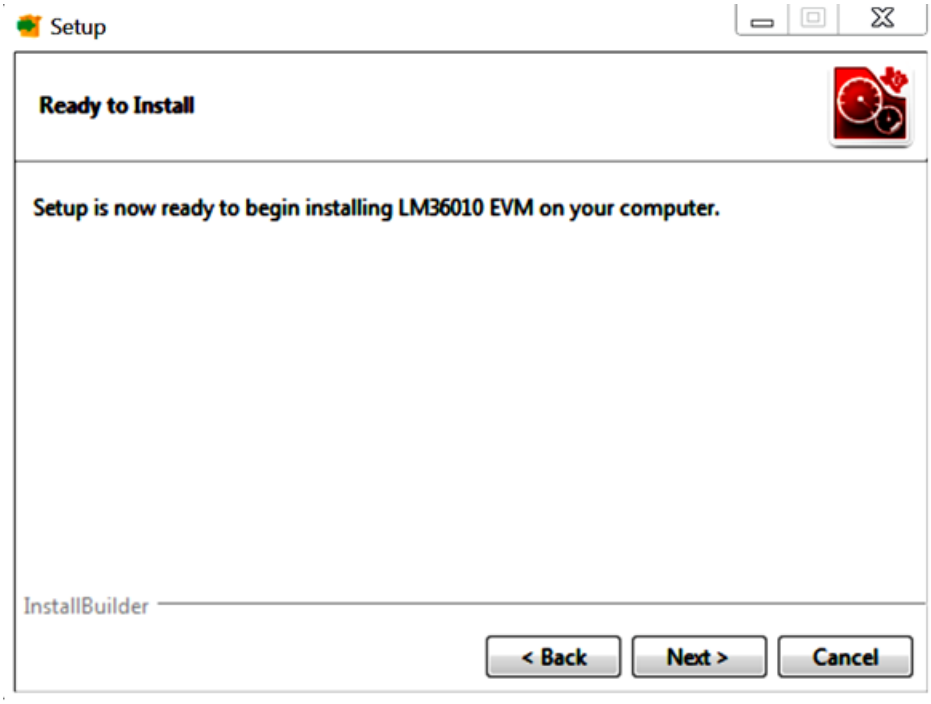

Figure 30. EVM Software Installation (Part 1)

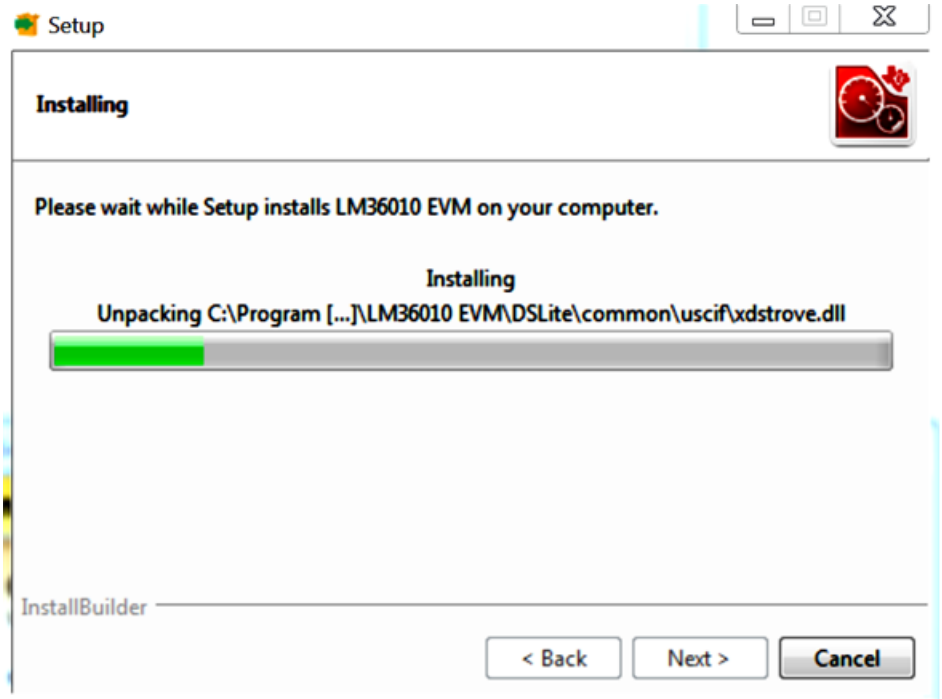

Figure 31. EVM Software Installation (Part 2)

After the installation is finished, the user has the option to open the program and create a shortcut on the Desktop. This step is optional. Click “Finish” to complete the installation process.

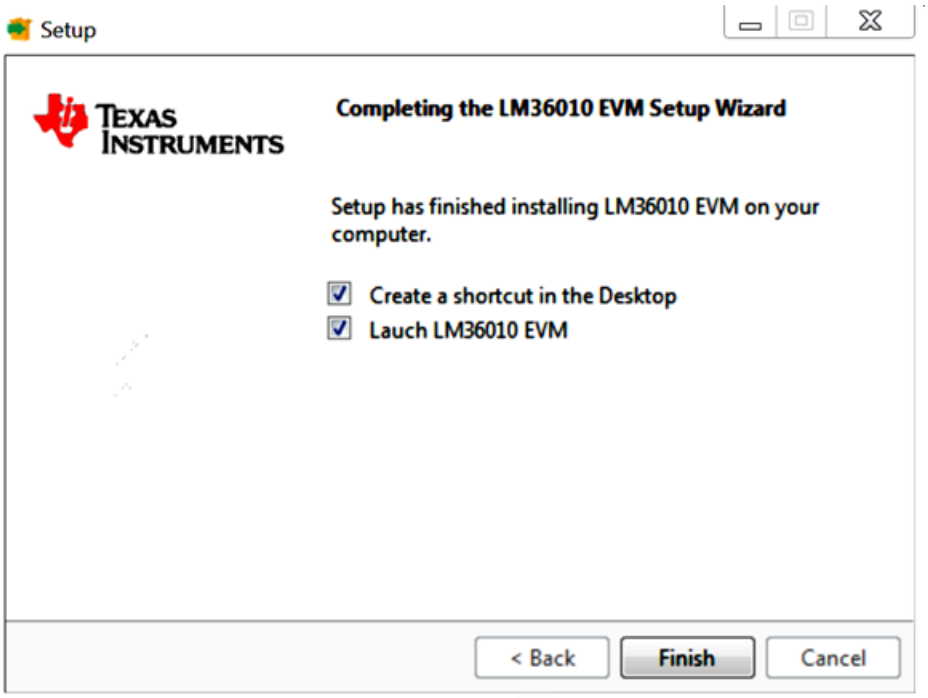

Figure 32. EVM Software Installation (Part 3)

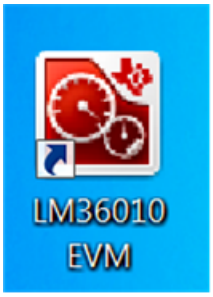

Figure 33. EVM Software Desktop Shortcut

3 GUI Operation

For proper operation, plug in the LM36010EVM and the LaunchPad to the computer before the GUI is opened. Once connected, and the program is executed, an EVM selection screen opens. Clicking on LM36010EVM leads to the appropriate GUI.

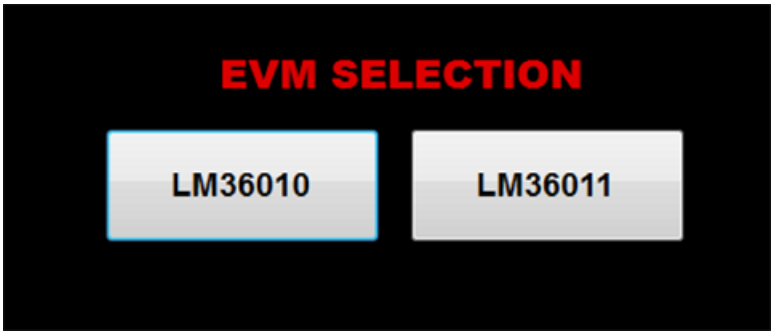

Figure 34. LM3601X Selection

A basic interface window opens with the default information view (Info). The status bar at the bottom of EVM software screen provides information regarding hardware connection status, I^2C communication status, and software version. Once the EVM software is connected to the hardware and starts to communicate with the firmware of MSP432, “Hardware Connected” and the light blue sign is displayed.

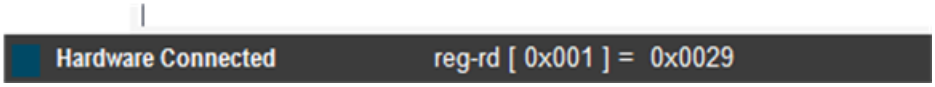

Figure 35. Status Bar

There are three available views of main menu: “Info”, “Register”, and “Control”. The components in each view are synchronized, so any changes performed in one view of menu are automatically updated in the others.

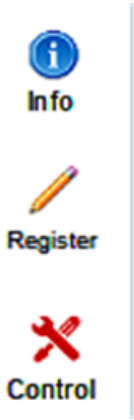

Figure 36. Menu

3.1 Information View

The Information View provides brief information of the LM36010EVM. For more detailed information, refer to the LM36010 data sheet.

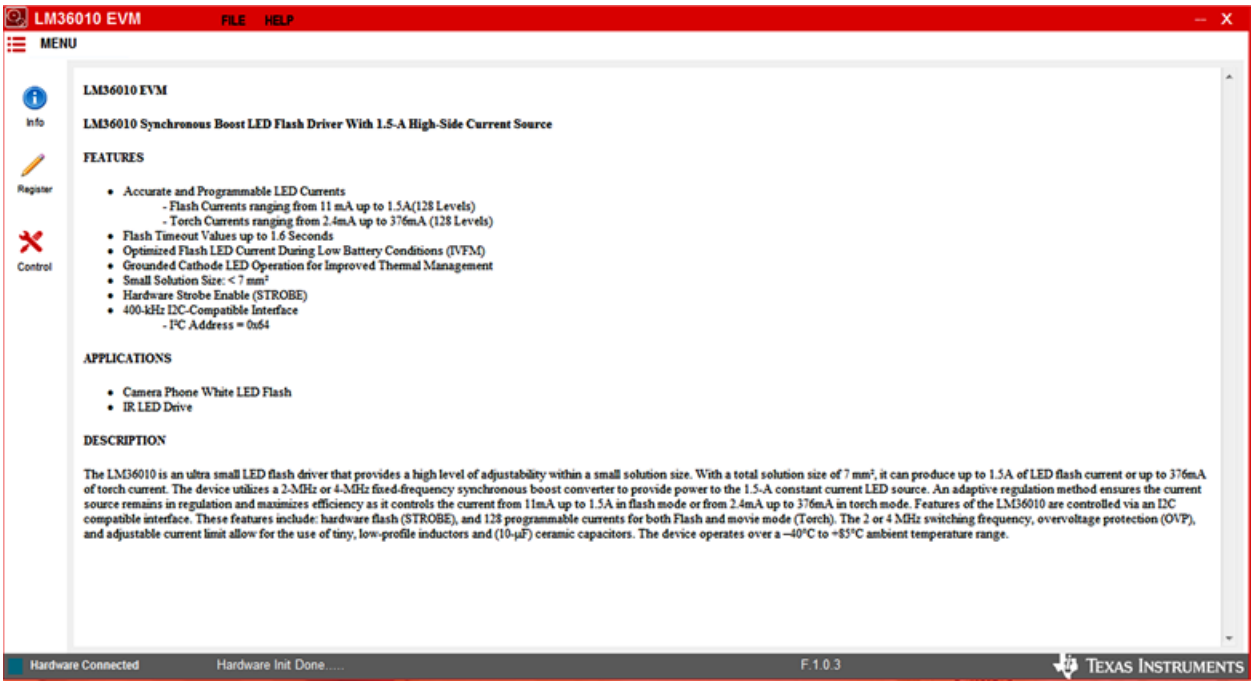

Figure 37. LM36010EVM Information View

3.2 Register View

The register view is shown when “Register” icon is clicked, and it provides the Register values, FieldView and Description fields. The user can enter the desired hex value to the registers in the “Value” column of Register values or in the "Value" column of FieldView, or can also perform a bit-wise configuration of any register fields by double-clicking on the corresponding register bit. "FieldView" displays the description of all fields of the selected register. Each register can be read independently or all registers can be read at once by utilizing the “Read” and “Read All” buttons, respectively.

The data is written to the register(s) in one of two ways, depending on the “Update Mode” field selection. In "Immediate" mode, the register data is written immediately following a “Value”, an individual bit, or a "Value" change. In “Deferred” mode, the displayed data is written to all registers upon depression of the “Write” button. The “Read All” button can be pressed to read back all the registers, which updates the values on the table.

Register settings can be saved to text file format by selecting “Save Registers” from file menu. Text file format register settings file can be loaded and programmed automatically by selecting “Load Register” from file menu.

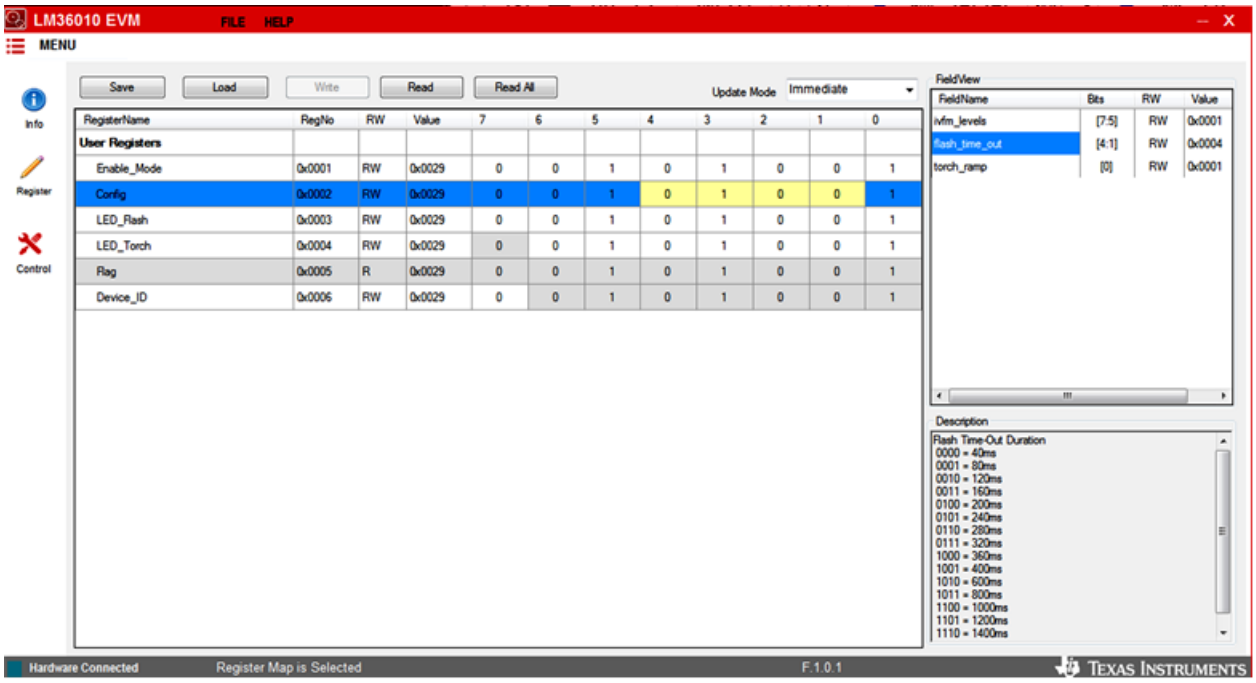

Figure 38. LM36010 Register View

3.3 Control View

The LM36010EVM GUI provides the user with access to all of the registers found on the device. The user can control these registers by clicking on “Control” on the left sidebar menu. Through a combination of buttons, drop-down boxes and sliders, the user can configure the LM36010EVM to perform in the desired mode. Unlike the Register View, the Control View only provides "Immediate" mode.

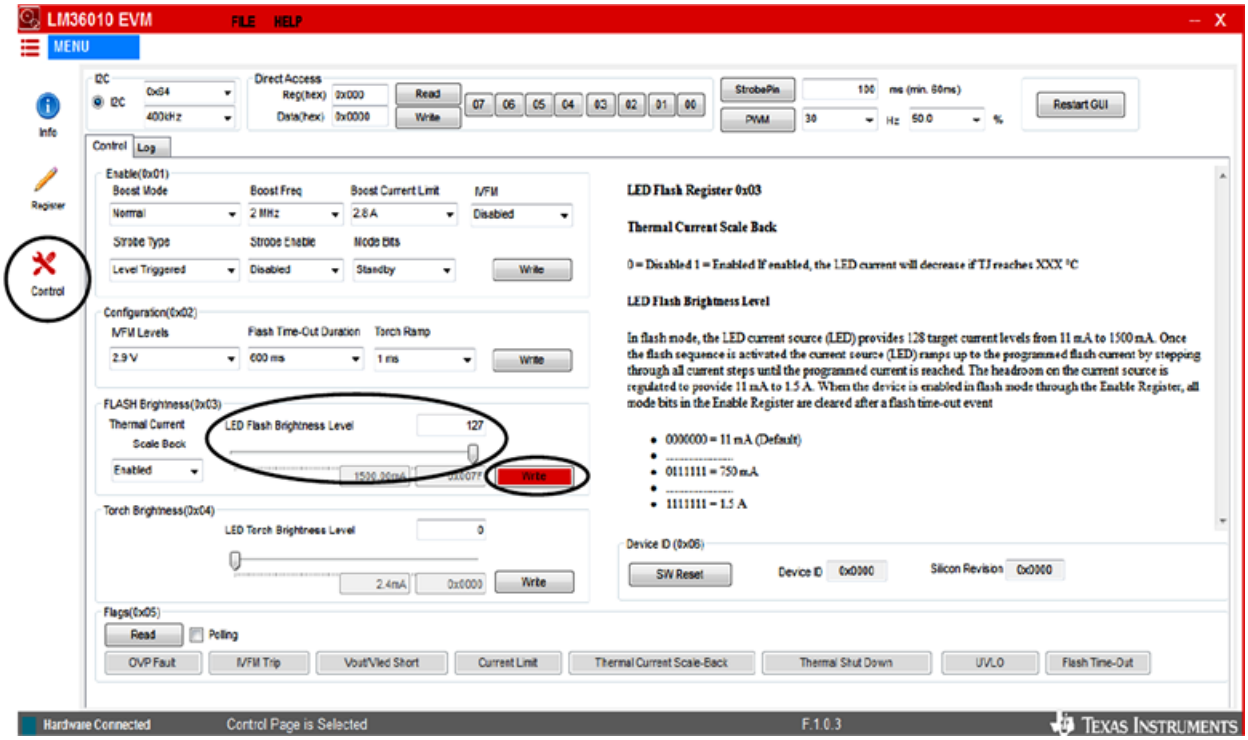

Figure 39. LM36010EVM Control View

3.3.1 I2C Interface Fields

The I²C Interface fields can be used to write or read any LM36010EVM register.

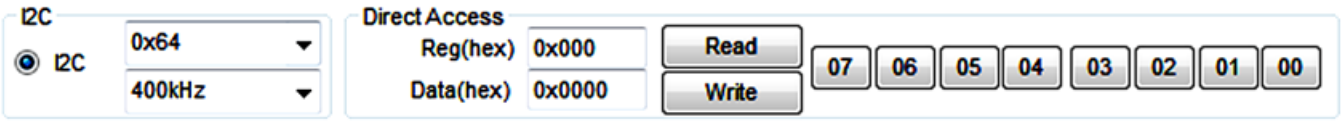

Figure 40. I2C Interface Fields

3.3.2 Control Panel

The Control Panel provides easy ways to control registers and pin values. There are two tabs available in the Control Panel: "Control" and "Log". The left side of these tabs contains the controls for the corresponding block of the LM36010EVM. The right side contains data log information.

The LM36010EVM has two main modes for testing: **Flash** and **Torch**. Both of them can be controlled on the Control Panel.

To produce a flash from the LED, the user can select **Flash** mode in the "Mode Bits" Options. Under "Configuration (0x02)", the flash duration can be changed. Under "FLASH Brightness (0x03)", the LED flash brightness level can either be adjusted with the scale or be written in the field provided. The max brightness code is 127, corresponding to 1.5 A. Once the settings are adjusted, the user can press the "Write" button to see the flash. Note that the LM36010EVM automatically switches to **Stand-by** mode after the **Flash** event.

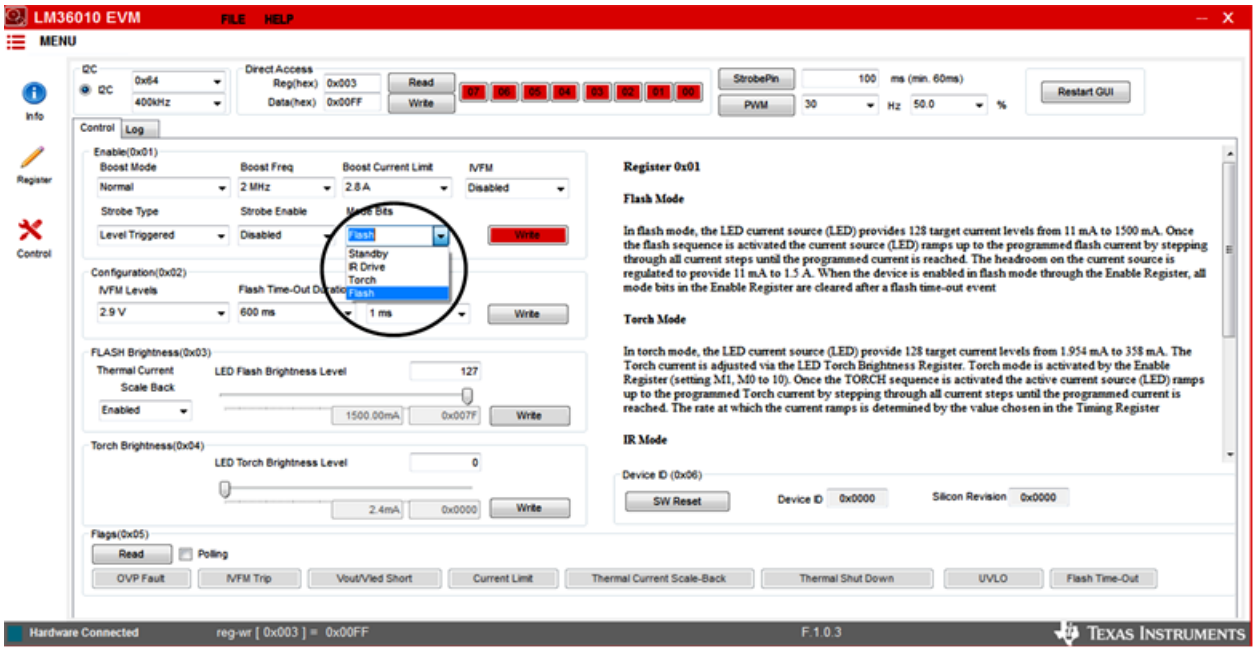

Figure 41. Flash Settings

To produce torch from the LED, the user can select **Torch** mode in the "Mode Bits" Options. Under "Torch Brightness (0x04)", the LED torch brightness level can be adjusted either with the scale or be written in the field provided. The maximum brightness code is 127. Once the settings are adjusted, the user can press the "Write" button to see the torch. LM36010EVM remains in **Torch** mode until it is switched to another mode.

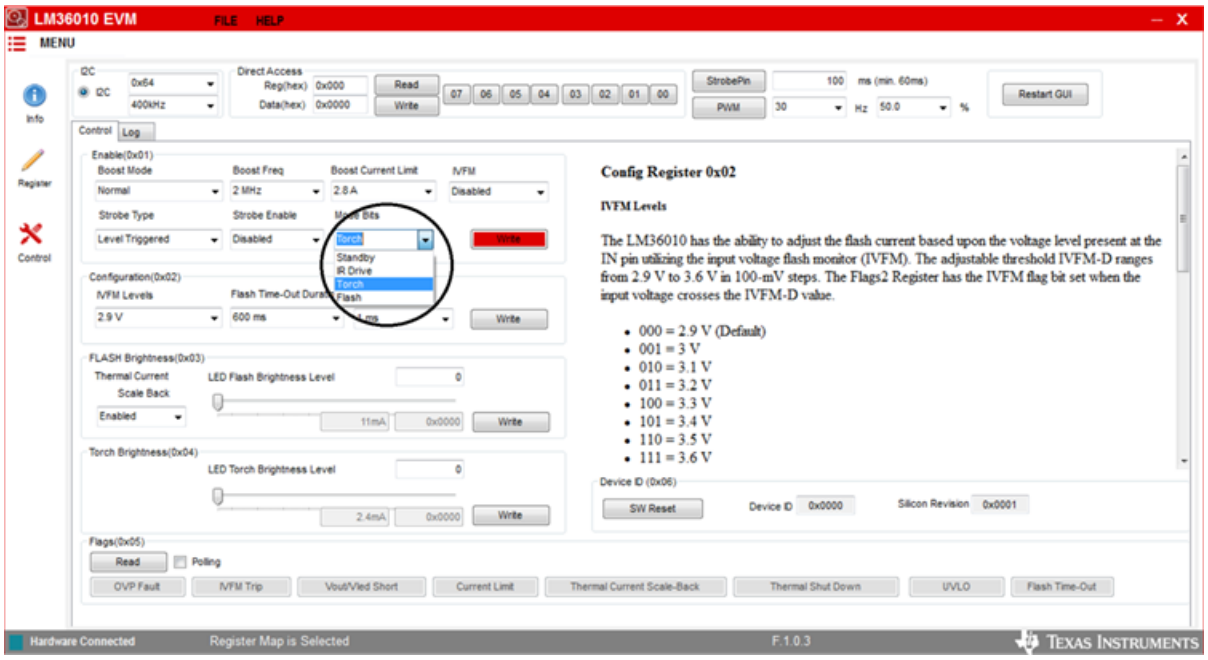

Figure 42. Torch Settings

Note that no data is written to the device until the “Write” button found within the corresponding register is pressed.

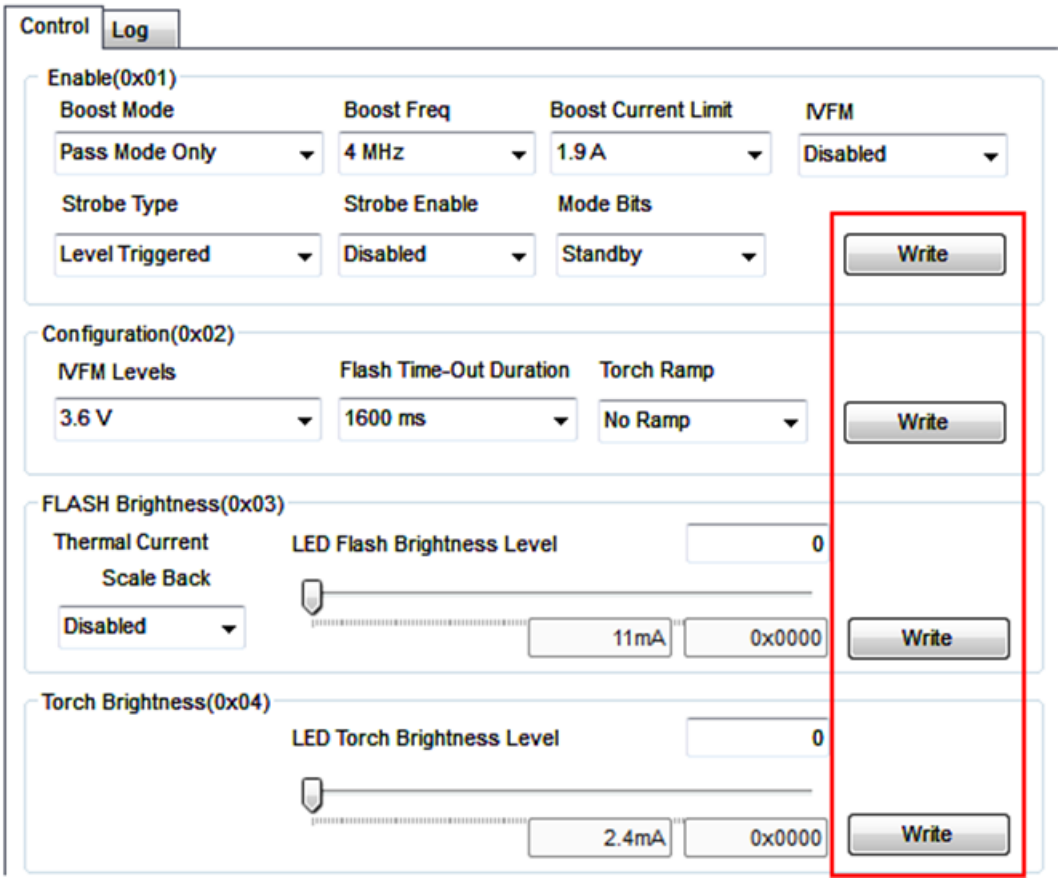

Figure 43. Write Buttons

3.3.3 Flags

The contents of the LM36010 fault registers are read upon clicking the “Read Flags” button. The registers are cleared upon read back.

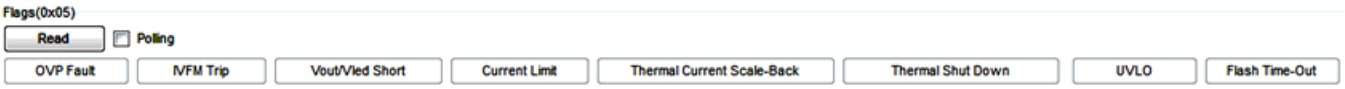

Figure 44. Flags

3.3.4 I/O Pin Controls

The LM36010 provides the user with the capability to control the STROBE input without the need of an external supply. The "StrobePin" button toggles the STROBE pin high for the duration entered in the field next to the button. The "PWM" button along with the frequency and duty cycle fields generate a continuous pulse train that can be used to generate a current pulse pattern on the enabled LED.

Figure 45. I/O Pin Controls

4 Schematic

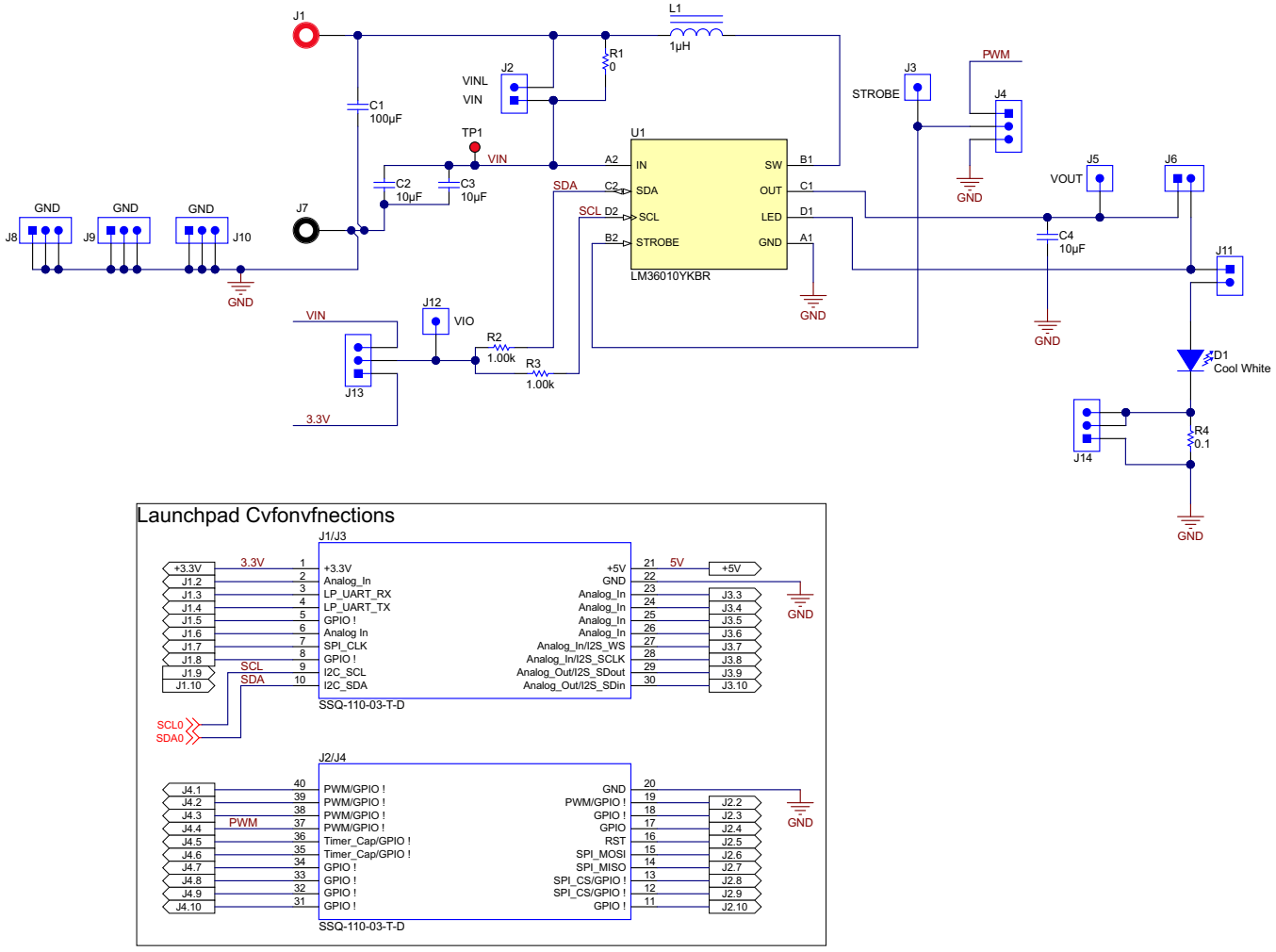

Figure 46. LM36010EVM Schematic

5 Board Layout

Figure 47, Figure 48, and Figure 49 show the board layout for the LM36010EVM. The EVM offers resistors, capacitors, and jumpers to enable the device and to configure it as desired.

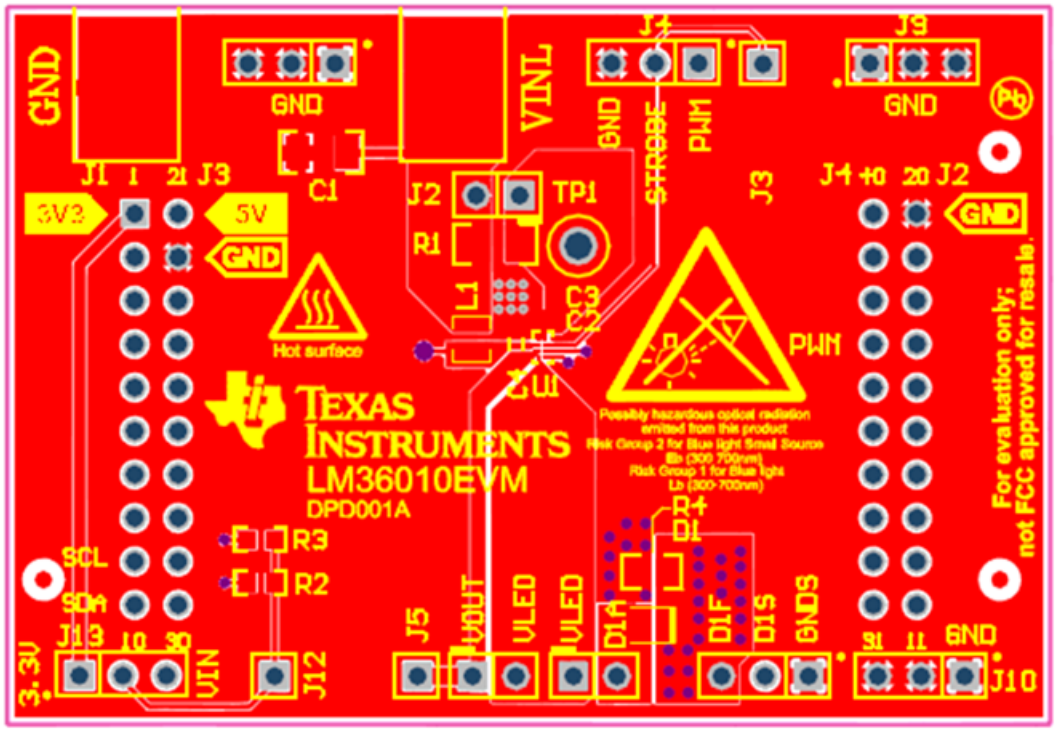

Figure 47. Top Assembly Layer

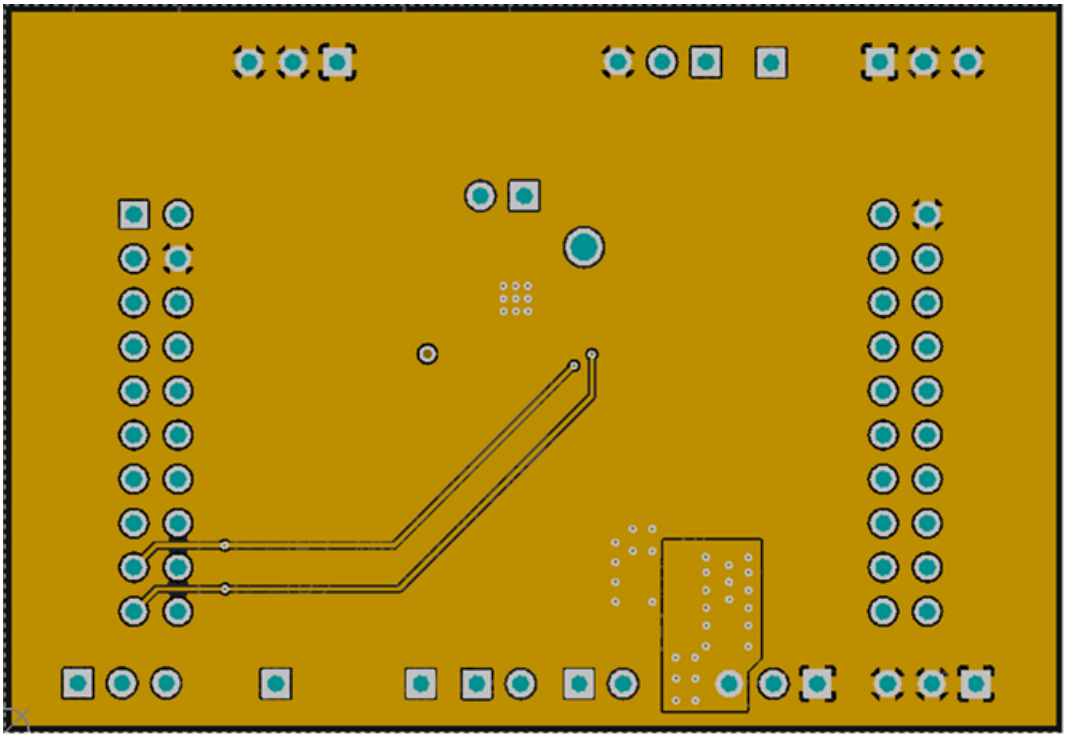

Figure 48. Middle Layer 1 Routing

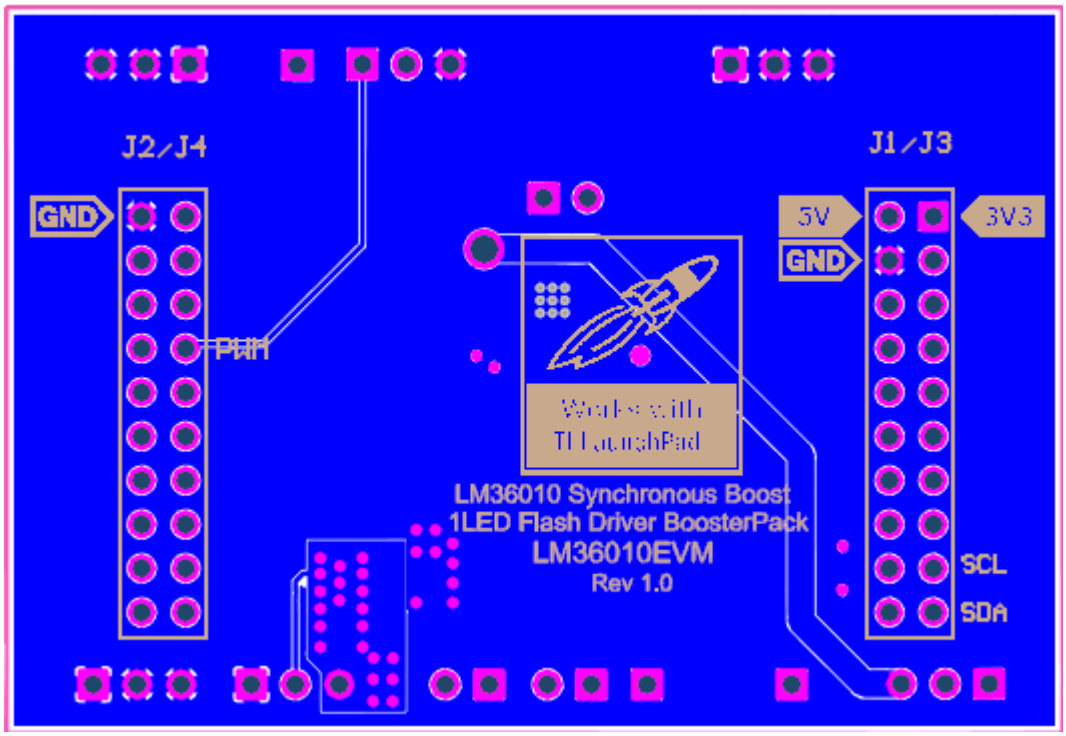

Figure 49. Bottom Assembly Layer (UNMIRRORED)

6 LM36010EVM Bill of Materials

Table 2. Bill of Materials

Designator	Quantity	Value	Description	Package Reference	PartNumber	Manufacturer	Alternate PartNumber	Alternate Manufacturer
!PCB1	1		Printed Circuit Board		DPD001	Any	-	-
C1	1	100uF	CAP, CERM, 100uF, 6.3V, +/-20%, X5R, 1206	1206	GRM31CR60J107ME39L	MuRata	-	-
C2	1	10uF	CAP, CERM, 10uF, 6.3V, +/-20%, X5R, 0402	402	CL05A106MQ5NUNC	Samsung		
C4	1	10uF	CAP, CERM, 10 µF, 25 V, +/- 20%, X5R, 0603	603	GRM188R61E106MA73D	MuRata		
D1	1	Cool White	LED, Cool White, SMD	2.04x0.7x1.64mm	LXCL-EYW4	Philips Lumileds		
J1	1		Standard Banana Jack, Insulated, Red	6091	6091	Keystone		
J1/J3, J2/J4	2		Receptacle, 2.54mm, 10x2, Tin, TH	10x2 Receptacle	SSQ-110-03-T-D	Samtec	CRD-081413-A-G	Major League Electronics
J2, J6, J11	3		Header, 100mil, 2x1, Gold, TH	2x1 Header	TSW-102-07-G-S	Samtec		
J3, J5, J12	3		Header, 100mil, 1pos, Gold, TH	Testpoint	TSW-101-07-G-S	Samtec		
J4, J8, J9, J10, J13, J14	6		Header, 100mil, 3x1, Gold, TH	Header, 100mil, 3x1, TH	HTSW-103-07-G-S	Samtec		
J7	1		Standard Banana Jack, Insulated, Black	6092	6092	Keystone		
L1	1	1uH	Inductor, Shielded, Metal Composite, 1 µH, 2.6 A, 0.058 ohm, SMD	1.6x2mm	DFE201610P-1R0M=P2	MuRata Toko		
R1	1	0	RES, 0, 5%, 0.25 W, 1206	1206	RC1206JR-070RL	Yageo America		
R2, R3	2	1.00k	RES, 1.00 k, 1%, 0.1 W, 0603	603	CRCW06031K00FKEA	Vishay-Dale		
R4	1	0.1	RES, 0.1 ohm, 5%, 0.125W, 0805	805	ERJ-6RSJR10V	Panasonic	-	-
SH-J1, SH-J2, SH-J3	3	1x2	Shunt, 100mil, Flash Gold, Black	Closed Top 100mil Shunt	SPC02SYAN	Sullins Connector Solutions		
TP1	1	Red	Test Point, TH, Compact, Red	Keystone5005	5005	Keystone	-	-
U1	1		Synchronous Boost LED Flash Driver with 1.5-A High-Side Current Source, YKB0008AGAG (DSBGA-8)	YKB0008AGAG	LM36010YKBR	Texas Instruments		Texas Instruments
C3	0	10uF	CAP, CERM, 10uF, 6.3V, +/-20%, X5R, 0402	402	CL05A106MQ5NUNC	Samsung		
FID1, FID2, FID3	0		Fiducial mark. There is nothing to buy or mount.	Fiducial	N/A	N/A		

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