

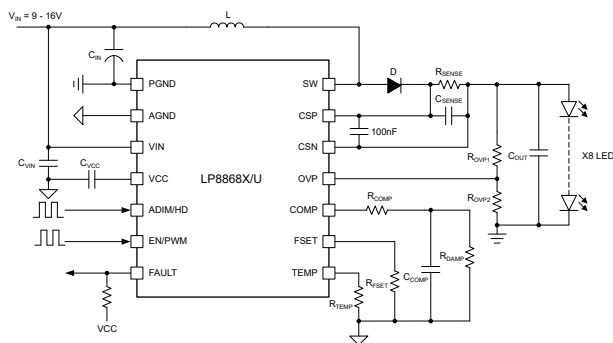
# LP8868-Q1 誘導性高速調光機能を搭載した車載用マルチトポロジ LED ドライバ

## 1 特長

- 車載アプリケーション用に AEC-Q100 認定済み:
  - 温度グレード 1:
    - 40°C ~ +125°C, T<sub>A</sub>
- 降圧、昇降圧、昇圧トポロジ用の MOSFET を内蔵
  - 広い入力電圧範囲: 4.5V ~ 65V
  - 5.2A および 150mΩ の MOSFET を内蔵
  - スイッチング周波数: 100kHz ~ 2.2MHz
  - 拡散スペクトラムによる EMI の低減
- 高精度のパワー FET 調光法
  - 降圧トポロジで最大 4A の出力電流
  - アナログ調光法 (調光比 256:1)
  - 高速 PWM 調光法 (パルス幅 150ns)
  - ハイブリッドおよびフレキシブル調光法
- 包括的な保護機能を搭載:
  - フォルト出力
  - LED の断線 / 短絡保護
  - サイクル単位の電流制限
  - スイッチング FET の障害保護
  - サーマル・シャットダウン
  - サーマル・フォールドバック曲線を設定可能

## 2 アプリケーション

- 車載インフォテインメント
- 車載用計器盤
- ヘッドアップ・ディスプレイ (HUD)
- 車載ライティング



昇圧 LED ドライバ・アプリケーションの標準回路図

## 3 概要

LP8868-Q1 family は、4.5V ~ 65 の広い入力電圧範囲に対応した非同期マルチトポロジ ソリューションです。ローサイド NMOS スイッチを内蔵することにより、このデバイスは高電力密度および高効率で LED を駆動できます。また、このファミリーは、同相カソード接続および単層 PCB 設計もサポートしています。スイッチング周波数は 100kHz ~ 2.2MHz で構成可能で、オプションのスペクトラム拡散機能により EMI 性能が向上します。

LP8868-Q1 family は、アナログ調光法、PWM 調光法、ハイブリッドおよびフレキシブル調光法の 4 つの調光オプションをサポートしています。各調光方法は、PWM および ADIM 入力ピン通して単純な High 信号と Low 信号によって構成できます。このファミリーは、適応型オフ時間電流モード制御とスマートで正確なサンプリングを採用して、誘導性高速調光 (IFD) を可能にし、高い調光精度を実現します。

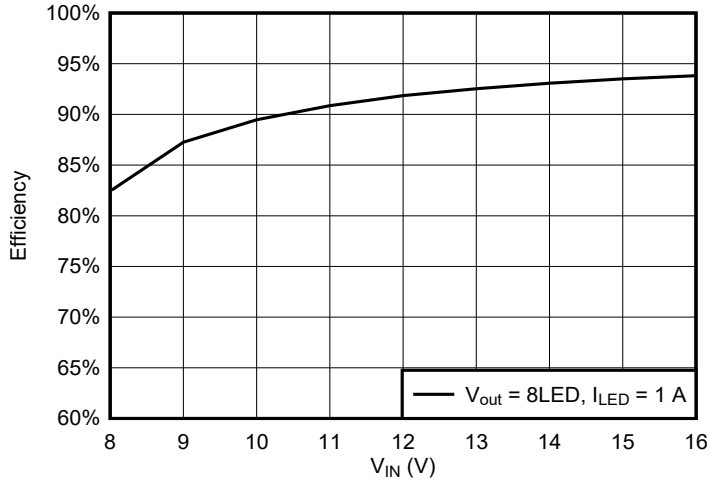
LP8868-Q1 family は、LED の断線と短絡、センス抵抗の開放と短絡、構成可能なサーマル フォールドバック、サーマル シャットダウンなど、複数の系統的な保護機能も提供します。フォルト出力は、フォルト状態が検出されるとすぐにアクノリッジ信号を送信します。

### パッケージ情報

部品番号	パッケージ 1	本体サイズ (公称)
LP8868-Q1	VSON (14)	4.5mm × 3.0mm
	HVSSOP (12) <sup>2</sup>	4mm × 3.0mm

- 利用可能なすべてのパッケージについては、このデータシートの末尾にある注文情報を参照してください。
- 製品プレビュー





効率と入力電圧との関係

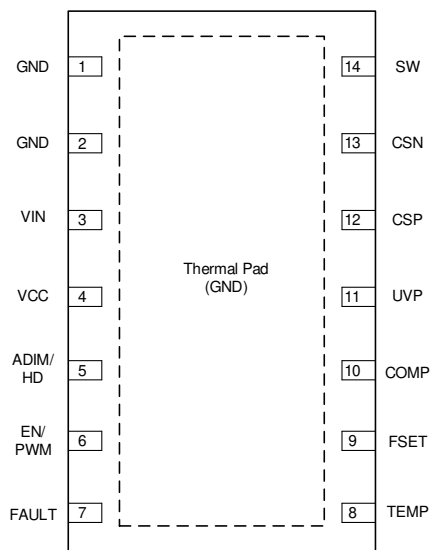
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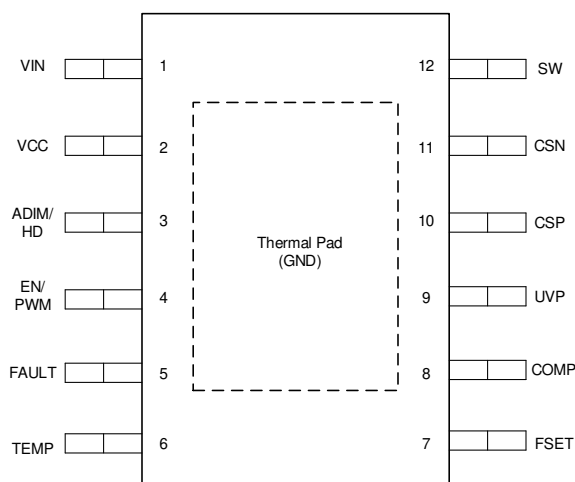
## 4 Comparison Table

Part Number	Topology	MOSFET Current Limit (Typical)	Spread Spectrum
LP8868XQDMTRQ1	Boost	6 A	Enabled
LP8868YQDMTRQ1	Buck-boost	6 A	Enabled
LP8868ZQDMTRQ1	Buck	6 A	Enabled
LP8868UQDMTRQ1	Boost	6 A	Disabled
LP8868VQDMTRQ1	Buck-boost	6 A	Disabled
LP8868WQDMTRQ1	Buck	6 A	Disabled

## 5 Pin Configuration and Functions



5-1. 14-Pin Buck VSON Top View



HVSSOP is product preview

5-2. 12-Pin Buck HVSSOP Top View

表 5-1. Pin Functions

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
No.	NAME		
1	PGND	G	Power ground pin.
2	AGND	G	Analog ground pin.
3	VIN	P	Input power pin.
4	VCC	P	Internal LDO output pin. Connect with a 10-V, 1-uF capacitor to GND.
5	ADIM/HD	I	Analog dimming or hybrid dimming pin. Pull high for PWM dimming only, pull low for hybrid dimming, input PWM signal for analog dimming.

表 5-1. Pin Functions (続き)

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
No.	NAME		
6	PWM/EN	I	PWM dimming or EN pin. Pull high for always on, pull low for disabling the device, input PWM signal for PWM dimming.
7	FAULT	O	Open drain output. Pull low when fault is detected.
8	TEMP	I/O	Thermal foldback pin. Put different resistor values to GND to set different thermal foldback behavior curves.
9	FSET	I/O	Switching frequency set pin, with range of 100 kHz ~ 2.2 MHz. Put different resistor values to GND for different switching frequencies.
10	COMP	I/O	Error-amplifier output. Connect capacitors to GND. Different capacitor values determine different softstart times and bandwidths.
11	UVP	I	Undervoltage detection pin. Put different resistor dividers to set the LED open detection thresholds.
12	CSP	I	LED current sense positive pin.
13	CSN	I	LED current sense negative pin.
14	SW	P	Switching node pin. Internally connected to the low-side MOSFET. Connect with the power inductor and the schottky diode.
Pad	Thermal Pad	G	Power ground pin.

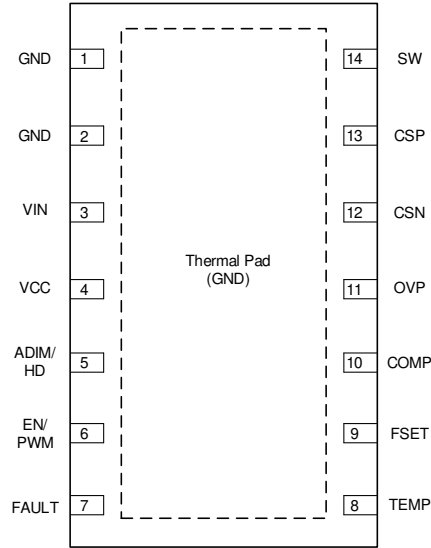


図 5-3. 14-Pin Boost/Buck-Boost VSON Top View

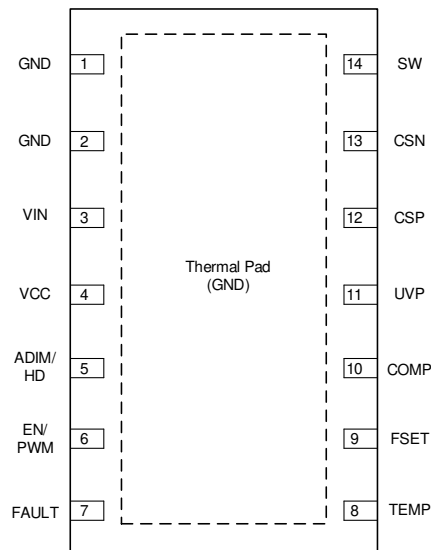


図 5-4. 12-Pin Boost/Buck-Boost HVSSOP Top View

HVSSOP is product preview

表 5-2. Pin Functions for boost/buck-boost topology

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
VSON Package	NAME		
1	PGND	G	Power ground pin.
2	AGND	G	Analog ground pin.
3	VIN	P	Input power pin.
4	VCC	P	Internal LDO output pin. Connect with a 10-V, 1-uF capacitor to GND.
5	ADIM/HD	I	Analog dimming or hybrid dimming pin. Pull high for PWM dimming only, pull low for hybrid dimming, input PWM signal for analog dimming.

**表 5-2. Pin Functions for boost/buck-boost topology (続き)**

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
VSON Package	NAME		
6	PWM/EN	I	PWM dimming or EN pin. Pull high for always on, pull low for disabling the device, input PWM signal for PWM dimming.
7	FAULT	O	Open drain output. Pull low when fault is detected.
8	TEMP	I/O	Thermal foldback pin. Put different resistor values to GND to set different thermal foldback behavior curves.
9	FSET	I/O	Switching frequency set pin, with range of 100 kHz ~ 2.2 MHz. Put different resistor values to GND for different switching frequencies.
10	COMP	I/O	Error-amplifier output. Connect capacitors to GND. Different capacitor values determine different softstart times and bandwidths.
11	OVP	I	Overvoltage detection pin. Put different resistor dividers to set the LED open detection thresholds.
12	CSN	I	LED current sense negative pin.
13	CSP	I	LED current sense positive pin.
14	SW	P	Switching node pin. Internally connected to the low-side MOSFET. Connect with the power inductor and the schottky diode.
Pad	Thermal Pad	G	Power ground pin.

(1) I = Input, O = Output, P = Supply, G = Ground



## 6 Specifications

### 6.1 Absolute Maximum Ratings

over operating ambient temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
Voltage on pins	VIN, UVP, OVP, CSP, CSN, SW,	-0.3	65	V
Voltage on pins	VCC, ADIM/HD, EN/PWM, FAULT, TEMP, FSET, COMP	-0.3	5.5	V
Operation junction temperature	T <sub>J</sub>	-40	125	°C
Storage temperature	T <sub>stg</sub>	-65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### 6.2 ESD Ratings

			VALUE	UNIT
V <sub>(ESD)</sub>	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±2000	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.  
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Conditions

over operating ambient temperature range (unless otherwise noted)

		MIN	MAX	UNIT
Input voltage range	VIN	4.5	63	V
Input voltage range	UVP, OVP, CSP, CSN	0	63	V
Input voltage range	VCC, ADIM/HD, EN/PWM, TEMP, FSET	0	5	V
Output voltage range	SW	0	63	V
	FAULT, COMP	0	5	V
Operating junction temperature, T <sub>J</sub>		-40	125	°C

### 6.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		Device	UNIT
		SON	
		14 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	39.1	°C/W
R <sub>θJC(top)</sub>	Junction-to-case (top) thermal resistance	39.5	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	14.7	°C/W
ψ <sub>JT</sub>	Junction-to-top characterization parameter	0.9	°C/W
ψ <sub>JB</sub>	Junction-to-board characterization parameter	14.7	°C/W

- (1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, [SPRA953](#).

## 6.5 Electrical Characteristics

The electrical ratings specified in this section apply to all specifications in this document, unless otherwise noted. These specifications are interpreted as conditions that do not degrade the device parametric or functional specifications for the life of the product containing it.  $T_J = -40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ ,  $V_{IN} = 4.5\text{ V}$  to  $60\text{ V}$ , (unless otherwise noted).

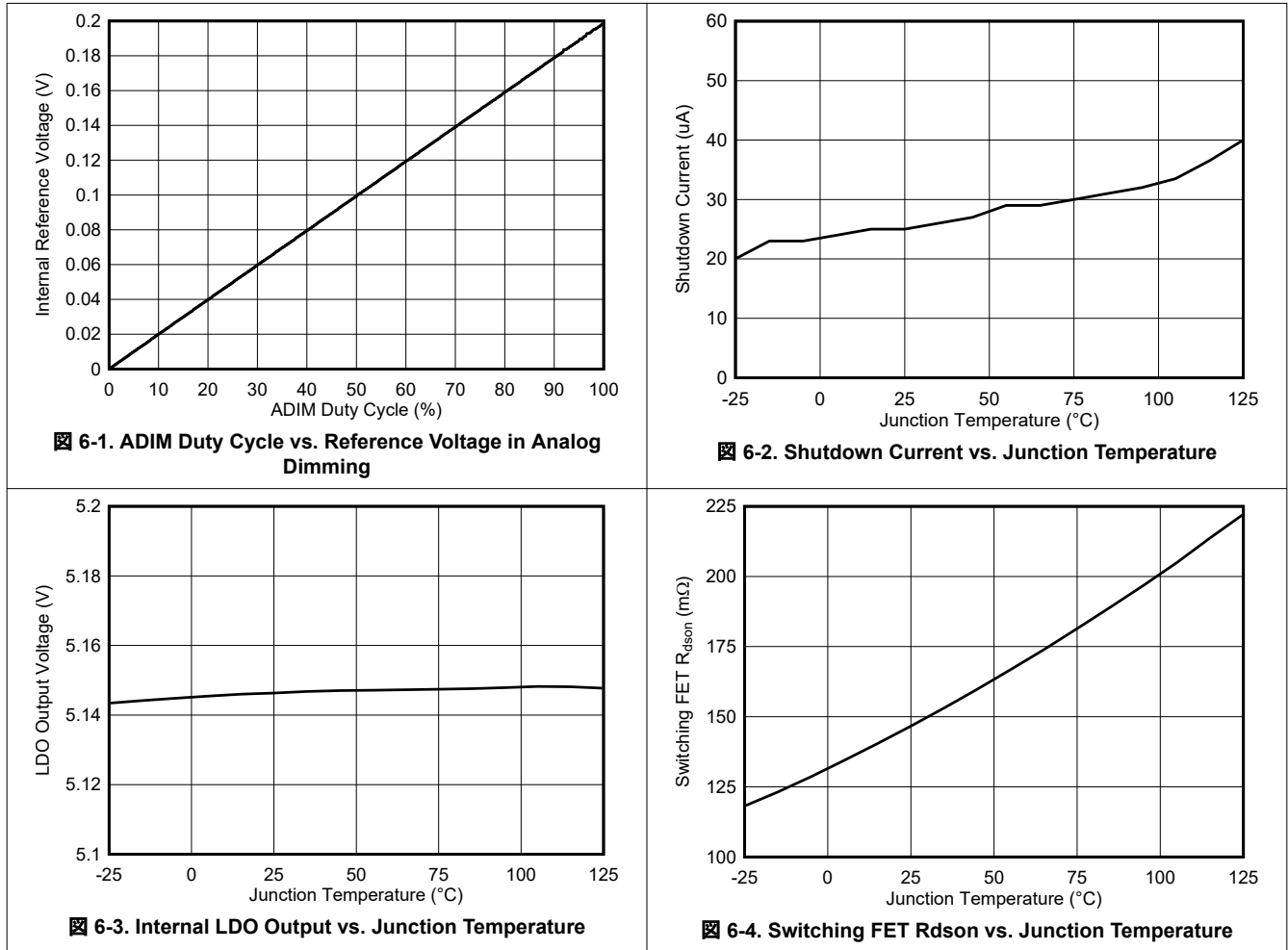
PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>INPUT SUPPLY</b>						
$V_{VIN\_UVLO}$	$V_{IN}$ undervoltage lockout	Rising $V_{IN}$	3.0	3.2	3.4	V
		Falling $V_{IN}$	2.8	3.0	3.2	V
	Hysteresis			0.2		V
$I_{SD}$	Shut down current from $V_{IN}$	$V_{IN} = 12\text{ V}$ , $V_{EN/PWM} = 0\text{ V}$		0.8	2.3	$\mu\text{A}$
$I_{OFF}$	PWM off current from $V_{IN}$	$V_{IN} = 12\text{ V}$ , $V_{EN/PWM} = 0\text{ V}$		2.5		mA
$I_{OP}$	Normal operating current	400-kHz switching frequency		4.6		mA
$I_{OP}$	Normal operating current	2.2-MHz switching frequency		10.0		mA
$V_{VCC}$	Internal LDO output voltage	$I_{VCC} = 10\text{ mA}$	5.0	5.15	5.3	V
$I_{VCC\_LIM}$	Internal LDO output current limit		38	47	56	mA
<b>DIMMING</b>						
$V_{PWM\_L}$	Low-level input voltage				0.4	V
$V_{PWM\_H}$	High-level input voltage		1.2			V
$V_{ADIM\_L}$	Low-level input voltage				0.4	V
$V_{ADIM\_H}$	High-level input voltage		1.2			V
$t_{PWM\_OUT\_ON}$	PWM output minimum on time				150	ns
$t_{PWM\_IN\_ON}$	PWM input minimum on time				150	ns
$t_{PWM\_IN\_OFF}$	PWM input minimum off time to disable device		57		77	ms
$f_{ADIM}$	Analog Dimming input frequency	6-bit ADIM resolution	0.1		156	kHz
$f_{ADIM}$	Analog Dimming input frequency	8-bit ADIM resolution	0.1		39	kHz
<b>FAULT</b>						
$V_{OL}$	Output level low	$I = 3\text{ mA}$			0.1	V
$I_{LEAKAGE}$	Output leakage current	$V = 5\text{ V}$			1	$\mu\text{A}$
<b>FEEDBACK AND ERROR AMPLIFIER</b>						
$g_{M(ea)}$	Transconductance gain	ADIM 100% duty cycle, $V_{CSP-CSN} = 200\text{ mV}$ , $V_{COMP} = 1.5\text{ V}$	205	265	325	$\mu\text{A/V}$
$I_{COMP}$	Source/sink current	ADIM 100% duty cycle, $V_{CSP-CSN} = 200\text{ mV} \pm 200\text{ mV}$ , $V_{COMP} = 1.5\text{ V}$	$\pm 24$	$\pm 40$	$\pm 56$	$\mu\text{A}$
$V_{CSP-CSN}$	Current sense threshold	ADIM 100% duty cycle	194	200	206	mV
$V_{CSP-CSN}$	Current sense threshold	ADIM 12.5% duty cycle, compared with 100% duty cycle	11.875	12.5	13.125	%
$V_{CSP-CSN}$	Current sense threshold	ADIM 1.17% duty cycle, compared with 100% duty cycle	0.82	1.17	1.52	%
$I_{LEAK\_CSP/N}$	CSP+CSN pin leakage current	$V_{IN} = 60\text{ V}$ , $V_{EN/PWM} = 5\text{ V}$	22		31	$\mu\text{A}$
$I_{LEAK\_CSP/N}$	CSP+CSN pin leakage current	$V_{IN} = 60\text{ V}$ , $V_{EN/PWM} = 0\text{ V}$	10		15	$\mu\text{A}$
<b>POWER STAGE</b>						
$R_{DSON}$	Switching FET on resistance	$V_{IN} \geq 5\text{ V}$		150		m $\Omega$
$t_{min\_ON}$	Switching FET minimum on time			100		ns
$t_{min\_OFF}$	Switching FET minimum off time			100		ns
$f_{SW}$	Switching FET frequency		0.1		2.2	MHz
<b>CURRENT LIMIT</b>						
$I_{LIM}$	Switching FET cycle-by-cycle current limit (LP8868X/LP8868Y/LP8868U/LP8868V)		5.8	6.5	7.6	A
$I_{LIM}$	Switching FET cycle-by-cycle current limit (LP8868Z/LP8868W)		5.2	6	7	A
<b>THERMAL PROTECTION</b>						
$T_{th}$	Thermal foldback starting temperature threshold	$R_{TEMP} = 20\text{ k}\Omega$		130		$^{\circ}\text{C}$

The electrical ratings specified in this section apply to all specifications in this document, unless otherwise noted. These specifications are interpreted as conditions that do not degrade the device parametric or functional specifications for the life of the product containing it.  $T_J = -40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ ,  $V_{IN} = 4.5\text{ V}$  to  $60\text{ V}$ , (unless otherwise noted).

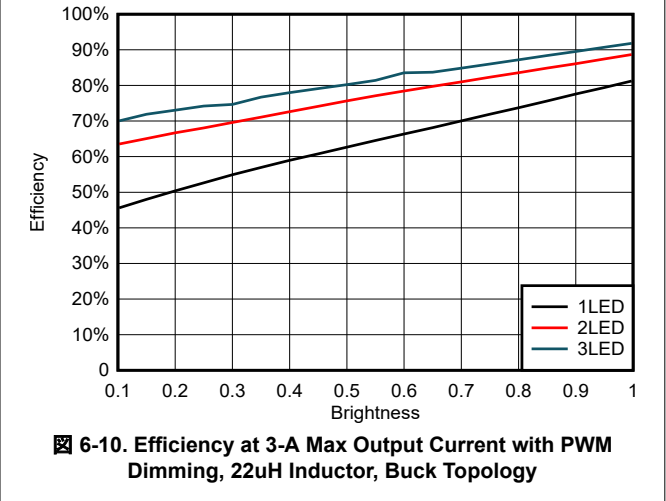
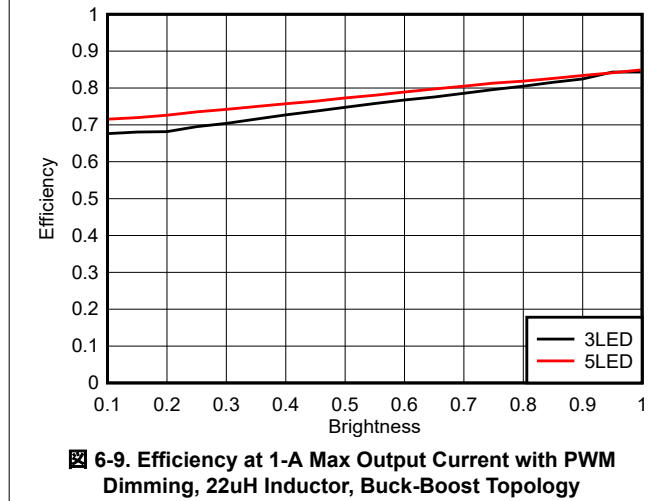
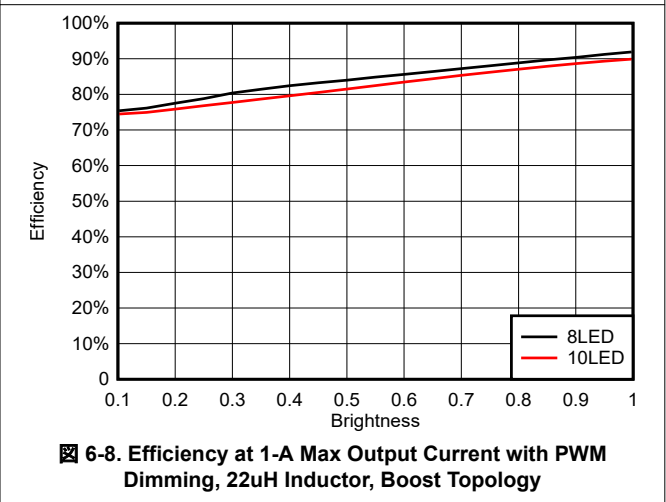
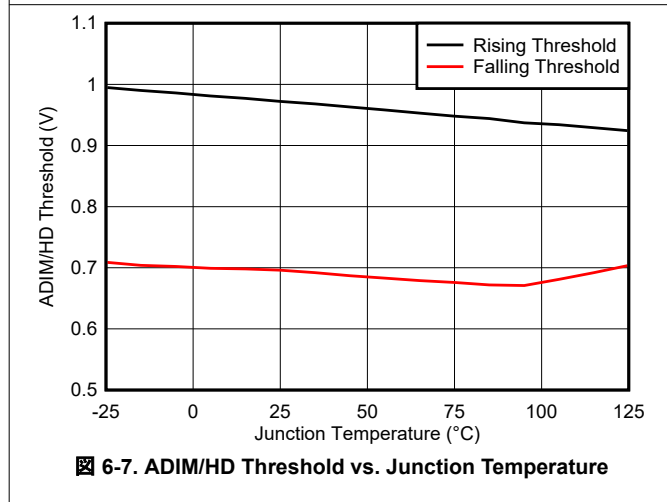
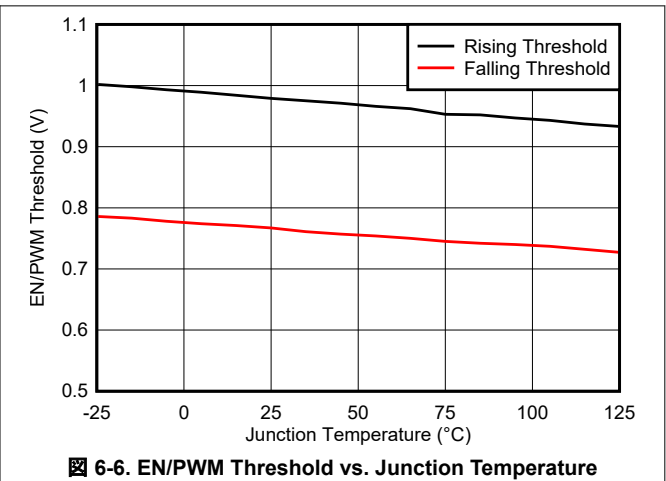
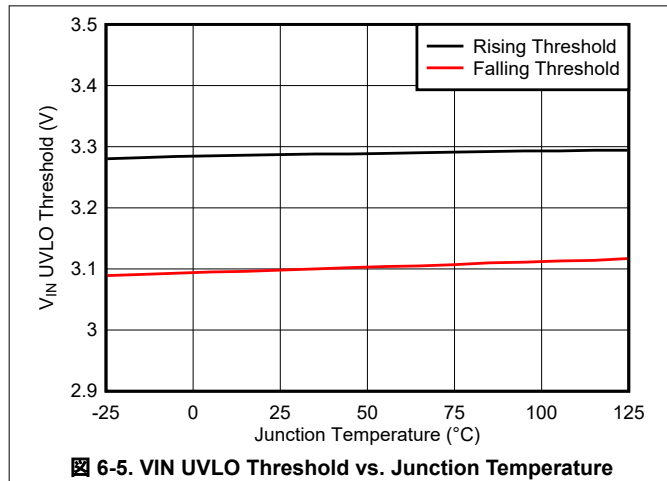
PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
T <sub>TSD</sub>	Thermal shutdown temperature			165		°C
	Hysteresis			15		°C

## 6.6 Typical Characteristics

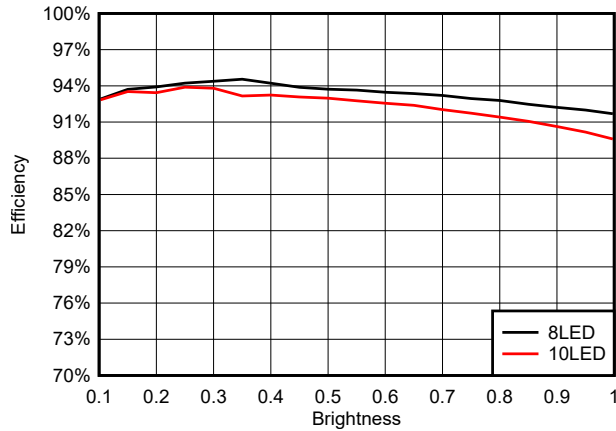
$V_{IN} = 12\text{ V}$ ,  $L = 22\ \mu\text{H}$ ,  $F_{SW} = 400\text{ kHz}$ , unless otherwise specified




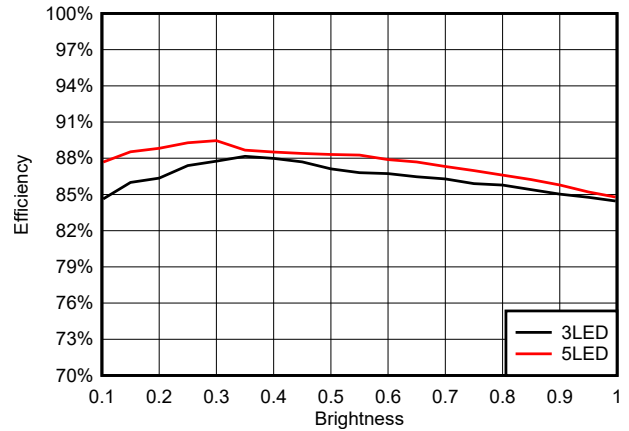
## 6.6 Typical Characteristics (continued)




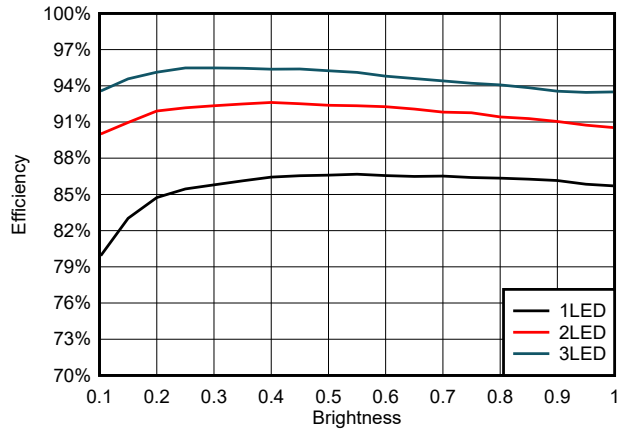
## 6.6 Typical Characteristics (continued)




**6-11. Efficiency at 1-A Max Output Current with Analogy Dimming, 22uH Inductor, Boost Topology**




**6-12. Efficiency at 1-A Max Output Current with Analogy Dimming, 22uH Inductor, Buck-Boost Topology**




**6-13. Efficiency at 3-A Max Output Current with Analogy Dimming, 22uH Inductor, Buck Topology**

## 7 Detailed Description

### 7.1 Overview

The LP8868-Q1 family is a 4-A non-synchronous Buck / Boost / Buck-Boost LED driver with 4.5-V to 65-V wide input range. By integrating the low-side NMOS switch with constant current and constant voltage controls, the device is capable of not only driving LEDs but also charging batteries with high power density and high efficiency.

The switching frequency is configurable through FSET pin, ranging from 100 kHz to 2.2 MHz, with optional spread spectrum feature to decrease the EMC emission and reduce the input filter size. The device supports four dimming options, including analog dimming, PWM dimming, hybrid dimming and flexible dimming. Each dimming method can be configured through the PWM and ADIM input pins by means of simple high/low sequencing signals at startup.

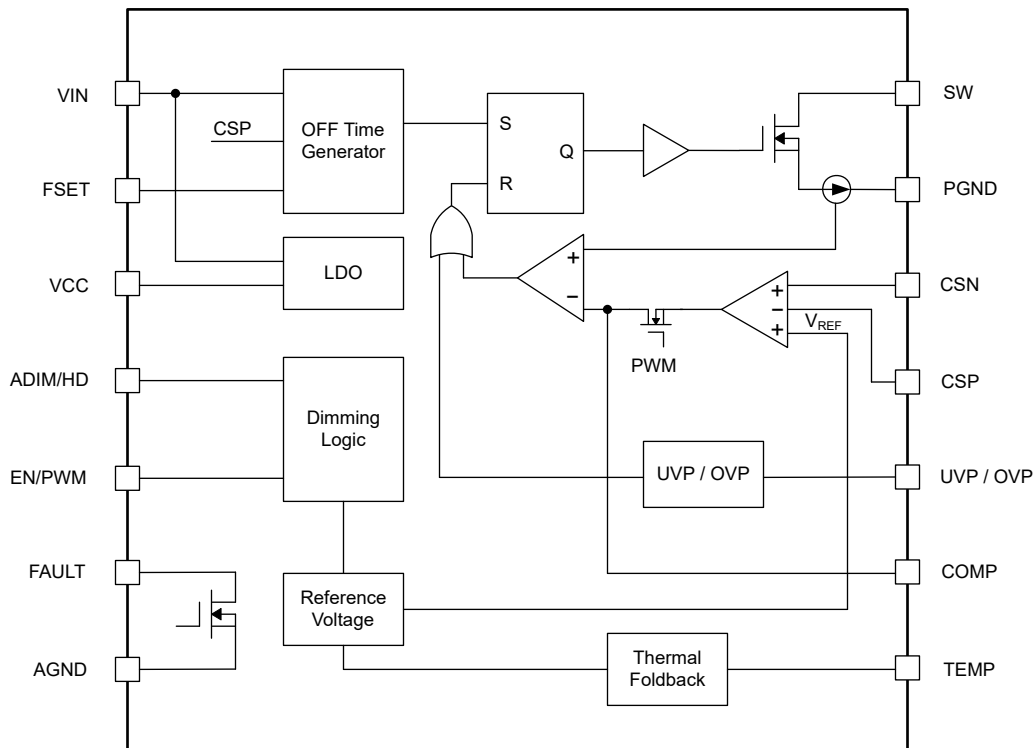
The device adopts an adaptive off-time current mode control along with smart and accurate sampling to enable inductive fast dimming (IFD) and achieve high dimming ratio. The compensation bandwidth can be adjusted through an external capacitor on COMP pin based on system requirement.

The LP8868-Q1 family has extensive fault detection feature:

- LED open and short detection
- Sense resistor open and short detection
- Configurable thermal foldback and thermal shutdown protection

Fault condition is indicated through the FAULT output pin.

### 7.2 Functional Block Diagram



## 7.3 Feature Description

### 7.3.1 Adaptive Off-Time Current Mode Control

The LP8868-Q1 family adopts an adaptive off-time current mode control to support fast transient response over a wide range of operation. The switching frequency is configurable through FSET pin, ranging from 100 kHz to 2.2 MHz.

For average output current regulation, the sensed voltage across the sensing resistor between the CSP and CSN pins is compared with the internal voltage reference,  $V_{REF}$ , through the error amplifier. The output of the error amplifier,  $V_{COMP}$ , passes through an external compensation network and is then compared with the peak current feedback at the PWM comparator

During each switching cycle, when the internal N-MOSFET is turned on, the peak current is sensed through the internal FET. When the sensed value of peak current reaches  $V_{COMP}$  at the input of PWM comparator, the N-MOSFET is turned off and the adaptive off-time counter starts counting. Once the adaptive off-time counter stops counting, the counter keeps reset until when the N-MOSFET turns off. The counting off time is determined by the external resistor connected to the FSET pin and the input/output feedforward. Thus, the device is able to maintain a nearly constant switching frequency at steady state and regulate the output average current at a desired value.

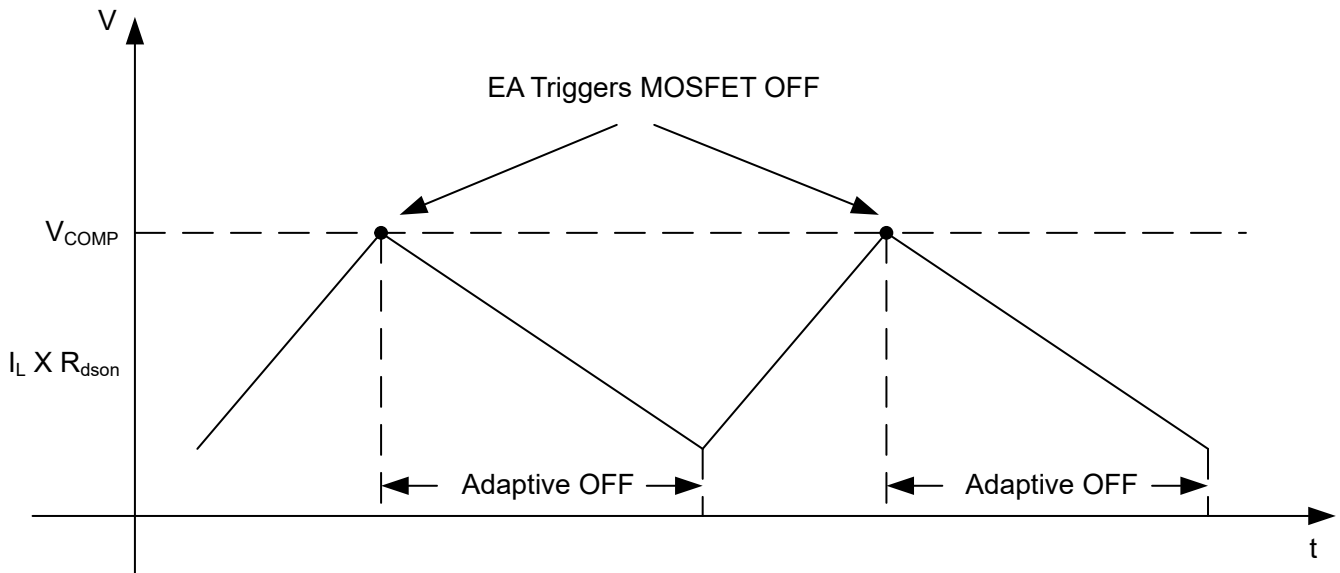


図 7-1. Adaptive off-time current mode control method

### 7.3.1.1 Switching Frequency Settings

The switching frequency of LP8868 family is adjustable from 100 kHz to 2.2 MHz by means of changing  $R_{FSET}$  connected between FSET pin and AGND. The default switching frequency is 100 kHz when the FSET pin is connected to nothing.

The resistor value and the corresponding switching frequency are listed in the below table:

**表 7-1. Switching Frequency vs.  $R_{FSET}$  resistor value**

Switching Frequency	Resistor Value (k $\Omega$ )
100 kHz	232
200 kHz	138
300 kHz	83
400 kHz	59
600 kHz	38
800 kHz	28
1 MHz	23
1.2 MHz	18
1.5 MHz	13
1.8 MHz	11
2.2 MHz	9

For example, if  $R_{FSET}$  is set to 59 k $\Omega$ , the corresponding switching frequency is 400 kHz.

In most cases, lower switching frequency has higher system efficiency and better thermal performance.

### 7.3.1.2 Spread Spectrum

The LP8868X/Y/Z-Q1 enables the spread spectrum feature ( $\pm 7\%$  from central frequency, 2-kHz modulation frequency) which reduces EMI noise at the switching frequency and its harmonic frequencies.

On the other hand, the LP8868U/V/W-Q1 disables the spread spectrum feature toward better brightness performance in low brightness scenario.

### 7.3.2 Setting LED Current

The output current of the LED is controlled with external resistor  $R_{sense}$  between CSP and CSN pins.  $R_{sense}$  value for the target current can be calculated using equation 式 1. Noted that, to relised IFD function and improve the accuracy of the output current in low duty cycle, the capacitor in parallel with sense resistor is required for boost and buck-boost topology. And it is optional for buck topology.

$$R_{SENSE} = \frac{V_{REF}}{I_{LED\_FS}} \quad (1)$$

where

- $V_{REF} = 200$  mV
- $R_{SENSE}$  is current setting resistor, m $\Omega$
- $I_{LED}$  is output current, mA

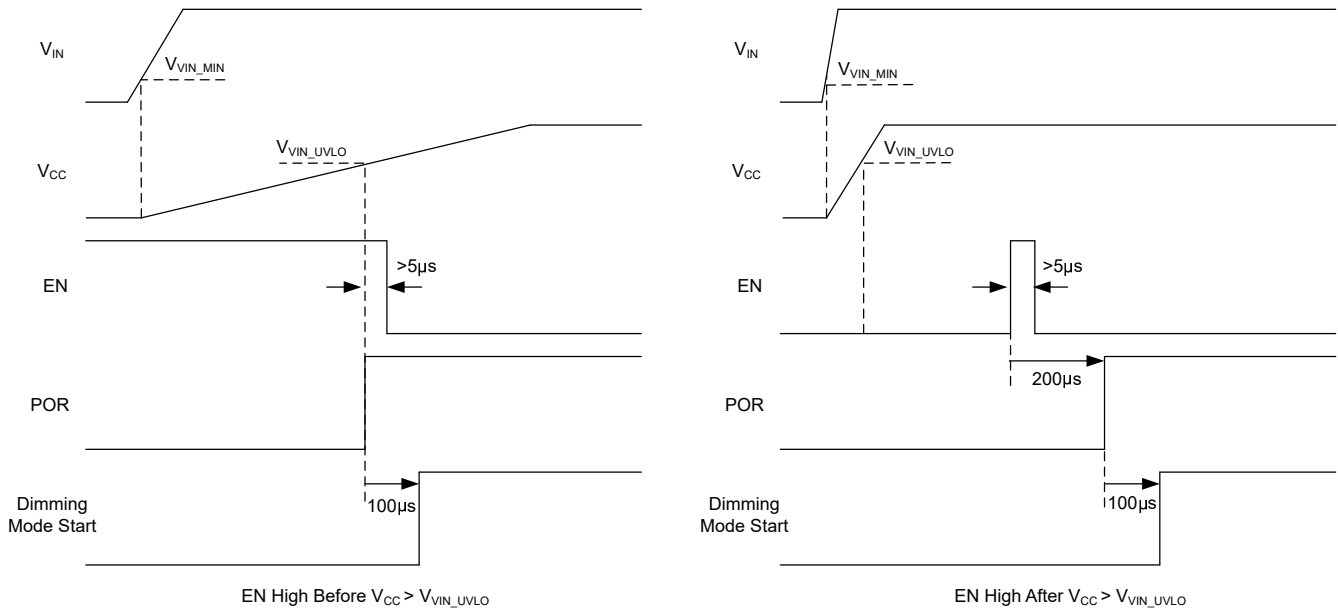
For example, if  $R_{sense}$  is set to 100 m $\Omega$ .  $I_{LED}$  will be 2 A.



### 7.3.3 Internal Soft Start

The LP8868-Q1 family implements the internal soft-start function. Once  $V_{IN}$  rises above  $V_{VIN\_MIN}$ , the internal LDO starts to charge  $V_{CC}$  capacitor. It takes approximately 800  $\mu\text{s}$  for  $V_{CC}$  to rise above  $V_{VIN\_UVLO}$  if a 1- $\mu\text{F}$  capacitor is connected to  $V_{CC}$  pin. If EN/PWM pin is pulled high before  $V_{CC}$  rises above  $V_{VIN\_UVLO}$ , the POR is enabled right after  $V_{CC}$  above  $V_{VIN\_UVLO}$  and waits for 100  $\mu\text{s}$  to start dimming mode. EN/PWM pin has to stay high for more than 5  $\mu\text{s}$  after  $V_{CC}$  rises above  $V_{VIN\_UVLO}$ . In this case, if using 1- $\mu\text{F}$   $V_{CC}$  capacitor, it is recommended to wait for 1 ms to start dimming mode after  $V_{IN}$  rises above  $V_{VIN\_MIN}$ .

If EN/PWM pin has the first PWM pulse appearing after  $V_{CC}$  rises above  $V_{VIN\_UVLO}$ , the device waits for 200  $\mu\text{s}$  to enable POR and another 100  $\mu\text{s}$  to start dimming mode. Hence, without triggering  $V_{IN}$  UVLO, the device can be renabled after disabled and waits for 300  $\mu\text{s}$  to start dimming mode. Note that the initial enable PWM pulse lasting more than 5  $\mu\text{s}$  is required at EN/PWM input pin to enable the device. After dimming mode is started, the device enters four different dimming modes based on the configuration of ADIM/HD pin and EN/PWM pin.



**图 7-2. Startup Sequence**

### 7.3.4 Dimming Mode

The LP8868 family has four optional dimming modes determined by the waveform in PWM and ADIM pins. The dimming mode is started either 1 ms after VIN exits UVLO or 300 μs after renable by EN/PWM pin. The configuration to one of the four dimming modes are shown as below.

**表 7-2. Dimming Mode Configuration**

Dimming Mode	EN/PWM Pin	ADIM/HD Pin
PWM Dimming	PWM signal	High
Analog Dimming	High	PWM signal
Hybrid Dimming	PWM signal	Low
Flexible Dimming	PWM signal	PWM signal

#### 7.3.4.1 PWM dimming

The PWM dimming mode is enabled when the ADIM/HD input pin is always high and the PWM/EN input pin is configured by a PWM input signal. Device supports PWM input signals with ultra-narrow pulse width down to 200 ns in PWM dimming mode. The PWM output duty cycle can be changed in the opposite direction only when PWM input duty cycle changes by more than 0.38%.

In PWM dimming mode, when the PWM input signal at the PWM pin turns from low to high, the internal NMOS FET starts switching and the inductor current rises to the determined value. The LED current is then regulated at the determined value as long as the PWM input signal stays high. When the PWM input signal turns from high to low, the internal FET is turned off causing the inductor current falling to zero. The internal FET maintains off and the LED current stays zero if the PWM input signal stays low.

#### 7.3.4.2 Analog dimming

The LP8868 family supports analog dimming which regulates the LED current through the ADIM/HD pin. The analog dimming mode is enabled when the PWM/EN pin is always high and the ADIM/HD pin is configured by a PWM input signal. And the internal digital circuits is able to respond to the duty cycle change of the PWM input signal with tens of micro-seconds delay

The internal voltage reference,  $V_{REF}$ , changes in proportion to the duty cycle of the PWM input signal at the ADIM/HD pin.  $V_{REF}$  is 200 mV when the PWM input signal at the ADIM/HD pin has a 100% duty cycle, for instance, and  $V_{REF}$  is 20 mV when the PWM input signal has a 10% duty cycle.

### 7.3.4.3 Hybrid Dimming

The LP8868 family supports a unique hybrid dimming function to maximize the dimming performance, especially when both high dimming frequency and high dimming ratio are needed. The hybrid dimming mode is enabled when the ADIM/HD pin is always low and the PWM/EN pin is configured by a PWM input signal.

When the hybrid dimming is enabled, the LED current is regulated by the analog dimming at high brightness level (12.5% - 100%) and by the PWM dimming at low brightness level (0% - 12.5%), respectively. At high brightness level, the internal voltage reference,  $V_{REF}$ , changes in proportion to the duty cycle of the PWM input signal at the PWM/EN pin. At low brightness level,  $V_{REF}$  stays unchanged and an internal PWM generator is enabled. Thus, the LED is turned on and off corresponding to the on and off of the internal PWM signal of which the frequency and the duty cycle are configured by the PWM input signal at the PWM/EN pin. The detailed hybrid dimming behavior is illustrated in the below figure.

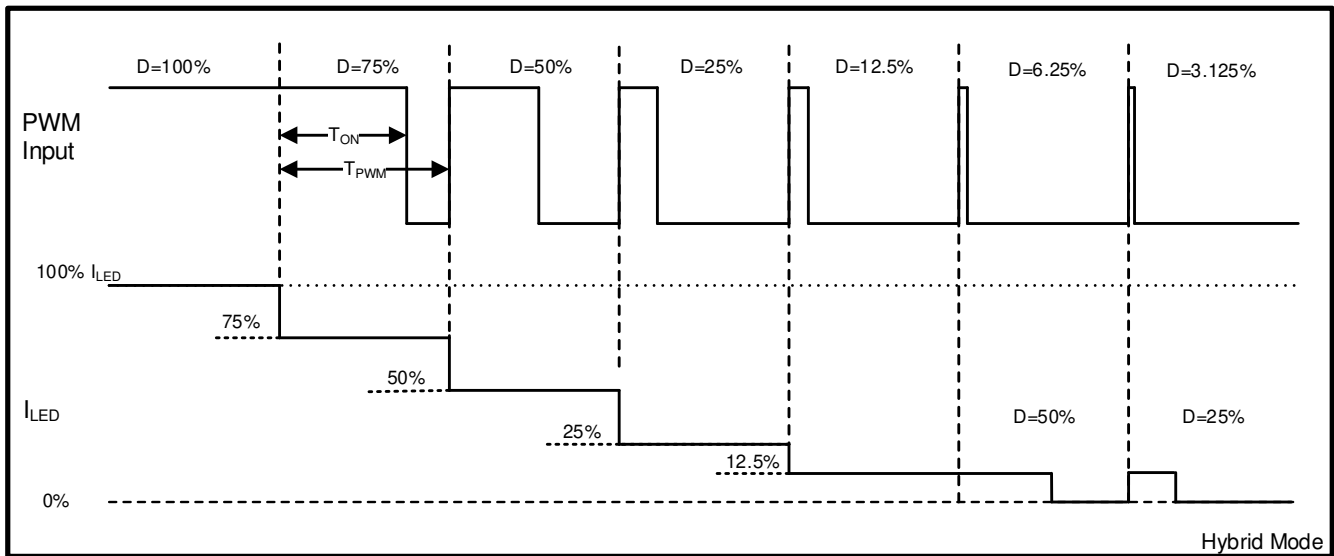


図 7-3. Hybrid Dimming

### 7.3.4.4 Flexible Dimming

The LP8868 family also supports flexible dimming to maximize the flexibility of dimming control, in which the LED current value and the on/off behavior can be controlled independently. The flexible dimming mode is enabled when both the ADIM/HD pin and the PWM/EN pin are configured by PWM input signals at the same time. Therefore, in flexible dimming mode, the LED is turned on and off corresponding to the on and off of the PWM input signal at the PWM/EN pin while the reference voltage changes in proportion to the duty cycle of the PWM input signal at the ADIM/HD pin.

### 7.3.5 Undervoltage Lockout

The LP8868 family implements an internal undervoltage-lockout (UVLO) circuitry connecting to the VCC pin. The UVLO is triggered and then device is disabled when the VCC pin voltage falls below the internal UVLO threshold voltage,  $V_{VCC\_UVLO}$  typically 3.0 V, with a typical 0.2-V hysteresis. The VCC pin is the output of an internal regulator of which the input is supplied by the VIN pin. Therefore, if VIN pin voltage falls close to above the  $V_{VCC\_UVLO}$  (around 500 mV above), the UVLO will be triggered.

### 7.3.6 Fault Protection

The LP8868 family is able to provide fault protections and send fault report signals in many fault conditions, including LED open, LED short to GND, sense resistor open and short, internal switching FET fault and thermal shutdown. The fault criterion for different topology is shown in below.

**表 7-3. Protections in Buck topology**

TYPE	CRITERION	BEHAVIOR
LED open load	$V_{UVLP} < 1.2 \text{ V}$ for 100us	Fault pin pulls low. The device stops switching when $V_{UVLP} < 1.2 \text{ V}$ .
LED+ and LED- short circuit	$V_{IN} - V_{CSP} < 300 \text{ mV}$ for 30ms	Fault pin pulls low. The keeps normal behavior.
LED- short to GND	$V_{UVLP} < 1.2 \text{ V}$ for 100us	Fault pin pulls low. The device stops switching and recovers when fault is removed.
Sense-resistor open load	$V_{CSP} - V_{CSN} > 300\text{mV}$ for 20us	Fault pin pulls low. The device stops switching and recovers when fault is removed.
Sense-resistor short circuit	Error Amplifier output high for 100us	Fault pin pulls low. The device keeps switching under the cycle-by-cycle current limit.
Switching FET open	Error Amplifier output high for 100us	Fault pin pulls low. The device keeps maximum duty cycle turn-on switching.
Switching FET short	$V_{CSP} - V_{CSN} > 300 \text{ mV}$ for 20us	Fault pin pulls low. The device stops switching and recovers when fault is removed.
Thermal shutdown	$T_J > T_{TSD}$ for 100us	Fault pin pulls low. The device stops switching when $T_J > T_{TSD}$ , and is re-activated when $T_J$ falls below the hysteresis level.
VIN UVLO	$V_{CC} < 3 \text{ V}$	Fault pin pulls low. The device stops switching and recovers when fault is removed.

**表 7-4. Protections in Boost / Buck-Boost topology**

TYPE	CRITERION	BEHAVIOR
LED open load	$V_{OVP} > 1.2 \text{ V}$ for 100us	Fault pin pulls low. The device stops switching when $V_{OVP} > 1.2 \text{ V}$ .
LED+ and LED- short circuit (Buck-Boost)	$V_{CSP} - V_{IN} < 300\text{mV}$ for 30ms	Fault pin pulls low. The device keeps normal behavior.
LED+ short to GND	$CSP - V_{CSN} > 300\text{mV}$ for 20us	Fault pin pulls low. The device stops switching and recovers when fault is removed.
Sense-resistor open load	$V_{CSP} - V_{CSN} > 300\text{mV}$ for 20us	Fault pin pulls low. The device stops switching and recovers when fault is removed.
Sense-resistor short circuit	Error Amplifier output high for 100us	Fault pin pulls low. The device keeps switching under the cycle-by-cycle current limit.
Switching FET open	Error Amplifier output high for 100us	Fault pin pulls low. The device keeps maximum duty cycle turn-on switching.
Switching FET short	Error Amplifier output high for 100us	Fault pin pulls low. The device tries to keep switching.
Thermal shutdown	$T_J > T_{TSD}$ for 100us	Fault pin pulls low. The device stops switching when $T_J > T_{TSD}$ , and is re-activated when $T_J$ falls below the hysteresis level.
VIN UVLO	$V_{CC} < 3 \text{ V}$	Fault pin pulls low. The device stops switching and recovers when fault is removed.

### 7.3.7 Thermal Foldback

The LP8868 family integrates thermal shutdown protection to prevent the device from overheating. In order to provide design margin of system thermal performance, the device enables a programmable thermal foldback function which automatically reduces the full-scale output current,  $I_{FS}$ , at high junction temperature. When the device along with the LEDs are mounted on the same thermal substrate, the thermal performance is effectively improved due to the reduction of dissipation need for both and LED.

As the junction temperature rises above the thermal foldback threshold temperature,  $T_{th}$ , the full-scale current starts to reduce following the current-temperature curve shown in the below figure. The current starts to reduce from the 100% level at typically rate of 2% of  $I_{FS}$  per  $^{\circ}C$  until it drops to 50% of the full scale. Once the junction temperature rises  $25^{\circ}C$  above the  $T_{th}$ , the current continues to decrease at a lower rate until the temperature reaches above the overtemperature shutdown threshold temperature,  $T_{TSD}$ .

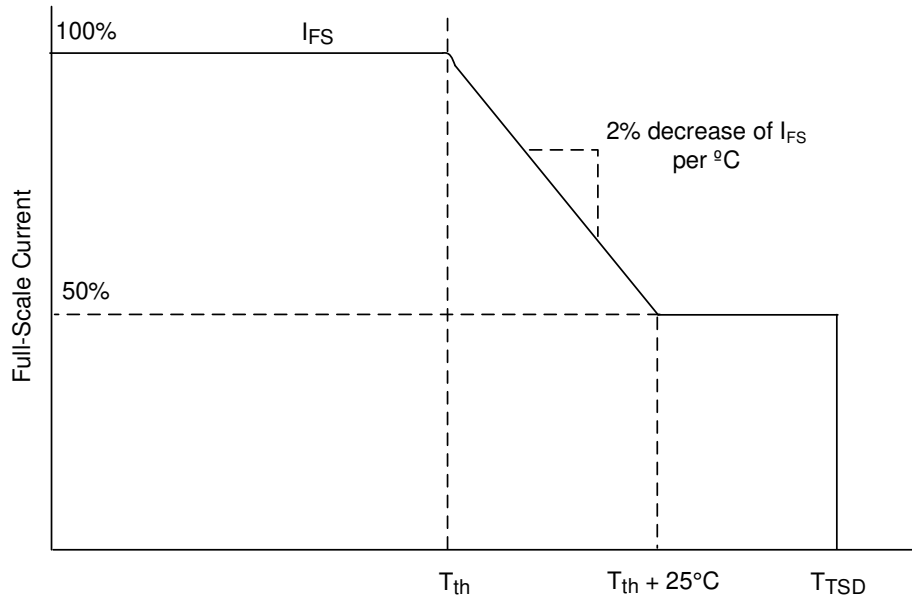


図 7-4. Thermal Foldback

The  $T_{th}$  can be adjusted by changing the resistor  $R_{TEMP}$  connected between the TEMP and GND pin. The  $T_{th}$  and the corresponding  $R_{TEMP}$  value are listed in below table.

表 7-5.  $T_{th}$  vs.  $R_{TEMP}$  resistor value

$T_{th}$ ( $^{\circ}C$ )	Resistor Value (k $\Omega$ )
80	200
90	100
100	60
110	40
120	28
130	20
140	15
150	10

## 8 Application and Implementation


### 8.1 Application Information

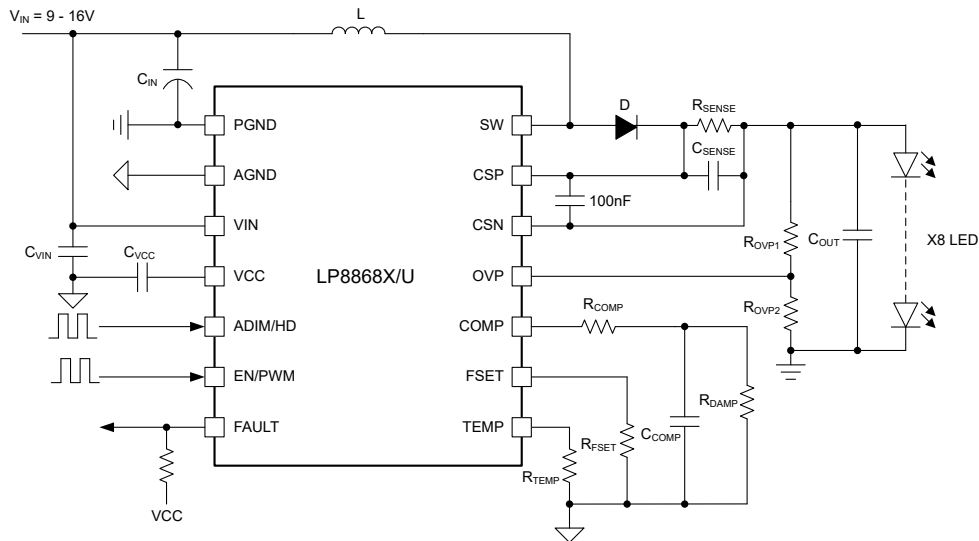
LP8868 family can support buck / boost / buck-boost topology with different part number.

The LP8868X is typically used as a boost converter, the LP8868Y is typically used as a buck-boost converter and the LP8868Z is typically used as a buck converter.

### 8.2 Typical Application

#### 8.2.1 LP8868XQDMTRQ1 12-V Input, 1-A Output, 8-piece LED With Boost Topology

 8-1 shows a typical application for the LP8868X in a boost topology. The switching current limit is 5.8 A and it will limit the output current.



 8-1. Typical Application for Boost Topology with LP8868X

#### 8.2.1.1 Design Requirements

For this design example, use the parameters in the following table.

**表 8-1. Design Parameters**

PARAMETER	VALUE
Input voltage range	9 V -16 V
LED string	8 LED
Output voltage	24 V
Switching frequency	400 kHz
Maximum LED current	1 A
Inductor current ripple	40% of maximum inductor current
Dimming type	PWM dimming/ADIM dimming

## 8.2.1.2 Detailed Design Procedure

### 8.2.1.2.1 Inductor Selection

For this design, the input voltage is 9 V to 16 V. The output is 8 white LEDs in series and the inductor current ripple by requirement is less than 40% of maximum LED current. To choose a proper peak-to-peak inductor current ripple, the low-side FET current limit should not be violated when the converter works in no-load condition. This requires half of the peak-to-peak inductor current ripple to be lower than that limit. Another consideration is to ensure reasonable inductor core loss and copper loss caused by the peak-to-peak current ripple. Once this peak-to-peak inductor current ripple is chosen, use 式 2 to calculate the recommended value of the inductor L.

$$L = \frac{V_{IN(max)} \times (V_{OUT} - V_{IN(max)})}{V_{OUT} \times K_{IND} \times I_{L(max)} \times f_{SW}} \quad (2)$$

where

- $K_{IND}$  is a coefficient that represents the amount of inductor ripple current relative to the maximum LED current.
- $I_{L(max)}$  is the maximum inductor current.
- $f_{SW}$  is the switching frequency.
- $V_{IN(max)}$  is the maximum input voltage.
- $V_{OUT}$  is the sum of the voltage across LED load and the voltage across sense resistor.

With the chosen inductor value, the user can calculate the actual inductor current ripple using 式 3.

$$I_{L(ripple)} = \frac{V_{IN(max)} \times (V_{OUT} - V_{IN(max)})}{V_{OUT} \times L \times f_{SW}} \quad (3)$$

The design ratings of inductor RMS current and saturation current must be greater than those seen in the system requirement. This is to ensure no inductor overheat or saturation occurring. During power up, transient conditions or fault conditions, the inductor current may exceed its normal operating current and reach the current limit. Therefore, it is preferred to select a saturation current rating equal to or greater than the converter current limit. The peak-inductor-current and RMS current equations are shown in 式 4 and 式 5.

$$I_{L(peak)} = I_{L(max)} + \frac{I_{L(ripple)}}{2} \quad (4)$$

$$I_{L(rms)} = \sqrt{I_{L(max)}^2 + \frac{I_{L(ripple)}^2}{2}} \quad (5)$$

In this design,  $V_{IN(max)} = 16V$ ,  $V_{OUT} = 24 V$ ,  $I_{LED} = 1 A$ , considering the efficiency as 0.9,  $I_{L(max)} = 2.96 A$ ,  $f_{SW} = 400 \text{ kHz}$ , choose  $K_{IND} = 0.4$ , the calculated inductance is  $11.25 \mu\text{H}$ . A  $10\text{-}\mu\text{H}$  inductor is chosen. With this inductor, the ripple, peak, and rms currents of the inductor are  $1.212 A$ ,  $3.569 A$ ,  $3.084 A$ , respectively.

### 8.2.1.2.2 Input Capacitor Selection

An input capacitor is required to reduce the surge current drawn from the input supply and the switching noise coming from the device. Electrolytic capacitors are recommended for energy storage. Ceramic capacitors with X5R or X7R dielectrics are highly recommended because of their low ESR and small temperature coefficients. For most applications, it is recommended to place a  $10\text{-}\mu\text{F}$  ceramic capacitor along with a  $0.1\text{-}\mu\text{F}$  capacitor from VIN to PGND/AGND to provide high-frequency filtering. The input capacitor voltage rating must be greater than the maximum input voltage. Use 式 6 to calculate the input ripple voltage, where  $ESR_{CIN}$  is the ESR of input capacitor, and  $K_{DR}$  is the derating coefficient of ceramic capacitance at the applied DC voltage.

$$V_{IN(ripple)} = \frac{I_{L(ripple)}}{8 \times C_{IN} \times f_{SW}} \quad (6)$$

In this design, a 33-μF, 100V electrolytic capacitor, a 1-μF, 100V X7R ceramic capacitor and a 0.1-μF, 100V X7R ceramic capacitor are chosen, yielding around 100-mV input ripple voltage.

### 8.2.1.2.3 Output Capacitor Selection

The output capacitor reduces the high-frequency current ripple through the LED string. Excessive current ripple increases the RMS current in the LED string, therefore increasing the LED temperature.

1. Calculate the total dynamic resistance of the LED string ( $R_{LED}$ ) using the LED manufacturer's datasheet.
2. Calculate the required impedance of the output capacitor ( $Z_{OUT}$ ) given the acceptable peak-to-peak ripple current through the LED string,  $I_{LED(ripple)}$ .  $I_{L(ripple)}$  is the peak-to-peak inductor ripple current as calculated with the selected inductor.
3. Calculate the minimum effective output capacitance required.
4. Increase the output capacitance appropriately due to the derating effect of applied DC voltage.

See 式 7, 式 8, and 式 9.

$$R_{LED} = \frac{\Delta V_F}{\Delta I_F} \times \# \text{ of LEDs} \quad (7)$$

$$Z_{COUT} = \frac{R_{LED} \times I_{LED(ripple)}}{I_{L(max)} - I_{LED(ripple)}} \quad (8)$$

$$C_{COUT} = \frac{1}{2\pi \times f_{SW} \times Z_{COUT}} \quad (9)$$

Once the output capacitor is chosen, 式 10 can be used to estimate the peak-to-peak ripple current through the LED string.

$$I_{LED(ripple)} = \frac{Z_{COUT} \times I_{L(ripple)}}{Z_{COUT} + R_{LED}} \quad (10)$$

Ceramic capacitors with X5R or X7R dielectrics are highly recommended because of their low ESR and small temperature coefficients. In this design, a 10-μF, 50-V X7R ceramic capacitor is chosen.

### 8.2.1.2.4 Sense Resistor Selection

The maximum LED current is 1 A at 100% PWM duty and the corresponding  $V_{REF}$  is 200 mV. By using 式 11, the sense resistance is calculated as 200 mΩ. Note that the power consumption of the sense resistor is 200 mW, requiring enough margin of the resistor's power rating in selection.

$$R_{SENSE} = \frac{V_{REF}}{I_{LED\_FS}} \quad (11)$$

In boost topology,  $C_{SENSE}$  is required to achieve the IFD control. Using 式 12, a 10-μF, 50-V X7R ceramic capacitor is chosen for  $C_{SENSE}$  to suppress the ac magnitude of sense feedback less than 200 mV.

$$C_{SENSE} = \frac{0.25 \times I_{L(max)}}{200mV \times f_{SW}} \quad (12)$$

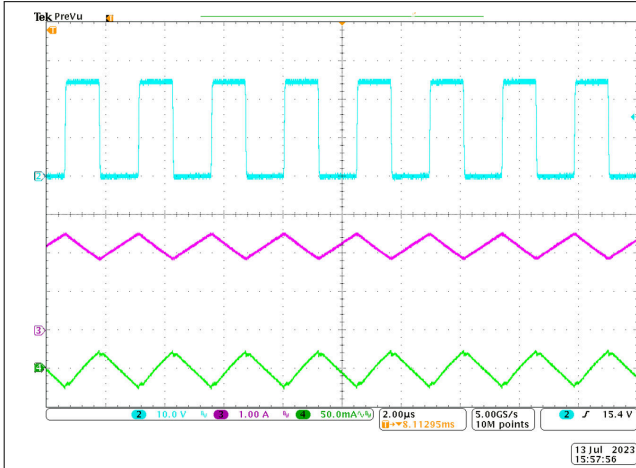
### 8.2.1.2.5 Other External Components Selection

In this design, a 0.1-μF, 50-V X7R ceramic capacitor is chosen for high-frequency filtering of sense feedback.

For loop stability, it is recommended to select a 1-nF, 10-V X7R ceramic capacitor for  $C_{COMP}$  and a 1-kΩ resistor for  $R_{COMP}$ . A 1-MΩ resistor is chosen for  $R_{DAMP}$  to suppress the overshoot current at rising edge of PWM on.

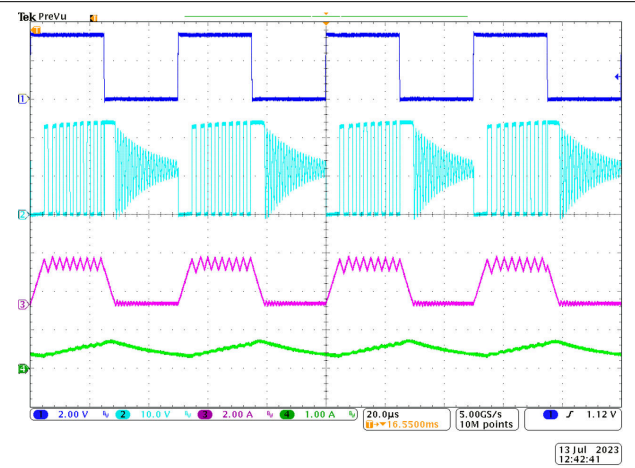


### 8.2.1.3 Application Curves



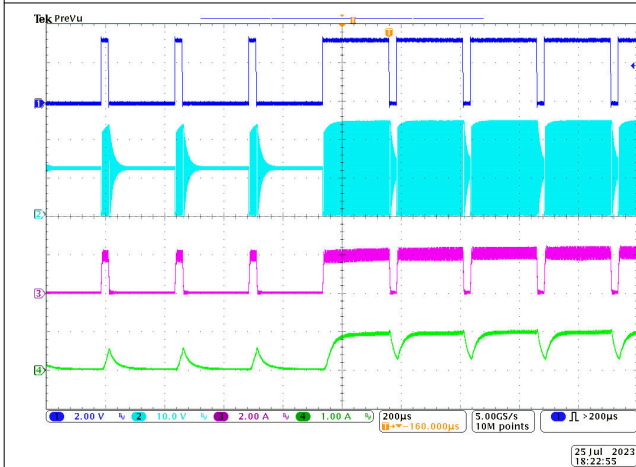
Ch 2: SW, Ch 3: Inductor Current, Ch 4: LED Current Ripple (AC)

**図 8-2. LED Current Ripple at ADIM = 100%, 1 kHz and  $F_{sw} = 400$  kHz**



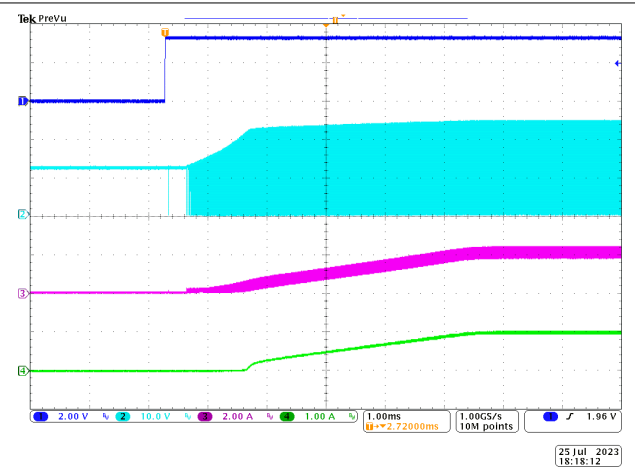
Ch 1: PWM/EN, Ch 2: SW, Ch 3: Inductor Current, Ch 4: LED Current

**図 8-3. LED Current Ripple at PWM = 50%, 20 kHz and  $F_{sw} = 400$  kHz**



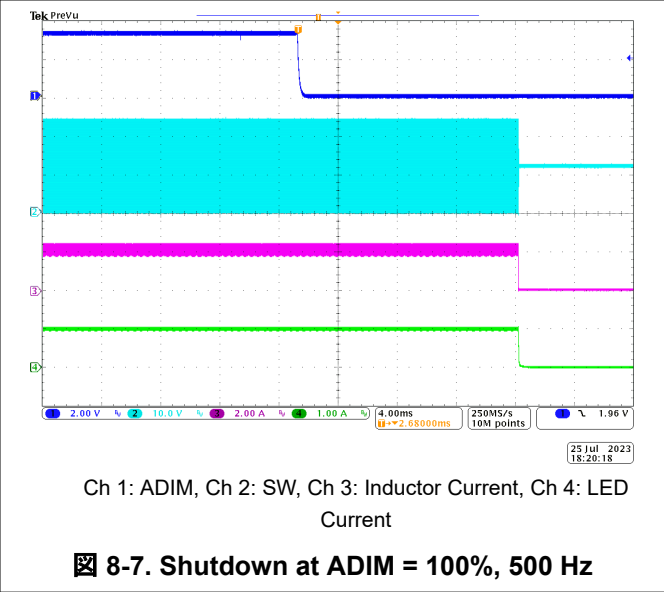
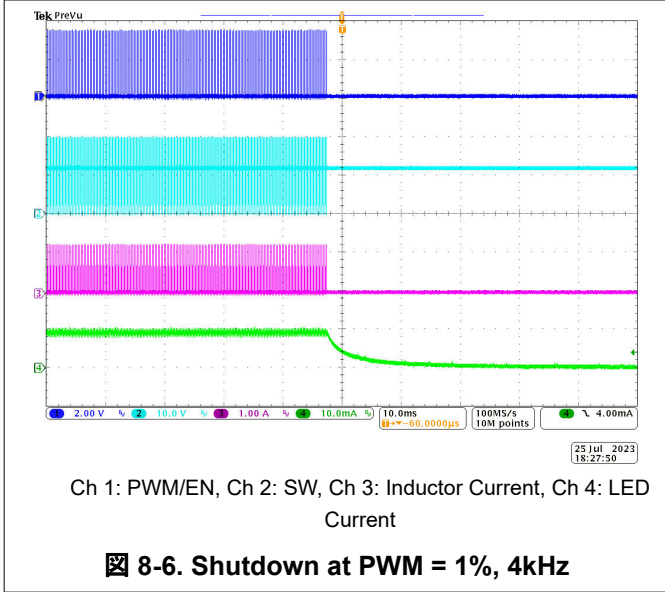
Ch 1: PWM/EN, Ch 2: SW, Ch 3: Inductor Current, Ch 4: LED Current

**図 8-4. LED Current Transient for a PWM Transition from 10% to 99%, 4 kHz**



Ch 1: ADIM, Ch 2: SW, Ch 3: Inductor Current, Ch 4: LED Current

**図 8-5. Startup at ADIM = 100%, 500Hz**



## 8.2.2 LP8868YQDMTRQ1 12-V Input, 1-A Output, 5-piece LED With Buck-Boost Topology

Figure 8-8 shows a typical application for the LP8868Y in a buck-boost topology. The switching current limit is 5.8 A and it will limit the output current.

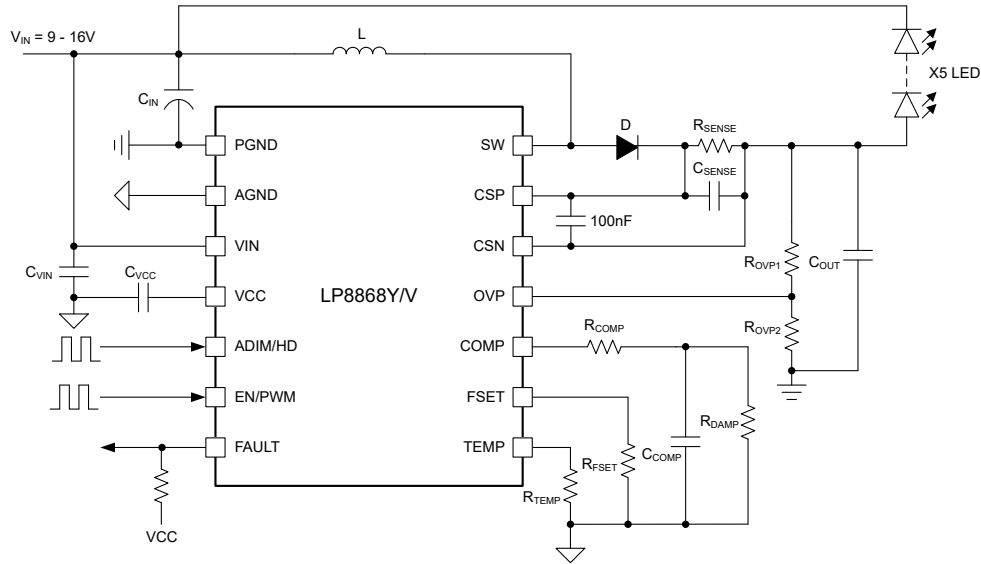


Figure 8-8. Typical Application for Buck-Boost Topology with LP8868Y

### 8.2.2.1 Design Requirements

For this design example, use the parameters in the following table.

Table 8-2. Design Parameters

PARAMETER	VALUE
Input voltage range	9 V -16 V
LED string	5 LED
Output voltage	15 V
Switching frequency	400 kHz
Maximum LED current	1 A
Inductor current ripple	40% of maximum inductor current
Dimming type	PWM dimming/ADIM dimming

## 8.2.2.2 Detailed Design Procedure

### 8.2.2.2.1 Inductor Selection

For this design, the input voltage is 9 V to 16 V. The output is 8 white LEDs in series and the inductor current ripple by requirement is less than 40% of maximum LED current. To choose a proper peak-to-peak inductor current ripple, the low-side FET current limit should not be violated when the converter works in no-load condition. This requires half of the peak-to-peak inductor current ripple to be lower than that limit. Another consideration is to ensure reasonable inductor core loss and copper loss caused by the peak-to-peak current ripple. Once this peak-to-peak inductor current ripple is chosen, use 式 13 to calculate the recommended value of the inductor L.

$$L = \frac{V_{IN(max)} \times V_{OUT}}{(V_{OUT} + V_{IN(max)}) \times K_{IND} \times I_{L(max)} \times f_{SW}} \quad (13)$$

where

- $K_{IND}$  is a coefficient that represents the amount of inductor ripple current relative to the maximum LED current.
- $I_{L(max)}$  is the maximum inductor current.
- $f_{SW}$  is the switching frequency.
- $V_{IN(max)}$  is the maximum input voltage.
- $V_{OUT}$  is the sum of the voltage across LED load and the voltage across sense resistor.

With the chosen inductor value, the user can calculate the actual inductor current ripple using 式 14.

$$I_{L(ripple)} = \frac{V_{IN(max)} \times V_{OUT}}{(V_{OUT} + V_{IN(max)}) \times L \times f_{SW}} \quad (14)$$

The design ratings of inductor RMS current and saturation current must be greater than those seen in the system requirement. This is to ensure no inductor overheat or saturation occurring. During power up, transient conditions or fault conditions, the inductor current may exceed its normal operating current and reach the current limit. Therefore, it is preferred to select a saturation current rating equal to or greater than the converter current limit. The peak-inductor-current and RMS current equations are shown in 式 15 and 式 16.

$$I_{L(peak)} = I_{L(max)} + \frac{I_{L(ripple)}}{2} \quad (15)$$

$$I_{L(rms)} = \sqrt{I_{L(max)}^2 + \frac{I_{L(ripple)}^2}{2}} \quad (16)$$

In this design,  $V_{IN(max)} = 16V$ ,  $V_{OUT} = 15 V$ ,  $I_{LED} = 1 A$ , considering the efficiency as 0.8,  $I_{L(max)} = 2.083 A$ ,  $f_{SW} = 400 \text{ kHz}$ , choose  $K_{IND} = 0.4$ , the calculated inductance is  $23.22 \mu\text{H}$ . A  $22\text{-}\mu\text{H}$  inductor is chosen. With this inductor, the ripple, peak, and rms currents of the inductor are 1.09 A, 2.629 A, 2.222 A, respectively.

### 8.2.2.2.2 Input Capacitor Selection

An input capacitor is required to reduce the surge current drawn from the input supply and the switching noise coming from the device. Electrolytic capacitors are recommended for energy storage. Ceramic capacitors with X5R or X7R dielectrics are highly recommended because of their low ESR and small temperature coefficients. For most applications, it is recommended to place a  $10\text{-}\mu\text{F}$  capacitor along with a  $0.1\text{-}\mu\text{F}$  capacitor from VIN to PGND/AGND to provide high-frequency filtering. The input capacitor voltage rating must be greater than the maximum input voltage. Use 式 17 to calculate the input ripple voltage, where  $ESR_{CIN}$  is the ESR of input capacitor, and  $K_{DR}$  is the derating coefficient of ceramic capacitance at the applied DC voltage.

$$V_{IN(ripple)} = I_{L(max)} \times \left( \frac{V_{OUT}}{K_{DR} \times C_{IN} \times f_{SW} \times (V_{IN(max)} + V_{OUT})} + ESR_{CIN} \right) \quad (17)$$

In this design, a 10- $\mu$ F, 100V electrolytic capacitor, a 2.2- $\mu$ F, 100V X7R ceramic capacitor and a 0.1- $\mu$ F, 100V X7R ceramic capacitor are chosen, yielding around 504-mV input ripple voltage.

### 8.2.2.2.3 Output Capacitor Selection

The output capacitor reduces the high-frequency current ripple through the LED string. Excessive current ripple increases the RMS current in the LED string, therefore increasing the LED temperature.

1. Calculate the total dynamic resistance of the LED string ( $R_{LED}$ ) using the LED manufacturer's datasheet.
2. Calculate the required impedance of the output capacitor ( $Z_{COUT}$ ) given the acceptable peak-to-peak ripple current through the LED string,  $I_{LED(ripple)}$ ,  $I_{L(ripple)}$  is the peak-to-peak inductor ripple current as calculated with the selected inductor.
3. Calculate the minimum effective output capacitance required.
4. Increase the output capacitance appropriately due to the derating effect of applied DC voltage.

See 式 18, 式 19, and 式 20.

$$R_{LED} = \frac{\Delta V_F}{\Delta I_F} \times \# \text{ of LEDs} \quad (18)$$

$$Z_{COUT} = \frac{R_{LED} \times I_{LED(ripple)}}{I_{L(max)} - I_{LED(ripple)}} \quad (19)$$

$$C_{COUT} = \frac{1}{2\pi \times f_{SW} \times Z_{COUT}} \quad (20)$$

Once the output capacitor is chosen, 式 21 can be used to estimate the peak-to-peak ripple current through the LED string.

$$I_{LED(ripple)} = \frac{Z_{COUT} \times I_{L(ripple)}}{Z_{COUT} + R_{LED}} \quad (21)$$

Ceramic capacitors with X5R or X7R dielectrics are highly recommended because of their low ESR and small temperature coefficients. In this design, a 10- $\mu$ F, 50-V X7R ceramic capacitor is chosen.

### 8.2.2.2.4 Sense Resistor Selection

The maximum LED current is 1 A at 100% PWM duty and the corresponding  $V_{REF}$  is 200 mV. By using 式 22, the sense resistance is calculated as 200 m $\Omega$ . Note that the power consumption of the sense resistor is 200 mW, requiring enough margin of the resistor's power rating in selection.

$$R_{SENSE} = \frac{V_{REF}}{I_{LED\_FS}} \quad (22)$$

In buck-boost topology,  $C_{SENSE}$  is required to achieve the IFD control. Using 式 23, a 10- $\mu$ F, 50-V X7R ceramic capacitor is chosen for  $C_{SENSE}$  to suppress the ac magnitude of sense feedback less than 200 mV.

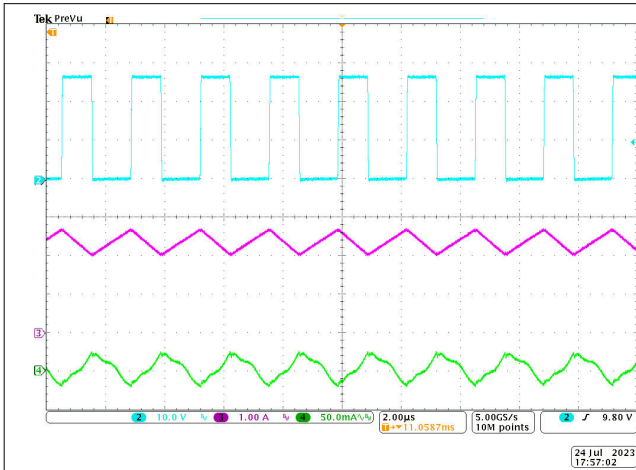
$$C_{SENSE} = \frac{0.25 \times I_{L(max)}}{200mV \times f_{SW}} \quad (23)$$

### 8.2.2.2.5 Other External Components Selection

In this design, a 0.1- $\mu$ F, 50-V X7R ceramic capacitor is chosen for high-frequency filtering of sense feedback.

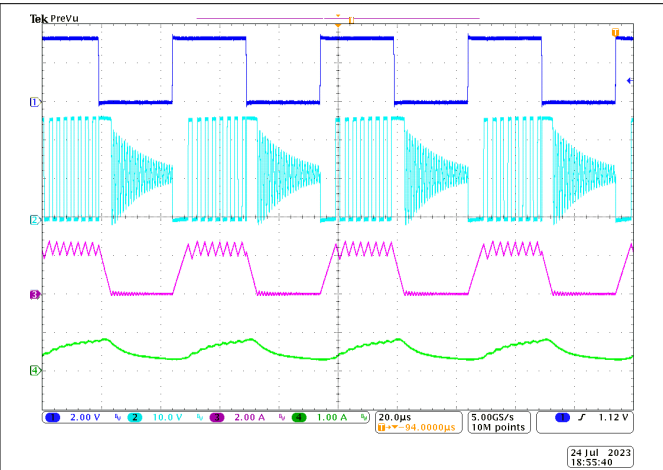
For loop stability, it is recommended to select a 1-nF, 10-V X7R ceramic capacitor for  $C_{COMP}$  and a 1-k $\Omega$  resistor for  $R_{COMP}$ . A 1-M $\Omega$  resistor is chosen for  $R_{DAMP}$  to suppress the overshoot current at rising edge of PWM on.

### 8.2.2.3 Application Curves



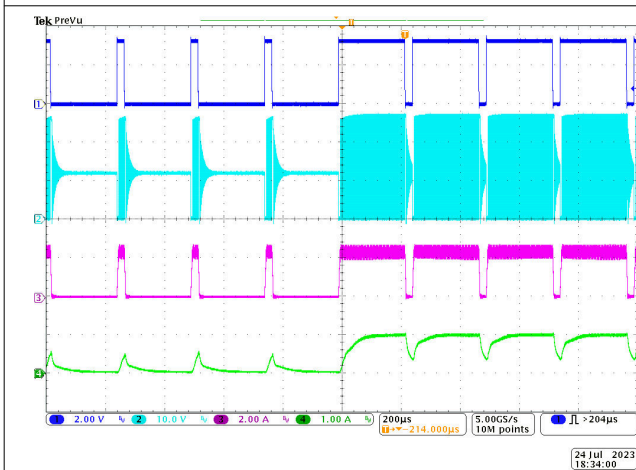
Ch 2: SW, Ch 3: Inductor Current, Ch 4: LED Current Ripple (AC)

**図 8-9. LED Current Ripple at ADIM = 100%, 1 kHz and  $F_{SW} = 400$  kHz**



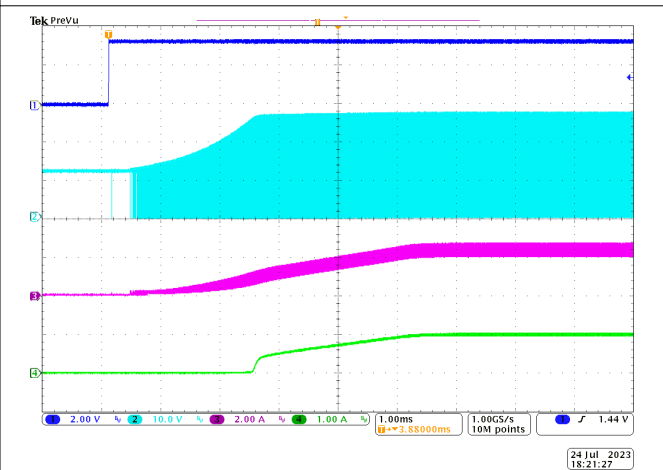
Ch 1: PWM/EN, Ch 2: SW, Ch 3: Inductor Current, Ch 4: LED Current

**図 8-10. LED Current Ripple at PWM = 50%, 20 kHz and  $F_{SW} = 400$  kHz**



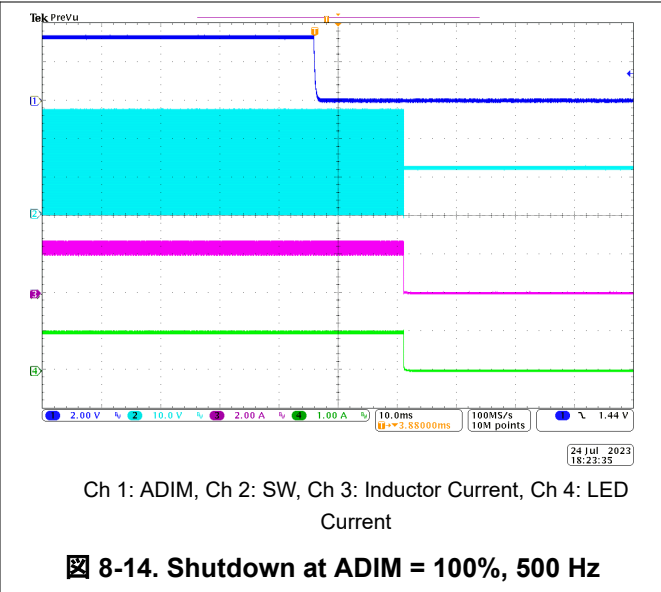
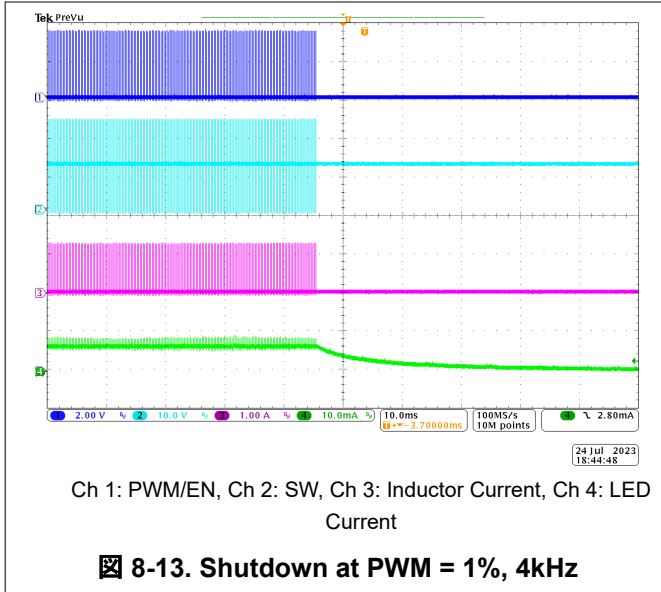
Ch 1: PWM/EN, Ch 2: SW, Ch 3: Inductor Current, Ch 4: LED Current

**図 8-11. LED Current Transient for a PWM Transition from 10% to 99%, 4 kHz**



Ch 1: ADIM, Ch 2: SW, Ch 3: Inductor Current, Ch 4: LED Current

**図 8-12. Startup at ADIM = 100%, 500Hz**



### 8.2.3 LP8868ZQDMTRQ1 12-V Input, 2-A Output, 1-piece LED With Buck Topology

Figure 8-15 shows a typical application for the LP8868Z in a buck topology. The switching current limit is 5.2 A and the output current limit is equal to the limit of switching current limit.

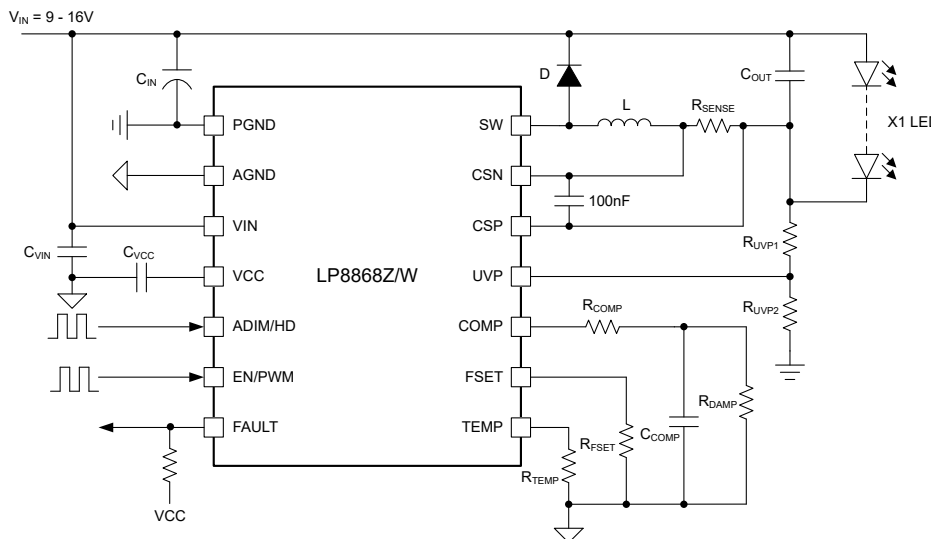


Figure 8-15. Typical Application for Buck Topology with LP8868Z

#### 8.2.3.1 Design Requirements

For this design example, use the parameters in the following table.

Table 8-3. Design Parameters

PARAMETER	VALUE
Input voltage range	9 V -16 V
LED string	1 LED
Output voltage	3 V
Switching frequency	400 kHz
Maximum LED current	2 A
Inductor current ripple	40% of maximum inductor current
Dimming type	PWM dimming/ADIM dimming



### 8.2.3.2 Detailed Design Procedure

#### 8.2.3.2.1 Inductor Selection

For this design, the input voltage is 9V to 16V. The output is single white LED and the inductor current ripple by requirement is less than 40% of maximum LED current. To choose a proper peak-to-peak inductor current ripple, the low-side FET current limit should not be violated when the converter works in no-load condition. This requires half of the peak-to-peak inductor current ripple to be lower than that limit. Another consideration is to ensure reasonable inductor core loss and copper loss caused by the peak-to-peak current ripple. Once this peak-to-peak inductor current ripple is chosen, use 式 24 to calculate the recommended value of the inductor L.

$$L = \frac{V_{OUT} \times (V_{IN(max)} - V_{OUT})}{V_{IN(max)} \times K_{IND} \times I_{L(max)} \times f_{SW}} \quad (24)$$

where

- $K_{IND}$  is a coefficient that represents the amount of inductor ripple current relative to the maximum LED current.
- $I_{L(max)}$  is the maximum LED current.
- $f_{SW}$  is the switching frequency.
- $V_{IN(max)}$  is the maximum input voltage.
- $V_{OUT}$  is the sum of the voltage across LED load and the voltage across sense resistor.

With the chosen inductor value, the user can calculate the actual inductor current ripple using 式 25.

$$I_{L(ripple)} = \frac{V_{OUT} \times (V_{IN(max)} - V_{OUT})}{V_{IN(max)} \times L \times f_{SW}} \quad (25)$$

The design ratings of inductor RMS current and saturation current must be greater than those seen in the system requirement. This is to ensure no inductor overheat or saturation occurring. During power up, transient conditions or fault conditions, the inductor current may exceed its normal operating current and reach the current limit. Therefore, it is preferred to select a saturation current rating equal to or greater than the converter current limit. The peak-inductor-current and RMS current equations are shown in 式 26 and 式 27.

$$I_{L(peak)} = I_{L(max)} + \frac{I_{L(ripple)}}{2} \quad (26)$$

$$I_{L(rms)} = \sqrt{I_{L(max)}^2 + \frac{I_{L(ripple)}^2}{2}} \quad (27)$$

In this design,  $V_{IN(max)} = 16V$ ,  $V_{OUT} = 3V$ ,  $I_{LED} = 2A$ , considering the efficiency as 0.9,  $I_{L(max)} = 0.741A$ ,  $f_{SW} = 400kHz$ , choose  $K_{IND} = 0.4$ , the calculated inductance is 20.57  $\mu H$ . A 22- $\mu H$  inductor is chosen. With this inductor, the ripple, peak, and rms currents of the inductor are 0.277 A, 0.879 A, 0.766 A, respectively.

#### 8.2.3.2.2 Input Capacitor Selection

An input capacitor is required to reduce the surge current drawn from the input supply and the switching noise coming from the device. Electrolytic capacitors are recommended for energy storage. Ceramic capacitors with X5R or X7R dielectrics are highly recommended because of their low ESR and small temperature coefficients. For most applications, it is recommended to place a 10- $\mu F$  capacitor along with a 0.1- $\mu F$  capacitor from VIN to PGND/AGND to provide high-frequency filtering. The input capacitor voltage rating must be greater than the maximum input voltage. Use 式 28 to calculate the input ripple voltage, where  $ESR_{CIN}$  is the ESR of input capacitor, and  $K_{DR}$  is the derating coefficient of ceramic capacitance at the applied DC voltage.

$$V_{IN(ripple)} = I_{L(max)} \times \left( \frac{V_{OUT}}{K_{DR} \times C_{IN} \times f_{SW} \times V_{IN(max)}} + ESR_{CIN} \right) \quad (28)$$

In this design, a 33- $\mu F$ , 100V electrolytic capacitor, a 2.2- $\mu F$ , 100V X7R ceramic capacitor and a 0.1- $\mu F$ , 100V X7R ceramic capacitor are chosen, yielding around 70-mV input ripple voltage.

### 8.2.3.2.3 Output Capacitor Selection

The output capacitor reduces the high-frequency current ripple through the LED string. Excessive current ripple increases the RMS current in the LED string, therefore increasing the LED temperature.

1. Calculate the total dynamic resistance of the LED string ( $R_{LED}$ ) using the LED manufacturer's datasheet.
2. Calculate the required impedance of the output capacitor ( $Z_{COUT}$ ) given the acceptable peak-to-peak ripple current through the LED string,  $I_{LED(ripple)}$ .  $I_{L(ripple)}$  is the peak-to-peak inductor ripple current as calculated with the selected inductor.
3. Calculate the minimum effective output capacitance required.
4. Increase the output capacitance appropriately due to the derating effect of applied DC voltage.

See 式 29, 式 30, and 式 31.

$$R_{LED} = \frac{\Delta V_F}{\Delta I_F} \times \# \text{ of LEDs} \quad (29)$$

$$Z_{COUT} = \frac{R_{LED} \times I_{LED(ripple)}}{I_{L(max)} - I_{LED(ripple)}} \quad (30)$$

$$C_{COUT} = \frac{1}{2\pi \times f_{SW} \times Z_{COUT}} \quad (31)$$

Once the output capacitor is chosen, 式 32 can be used to estimate the peak-to-peak ripple current through the LED string.

$$I_{LED(ripple)} = \frac{Z_{COUT} \times I_{L(ripple)}}{Z_{COUT} + R_{LED}} \quad (32)$$

Ceramic capacitors with X5R or X7R dielectrics are highly recommended because of their low ESR and small temperature coefficients. In this design, a 10- $\mu$ F, 35-V X7R ceramic capacitor is chosen.

### 8.2.3.2.4 Sense Resistor Selection

The maximum LED current is 2 A at 100% PWM duty and the corresponding  $V_{REF}$  is 200 mV. By using 式 33, the sense resistance is calculated as 100 m $\Omega$ . Note that the power consumption of the sense resistor is 400 mW, requiring enough margin of the resistor's power rating in selection.

$$R_{SENSE} = \frac{V_{REF}}{I_{LED\_FS}} \quad (33)$$

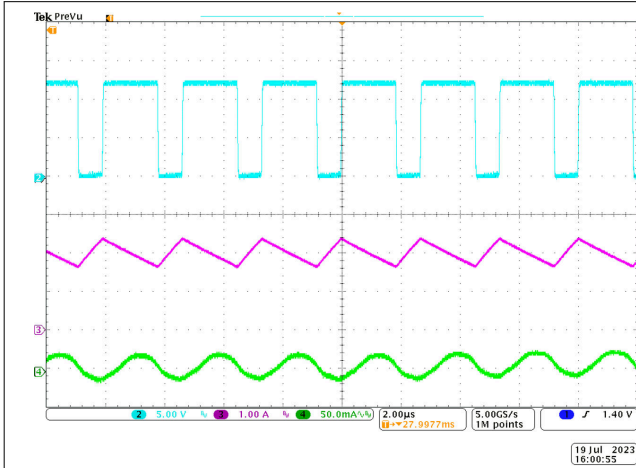
In buck topology,  $C_{sense}$  is optional to use,

### 8.2.3.2.5 Other External Components Selection

In this design, a 0.1- $\mu$ F, 50-V X7R ceramic capacitor is chosen for high-frequency filtering of sense feedback.

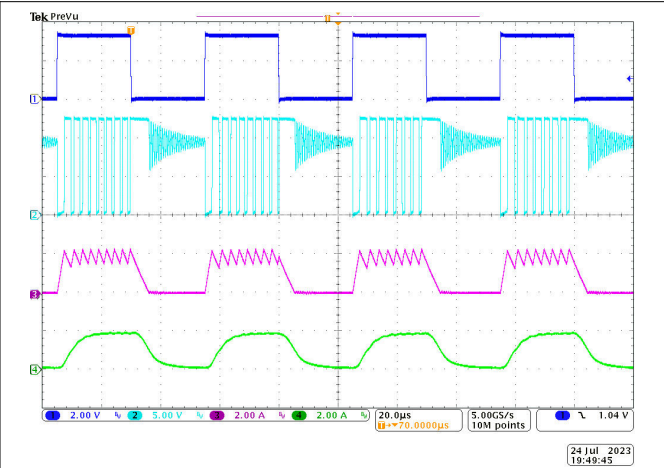
For loop stability, it is recommended to select a 1-nF, 10-V X7R ceramic capacitor for  $C_{COMP}$  and a 1-k $\Omega$  resistor for  $R_{COMP}$ . A 1-M $\Omega$  resistor is chosen for  $R_{DAMP}$  to suppress the overshoot current at rising edge of PWM on.

### 8.2.3.3 Application Curves



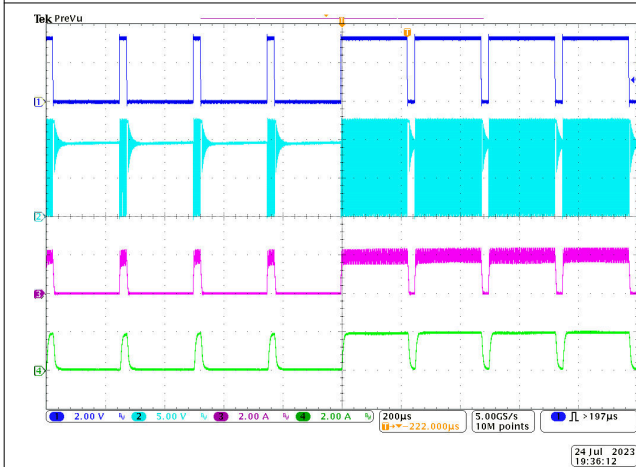
Ch 2: SW, Ch 3: Inductor Current, Ch 4: LED Current (AC)

**図 8-16. LED Current Ripple at ADIM = 100%, 1 kHz and  $F_{sw} = 400$  kHz**



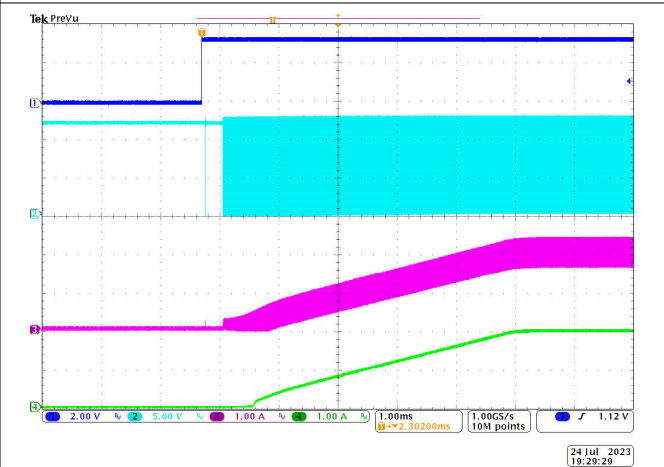
Ch 1: PWM/EN, Ch 2: SW, Ch 3: Inductor Current, Ch 4: LED Current

**図 8-17. LED Current Ripple at PWM = 50%, 20 kHz and  $F_{sw} = 400$  kHz**



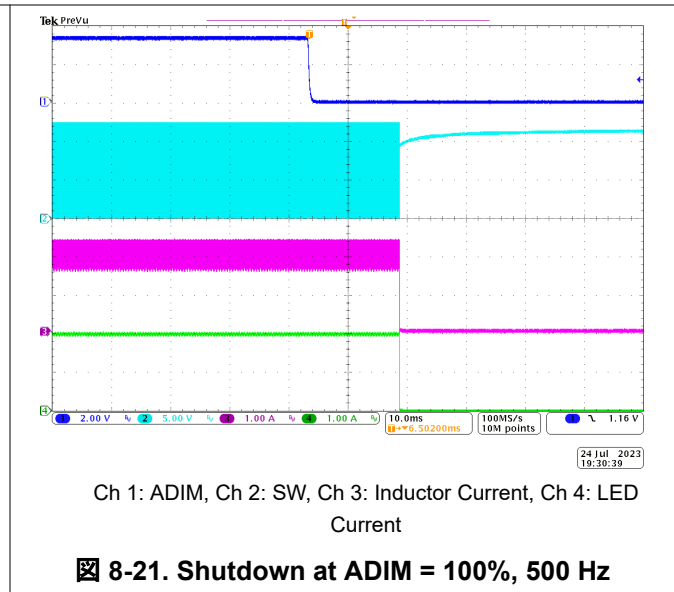
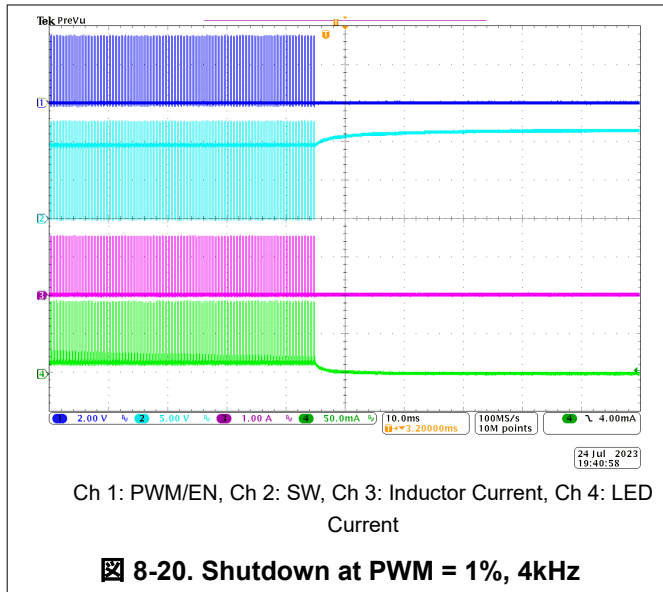
Ch 1: PWM/EN, Ch 2: SW, Ch 3: Inductor Current, Ch 4: LED Current

**図 8-18. LED Current Transient for a PWM Transition from 10% to 99%, 4 kHz**



Ch 1: ADIM, Ch 2: SW, Ch 3: Inductor Current, Ch 4: LED Current

**図 8-19. Startup at ADIM = 100%, 500Hz**



### 8.3 Power Supply Recommendations

The device is designed to operate from an input voltage supply ranging between 4.5 V and 65 V. This input supply must be well regulated. The device requires an input capacitor to reduce the surge current drawn from the input supply and the switching noise from the device. Ceramic capacitors with X5R or X7R dielectrics are highly recommended because of their low ESR and small temperature coefficients. For most applications, a 10- $\mu$ F capacitor is enough.

### 8.4 Layout

The LP8868-Q1 family requires a proper layout for optimal performance. The following section gives some guidelines to ensure a proper layout.

#### 8.4.1 Layout Guidelines

Examples of a proper layout for boost topology, buck-boost topology and buck topology of LP8868 family is shown below.

- Creating a large GND plane for good electrical and thermal performance is important.
- The IN and GND traces should be as wide as possible to reduce trace impedance. Wide traces have the additional advantage of providing excellent heat dissipation.
- Thermal vias can be used to connect the top-side GND plane to additional printed-circuit board (PCB) layers for heat dissipation and grounding.
- The input capacitors must be located as close as possible to the IN pin and the GND pin.
- The VCC capacitor should be placed as close as possible to VCC pin to ensure stable LDO output voltage.
- The SW trace must be kept as short as possible to reduce parasitic inductance and thereby reduce transient voltage spikes. Short SW trace also reduces radiated noise and EMI.
- Do not allow switching current to flow under the device.
- The routing of CSN and CSP traces are recommended to be in parallel and kept as short as possible and placed away from the high-voltage switching trace and the ground shield.
- The compensation capacitor must be placed as close as possible to COMP pin so as to prevent oscillation and system instability.

### 8.4.2 Layout Example

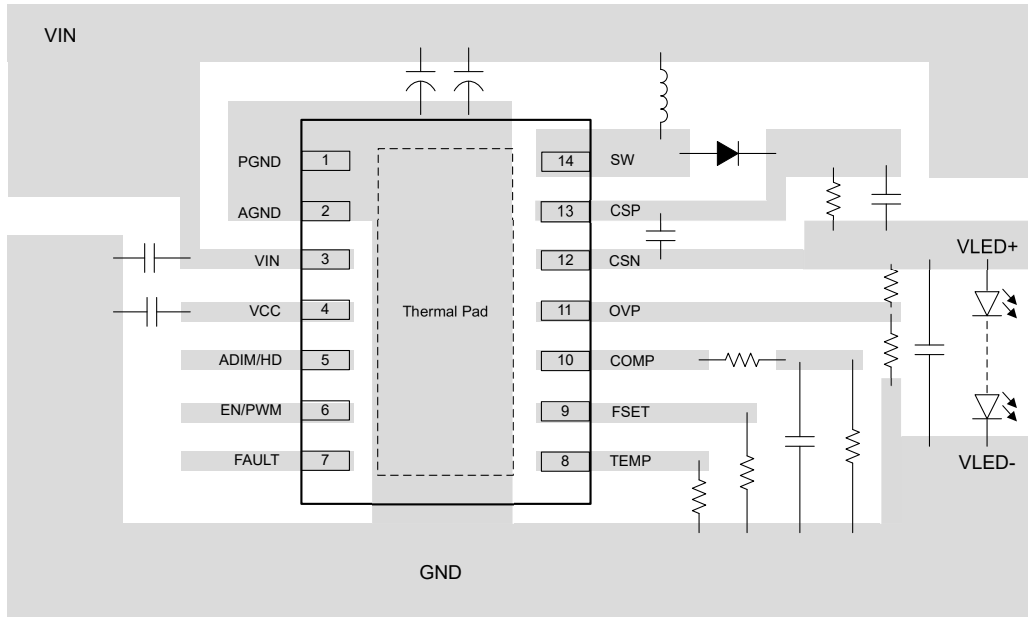


図 8-22. Boost Topology Top View Layout Example

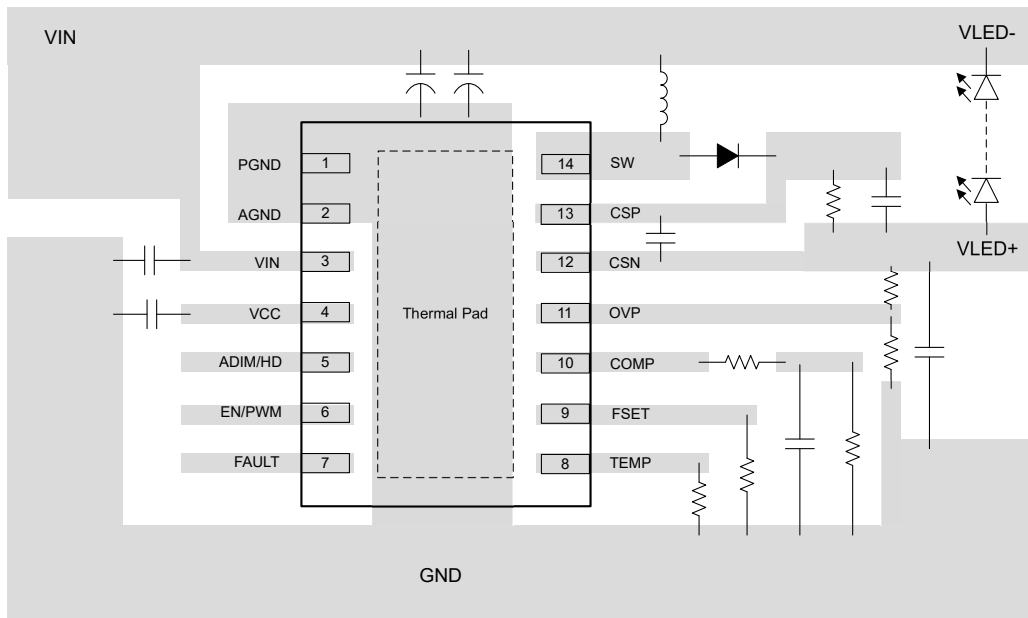
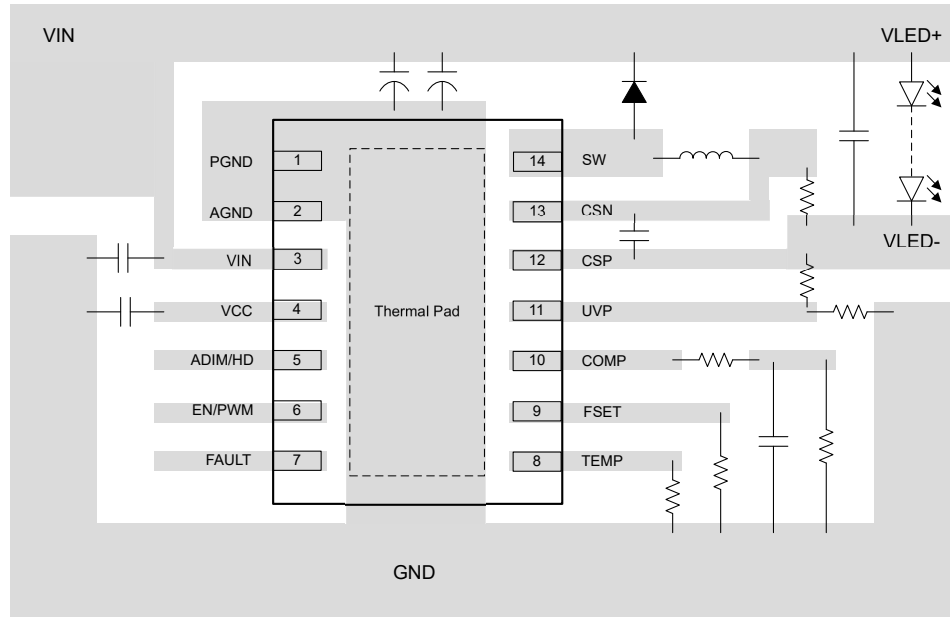


図 8-23. Buck-Boost Topology Top View Layout Example



**8-24. Buck Topology Top View Layout Example**

## 9 Device and Documentation Support

TI offers an extensive line of development tools. Tools and software to evaluate the performance of the device, generate code, and develop solutions are listed below.

### 9.1 ドキュメントの更新通知を受け取る方法

ドキュメントの更新についての通知を受け取るには、[www.tij.co.jp](http://www.tij.co.jp) のデバイス製品フォルダを開いてください。[通知] をクリックして登録すると、変更されたすべての製品情報に関するダイジェストを毎週受け取ることができます。変更の詳細については、改訂されたドキュメントに含まれている改訂履歴をご覧ください。

### 9.2 サポート・リソース

テキサス・インスツルメンツ E2E™ サポート・フォーラムは、エンジニアが検証済みの回答と設計に関するヒントをエキスパートから迅速かつ直接得ることができる場所です。既存の回答を検索したり、独自の質問をしたりすることで、設計に必要な支援を迅速に得ることができます。

リンクされているコンテンツは、各寄稿者により「現状のまま」提供されるものです。これらはテキサス・インスツルメンツの仕様を構成するものではなく、必ずしもテキサス・インスツルメンツの見解を反映したものではありません。テキサス・インスツルメンツの[使用条件](#)を参照してください。

### 9.3 商標

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### 9.4 静電気放電に関する注意事項



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ESD による破損は、わずかな性能低下からデバイスの完全な故障まで多岐にわたります。精密な IC の場合、パラメータがわずかに変化するだけで公表されている仕様から外れる可能性があるため、破損が発生しやすくなっています。

### 9.5 用語集

[テキサス・インスツルメンツ用語集](#) この用語集には、用語や略語の一覧および定義が記載されています。

## 10 Revision History

Changes from Revision * (July 2023) to Revision A (November 2023)	Page
• 量産データに LP8868U-Q1, LP8868V-Q1, LP8868W-Q1 を追加.....	1

## 11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most-current data available for the designated s. This data is subject to change without notice and without revision of this document. For browser-based versions of this data sheet, see the left-hand navigation pane.



**PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
LP8868UQDMTRQ1	ACTIVE	VSON	DMT	14	3000	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 125	L868U	<a href="#">Samples</a>
LP8868VQDMTRQ1	ACTIVE	VSON	DMT	14	3000	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 125	L868V	<a href="#">Samples</a>
LP8868WQDMTRQ1	ACTIVE	VSON	DMT	14	3000	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 125	L868W	<a href="#">Samples</a>
LP8868XQDMTRQ1	ACTIVE	VSON	DMT	14	3000	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 125	L868X	<a href="#">Samples</a>
LP8868YQDMTRQ1	ACTIVE	VSON	DMT	14	3000	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 125	L868Y	<a href="#">Samples</a>
LP8868ZQDMTRQ1	ACTIVE	VSON	DMT	14	3000	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 125	L868Z	<a href="#">Samples</a>

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "-" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

**TAPE AND REEL INFORMATION**

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LP8868UQDMTRQ1	VSON	DMT	14	3000	330.0	12.4	3.3	4.8	1.2	8.0	12.0	Q1
LP8868VQDMTRQ1	VSON	DMT	14	3000	330.0	12.4	3.3	4.8	1.2	8.0	12.0	Q1
LP8868WQDMTRQ1	VSON	DMT	14	3000	330.0	12.4	3.3	4.8	1.2	8.0	12.0	Q1
LP8868XQDMTRQ1	VSON	DMT	14	3000	330.0	12.4	3.3	4.8	1.2	8.0	12.0	Q1
LP8868YQDMTRQ1	VSON	DMT	14	3000	330.0	12.4	3.3	4.8	1.2	8.0	12.0	Q1
LP8868ZQDMTRQ1	VSON	DMT	14	3000	330.0	12.4	3.3	4.8	1.2	8.0	12.0	Q1

**TAPE AND REEL BOX DIMENSIONS**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LP8868UQDMTRQ1	VSON	DMT	14	3000	367.0	367.0	35.0
LP8868VQDMTRQ1	VSON	DMT	14	3000	367.0	367.0	35.0
LP8868WQDMTRQ1	VSON	DMT	14	3000	367.0	367.0	35.0
LP8868XQDMTRQ1	VSON	DMT	14	3000	367.0	367.0	35.0
LP8868YQDMTRQ1	VSON	DMT	14	3000	367.0	367.0	35.0
LP8868ZQDMTRQ1	VSON	DMT	14	3000	367.0	367.0	35.0

## GENERIC PACKAGE VIEW

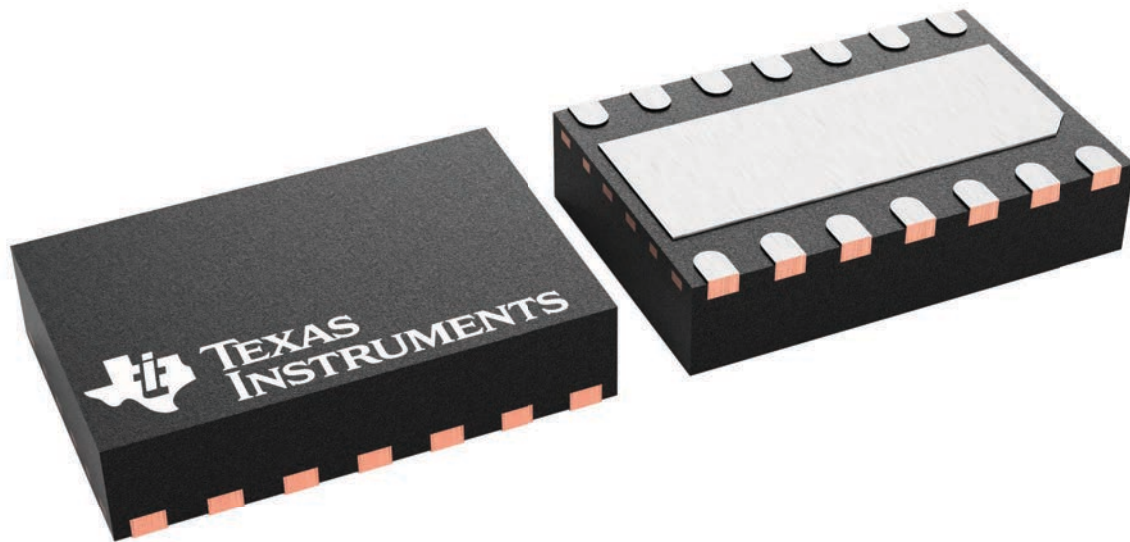
**DMT 14**

**VSON - 0.9 mm max height**

3 x 4.5, 0.65 mm pitch

PLASTIC SMALL OUTLINE - NO LEAD

This image is a representation of the package family, actual package may vary.  
Refer to the product data sheet for package details.



4225088/A

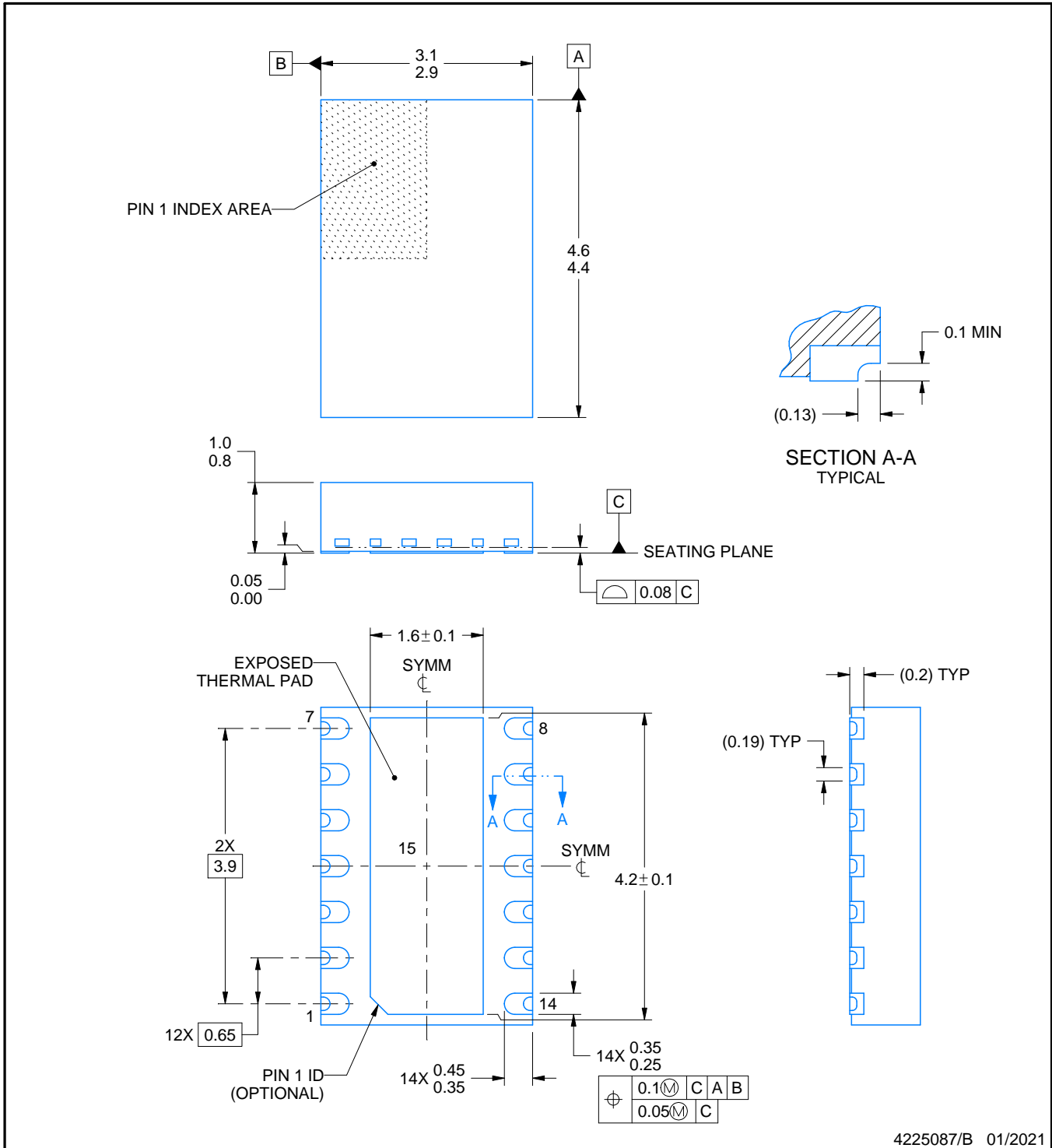
# DMT0014B



## PACKAGE OUTLINE

VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



4225087/B 01/2021

**NOTES:**

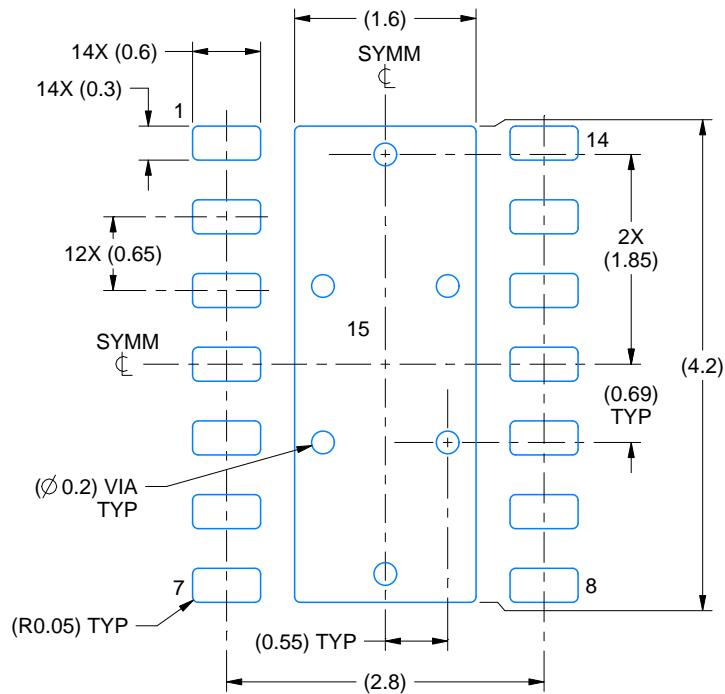
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

# EXAMPLE BOARD LAYOUT

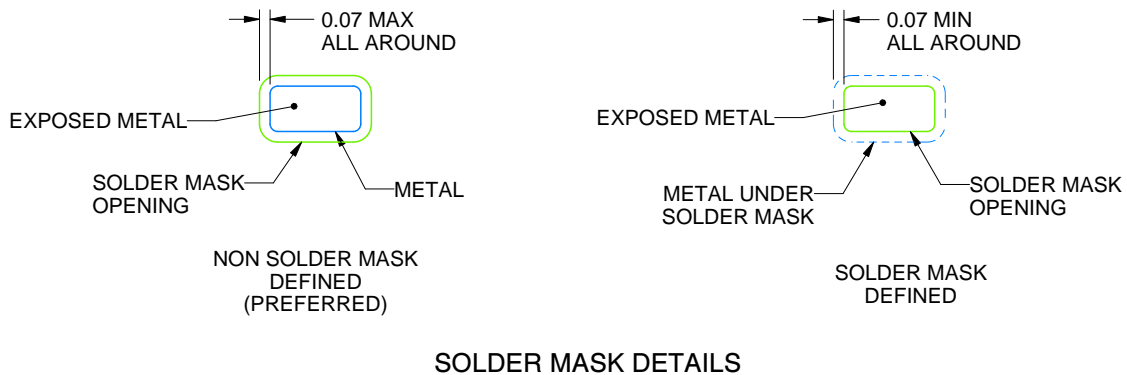
DMT0014B

VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:15X



SOLDER MASK DETAILS

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NOTES: (continued)

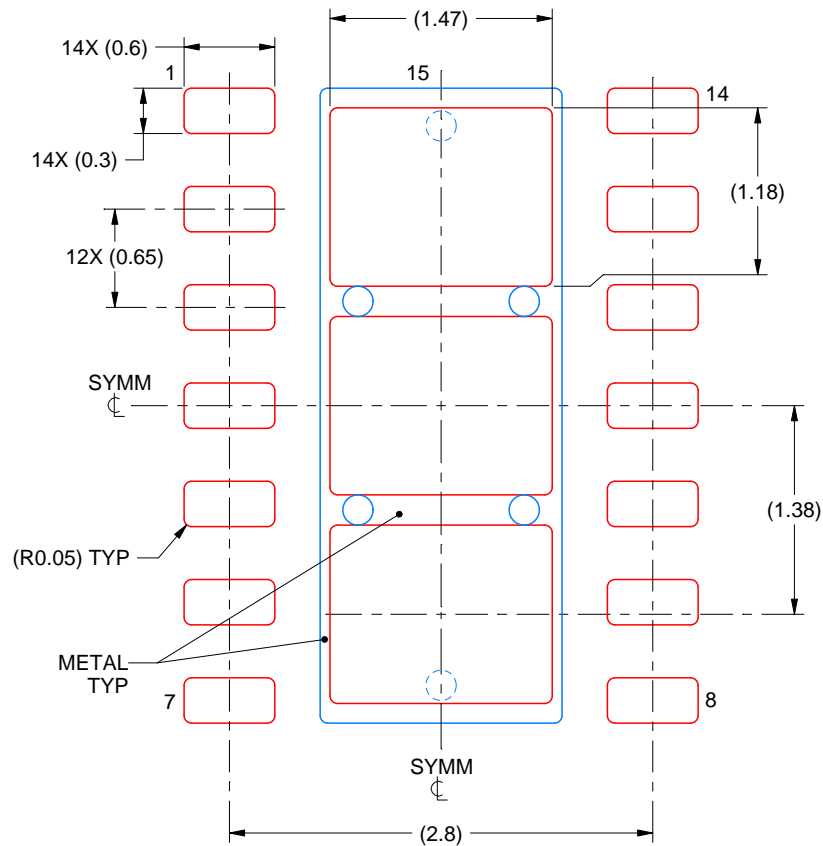
4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 ([www.ti.com/lit/slua271](http://www.ti.com/lit/slua271)).
5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

# EXAMPLE STENCIL DESIGN

DMT0014B

VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



SOLDER PASTE EXAMPLE  
BASED ON 0.125 mm THICK STENCIL  
EXPOSED PAD 15  
77.4% PRINTED SOLDER COVERAGE BY AREA  
SCALE:20X

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NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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