

TPS25221 2.5V~5.5V、2A連続電流制限付きスイッチ

1 特長

- 2.5V~5.5Vの $V_{OPERATING}$
- TPS2553 とピン互換
- 2Aの I_{CONT_MAX}
- 0.275A~2.7Aの変 I_{LIMIT} (1.7Aで $\pm 6.5\%$)
- 70m Ω (標準値)の R_{ON}
- 1.5 μ sの短絡応答
- 8msのフォルト報告グリッチ除去
- 逆電流のブロック(ディスエーブル時)
- ソフトスタート機能内蔵
- UL 60950およびUL 62368認定
- IEC 61000-4-2に従い15kVのESD保護(外部容量あり)

2 アプリケーション

- USBポート/ハブ、ラップトップ、デスクトップ
- HDTV
- セット・トップ・ボックス
- 光学ソケット保護

3 概要

TPS25221は、大きな容量性負荷と短絡が発生する可能性のあるアプリケーションを対象としています。プログラム可能な電流制限スレッシュホールドは、外付け抵抗を使用して275mA~2.7A (標準値)に設定できます。 I_{LIMIT} の精度は、より高い電流制限設定において、 $\pm 6\%$ まで高めることができます。電源スイッチの立ち上がりおよび立ち下がり時間は、電源オン/オフ時の電流サージを最小限に抑えるように制御されます。

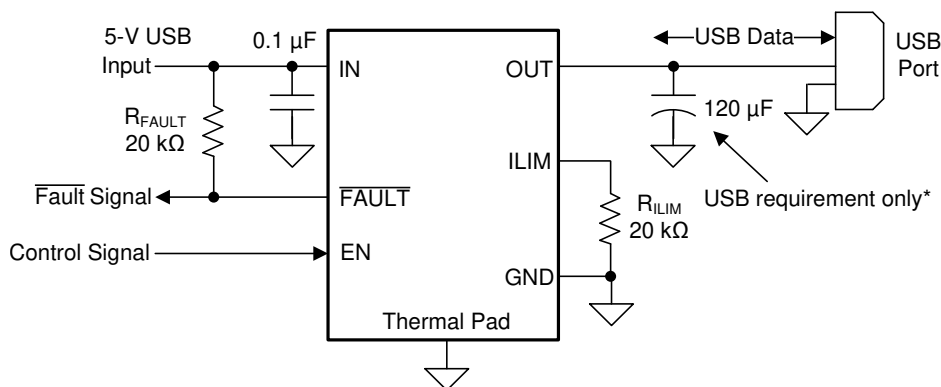
負荷が、プログラムされた I_{LIMIT} を超える電流の抽出を試みると、内部FETが定電流モードに移行し、 I_{LOAD} を I_{LIMIT} 以下に維持します。FAULT出力は、過電流の状況が発生したとき、組み込みのグリッチ除去時間の後でLOWにアサートされます。

製品情報⁽¹⁾

| 型番 | パッケージ | 本体サイズ(公称) |
|----------|------------|-----------------|
| TPS25221 | SOT-23 (6) | 2.90mm×1.60mm |
| | WSON (6) | 2.00mm × 2.00mm |

(1) 提供されているすべてのパッケージについては、巻末の注文情報を参照してください。

概略回路図



*USB requirement that downstream facing ports are bypassed with at least 120 μ F per hub.

目次

| | | | | | |
|----------|--|-----------|-----------|--|-----------|
| 1 | 特長 | 1 | 10 | Application and Implementation | 14 |
| 2 | アプリケーション | 1 | 10.1 | Application Information..... | 14 |
| 3 | 概要 | 1 | 10.2 | Typical Applications | 15 |
| 4 | 改訂履歴 | 2 | 11 | Power Supply Recommendations | 21 |
| 5 | Device Comparison Table | 3 | 11.1 | Self-Powered and Bus-Powered Hubs | 21 |
| 6 | Pin Configuration and Functions | 3 | 11.2 | Low-Power Bus-Powered and High-Power Bus- Powered Functions | 21 |
| 7 | Specifications | 4 | 11.3 | Power Dissipation and Junction Temperature | 21 |
| 7.1 | Absolute Maximum Ratings | 4 | 12 | Layout | 23 |
| 7.2 | ESD Ratings | 4 | 12.1 | Layout Guidelines | 23 |
| 7.3 | Recommended Operating Conditions..... | 4 | 12.2 | Layout Example | 23 |
| 7.4 | Thermal Information | 4 | 13 | デバイスおよびドキュメントのサポート | 24 |
| 7.5 | Electrical Characteristics..... | 5 | 13.1 | デバイス・サポート | 24 |
| 7.6 | Typical Characteristics..... | 7 | 13.2 | ドキュメントのサポート | 24 |
| 8 | Parameter Measurement Information | 10 | 13.3 | ドキュメントの更新通知を受け取る方法..... | 24 |
| 9 | Detailed Description | 11 | 13.4 | コミュニティ・リソース | 24 |
| 9.1 | Overview | 11 | 13.5 | 商標 | 24 |
| 9.2 | Functional Block Diagram | 11 | 13.6 | 静電気放電に関する注意事項 | 24 |
| 9.3 | Feature Description..... | 12 | 13.7 | Glossary | 24 |
| 9.4 | Device Functional Modes..... | 13 | 14 | メカニカル、パッケージ、および注文情報 | 24 |
| 9.5 | Programming..... | 13 | | | |

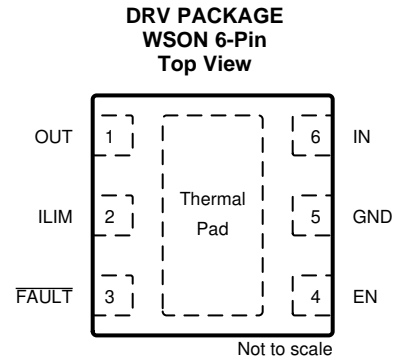
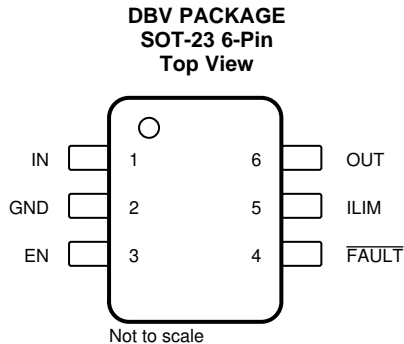
4 改訂履歴

| | | |
|---|--|-------------|
| Revision C (May 2019) から Revision D に変更 | | Page |
| • | Removed content from the <i>Programming the Current-Limit Threshold</i> section | 13 |
| Revision B (November 2018) から Revision C に変更 | | Page |
| • | Changed the Storage temperature From: TBD to: MIN = -65°C MAX = 150°C in the <i>Absolute Maximum Ratings</i> | 4 |
| Revision A (May 2018) から Revision B に変更 | | Page |
| • | 「 特長 」一覧の項目から保留中を削除 | 1 |
| 2018年1月発行のものから更新 | | Page |
| • | 量産用にリリース..... | 1 |

5 Device Comparison Table

| MAX OPERATING CURRENT | OUTPUT DISCHARGE | ENABLE | CURRENT LIMIT | LATCH OFF | Package | BASE PART NUMBER |
|-----------------------|------------------|--------|---------------|-----------|------------|------------------|
| 2 | N | High | Adjustable | N | SOT-23 (6) | TPS25221DBV |
| 2 | N | High | Adjustable | N | WSON (6) | TPS25221DRV |

6 Pin Configuration and Functions



Pin Functions

| NAME | PIN | | I/O | DESCRIPTION |
|-------------|--------|------|-----|---|
| | SOT-23 | WSON | | |
| IN | 1 | 6 | I | Input voltage and power switch drain; connect a 0.1 μ F or greater ceramic capacitor from IN to GND close to IC |
| GND | 2 | 5 | -- | Ground connection |
| EN | 3 | 4 | I | Enable input, logic high/low turns on power switch |
| FAULT | 4 | 3 | O | Active-low open-drain output, asserted during over-current, or over-temperature conditions |
| ILIM | 5 | 2 | O | External resistor used to set current limit threshold |
| OUT | 6 | 1 | O | Power switch output, connect to load |
| Thermal Pad | -- | PAD | -- | Internally connected to GND; used to heat-sink the part to the circuit board traces. Connect thermal pad to GND pin externally. |

7 Specifications

7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

| | MIN | MAX | UNIT |
|--|--------------------|-----|------|
| Voltage range on IN, OUT, EN, $\overline{\text{FAULT}}$, ILIM | -0.3 | 6 | V |
| Voltage range from IN to OUT | -6 | 6 | |
| Continuous $\overline{\text{FAULT}}$ sink current | 0 | 25 | mA |
| ILIM source current | 0 | 1 | mA |
| Maximum junction temperature, T_j | Internally Limited | | |
| Storage temperature, T_{stg} | -65 | 150 | °C |

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

7.2 ESD Ratings

| | | VALUE | UNIT |
|--------------------|--|--------|------|
| $V_{\text{(ESD)}}$ | Electrostatic discharge | | |
| | Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾ | ±2000 | V |
| | Charged-device model (CDM), per JEDEC specification JESD22-C101 or ANSI/ESDA/JEDEC JS-002 ⁽²⁾ | ±500 | V |
| | IEC 61000-4-2 contact discharge ⁽³⁾ | ±8000 | V |
| | IEC 61000-4-2 air-gap discharge ⁽³⁾ | ±15000 | V |

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
 (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.
 (3) Surges per EN61000-4-2. 1999 applied to output terminals of EVM. These are passing tests levels, not failure threshold.

7.3 Recommended Operating Conditions

Voltages are respect to GND (unless otherwise noted)

| | | | MIN | NOM | MAX | UNIT |
|--------------------|--|---------------------------|-----|-----|------|------|
| V_{IN} | Supply voltage | IN | 2.5 | | 5.5 | V |
| V_{EN} | Input voltage | EN | 0 | | 5.5 | V |
| V_{IH} | High-level input voltage | EN | 1.7 | | | V |
| V_{IL} | Low-level input voltage | EN | | | 0.66 | V |
| I_{CON} | Output continuous current | OUT | 0 | | 2 | A |
| R_{ILIM} | Current-limit threshold resistor range (nominal 1%) from ILIM to GND | | 20 | | 210 | kΩ |
| I_{FAULT} | Sink current into $\overline{\text{FAULT}}$ | $\overline{\text{FAULT}}$ | 0 | | 10 | mA |
| T_j | Operating junction temperature | | -40 | | 125 | °C |

7.4 Thermal Information

| THERMAL METRIC ⁽¹⁾ | TPS25221 | | UNIT | |
|-------------------------------|--|------------|-------|------|
| | DBV (SOT-23) | DRV (WSON) | | |
| | 6-PIN | 6-PIN | | |
| $R_{\theta\text{JA}}$ | Junction-to-ambient thermal resistance | 193.2 | 83 | °C/W |
| $R_{\theta\text{JC(top)}}$ | Junction-to-case (top) thermal resistance | 127.1 | 100.5 | °C/W |
| $R_{\theta\text{JB}}$ | Junction-to-board thermal resistance | 65.6 | 46.5 | °C/W |
| ψ_{JT} | Junction-to-top characterization parameter | 49.0 | 8.7 | °C/W |
| ψ_{JB} | Junction-to-board characterization parameter | 65.3 | 46.4 | °C/W |
| $R_{\theta\text{JC(bot)}}$ | Junction-to-case (bottom) thermal resistance | -- | 24.4 | °C/W |

- (1) Proper thermal design is required to ensure $T_j < 125^\circ\text{C}$ for best long term reliability. This is particularly important at higher currents, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

7.5 Electrical Characteristics

over recommended operating conditions, $V_{EN} = V_{IN}$, $R_{FAULT} = 10\text{ k}\Omega$ (unless otherwise noted)

| PARAMETER | | TEST CONDITIONS | | MIN | TYP | MAX | UNIT | | |
|---|---|--|--|------|------|------|------------------|-----|---|
| POWER SWITCH | | | | | | | | | |
| $r_{DS(on)}$ | Static drain-source on-state resistance | DBV package, $T_J = 25^\circ\text{C}$ | | 70 | 80 | | m Ω | | |
| | | DBV package, $-40^\circ\text{C} \leq T_J \leq 125^\circ\text{C}$ | | | | 110 | | | |
| | | DRV package, $T_J = 25^\circ\text{C}$ | | 70 | 92 | | | | |
| | | DRV package, $-40^\circ\text{C} \leq T_J \leq 125^\circ\text{C}$ | | | | 122 | | | |
| r | Rise time, output | $V_{IN} = 5.5\text{ V}$ | $C_L = 1\text{ }\mu\text{F}$, $R_L = 100\text{ }\Omega$, (see 1) | 0.55 | 0.95 | | ms | | |
| | | $V_{IN} = 2.5\text{ V}$ | | 0.35 | 0.62 | | | | |
| t_f | Fall time, output | $V_{IN} = 5.5\text{ V}$ | | 0.24 | 0.3 | | | | |
| | | $V_{IN} = 2.5\text{ V}$ | | 0.22 | 0.28 | | | | |
| ENABLE INPUT EN OR $\overline{\text{EN}}$ | | | | | | | | | |
| | Enable pin turn on/off threshold | | | | 0.8 | | | 1.6 | V |
| I_{EN} | Input current | $V_{EN} = 0\text{ V}$ or 5.5 V | | -0.5 | 0 | 0.5 | μA | | |
| t_{on} | Turnon time | $C_L = 1\text{ }\mu\text{F}$, $R_L = 100\text{ }\Omega$, (see 2) | | | | 3 | ms | | |
| t_{off} | Turnoff time | $C_L = 1\text{ }\mu\text{F}$, $R_L = 100\text{ }\Omega$, (see 2) | | | | 0.7 | ms | | |
| CURRENT LIMIT | | | | | | | | | |
| I_{OS} | Current-limit threshold (Maximum DC output current I_{OUT} delivered to load) and Short-circuit current, I_{OUT} connected to GND | $R_{ILIM} = 20\text{ k}\Omega$ | $T_J = 25^\circ\text{C}$ | 2585 | 2720 | 2850 | mA | | |
| | | | $-40^\circ\text{C} \leq T_J \leq 125^\circ\text{C}$ | 2560 | | 2880 | | | |
| | | $R_{ILIM} = 30\text{ k}\Omega$ | $T_J = 25^\circ\text{C}$ | 1710 | 1820 | 1930 | | | |
| | | | $-40^\circ\text{C} \leq T_J \leq 125^\circ\text{C}$ | 1700 | | 1945 | | | |
| | | $R_{ILIM} = 80\text{ k}\Omega$ | $T_J = 25^\circ\text{C}$ | 630 | 690 | 755 | | | |
| | | | $-40^\circ\text{C} \leq T_J \leq 125^\circ\text{C}$ | 610 | | 790 | | | |
| | | $R_{ILIM} = 210\text{ k}\Omega$ | $T_J = 25^\circ\text{C}$ | 220 | 275 | 330 | | | |
| | | | $-40^\circ\text{C} \leq T_J \leq 125^\circ\text{C}$ | 210 | | 370 | | | |
| t_{IOS} | Response time to short circuit | $V_{IN} = 5\text{ V}$ (see 4) | | | 1.5 | | μs | | |
| SUPPLY CURRENT | | | | | | | | | |
| I_{SD} | Supply current, switch disable | $V_{IN} = 5.5\text{ V}$, No load on OUT, $V_{EN} = 0\text{ V}$, $R_{ILIM} = 20\text{ k}\Omega$ | | | 0.02 | 0.5 | μA | | |
| I_{SE} | Supply current, switch enable | $V_{IN} = 5.5\text{ V}$, No load on OUT, $R_{ILIM} = 20\text{ k}\Omega$ | | | 75 | 90 | μA | | |
| UNDERVOLTAGE LOCKOUT | | | | | | | | | |
| UVLO | Low-level input voltage, IN | V_{IN} rising | | 2.37 | 2.47 | | V | | |
| | Hysteresis, IN | $T_J = 25^\circ\text{C}$ | | 45 | | | mV | | |
| FAULT FLAG | | | | | | | | | |
| V_{OL} | Output low voltage, $\overline{\text{FAULT}}$ | $I_{FAULT} = 1\text{ mA}$ | | | | 180 | mV | | |
| | Off-state leakage | $V_{FAULT} = 5.5\text{ V}$ | | | | 0.5 | μA | | |
| | $\overline{\text{FAULT}}$ deglitch | $\overline{\text{FAULT}}$ assertion or de-assertion due to overcurrent condition | | 6 | 8 | 12 | ms | | |
| THERMAL SHUTDOWN | | | | | | | | | |
| | Thermal shutdown threshold | | | 165 | | | $^\circ\text{C}$ | | |
| | Thermal shutdown threshold in current-limit | | | 145 | | | $^\circ\text{C}$ | | |
| | Hysteresis | | | 20 | | | $^\circ\text{C}$ | | |



图 1. Power-On and Off Timing



图 2. Enable Timing, Active High Enable



图 3. Enable Timing, Active Low Enable

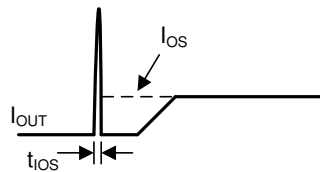


图 4. Output Short Circuit Parameters

7.6 Typical Characteristics

See [Figure 21](#) for reference schematic



$V_{IN} = 5\text{ V}$, $R_{ILIM} = 20\text{ k}\Omega$, $R_{OUT} = 5\text{ }\Omega$

Figure 5. Turnon Delay and Rise Time



$V_{IN} = 5\text{ V}$, $R_{ILIM} = 20\text{ k}\Omega$, $R_{OUT} = 5\text{ }\Omega$

Figure 6. Turnoff Delay and Fall Time



$V_{IN} = 5\text{ V}$, $R_{ILIM} = 20\text{ k}\Omega$, $R_{OUT} = 0\text{ }\Omega$

Figure 7. Device Enabled into Short-Circuit



$V_{IN} = 5\text{ V}$, $R_{ILIM} = 20\text{ k}\Omega$

Figure 8. Full-Load to Short-Circuit Transient Response



$V_{IN} = 5\text{ V}$, $R_{ILIM} = 20\text{ k}\Omega$

Figure 9. Short-Circuit to Full-Load Recovery Response



$V_{IN} = 5\text{ V}$, $R_{ILIM} = 20\text{ k}\Omega$

Figure 10. No-Load to Short-Circuit Transient Response

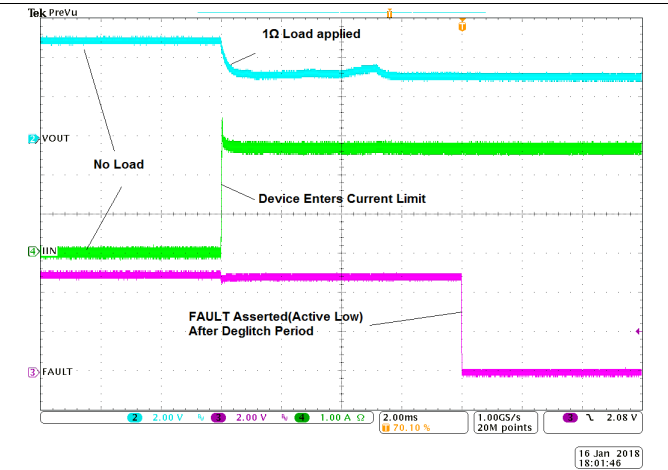
Typical Characteristics (continued)

See [Figure 21](#) for reference schematic



$V_{IN} = 5\text{ V}$, $R_{ILIM} = 20\text{ k}\Omega$

Figure 11. Short-Circuit to No-Load Recovery Response



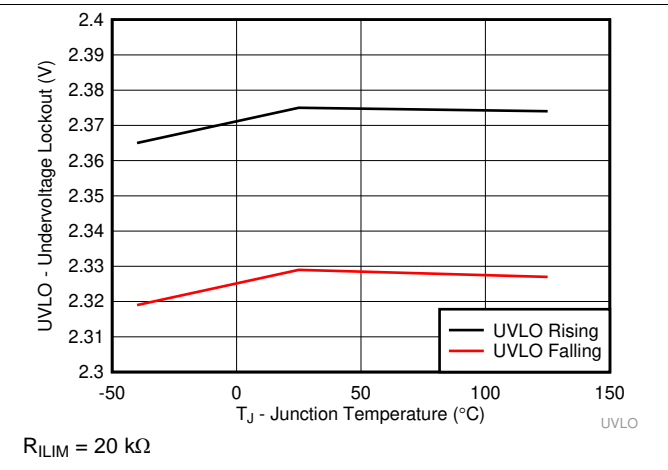
$V_{IN} = 5\text{ V}$, $R_{ILIM} = 20\text{ k}\Omega$

Figure 12. No Load to 1-Ω Transient Response



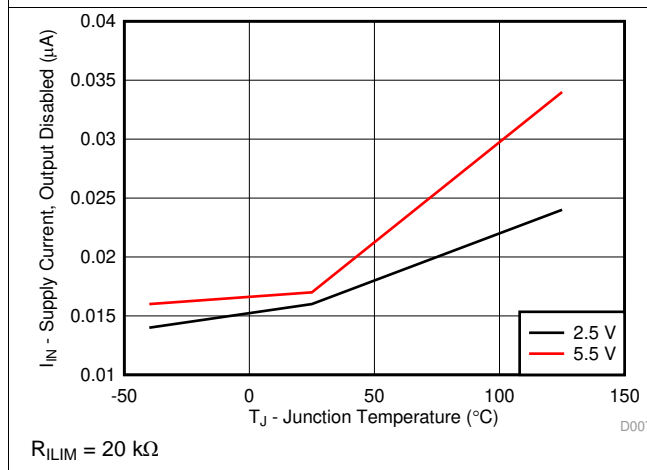
$V_{IN} = 5\text{ V}$, $R_{ILIM} = 20\text{ k}\Omega$

Figure 13. 1-Ω to No Load Transient Response



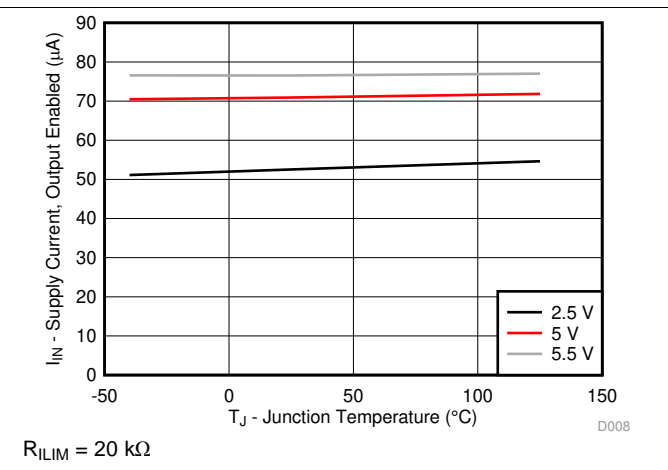
$R_{ILIM} = 20\text{ k}\Omega$

Figure 14. UVLO – Undervoltage Lockout – V



$R_{ILIM} = 20\text{ k}\Omega$

Figure 15. I_{IN} – Supply Current, Output Disabled – μA

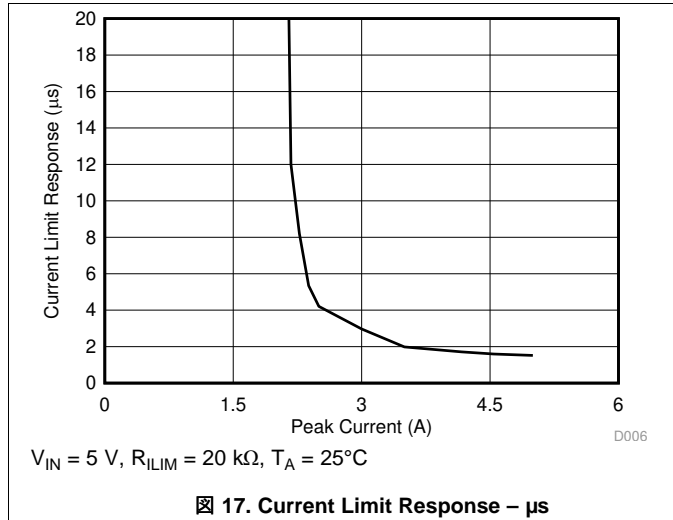


$R_{ILIM} = 20\text{ k}\Omega$

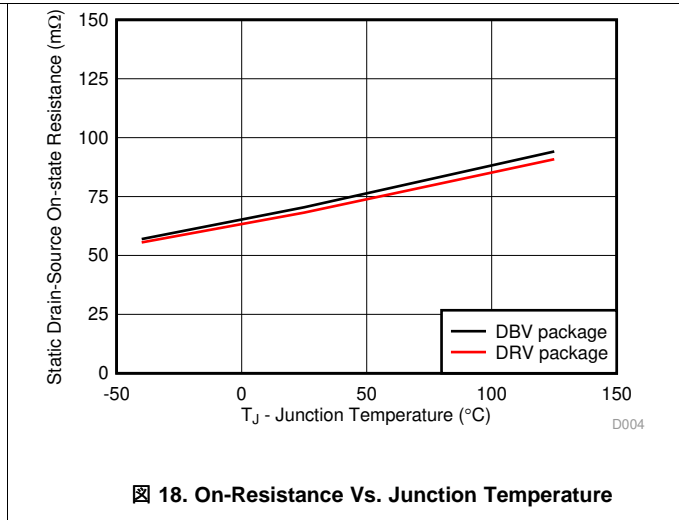
Figure 16. I_{IN} – Supply Current, Output Enabled – μA

Typical Characteristics (continued)

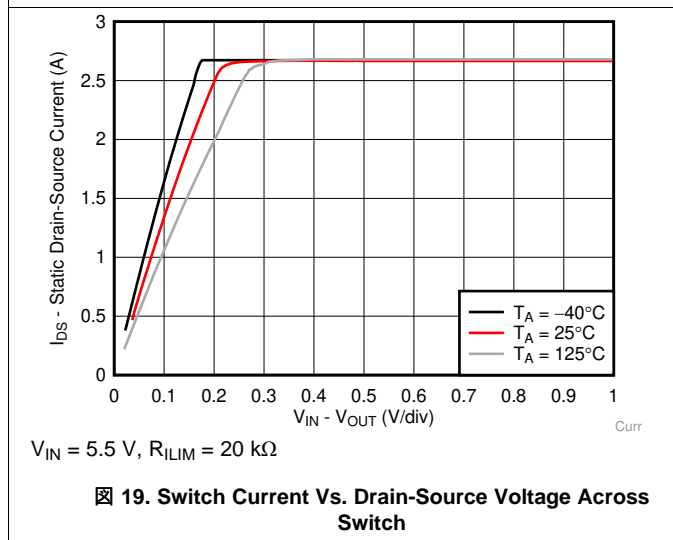
See [21](#) for reference schematic



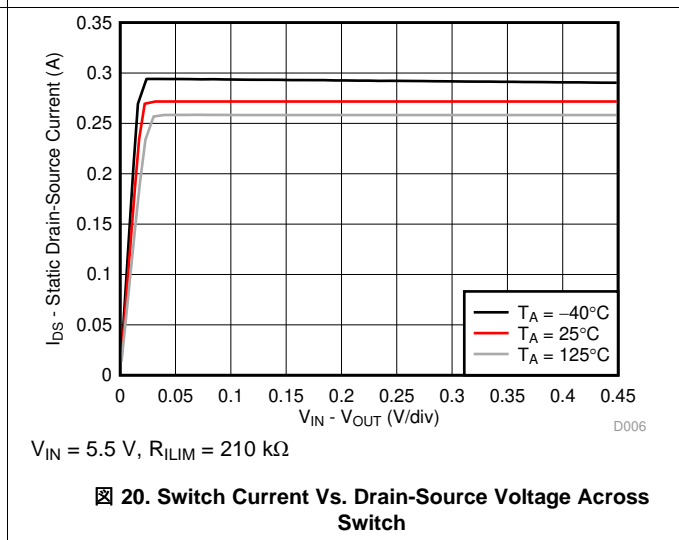
17. Current Limit Response – μs



18. On-Resistance Vs. Junction Temperature



19. Switch Current Vs. Drain-Source Voltage Across Switch



20. Switch Current Vs. Drain-Source Voltage Across Switch

8 Parameter Measurement Information

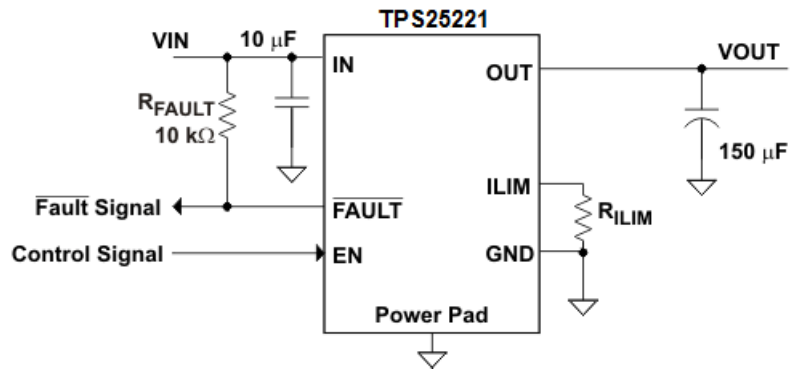


图 21. Typical Characteristics Reference Schematic

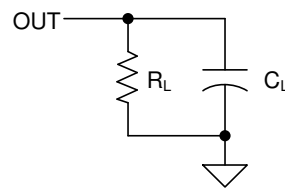


图 22. Output Rise / Fall Test Load



图 23. Output Voltage vs Current-Limit Threshold

9 Detailed Description

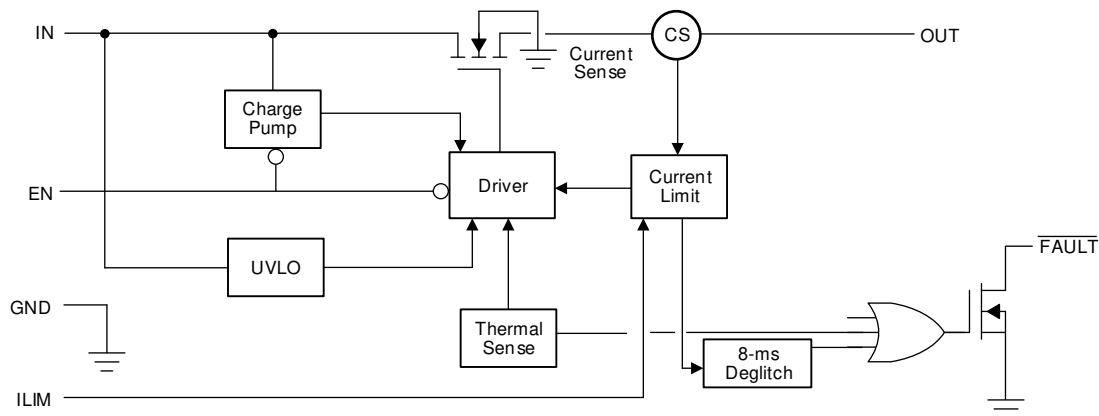
9.1 Overview

The TPS25221 is current-limited, power-distribution switch using N-channel MOSFETs for applications where short circuits or heavy capacitive loads are encountered. The TPS25221 allows the user to program the current limit threshold between 275 mA to 2.7A (typical) through an external resistor.

This device incorporates an internal charge pump and the gate drive circuitry necessary to drive the N-channel MOSFET. The charge pump supplies power to the driver circuit and provides the necessary voltage to pull the gate of the MOSFET above the source. The charge pump operates from input voltages as low as 2.5 V and requires little supply current. The driver controls the gate voltage of the power switch. The driver incorporates circuitry that controls the rise and fall times of the output voltage to limit large current and voltage surges and provides built-in soft-start functionality.

The TPS25221 limits the output current to the current-limit threshold I_{OS} during an over-current or short-circuit event by reducing the charge pump voltage driving the N-channel MOSFET and operating it in the saturation region. The result of limiting the output current to I_{OS} reduces the output voltage at OUT because N-channel MOSFET is no longer fully enhanced (see [Figure 22](#)).

9.2 Functional Block Diagram



9.3 Feature Description

9.3.1 Over-current Conditions

The TPS25221 responds to over-current conditions by limiting output current to I_{OS} as show in [Figure 24](#). When an overload condition occurs, the device maintains a constant output current and the output voltage reduces accordingly. Two possible overload conditions can occur.

1. The first condition is when a short circuit or overload is present when the device is powered-up or enabled. The short circuit and overload holds the output near zero potential with respect to ground and the TPS25221 ramps the output current to I_{OS} . The TPS25221 limits the current to I_{OS} until the overload condition is removed or the device begins to thermal cycle.
2. The second condition is when a short circuit, partial short circuit, or transient overload occurs when the device is on and the internal NFET is fully enhanced. The device responds to the over-current condition by turning off the NFET within the time limit specified by t_{IOS} (see [Figure 4](#)). The current-sense amplifier is over-driven during this time and momentarily disables the internal N-channel MOSFET. The current-sense amplifier then recovers and ramps the output current to I_{OS} . Similar to the previous case, the TPS25221 limits the current to I_{OS} until the overload condition is removed or the device begins to thermal cycle.

The TPS25221 thermal cycles if an overload condition is present long enough to activate thermal limiting in any of the above cases. Thermal limiting turns off the internal NFET and starts when the junction temperature exceeds 145°C (typical). The device remains off until the junction temperature cools 20°C (typical) and then restarts.

9.3.2 Fault Response

The $\overline{\text{FAULT}}$ open-drain output is asserted (active low) during an over-current or over-temperature condition. The TPS25221 asserts the $\overline{\text{FAULT}}$ signal until the fault condition is removed and the device resumes normal operation. The TPS25221 is designed to eliminate nuisance $\overline{\text{FAULT}}$ reporting by using an internal 8 ms deglitch delay when reporting a fault. This ensures that $\overline{\text{FAULT}}$ is not accidentally asserted due to normal transient conditions, such as starting into a heavy capacitive load. The deglitch circuitry delays asserting and de-asserting current limit induce FAULT reports. The FAULT signal is not deglitched when the MOSFET is disabled due to an over-temperature condition, but is deglitched after the device has cooled and begins to turn on. This unidirectional deglitch prevents $\overline{\text{FAULT}}$ oscillation during an over-temperature event.

9.3.3 Undervoltage Lockout (UVLO)

The undervoltage lockout (UVLO) circuit disables the power switch until the input voltage reaches the UVLO turn-on threshold. Built-in hysteresis prevents unwanted on/off cycling due to input voltage droop during turn on.

9.3.4 Enable, (EN)

The logic enable controls the power switch and device supply current. The supply current is reduced to less than 0.5 μA .

The TPS25221 is active high logic, when a logic low is present on EN, the part is disabled. A logic high input on EN enables the driver, control circuits, and power switch. The enable input is compatible with both TTL and CMOS logic levels.

9.3.5 Thermal Sense

The TPS25221 has self-protection features using two independent thermal-sensing circuits that monitor the operating temperature of the power switch and disable operation if the temperature exceeds the Over Temperature Shutdown Threshold (OTSD). The TPS25221 device operates in constant-current mode during overload conditions, which increases the voltage drop across power-switch. Power dissipation in the package is proportional to the voltage drop across the power switch, which increases the junction temperature during an over-current condition. The first thermal sensor turns off the power switch when the die temperature exceeds 145°C (typical) and the part is in current limit. Hysteresis is built into the thermal sensor, and the switch turns on after the device has cooled approximately 20°C (typical). The TPS25221 continues to cycle off and on until the fault condition is removed.

The ambient thermal sensor turns off the power-switch when the junction temperature exceeds 165°C (typical) in non-current limit condition. The part will turn the switch back on once the junction temperature has cooled approximately 20°C (typical).

Feature Description (continued)

The open-drain fault reporting output $\overline{\text{FAULT}}$ is asserted (active low) immediately during an over-temperature shutdown condition.

9.4 Device Functional Modes

表 1. Protection Function Table

| EVENT | CONDITION | ACTION |
|--------------------|-----------------------------------|--|
| Overload on OUT | $I_{\text{LOAD}} > I_{\text{OS}}$ | The device outputs $I_{\text{OS}} \times R_{\text{LOAD}}$ until thermal shutdown. The fault indicator asserts when the over-current condition persists for more 8 ms, the fault does not de-assert until over-current is removed and persists for 8 ms. |
| Overheating | $T_J > 165\text{ C}$ | The device immediately shuts off the internal power switch and the fault indicator asserts immediately when the junction temperature exceeds 165°C (typical). The device has a thermal hysteresis of 20°C (typical). The fault indicator de-asserts when the junction temperature falls below 145°C (typical). |
| Undervoltage on IN | $V_{\text{IN}} < 2.37\text{ V}$ | The device immediately shuts off the internal current-limited switch. |

9.5 Programming

9.5.1 Programming the Current-Limit Threshold

The over-current threshold is user programmable through an external resistor. The TPS25221 uses an internal regulation loop to provide a regulated voltage on the ILIM pin. The current-limit threshold is proportional to the current sourced out of ILIM. The recommended 1% resistor range for R_{ILIM} is $20\text{ k}\Omega \leq R_{\text{ILIM}} \leq 210\text{ k}\Omega$ to ensure stability of the internal regulation loop. Many applications require that the minimum current limit is above a certain current level or that the maximum current limit is below a certain current level, so it is important to consider the tolerance of the over-current threshold when selecting a value for R_{ILIM} . The following equations and [Figure 24](#) can be used to calculate the resulting over-current threshold for a given external resistor value (R_{ILIM}). [Figure 24](#) includes current-limit tolerance due to variations caused by temperature and process. However, the equations do not account for tolerance due to external resistor variation, so it is important to account for this tolerance when selecting R_{ILIM} . The traces routing the R_{ILIM} resistor to the TPS25221 must be as short as possible to reduce parasitic effects on the current-limit accuracy.

R_{ILIM} can be selected to provide a current-limit threshold that occurs: 1) above a minimum load current or 2) below a maximum load current.

To design above a minimum current-limit threshold, find the intersection of R_{ILIM} and the maximum desired load current on the $I_{\text{OS}(\text{min})}$ curve and choose a value of R_{ILIM} below this value. Programming the current limit above a minimum threshold is important to ensure start-up into full load or heavy capacitive loads. The resulting maximum current-limit threshold is the intersection of the selected value of R_{ILIM} and the $I_{\text{OS}(\text{max})}$ curve.

To design below a maximum current-limit threshold, find the intersection of R_{ILIM} and the maximum desired load current on the $I_{\text{OS}(\text{max})}$ curve and choose a value of R_{ILIM} above this value. Programming the current limit below a maximum threshold is important to avoid current limiting upstream power supplies, causing the input voltage bus to droop. The resulting minimum current-limit threshold is the intersection of the selected value of R_{ILIM} and the $I_{\text{OS}(\text{min})}$ curve.

Current-Limit Threshold Equation (I_{OS}):

$$I_{\text{OSmax}}(\text{mA}) = \frac{52640\text{V}}{R_{\text{ILIM}}^{0.97}\text{k}\Omega}$$

$$I_{\text{OSnom}}(\text{mA}) = \frac{55960\text{V}}{R_{\text{ILIM}}^{1.004}\text{k}\Omega}$$

$$I_{\text{OSmin}}(\text{mA}) = \frac{56850\text{V}}{R_{\text{ILIM}}^{1.033}\text{k}\Omega}$$

where:

$$20\text{ k}\Omega \leq R_{\text{ILIM}} \leq 210\text{ k}\Omega.$$

(1)

Programming (continued)

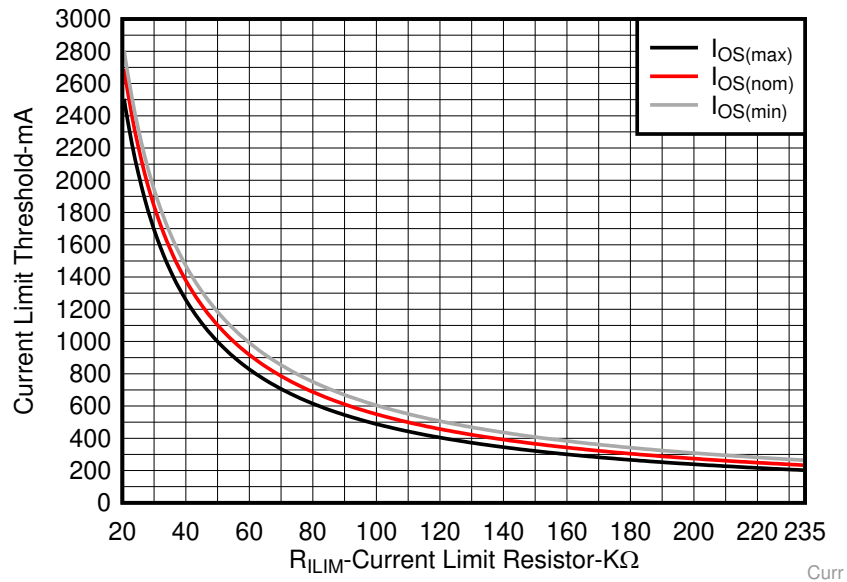


Figure 24. Current-Limit Threshold vs Current-Limit Resistor (R_{ILIM})

10 Application and Implementation

注

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

10.1 Application Information

10.1.1 Constant-Current

During normal operation, the TPS25221 load current is less than the current-limit threshold and the device is not limiting current. During normal operation the N-channel MOSFET is fully enhanced, and $V_{OUT} = V_{IN} - (I_{OUT} \times r_{DS(on)})$. The voltage drop across the MOSFET is relatively small compared to V_{IN} , and V_{OUT} is approximately equal to V_{IN} .

The TPS25221 limits current to the programmed current-limit threshold, set by R_{ILIM}, reducing gate drive to the internal NFET, which increases R_{ds(on)} and reduces load current. This allows the device to effectively regulate the current to the current-limit threshold. Increasing the resistance of the MOSFET means that the voltage drop across the device is no longer negligible ($V_{IN} \neq V_{OUT}$), and V_{OUT} decreases. The amount that V_{OUT} decreases is proportional to the magnitude of the overload condition. The expected V_{OUT} can be calculated by:

$$I_{OS} \times R_{LOAD}$$

where:

$$I_{OS} \text{ is the current-limit threshold and } R_{LOAD} \text{ is the magnitude of the overload condition.} \tag{2}$$

For example, if I_{OS} is programmed to 1 A and a 1 Ω overload condition is applied, the resulting V_{OUT} is 1 V.

While in current limit the power dissipation in the package can raise the die temperature above the thermal shutdown threshold (145°C typical), and the device turns off until the die temperature decreases by the hysteresis of the thermal shutdown circuit (20°C typical). The device then turns on and continues to thermal cycle until the overload condition is removed.

10.2 Typical Applications

10.2.1 Two-Level Current-Limit Circuit

Some applications require different current-limit thresholds depending on external system conditions. [Figure 25](#) shows an implementation for an externally controlled, two-level current-limit circuit. The current-limit threshold is set by the total resistance from ILIM to GND (see the [Programming the Current-Limit Threshold](#) section). A logic-level input enables or disables MOSFET Q1 and changes the current-limit threshold by modifying the total resistance from ILIM to GND. Additional MOSFET and resistor combinations can be used in parallel to Q1/R2 to increase the number of additional current-limit levels.

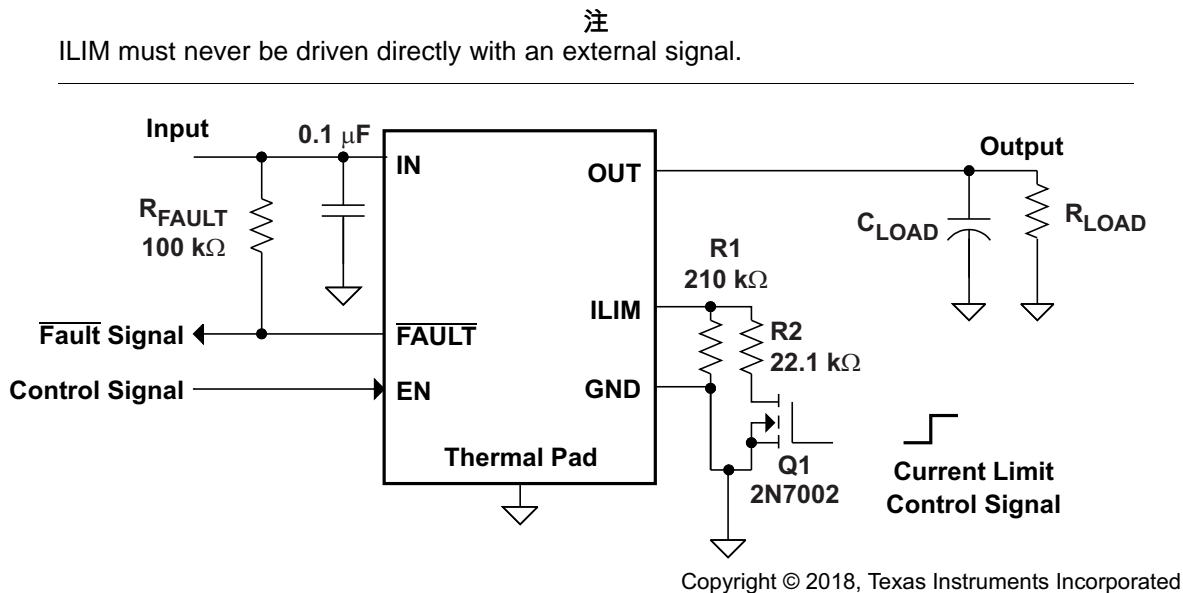


Figure 25. Two-Level Current-Limit Circuit

10.2.1.1 Design Requirements

For this example, use the parameters shown in [Table 2](#).

Table 2. Design Requirements

| PARAMETER | VALUE |
|-------------------------------|---------|
| Input voltage | 5 V |
| Output voltage | 5 V |
| Above a minimum current limit | 1000 mA |
| Below a maximum current limit | 500 mA |

10.2.1.2 Detailed Design Procedures

10.2.1.2.1 Designing Above a Minimum Current Limit

Some applications require that current limiting cannot occur below a certain threshold. For this example, assume that 1 A must be delivered to the load so that the minimum desired current-limit threshold is 1000 mA. Use the I_{OS} equations and [Figure 24](#) to select R_{ILIM} .

$$\begin{aligned}
 I_{OSmin} \text{ (mA)} &= 1000\text{mA} \\
 I_{OSmin} \text{ (mA)} &= \frac{56850\text{V}}{R_{ILIM}^{1.033}\text{k}\Omega} \\
 R_{ILIM} \text{ (k}\Omega) &= \left(\frac{56850\text{V}}{I_{OSmin}\text{mA}} \right)^{\frac{1}{1.033}} \\
 R_{ILIM} \text{ (k}\Omega) &= 50\text{k}\Omega
 \end{aligned} \tag{3}$$

Select the closest 1% resistor less than the calculated value: $R_{ILIM} = 49.9 \text{ k}\Omega$. This sets the minimum current-limit threshold at 1 A . Use the I_{OS} equations, [Figure 24](#), and the previously calculated value for R_{ILIM} to calculate the maximum resulting current-limit threshold.

$$\begin{aligned}
 R_{ILIM} \text{ (k}\Omega) &= 49.9\text{k}\Omega \\
 I_{OSmax} \text{ (mA)} &= \frac{52640\text{V}}{R_{ILIM}^{0.97}\text{k}\Omega} \\
 I_{OSmax} \text{ (mA)} &= \frac{52640\text{V}}{49.9^{0.97}\text{k}\Omega} \\
 I_{OSmax} \text{ (mA)} &= 1186\text{mA}
 \end{aligned} \tag{4}$$

The resulting maximum current-limit threshold is 1186 mA with a 49.9 k Ω resistor.

10.2.1.2.2 Designing Below a Maximum Current Limit

Some applications require that current limiting must occur below a certain threshold. For this example, assume that the desired upper current-limit threshold must be below 500 mA to protect an up-stream power supply. Use the I_{OS} equations and [Figure 24](#) to select R_{ILIM} .

$$\begin{aligned}
 I_{OSmax} \text{ (mA)} &= 500\text{mA} \\
 I_{OSmax} \text{ (mA)} &= \frac{52640\text{V}}{R_{ILIM}^{0.97}\text{k}\Omega} \\
 R_{ILIM} \text{ (k}\Omega) &= \left(\frac{52640\text{V}}{I_{OSmax}\text{mA}} \right)^{\frac{1}{0.97}} \\
 R_{ILIM} \text{ (k}\Omega) &= 121.6\text{k}\Omega
 \end{aligned} \tag{5}$$

Select the closest 1% resistor greater than the calculated value: $R_{ILIM} = 124 \text{ k}\Omega$. This sets the maximum current-limit threshold at 500 mA . Use the I_{OS} equations, [Figure 24](#), and the previously calculated value for R_{ILIM} to calculate the minimum resulting current-limit threshold.

$$\begin{aligned}
 R_{ILIM} \text{ (k}\Omega) &= 124\text{k}\Omega \\
 I_{OSmin} \text{ (mA)} &= \frac{56850\text{V}}{R_{ILIM}^{1.033}\text{k}\Omega} \\
 I_{OSmin} \text{ (mA)} &= \frac{56850\text{V}}{124^{1.033}\text{k}\Omega} \\
 I_{OSmin} \text{ (mA)} &= 391\text{mA}
 \end{aligned} \tag{6}$$

The resulting minimum current-limit threshold is 391 mA with a 124 k Ω resistor.

10.2.1.2.3 Accounting for Resistor Tolerance

The previous sections described the selection of R_{ILIM} given certain application requirements and the importance of understanding the current-limit threshold tolerance. The analysis focused only on TPS25221 performance and assumed an exact resistor value. However, resistors sold in quantity are not exact and are bounded by an upper and lower tolerance centered around a nominal resistance. The additional R_{ILIM} resistance tolerance directly affects the current-limit threshold accuracy at a system level. The following table shows a process that accounts

for worst-case resistor tolerance assuming 1% resistor values. Step one follows the selection process outlined in the application examples above. Step two determines the upper and lower resistance bounds of the selected resistor. Step three uses the upper and lower resistor bounds in the I_{OS} equations to calculate the threshold limits. It is important to use tighter tolerance resistors, for example, 0.5% or 0.1%, when precision current limiting is desired.

表 3. Common R_{ILIM} Resistor Selections

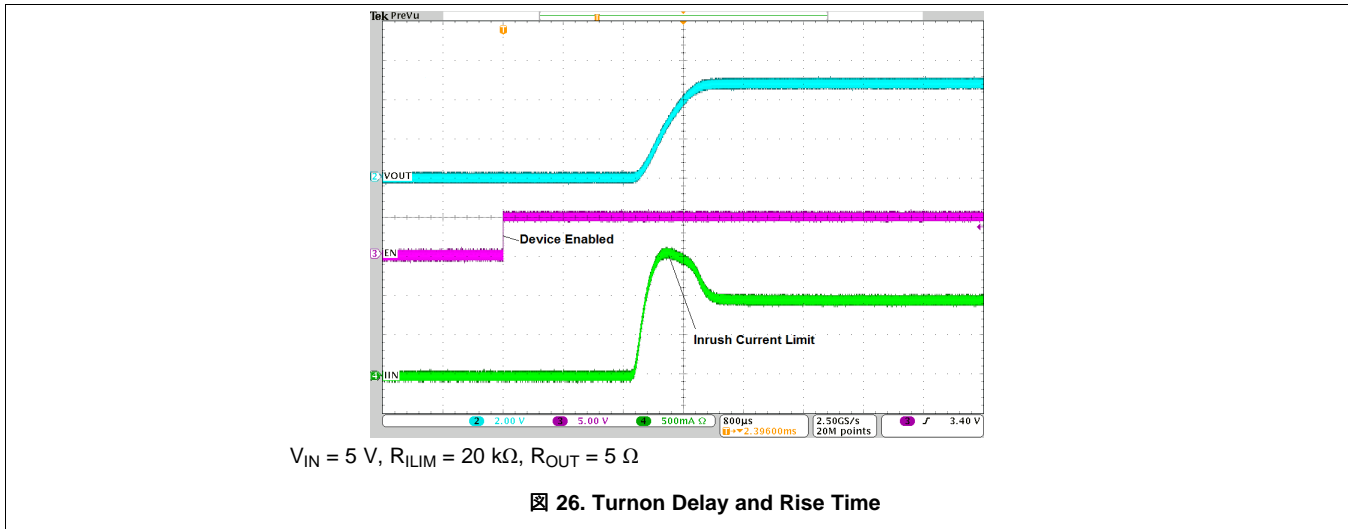
| DESIRED NOMINAL CURRENT LIMIT (mA) | IDEAL RESISTOR (k Ω) | CLOSEST 1% RESISTOR (k Ω) | RESISTOR TOLERANCE | | ACTUAL LIMITS | | |
|--|------------------------------------|---|----------------------|-----------------------|--------------------|--------------------|--------------------|
| | | | 1% LOW (k Ω) | 1% HIGH (k Ω) | $I_{OS(min)}$ (mA) | $I_{OS(nom)}$ (mA) | $I_{OS(max)}$ (mA) |
| 275 | 199.2 | 200 | 198 | 202 | 236 | 274 | 312 |
| 400 | 137.2 | 137 | 135.6 | 138.4 | 349 | 401 | 450 |
| 500 | 109.8 | 110 | 108.9 | 111.1 | 438 | 499 | 556 |
| 600 | 91.6 | 90.9 | 90.0 | 91.8 | 533 | 605 | 669 |
| 700 | 78.6 | 78.7 | 77.9 | 79.5 | 619 | 699 | 770 |
| 800 | 68.8 | 68.1 | 67.4 | 68.8 | 719 | 808 | 886 |
| 900 | 61.2 | 61.9 | 61.3 | 62.5 | 793 | 889 | 972 |
| 1000 | 55.1 | 54.9 | 54.4 | 55.4 | 898 | 1003 | 1092 |
| 1200 | 45.9 | 46.4 | 45.9 | 46.9 | 1068 | 1188 | 1285 |
| 1400 | 39.4 | 39.2 | 38.8 | 39.6 | 1272 | 1407 | 1514 |
| 1600 | 34.5 | 34.8 | 34.5 | 35.1 | 1438 | 1585 | 1699 |
| 1800 | 30.7 | 30.9 | 30.6 | 31.2 | 1626 | 1786 | 1907 |
| 2000 | 27.6 | 27.4 | 27.1 | 27.7 | 1841 | 2015 | 2143 |
| 2200 | 25.1 | 24.9 | 24.7 | 25.1 | 2032 | 2219 | 2351 |
| 2400 | 23.0 | 23.2 | 23.0 | 23.4 | 2186 | 2382 | 2518 |
| 2600 | 21.3 | 21.5 | 21.3 | 21.7 | 2365 | 2571 | 2711 |
| 2700 | 20.5 | 20.5 | 20.3 | 20.7 | 2484 | 2697 | 2839 |

10.2.1.2.4 Input and Output Capacitance

Input and output capacitance improves the performance of the device; the actual capacitance must be optimized for the particular application. For all applications, TI recommends placing a 0.1 μ F or greater ceramic bypass capacitor between IN and GND as close to the device as possible for local noise de-coupling. This precaution reduces ringing on the input due to power-supply transients. Additional input capacitance may be needed on the input to reduce voltage overshoot from exceeding the absolute maximum voltage of the device during heavy transient conditions. This is especially important during bench testing when long, inductive cables are used to connect the evaluation board to the bench power-supply.

TI recommends placing a high-value electrolytic capacitor on the output pin when large transient currents are expected on the output.

10.2.1.3 Application Curve



10.2.2 Auto-Retry Functionality

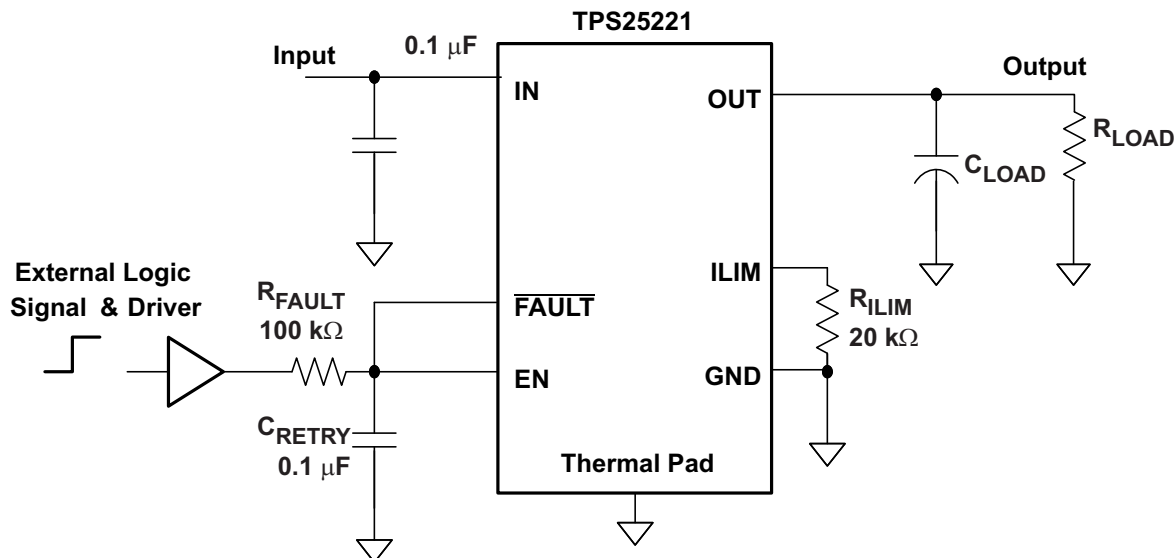
Some applications require that an over-current condition disables the part momentarily during a fault condition and re-enables after a pre-set time. This *auto-retry* functionality can be implemented with an external resistor and capacitor. During a fault condition, $\overline{\text{FAULT}}$ pulls low disabling the part. The part is disabled when EN is pulled low, and $\overline{\text{FAULT}}$ goes high impedance allowing C_{RETRY} to begin charging. The part re-enables when the voltage on EN reaches the turn-on threshold, and the auto-retry time is determined by the resistor-capacitor time constant. The device continues to cycle in this manner until the fault condition is removed.



Copyright © 2018, Texas Instruments Incorporated

Figure 27. Auto-Retry Functionality

Some applications require auto-retry functionality and the ability to enable or disable with an external logic signal. [Figure 28](#) shows how an external logic signal can drive EN through R_{FAULT} and maintain auto-retry functionality. The resistor-capacitor time constant determines the auto-retry time-out period.



Copyright © 2018, Texas Instruments Incorporated

图 28. Auto-Retry Functionality With External EN Signal

10.2.2.1 Design Requirements (added)

For this example, use the parameters shown in 表 4.

表 4. Design Requirements

| PARAMETER | VALUE |
|-------------------------------|---------|
| Input voltage | 5 V |
| Output voltage | 5 V |
| Above a minimum current limit | 1000 mA |
| Below a maximum current limit | 500 mA |

10.2.2.2 Detailed Design Procedure

Refer to [Programming the Current-Limit Threshold](#) section for the current limit setting. For auto-retry functionality, once $\overline{\text{FAULT}}$ asserted, EN pull low, TPS25221 is disabled, $\overline{\text{FAULT}}$ des-asserted, C_{RETRY} is slowly charged to EN logic high through R_{FAULT} , then enable, after deglitch time, $\overline{\text{FAULT}}$ asserted again. In the event of an overload, TPS25221 cycles and has output average current. ON-time with output current is decided by $\overline{\text{FAULT}}$ deglitch time. OFF-time without output current is decided by $R_{\text{FAULT}} \times C_{\text{RETRY}}$ constant time to EN logic high and t_{on} time. Therefore, set the $R_{\text{FAULT}} \times C_{\text{RETRY}}$ to get the desired output average current during overload.

10.2.3 Typical Application as USB Power Switch



图 29. Typical Application as USB Power Switch

10.2.3.1 Design Requirements

For this example, use the parameters shown in 表 5.

表 5. Design Requirements

| PARAMETER | VALUE |
|----------------|---------|
| Input voltage | 5 V |
| Output voltage | 5 V |
| Current | 1200 mA |

10.2.3.1.1 USB Power-Distribution Requirements

USB can be implemented in several ways regardless of the type of USB device being developed. Several power-distribution features must be implemented.

- Self Powered Hub (SPH) must:
 - Current limit downstream ports
 - Report over-current conditions
- Bus Powered Hub (BPH) must:
 - Enable or disable power to downstream ports
 - Power up at <100 mA
 - Limit inrush current (<44 Ω and 10 μF)
- Functions must:
 - Limit inrush currents
 - Power up at <100 mA

The feature set of the TPS25221 meets each of these requirements. The integrated current limiting and over-current reporting is required by self-powered hubs. The logic-level enable and controlled rise times meet the need of both input and output ports on bus-powered hubs and the input ports for bus-powered functions.

10.2.3.2 Detailed Design Procedure

10.2.3.2.1 Universal Serial Bus (USB) Power-Distribution Requirements

One application for this device is for current limiting in universal serial bus (USB) applications. The original USB interface was a 12-Mbps or 1.5-Mbps, multiplexed serial bus designed for low-to-medium bandwidth PC peripherals (for example, keyboards, printers, scanners, and mice). As the demand for more bandwidth increased, the USB 2.0 standard was introduced increasing the maximum data rate to 480 Mbps. The four-wire USB interface is conceived for dynamic attach-detach (hot plug-unplug) of peripherals. Two lines are provided for differential data, and two lines are provided for 5-V power distribution.

USB data is a 3.3-V level signal, but power is distributed at 5 V to allow for voltage drops in cases where power is distributed through more than one hub across long cables. Each function must provide its own regulated 3.3 V from the 5-V input or its own internal power supply. The USB specification classifies two different classes of devices depending on its maximum current draw. A device classified as low-power can draw up to 100 mA as defined by the standard. A device classified as high-power can draw up to 500 mA. It is important that the minimum current-limit threshold of the current-limiting power-switch exceed the maximum current-limit draw of the intended application. The latest USB standard must always be referenced when considering the current-limit threshold.

The USB specification defines two types of devices as hubs and functions. A USB hub is a device that contains multiple ports for different USB devices to connect and can be self-powered (SPH) or bus-powered (BPH). A function is a USB device that is able to transmit or receive data or control information over the bus. A USB function can be embedded in a USB hub. A USB function can be one of three types included in the list below.

- Low-power, bus-powered function
- High-power, bus-powered function
- Self-powered function

SPHs and BPHs distribute data and power to downstream functions. The TPS25221 has higher current capability than required for a single USB port allowing it to power multiple downstream ports.

11 Power Supply Recommendations

11.1 Self-Powered and Bus-Powered Hubs

A SPH has a local power supply that powers embedded functions and downstream ports. This power supply must provide between 4.75 V to 5.25 V to downstream facing devices under full-load and no-load conditions. SPHs are required to have current-limit protection and must report over-current conditions to the USB controller. Typical SPHs are desktop PCs, monitors, printers, and stand-alone hubs.

A BPH obtains all power from an upstream port and often contains an embedded function. It must power up with less than 100 mA. The BPH usually has one embedded function, and power is always available to the controller of the hub. If the embedded function and hub require more than 100 mA on power up, keep the power to the embedded function off until enumeration is completed. This can be accomplished by removing power or by shutting off the clock to the embedded function. Power-switching the embedded function is not necessary if the aggregate power draw for the function and controller is less than 100 mA. The total current drawn by the bus-powered device is the sum of the current to the controller, the embedded function, and the downstream ports, and it is limited to 500 mA from an upstream port.

11.2 Low-Power Bus-Powered and High-Power Bus-Powered Functions

Both low-power and high-power bus-powered functions obtain all power from upstream ports. Low-power functions always draw less than 100 mA; high-power functions must draw less than 100 mA at power up and can draw up to 500 mA after enumeration. If the load of the function is more than the parallel combination of 44 Ω and 10 μF at power up, the device must implement inrush current limiting.

11.3 Power Dissipation and Junction Temperature

The low ON-resistance of the N-channel MOSFET allows small surface-mount packages to pass large currents. It is required design practice to determine power dissipation and junction temperature. The below analysis gives an approximation for calculating junction temperature based on the power dissipation in the package. However, it is important to note that thermal analysis is strongly dependent on additional system level factors. Such factors include air flow, board layout, copper thickness and surface area, and proximity to other devices dissipating power. Good thermal design practice must include all system level factors in addition to individual component analysis.

Begin by determining the $r_{\text{DS(on)}}$ of the N-channel MOSFET relative to the input voltage and operating temperature. As an initial estimate, use the highest operating ambient temperature expected and read $r_{\text{DS(on)}}$ from the typical characteristics graph. Using this value, the power dissipation can be calculated using 式 7:

Power Dissipation and Junction Temperature (continued)

$$P_D = r_{DS(on)} \times I_{OUT}^2$$

where

- P_D = Total power dissipation (W)
- $r_{DS(on)}$ = Power switch on-resistance (Ω)
- I_{OUT} = Maximum current-limit threshold (A)
- This step calculates the total power dissipation of the N-channel MOSFET. (7)

Finally, calculate the junction temperature:

$$T_J = P_D \times \theta_{JA} + T_A$$

where

- T_A = Ambient temperature ($^{\circ}\text{C}$)
- θ_{JA} = Thermal resistance ($^{\circ}\text{C}/\text{W}$)
- P_D = Total power dissipation (W) (8)

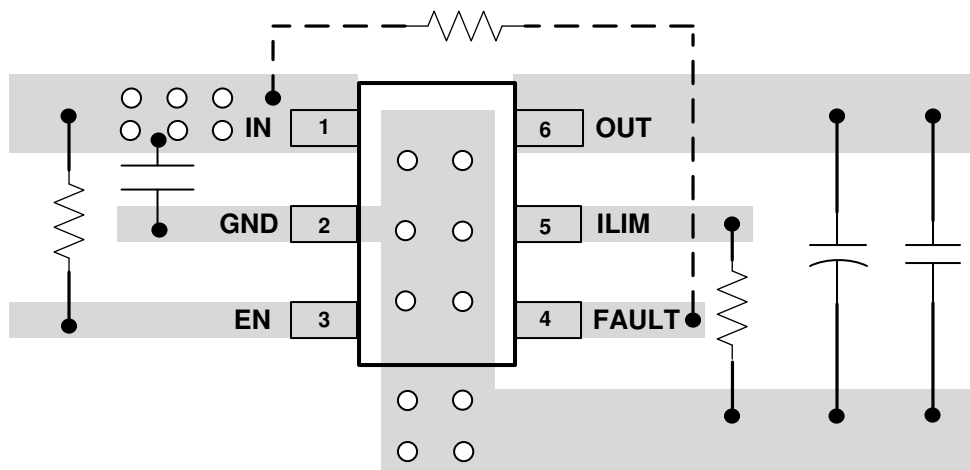
Compare the calculated junction temperature with the initial estimate. If they are not within a few degrees, repeat the calculation using the *refined* $r_{DS(on)}$ from the previous calculation as the new estimate. Two or three iterations are generally sufficient to achieve the desired result. The final junction temperature is highly dependent on thermal resistance θ_{JA} , and thermal resistance is highly dependent on the individual package and board layout. The table provides example thermal resistances for specific packages and board layouts.

12 Layout

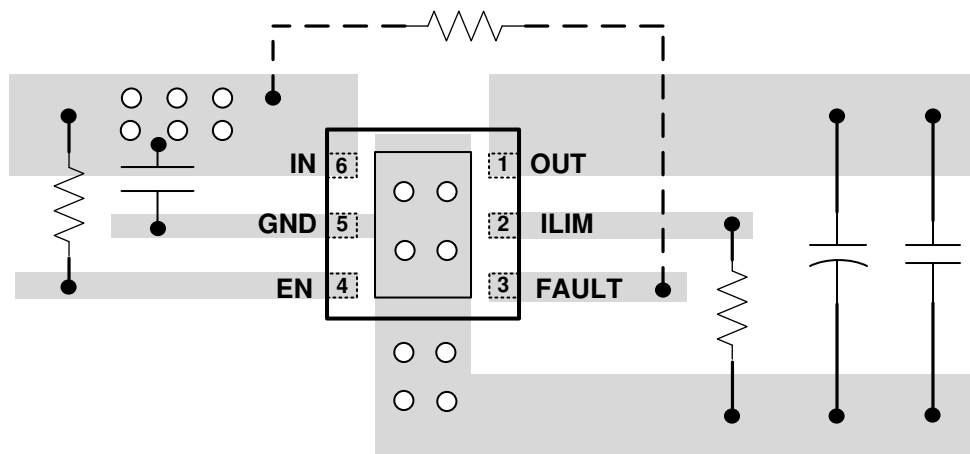
12.1 Layout Guidelines

- TI recommends placing the 100-nF bypass capacitor near the IN and GND pins, and make the connections using a low-inductance trace.
- TI recommends placing a high-value electrolytic capacitor and a 100-nF bypass capacitor on the output pin when large transient currents are expected on the output.
- The traces routing the RILIM resistor to the device must be as short as possible to reduce parasitic effects on the current limit accuracy.
- The thermal pad must be directly connected to PCB ground plane using wide and short copper trace.

12.2 Layout Example



☒ 30. TPS25221DBV Board Layout



☒ 31. TPS25221DRV Board Layout

13 デバイスおよびドキュメントのサポート

13.1 デバイス・サポート

13.1.1 デベロッパー・ネットワークの製品に関する免責事項

デベロッパー・ネットワークの製品またはサービスに関するTIの出版物は、単独またはTIの製品、サービスと一緒に提供される場合に関係なく、デベロッパー・ネットワークの製品またはサービスの適合性に関する是認、デベロッパー・ネットワークの製品またはサービスの是認の表明を意味するものではありません。

13.2 ドキュメントのサポート

13.2.1 関連資料

関連資料については、以下を参照してください。

- 『TPS25221評価基板 ユーザー・ガイド』(SLVUBD1)

13.3 ドキュメントの更新通知を受け取る方法

ドキュメントの更新についての通知を受け取るには、ti.comのデバイス製品フォルダを開いてください。右上の「アラートを受け取る」をクリックして登録すると、変更されたすべての製品情報に関するダイジェストを毎週受け取れます。変更の詳細については、修正されたドキュメントに含まれている改訂履歴をご覧ください。

13.4 コミュニティ・リソース

[TI E2E™ support forums](#) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

13.5 商標

E2E is a trademark of Texas Instruments.

13.6 静電気放電に関する注意事項



すべての集積回路は、適切なESD保護方法を用いて、取扱いと保存を行うようにして下さい。

静電気放電はわずかな性能の低下から完全なデバイスの故障に至るまで、様々な損傷を与えます。高精度の集積回路は、損傷に対して敏感であり、極めてわずかなパラメータの変化により、デバイスに規定された仕様に適合しなくなる場合があります。

13.7 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

14 メカニカル、パッケージ、および注文情報

以降のページには、メカニカル、パッケージ、および注文に関する情報が記載されています。この情報は、そのデバイスについて利用可能な最新のデータです。このデータは予告なく変更されることがあり、ドキュメントが改訂される場合もあります。本データシートのブラウザ版を使用されている場合は、画面左側の説明をご覧ください。

PACKAGING INFORMATION

| Orderable part number | Status (1) | Material type (2) | Package Pins | Package qty Carrier | RoHS (3) | Lead finish/ Ball material (4) | MSL rating/ Peak reflow (5) | Op temp (°C) | Part marking (6) |
|------------------------------|---------------|----------------------|------------------|-----------------------|-------------|--------------------------------------|-----------------------------------|--------------|---------------------|
| TPS25221DBVR | Active | Production | SOT-23 (DBV) 6 | 3000 LARGE T&R | Yes | NIPDAU SN | Level-1-260C-UNLIM | -40 to 125 | 1B4F |
| TPS25221DBVR.A | Active | Production | SOT-23 (DBV) 6 | 3000 LARGE T&R | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 1B4F |
| TPS25221DBVT | Active | Production | SOT-23 (DBV) 6 | 250 SMALL T&R | Yes | NIPDAU SN | Level-1-260C-UNLIM | -40 to 125 | 1B4F |
| TPS25221DBVT.A | Active | Production | SOT-23 (DBV) 6 | 250 SMALL T&R | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 1B4F |
| TPS25221DRVR | Active | Production | WSON (DRV) 6 | 3000 LARGE T&R | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 1C7H |
| TPS25221DRVR.A | Active | Production | WSON (DRV) 6 | 3000 LARGE T&R | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 1C7H |
| TPS25221DRVRG4 | Active | Production | WSON (DRV) 6 | 3000 LARGE T&R | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 1C7H |
| TPS25221DRVRG4.A | Active | Production | WSON (DRV) 6 | 3000 LARGE T&R | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 1C7H |
| TPS25221DRVT | Active | Production | WSON (DRV) 6 | 250 SMALL T&R | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 1C7H |
| TPS25221DRVT.A | Active | Production | WSON (DRV) 6 | 250 SMALL T&R | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 1C7H |

(1) **Status:** For more details on status, see our [product life cycle](#).

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

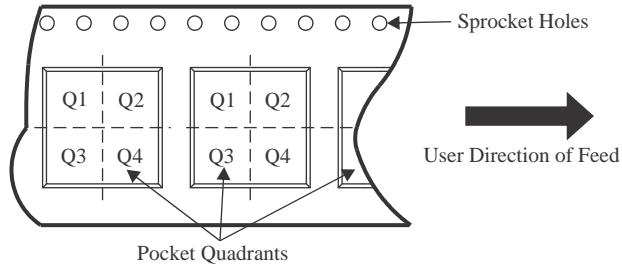
Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative

and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

TAPE AND REEL INFORMATION

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE


*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|----------------|--------------|-----------------|------|------|--------------------|--------------------|---------|---------|---------|---------|--------|---------------|
| TPS25221DBVR | SOT-23 | DBV | 6 | 3000 | 180.0 | 8.4 | 3.2 | 3.2 | 1.4 | 4.0 | 8.0 | Q3 |
| TPS25221DBVT | SOT-23 | DBV | 6 | 250 | 180.0 | 8.4 | 3.23 | 3.17 | 1.37 | 4.0 | 8.0 | Q3 |
| TPS25221DBVT | SOT-23 | DBV | 6 | 250 | 180.0 | 8.4 | 3.2 | 3.2 | 1.4 | 4.0 | 8.0 | Q3 |
| TPS25221DRVR | WSON | DRV | 6 | 3000 | 178.0 | 8.4 | 2.25 | 2.25 | 1.0 | 4.0 | 8.0 | Q2 |
| TPS25221DRVR | WSON | DRV | 6 | 3000 | 180.0 | 8.4 | 2.3 | 2.3 | 1.15 | 4.0 | 8.0 | Q2 |
| TPS25221DRVRG4 | WSON | DRV | 6 | 3000 | 180.0 | 8.4 | 2.3 | 2.3 | 1.15 | 4.0 | 8.0 | Q2 |
| TPS25221DRVT | WSON | DRV | 6 | 250 | 180.0 | 8.4 | 2.3 | 2.3 | 1.15 | 4.0 | 8.0 | Q2 |

TAPE AND REEL BOX DIMENSIONS


*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
|----------------|--------------|-----------------|------|------|-------------|------------|-------------|
| TPS25221DBVR | SOT-23 | DBV | 6 | 3000 | 210.0 | 185.0 | 35.0 |
| TPS25221DBVT | SOT-23 | DBV | 6 | 250 | 183.0 | 183.0 | 20.0 |
| TPS25221DBVT | SOT-23 | DBV | 6 | 250 | 210.0 | 185.0 | 35.0 |
| TPS25221DRVR | WSON | DRV | 6 | 3000 | 205.0 | 200.0 | 33.0 |
| TPS25221DRVR | WSON | DRV | 6 | 3000 | 210.0 | 185.0 | 35.0 |
| TPS25221DRVRG4 | WSON | DRV | 6 | 3000 | 210.0 | 185.0 | 35.0 |
| TPS25221DRVT | WSON | DRV | 6 | 250 | 210.0 | 185.0 | 35.0 |

GENERIC PACKAGE VIEW

DRV 6

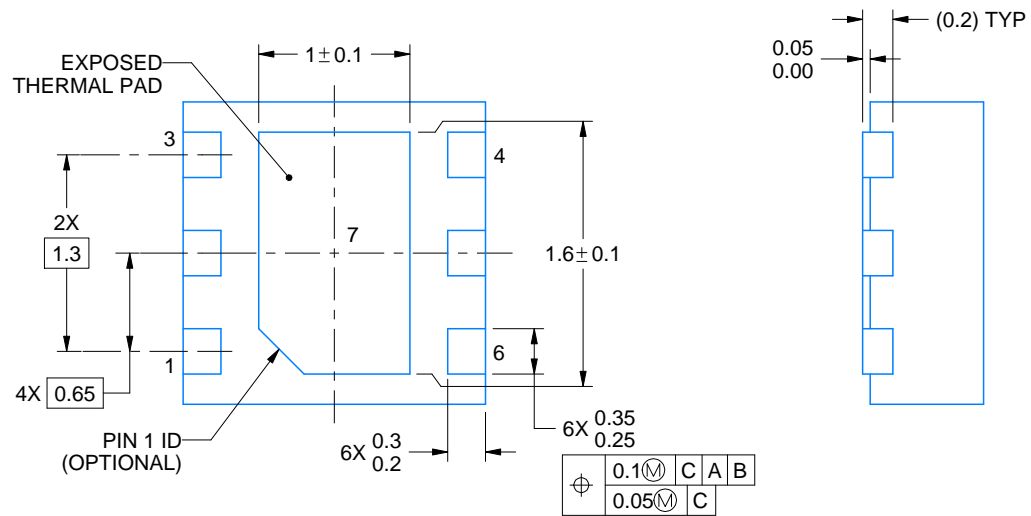
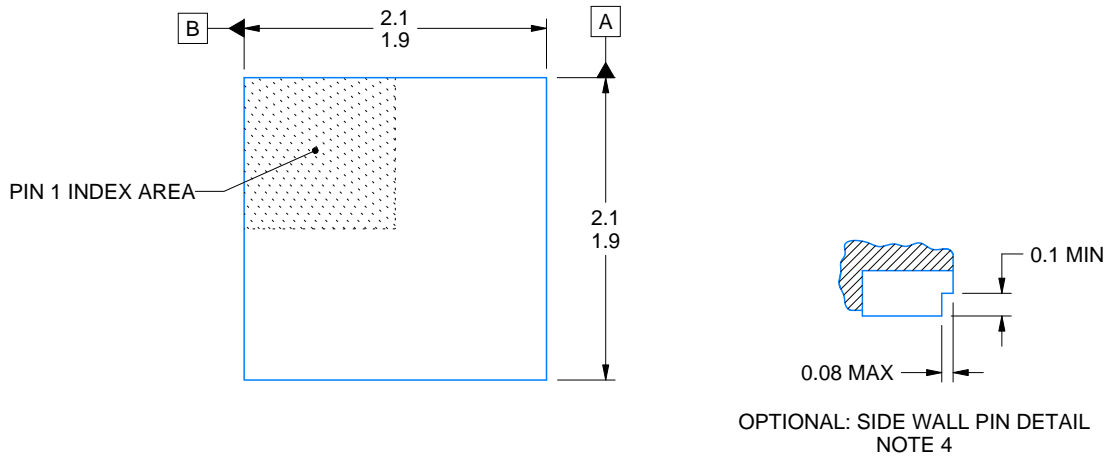
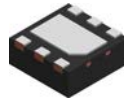
WSON - 0.8 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



Images above are just a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.

4206925/F



4222173/C 11/2025

NOTES:

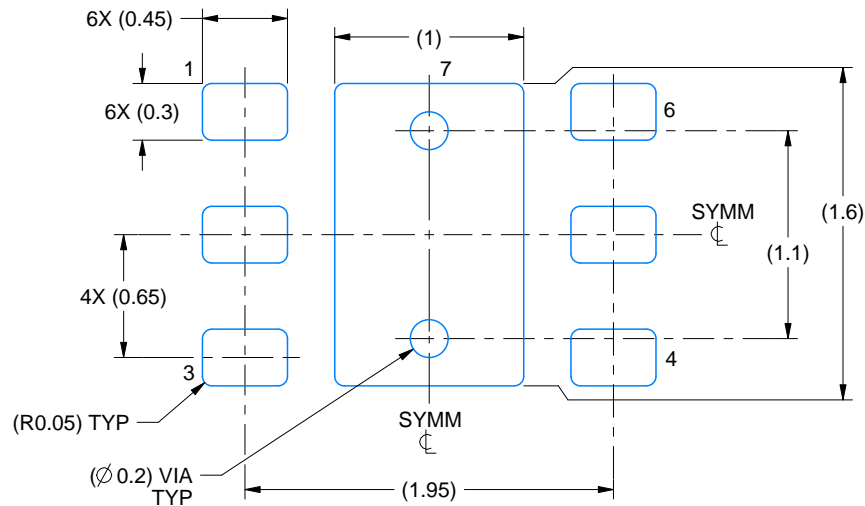
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.
4. Minimum 0.1 mm solder wetting on pin side wall. Available for wettable flank version only.

EXAMPLE BOARD LAYOUT

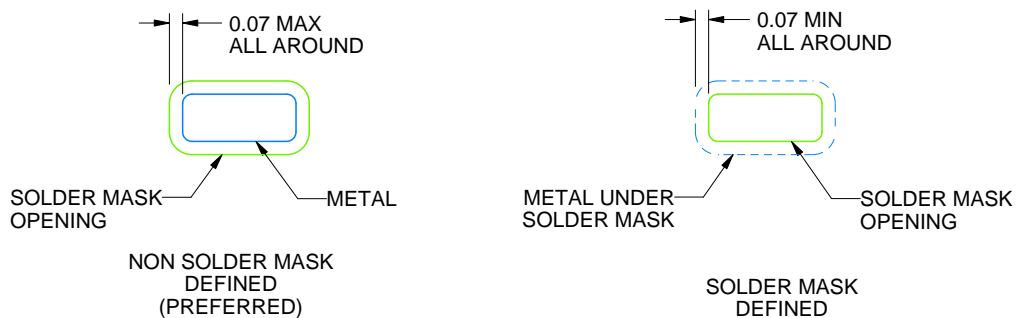
DRV0006A

WSON - 0.8 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



LAND PATTERN EXAMPLE
SCALE:25X



SOLDER MASK DETAILS

4222173/C 11/2025

NOTES: (continued)

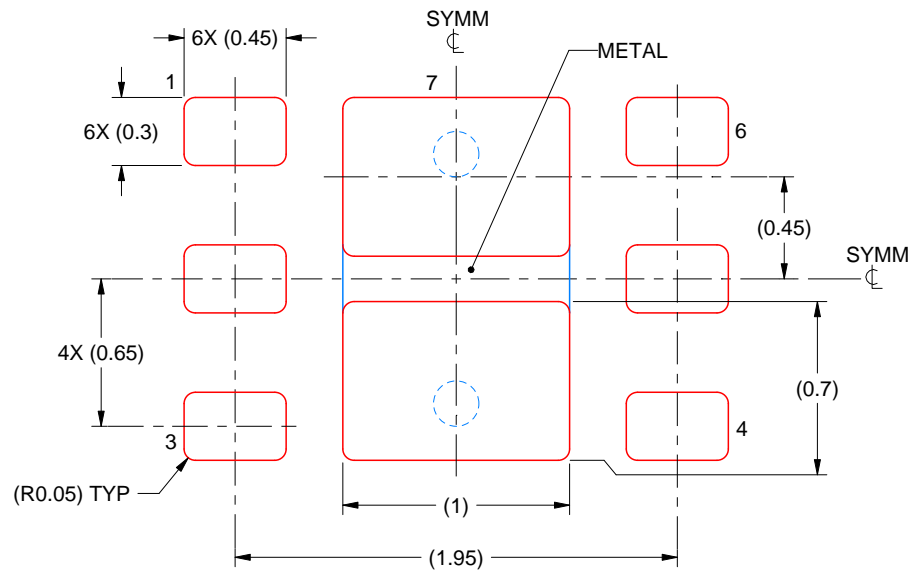
5. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
6. Vias are optional depending on application, refer to device data sheet. If some or all are implemented, recommended via locations are shown.

EXAMPLE STENCIL DESIGN

DRV0006A

WSON - 0.8 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD #7
88% PRINTED SOLDER COVERAGE BY AREA UNDER PACKAGE
SCALE:30X

4222173/C 11/2025

NOTES: (continued)

7. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

EXAMPLE BOARD LAYOUT

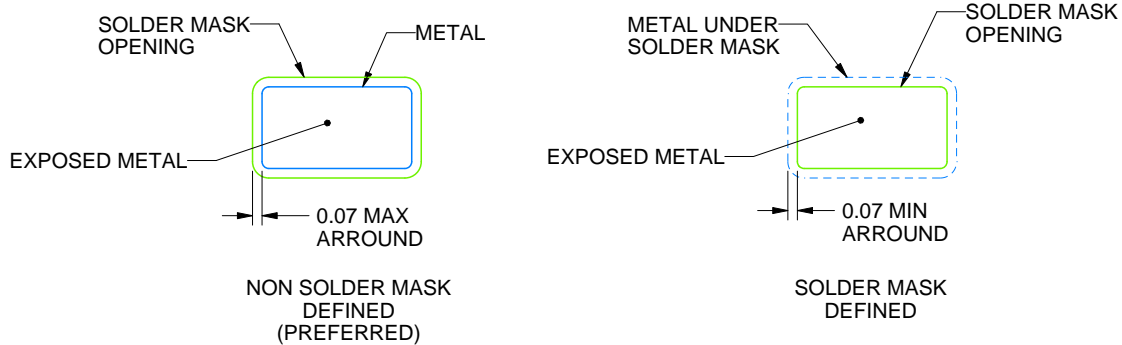
DBV0006A

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:15X



SOLDER MASK DETAILS

4214840/G 08/2024

NOTES: (continued)

- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

DBV0006A

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL
SCALE:15X

4214840/G 08/2024

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

重要なお知らせと免責事項

TI は、技術データと信頼性データ (データシートを含みます)、設計リソース (リファレンス デザインを含みます)、アプリケーションや設計に関する各種アドバイス、Web ツール、安全性情報、その他のリソースを、欠陥が存在する可能性のある「現状のまま」提供しており、商品性および特定目的に対する適合性の黙示保証、第三者の知的財産権の非侵害保証を含むいかなる保証も、明示的または黙示的にかかわらず拒否します。

これらのリソースは、TI 製品を使用する設計の経験を積んだ開発者への提供を意図したものです。(1) お客様のアプリケーションに適した TI 製品の選定、(2) お客様のアプリケーションの設計、検証、試験、(3) お客様のアプリケーションに該当する各種規格や、その他のあらゆる安全性、セキュリティ、規制、または他の要件への確実な適合に関する責任を、お客様のみが単独で負うものとし、

上記の各種リソースは、予告なく変更される可能性があります。これらのリソースは、リソースで説明されている TI 製品を使用するアプリケーションの開発の目的でのみ、TI はその使用をお客様に許諾します。これらのリソースに関して、他の目的で複製することや掲載することは禁止されています。TI や第三者の知的財産権のライセンスが付与されている訳ではありません。お客様は、これらのリソースを自身で使用した結果発生するあらゆる申し立て、損害、費用、損失、責任について、TI およびその代理人を完全に補償するものとし、TI は一切の責任を拒否します。

TI の製品は、[TI の販売条件](#)、[TI の総合的な品質ガイドライン](#)、[ti.com](#) または TI 製品などに関連して提供される他の適用条件に従い提供されます。TI がこれらのリソースを提供することは、適用される TI の保証または他の保証の放棄の拡大や変更を意味するものではありません。TI がカスタム、またはカスタマー仕様として明示的に指定していない限り、TI の製品は標準的なカタログに掲載される汎用機器です。

お客様がいかなる追加条項または代替条項を提案する場合も、TI はそれらに異議を唱え、拒否します。

Copyright © 2026, Texas Instruments Incorporated

最終更新日 : 2025 年 10 月