

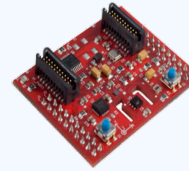
Meet the
Hercules™ RM57Lx

LaunchPad Development Kit

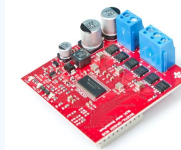
Part Number: LAUNCHXL2-RM57L



BoosterPack Ecosystem



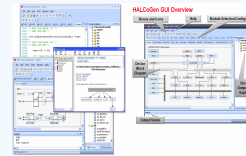
Sensor Hub BoosterPack
InvenSense MPU-9150 9-axis MEMS motion sensor
- 3-axis gyroscope
- 3-axis accelerometer
- 3-axis compass
• Bosch Sensortec BMP180 pressure sensor
• Sensirion SHT32 humidity & ambient temperature sensor
• Intersil ISL29023 light & IR



DRV8301 Motor Driver BoosterPack
- Spin Any Three Phase Motor!
- 6-24V Supply Input
- 10A Continuous/14A Peak

>> See them all @ ti.com/boosterpacks

Software Tools



HALCoGen
A powerful GUI based code generation tool that allows users to configure peripherals and other MCU parameters.

Easily import code into CCS and other IDEs.

www.ti.com/tool/halcodegen

Professional Software tools

LaunchPad is also supported by professional IDEs that provide industrial-grade features and full debug-capability. Set breakpoints, watch variables & more with LaunchPad.

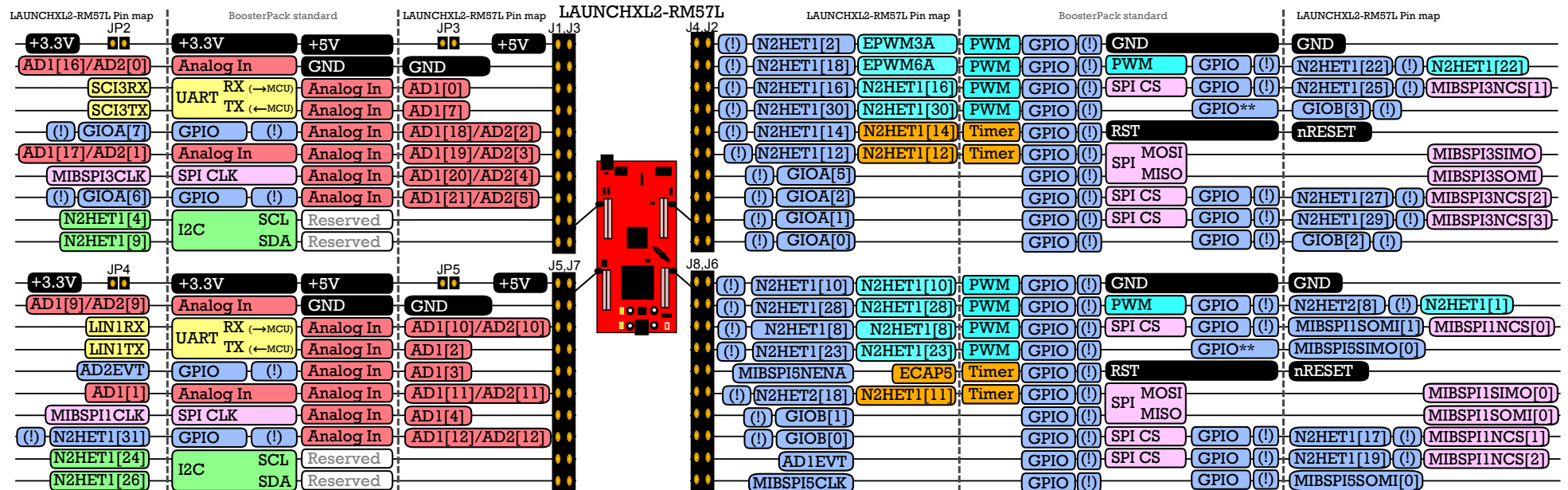
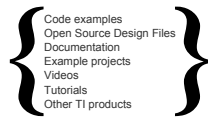
www.ti.com/ccs



Code Composer Studio™ IDE

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Disclaimer: www.ti.com/lit/szzz027

Resources
ti.com/launchpad



When using some BoosterPacks, JP2, 3, 4, or 5 may need to be removed. For example, using this LaunchPad with BoosterPack BOOSTXL-DRV8301 that includes a 3.3V regulator. To avoid conflict between the LaunchPad's 3.3V regulator and the regulator on the BoosterPack, JP2 (or JP4) should be removed.

Below are the pins exposed @ the 2x BoosterPack connector sites.

Mapping to the booster pack standard is shown. In some cases a function can be either a GPIO or another function, and may be listed twice (color coded as both GPIO and again as the function). Additional functions beyond the booster pack standard may be available. For details consult the launchpad schematic.

(I) Denotes I/O pins that are interrupt-capable.

A closer look at your new LaunchPad Development Kit

Featured microcontroller: Hercules RM57L843

This LaunchPad is great for...

- Starting evaluation with Hercules RM MCUs designed for IEC61508 functional safety industrial and medical applications.
- Evaluating Precision Ethernet PHY DP83630 supporting IEEE1588.
- Getting hands-on experience with the MCU's hardware integrated safety and diagnostic features.
- Getting familiar with SafeTI software and development tools that ease development of functional safety applications.

What comes in the box?

LAUNCHXL2-RM57L LaunchPad

XDS110 Class Debug Probe
Enables JTAG programming, debugging & application UART via USB.

QSG
This Quick Start Guide

Micro-USB Cable

Download Software
ti.com/launchxl2-rm57l

RM57L843 Microcontroller

- 330 MHz LockStep ARM[®]Cortex[®]R5F Cached CPU
- 32K I\$, 32K D\$ with ECC
- 4MB of Embedded Flash with ECC
- 512KB of Embedded SRAM with ECC
- 128KB of Embedded Flash for EEPROM with ECC
- Built-in Self-Test for CPUs and on-chip RAMs
- Error Signaling, Clock and Voltage Monitor

- 2 x Programmable High-End Timer (N2HET) Modules
- Enhanced Timing Peripherals for Motor Control
 - 7 x ePWM, 6 x eCAP, 2 x eQEP
- 2 x 12-bit Analog-to-Digital Converter (ADC)
- 10/100 Mbps Ethernet MAC (EMAC)
- Multiple Communication Modules
 - UART/SCI, LIN, Multi-buffered SPI, I2C
 - 4 x CAN Controller Modules (DCAN)

LAUNCHXL2-RM57L Overview

Optional TI CTI-20 JTAG Header
for use with external debug probes

Optional +5V power supply jack

USB Connector

40-pin BoosterPack plug-in module Connector (J1-J4)

Hercules RM57Lx MCU

Optional 40-pin BoosterPack plug-in module connector (J5-J8)

Potentiometer (to ADC input)

Power-on Reset Switch
Warm Reset Switch

User Switch B
User Switch A

User LED 2
User LED 3

Additional MCU I/Os for Prototyping (on both edges)

DP83630 Ethernet PHY

XDS110 Class Debug

OSC Fault Injection Button

Current Limit LED
On indicates External power is necessary

Out-of-box Demo

Find more information @ ti.com/launchxl2-rm57l

- (Optional) Installing Code Composer Studio (CCS)**
The virtual COM port drivers that are required to see the console output of the out of box demo are bundled with CCS. If you wish to see this part of the demo, install CCS v6.0.1 or later before connecting the LaunchPad to the PC.
 - Connecting to a Computer and Powering the LaunchPad**
The LaunchPad is configured by default to be USB powered (JP6 must be shorted), which can be done by connecting the LaunchPad to a computer using the included USB cable. If you skipped the optional step 1, ignore any error/warning messages about missing drivers during this step.
 - (Optional) Opening a Terminal Program**
If you completed step 1 and wish to see the console output of the demo, this is the time to configure the terminal program of your choice:
 - > Select COM port identified as "XDS Class Application/User UART" from your computer's device manager.
 - > Configure Baud Rate: 19200, Data Bits: 8, Stop Bits: 2 and Parity: None.
 - Running the Out-of-box Demo**
This LaunchPad comes pre-programmed with a demo set that highlights several of MCU's safety features. When powered the LaunchPad will start blinking USER LEDs.

Demo 1: A potentiometer is connected to the MCU's Analog Input 1. LED3 blinks according to the input voltage and a change in the potentiometer setting will cause it to blink faster or slower.

Demo 2: Pushing button KILL OSC will short the OSC to GND and cause an Oscillator Fault in the MCU. The on-chip monitor will detect and trigger an error signal causing the ERR LED to light up. Use the MCU Reset push-button to bring the LaunchPad back to normal operation.

Demo 3: The push-button USER SWITCH B will inject a core compare error (CPU mismatch). An on-chip monitor will detect the fault and trigger an error signal causing the ERR LED to light up.

Demo 4: The push-button USER SWITCH A will inject a single bit error in the MCU's flash on every push. ECC logic corrects single bit errors in flash and counts them. LED2 toggles with every injection of the single bit error.
- When you are ready to take the next step, complete *Project 0*. Go to www.ti.com/launchpad and click on the Project 0 link for Hercules RM57Lx LaunchPad. Find other projects on wiki: processors.wiki.ti.com/index.php/LAUNCHXL2-RM57L



SafeTI™ Design Packages for Functional Safety

Find more information @ ti.com/safeti

SafeTI™ design packages help designers meet industry standard functional safety requirements while managing both systematic and random failures. Using SafeTI components helps make it easier for designers to achieve applicable end-product certification and get to market quickly with their safety critical systems which are pervasive in our world today.

- Complementary embedded processing and analog products that work together to help designer meet safety standards
- Safety development process certified suitable for use in development of IEC61508 and ISO26262 compliant semiconductors
- Safety related documentation: *Safety Analysis Report, Safety Manual and Safety Report*
- Safety Tools and Software (See below)

SafeTI Diagnostic Library

Software library of functions and response handlers for various safety features of the Hercules Safety MCUs.
Download: ti.com/tool/safeti_diag_lib

SafeTI Compiler Qualification Kit

Assists developers in qualifying their use of the TI ARM Compiler to functional safety standards such as IEC 61508 and ISO 26262.
Learn more: ti.com/tool/safeti_cqkit

SafeTI Compliance Support Packages

SafeTI Compliance Support Packages for HALCoGen and SafeTI Diagnostic Library provide the necessary documentation, reports and unit test capability to assist developers who need to comply with functional safety standards such as ISO 26262 and IEC 61508.



Hercules MCU E2E Support Forum:
>> ti.com/hercules-support

Hercules Training Videos:
>> ti.com/herculestraining

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