

# LMH32401 450-MHz, Programmable Gain, Differential Output Transimpedance Amplifier

## 1 Features

- Integrated programmable gain: 2 k $\Omega$  or 20 k $\Omega$
- Performance, gain = 2 k $\Omega$ , C<sub>PD</sub> = 1 pF:
  - Bandwidth: 450 MHz
  - Input-referred noise: 250 nA<sub>RMS</sub>
  - Rise, fall time: 0.8 ns
- Performance, gain = 20 k $\Omega$ , C<sub>PD</sub> = 1 pF:
  - Bandwidth: 275 MHz
  - Input-referred noise: 49 nA<sub>RMS</sub>
  - Rise, fall time: 1.3 ns
- Integrated ambient light cancellation
- Integrated 100-mA protection clamp
- Integrated output multiplexer
- Wide output swing: 1.5 V<sub>PP</sub>
- Quiescent current: 30 mA
- Packages: 16-pin VQFN and bare die
- Temperature range: –40 to +125°C

## 2 Applications

- [Mechanically scanning LIDAR](#)
- [Solid-state scanning LIDAR](#)
- [Laser distance meter](#)
- [Optical ToF position sensor](#)
- [Drone vision](#)
- [Industrial robot LIDAR](#)
- [Mobile robot LIDAR](#)
- [Vacuum robot LIDAR](#)

## 3 Description

The LMH32401 device is a programmable-gain, single-ended, input-to-differential output transimpedance amplifier for light detection and ranging (LIDAR) applications and laser distance measurement systems. The LMH32401 device can be configured in a gain of 2 k $\Omega$  or 20 k $\Omega$ . The LMH32401 device has 1.5 V<sub>PP</sub> of output swing and is designed to drive a 100- $\Omega$  load.

The LMH32401 device has an integrated 100-mA clamp that protects the amplifier and allows the device to recover rapidly from an overloaded input condition. The LMH32401 device also features an integrated ambient light cancellation circuit that can be used instead of AC coupling between the photodiode and the amplifier to save board space in addition to reducing system cost. The ambient light cancellation circuit can be disabled in cases where DC coupling is required.

The LMH32401 device can be placed in low-power mode using the  $\overline{\text{EN}}$  pin to conserve power when the amplifier is not being used. Putting the amplifier in low-power mode places its output pins in a high-impedance state. This feature allows several LMH32401 amplifiers to be multiplexed to a single ADC with the  $\overline{\text{EN}}$  control pin serving as the multiplexer select function.

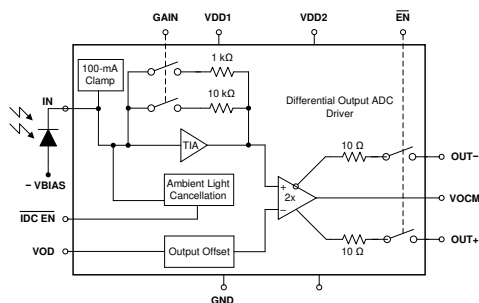
### Package Information<sup>(1)</sup>

PART NUMBER	PACKAGE	BODY SIZE (NOM)
LMH32401	VQFN (16)	3.00 mm × 3.00 mm

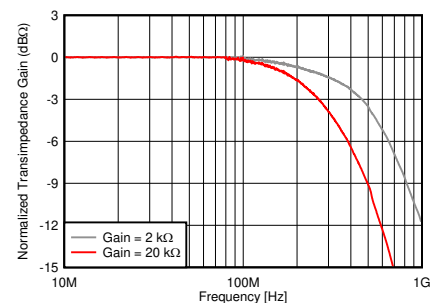
### Device Information<sup>(1)</sup>

PART NUMBER	PACKAGE	DIE SIZE (NOM)
LMH32401	Bare die	1.025 mm × 1.060 mm

- (1) For all available packages, see the package option addendum at the end of the data sheet.



Simplified Block Diagram



Closed-Loop Transimpedance Bandwidth



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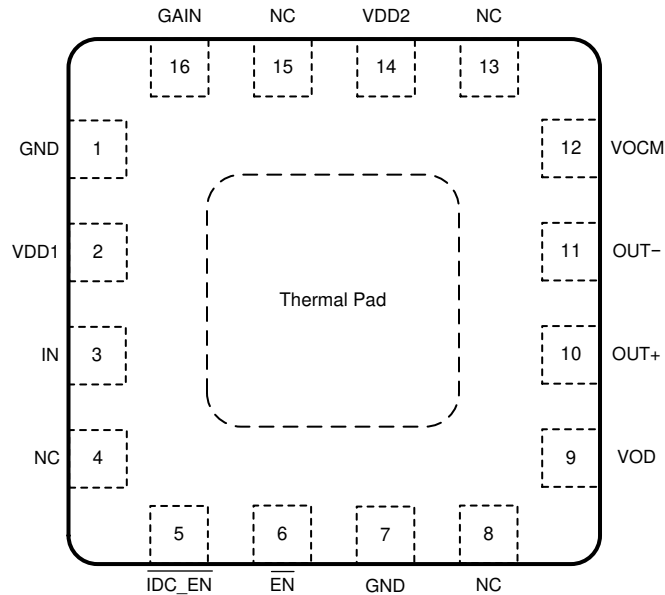
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## 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

<b>Changes from Revision C (August 2022) to Revision D (January 2023)</b>	<b>Page</b>
<ul style="list-style-type: none"> <li>Updated the <i>backside potential</i> information for <i>bare die package</i> information in the <i>Pin Configuration and Functions</i> section .....</li> </ul>	3
<b>Changes from Revision B (February 2022) to Revision C (August 2022)</b>	<b>Page</b>
<ul style="list-style-type: none"> <li>Changed the status of the Bare die from: <i>Preview</i> to: <i>Active</i> .....</li> <li>Updated the <i>bare die package</i> information in the <i>Pin Configuration and Functions</i> section.....</li> </ul>	1 3
<b>Changes from Revision A (September 2020) to Revision B (February 2022)</b>	<b>Page</b>
<ul style="list-style-type: none"> <li>Updated the numbering format for tables, figures, and cross-references throughout the document.....</li> <li>Added <i>bare die preview package</i> to the <i>Features</i> section and <i>Device Information</i> table.....</li> <li>Added the <i>bare die preview package</i> to the <i>Pin Configuration and Functions</i> section.....</li> </ul>	1 1 3
<b>Changes from Revision * (October 2019) to Revision A (June 2020)</b>	<b>Page</b>
<ul style="list-style-type: none"> <li>Changed status From: Advanced Information To: Production Data .....</li> </ul>	1

## 5 Pin Configuration and Functions



Not to scale

Figure 5-1. RGT Package, 16-Pin VQFN with Exposed Thermal Pad (Top View)

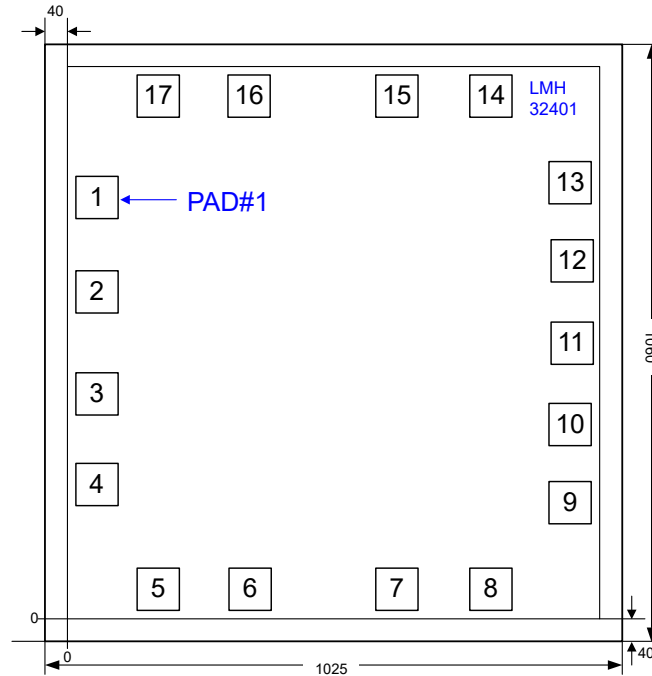
Table 5-1. Pin Functions

PIN		TYPE <sup>(2)</sup>	DESCRIPTION
NAME	NO.		
$\overline{\text{EN}}$	6	I	Device enable pin. $\overline{\text{EN}}$ = logic low = normal operation (default) <sup>(1)</sup> ; $\overline{\text{EN}}$ = logic high = power off mode.
GAIN	16	I	Gain setting. GAIN = low = 2 k $\Omega$ (default) <sup>(1)</sup> ; GAIN = high = 20 k $\Omega$ .
GND	1, 7	I	Amplifier ground.
$\overline{\text{IDC\_EN}}$	5	I	Ambient light cancellation (ALC) loop enable. $\overline{\text{IDC\_EN}}$ = logic low = enable DC current cancellation (default) <sup>(1)</sup> ; $\overline{\text{IDC\_EN}}$ = logic high = disable DC current cancellation.
IN	3	I	Transimpedance amplifier input.
NC	4, 8, 13, 15	—	No connection.
OUT–	11	O	Inverting amplifier output. When light is incident on the photodiode the output pin transitions in a negative direction from the no light condition (APD anode connected to negative bias).
OUT+	10	O	Noninverting amplifier output. When light is incident on the photodiode the output pin transitions in a positive direction from the no light condition (APD anode connected to negative bias).
VDD1	2	I	Positive power supply for the transimpedance amplifier stage.
VDD2	14	I	Positive power supply for the differential amplifier stage. Tie VDD1 and VDD2 to the same power supply with independent power-supply bypassing.
VOVM	12	I	Differential amplifier common-mode output setting.
VOD	9	I	Differential amplifier differential output offset setting.
Thermal pad		—	Connect the thermal pad to GND or the most negative power supply of the device under test (DUT).

(1) TI recommends driving a digital pin with a low-impedance source rather than leaving the pin floating because fast-moving transients can couple into the pin and inadvertently change the logic level.

(2) I = input, O = output

DIE THICKNESS	BACKSIDE FINISH	BACKSIDE POTENTIAL	BOND PAD METALLIZATION
381 µm	Silicon with backgrind	Wafer backside is not electrically isolated and should be held at the same potential as the most negative power supply connected to the die (GND)	AlCu



**Figure 5-2. Bare Die Package**

**Table 5-2. Bond Pad Coordinates of Bare Die Version in Microns**

PAD NUMBER	PAD NAME	X-MIN	Y-MIN	X-MAX	Y-MAX
1	GND	15	711.4	90	786.4
2	VDD1	15	543	90	618
3	IN	15	362	90	437
4	NC	15	201	90	276
5	IDC_EN	124.675	15	199.675	90
6	EN	286.675	15	361.675	90
7	GND	547.7	15	622.7	90
8	NC	713.675	15	788.675	90
9	VOD	855	169.075	930	244.075
10	OUT+	855	307.6	930	382.6
11	NC	855	452.5	930	527.5
12	OUT-	855	597.325	930	672.325
13	VOCM	855	736.05	930	811.05
14	NC	713.65	890	788.65	965
15	VDD2	547.675	890	622.675	965
16	NC	286.675	890	361.675	965
17	GAIN	124.675	890	199.675	965

## 6 Specifications

### 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
V <sub>DD1</sub> , V <sub>DD2</sub>	Total supply voltage, V <sub>DD</sub> <sup>(2)</sup>		3.65	V
	Voltage at output pins	0	V <sub>DD</sub>	V
	Voltage at logic pins	-0.25	V <sub>DD</sub>	V
I <sub>IN</sub>	Continuous current into IN		25	mA
I <sub>OUT</sub>	Continuous output current		35	mA
T <sub>J</sub>	Junction temperature		150	°C
T <sub>A</sub>	Operating free-air temperature	-40	125	°C
T <sub>stg</sub>	Storage temperature	-65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Rating* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Condition*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) VDD1 and VDD2 should always be tied to the same supply and have separate power-supply bypass capacitors.

### 6.2 ESD Ratings

			VALUE	UNIT
V <sub>(ESD)</sub>	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/ JEDEC JS-001, all pins <sup>(1)</sup>	±1000	V
		Charged device model (CDM), per JEDEC specification JESD22-C101, all pins <sup>(2)</sup>	±250	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process. Manufacturing with less than 500-V HBM is possible with the necessary precautions.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process. Manufacturing with less than 250-V CDM is possible with the necessary precautions.

### 6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V <sub>DD</sub>	Total supply voltage	3	3.3	3.45	V
T <sub>A</sub>	Operating free-air temperature	-40		125	°C

### 6.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		LMH32401 <sup>(2)</sup>	UNIT
		RGT (VQFN)	
		12 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	56.3	°C/W
R <sub>θJC(top)</sub>	Junction-to-case (top) thermal resistance	67	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	31.3	°C/W
Ψ <sub>JT</sub>	Junction-to-top characterization parameter	3.7	°C/W
Ψ <sub>JB</sub>	Junction-to-board characterization parameter	31.2	°C/W
R <sub>θJC(bot)</sub>	Junction-to-case (bottom) thermal resistance	15.6	°C/W

- (1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.
- (2) Thermal information is applicable to packaged parts only.

## 6.5 Electrical Characteristics: Gain = 2 k $\Omega$

$V_{DD} = 3.3\text{ V}$ ,  $V_{OCM} = \text{open}$ ,  $V_{OD} = 0\text{ V}$ ,  $C_{PD}^{(1)} = 1\text{ pF}$ ,  $\overline{EN} = 0\text{ V}$ ,  $GAIN = 0\text{ V}$ ,  $\overline{IDC\_EN} = 3.3\text{ V}$ ,  $R_L = 100\ \Omega$ , and  $T_A = 25^\circ\text{C}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>AC PERFORMANCE</b>						
SSBW	Small-signal bandwidth	$V_{OUT} = 100\text{ mV}_{PP}$		450		MHz
LSBW	Large-signal bandwidth	$V_{OUT} = 1\text{ V}_{PP}$		450		MHz
$t_R, t_F$	Rise and fall time	$V_{OUT} = 100\text{ mV}_{PP}$ , pulse width = 10 ns		0.8		ns
	Slew rate <sup>(2)</sup>	$V_{OUT} = 1\text{ V}_{PP}$ , pulse width = 10 ns		1100		V/ $\mu\text{s}$
	Overload pulse extension <sup>(3)</sup>	$I_{IN} = 10\text{ mA}$ , pulse width = 10 ns		4		ns
$i_{IN}$	Integrated input current noise	$f = 500\text{ MHz}$		250		nA <sub>RMS</sub>
<b>DC PERFORMANCE</b>						
$Z_{21}$	Small-signal transimpedance gain <sup>(4)</sup>		1.75	2	2.25	k $\Omega$
$V_{OD}$	Differential output offset voltage ( $V_{OUT-} - V_{OUT+}$ )		-12	3.5	12	mV
$\Delta V_{OD}/\Delta T_A$	Differential output offset voltage drift			$\pm 5.5$		$\mu\text{V}/^\circ\text{C}$
<b>INPUT PERFORMANCE</b>						
$R_{IN}$	Input Resistance		60	100	120	$\Omega$
$V_{IN}$	Default input bias voltage	Input pin floating	2.42	2.47	2.52	V
$\Delta V_{IN}/\Delta T_A$	Default input bias voltage drift	Input pin floating		1.1		mV/ $^\circ\text{C}$
$I_{IN}$	DC input current range	$Z_{21} < 3\text{-dB degradation from}$ $I_{IN} = 50\ \mu\text{A}$	600	705		$\mu\text{A}$

- (1) Input capacitance of photodiode.
- (2) Average of rising and falling slew rate.
- (3) Pulse width extension measured at 50% of pulse height of a square wave.
- (4) Gain measured at the amplifier output pins when driving a 100- $\Omega$  resistive load. At higher resistor loads the gain increases.

## 6.6 Electrical Characteristics: Gain = 20 kΩ

$V_{DD} = 3.3\text{ V}$ ,  $V_{OCM} = \text{open}$ ,  $V_{OD} = 0\text{ V}$ ,  $C_{PD}^{(1)} = 1\text{ pF}$ ,  $\overline{EN} = 0\text{ V}$ ,  $GAIN = 3.3\text{ V}$ ,  $\overline{IDC\_EN} = 3.3\text{ V}$ ,  $R_L = 100\ \Omega$ , and  $T_A = 25^\circ\text{C}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>AC PERFORMANCE</b>						
SSBW	Small-signal bandwidth	$V_{OUT} = 100\text{ mV}_{PP}$		275		MHz
LSBW	Large-signal bandwidth	$V_{OUT} = 1\text{ V}_{PP}$		275		MHz
$t_R, t_F$	Rise and fall time	$V_{OUT} = 100\text{ mV}_{PP}$ , pulse width = 10 ns		1.3		ns
	Slew rate <sup>(2)</sup>	$V_{OUT} = 1\text{ V}_{PP}$ , pulse width = 10 ns		700		V/ $\mu\text{s}$
	Overload pulse extension <sup>(4)</sup>	$I_{IN} = 10\text{ mA}$ , pulse width = 10 ns		4		ns
$i_{IN}$	Integrated input current noise	$f = 250\text{ MHz}$		49		nA <sub>RMS</sub>
<b>DC PERFORMANCE</b>						
$Z_{21}$	Small-signal transimpedance gain <sup>(3)</sup>		17	20	22.5	kΩ
$V_{OD}$	Differential output offset voltage ( $V_{OUT-} - V_{OUT+}$ )		-20	5	20	mV
$\Delta V_{OD}/\Delta T_A$	Differential output offset voltage			±17.5		$\mu\text{V}/^\circ\text{C}$
<b>INPUT PERFORMANCE</b>						
$R_{IN}$	Input Resistance		270	350	410	Ω
$V_{IN}$	Default input bias voltage	Input pin floating	2.42	2.47	2.52	V
$\Delta V_{IN}/\Delta T_A$	Default input bias voltage drift	Input pin floating		1.1		$\text{mV}/^\circ\text{C}$
$I_{IN}$	DC input current range	$Z_{21} < 3\text{-dB degradation from } I_{IN} = 5\ \mu\text{A}$	60	72		$\mu\text{A}$

- (1) Input capacitance of photodiode.
- (2) Average of rising and falling slew rate.
- (3) Gain measured at the amplifier output pins when driving a 100-Ω resistive load. At higher resistor loads the gain increases.
- (4) Pulse width extension measured at 50% of pulse height of a square wave.

## 6.7 Electrical Characteristics: Both Gains

$V_{DD} = 3.3\text{ V}$ ,  $V_{OCM} = \text{open}$ ,  $V_{OD} = 0\text{ V}$ ,  $C_{PD}^{(1)} = 1\text{ pF}$ ,  $\overline{EN} = 0\text{ V}$ ,  $GAIN = 0\text{ V} / 3.3\text{ V}$ ,  $\overline{IDC\_EN} = 3.3\text{ V}$ ,  $R_L = 100\ \Omega$ , and  $T_A = 25^\circ\text{C}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>OUTPUT PERFORMANCE</b>						
$V_{OH}$	Single-sided output voltage swing (high) <sup>(2)</sup>	$T_A = 25^\circ\text{C}$	2.87	2.9		V
$V_{OL}$	Single-sided output voltage swing (low) <sup>(2)</sup>	$T_A = 25^\circ\text{C}$		0.36	0.39	V
$I_{OUT}$	Linear output drive (sink and source)	$T_A = 25^\circ\text{C}$ , $I_{IN} = 500\ \mu\text{A}$ , gain = 2 k $\Omega$ , $R_L = 25\ \Omega$	24	26.6	32	mA
		$T_A = -40^\circ\text{C}$ , $I_{IN} = 500\ \mu\text{A}$ , gain = 2 k $\Omega$ , $R_L = 25\ \Omega$		27.1		
		$T_A = 125^\circ\text{C}$ , $I_{IN} = 500\ \mu\text{A}$ , gain = 2 k $\Omega$ , $R_L = 25\ \Omega$		25.1		
$I_{SC}$	Output short-circuit current (differential) <sup>(3)</sup>			70		mA
$Z_{OUT}$	DC output impedance (amplifier enabled)	Differential impedance	18	21	24	$\Omega$
$Z_{OUT}$	DC output impedance in shutdown	Differential impedance	2.8	3.3		k $\Omega$
<b>OUTPUT COMMON-MODE CONTROL (<math>V_{OCM}</math>) PERFORMANCE</b>						
SSBW	Small-signal bandwidth	$V_{OCM} = 100\text{ mV}_{PP}$ at VO <sub>CM</sub> pin		285		MHz
LSBW	Large-signal bandwidth	$V_{OCM} = 1\text{ V}_{PP}$ at VO <sub>CM</sub> pin		85		MHz
$e_N$	Output common-mode noise	$f = 10\text{ MHz}$ , 1-nF capacitor to GND on VO <sub>CM</sub> pin		17.8		nV/ $\sqrt{\text{Hz}}$
$A_V$	Gain, ( $\Delta V_{OCM}/\Delta V_{OCM}$ )	IN floating, VO <sub>CM</sub> = 1.1 V (driven)		1		V/V
	Gain error	$T_A = 25^\circ\text{C}$ , VO <sub>CM</sub> = 0.7 V to 2.3 V	-2%	0.5%	2%	
		$T_A = -40^\circ\text{C}$ to $125^\circ\text{C}$ , VO <sub>CM</sub> = 0.7 V to 2.3 V		$\pm 1\%$		
	Input impedance			17		k $\Omega$
VO <sub>CMOS</sub>	VO <sub>CM</sub> pin default offset from 1.1 V	VO <sub>CM</sub> floating, (VO <sub>CM</sub> measured - 1.1 V)	0	10	20	mV
$\Delta V_{OCM}/\Delta I_{IN}$	VO <sub>CM</sub> error vs Input current	Gain = 20 k $\Omega$ , VO <sub>CM</sub> driven to 1.1 V		-15		$\mu\text{V}/\mu\text{A}$
$V_{OCM}$	Output common-mode voltage, $(V_{OUT+} + V_{OUT-})/2$	$T_A = 25^\circ\text{C}$ , VO <sub>CM</sub> pin floating	1.05	1.1	1.15	V
	Output common-mode voltage drift, $(\Delta V_{OCM}/\Delta T_A)$	$T_A = -40^\circ\text{C}$ to $125^\circ\text{C}$ , VO <sub>CM</sub> pin floating		75		$\mu\text{V}/^\circ\text{C}$
$V_{OCM}$	Output common-mode voltage, $(V_{OUT+} + V_{OUT-})/2$	$T_A = 25^\circ\text{C}$ , VO <sub>CM</sub> pin driven to 1.1 V	1.05	1.1	1.15	V
	Output common-mode voltage drift, $(\Delta V_{OCM}/\Delta T_A)$	$T_A = -40^\circ\text{C}$ to $125^\circ\text{C}$ , VO <sub>CM</sub> pin driven to 1.1 V		-14		$\mu\text{V}/^\circ\text{C}$

$V_{DD} = 3.3\text{ V}$ ,  $V_{OCM} = \text{open}$ ,  $V_{OD} = 0\text{ V}$ ,  $C_{PD}^{(1)} = 1\text{ pF}$ ,  $\overline{EN} = 0\text{ V}$ ,  $GAIN = 0\text{ V} / 3.3\text{ V}$ ,  $\overline{IDC\_EN} = 3.3\text{ V}$ ,  $R_L = 100\ \Omega$ , and  $T_A = 25^\circ\text{C}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>OUTPUT DIFFERENTIAL OFFSET (<math>V_{OD}</math>) PERFORMANCE</b>						
SSBW	Small-signal bandwidth	$V_{OD} = 100\text{ mV}_{PP}$ at VOD pin		45		MHz
LSBW	Large-signal bandwidth	$V_{OD} = 1\text{ V}_{PP}$		14		MHz
$V_{OS\_D}$	Differential output offset, $V_{OUT} = (V_{OUT-} - V_{OUT+})$	IN floating, $V_{OD} = 0.5\text{ V}$	490	510	530	mV
	Differential output offset drift, $\Delta V_{OS\_D}/\Delta T_A$	IN floating, $V_{OD} = 0.5\text{ V}$		0.03		mV/°C
$V_{OS\_D}$	Differential output offset, $V_{OUT} = (V_{OUT-} - V_{OUT+})$	IN floating, VOD floating	490	510	530	mV
	Differential output offset drift, $\Delta V_{OS\_D}/\Delta T_A$	IN floating, VOD floating		0.04		mV/°C
$A_V$	Gain, $(\Delta V_{OUT}/\Delta V_{OD})$ , where $V_{OUT} = (V_{OUT-} - V_{OUT+})$	IN floating, $V_{OCM} = 1.1\text{ V}$ (driven)		1.01		V/V
	Gain error	$T_A = 25^\circ\text{C}$ , $V_{OD} = 0\text{ V}$ to $1.2\text{ V}$	-5%	-1%	5%	
		$T_A = -40^\circ\text{C}$ to $125^\circ\text{C}$ , $V_{OD} = 0\text{ V}$ to $1.2\text{ V}$		$\pm 1.5\%$		
	Input impedance			2.5		k $\Omega$
<b>AMBIENT LIGHT CANCELLATION PERFORMANCE (<math>\overline{IDC\_EN} = 0\text{ V}</math>) <sup>(4)</sup></b>						
	Settling time (within $V_{OD}$ limit)	$I_{IN} = 0\ \mu\text{A} \rightarrow 100\ \mu\text{A}$ , $GAIN = 2\text{ k}\Omega$		18		$\mu\text{s}$
		$I_{IN} = 0\ \mu\text{A} \rightarrow 10\ \mu\text{A}$ , $GAIN = 20\text{ k}\Omega$		2.5		
		$I_{IN} = 100\ \mu\text{A} \rightarrow 0\ \mu\text{A}$ , $GAIN = 2\text{ k}\Omega$		35		
		$I_{IN} = 10\ \mu\text{A} \rightarrow 0\ \mu\text{A}$ , $GAIN = 20\text{ k}\Omega$		13		
	Ambient light current cancellation range	Differential output offset ( $V_{OUT-} - V_{OUT+}$ ) shift from $I_{DC} = 10\ \mu\text{A} < \pm 10\text{ mV}$	2	3		mA
<b>POWER SUPPLY</b>						
$I_Q$	Quiescent current, total	$T_A = 25^\circ\text{C}$	24	30	33.5	mA
		$T_A = 125^\circ\text{C}$		32		
		$T_A = -40^\circ\text{C}$		27		
PSRR+	Positive power-supply rejection ratio, $V_{DD1} = V_{DD2}$		54	66		dB
<b>SHUTDOWN</b>						
$I_Q$	Disabled quiescent current ( $\overline{EN} = V_{DD}$ )	$T_A = 25^\circ\text{C}$	2.4	3.3	4.2	mA
		$T_A = -40^\circ\text{C}$		2.75		
		$T_A = 125^\circ\text{C}$		5.2		
	Enable pin input bias current	$T_A = 25^\circ\text{C}$		75	120	$\mu\text{A}$

- (1) Input capacitance of photodiode.
- (2) Output levels achieved by adjusting  $V_{OCM}$ ,  $V_{OD}$ , and input current.
- (3) Device cannot withstand continuous short-circuit between the differential outputs.
- (4) Enabling the ambient light cancellation loop adds noise to the system.

## 6.8 Electrical Characteristics: Logic Threshold and Switching Characteristics

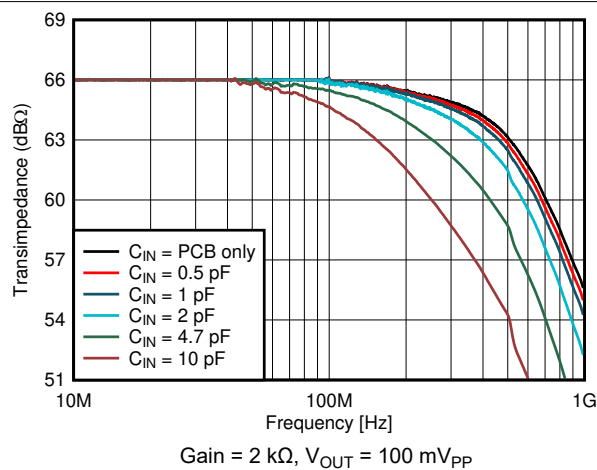
$V_{DD} = 3.3\text{ V}$ ,  $V_{OCM} = \text{Open}$ ,  $V_{OD} = 0\text{ V}$ ,  $C_{PD}^{(1)} = 1\text{ pF}$ ,  $\overline{EN} = 0\text{ V}$ ,  $\text{GAIN} = 0\text{ V} / 3.3\text{ V}$ ,  $\overline{IDC\_EN} = 3.3\text{ V}$ ,  $R_L = 100\ \Omega$ , and  $T_A = 25^\circ\text{C}$ . (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>LOGIC THRESHOLD PERFORMANCE</b>					
High gain enable, threshold voltage	Amplifier in high gain above this voltage		1.8	2	V
Low gain enable, threshold voltage	Amplifier in low gain below this voltage	0.8	1		V
$\overline{EN}$ control, disable threshold voltage	Amplifier disabled above this voltage		1.8	2	V
$\overline{EN}$ control, enable threshold voltage	Amplifier enabled below this voltage	0.8	1		V
$\overline{IDC\_EN}$ control, disable threshold voltage	Ambient light cancellation loop disabled above this voltage		1.8	2	V
$\overline{IDC\_EN}$ control, enable threshold voltage	Ambient light cancellation loop enabled below this voltage	0.8	1		V
<b>GAIN CONTROL TRANSIENT PERFORMANCE</b>					
High gain to low gain transition-time, (1% settling)	Ambient loop disabled, $f_{IN} = 25\text{ MHz}$ , $V_{OUT} = 1\text{ V}_{PP}$ (Initial condition), $I_{DC} = 0\ \mu\text{A}$		90		ns
Low gain to high gain transition-time, (1% settling)	Ambient loop disabled, $f_{IN} = 25\text{ MHz}$ , $V_{OUT} = 1\text{ V}_{PP}$ (Final condition), $I_{DC} = 0\ \mu\text{A}$		750		ns
High gain to low gain transition-time, (1% settling)	Ambient loop enabled, $f_{IN} = 25\text{ MHz}$ , $V_{OUT} = 1\text{ V}_{PP}$ (Initial condition), $I_{DC} = 100\ \mu\text{A}$		4		$\mu\text{s}$
Low gain to high gain transition-time, (1% settling)	Ambient loop enabled, $f_{IN} = 25\text{ MHz}$ , $V_{OUT} = 1\text{ V}_{PP}$ (Final condition), $I_{DC} = 100\ \mu\text{A}$		4		$\mu\text{s}$
<b>EN CONTROL TRANSIENT PERFORMANCE</b>					
Enable transition-time (1% settling)	Ambient loop disabled, $f_{IN} = 25\text{ MHz}$ , $V_{OUT} = 1\text{ V}_{PP}$ , $I_{DC} = 0\ \mu\text{A}$ , $\text{GAIN} = 2\text{ k}\Omega$		125		ns
Disable transition-time (1% settling)	Ambient loop disabled, $f_{IN} = 25\text{ MHz}$ , $V_{OUT} = 1\text{ V}_{PP}$ , $I_{DC} = 0\ \mu\text{A}$ , $\text{GAIN} = 2\text{ k}\Omega$		3		ns
Enable transition-time (1% settling)	Ambient loop disabled, $f_{IN} = 25\text{ MHz}$ , $V_{OUT} = 1\text{ V}_{PP}$ , $I_{DC} = 0\ \mu\text{A}$ , $\text{GAIN} = 20\text{ k}\Omega$		850		ns
Disable transition-time (1% settling)	Ambient loop disabled, $f_{IN} = 25\text{ MHz}$ , $V_{OUT} = 1\text{ V}_{PP}$ , $I_{DC} = 0\ \mu\text{A}$ , $\text{GAIN} = 20\text{ k}\Omega$		3		ns
Enable transition-time (1% settling)	Ambient loop enabled, $f_{IN} = 25\text{ MHz}$ , $V_{OUT} = 1\text{ V}_{PP}$ , $I_{DC} = 100\ \mu\text{A}$ , $\text{GAIN} = 2\text{ k}\Omega$		10		$\mu\text{s}$
Disable transition-time (1% settling)	Ambient loop enabled, $f_{IN} = 25\text{ MHz}$ , $V_{OUT} = 1\text{ V}_{PP}$ , $I_{DC} = 100\ \mu\text{A}$ , $\text{GAIN} = 20\text{ k}\Omega$		3.5		ns
Enable transition-time (1% settling)	Ambient loop enabled, $f_{IN} = 25\text{ MHz}$ , $V_{OUT} = 1\text{ V}_{PP}$ , $I_{DC} = 100\ \mu\text{A}$ , $\text{GAIN} = 20\text{ k}\Omega$		4		$\mu\text{s}$
Disable transition-time (1% settling)	Ambient loop enabled, $f_{IN} = 25\text{ MHz}$ , $V_{OUT} = 1\text{ V}_{PP}$ , $I_{DC} = 100\ \mu\text{A}$ , $\text{GAIN} = 2\text{ k}\Omega$		3		ns

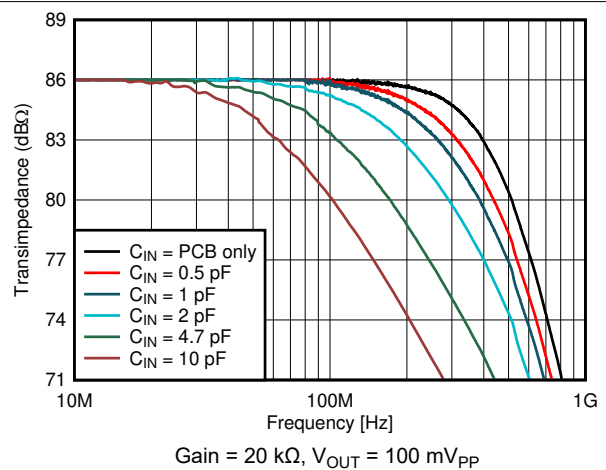
(1) Input capacitance of photodiode.

## 6.9 Typical Characteristics

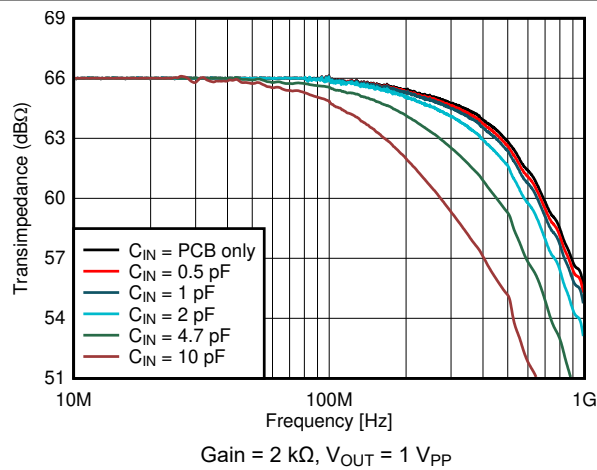
At  $V_{DD} = 3.3\text{ V}$ ,  $V_{OCM} = \text{open}$ ,  $V_{OD} = 0\text{ V}$ ,  $C_{PD} = 1\text{ pF}$ ,  $\overline{EN} = 0\text{ V}$  (enabled),  $\overline{IDC\_EN} = 3.3\text{ V}$  (disabled),  $R_L = 100\ \Omega$  (differential load between  $OUT+$  and  $OUT-$ ), and  $T_A = 25^\circ\text{C}$  (unless otherwise noted).



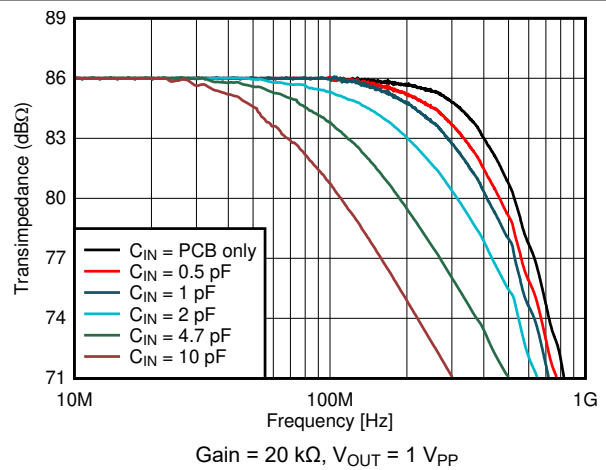
**Figure 6-1. Small Signal Response vs Input Capacitance**



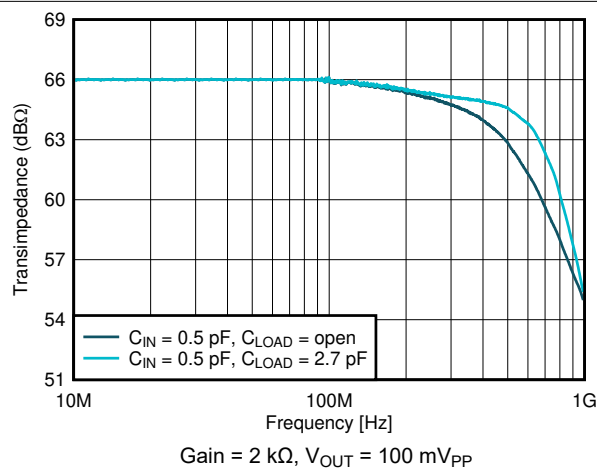
**Figure 6-2. Small Signal Response vs Input Capacitance**



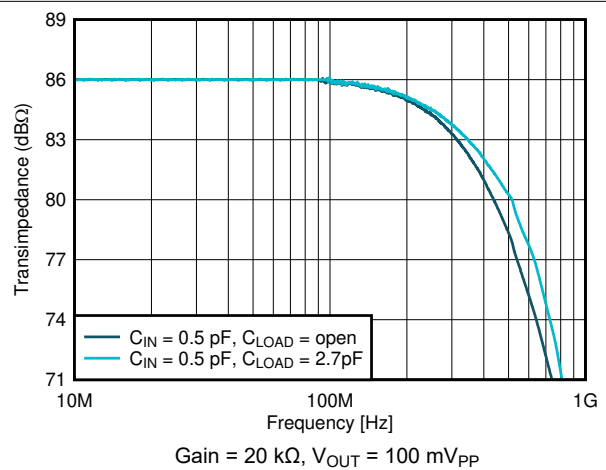
**Figure 6-3. Large Signal Response vs Input Capacitance**



**Figure 6-4. Large Signal Response vs Input Capacitance**



**Figure 6-5. Small Signal Response vs Load Capacitance**



**Figure 6-6. Small Signal Response vs Load Capacitance**

### 6.9 Typical Characteristics (continued)

At  $V_{DD} = 3.3\text{ V}$ ,  $V_{OCM} = \text{open}$ ,  $V_{OD} = 0\text{ V}$ ,  $C_{PD} = 1\text{ pF}$ ,  $\overline{EN} = 0\text{ V}$  (enabled),  $\overline{IDC\_EN} = 3.3\text{ V}$  (disabled),  $R_L = 100\ \Omega$  (differential load between  $OUT+$  and  $OUT-$ ), and  $T_A = 25^\circ\text{C}$  (unless otherwise noted).

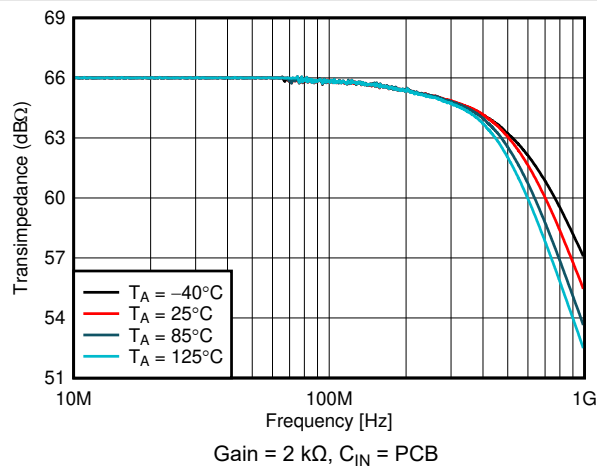


Figure 6-7. Small Signal Response vs Ambient Temperature

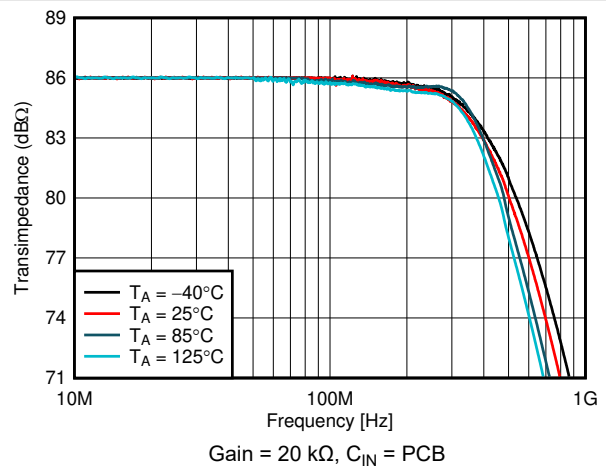


Figure 6-8. Small Signal Response vs Ambient Temperature

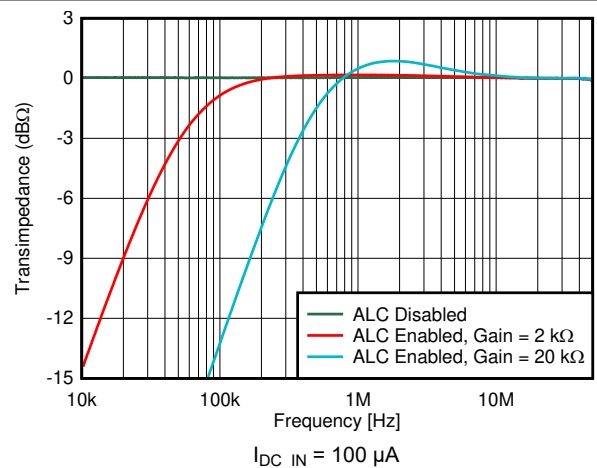


Figure 6-9. Low-side Frequency Response vs Ambient Light Cancellation

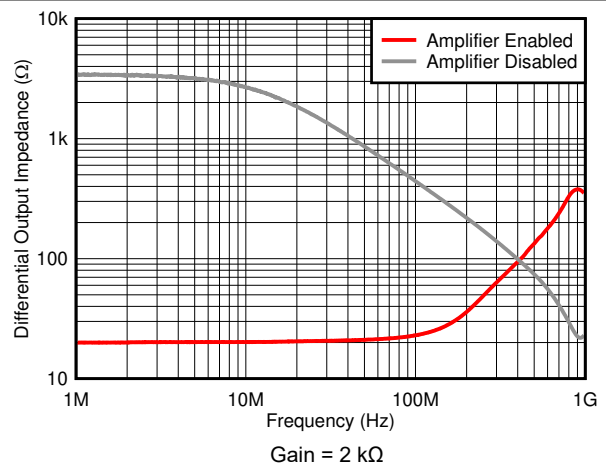


Figure 6-10. Closed-loop Output Impedance vs Frequency

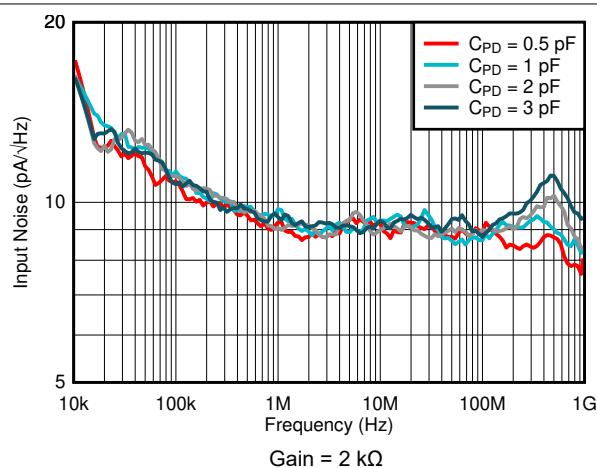


Figure 6-11. Input Noise Density vs Input Capacitance

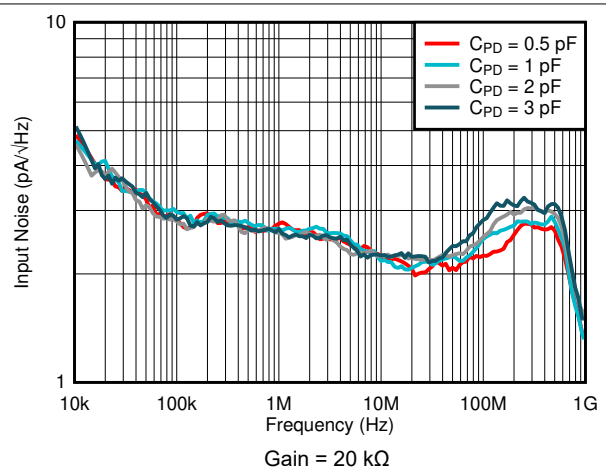


Figure 6-12. Input Noise Density vs Input Capacitance

### 6.9 Typical Characteristics (continued)

At  $V_{DD} = 3.3\text{ V}$ ,  $V_{OCM} = \text{open}$ ,  $V_{OD} = 0\text{ V}$ ,  $C_{PD} = 1\text{ pF}$ ,  $\overline{EN} = 0\text{ V}$  (enabled),  $\overline{IDC\_EN} = 3.3\text{ V}$  (disabled),  $R_L = 100\ \Omega$  (differential load between  $OUT+$  and  $OUT-$ ), and  $T_A = 25^\circ\text{C}$  (unless otherwise noted).

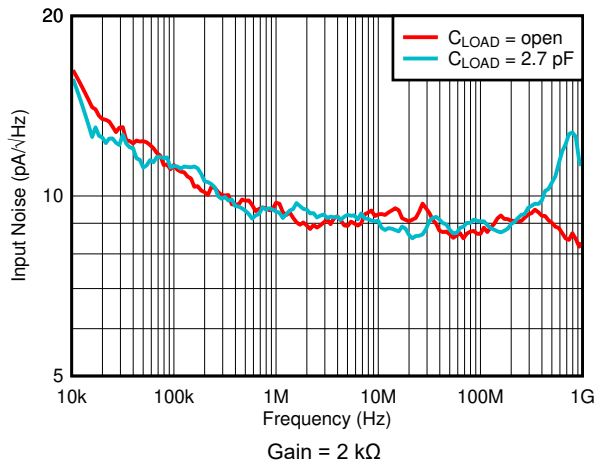


Figure 6-13. Input Noise Density vs Load Capacitance

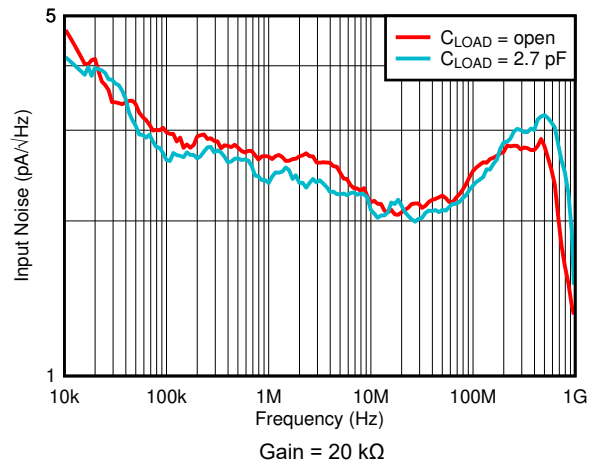


Figure 6-14. Input Noise Density vs Load Capacitance

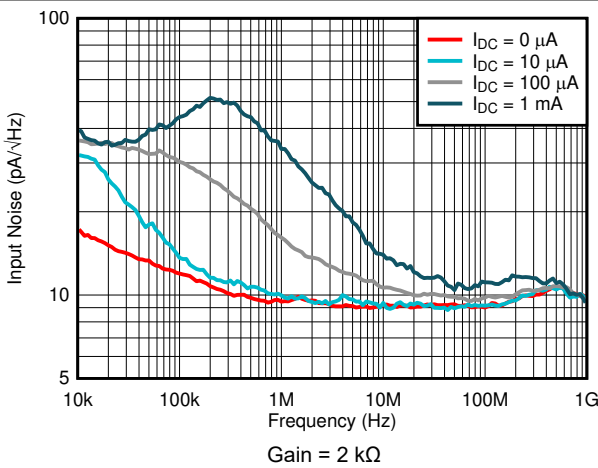


Figure 6-15. Input Noise Density vs Ambient Light DC Current

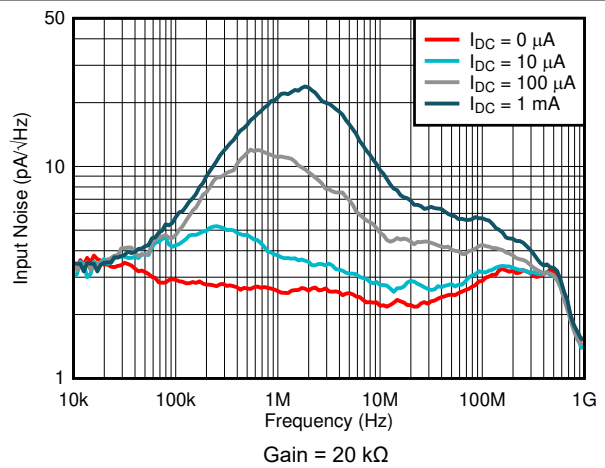


Figure 6-16. Input Noise Density vs Ambient Light DC Current

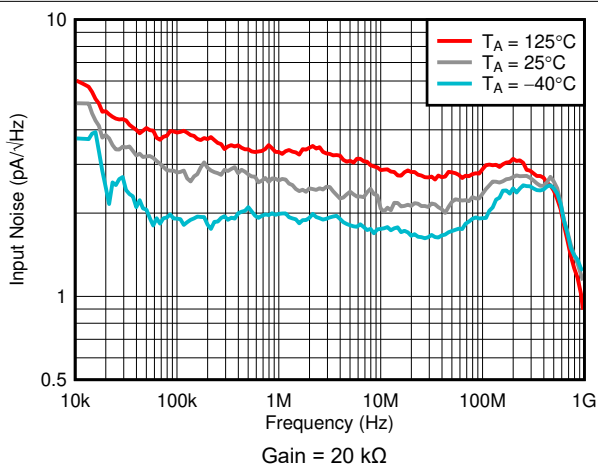


Figure 6-17. Input Noise Density vs Ambient Temperature

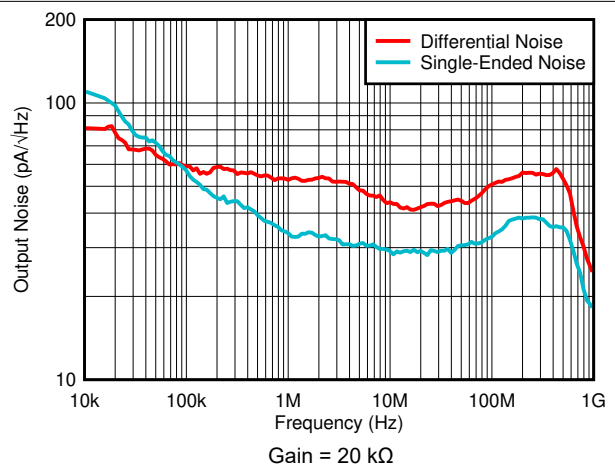


Figure 6-18. Output Noise Density vs Output Configuration

## 6.9 Typical Characteristics (continued)

At  $V_{DD} = 3.3\text{ V}$ ,  $V_{OCM} = \text{open}$ ,  $V_{OD} = 0\text{ V}$ ,  $C_{PD} = 1\text{ pF}$ ,  $\overline{\text{EN}} = 0\text{ V}$  (enabled),  $\overline{\text{IDC\_EN}} = 3.3\text{ V}$  (disabled),  $R_L = 100\ \Omega$  (differential load between  $\text{OUT}+$  and  $\text{OUT}-$ ), and  $T_A = 25^\circ\text{C}$  (unless otherwise noted).

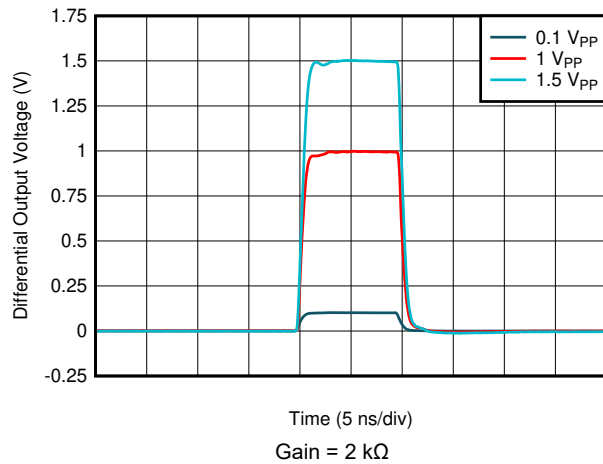


Figure 6-19. Pulse Response vs Output Swing

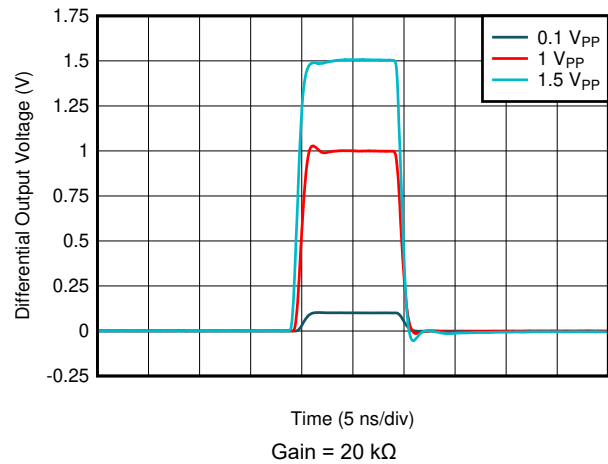


Figure 6-20. Pulse Response vs Output Swing

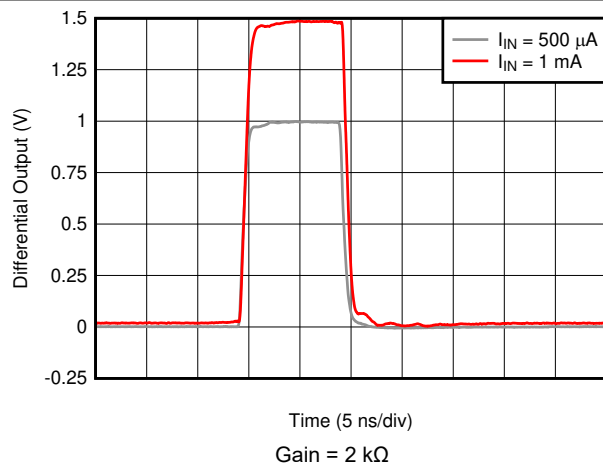


Figure 6-21. Overloaded Pulse Response

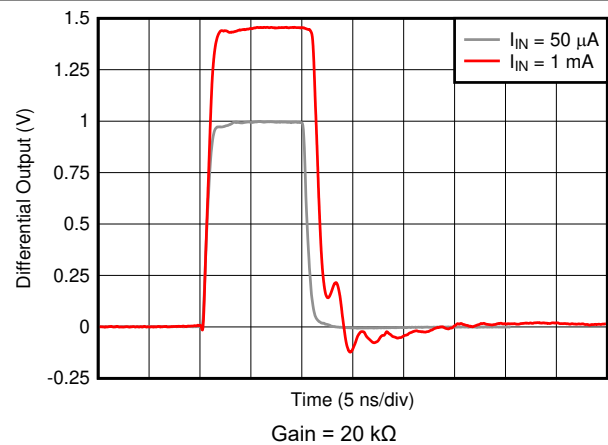


Figure 6-22. Overloaded Pulse Response

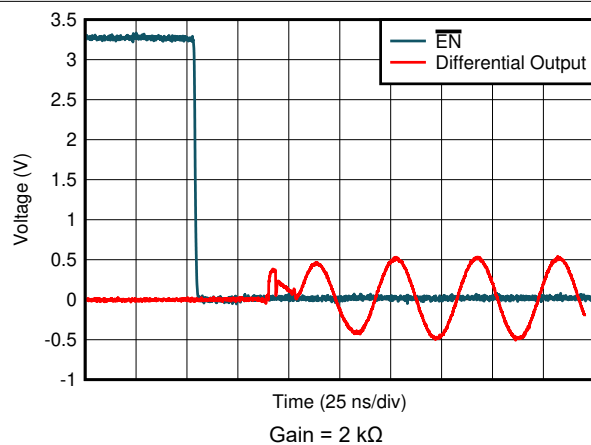


Figure 6-23. Turn-On Time

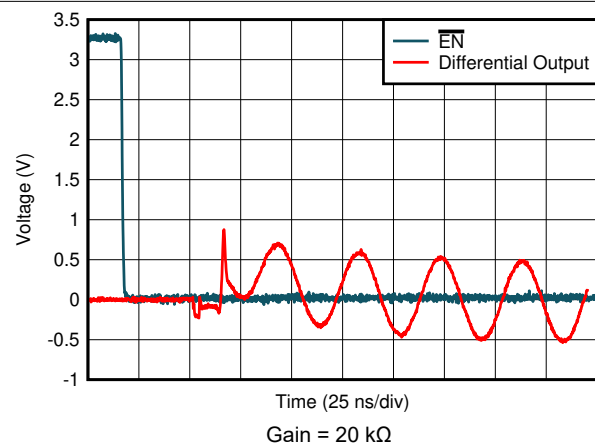


Figure 6-24. Turn-On Time

## 6.9 Typical Characteristics (continued)

At  $V_{DD} = 3.3\text{ V}$ ,  $V_{OCM} = \text{open}$ ,  $V_{OD} = 0\text{ V}$ ,  $C_{PD} = 1\text{ pF}$ ,  $\overline{\text{EN}} = 0\text{ V}$  (enabled),  $\overline{\text{IDC\_EN}} = 3.3\text{ V}$  (disabled),  $R_L = 100\ \Omega$  (differential load between  $\text{OUT}+$  and  $\text{OUT}-$ ), and  $T_A = 25^\circ\text{C}$  (unless otherwise noted).

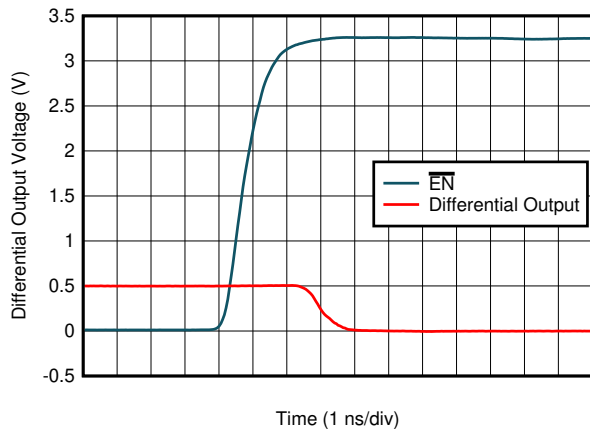


Figure 6-25. Turn-Off Time

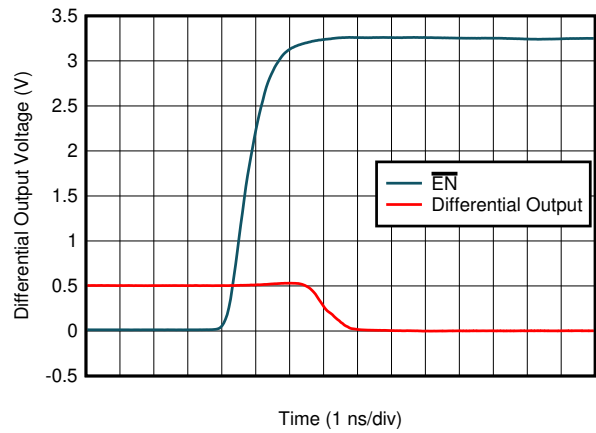


Figure 6-26. Turn-Off Time

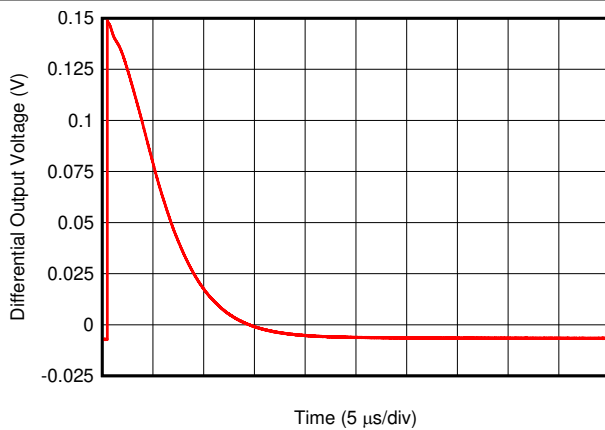


Figure 6-27. Ambient Loop Cancellation Settling Time

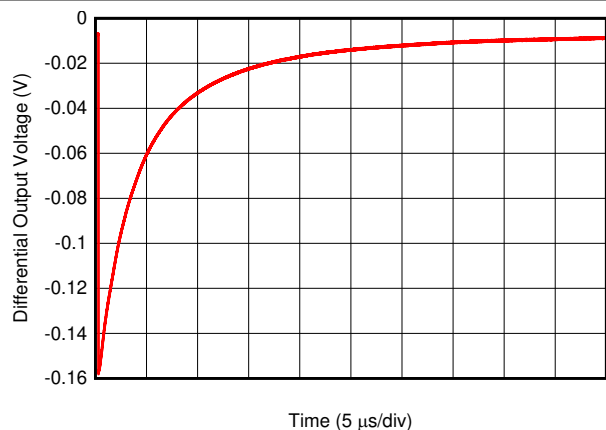


Figure 6-28. Ambient Loop Cancellation Settling Time

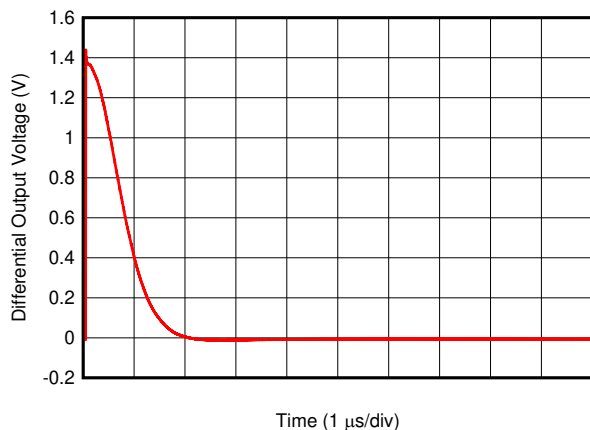


Figure 6-29. Ambient Loop Cancellation Settling Time

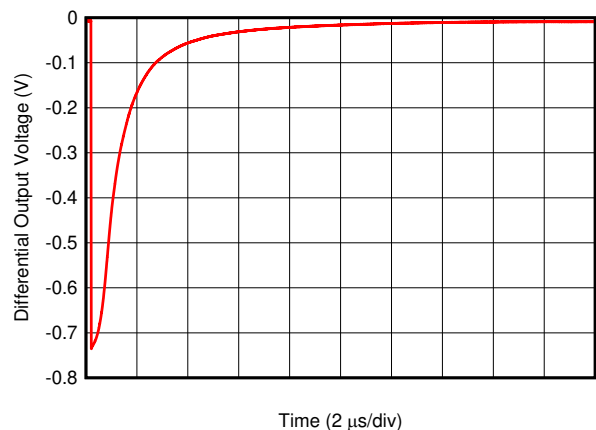


Figure 6-30. Ambient Loop Cancellation Settling Time

<sup>1</sup> Current due to ambient light transitions at  $t = 0$  in.

### 6.9 Typical Characteristics (continued)

At  $V_{DD} = 3.3\text{ V}$ ,  $V_{OCM} = \text{open}$ ,  $V_{OD} = 0\text{ V}$ ,  $C_{PD} = 1\text{ pF}$ ,  $\overline{EN} = 0\text{ V}$  (enabled),  $\overline{IDC\_EN} = 3.3\text{ V}$  (disabled),  $R_L = 100\ \Omega$  (differential load between  $OUT+$  and  $OUT-$ ), and  $T_A = 25^\circ\text{C}$  (unless otherwise noted).

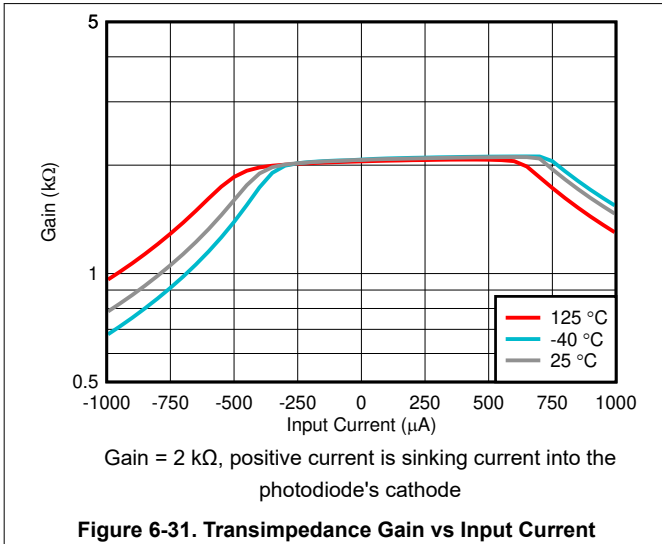


Figure 6-31. Transimpedance Gain vs Input Current

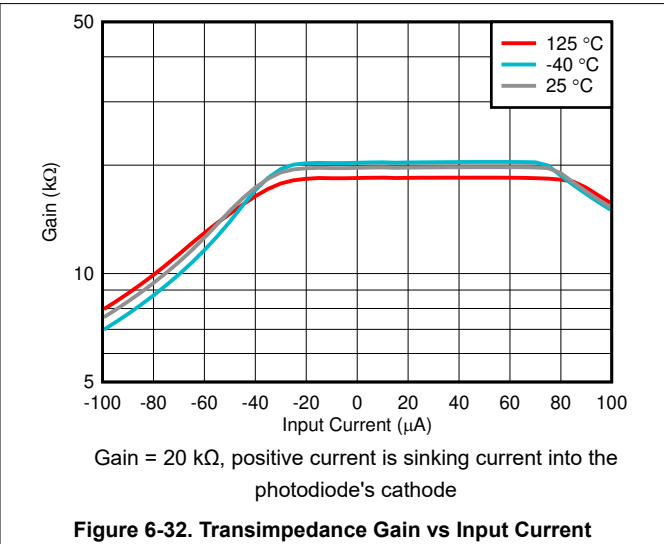


Figure 6-32. Transimpedance Gain vs Input Current

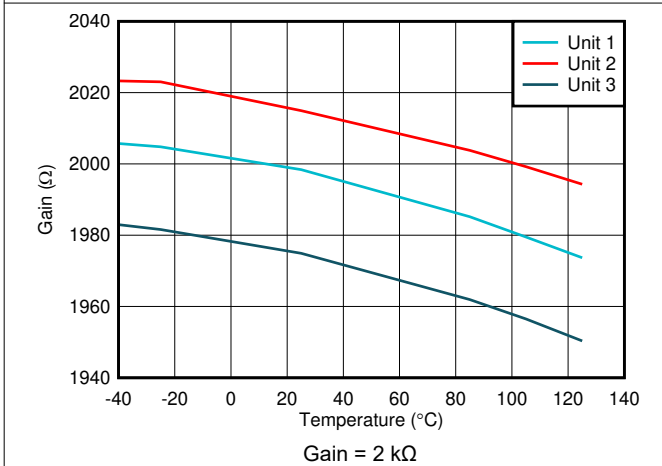


Figure 6-33. Transimpedance Gain vs Ambient Temperature

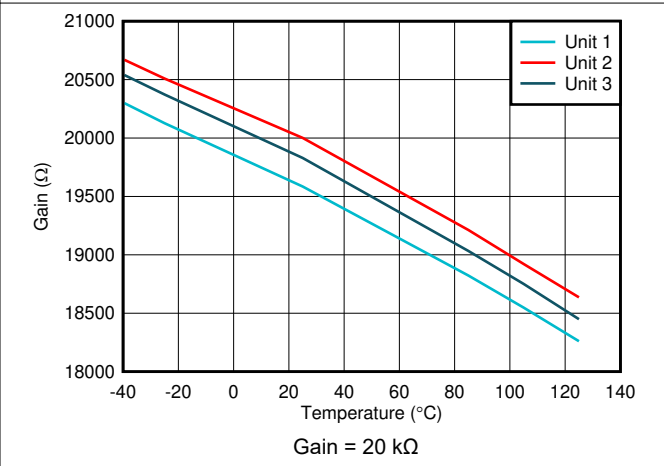


Figure 6-34. Transimpedance Gain vs Ambient Temperature

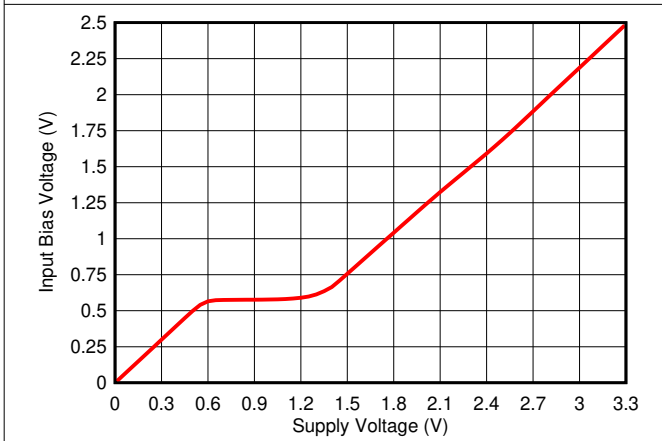


Figure 6-35. Input Bias Voltage vs Supply Voltage

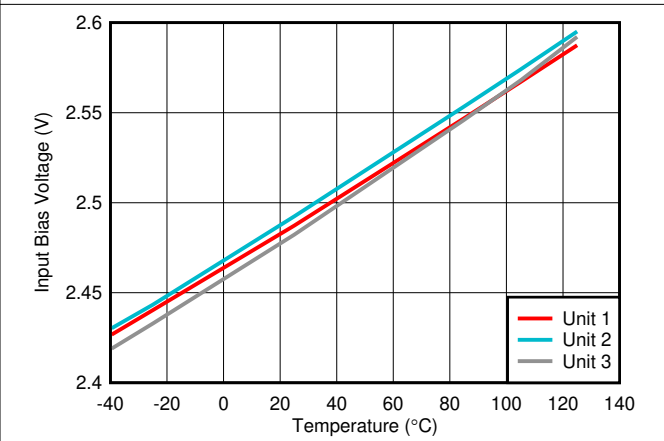


Figure 6-36. Input Bias Voltage vs Ambient Temperature

## 6.9 Typical Characteristics (continued)

At  $V_{DD} = 3.3\text{ V}$ ,  $V_{OCM} = \text{open}$ ,  $V_{OD} = 0\text{ V}$ ,  $C_{PD} = 1\text{ pF}$ ,  $\overline{\text{EN}} = 0\text{ V}$  (enabled),  $\overline{\text{IDC\_EN}} = 3.3\text{ V}$  (disabled),  $R_L = 100\ \Omega$  (differential load between  $\text{OUT}+$  and  $\text{OUT}-$ ), and  $T_A = 25^\circ\text{C}$  (unless otherwise noted).

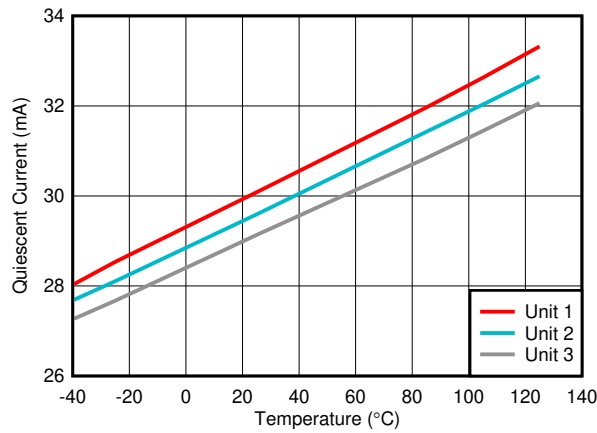


Figure 6-37. Quiescent Current vs Ambient Temperature

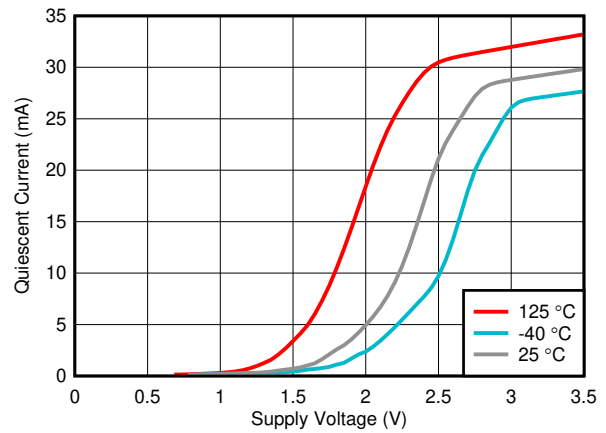
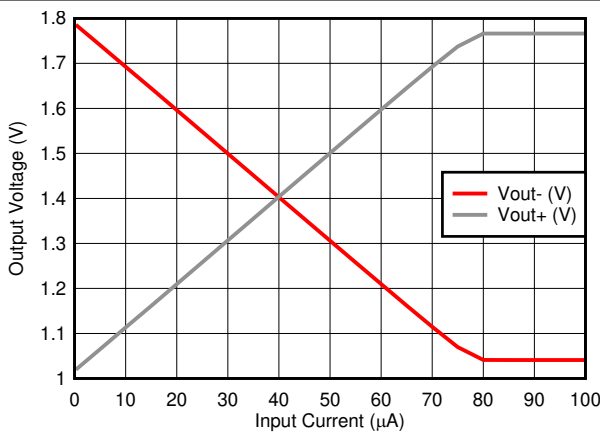
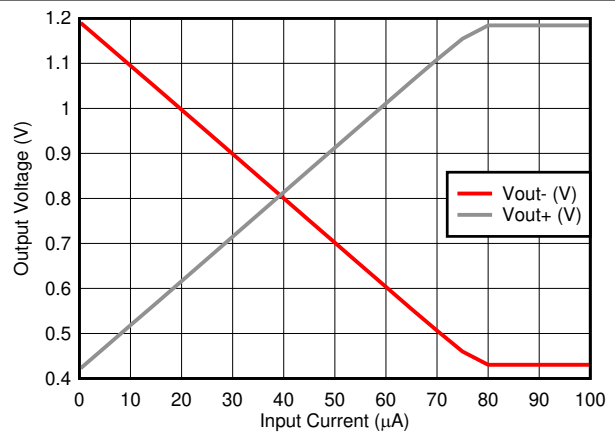


Figure 6-38. Quiescent Current vs Supply Voltage



$V_{OD} = 0.75\text{ V}$ ,  $V_{OCM} = 1.4\text{ V}$

Figure 6-39. High-side Swing vs Input Current



$V_{OD} = 0.75\text{ V}$ ,  $V_{OCM} = 0.8\text{ V}$

Figure 6-40. Low-side Swing vs Input Current

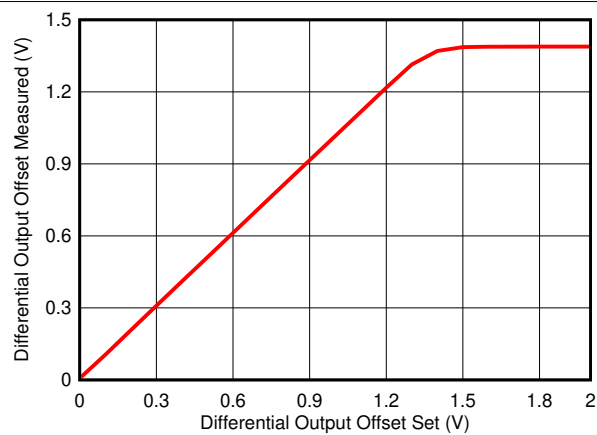


Figure 6-41. Differential Output Offset Gain

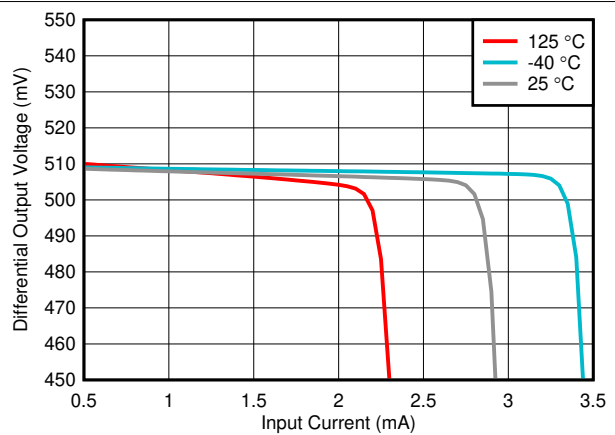
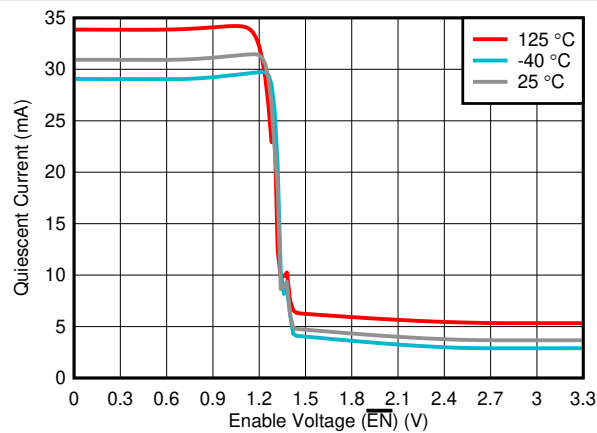


Figure 6-42. Ambient Light Cancellation Range vs Ambient Temperature

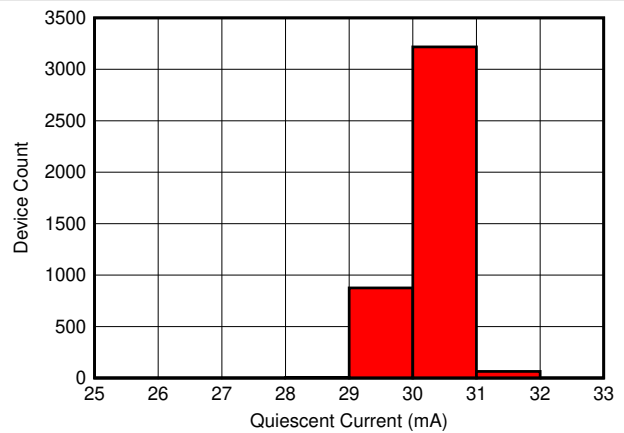
### 6.9 Typical Characteristics (continued)

At  $V_{DD} = 3.3\text{ V}$ ,  $V_{OCM} = \text{open}$ ,  $V_{OD} = 0\text{ V}$ ,  $C_{PD} = 1\text{ pF}$ ,  $\overline{\text{EN}} = 0\text{ V}$  (enabled),  $\overline{\text{IDC\_EN}} = 3.3\text{ V}$  (disabled),  $R_L = 100\ \Omega$  (differential load between  $\text{OUT}+$  and  $\text{OUT}-$ ), and  $T_A = 25^\circ\text{C}$  (unless otherwise noted).

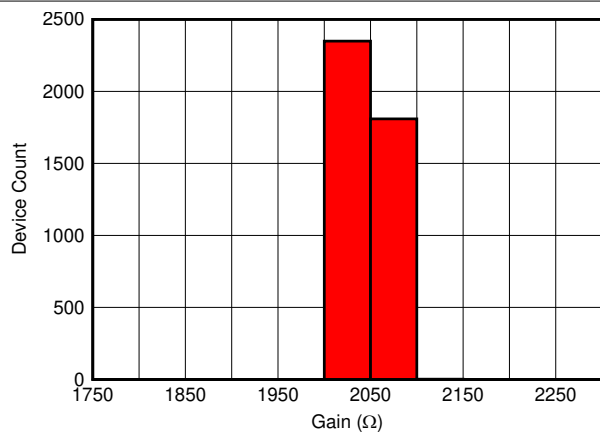


Logic switching demonstrated using EN pin.  $\overline{\text{IDC\_EN}}$  and gain pins behave similarly.

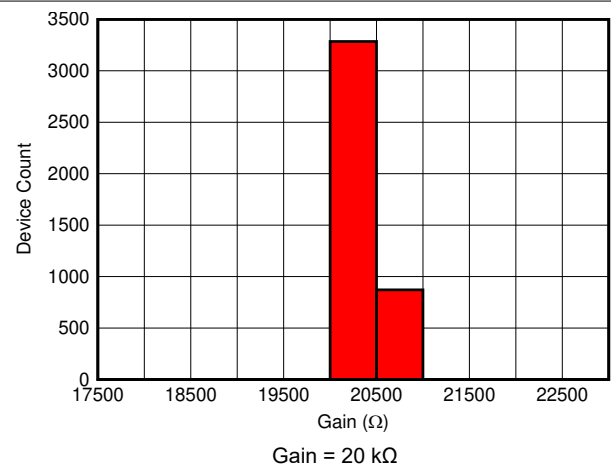
**Figure 6-43. Logic Threshold vs Ambient Temperature**



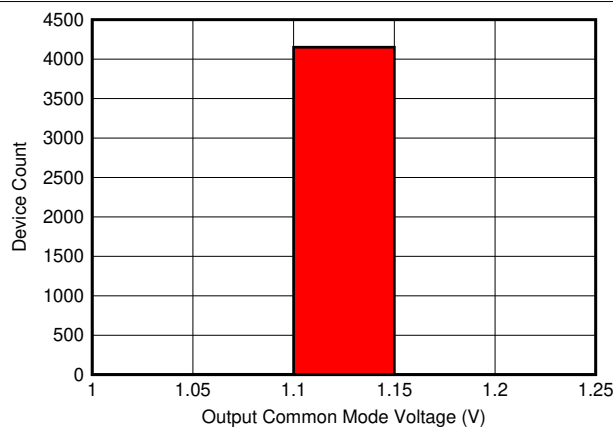
**Figure 6-44. Quiescent Current Distribution**



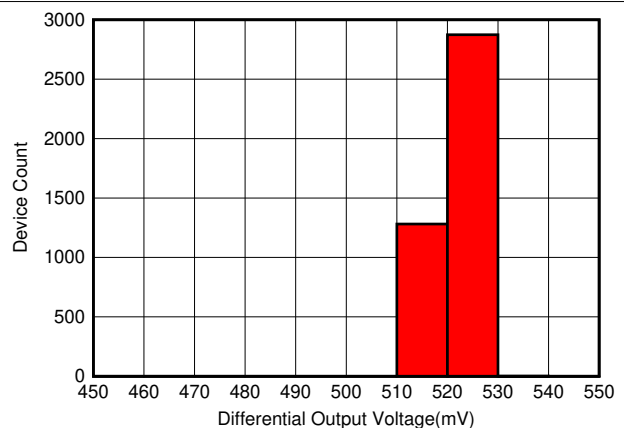
**Figure 6-45. Transimpedance Gain (Low) Distribution**



**Figure 6-46. Transimpedance Gain (High) Distribution**



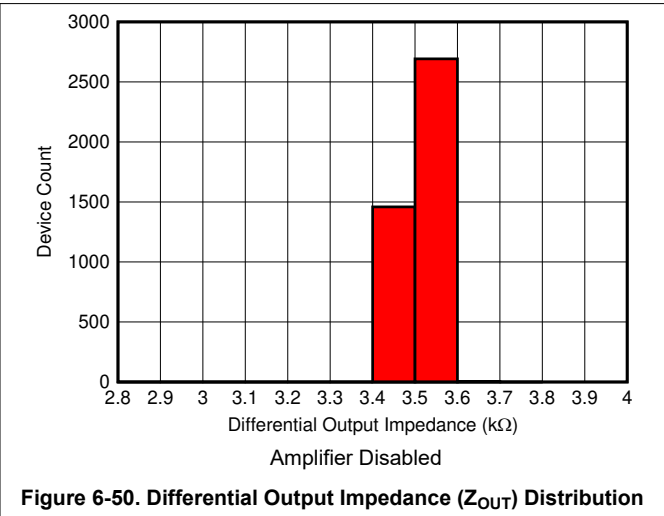
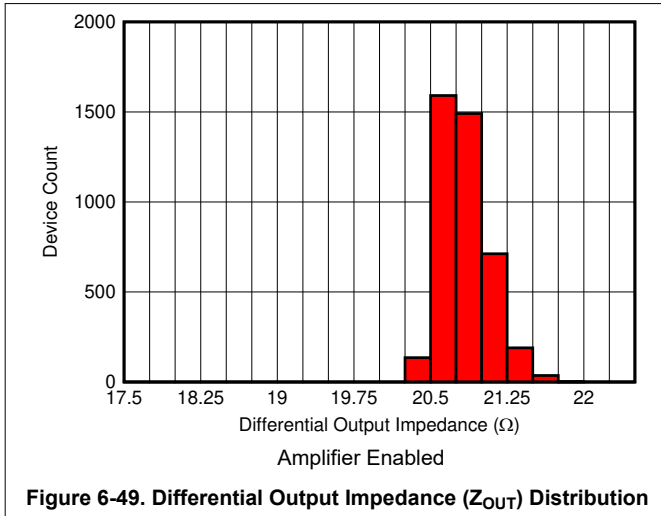
**Figure 6-47. Output Common-Mode Voltage ( $V_{OCM}$ ) Distribution**



**Figure 6-48. Differential Output Offset Voltage ( $V_{OD}$ ) Distribution**

### 6.9 Typical Characteristics (continued)

At  $V_{DD} = 3.3\text{ V}$ ,  $V_{OCM} = \text{open}$ ,  $V_{OD} = 0\text{ V}$ ,  $C_{PD} = 1\text{ pF}$ ,  $\overline{\text{EN}} = 0\text{ V}$  (enabled),  $\overline{\text{IDC\_EN}} = 3.3\text{ V}$  (disabled),  $R_L = 100\ \Omega$  (differential load between  $\text{OUT+}$  and  $\text{OUT-}$ ), and  $T_A = 25^\circ\text{C}$  (unless otherwise noted).





## 7.3 Feature Description

### 7.3.1 Switched Gain Transimpedance Amplifier

The LMH32401 device features a programmable gain transimpedance amplifier (TIA) stage followed by a fixed-gain, single-ended input to differential output amplifier stage. The closed-loop bandwidth and noise of a TIA are affected by the transimpedance gain and photodiode capacitance. For a given value of photodiode capacitance, the LMH32401 device has higher bandwidth in its low-gain configuration compared to the high-gain configuration. Increasing the gain of the TIA stage by a factor of  $X$  increases the output signal by a factor  $X$ , but the noise contribution from the resistor only increases by  $\sqrt{X}$ . The input-referred noise density of the low-gain configuration is therefore higher than the input-referred noise density of the high-gain configuration.

The gain of the TIA stage is controlled by the GAIN pin. Setting this pin low places the TIA in its low-gain configuration, whereas setting the pin high places the TIA in a high-gain configuration. The LMH32401 device defaults to its low-gain configuration when the GAIN pin is left floating.

### 7.3.2 Clamping and Input Protection

The LMH32401 device is designed to work with photodiode (PD) configurations that can source or sink current; however, the LMH32401 is optimized for a sinking current configuration. It is assumed that the LMH32401 device is being used with a PD that is configured with its cathode tied to the amplifier input and the anode tied to a negative supply voltage, unless stated otherwise.

The LMH32401 features two internal clamps, a fast recovery clamp and a soft clamp. The fast recovery clamp is the active clamp when the photodiode is sinking a photocurrent. The soft clamp is the active clamp when the photodiode is sourcing a photocurrent. Stray reflections from nearby objects with high reflectivity can produce large output current pulses from the PD. The linear input range of the LMH32401 device is approximately 65  $\mu\text{A}$  in the high-gain configuration and 650  $\mu\text{A}$  in the low-gain configuration (PD sinking the photocurrent).

Input currents in excess of the linear current range cause the internal nodes of the amplifier to saturate, which increases the amplifier recovery time. The end result is a broadening of the output pulse leading to blind zones in the system response. To protect against this condition, the LMH32401 features an integrated clamp that absorbs and diverts the excess current to the positive supply ( $V_{\text{DD1}}$ ) when the amplifier detects its nodes entering a saturated condition. The integrated clamp minimizes the pulse extension to less than a few ns for input pulses up to 100 mA. The power-supply pins ( $V_{\text{DD1}}$  and  $V_{\text{DD2}}$ ) must each have their own bypass capacitors to prevent large input pulses from affecting the differential output stage. When the amplifier is in low-power mode, the clamp circuitry is still active, thereby protecting the TIA input.

### 7.3.3 ESD Protection

All LMH32401 pins have an internal electrostatic discharge (ESD) protection diode to the positive and negative supply rails to protect the amplifier from ESD events.

### 7.3.4 Differential Output Stage

The differential output stage of the LMH32401 device performs the following two functions, which are common across all differential amplifiers:

1. Converts the single-ended output from the TIA stage to a differential output.
2. Performs a common-mode output shift to match the specified ADC input common-mode voltage.

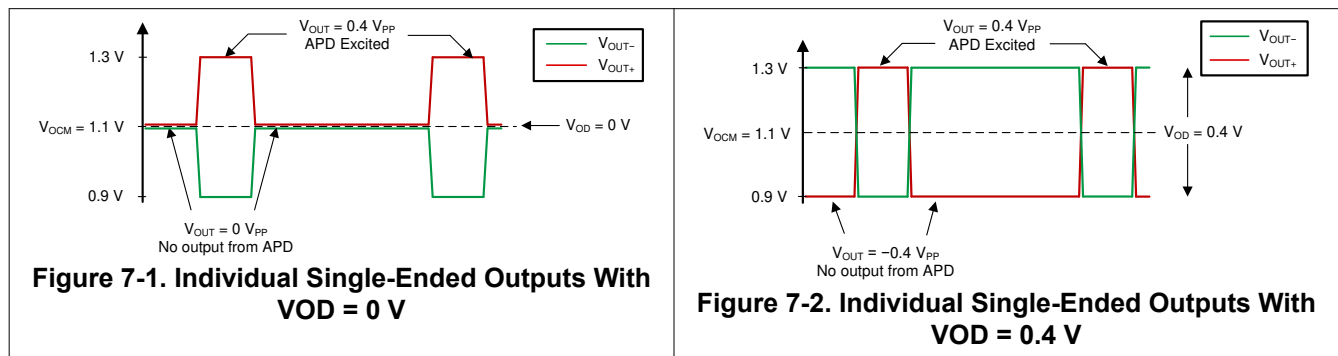
The differential output stage has two 10- $\Omega$  series resistors on its output to isolate the amplifier output stage transistors from the package bond-wire inductance and printed circuit board (PCB) capacitance. The net gain of the LMH32401 device (TIA + output stage) is 2 k $\Omega$  (low gain) and 20 k $\Omega$  (high gain) when driving an external 100- $\Omega$  resistor. When the external load resistor is increased above 100  $\Omega$ , the effective gain from the IN pin to the differential output pin increases. Conversely, when the external load resistor is decreased to less than 100  $\Omega$ , the effective gain from the IN pin to the differential output pin decreases as a result of the larger voltage drop across the two internal 10- $\Omega$  resistors. When there is no load resistor between the OUT+ and OUT– pins, the effective gain of the LMH32401 is 2.4 k $\Omega$  and 24 k $\Omega$  in the low-gain and high-gain configurations, respectively.

The output common-mode voltage of the LMH32401 device can be set externally through the VO<sub>CM</sub> pin. A resistor divider internal to the amplifier, between VDD2 and ground sets the default voltage to 1.1 V. The internal resistors generate common-mode noise that is typically rejected by the CMRR of the subsequent ADC stage. To maximize the amplifier signal-to-noise ratio (SNR), place an external noise bypass capacitor to ground on the VO<sub>CM</sub> pin. In single-ended signal chains, such as ToF systems that use time-to-digital converters (TDCs), only a single output of the LMH32401 device is needed. In such situations, terminate the unused differential output in the same manner as the used output to maintain balance and symmetry. The signal swing of the single-ended output is half the available differential output swing. Additionally, the common-mode noise of the output stage, which is typically rejected by the differential input ADC, is now added to the total noise, further degrading SNR.

The output stage of the LMH32401 device has an additional VOD input that sets the differential output between OUT<sub>-</sub> and OUT<sub>+</sub>. [Figure 7-1](#) shows how each output pin of the LMH32401 device is at the voltage set by the VO<sub>CM</sub> pin (default = 1.1 V) when the photodiode output current is zero and the VOD input is set to 0 V. When the VOD pin is driven to a voltage of X volts, the two output pins are separated by X volts when the photodiode current is zero. The average voltage is still equal to VO<sub>CM</sub>. For example, [Figure 7-2](#) shows if VO<sub>CM</sub> is set to 1.1 V and VOD is set to 0.4 V, then OUT<sub>-</sub> = 1.1 V + 0.2 V = 1.3 V and OUT<sub>+</sub> = 1.1 V – 0.2 V = 0.9 V.

The VOD pin is functional only when the LMH32401 device is used with a PD that sinks the photocurrent. Set VOD = 0 V when the LMH32401 device is interfaced with a PD that sources the photocurrent. The VOD output offset feature is included in the LMH32401 device because the output current of a photodiode is unipolar. Depending on the reverse bias configuration, the photodiode can either sink or source current, but cannot do both at the same time. With the anode connected to a negative bias and the cathode connected to the TIA stage input, the photodiode can only sink current, which implies that the TIA stage output swings in a positive direction above its default input bias voltage (2.47 V). Subsequently, OUT<sub>-</sub> only swings below VO<sub>CM</sub> and OUT<sub>+</sub> only swings above VO<sub>CM</sub>. [Figure 7-1](#) shows how the LMH32401 device only uses half of its output swing range ( $V_{OUT} = V_{OUT+} - V_{OUT-}$ ) when VOD = 0 V, because one output never swings below VO<sub>CM</sub> and the other output never goes above VO<sub>CM</sub>. The signal dynamic range in this case is  $0.4 V_{PP} - 0 V = 0.4 V_{PP}$ .

[Figure 7-2](#) shows how the VOD pin voltage allows OUT<sub>-</sub> to be level-shifted above VO<sub>CM</sub> and OUT<sub>+</sub> to be level-shifted below VO<sub>CM</sub> to maximize the output swing capabilities of the amplifier. The signal dynamic range in this case is  $0.4 V_{PP} - (-0.4 V_{PP}) = 0.8 V_{PP}$ .



When the LMH32401 device drives a 100-Ω load, the voltage set at the VOD pin is equal to the differential output offset ( $V_{OD} = V_{OUT+} - V_{OUT-}$ ) when the input signal current is zero. Use [Equation 1](#) to calculate the differential output offset under other load conditions.

$$V_{OD} = 1.2 \times VOD \times \frac{R_L}{(R_L \times 20 \Omega)} \quad (1)$$

Where:

- VOD = Voltage applied at pin 9
- $V_{OD} = (V_{OUT+} - V_{OUT-})$
- $R_L$  = External load resistance

## 7.4 Device Functional Modes

### 7.4.1 Ambient Light Cancellation (ALC) Mode

The LMH32401 device has an integrated DC cancellation loop that cancels and voltage offsets from incidental ambient light. The ALC mode only works when the PD is sinking the photocurrent. The DC cancellation loop is enabled by setting  $\overline{\text{DC\_EN}}$  low. Incident ambient light on a photodiode produces a DC current resulting in an offset voltage at the output of the LMH32401's TIA stage. The *Functional Block Diagram* shows how the ALC loop senses the low-frequency DC offset at the output of the TIA stage and compares it against an internal reference voltage ( $V_{\text{REF}}$ ). The ALC loop then outputs an opposing DC current ( $I_{\text{DC}}$ ) to compensate for the differential offset voltage at its input. The loop has a high-pass cutoff frequency of 100 kHz. The ambient light cancellation loop is disabled when the amplifier is placed in power-down mode.

The shot noise current introduced by the DC cancellation loop increases the overall amplifier noise; so, if the ambient light level is negligible, then disable the loop to improve SNR. The cancellation loop helps save PCB space and system costs by eliminating the need for external AC coupling passive components. Additionally, the extra trace inductance and PCB capacitance introduced by using external AC coupling components degrades the LMH32401 device dynamic performance.

### 7.4.2 Power-Down Mode (Multiplexer Mode)

The LMH32401 device can be placed in low-power mode by setting  $\overline{\text{EN}}$  high, which helps in saving system power. Enabling low-power mode puts the outputs of the internal amplifiers in the LMH32401 device, including the differential outputs, in a high-impedance state. *Figure 7-3* shows how this device feature can further save board space and cost by eliminating the need for a discrete high-speed multiplexer, if a system consists of several photodiode and amplifier channels multiplexed to a single ADC channel. The disabled channel outputs are not an ideal open circuit so as the number of multiplexed channels increases the disabled channels begin to load the enabled channel. Multiplexing more than four channels in parallel degrades the performance of the enabled channel. When the amplifier is in its low-power mode, the clamp circuitry is still active thereby protecting the TIA input. The ambient light cancellation loop is disabled when the amplifier is placed in power-down mode. When the LMH32401 device is brought out of power-down operation the ambient light cancellation loop requires several time constants to settle. *Figure 6-9* shows the low-frequency loop response which in turn determines the time constant needed for the loop to settle.

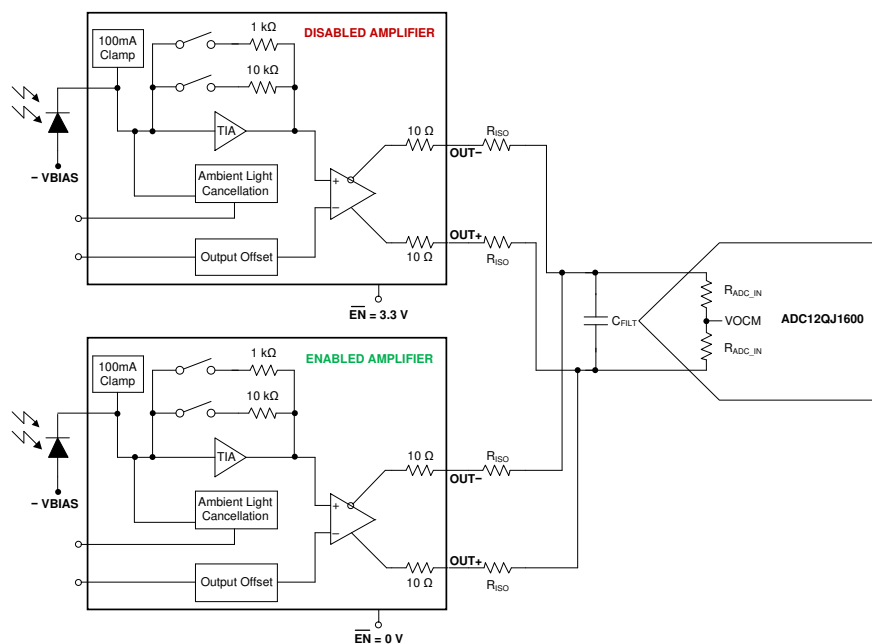


Figure 7-3. Configuring Two LMH32401 Devices in Multiplexer Mode to Drive a Single ADC

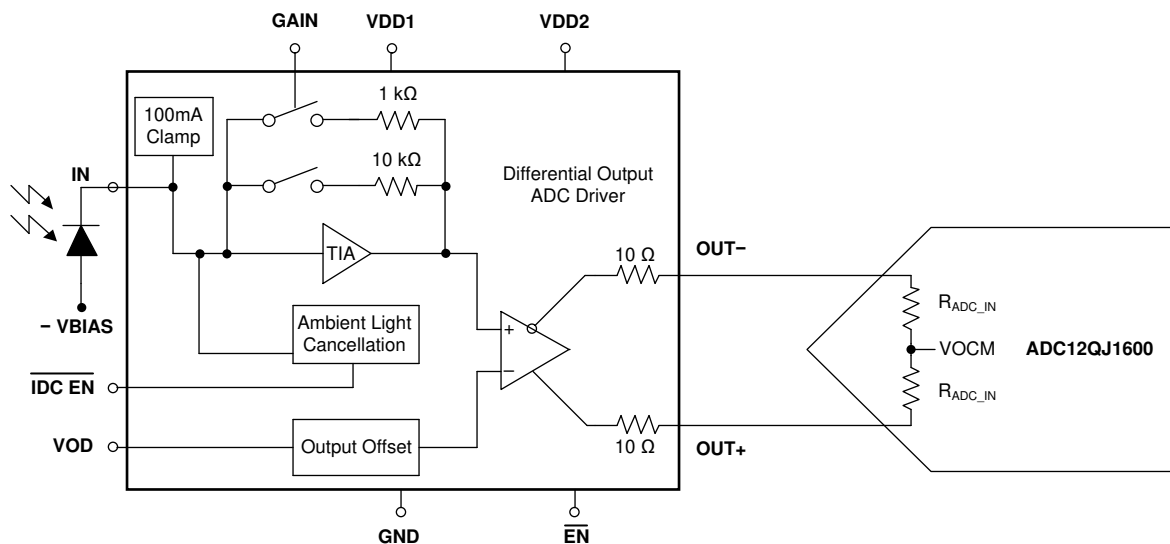
## 8 Application and Implementation

### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

### 8.1 Application Information

The differential outputs of the LMH32401 device can directly drive a high-speed differential input ADC. [Figure 8-1](#) shows the LMH32401 differential outputs directly driving the [ADC12QJ1600](#). The effective signal gain between the TIA input and the ADC input is 2 k $\Omega$  or 20 k $\Omega$  when driving an ADC with a 100- $\Omega$  differential input impedance ( $R_{ADC\_IN} = 50 \Omega$ ). [Equation 2](#) gives the effective signal gain between the TIA input and the ADC input when driving an ADC with any other value of differential input impedance ( $R_{ADC\_IN} \neq 50 \Omega$ ).



**Figure 8-1. LMH32401 to ADC Interface**

$$A_v = 2 \text{ k}\Omega \text{ (or } 20 \text{ k}\Omega) \times 1.2 \times \frac{2 \times R_{ADC\_IN}}{(2 \times R_{ADC\_IN} + 20 \Omega)} \quad (2)$$

Where:

- $A_v$  = Differential gain from the TIA input to the ADC input
- $R_{ADC\_IN}$  = Input resistance of the ADC

[Figure 8-2](#) shows a matching resistor network between the LMH32401 output and the ADC12QJ1600 input. The matching network is needed to prevent signal reflections when the signal path between the LMH32401 and ADC is very long. [Equation 3](#) gives the effective gain from the TIA input to the ADC input when using a matching resistor network.

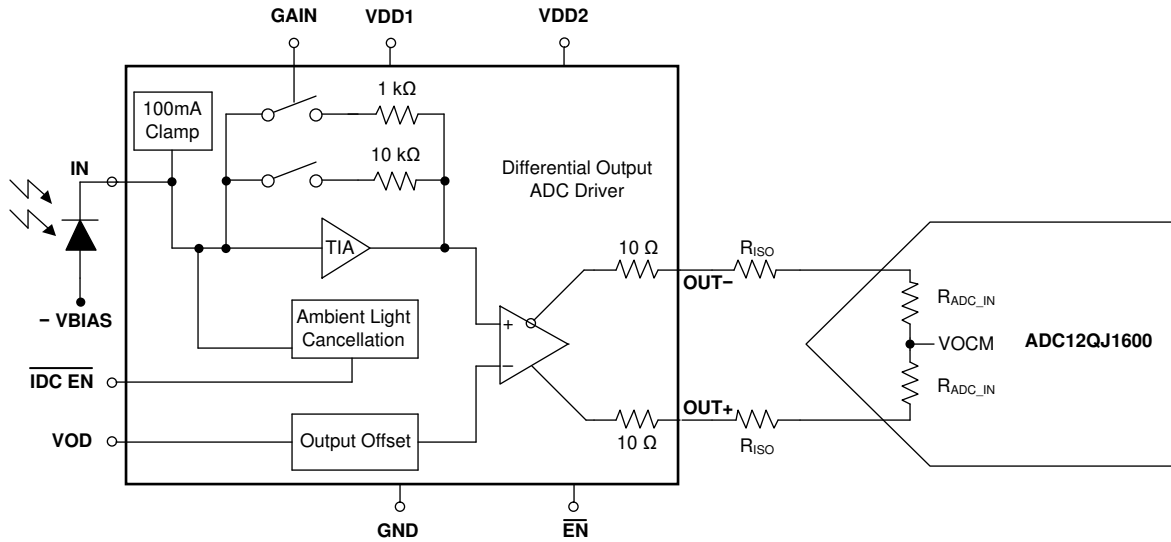


Figure 8-2. LMH32401 to ADC Interface with a Matching Resistor Network

$$A_V = 2 \text{ k}\Omega \text{ (or } 20 \text{ k}\Omega) \times 1.2 \times \frac{2 \times R_{\text{ADC\_IN}}}{(2 \times R_{\text{ADC\_IN}} + 2 \times R_{\text{ISO}} + 20 \Omega)} \quad (3)$$

Where:

- $A_V$  = Gain from the TIA input to the ADC input
- $R_{\text{ADC\_IN}}$  = Differential input resistance of the ADC
- $R_{\text{ISO}}$  = Series resistance between the TIA and ADC

Equation 4 gives the voltage to be applied at the VOD pin (pin 9) if a certain differential offset voltage ( $V_{\text{OD}}$ ) is needed at the ADC input for the circuit in Figure 8-2.

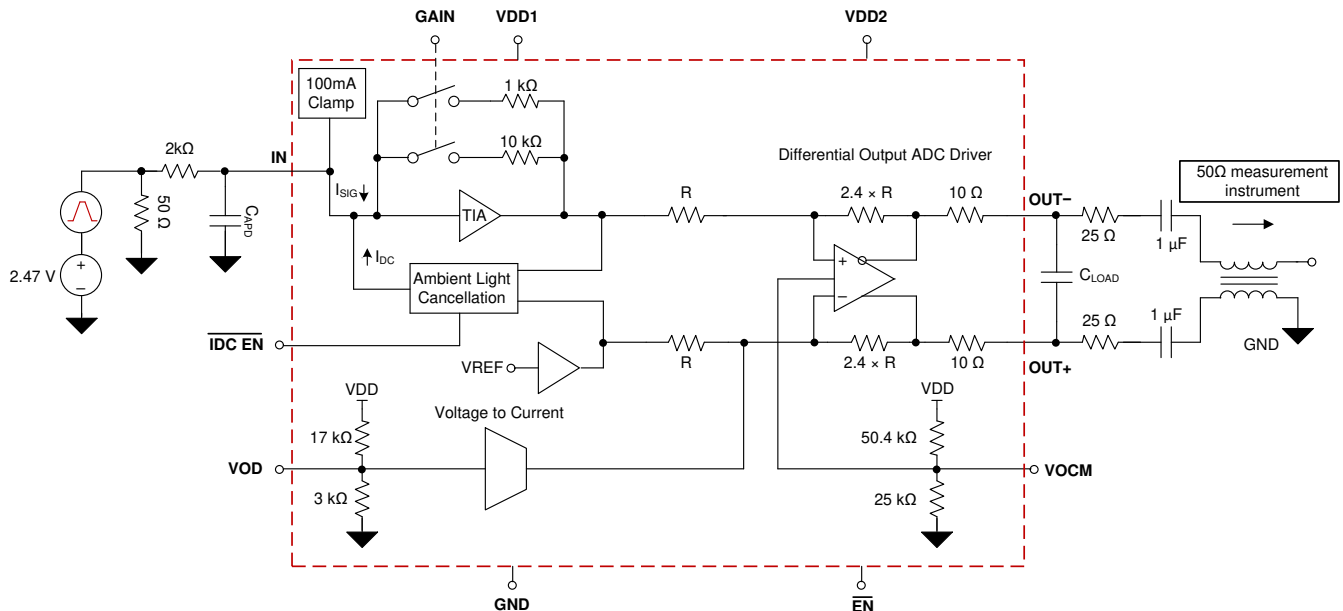
$$V_{\text{OD}} = V_{\text{OD}} \times \left( \frac{1}{1.2} \right) \times \frac{(2 \times R_{\text{ADC\_IN}} + 2 \times R_{\text{ISO}} + 20 \Omega)}{(2 \times R_{\text{ADC\_IN}})} \quad (4)$$

Where:

- $V_{\text{OD}}$  = Voltage applied at pin 9
- $V_{\text{OD}}$  = Desired differential offset voltage at the ADC input
- $R_{\text{ADC\_IN}}$  = Differential input resistance of the ADC
- $R_{\text{ISO}}$  = Series resistance between the TIA and ADC

## 8.2 Typical Application

This section demonstrates the performance of the LMH32401 device when the input current flows into the IN pin. Figure 8-3 shows the circuit used to test the LMH32401 device with a voltage source. This configuration demonstrates the use case when the photodiode's anode is tied to the amplifier input and its cathode is tied to a positive voltage greater than 2.47 V.



**Figure 8-3. LMH32401 Test Circuit**

### 8.2.1 Design Requirements

The objective is to design a low-noise, wideband differential output transimpedance amplifier. The design requirements are as follows:

- Amplifier supply voltage: 3.3 V
- Transimpedance gain: 2 kΩ and 20 kΩ
- Input capacitance:  $C_{PCB} \cong 1$  pF
- Target bandwidth: > 250 MHz
- Differential output offset (VOD): 0 V
- Ambient light cancellation (IDC\_EN): 3.3 V (disabled)

### 8.2.2 Detailed Design Procedure

Figure 8-3 shows the LMH32401 device test circuit used to measure its bandwidth and transient pulse response. The voltage source is DC biased close to the input bias voltage of the LMH32401 device (approximately 2.47 V). The internal design of the LMH32401 device is optimized to only source current out of the input pin (pin 3), and all the data shown previously is with the current flowing out of the pin. When the voltage input from the source exceeds 2.47 V, the LMH32401 device input will sink the current. Set VOD = 0 V when the input has to sink the current from the photodiode, or in this case the voltage source. Set the DC bias so that sum of the input AC and DC component is always greater than the input voltage (2.47 V) when testing the LMH32401 device with a network analyzer or sinusoidal source.

Figure 8-4 and Figure 8-5 shows the bandwidth of the LMH32401 device when its input is sinking the current. The input current range of the LMH32401 device is reduced when it is sinking the current. This effect is seen by the decrease in bandwidth as the output swing increases and is more pronounced in a gain configuration of 20 kΩ. Compare Figure 8-4 with Figure 6-1 and Figure 6-3 to see the effect of current direction and input range in a 2 kΩ gain configuration. In a similar way, compare Figure 8-5 with Figure 6-2 and Figure 6-4 to see the effect of current direction and input range in a gain of 20 kΩ.

Figure 8-6 and Figure 8-7 show the pulsed output response of the LMH32401 device when the input current is increased past the amplifier linear input range. When the input is sinking current, a soft clamp will aid in fast recovery; however, the pulse will stretch slightly as the input current overrange increases. Compare Figure 8-6 with Figure 6-21 to see the pulse extension effect in a gain of 2 kΩ. Compare Figure 8-7 with Figure 6-22 to see the pulse extension effect in a gain of 20 kΩ. Knowledge of the pulse extension can be used to determine the approximate input current even under overrange situations that can occur due to the presence of retro-reflectors in the environment. As shown in Figure 7-1, each half of the differential output pulse will only swing above or below the VOVM voltage and the resulting maximum differential output swing is 0.75 V<sub>PP</sub> since VOD is set to 0 V. Consequently only half of the total ADC range is utilized in this photodiode configuration.

### 8.2.3 Application Curves

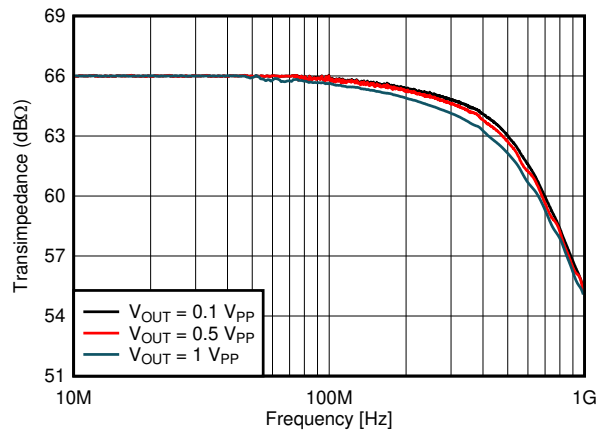


Figure 8-4. Bandwidth vs Output Swing  
(Gain = 2 kΩ)

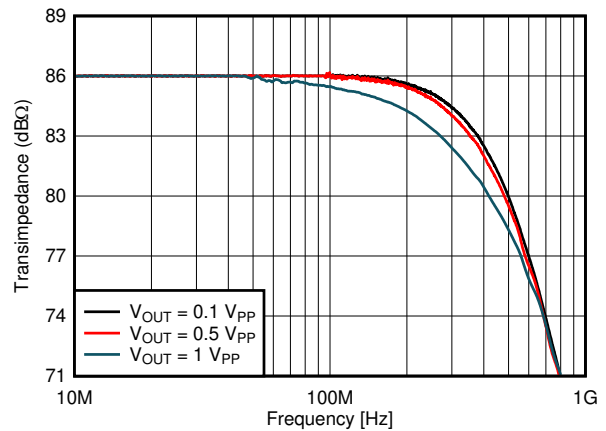


Figure 8-5. Bandwidth vs Output Swing  
(Gain = 20 kΩ)

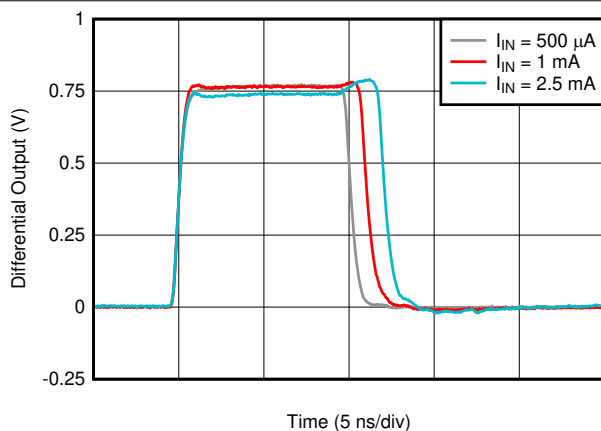


Figure 8-6. Pulse Response vs Input Current  
(Gain = 2 kΩ)

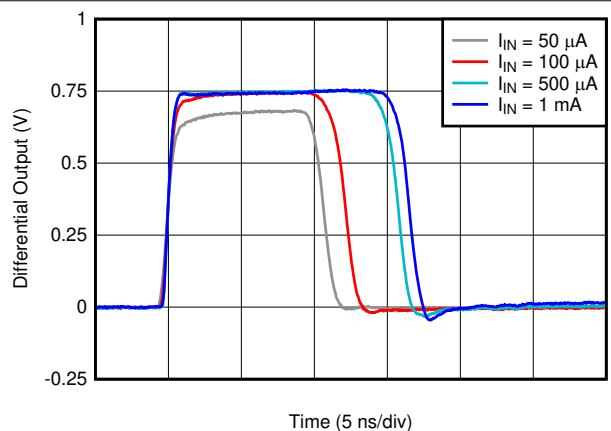


Figure 8-7. Pulse Response vs Input Current  
(Gain = 20 kΩ)

## 9 Power Supply Recommendations

The LMH32401 device operates on 3.3-V supplies. The VDD1 and VDD2 pins must always be driven from the same supply source and individually bypassed. A low power-supply source impedance must be maintained across frequency. So use multiple bypass capacitors in parallel. Place the bypass capacitors as close to the supply pins as possible. Place the smallest capacitor on the same side of the PCB as the LMH32401 device. Placing the larger valued bypass capacitors on the same side of the PCB is preferable as well. However, if there are space constraints, then the capacitors can be moved to the opposite side of the PCB using multiple vias to reduce the series inductance resulting from the vias. The LMH32401 device can operate on bipolar supplies by connecting pins 1 and 7 to the negative supply. The thermal pad must always be connected to the most negative supply. The digital pin threshold voltages must be appropriately level shifted as they are connected to voltages at pins 1 and 7.

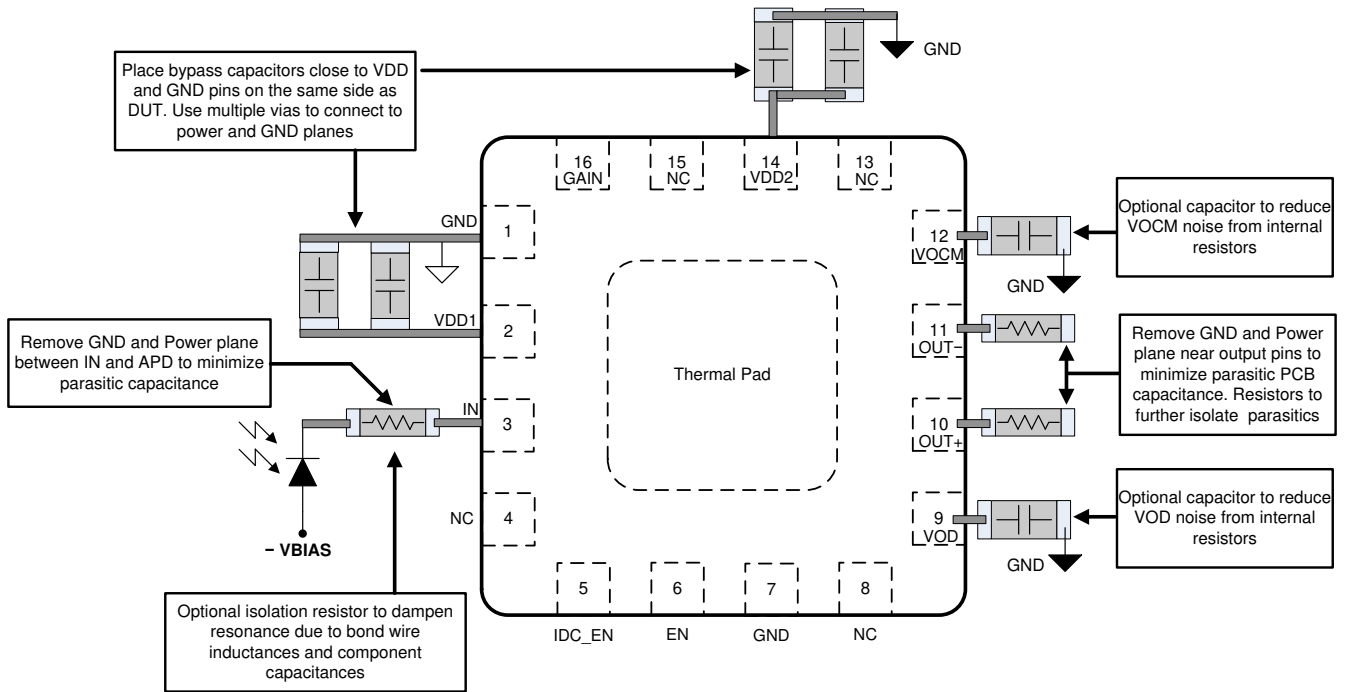
## 10 Layout

### 10.1 Layout Guidelines

Achieving optimum performance with a high-frequency amplifier such as the LMH32401 device requires careful attention to board layout parasitics and external component types. Recommendations that optimize performance include the following:

- **Minimize parasitic capacitance from the signal I/O pins to ac ground.** Parasitic capacitance on the output pins can cause instability whereas parasitic capacitance on the input pin reduces the amplifier bandwidth. To reduce unwanted capacitance, cut out the power and ground traces under the signal input and output pins. Otherwise, ground and power planes must be unbroken elsewhere on the board.
- **Minimize the distance from the power-supply pins to high-frequency bypass capacitors.** Use high-quality, 100-pF to 0.1- $\mu$ F, C0G and NPO-type decoupling capacitors with voltage ratings at least three times greater than the amplifiers maximum power supplies. Place the smallest value capacitors on the same side as the DUT. If space constraints force the larger value bypass capacitors to be placed on the opposite side of the PCB, then use multiple vias on the supply and ground side of the capacitors. This configuration makes sure that there is a low-impedance path to the amplifiers power-supply pins across the amplifiers gain bandwidth specification. Avoid narrow power and ground traces to minimize inductance between the pins and the decoupling capacitors. Larger (2.2- $\mu$ F to 6.8- $\mu$ F) decoupling capacitors that are effective at lower frequency must be used on the supply pins. Place these decoupling capacitors further from the device. Share the decoupling capacitors among several devices in the same area of the printed circuit board (PCB).

## 10.2 Layout Example



**Figure 10-1. Layout Recommendation**

## 11 Device and Documentation Support

### 11.1 Device Support

#### 11.1.1 Development Support

- Texas Instruments, [LMH32401 Transimpedance Amplifier Evaluation Module](#).
- Texas Instruments, [Optical Front-End System Reference Design design guide](#).
- Texas Instruments, [LIDAR-Pulsed Time-of-Flight Reference Design Using High-Speed Data Converters design guide](#).
- Texas Instruments, [LIDAR Pulsed Time of Flight Reference Design design guide](#).

### 11.2 Documentation Support

#### 11.2.1 Related Documentation

For related documentation see the following:

- Texas Instruments, [LMH32401IRGT Evaluation Module user's guide](#).
- Texas Instruments, [Transimpedance Considerations for High-Speed Amplifiers application report](#).
- Texas Instruments, [What You Need To Know About Transimpedance Amplifiers – Part 1 blog](#).
- Texas Instruments, [An Introduction to Automotive LIDAR](#).
- Texas Instruments, [Maximizing the Dynamic Range of Analog Front Ends Having a Transimpedance Amplifier](#).
- Texas Instruments, [Time of Flight and LIDAR – Optical Front End Design](#).
- Texas Instruments, [What You Need To Know About Transimpedance Amplifiers – Part 2 blog](#).
- Texas Instruments, [Training Video: How to Design Transimpedance Amplifier Circuits](#).
- Texas Instruments, [Training Video: High-Speed Transimpedance Amplifier Design Flow](#).
- Texas Instruments, [Training Video: How to Convert a TINA-TI Model into a Generic SPICE Model](#).

### 11.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on [ti.com](#). Click on [Subscribe to updates](#) to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

### 11.4 Support Resources

[TI E2E™ support forums](#) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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### 11.5 Trademarks

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All trademarks are the property of their respective owners.

### 11.6 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 11.7 Glossary

[TI Glossary](#) This glossary lists and explains terms, acronyms, and definitions.

## 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

**PACKAGING INFORMATION**

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">LMH32401IRGTR</a>	Active	Production	VQFN (RGT)   16	3000   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	L32401
LMH32401IRGTR.B	Active	Production	VQFN (RGT)   16	3000   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	L32401
<a href="#">LMH32401IRGTT</a>	Active	Production	VQFN (RGT)   16	250   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	L32401
LMH32401IRGTT.B	Active	Production	VQFN (RGT)   16	250   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	L32401
<a href="#">LMH32401YR</a>	Active	Production	DIESALE (Y)   0	3000   LARGE T&R	Yes	Call TI	N/A for Pkg Type	-40 to 125	
LMH32401YR.B	Active	Production	DIESALE (Y)   0	3000   LARGE T&R	Yes	Call TI	N/A for Pkg Type	-40 to 125	

(1) **Status:** For more details on status, see our [product life cycle](#).

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

**Important Information and Disclaimer:** The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

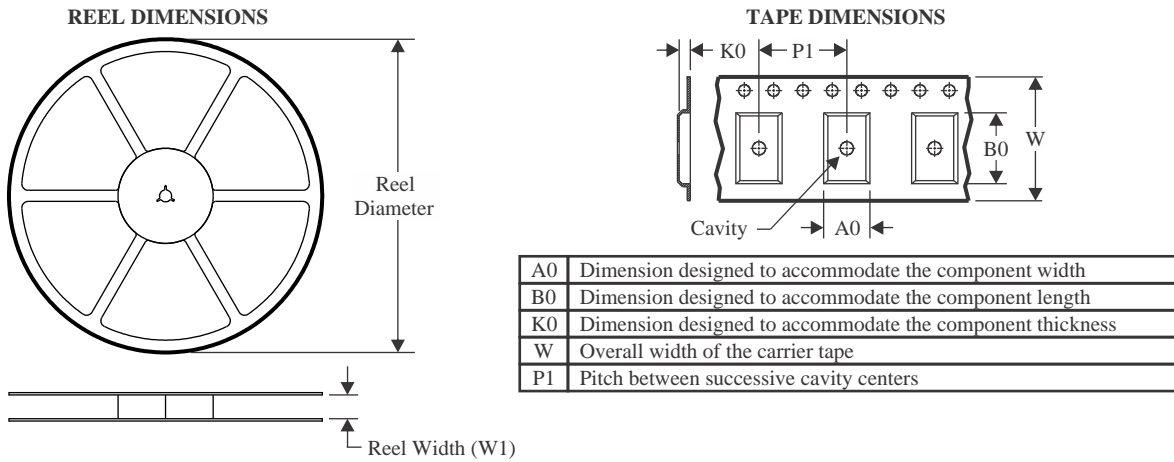
In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

**OTHER QUALIFIED VERSIONS OF LMH32401 :**

- Automotive : [LMH32401-Q1](#)

## NOTE: Qualified Version Definitions:

- Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

**TAPE AND REEL INFORMATION**

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMH32401IRGTR	VQFN	RGT	16	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
LMH32401IRGTT	VQFN	RGT	16	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
LMH32401YR	DIESALE	Y	0	3000	180.0	8.4	1.1	1.1	0.4	4.0	8.0	Q1

## TAPE AND REEL BOX DIMENSIONS



\*All dimensions are nominal

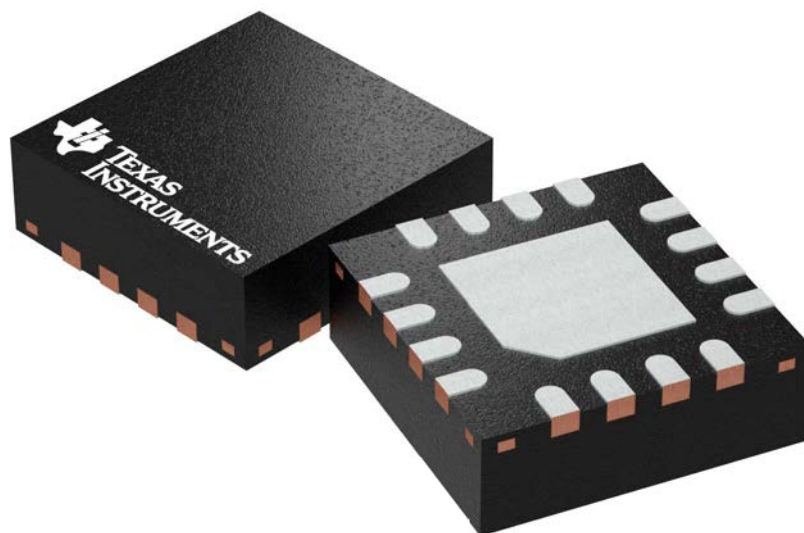
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LMH32401IRGTR	VQFN	RGT	16	3000	367.0	367.0	35.0
LMH32401IRGTT	VQFN	RGT	16	250	210.0	185.0	35.0
LMH32401YR	DIESALE	Y	0	3000	210.0	185.0	35.0

**RGT 16**

**GENERIC PACKAGE VIEW**

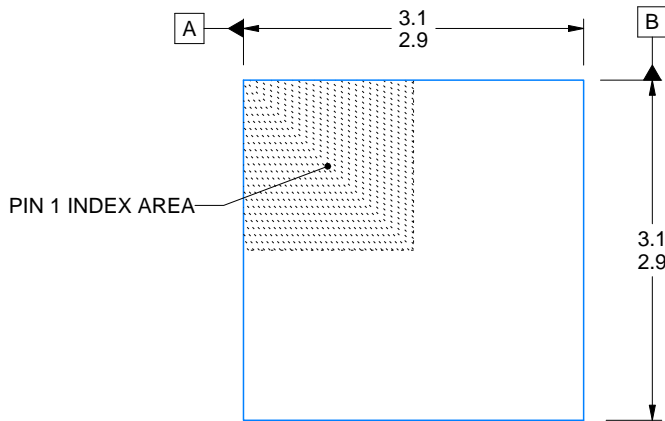
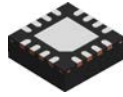
**VQFN - 1 mm max height**

PLASTIC QUAD FLATPACK - NO LEAD

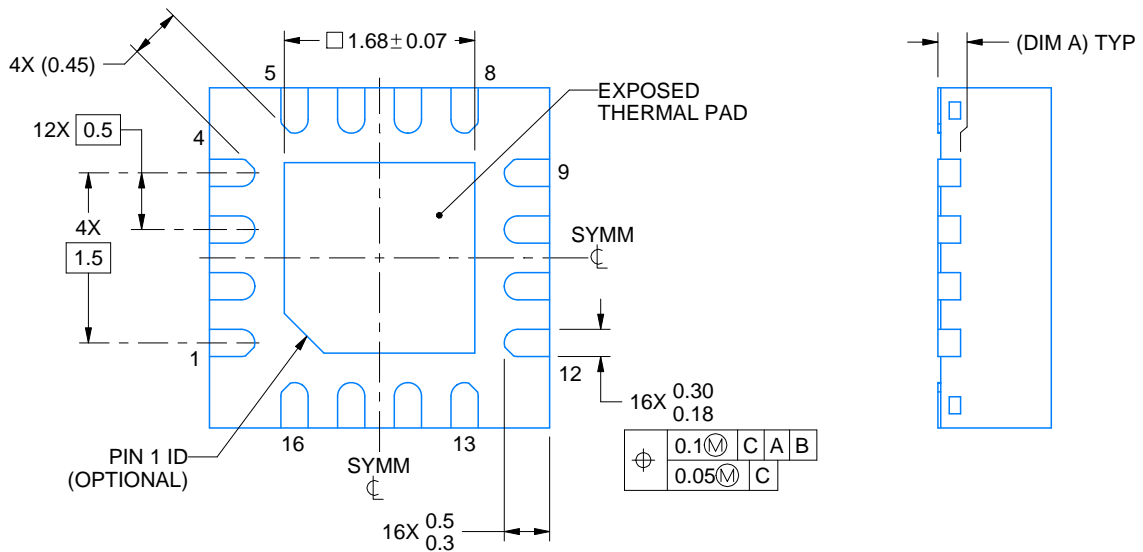
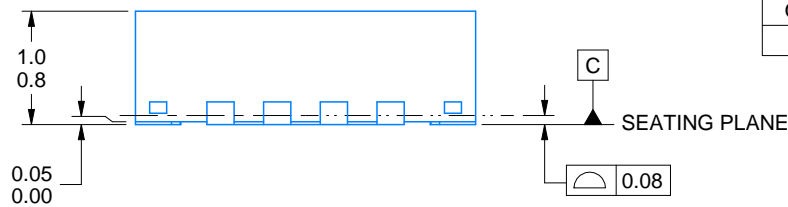


Images above are just a representation of the package family, actual package may vary.  
Refer to the product data sheet for package details.

4203495/1



SIDE WALL METAL THICKNESS DIM A	
OPTION 1	OPTION 2
0.1	0.2



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NOTES:

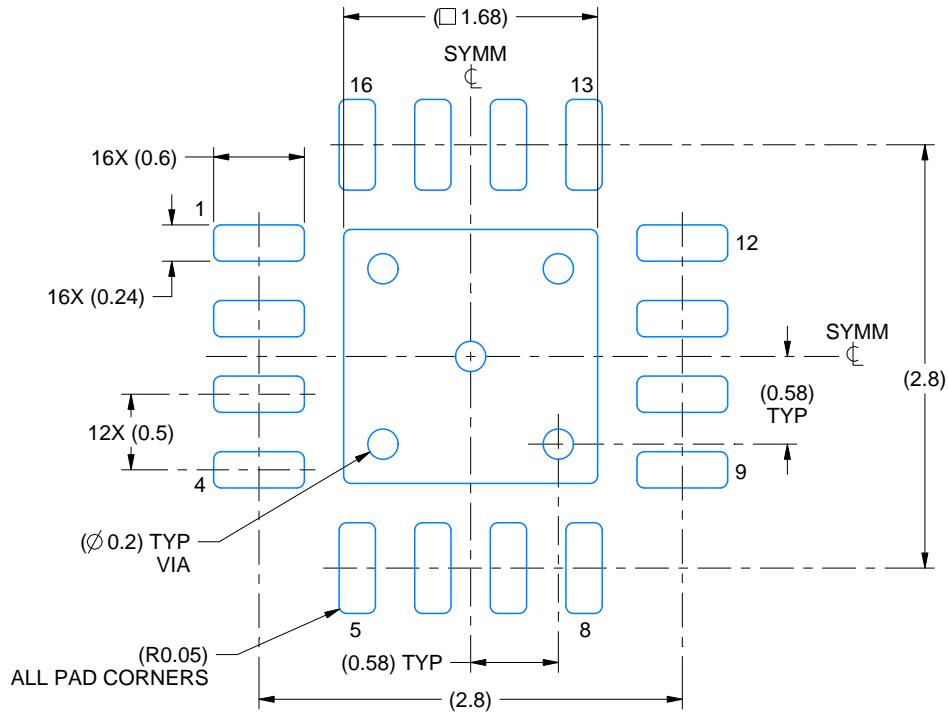
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

# EXAMPLE BOARD LAYOUT

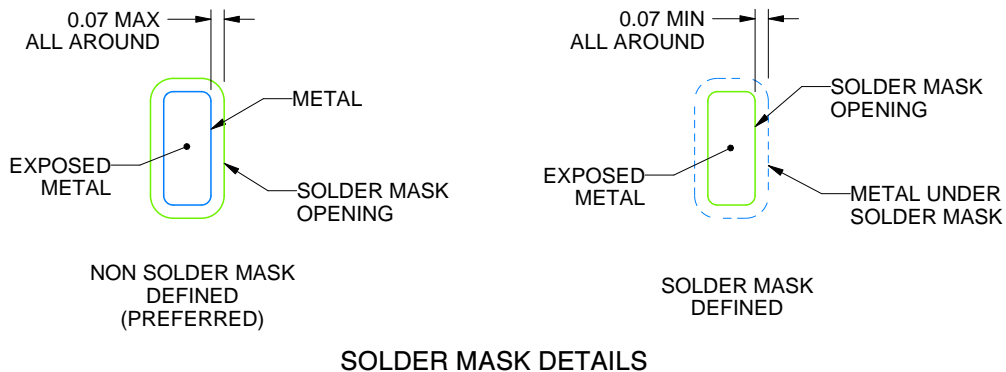
RGT0016C

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:20X



SOLDER MASK DETAILS

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NOTES: (continued)

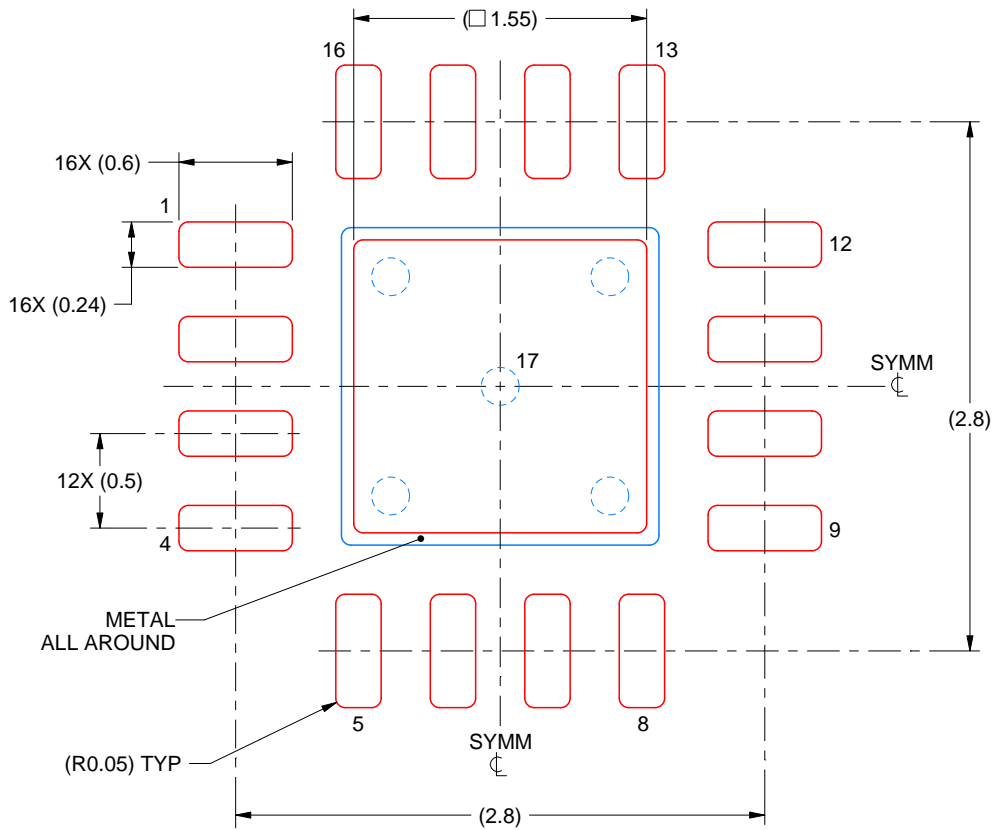
4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 ([www.ti.com/lit/slua271](http://www.ti.com/lit/slua271)).
5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

# EXAMPLE STENCIL DESIGN

RGT0016C

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



**SOLDER PASTE EXAMPLE**  
BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD 17:  
85% PRINTED SOLDER COVERAGE BY AREA UNDER PACKAGE  
SCALE:25X

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NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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