







OPA863, OPA2863, OPA4863 SBOS982J - JUNE 2020 - REVISED JUNE 2023

OPAx863 Low-Power, 110-MHz, Rail-to-Rail Input/Output Voltage-Feedback Op Amps

1 Features

Wide-bandwidth

- Unity-gain bandwidth: 110-MHz (A_V = 1 V/V)

Gain-bandwidth product: 50-MHz

Low power

Quiescent current: 700-µA/ch (typical)

Power down mode: 1.5- μ A (maximum, V_S = 3 V)

Supply voltage: 2.7-V to 12.6-V Input voltage noise: 5.9-nV/√Hz

Slew rate: 105-V/µs

Rail-to-rail input and output

 HD_2/HD_3 : -129 dBc/-138 dBc at 20 kHz (2- V_{PP})

Operating temperature range:

-40°C to +125°C

Additional features:

Overload power limit

Output short-circuit protection

High-precision version: OPAx863A

2 Applications

Low-power SAR and ΔΣ ADC driver

ADC reference buffer

Low-side current sensing

Photodiode TIA interface

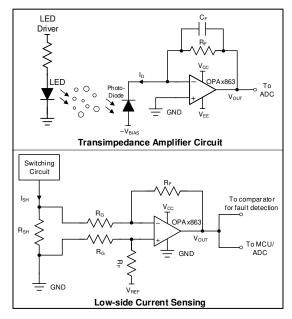
Inductive sensing

Ultrasonic flow meter

Multifunction printer

MDAC output buffer

Gain and active filter stages



Application Circuits Using OPAx863

3 Description

The OPAx863 devices are low-power, unity-gain stable, rail-to-rail input and output, voltage-feedback operational amplifiers designed to operate over a power-supply range of 2.7 V to 12.6 V. Consuming only 700 µA per channel, the OPAx863 offers a gainbandwidth product of 50 MHz, slew rate of 105 V/µs with a voltage noise density of 5.9 nV/ $\sqrt{\text{Hz}}$.

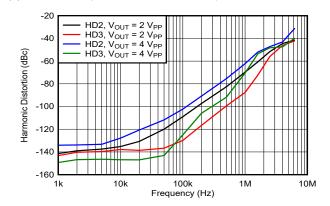
The rail-to-rail input stage with 2.7-V supply operation is useful in portable, battery-powered applications. The rail-to-rail input stage is well-matched for gainbandwidth product and noise across the full input common-mode voltage range, enabling excellent performance with wide-input dynamic range. The OPAx863 feature a power-down (PD) mode with a PD quiescent current (IQ) of 1.5-µA (maximum) and a turn-on or turn-off time within 6.5-µs using a 3-V supply.

The OPAx863 includes overload power limiting to limit the increase in IQ with saturated outputs, thereby preventing excessive power dissipation in powerconscious, battery-operated systems. The output stage is short-circuit protected, making these devices conducive to ruggedized environments.

Device Information(1)(2)

PART NUMBER	CHANNEL COUNT	PACKAGE				
OPA863	Single	DBV (SOT-23, 5)				
UPA603	Sirigle	DBV (SOT-23, 6)				
		DGK (VSSOP, 8)				
OPA2863	Dual	RUN (WQFN, 10)				
		D (SOIC, 8)				
OPA4863	Quad	PW (TSSOP, 14)				

- For all available packages, see the orderable addendum at the end of the data sheet.
- For related products, see Device Comparison



Distortion Performance in G = 1 V/V



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• Added the D package, 8-pin SOIC and RUN package, 10-pin WQFN to the data sheet......1



5 Device Comparison Table

DEVICE	±V _S (V)	I _Q / CHANNEL (mA)	GBWP (MHz)	SLEW RATE (V/µs)	VOLTAGE NOISE (nV/√ Hz)	AMPLIFIER DESCRIPTION
OPA2863	±6.3	0.70	50	105	5.9	Unity-gain stable RRIO Bipolar Amplifier
LMH6643	±6.4	2.7	65	130	17	Unity-gain stable NRI/RRO Bipolar Amplifier
OPAx810	±13.5	3.6	70	200	6.3	Unity-gain stable RRIO FET-Input Amplifier
OPAx837	±2.7	0.6	50	105	4.7	Unity-gain stable NRI/RRO Bipolar Amplifier
OPAx607	±2.75	0.9	50	24	3.8	Decompensated Gain of 6 V/V stable CMOS Amplifier

6 Pin Configuration and Functions

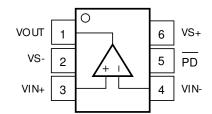


Figure 6-1. OPA863 DBV Package, 6-Pin SOT-23 (Top View)

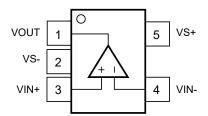


Figure 6-2. OPA863 DBV Package, 5-Pin SOT-23 (Top View)

Table 6-1. Pin Functions: OPA863

	PIN				
	N	NO.		DESCRIPTION	
NAME	DBV (SOT-23, 5)	DBV (SOT-23, 6)	TYPE ⁽¹⁾		
PD	_	5	I	Power down. Low = disabled, high = normal operation (pin must be driven).	
VIN+	3	3	I	Noninverting input pin	
VIN-	4	4	I	Inverting input pin	
VOUT	1	1	0	Output pin	
VS-	2	2	Р	Negative power-supply pin	
VS+	5	6	Р	Positive power-supply pin	

⁽¹⁾ I = input, O = output, and P = power.



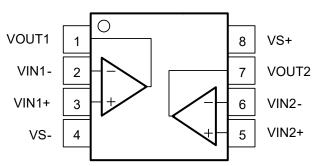


Figure 6-3. OPA2863 D Package, 8-Pin SOIC and DGK Package, 8-Pin VSSOP, (Top View)

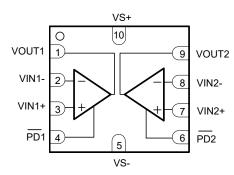


Figure 6-4. OPA2863 RUN Package, 10-Pin WQFN (Top View)

Table 6-2. Pin Functions: OPA2863

	PIN						
	N	0.	(4)				
NAME	D (SOIC), DGK (VSSOP)	RUN (WQFN)	TYPE ⁽¹⁾	DESCRIPTION			
PD1	_	4	I	Amplifier 1 power down. Low = disabled, high = normal operation (pin must be driven).			
PD2	_	6	I	Amplifier 2 power down. Low = disabled, high = normal operation (pin must be driven).			
VIN1-	2	2	I	Amplifier 1 inverting input pin			
VIN1+	3	3	1	Amplifier 1 noninverting input pin			
VIN2-	6	8	I	Amplifier 2 inverting input pin			
VIN2+	5	7	I	Amplifier 2 noninverting input pin			
VOUT1	1	1	0	Amplifier 1 output pin			
VOUT2	7	9	0	Amplifier 2 output pin			
VS-	4	5	Р	Negative power-supply pin			
VS+	8	10	Р	Positive power-supply pin			

⁽¹⁾ I = input, O = output, and P = power.



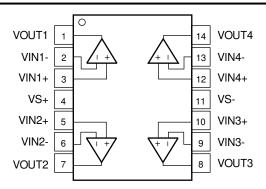


Figure 6-5. OPA4863 PW Package, 14-Pin TSSOP (Top View)

Table 6-3. Pin Functions: OPA4863

PIN		TYPE ⁽¹⁾	DESCRIPTION		
NAME	NO.	IYPE	DESCRIPTION		
VIN1-	2	I	Amplifier 1 inverting input pin		
VIN1+	3	I	Amplifier 1 noninverting input pin		
VIN2-	6	I	Amplifier 2 inverting input pin		
VIN2+	5	I	Amplifier 2 noninverting input pin		
VIN3-	9	I	Amplifier 3 inverting input pin		
VIN3+	10	I	Amplifier 3 noninverting input pin		
VIN4-	13	I	Amplifier 4 inverting input pin		
VIN4+	12	I	Amplifier 4 noninverting input pin		
VOUT1	1	0	Amplifier 1 output pin		
VOUT2	7	0	Amplifier 2 output pin		
VOUT3	8	0	Amplifier 3 output pin		
VOUT4	14	0	Amplifier 4 output pin		
VS-	11	Р	Negative power-supply pin		
VS+	4	Р	Positive power-supply pin		

⁽¹⁾ I = input, O = output, and P = power.



7 Specifications

7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)(1)

		MIN	MAX	UNIT
\/ to \/	Supply voltage		13	V
V_{S-} to V_{S+}	Supply turn-on/off maximum dV/dt, DBV-6 and D packages		0.1	V/µs
VI	Input voltage	V _{S-} - 0.5	V _{S+} + 0.5	V
V _{ID}	Differential input voltage		±1	V
I _I	Continuous input current ⁽²⁾		±10	mA
Io	Continuous output current ⁽³⁾		±30	mA
	Continuous power dissipation	See Thermal In	nformation	
TJ	Maximum junction temperature		150	°C
T _A	Operating free-air temperature	-40	125	°C
T _{stg}	Storage temperature	-65	150	°C

⁽¹⁾ Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

7.2 ESD Ratings

			VALUE	UNIT
V	Electrostatic	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±2000	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \
V(ESD)	discharge	Charged device model (CDM), per ANSI/ESDA/JEDEC JS-002 ⁽²⁾	±1000]

⁽¹⁾ JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V _{S+} - V _{S-}	Total supply voltage	2.7	10	12.6	V
T _A	Ambient temperature	-40	25	125	°C

⁽²⁾ Continuous input current limit for both the ESD diodes to supply pins and amplifier differential input clamp diode. The differential input clamp diode limits the voltage across it to 1 V with this continuous input current flowing through it.

⁽³⁾ Long-term continuous current for electromigration limits.

⁽²⁾ JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



7.4 Thermal Information: OPA863

			OPA863			
	THERMAL METRIC ⁽¹⁾	DBV (S	UNIT			
		5 PINS	6 PINS			
$R_{\theta JA}$	Junction-to-ambient thermal resistance	168.3	161.8	°C/W		
R _{θJC(top)}	Junction-to-case (top) thermal resistance	64.3	73.9	°C/W		
$R_{\theta JB}$	Junction-to-board thermal resistance	40.6	42.6	°C/W		
Ψ_{JT}	Junction-to-top characterization parameter	14.2	21.2	°C/W		
Y_{JB}	Junction-to-board characterization parameter	40.3	42.5	°C/W		

For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application

7.5 Thermal Information: OPA2863

			OPA2863			
	THERMAL METRIC ⁽¹⁾	DGK (VSSOP)	D (SOIC)	RUN (WQFN)	UNIT	
		8 PINS	8 PINS	10 PINS		
$R_{\theta JA}$	Junction-to-ambient thermal resistance	180.3	120.0	110.2	°C/W	
R _{0JC(top)}	Junction-to-case (top) thermal resistance	67.5	63.3	66.8	°C/W	
$R_{\theta JB}$	Junction-to-board thermal resistance	101.9	63.2	43.6	°C/W	
Ψ_{JT}	Junction-to-top characterization parameter	9.8	17.2	2.9	°C/W	
Y_{JB}	Junction-to-board characterization parameter	100.1	62.5	43.5	°C/W	

For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

7.6 Thermal Information: OPA4863

		OPA4863	
	THERMAL METRIC ⁽¹⁾	PW (TSSOP)	UNIT
		14 PINS	
R _{0JA}	Junction-to-ambient thermal resistance	99.5	°C/W
R _{0JC(top)}	Junction-to-case (top) thermal resistance	27.6	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	56.1	°C/W
Ψ_{JT}	Junction-to-top characterization parameter	4.4	°C/W
Y_{JB}	Junction-to-board characterization parameter	55.3	°C/W

For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.



7.7 Electrical Characteristics: $V_S = 10 \text{ V}$

at $V_{S+} = 5$ V, $V_{S-} = -5$ V, G = 1 V/V, $R_F = 0$ Ω for G = 1 V/V, otherwise $R_F = 1$ k Ω for other gains, $C_L = 1$ pF, $R_L = 2$ k Ω referenced to mid-supply, input and output common-mode is at mid-supply, and $T_A \cong 25^{\circ}C$ (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
AC PERI	FORMANCE					
SSBW	Small-signal bandwidth	V _{OUT} = 20 mV _{PP} , G = 1, < 1 dB peaking		110		MHz
GBWP	Gain-bandwidth product			50		MHz
LSBW	Large-signal bandwidth	V _{OUT} = 2 V _{PP}		17		MHz
	Bandwidth for 0.1-dB flatness	V _{OUT} = 20 mV _{PP}		15		MHz
SR	Slew rate	V _{OUT} = 2–V step, G = –1		105		V/µs
	Rise, fall time	V _{OUT} = 200–mV step		9		ns
	Settling time to 0.1%	V = 2 V = t= =		57		
	Settling time to 0.01%	V _{OUT} = 2–V step		70		ns
	Overshoot/undershoot	V _{OUT} = 2–V step		1		%
	O a salah sa	G = -1, 0.5 V overdrive beyond supplies		70		
	Overdrive recovery time	G = 1, 0.5 V overdrive beyond supplies		100		ns
HD2	Second-order harmonic distortion			-129		
HD3	Third-order harmonic distortion	f = 20 kHz, V _{OUT} = 2 V _{PP}		-138		dBc
HD2	Second-order harmonic distortion			-107		
HD3	Third-order harmonic distortion	f = 100 kHz, V _{OUT} = 2 V _{PP}		-125		dBc
e _N	Input voltage noise	Flatband, 1/f corner at 25 Hz		5.9		nV/√Hz
i _N	Input current noise	Flatband, 1/f corner at 2 kHz		0.4		pA/√Hz
	Closed-loop output impedance	f = 1 MHz			Ω	
	Channel-to-channel crosstalk	f = 1 MHz, V _{OUT} = 2 V _{PP} , OPA2863	,	-124		dBc
DC PERI	FORMANCE					
A _{OL}	Open-loop voltage gain	V _{OUT} = ±2.5 V	110	128		dB
V _{OS}	Input-referred offset voltage		-1.3	±0.4	1.3	mV
	Input offset voltage drift	T _A = -40°C to +125°C, D, DBV-5, RUN and DGK packages	-3.5	±1 3.5		
		T _A = -40°C to +125°C, PW package	-4	±1	4	μV/°C
	par sheet relaage anni	T _A = 0°C to +85°C, DBV-6 package	-4.4	±1	4.4	μ., σ
		T _A = -40°C to +125°C, DBV-6 package	-4.9	±1	4.9	
		T _A ≅ 25°C		0.3	0.73	
	Input bias current	T _A = -40°C to +85°C			1.2	μΑ
		T _A = -40°C to +125°C			1.6	
	Input bias current drift	T _A = -40°C to +125°C		±3	7.6	nA/°C
	Input offset current		-30	±10	30	nA
INPUT	<u>'</u>					
	Input common-mode voltage range		V _S 0.2		V _{S+} +0.2	V
CMRR	Common-mode rejection ratio	V _{CM} = V _S – 0.2 V to V _{S+} – 1.6 V	100	120	<u> </u>	dB
	Input impedance common-mode	S 5		650 0.8		MΩ pF
	Input impedance differential mode			200 0.5		kΩ pF
OUTPUT						
		T _A ≅ 25°C		V _S _+0.14	V _S _+0.2	
V_{OL}	Output voltage, low	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$		V _S _+0.15	V _S _+0.22	V
		T _A ≅ 25°C	V _{S+} -0.2	V _{S+} -0.14	<u> </u>	
V_{OH}	Output voltage, high	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$	V _{S+} -0.2	V _{S+} -0.15		V



7.7 Electrical Characteristics: V_S = 10 V (continued)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
	Linear output drive (sourcing/ sinking)	V _{OUT} = ±2.5 V, ΔV _{OS} < 1 mV OPA863 and OPA2863 ⁽¹⁾	25	30		mA	
	Short-circuit current			45		mA	
POWER	SUPPLY						
	Ouissant surrent per amplifier	T _A ≅ 25°C		700	970		
IQ	Quiescent current per amplifier	T _A = -40°C to +125°C			1280	μA	
PSRR	Power-supply rejection ratio	$\Delta V_{S} = \pm 2 V^{(2)}$	100	120		dB	
POWER	DOWN (Pin Must be Driven)		,				
	Enable voltage threshold	Specified <i>on</i> above V _{S+} – 0.5 V			4.5	V	
	Disable voltage threshold	Specified off below V _{S+} – 1.5 V	3.5			V	
	Power-down quiescent current per channel	<u>PD</u> ≤ V _{S+} – 1.5 V		2	3.3	μA	
	Power-down pin bias current			2	50	nA	
	Turn-on time delay			6		μs	
	Turn-off time delay			4.5		μs	
AUXILIA	ARY INPUT STAGE						
	Gain-bandwidth product			50		MHz	
	Input voltage noise	Flatband, 1/f corner at 25 Hz		6		nV/√Hz	
	Input current noise	Flatband, 1/f corner at 100 Hz		0.4		pA/√Hz	
	Input-referred offset voltage		-1.3	±0.15	1.3	mV	
	Input bigg gurrant	T _A ≅ 25°C		0.2	0.6		
	Input bias current	T _A = -40°C to +125°C		0.2	1.3	μΑ	
	Common-mode rejection ratio	V _{CM} = 4.1 V to 5.2 V	100	120		dB	
	Power supply rejection ratio	$\Delta V_S = \pm 0.6 \text{ V}$	100	120		dB	

⁽¹⁾ Change in input offset voltage from no-load condition.

⁽²⁾ Change in supply voltage from the default test condition with only one of the positive or negative supplies changing corresponding to +PSRR and -PSRR.



7.8 Electrical Characteristics: $V_S = 3 V$

at V_{S+} = 3 V, V_{S-} = 0 V, G = 1, R_F = 0 Ω for G =1 V/V, otherwise R_F = 1 k Ω for other gains, C_L = 1 pF, R_L = 2 k Ω connected to 1 V, input and output V_{CM} = 1 V, and T_A \cong 25°C (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
AC PER	FORMANCE						
SSBW	Small-signal bandwidth	V _{OUT} = 20 mV _{PP} , G = 1		97		MHz	
GBWP	Gain-bandwidth product			50		MHz	
LSBW	Large-signal bandwidth	V _{OUT} = 1 V _{PP}		26		MHz	
	Bandwidth for 0.1-dB flatness	V _{OUT} = 20 mV _{PP}		10		MHz	
SR	Slew rate	V _{OUT} = 1–V step, Gain = –1		105		V/µs	
	Rise, fall time	V _{OUT} = 200–mV step		10		ns	
	Settling time to 0.1%			58			
	Settling time to 0.01%	V _{OUT} = 1–V step		90		ns	
	Overshoot			2			
	Undershoot	V _{OUT} = 1–V step		16		%	
		G = -1, 0.5V overdrive beyond supplies					
	Overdrive recovery time	G = 1, 0.5V overdrive beyond supplies	95 100			ns	
HD2	Second-order harmonic distortion			-123			
HD3	Third-order harmonic distortion	f = 20 kHz, V _{OUT} = 1 V _{PP}		-132		dBc	
HD2	Second-order harmonic distortion			-109			
HD3	Third-order harmonic distortion	f = 100 kHz, V _{OUT} = 1 V _{PP}		-129			
e _N	Input voltage noise	Flatband, 1/f corner at 25 Hz	6			nV/√Hz	
	Input current noise	Flatband, 1/f corner at 2 kHz		0.4		pA/√Hz	
	Closed-loop output impedance	f = 1 MHz		0.2		Ω	
	Channel-to-channel crosstalk	f = 1 MHz, V _{OUT} = 1 V _{PP} , OPA2863		-127		dBc	
DC PER	FORMANCE						
A _{OL}	Open-loop voltage gain	V _{OUT} = 1 V to 2 V	104	123		dB	
V _{OS}	Input-referred offset voltage	- 001	-1.3	±0.4	1.3	mV	
- 03		T _A = -40°C to +125°C, D, DBV-5, RUN, and DGK packages	-3.5	±1	3.5		
	Input offset voltage drift	$T_A = -40$ °C to +125°C, PW package	-4	_4 ±1		μV/°C	
	input onset voltage unit	$T_A = 0$ °C to +85°C, DBV-6 package	-4.4	±1	4.4	μν, σ	
		$T_A = -40$ °C to +125°C, DBV-6 package	– 5	±1	5		
		T _A ≅ 25°C		0.3	0.73		
	Input bias current	$T_A = -40^{\circ}\text{C to } +85^{\circ}\text{C}$			1.2	μA	
		$T_A = -40^{\circ} \text{C to } +125^{\circ} \text{C}$			1.56	,	
	Input bias current drift	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$		±3	7.4	nA/°C	
	Input offset current		-30	±10	30	nA	
INPUT		I				.,,	
01	Input common-mode voltage range		V _S 0.2		V _{S+} +0.2	V	
CMRR	Common-mode rejection ratio	$V_{CM} = V_{S-} - 0.2 \text{ V to } V_{S+} - 1.6 \text{ V}$	94	115	*3+.0.2	dB	
J.VII.VIV	Input impedance common-mode	VOW VS- 0.2 V to VS+ - 1.0 V	J -1	360 0.9		MΩ pF	
	Input impedance differential mode			200 0.5		kΩ pF	



7.8 Electrical Characteristics: V_S = 3 V (continued)

at V_{S+} = 3 V, V_{S-} = 0 V, G = 1, R_F = 0 Ω for G =1 V/V, otherwise R_F = 1 k Ω for other gains, C_L = 1 pF, R_L = 2 k Ω connected to 1 V, input and output V_{CM} = 1 V, and T_A \cong 25°C (unless otherwise noted)

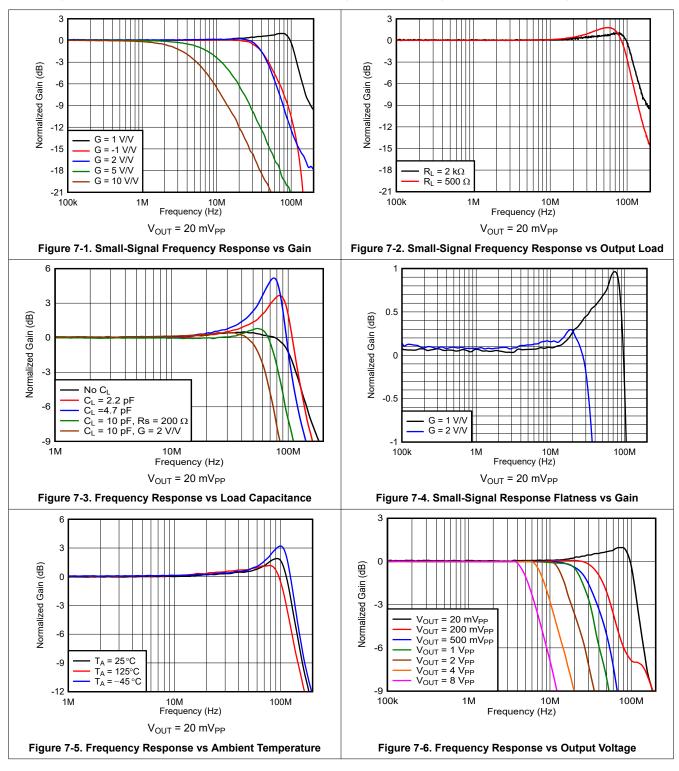
PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
OUTPU	Т		<u>'</u>			
		T _A ≅ 25°C		V _S _+ 0.13	V _S _+ 0.15	.,
V _{OL}	Output voltage, low	T _A = -40°C to +125°C		V _S _+ 0.13	V _S _+ 0.16	V
.,	Outrout valte as high	T _A ≅ 25°C		V _{S+} -0.13		
V _{OH}	Output voltage, high	T _A = -40°C to +125°C	V _{S+} -0.15	V _{S+} -0.13		V
	Linear output drive (sourcing/ sinking)	V _{OUT} = ±0.7 V, ΔV _{OS} < 1 mV OPA863 and OPA2863 ⁽¹⁾	23	33		mA
	Short-circuit current			45		mA
POWER	SUPPLY					
	Quiescent current per amplifier	T _A ≅ 25°C		690	910	
I _Q	Quiescent current per amplifier	T _A = -40°C to +125°C		-	1180	μA
PSRR	Power-supply rejection ratio	$\Delta V_S = \pm 1 \ V^{(2)}$	100	120		dB
POWER	R DOWN (Pin Must be Driven)					
	Enable voltage threshold	Specified <i>on</i> above V _{S+} – 0.5 V			2.5	V
	Disable voltage threshold	Specified off below V _{S+} – 1.5 V	1.5			V
	Power-down quiescent current per channel	<u>PD</u> ≤ V _{S+} – 1.5 V		0.8	1.5	μΑ
	Power-down pin bias current			1	50	nA
	Turn-on time delay			6.5		μs
	Turn-off time delay			5		μs
AUXILIA	ARY INPUT STAGE					
	Gain-bandwidth product			50		MHz
	Input voltage noise	Flatband, 1/f corner at 25 Hz		6		nV/√Hz
	Input current noise	Flatband, 1/f corner at 100 Hz		0.4		pA/√Hz
	Input-referred offset voltage		-1.3	±0.15	1.3	mV
	Input bias current	T _A ≅ 25°C		0.2	0.6	
	input bias current	T _A = -40°C to +125°C		0.4	1.2	μA
	Common-mode rejection ratio	V _{CM} = 2.1 V to 3.2 V	100	120		dB
	Power supply rejection ratio	$\Delta V_S = \pm 0.6 \text{ V}$	100	115		dB

⁽¹⁾ Change in input offset voltage from no-load condition.

⁽²⁾ Change in supply voltage from the default test condition with only one of the positive or negative supplies changing corresponding to +PSRR and -PSRR.

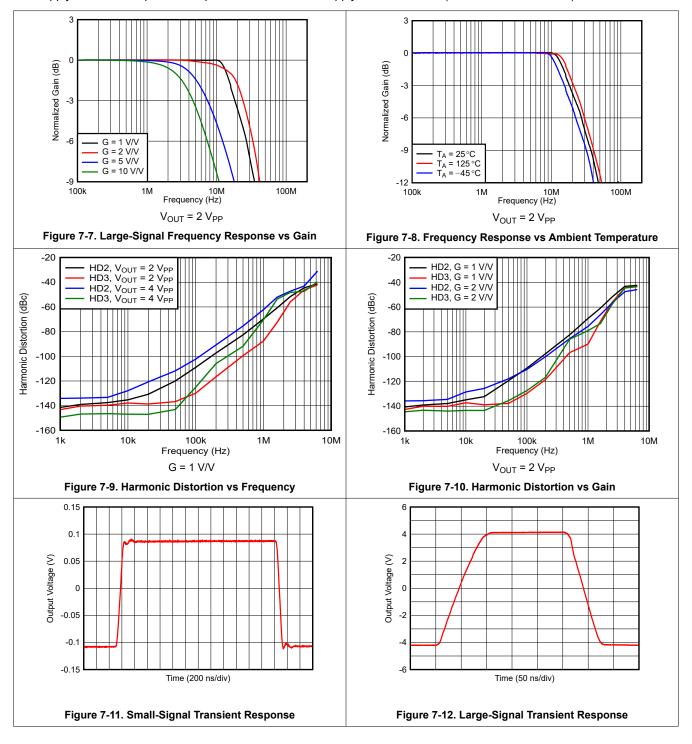


7.9 Typical Characteristics: $V_S = 10 \text{ V}$



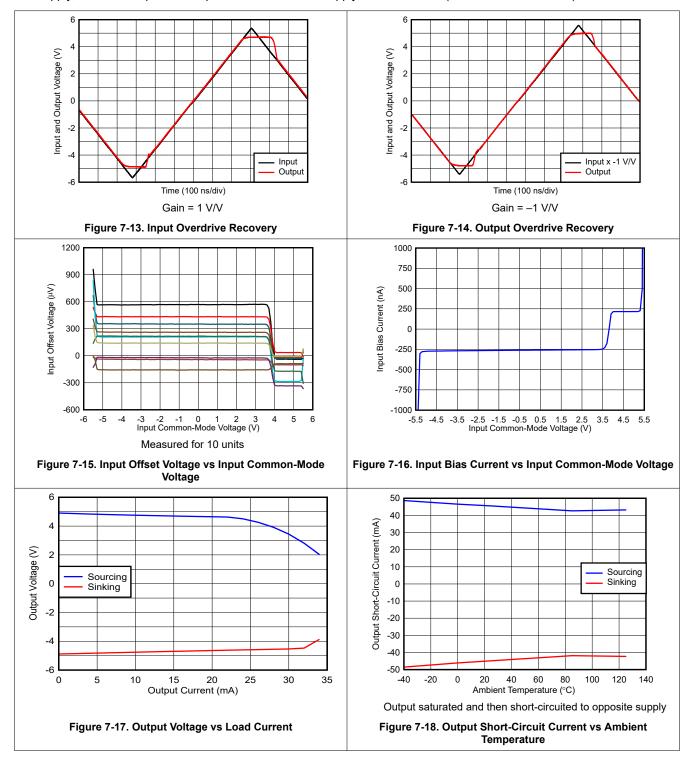


7.9 Typical Characteristics: $V_S = 10 \text{ V}$ (continued)



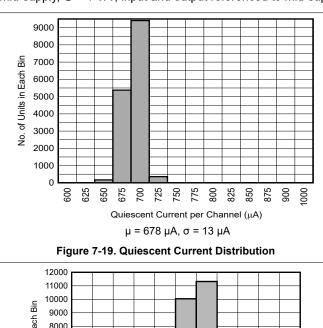


7.9 Typical Characteristics: V_S = 10 V (continued)





7.9 Typical Characteristics: $V_S = 10 \text{ V}$ (continued)



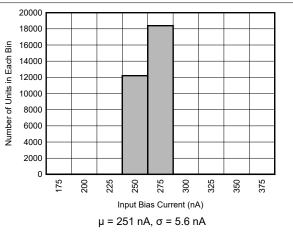
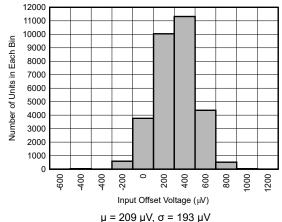


Figure 7-20. Input Bias Current Distribution



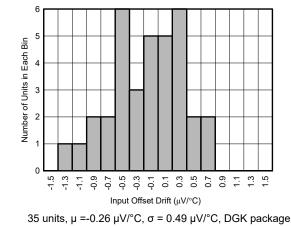
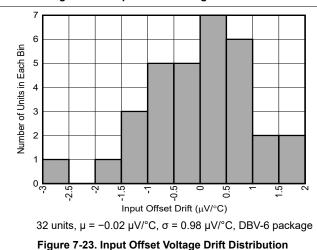




Figure 7-22. Input Offset Voltage Drift Distribution



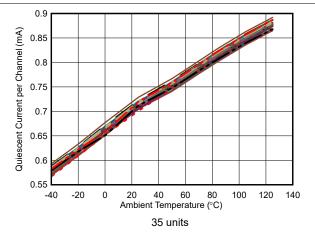
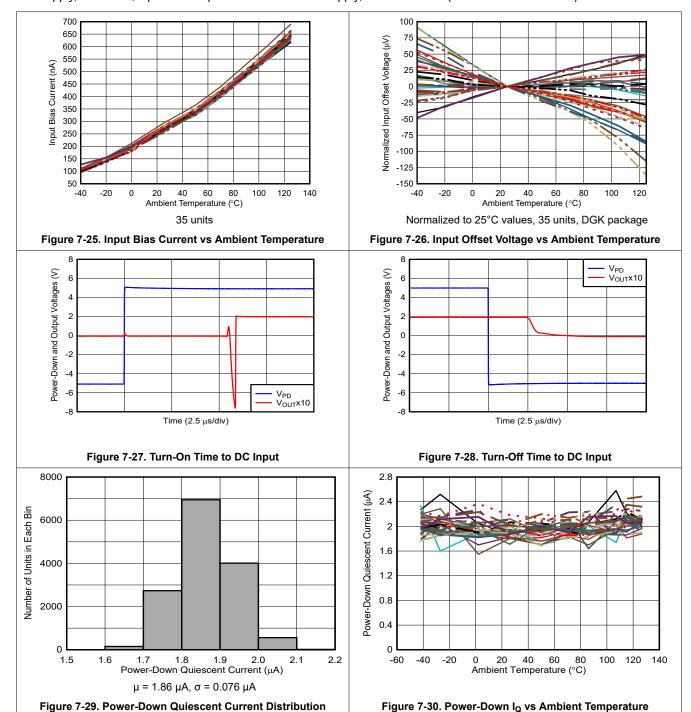


Figure 7-24. Quiescent Current vs Ambient Temperature



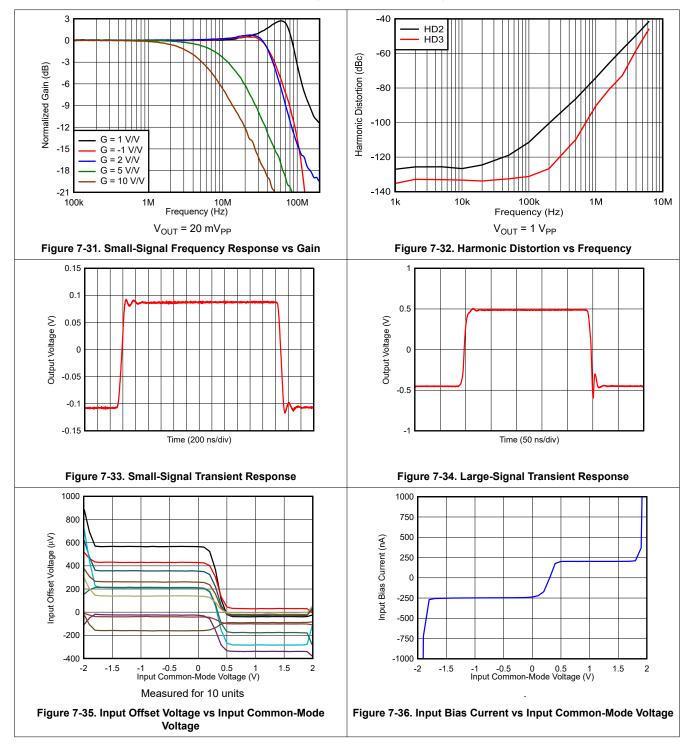
7.9 Typical Characteristics: V_S = 10 V (continued)





7.10 Typical Characteristics: V_S = 3 V

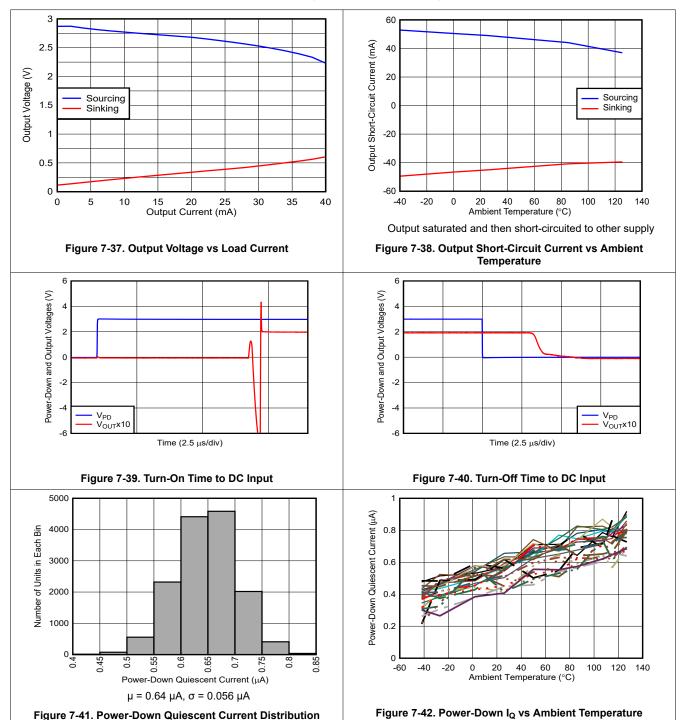
at V_{S+} = 3 V, V_{S-} = 0 V, R_F = 0 Ω for Gain = 1 V/V, otherwise R_F = 1 k Ω for other gains, C_L = 1 pF, R_L = 2 k Ω connected to 1 V, G = 1 V/V, input and output V_{CM} = 1 V, and T_A \cong 25°C (unless otherwise noted)





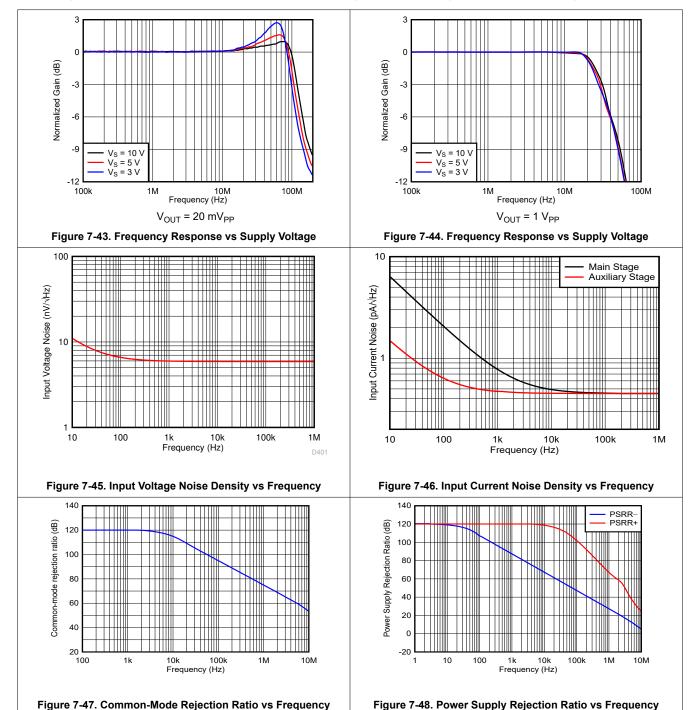
7.10 Typical Characteristics: $V_S = 3 V$ (continued)

at V_{S+} = 3 V, V_{S-} = 0 V, R_F = 0 Ω for Gain = 1 V/V, otherwise R_F = 1 k Ω for other gains, C_L = 1 pF, R_L = 2 k Ω connected to 1 V, G = 1 V/V, input and output V_{CM} = 1 V, and T_A \cong 25°C (unless otherwise noted)



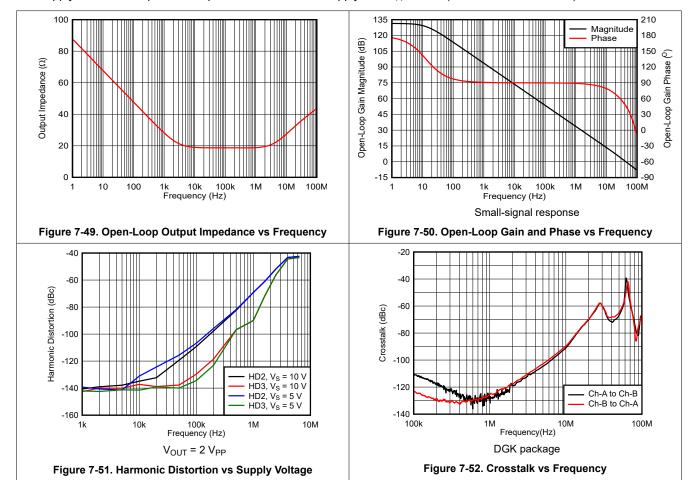


7.11 Typical Characteristics: $V_S = 3 V$ to 10 V





7.11 Typical Characteristics: $V_S = 3 \text{ V to } 10 \text{ V (continued)}$





8 Detailed Description

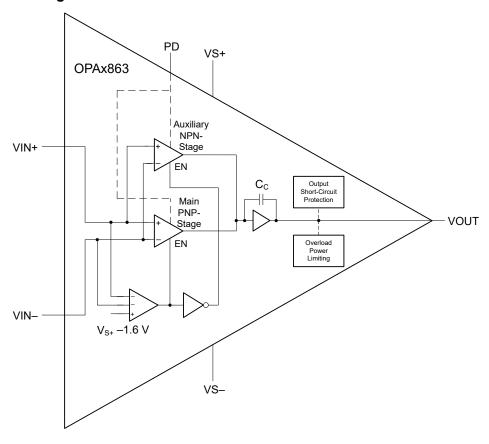
8.1 Overview

The OPAx863 devices are low-power, 50-MHz, rail-to-rail input and output (RRIO), bipolar, voltage-feedback operational amplifiers with a voltage noise density of 5.9 nV/ $\sqrt{\text{Hz}}$ and 1/f noise corner at 25 Hz. The OPAx863 work with a wide-supply voltage range of 2.7 V to 12.6 V, and consume only 700 μ A quiescent current. The OPAx863 operate with a 2.7 V supply, are RRIO capable, consume low-power, and offer a power-down mode, which makes them great amplifiers for 3.3-V or lower-voltage applications that require excellent ac performance. The main and auxiliary input stages of the amplifier are matched for gain bandwidth product (GBW), noise, and offset voltage and designed for applications that require wide dynamic input range and good SNR.

The device includes an overload power limit feature which limits the increase in quiescent current with overdriven and saturated outputs to either of the supply rails. For more details of this overload power limit feature, see Section 8.3.2.1. The amplifier's output is protected against short-circuit fault conditions.

The OPAx863 feature a power-down mode (PD) with a PD quiescent current of 1.5 μ A (maximum) with a 3-V supply, with turn-on and turn-off time within less than 6.5 μ s.

8.2 Functional Block Diagram



8.3 Feature Description

8.3.1 Input Stage

The OPAx863 include a rail-to-rail input stage. The main stage differential pair using PNP bipolar transistors operates for common-mode input voltages from $V_{S-} - 0.2$ V to $V_{S+} - 1.6$ V. The amplifier inputs transition into the auxiliary stage using NPN transistors for common-mode input voltages from $V_{S+} - 1.6$ V till $V_{S+} + 0.2$ V. The PNP and NPN input stages offer a gain-bandwidth product of 50 MHz and a voltage noise density of 6.3 nV/ \sqrt{Hz} . The offset voltage for the two input stages is matched to lie within the device specifications. The auxiliary NPN input stage does not use the slew-boost circuit during large-signal transient response. The input bias current for the PNP and NPN input stages is opposite in polarity, which adds an additional offset based on the values of the gain-setting and feedback resistors. A common-mode input voltage transition between these input stages causes a crossover distortion that must be considered in high-frequency applications requiring excellent linearity. Limit the common-mode input voltage to $V_{S+} - 1.6$ V (maximum) for main-stage operation across process and ambient temperature.

The OPAx863 are bipolar amplifiers; therefore, the two inputs are protected with antiparallel back-to-back diodes between the inputs, which limits the maximum input differential voltage to 1 V. The amplifier is slew limited, and the two inputs are pulled apart up to 1 V when the antiparallel diodes begin to conduct in very fast input or output transient conditions. Make sure to use gain-setting and feedback resistors large enough to limit the current through these diodes in such conditions.

8.3.2 Output Stage

The OPAx863 feature a rail-to-rail output stage with possible signal swing from V_{S-} + 0.2 V to V_{S+} – 0.2 V. Violating the output headroom of either supply causes output signal clipping and introduces distortion.

The OPAx863 integrate an output short-circuit protection circuit that makes the device rugged for use in real-world applications.

8.3.2.1 Overload Power Limit

The OPAx863 include overload power limiting that limits the increase in device quiescent current with output saturated to either of the supplies. Typically, when an amplifier output saturates, the two inputs are pulled apart, which can enable the slew-boost circuit. The input differential voltage is an error voltage in negative feedback that the amplifier core nullifies by engaging the slew-boost circuit and driving the output stage deeper into saturation. After the input to an amplifier attains a value large enough to saturate the output, any further increase in this input excitation results in a finite input differential voltage. As the output stage transistor is pushed deeper into saturation, the base-to-collector current gain (h_{FE}) drops with an increase in the base and collector current, and an increase in the device quiescent current. This increase in quiescent current can cause a catastrophic failure in multichannel, high-gain, high-density front-end designs, and reduce operating lifetime in portable, battery-powered systems.

The OPAx863 overload power limiting includes an intelligent output saturation-detection circuit that limits the device quiescent current to 2.2-mA per channel under dc overload conditions. This increase in quiescent current is smaller with ac input or output and output saturation duration for only a fraction of the overall signal time period. Table 8-1 compares the increase in quiescent current with 50-mV input overdrive for OPAx863 devices and other voltage-feedback amplifiers without overload power limit.

Table 8-1. Quiescent Current With Saturated Outputs

DEVICE	INPUT DIFFERENTIAL VOLTAGE	QUIESCENT CURRENT DURING OVERLOAD	INCREASE IN I _Q FROM STEADY-STATE CONDITION		
OPAx863 with overload power limit	50 mV	1.1 mA	1.57 ×		
Competitor amplifier without overload power limit	50 mV	1.96 mA	3.43 ×		



8.3.3 ESD Protection

As Figure 8-1 shows, all device pins are protected with internal ESD protection diodes to the power supplies. These diodes provide moderate protection to input overdrive voltages greater than the supplies. The protection diodes typically support 10-mA continuous input and output currents. Use series current limiting resistors if input voltages exceeding the supply voltages occur at the amplifier inputs, which makes sure that the current through the ESD diodes remains within the rated value. OPAx863 is a bipolar amplifier; therefore, the two inputs are protected with antiparallel, back-to-back diodes between the inputs that limits the maximum input differential voltage to approximately 1 V. Make sure to use gain-setting and feedback resistors large enough to limit the current through these diodes in fast slewing conditions.

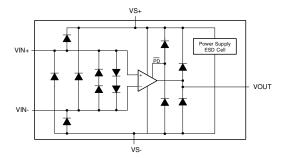


Figure 8-1. Internal ESD Protection

8.4 Device Functional Modes

8.4.1 Power-Down Mode

The OPAx863 includes a power-down mode for low-power standby operation with a quiescent current of only $1.5~\mu A$ (maximum) with a 3-V supply and high output impedance. Many low-power systems are active for only a small time interval when the parameters of interest are measured and remain in low-power standby mode for a majority of the time and an overall small average power consumption. The OPAx863 enables such a low-power operation with quick turn-on within less than $6.5~\mu s$. See the *Electrical Characteristics* tables for power-down pin control thresholds.

Always drive \overline{PD} pin to avoid false triggering and oscillations. If power-down mode is not used, then connect the \overline{PD} pin to V_{S+} . For applications that need power-down mode, use an external pull-up resistor from the \overline{PD} pin to V_{S+} (driven with an open-collector power-down control logic).

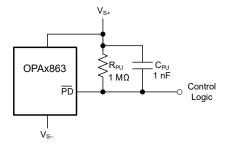


Figure 8-2. Power Down Control

Figure 8-2 shows the choice of value of the pull-up resistor R_{PU} , which impacts the current consumption in power-down mode. Using a large RPU reduces power consumption, but increases the noise at the PD pin, which can cause the amplifier to power down. A 1-nF capacitor can be used in parallel with RPU to avoid coupling of external noise and false triggering. For the case of the \overline{PD} pin driven to V_{S-} , the I_{PU} current through R_{PU} is given as:

$$I_{PU} = \frac{V_{S+} - V_{S-}}{R_{PU}} \tag{1}$$



9 Application and Implementation

Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

9.1 Application Information

The OPAx863 are classic voltage-feedback amplifiers with two high-impedance inputs and a low-impedance output. These devices have a GBW of 50 MHz, $5.9 \text{ nV}/\sqrt{\text{Hz}}$ of noise, RRIO capability, and precision performance consuming only 700 μ A quiescent current per channel These features make the OPAx863 an excellent choice for use in low-side current sensing, ADC input driver, and reference buffering with fast settling, buffers, high gain and filter circuits. The overload power limit makes the OPAx863 truly low-power in high-gain, multichannel systems limiting any increase in quiescent current during output overload conditions.

9.2 Typical Applications

9.2.1 Low-Side Current Sensing

Power converters use current-mode feedback control for excellent transient response and multiphase load sharing. Inverter stages control the phase currents for torque control in motor drives. As a result of the simplicity and low-cost, many of these topologies use difference-amplifier-based, low-side current sensing. Figure 9-1 shows the use of the OPAx863 in a difference amplifier circuit for low-side current sensing.

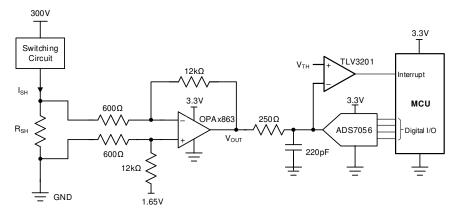


Figure 9-1. Low-Side Current Sensing in Power Converters

9.2.1.1 Design Requirements

Table 9-1. Design Requirements

PARAMETER	DESIGN REQUIREMENT			
Shunt resistor	10 mΩ			
Input current	15 A _{PP}			
Output voltage	3 V _{PP}			
Switching frequency	50 kHz			
Data acquisition	1 MSPS with 0.1% accuracy			
Input voltage due to ground bounce	10 Vpk			



9.2.1.2 Detailed Design Procedure

In a difference amplifier circuit, the output voltage is given by:

$$V_O = \frac{R_F}{R_G} I_{SH} R_{SH} + V_{REF} \tag{2}$$

For lowest system noise, small values of R_F and R_G are preferred. The smallest value of R_G is limited by the input transient voltage (10 V here) seen by the circuit, and is given by:

$$R_G = \frac{V_{IN(max.)} - V_D - V_S}{I_{D(max.)}}$$
(3)

Where,

- V_{IN(maximum)} is the maximum input transient voltage seen by the circuit.
- V_D is the forward voltage drop of ESD diodes at the amplifier input.
- I_{D(maximum)} is the maximum current rating of the ESD diodes at the amplifier input.

For a difference amplifier gain of 20 V/V, an R_F of 12 k Ω and R_G of 600 Ω are used. With a clock frequency of 40 MHz and the ADS7056 sampling at 1 MSPS, the available acquisition time for amplifier output settling is 550 ns. Figure 9-2 shows the simulation results for the circuit in Figure 9-1. The worst-case peak-to-peak input transient condition is simulated. The output of the OPAx863 device settles to within 0.1% accuracy within 543 ns. If using a slower clock frequency with the ADC is desired, then the acquisition time reduces with the same sampling rate, which degrades measurement accuracy. Alternatively, the sampling rate can be reduced to recover the required acquisition time and 0.1% accuracy.

9.2.1.3 Application Curves

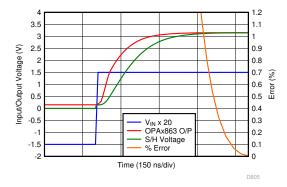


Figure 9-2. 0.1% Settling Performance



9.2.2 Front-End Gain and Filtering

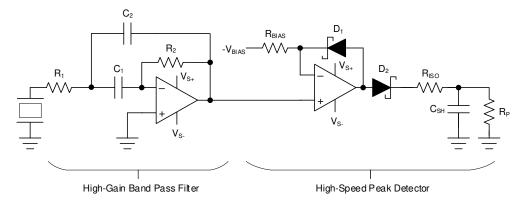


Figure 9-3. High-Gain Narrow Bandpass Filter and Peak Detector Circuit

Ultrasonic signaling is used for proximity and obstacle detection, level sensing, sonars, and so forth. Such signal chains detect the amplitude of received ultrasonic signal at a particular center frequency. Figure 9-3 shows a high-gain narrow bandpass filter and peak detector circuit using any of the OPAx863 devices. The signal at the frequency of interest is filtered out, gained, and peak detected to report the amplitude at the output of this circuit. The phase information is lost in this circuit. The OPAx863 devices are used with the 50-MHz GBW to add a single-stage gain and filtering, and the peak detection capability is easily made with the RRIO capability of these amplifiers.

9.2.3 Low-Power SAR ADC Driver and Reference Buffer

Figure 9-4 shows the use of the OPAx863 as a SAR ADC input driver and reference buffer driving the ADS7945. sensors, which are used for interface with the physical environment, exhibit high output impedance, and cannot drive SAR ADC inputs directly. A wide-GBW amplifier, such as the OPAx863, is needed to charge the switching capacitors at the SAR ADC input, and quickly settle to the required accuracy within the given acquisition time. The ADC core draws transient current from the reference input during the conversion (digitization) phase, which must be driven with a wide-GBW amplifier to offer fast settling and maintain a stable reference voltage for excellent digitization performance. The OPAx863 reference buffer is used in a composite loop with the OPA378 precision amplifier because of limitations in precision performance of wide-GBW amplifiers. The precision amplifier maintains low-offset output, whereas the OPAx863 devices provide the output drive and fast-settling performance.

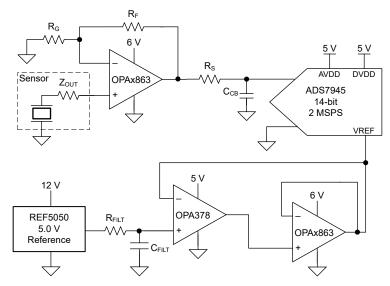


Figure 9-4. OPAx863 as Low-Power SAR ADC Driver



9.2.4 Variable Reference Generator Using MDAC

High-speed amplifiers can be used as a voltage buffer at MDAC output to generate a fast-settling variable reference voltage. Figure 9-5 shows a representative circuit using DAC8801 and OPAx863.

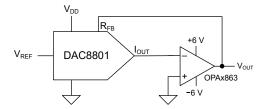


Figure 9-5. Variable Reference Generator Using MDAC and OPAx863

9.2.5 Clamp-On Ultrasonic Flow Meter

Figure 9-6 shows how ultrasonic flow meters measure the rate of flow of a liquid using transit-time difference $(t_{12}-t_{21})$, which depends on the flow rate. Figure 9-6 shows a representative schematic for a non-intrusive ultrasonic flow meter using the OPAx863 and 12-V transducer excitation. The OPAx863 are used for the forward path as a unity-gain buffer for 12-V pulsed transducer excitation at NODE 1. At the same time, the receiver circuit at NODE 2 (which also uses the OPAx863) first provides an ac-gain followed by a dc-level shift to lead to the PGA, ADC, and processor within the MSP430TM microcontroller.

NODE 2 and NODE 1 use similar transmit and receive circuits (discussed previously) for the reverse path. The OPAx863 wide GBW of 50 MHz introduces minimal phase-delay and low-noise for excellent flow rate measurement. The amplifier stays in power-down mode for a majority of the time in battery-powered systems. This configuration results in very small average system-level power consumption and prolonged battery lifetime with the 1.5-µA (maximum) power-down mode quiescent current with a 3-V supply. The transmit and receive signal chains are connected to the same point at the respective node transducers. Therefore, the OPAx863 12.6-V supply voltage capability enables 12-V transducer excitation without any damage to the front-end, or a need for external switches, thus enabling a more compact solution. These specifications make the OPAx863 an excellent choice for flow measurements in large diameter pipes and non-intrusive flow meters. The TIDM-02003 reference design discusses an ultrasonic gas flow sensing subsystem which uses high-speed amplifiers for front-end amplification.

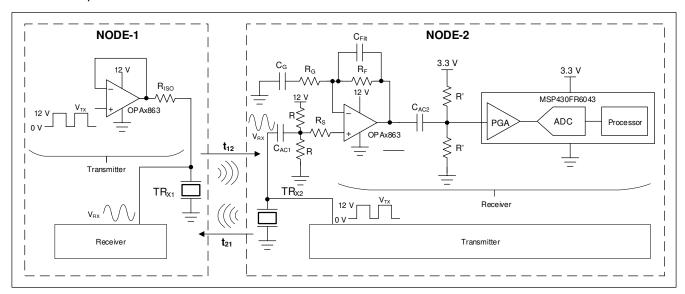


Figure 9-6. Non-Intrusive Ultrasonic Flow Meter



9.3 Power Supply Recommendations

The OPAx863 is intended to operate on supplies ranging from 2.7 V to 12.6 V. The OPAx863 devices operate on single-sided supplies, split and balanced bipolar supplies, or unbalanced bipolar supplies. Operating from a single supply has numerous advantages. The dc errors, due to the –PSRR term, can be minimized with the negative supply at ground. Typically, ac performance improves slightly at 10-V operation with minimal increase in supply current. Minimize the distance (< 0.1 in) from the power supply pins to high-frequency, 0.01-µF decoupling capacitors. A larger capacitor (2.2 µF typical) is used along with a high-frequency, 0.01-µF supply-decoupling capacitor at the device supply pins. Only the positive supply has these capacitors for single-supply operation. Use these capacitors from each supply to ground when a split-supply is used. If necessary, place the larger capacitors further from the device and share these capacitors among several devices in the same area of the printed circuit board (PCB). An optional supply decoupling capacitor across the two power supplies (for split-supply operation) reduces second harmonic distortion.

9.4 Layout

9.4.1 Layout Guidelines

Achieving optimum performance with a high-frequency amplifier (like the OPAx863) requires careful attention to board layout parasitics and external component types. The *OPA2863 DGK Evaluation Module* user's guide can be used as a reference when designing the circuit board. Recommendations that optimize performance includes the following:

- 1. **Minimize parasitic capacitance** to any ac ground for all of the signal I/O pins. Parasitic capacitance on the output and inverting input pins can cause instability on the noninverting input and can react with the source impedance to cause unintentional band-limiting. Open a window around the signal I/O pins in all of the ground and power planes around those pins to reduce unwanted capacitance. Otherwise, ground and power planes must be unbroken elsewhere on the board.
- 2. **Minimize the distance** (< 0.1 in) from the power-supply pins to high-frequency 0.01-μF decoupling capacitors. Avoid narrow power and ground traces to minimize inductance between the pins and the decoupling capacitors. The power-supply connections must always be decoupled with these capacitors. Larger (2.2-μF to 6.8-μF) decoupling capacitors, effective at lower frequency, must also be used on the supply pins. These capacitors can be placed somewhat farther from the device and shared among several devices in the same area of the PCB.
- 3. Careful selection and placement of external components preserves the high-frequency performance of the OPAx863. Resistors must be a low reactance type. Surface-mount resistors work best and allow a tighter overall layout. Other network components, such as noninverting input termination resistors, must also be placed close to the package. Keep resistor values as low as possible and consistent with load-driving considerations. Lowering the resistor values keeps the resistor noise terms low and minimizes the effect of the parasitic capacitance. Lower resistor values, however, increase the dynamic power consumption because R_F and R_G become part of the amplifier output load network.

9.4.1.1 Thermal Considerations

The OPAx863 does not require heat sinking or airflow in most applications. The maximum allowed junction temperature sets the maximum allowed internal power dissipation. Do not allow the maximum junction temperature to exceed 150°C.

Operating junction temperature (T_J) is given by,

$$T_{J} = T_{A} + P_{D} \times R_{\Theta J A} \tag{4}$$

where

- T_A is the ambient temperature
- P_D is the total power dissipation internal to the amplifier
- R_{OJA} is the junction-to-ambient thermal resistance

The total power dissipation $P_D = P_{DQ} + P_{DL}$

where

- $P_{DQ} = (V_{S+} V_{S-}) \times I_Q$, is the power dissipation due to the amplifier quiescent current
- $P_{DL}(max) = V_S^2 / (4 \times R_L)$, is the internal power dissipation due to the output load current

As a worst-case example, compute the maximum T_J using an OPA2863-DGK (VSSOP package) configured as a unity gain buffer, operating on ± 6 -V supplies at an ambient temperature of 25°C and driving a grounded 500- Ω load.

$$P_D = 12 \text{ V} \times 2 \text{ mA} + 6^2 / (4 \times 500 \Omega) = 42 \text{ mW}$$
 (5)

Maximum $T_J = 25^{\circ}\text{C} + (0.042 \text{ W} \times 180.3^{\circ}\text{C/W}) = 33^{\circ}\text{C}$, which is much less than the maximum allowed junction temperature of 150°C.

9.4.2 Layout Example

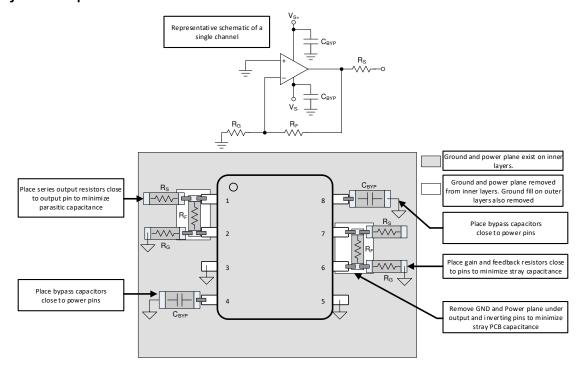


Figure 9-7. Layout Recommendation for Dual-Channel DGK Package



10 Device and Documentation Support

10.1 Documentation Support

10.1.1 Related Documentation

For related documentation, see the following:

- Texas Instruments, OPA2863ADGK Evaluation Module user's guide
- Texas Instruments, Single-Supply Op Amp Design Techniques application report

10.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

10.3 Support Resources

TI E2E[™] support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

10.4 Trademarks

MSP430[™] and TI E2E[™] are trademarks of Texas Instruments.

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10.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

10.6 Glossary

TI Glossary

This glossary lists and explains terms, acronyms, and definitions.

11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

www.ti.com 20-Jan-2024

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing		Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
OPA2863DR	ACTIVE	SOIC	D	8	3000	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 125	O2863D	Samples
OPA2863IDGKR	ACTIVE	VSSOP	DGK	8	2500	RoHS & Green	NIPDAUAG SN	Level-2-260C-1 YEAR	-40 to 125	2FJ4	Samples
OPA2863RUNR	ACTIVE	QFN	RUN	10	3000	RoHS & Green	NIPDAUAG	Level-2-260C-1 YEAR	-40 to 125	O263	Samples
OPA4863PWR	ACTIVE	TSSOP	PW	14	3000	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 125	OPA4863	Samples
OPA863DBVR	ACTIVE	SOT-23	DBV	5	3000	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 125	2QS5	Samples
OPA863SIDBVR	ACTIVE	SOT-23	DBV	6	3000	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 125	O863	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

PACKAGE OPTION ADDENDUM

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OTHER QUALIFIED VERSIONS OF OPA2863:

Automotive : OPA2863-Q1

NOTE: Qualified Version Definitions:

• Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

PACKAGE MATERIALS INFORMATION

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TAPE AND REEL INFORMATION





	-
A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
OPA2863DR	SOIC	D	8	3000	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
OPA2863IDGKR	VSSOP	DGK	8	2500	330.0	12.4	5.25	3.35	1.25	8.0	12.0	Q1
OPA2863RUNR	QFN	RUN	10	3000	180.0	8.4	2.2	2.2	1.2	4.0	8.0	Q2
OPA4863PWR	TSSOP	PW	14	3000	330.0	12.4	6.9	5.6	1.6	8.0	12.0	Q1
OPA863DBVR	SOT-23	DBV	5	3000	178.0	9.0	3.3	3.2	1.4	4.0	8.0	Q3
OPA863SIDBVR	SOT-23	DBV	6	3000	178.0	9.0	3.3	3.2	1.4	4.0	8.0	Q3



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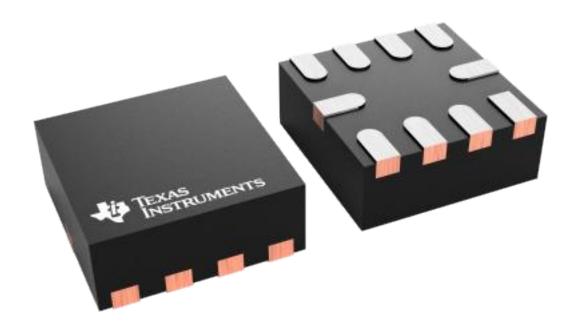
*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
OPA2863DR	SOIC	D	8	3000	356.0	356.0	35.0
OPA2863IDGKR	VSSOP	DGK	8	2500	366.0	364.0	50.0
OPA2863RUNR	QFN	RUN	10	3000	213.0	191.0	35.0
OPA4863PWR	TSSOP	PW	14	3000	356.0	356.0	35.0
OPA863DBVR	SOT-23	DBV	5	3000	180.0	180.0	18.0
OPA863SIDBVR	SOT-23	DBV	6	3000	190.0	190.0	30.0

2 X 2, 0.5 mm pitch

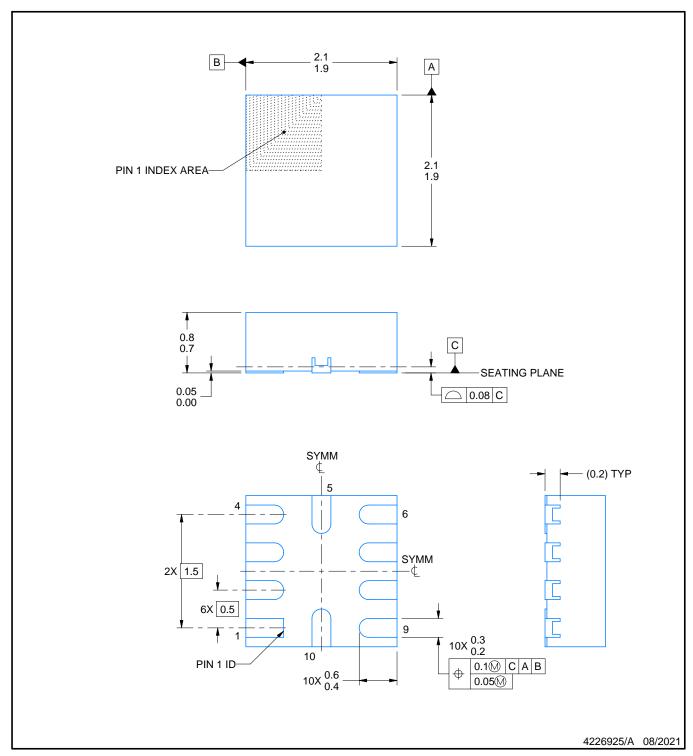
PLASTIC QUAD FLATPACK - NO LEAD

This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.





PLASTIC QUAD FLATPACK - NO LEAD

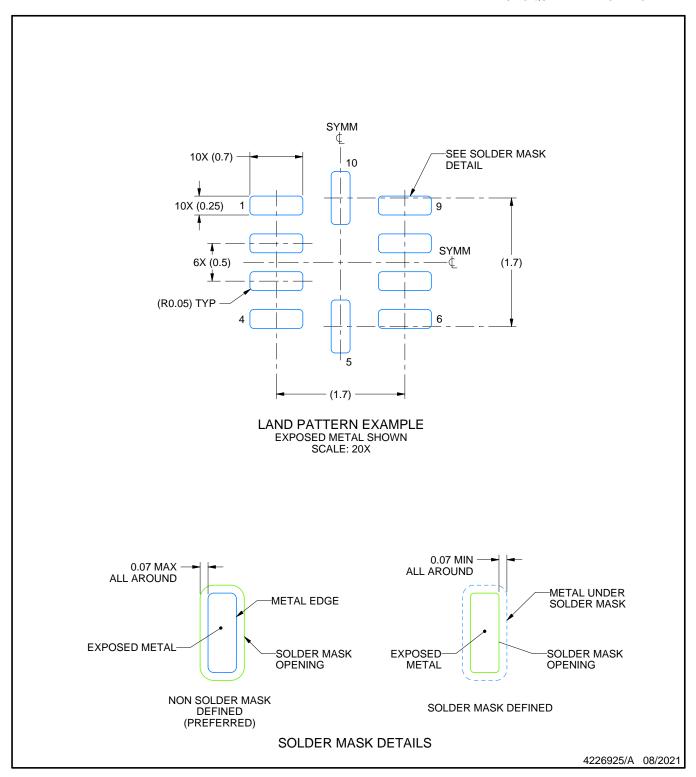


NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
 2. This drawing is subject to change without notice.



PLASTIC QUAD FLATPACK - NO LEAD

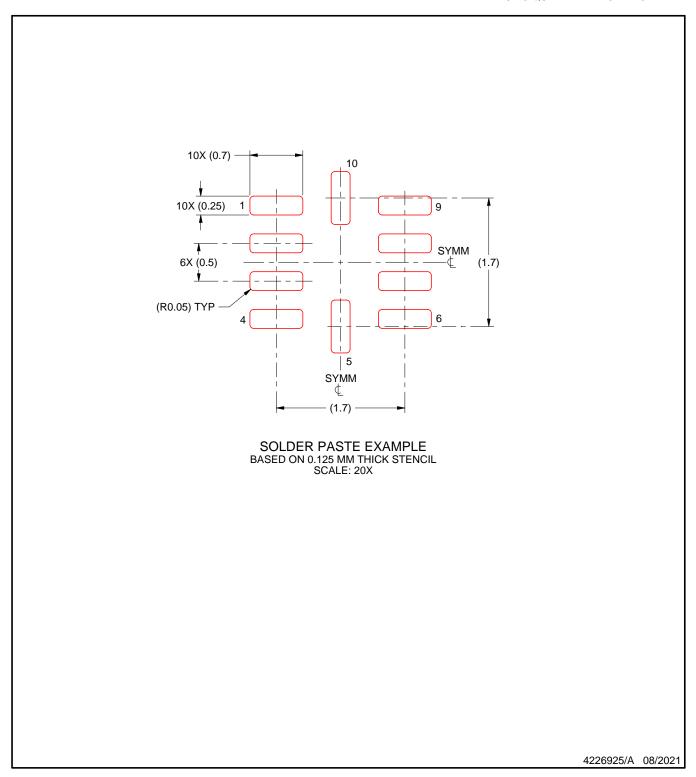


NOTES: (continued)

3. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).



PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.





SMALL OUTLINE INTEGRATED CIRCUIT



- 1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.



SMALL OUTLINE INTEGRATED CIRCUIT



- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.







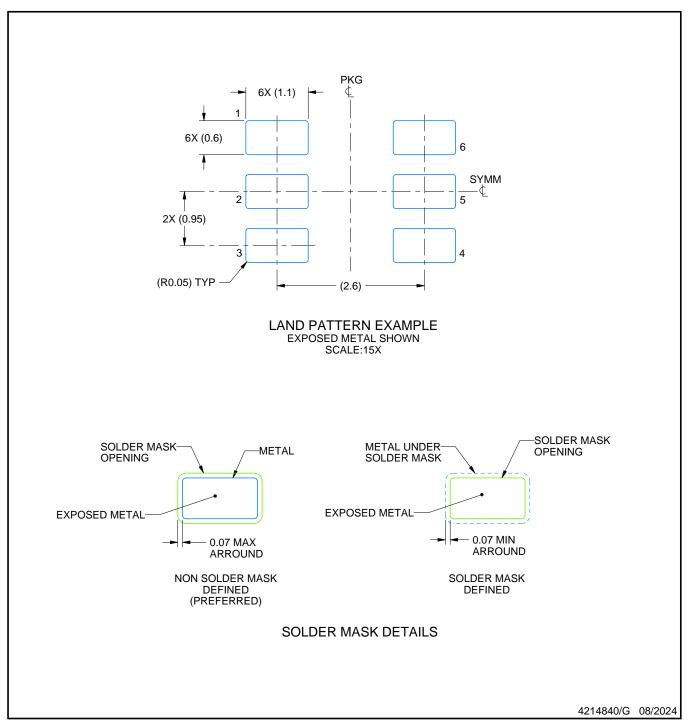
- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

 2. This drawing is subject to change without notice.

 3. Body dimensions do not include mold flash or protrusion. Mold flash and protrusion shall not exceed 0.25 per side.

- 4. Leads 1,2,3 may be wider than leads 4,5,6 for package orientation.
- 5. Refernce JEDEC MO-178.





NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.





- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.







- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

 2. This drawing is subject to change without notice.

 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-153.





NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.





- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.







- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
 2. This drawing is subject to change without notice.
 3. Reference JEDEC MO-178.

- 4. Body dimensions do not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.25 mm per side.
- 5. Support pin may differ or may not be present.





NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.





- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.







PowerPAD is a trademark of Texas Instruments.

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

 2. This drawing is subject to change without notice.

 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-187.





- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
- 8. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.
- 9. Size of metal pad may vary due to creepage requirement.





- 11. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 12. Board assembly site may have different recommendations for stencil design.



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