

Technical documentation



Support & training



TLC555-Q1 SLFS078C – OCTOBER 2006 – REVISED APRIL 2024

# TLC555-Q1 Automotive LinCMOS<sup>™</sup> Technology Timer

# 1 Features

- AEC-Q100 qualified for automotive applications:
  Temperature grade 1: -40°C to +125°C, T<sub>A</sub>
- Functional Safety-Capable
  - Documentation available to aid functional safety system design
- Very-low power consumption
- 1mW (typical) at V<sub>DD</sub> = 5V
- Capable of operation in astable mode
- CMOS output capable of swinging rail to rail
- High-output-current capability
  - Sink 100mA (typical)
  - Source 10mA (typical)
- Output fully compatible with CMOS, TTL, and MOS
- Low supply current reduces spikes during output transitions
- Single-supply operation from 2V to 15V
- Temperature range: –40°C to +125°C
- Functionally interchangeable with the NE555; has same pinout

# 2 Applications

- Precision timing
- Pulse generation
- Sequential timing
- Time delay generation
- Pulse width modulation
- Pulse position modulation
- Linear ramp generators
- Automotive lamp and LED lighting
- Telematics

# **3 Description**

The TLC555-Q1 is a monolithic timing circuit fabricated using TI LinCMOS<sup>™</sup> technology. The timer is fully compatible with CMOS, TTL, and MOS logic and operates at frequencies up to 2MHz. As a result of the high input impedance, this device supports smaller timing capacitors than capacitors used by the NE555. Thus, more accurate time delays and oscillations are possible. Power consumption is low across the full power-supply voltage range.

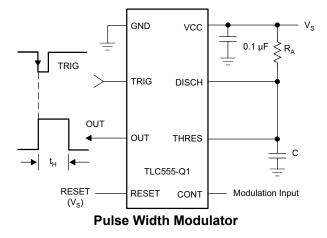
Like the NE555, the TLC555-Q1 has a trigger level equal to approximately one-third of the supply voltage, and a threshold level equal to approximately twothirds of the supply voltage. These levels can be altered by using the control voltage pin (CONT). When the trigger input (TRIG) falls below the trigger level, the flip-flop is set, and the output goes high. If TRIG is greater than the trigger level and the threshold input (THRES) is greater than the threshold level, the flip-flop is reset and the output goes low. The reset input (RESET) can override all other inputs and is used to initiate a new timing cycle. If RESET is low, the flip-flop is reset and the output goes low. Whenever the output is low, a low-impedance path is provided between the discharge pin (DISCH) and GND. Tie all unused inputs to an appropriate logic level to prevent false triggering.

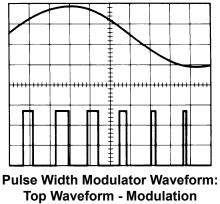
#### **Package Information**

PART NUMBER	PACKAGE <sup>(1)</sup>	PACKAGE SIZE <sup>(2)</sup>		
TLC555-Q1	SOIC (8)	4.9mm × 6.0mm		

(1) For more information, see Section 10.

(2) The package size (length × width) is a nominal value and includes pins, where applicable.





Bottom Waveform - Output Voltage

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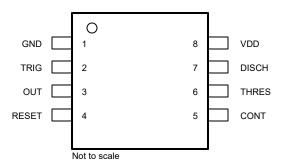


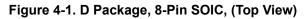
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# 4 Pin Configuration and Functions





#### **Table 4-1. Pin Functions**

PIN		ТҮРЕ	DESCRIPTION	
NAME	NO.		DESCRIPTION	
CONT	5	Input/Output	Controls comparator thresholds. Outputs 2/3 $V_{\text{DD}}$ , allows bypass capacitor connection.	
DISCH	7	Output	Open collector output to discharge timing capacitor	
GND	1	—	Ground	
OUT	3	Output	High current timer output signal	
RESET	4	Input	Active low reset input forces output and discharge low	
THRES	6	Input	End of timing input. THRES > CONT sets output low and discharge low.	
TRIG	2	Input	Start of timing input. TRIG < 1/2 CONT sets output high and discharge open.	
VDD	8	_	Input supply voltage, 2 V to 15 V	



# **5** Specifications

### 5.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

				MIN	MAX	UNIT
V <sub>DD</sub>	Supply voltage <sup>(2)</sup>				18	V
VI	Input voltage, any input			-0.3	V <sub>DD</sub>	V
	Sink current, discharge or output				150	mA
lo	Source current, output			15	mA	
	Continuous total power rating <sup>(3)</sup>	T <sub>A</sub> ≤ 25°C			900	mW
		T <sub>A</sub> = 125°C			180	11174
	Continuous total power dissipation derating	g factor <sup>(3)</sup> , T <sub>A</sub> ≥ 25°C			7.2	mW/°C
T <sub>A</sub>	Operating free-air temperature			-40	125	°C
T <sub>stg</sub>	Storage temperature			-65	150	°C

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltage values are with respect to network GND.

(3) See Thermal Information.

## 5.2 ESD Ratings

				VALUE	UNIT
	_	Human-body model (HBM), per AEC Q100-002 <sup>(1)</sup>		±1000	
V <sub>(ESD)</sub>	Electrostatic discharge	Charged-device model (CDM), per AEC Q100-011	All pins	±500	V
	je	Charged-device moder (CDM), per AEC Q100-011	Corner pins (1, 4, 5, and 8)	±750	

(1) AEC Q100-002 indicates that HBM stressing shall be in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

### **5.3 Recommended Operating Conditions**

		MIN	MAX	UNIT
V <sub>DD</sub>	Supply voltage	2	15	V
T <sub>A</sub>	Operating free-air temperature	-40	125	°C

### **5.4 Thermal Information**

		TLC555-Q1	
	THERMAL METRIC <sup>(1)</sup>	D (SOIC)	UNIT
		8 PINS	
R <sub>0JA</sub>	Junction-to-ambient thermal resistance	138.9	°C/W
R <sub>0JC(top)</sub>	Junction-to-case (top) thermal resistance	78.8	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	87.9	°C/W
Ψ <sub>JT</sub>	Junction-to-top characterization parameter	23.2	°C/W
Ψјв	Junction-to-board characterization parameter	86.9	°C/W
R <sub>0JC(bot)</sub>	Junction-to-case (bottom) thermal resistance	N/A	°C/W

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report.



# 5.5 Electrical Characteristics: V<sub>DD</sub> = 5 V

 $V_{DD}$  = 5 V, at specified free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS <sup>(1)</sup>		MIN	TYP	MAX	UNIT
\ <i>\</i>	<b>T</b> here <b>a</b> has held as a file and	25°C		2.8	3.3	3.8	
V <sub>IT</sub>	Threshold voltage	Full range		2.7		3.9	V
		25°C			10		
IIT	Threshold current	Full range			5000		pА
.,	<b>-</b>	25°C		1.36	1.66	1.96	
V <sub>I(TRIG)</sub>	Trigger voltage	Full range		1.26		2.06	V
	<b>-</b>	25°C			10		
I <sub>I(TRIG)</sub>	Trigger current	Full range			5000		pА
		25°C		0.4	1.1	1.5	
V <sub>I(RESET)</sub>	Reset voltage	Full range		0.3		1.8	V
			25°C		10		
	Reset current	$V_{RESET} = V_{DD}$	Full range		5000		pА
I <sub>I(RESET)</sub>		V <sub>RESET</sub> = 0 V	25°C		5.9		μA
			Full range		6		
	Control voltage (open-circuit) as a percentage of supply voltage	Full range			66.7%		
	Discharge-switch on-state	1 = 10 = 0	25°C		0.14	0.5	V
	voltage	I <sub>OL</sub> = 10 mA	Full range			0.6	V
	Discharge-switch off-state	25°C	ł		0.1		
	current	Full range			120		nA
\ <i>\</i>		1 - 1 - 1	25°C	4.1	4.8		- V
V <sub>OH</sub>	High-level output voltage	I <sub>OH</sub> = –1 mA	Full range	4.1			v
		L = 9 m 4	25°C		0.21	0.4	
		I <sub>OL</sub> = 8 mA	Full range			0.6	
V		L = 5 m A	25°C		0.13	0.3	V
V <sub>OL</sub>	Low-level output voltage	I <sub>OL</sub> = 5 mA	Full range			0.45	v
		L = 2.2 mA	25°C		0.08	0.3	
		I <sub>OL</sub> = 3.2 mA	Full range			0.4	
1	Supply surrent <sup>(2)</sup>	25°C			180	350	^
I <sub>DD</sub>	Supply current <sup>(2)</sup>	Full range				700	μA

Full-range  $T_A$  is -40°C to 125°C.

(1) (2) These values apply for the expected operating configurations in which THRES is connected directly to DISCH or TRIG.



# 5.6 Electrical Characteristics: V<sub>DD</sub> = 15 V

 $V_{DD}$  = 15 V, at specified free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS <sup>(1)</sup>		MIN	TYP	MAX	UNIT	
.,	Thursday I down the sur-	25°C		9.45	10	10.55		
V <sub>IT</sub>	Threshold voltage	Full range		9.35		10.65	V	
		25°C			10			
IT	Threshold current	Full range			5000		pА	
.,	<b>—</b> · · · ·	25°C		4.65	5	5.35		
V <sub>I(TRIG)</sub>	Trigger voltage	Full range		4.55		5.45	V	
	Trianan aumant	25°C			10			
I(TRIG)	Trigger current	Full range			5000		pА	
	Depart voltage	25°C		0.4	1.1	1.5	V	
V <sub>I(RESET)</sub>	Reset voltage	Full range		0.3		1.8	v	
		- X/	25°C		10			
	Depot ourrout	V <sub>RESET</sub> = V <sub>DD</sub>	Full range		5000		pА	
I <sub>I(RESET)</sub>	Reset current		25°C		17.8			
		V <sub>RESET</sub> = 0 V	Full range		18		μA	
	Control voltage (open-circuit) as a percentage of supply voltage	Full range			66.7%			
	Discharge-switch on-state voltage Discharge switch off-state current	1 = 100 = 1	25°C		0.77	1.7		
		I <sub>OL</sub> = 100 mA	Full range			1.8	V	
		25°C			0.1		~ ^	
		Full range			120		nA	
		I <sub>OH</sub> = -10 mA	25°C	12.5	14.2			
			Full range	12.5				
	High-level output voltage	I <sub>OH</sub> = –5 mA	25°C	13.5	14.6		V	
V <sub>OH</sub>		1 <sub>OH</sub> – –3 mA	Full range	13.5			v	
		I <sub>OH</sub> = –1 mA	25°C	14.2	14.9			
		IOH I IIIA	Full range	14.2				
		I <sub>OL</sub> = 100 mA	25°C		1.28	3.2		
		$I_{OL} = 100 \text{ mA}$	Full range			3.8		
,		$1 - 50 m^{1}$	25°C		0.63	1	V	
V <sub>OL</sub>	Low-level output voltage	I <sub>OL</sub> = 50 mA	Full range			1.5	v	
		$l_{\rm ev} = 10 \mathrm{mA}$	25°C		0.12	0.3		
		I <sub>OL</sub> = 10 mA	Full range			0.45		
1	Supply current <sup>(2)</sup>	25°C			360	600		
DD		Full range				1000	μA	

Full-range T<sub>A</sub> is -40°C to 125°C.
 These values apply for the expected operating configurations in which THRES is connected directly to DISCH or TRIG.



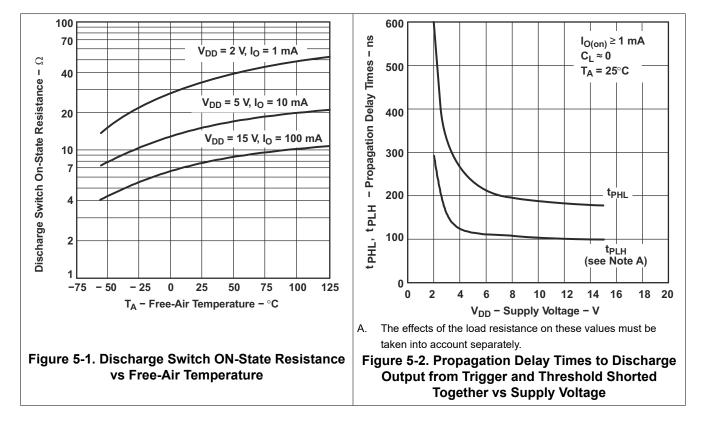
## **5.7 Switching Characteristics**

at V<sub>DD</sub> = 5 V, T<sub>A</sub> = 25°C (unless otherwise noted); characteristic values are specified by design, characterization, or both

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
	Supply voltage sensitivity of timing interval	$V_{DD}$ = 5 V to 15 V, C <sub>T</sub> = 0.1 μF R <sub>A</sub> = R <sub>B</sub> = 1 kΩ to 100 kΩ <sup>(1)</sup>		0.1	0.5	%/V
t <sub>r</sub>	Output pulse rise time	$R_{L} = 10 M\Omega, C_{L} = 10 pF$		20	75	ns
t <sub>f</sub>	Output pulse fall time	$R_{L} = 10 M\Omega, C_{L} = 10 pF$		15	60	ns
f <sub>max</sub>	Maximum frequency in astable mode	$R_A$ = 470 Ω, $C_T$ = 200 pF $R_B$ = 200 Ω <sup>(1)</sup>	1.2	2.1		MHz

(1)  $R_A$ ,  $R_B$ , and  $C_T$  are as defined in Figure 5-1.

### **5.8 Typical Characteristics**

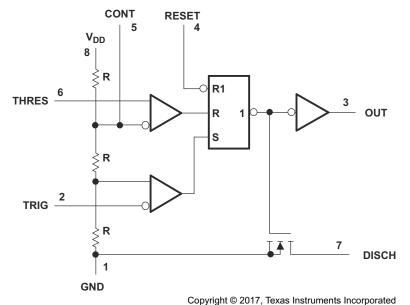




# 6 Detailed Description

#### 6.1 Overview

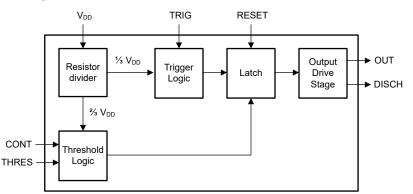
The TLC555-Q1 timer is used for general-purpose timing applications from 476 ns to hours or from < 1 MHz to 2.1 MHz. All inputs are level sensitive, and not edge-triggered.



Note: RESET can override TRIG, which can override THRES.

Figure 6-1. Simplified Schematic

#### 6.2 Functional Block Diagram



### 6.3 Feature Description

#### 6.3.1 Monostable Operation

For monostable operation, Figure 6-2 shows how any of these timers can be connected. If the output is low, application of a negative-going pulse to the trigger (TRIG) sets the flip-flop ( $\overline{Q}$  goes low), drives the output high, and turns off Q1. Capacitor C charges through R<sub>A</sub> until the voltage across the capacitor reaches the threshold voltage of the threshold (THRES) input. If TRIG returns to a high level, the output of the threshold comparator resets the flip-flop ( $\overline{Q}$  goes high), drives the output low, and discharges C through Q1.



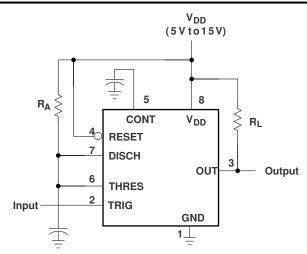
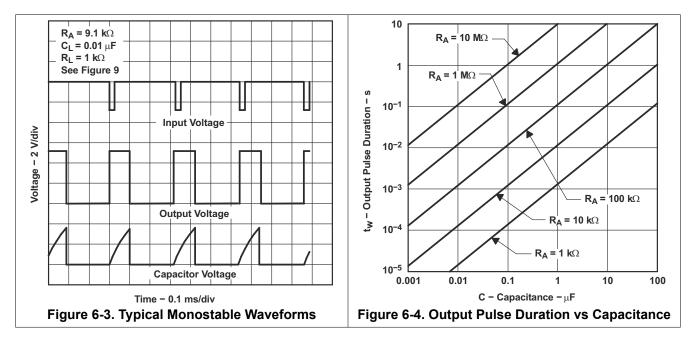


Figure 6-2. Circuit for Monostable Operation

Monostable operation is initiated when TRIG voltage falls below the trigger threshold. When initiated, the sequence ends only if TRIG is high for at least 10  $\mu$ s before the end of the timing interval. When the trigger is grounded, the comparator storage time can be as long as 10  $\mu$ s, which limits the minimum monostable pulse duration to 10  $\mu$ s. Because of the threshold level and saturation voltage of Q1, the output pulse duration is approximately t<sub>w</sub> = 1.1R<sub>A</sub>C. Figure 6-3 is a plot of the time constant for various values of R<sub>A</sub> and C. The threshold levels and charge rates are directly proportional to the supply voltage (V<sub>DD</sub>). As a result, the timing interval is independent of the supply voltage if the supply voltage is constant during the time interval.

Applying a negative-going trigger pulse simultaneously to RESET and TRIG during the timing interval discharges C and reinitiates the cycle, commencing on the positive edge of the reset pulse. The output is held low as long as the reset pulse is low. To prevent false triggering, connect RESET to  $V_{DD}$  when RESET is not being used. If the RESET function is required and the pin is driven by external logic or a microcontroller, use a pullup resistor to  $V_{DD}$  (such as 10 k $\Omega$ ) to prevent the RESET pin from floating. If the RESET function is not required, short the RESET pin directly to the  $V_{DD}$  pin.

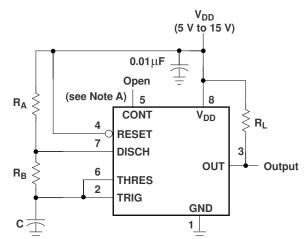




#### 6.3.2 Astable Operation

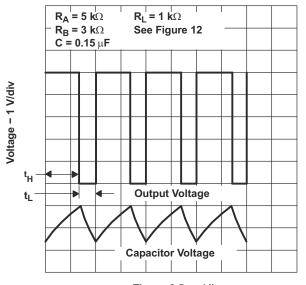
Figure 6-5 shows that adding a second resistor ( $R_B$ ) to the circuit and connecting the trigger input to the threshold input causes the timer to self-trigger and run as a multivibrator. The C capacitor charges through  $R_A$  and  $R_B$  and then only discharges through  $R_B$ . As a result, the values of  $R_A$  and  $R_B$  control the duty cycle.

This astable connection results in the C capacitor charging and discharging between the threshold-voltage level ( $\approx 0.67 \times V_{DD}$ ) and the trigger-voltage level ( $\approx 0.33 \times V_{DD}$ ). As in the monostable circuit, charge and discharge times (and as a result, the frequency and duty cycle) are independent of the supply voltage.



A. Decoupling CONT voltage to ground with a capacitor can improve operation. This must be evaluated for individual applications.

Figure 6-5. Circuit for Astable Operation





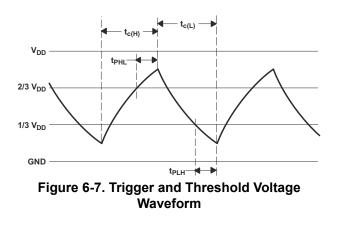




Figure 6-7 shows typical waveforms generated during astable operation. Calculate the output high-level duration ( $t_H$ ) and low-level duration  $t_L$  for frequencies less than or equal to 100 kHz as follows:

$$t_{\rm H} = 0.693 (R_{\rm A} + R_{\rm B})C$$
 (1)

$$t_{\rm L} = 0.693 (R_{\rm B})C$$
 (2)

Other useful relationships are shown as follows:

period = 
$$t_{H} + t_{L} = 0.693 (R_{A} + 2R_{B})C$$
 (3)

frequency 
$$\approx \frac{1.44}{(R_A + 2R_B)C}$$
 (4)

Output driver duty cycle = 
$$\frac{t_L}{t_H + t_L} = \frac{R_B}{R_A + 2R_B}$$
 (5)

Output waveform duty cycle = 
$$\frac{t_H}{t_H + t_L} = 1 - \frac{R_B}{R_A + 2R_B}$$
 (6)

Low-to-high ratio = 
$$\frac{t_L}{t_H} = \frac{R_B}{R_A + R_B}$$
 (7)

Equation 1 to Equation 7 do not account for any propagation delay times from the TRIG and THRES inputs to DISCH output. These delay times add directly to the period and overcharge the capacitor, which creates differences between calculated and actual values that increase with frequency. In addition, the internal on-state resistance  $r_{on}$  during discharge adds to  $R_B$  to provide another source of timing error in the calculation when  $R_B$  is very low. The following equations provide better agreement with measured values. The formulas in Equation 8 represent the actual low and high times when used at higher frequencies (beyond 100 kHz) because propagation delay and discharge on resistance is added to the formulas. The value of  $C_T$  includes both the nominal or deliberate timing capacitance, as well as parasitic capacitance on the PCB. Decoupling capacitance on CONT also affects the duty cycle, with an error contribution that depends on the capacitor leakage resistance. For additional discussion, see the *Design low-duty-cycle timer circuits* article.

$$\begin{split} t_{c(H)} &= C_T \, \left( R_A + R_B \right) \text{In} \left[ 3 - \text{exp} \left( \frac{-t_{\text{PLH}}}{C_T (R_B + r_{\text{on}})} \right) \right] + t_{\text{PHL}} \\ t_{c(L)} &= C_T \, \left( R_B + r_{\text{on}} \right) \text{In} \left[ 3 - \text{exp} \left( \frac{-t_{\text{PHL}}}{C_T (R_A + R_B)} \right) \right] + t_{\text{PLH}} \end{split}$$

(8)



These equations and those given earlier are similar in that a time constant is multiplied by the logarithm of a number or function. The limit values of the logarithmic terms must be between ln(2) at low frequencies, and ln(3) at extremely high frequencies. For a duty cycle close to 50%, an appropriate constant for the logarithmic terms can be substituted with good results. Output waveform duty cycles less than 50% require that  $t_{c(H)} / t_{c(L)} < 1$  and possibly that  $R_A \leq r_{on}$ . These conditions can be difficult to obtain. Figure 6-8 shows the nominal free-running frequency associated with various combinations of  $C_T$  and  $R_A + 2 \times R_B$ .

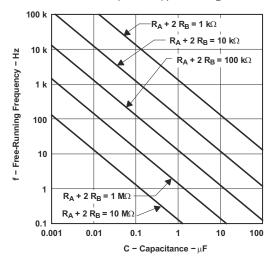


Figure 6-8. Free-Running Frequency

#### 6.3.3 Frequency Divider

By adjusting the length of the timing cycle, the basic circuit of the TLC555-Q1 can operate as a frequency divider. Figure 6-9 shows a divide-by-three circuit that reinforces that re-triggering cannot occur during the timing cycle.

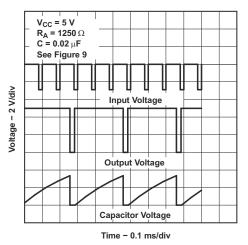


Figure 6-9. Divide-by-Three Circuit Waveforms



#### 6.4 Device Functional Modes

Table 6-1 lists the device functional modes. For a valid reset voltage condition, use an external pullup resistor to  $V_{DD}$  (if using the RESET functionality), or short the RESET pin directly to  $V_{DD}$  (if the RESET functionality is not used).

Table 6-1. Function Table								
RESET      TRIGGER VOLTAGE <sup>(1)</sup> THRESHOLD VOLTAGE <sup>(1)</sup> OUTPUT      DISCHARGE SWITCH								
Low	Irrelevant	Irrelevant	Low	On				
High	< 1/3 V <sub>DD</sub>	Irrelevant	High	Off				
High	> 1/3 V <sub>DD</sub>	> 2/3 V <sub>DD</sub>	Low	On				
High	> 1/3 V <sub>DD</sub>	< 2/3 V <sub>DD</sub>	As previously established					

(1) Voltage levels shown are nominal.



# 7 Application and Implementation

#### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

#### 7.1 Application Information

The TLC555-Q1 timer device uses resistor and capacitor charging delay to provide a programmable time delay or operating frequency. The following section presents a simplified discussion of the design process.

#### 7.2 Typical Applications

#### 7.2.1 Missing-Pulse Detector

The circuit shown in Figure 7-1 can detect a missing pulse or abnormally long spacing between consecutive pulses in a train of pulses. The timing interval of the mono-stable circuit is re-triggered continuously by the input pulse train if the pulse spacing is less than the timing interval. A longer pulse spacing, missing pulse, or terminated pulse train permits the timing interval to be completed, which generates an output pulse as shown in Figure 7-2.

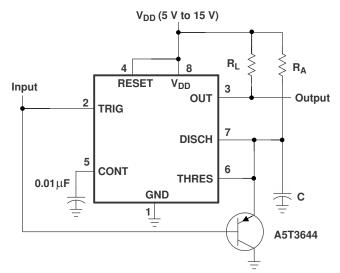


Figure 7-1. Circuit for Missing-Pulse Detector

#### 7.2.1.1 Design Requirements

Input fault (missing pulses) must be input high. Input stuck low is not detected because timing capacitor (C) remains discharged.

#### 7.2.1.2 Detailed Design Procedure

Select  $R_A$  and C so that  $R_A \times C > [maximum normal input high time]$ .  $R_L$  improves  $V_{OH}$ , but is not required for TTL compatibility.



#### 7.2.1.3 Application Curve

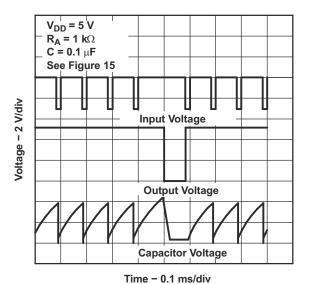
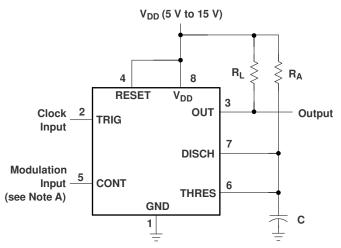


Figure 7-2. Completed Timing Waveforms for Missing-Pulse Detector

#### 7.2.2 Pulse-Width Modulation

The operation of the timer can be modified by modulating the internal threshold and trigger voltages by applying an external voltage (or current) to CONT. Figure 7-3 shows a circuit for pulse-width modulation. A continuous input pulse train triggers the mono-stable circuit, and a control signal modulates the threshold voltage. Figure 7-4 shows the resulting output pulse-width modulation. While a sine-wave modulation signal is shown, any wave shape can be used.



A. The modulating signal can be direct or capacitively coupled to CONT. For direct coupling, the effects of modulation source voltage and impedance on the bias of the timer must be considered.

Figure 7-3. Circuit for Pulse-Width Modulation

#### 7.2.2.1 Design Requirements

Clock input must have  $V_{OL}$  and  $V_{OH}$  levels that are less than and greater than 1/3 VDD. Modulation input can vary from ground to VDD. The application must be tolerant of a nonlinear transfer function; the relationship between modulation input and pulse width is not linear because the capacitor charge is based RC on an negative exponential curve.



#### 7.2.2.2 Detailed Design Procedure

Select  $R_A$  and C so that  $R_A \times C = 1/4$  [clock input period].  $R_L$  improves  $V_{OH}$ , but is not required for TTL compatibility.

#### 7.2.2.3 Application Curve

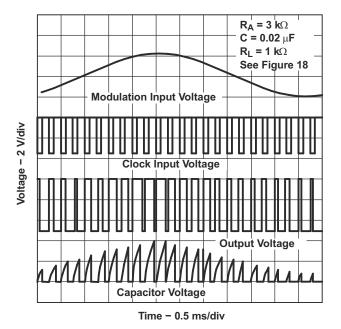
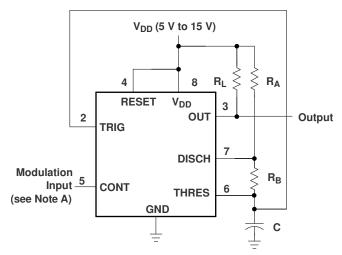


Figure 7-4. Pulse-Width-Modulation Waveforms

#### 7.2.3 Pulse-Position Modulation

As shown in Figure 7-5, any of these timers can be used as a pulse-position modulator. This application modulates the threshold voltage and the time delay of a free-running oscillator. Figure 7-6 shows a triangular-wave modulation signal for this type of circuit; however, any wave shape can be used.



A. The modulating signal can be direct or capacitively coupled to CONT. For direct coupling, the effects of modulation source voltage and impedance on the bias of the timer must be considered.

#### Figure 7-5. Circuit for Pulse-Position Modulation



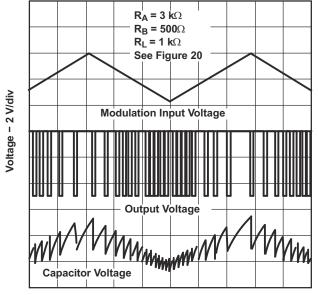
#### 7.2.3.1 Design Requirements

Both DC and AC coupled modulation inputs change the upper and lower voltage thresholds for the timing capacitor. Both frequency and duty cycle vary with the modulation voltage.

#### 7.2.3.2 Detailed Design Procedure

The nominal output frequency and duty cycle can be determined using formulas in Section 6.3.2.  $R_L$  improves  $V_{OH}$ , but is not required for TTL compatibility.

#### 7.2.3.3 Application Curve



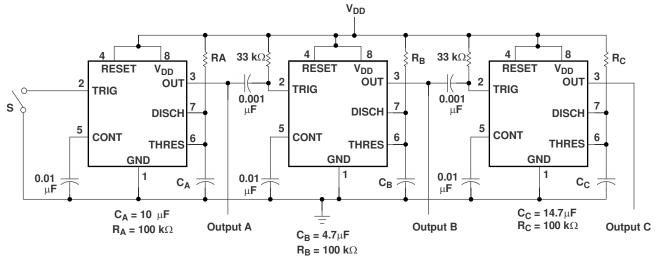
Time - 0.1 ms/div

Figure 7-6. Pulse-Position-Modulation Waveforms

#### 7.2.4 Sequential Timer

Many applications (such as computers) require signals for initializing conditions during start-up. Other applications (such as test equipment) require activation of test signals in sequence. These timing circuits can connect to provide sequential control. The timers can be used in various combinations of a-stable or mono-stable circuit connections with or without modulation for extremely flexible waveform control. Figure 7-7 shows a sequencer circuit with possible applications in many systems; Figure 7-8 shows the output waveforms.





NOTE A: S closes momentarily at t = 0.

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#### Figure 7-7. Sequential Timer Circuit

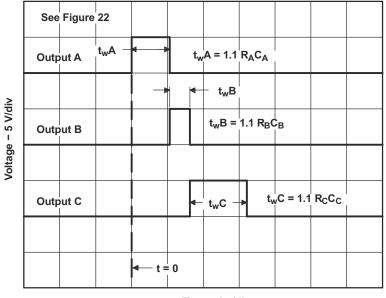
#### 7.2.4.1 Design Requirements

The sequential timer application chains together multiple mono-stable timers. The joining components are  $33-k\Omega$  resistors and  $0.001-\mu$ F capacitors. The output high to low edge passes a 10- $\mu$ s start pulse to the next mono-stable.

#### 7.2.4.2 Detailed Design Procedure

The timing resistors and capacitors can be selected using this formula:  $t_w = 1.1 \times R \times C$ .

#### 7.2.4.3 Application Curve



t - Time - 1 s/div

Figure 7-8. Sequential Timer Waveforms



#### 7.3 Power Supply Recommendations

The TLC555-Q1 requires a voltage supply within 4.5 V to 15 V. Adequate power supply bypassing is required to protect associated circuitry. The minimum recommended value is 0.1  $\mu$ F in parallel with a 1- $\mu$ F electrolytic. Place the bypass capacitors as close as possible to the TLC555-Q1 and minimize the trace length.

#### 7.4 Layout

#### 7.4.1 Layout Guidelines

Standard PCB rules apply to routing the TLC555-Q1. The 0.1  $\mu$ F in parallel with a 1- $\mu$ F electrolytic capacitor must be as close as possible to the TLC555-Q1. The capacitor used for the time delay must be placed as close to the discharge pin. A ground plane on the bottom layer can provide better noise immunity and signal integrity.

#### 7.4.2 Layout Example

Figure 7-9 shows the basic layout for various applications.

- C1 based on time delay calculations
- C2 0.01-µF bypass capacitor for control voltage pin
- C3 0.1-µF bypass ceramic capacitor
- C4 1-µF electrolytic bypass capacitor
- R1 based on time delay calculations

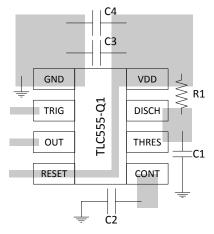


Figure 7-9. Recommended Layout



## 8 Device and Documentation Support

#### 8.1 Documentation Support

#### 8.1.1 Related Documentation

For related documentation see the following:

- Texas Instruments, TLC555-Q1 Used as a Positive and Negative Charge Pump application note
- Texas Instruments, EMC Compatible Automotive LED Rear Lamp With Sequential-Turn Animation Reference Design

#### 8.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

#### 8.3 Support Resources

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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#### 8.4 Trademarks

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#### 8.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### 8.6 Glossary

TI Glossary This glossary lists and explains terms, acronyms, and definitions.

#### **9 Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

С	hanges from Revision B (May 2015) to Revision C (April 2024)	Page
•	Added reference to functional safety documentation in <i>Features</i>	1
•	Deleted Description (continued) section	1
•	Updated Package Information table	
•	Deleted Dissipation Ratings and moved continuous total power dissipation specifications to Absolute	
	Maximum Ratings	3
•	Changed continuous total power dissipation power rating from 725mW to 900mW at $T_A \le 25^{\circ}$ C and from 145mW to 180mW at $T_A = 125^{\circ}$ C, and changed derating factor $T_A = 25^{\circ}$ C from 5.8mW/°C to 7.2mW/°C Absolute Maximum Ratings	;, in
•	Updated thermal resistance and characterization parameter values in Thermal Information	
•	Changed reset current (I <sub>I(RESET)</sub> ) test conditions to V <sub>RESET</sub> = V <sub>DD</sub> in both <i>Electrical Characteristics</i> table	s 4
•	Added new reset current (I <sub>I(RESET)</sub> ) typical values for test condition V <sub>RESET</sub> = 0V to both <i>Electrical</i>	
	Characteristics tables.	4
•	Changed supply current typical value from 170 $\mu$ A to 180 $\mu$ A in <i>Electrical Characteristics:</i> $V_{DD}$ = 5 V	4

SLFS078C - OCTOBER 2006 - REVISED APRIL 2024

•	Changed title of <i>Operating Characteristics</i> table to <i>Switching Characteristics</i> and clarified that values are specified by design or characterization	6
•	Deleted initial error of timing interval specification in Switching Characteristics	6
	Added text regarding input type to Overview	
	Changed functional block diagram to simplified schematic and moved to Overview	
	Added new Functional Block Diagram	
	Added guidance for RESET pin pullup resistance in Monostable Operation	
•	Changed V <sub>CC</sub> to V <sub>DD</sub> in <i>Monostable Operation</i>	7
	Added clarity regarding nominal operating frequency and parasitic terms in Astable Operation	
	Changed V <sub>CC</sub> to V <sub>DD</sub> in Astable Operation	
	Deleted Figure 11, Equivalent Schematic, and added guidance concerning the RESET pin in Device	
	Functional Modes	12
•	Changed V <sub>CC</sub> to V <sub>DD</sub> in Table 6-1, <i>Function Table</i>	12
	Added references to application note and reference design in Documentation Support section	

## Changes from Revision A (October 2012) to Revision B (May 2015)

Added ESD Ratings table, Feature Description section, Device Functional Modes, Application and

Implementation section, Power Supply Recommendations section, Layout section, Device and 

С	Changes from Revision * (October 2006) to Revision A (October 2012)					
•	Added AEC-Q100 qualifying text to <i>Features</i> section	1				
•	Updated data sheet text to the latest documentation and translation standards	1				
•	Updated next-to-last paragraph in Description and Ordering Information sections	1				
•	In the 5-V and 15-V Electrical Characteristics tables, changed all "MAX" entries in the T <sub>A</sub> column to					
	"Full range"	4				
•	Deleted the last Electrical Characteristics table, which contained only redundant data					

# 10 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

Product Folder Links: TLC555-Q1





## PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
TLC555QDRQ1	ACTIVE	SOIC	D	8	2500	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 125	TL555Q	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

<sup>(6)</sup> Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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#### OTHER QUALIFIED VERSIONS OF TLC555-Q1 :



15-Nov-2022

Catalog : TLC555

Military : TLC555M

NOTE: Qualified Version Definitions:

- Catalog TI's standard catalog product
- Military QML certified for Military and Defense Applications

# TEXAS INSTRUMENTS

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15-Feb-2025

# TUBE



# - B - Alignment groove width

\*All dimensions are nominal

Device	evice Package Name		Pins	SPQ	L (mm)	W (mm)	Τ (μm)	B (mm)
TLC555QDRQ1	D	SOIC	8	2500	506.6	8	3940	4.32

# D0008A



# **PACKAGE OUTLINE**

# SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



#### NOTES:

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.

- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.



# D0008A

# **EXAMPLE BOARD LAYOUT**

# SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



# D0008A

# **EXAMPLE STENCIL DESIGN**

# SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

9. Board assembly site may have different recommendations for stencil design.



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