

## 1 Features

- ## 2 Applications

- Factory automation and control
- Communications equipment
- Retail automation and payment
- Test and measurement
- Pro audio, video, and signage
- Personal electronics

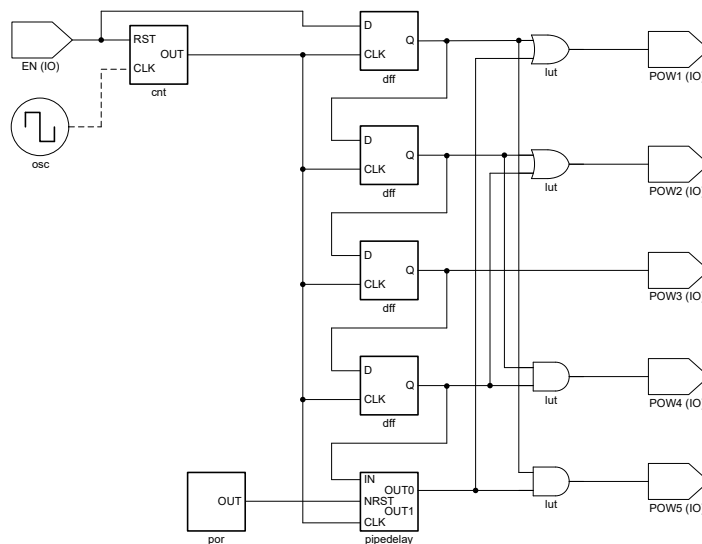
The TPLD801 is part of the TI programmable logic device (TPLD) family of devices that feature versatile programmable logic ICs with combinational logic, sequential logic, and analog blocks. TPLD provides a fully integrated, low power solution to implement common system functions, such as timing delays, voltage monitors, system resets, power sequencers, I/O expanders, and more. This device features configurable I/O structures that extends compatibility within mixed-signal environments, reducing the number of discrete components required.

System designers can create circuits and configure the macro-cells, I/O pins, and interconnections by temporarily emulating the non-volatile memory or by permanently programming the one-time programmable (OTP) through InterConnect Studio. The TPLD801 is supported by hardware and software ecosystem with application notes, reference designs and design examples. Visit [ti.com](https://ti.com) for more information and access to design tools.

## Device Information

PART NUMBER	PACKAGE <sup>(1)</sup>	BODY SIZE (NOM)
TPLD801	DRL (SOT-5X3, 8)	2.1mm × 1.6mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

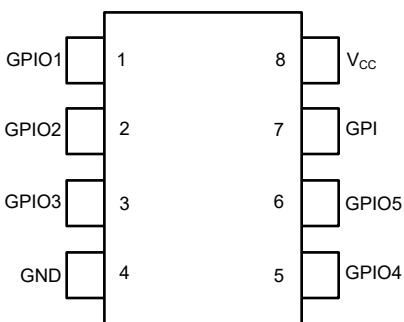


## Simplified Application

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## 4 Pin Configuration and Functions



**Figure 4-1. DRL Package, 8-pin SOT-5X3 (Top View)**

**Table 4-1. Pin Functions**

PIN			DESCRIPTION	
NAME	NO.	TYPE <sup>(1)</sup>	Primary function	Secondary function (if any)
GPIO1	1	I/O	General-purpose I/O.	External OSC IN
GPIO2	2	I/O	General-purpose I/O.	
GPIO3	3	I/O	General-purpose I/O with output enable (OE). <sup>(3)</sup>	
GND	4	P	Ground.	
GPIO4	5	I/O	General-purpose I/O.	
GPIO5	6	I/O	General-purpose I/O.	
GPI	7	I	General purpose input. <sup>(2)</sup>	
VCC	8	P	Positive supply.	

(1) P = power, I/O = input/output, I = Input

(2) The general-purpose input (GPI) pin will sustain a high-voltage (V<sub>PP</sub>) during programming. Take special precaution with peripherals connected to this pin if performing in-system programming.

(3) The output enable (OE) connection is available through the connection mux and can be configured in InterConnect Studio.

## 5 Specifications

### 5.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

			MIN	MAX	UNIT
$V_{CC}$	Supply voltage on $V_{CC}$ relative to GND		-0.5	7	V
$V_I$	Input voltage		-0.5	$V_{CC} + 0.5$	V
$V_O$	Output voltage		-0.5	$V_{CC} + 0.5$	V
$I_{IOK}$	Input-output clamp current	$V_{IO} < 0$ or $V_{IO} > V_{CC}$	-50	50	mA
$I_O$	Continuous output current	$V_O = 0$ to $V_{CC}$	-50	50	mA
$I_{DC}$	Maximum average or DC current (through each pin)	Push-pull 1X		12	mA
		Push-pull 2X		17	
		Open-drain NMOS 1X		18	
		Open-drain NMOS 2X		28	
$T_J$	Junction temperature			150	°C
$T_{stg}$	Storage temperature		-65	150	°C

- (1) Operation outside the *Absolute Maximum Ratings* may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under *Recommended Operating Conditions*. If used outside the *Recommended Operating Conditions* but within the *Absolute Maximum Ratings*, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

### 5.2 ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins <sup>(1)</sup>	±2000	V
		Charged device model (CDM), per ANSI/ESDA/JEDEC specification JS-002, all pins <sup>(2)</sup>	±1000	

- (1) JEDEC document JEP155 states that 500V HBM allows safe manufacturing with a standard ESD control process.  
 (2) JEDEC document JEP157 states that 250V CDM allows safe manufacturing with a standard ESD control process.

### 5.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

			$V_{CC}$	MIN	MAX	UNIT
$V_{CC}$	Supply voltage			1.65	5.5	V
$V_I$	Input voltage			0	$V_{CC}$	V
$V_O$	Output voltage			0	$V_{CC}$	V
$V_{IH}$	High-level input voltage	Logic input	1.65V to 5.5V	$0.53 \times V_{CC}$		V
		Low-voltage logic input	$1.8V \pm 0.15V$	0.90		
			$3.3V \pm 0.3V$	1.08		
			$5V \pm 0.5V$	1.23		
$V_{IL}$	Low-level input voltage	Logic input	1.65V to 5.5V		$0.36 \times V_{CC}$	V
		Low-voltage logic input	$1.8V \pm 0.15V$		0.46	
			$3.3V \pm 0.3V$		0.63	
			$5V \pm 0.5V$		0.74	
$F_{(EXT)}$	External Oscillator Frequency		$1.8V \pm 0.15V$		8	MHz
			$3.3V \pm 0.3V$		8	
			$5V \pm 0.5V$		8	
$T_A$	Ambient temperature			-40	125	°C

## 5.4 Thermal Information

## 5.5 Electrical Characteristics

over operating free-air temperature range (unless otherwise noted)

PARAMETER			TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
<b>Supply and Power-on Reset</b>								
V <sub>PORR</sub>	Power-on reset voltage, V <sub>CC</sub> rising		V <sub>I</sub> = V <sub>CC</sub> or GND, I <sub>O</sub> = 0	1.65V to 5.5V	1.04	1.30	1.50	V
V <sub>PORF</sub>	Power-on reset voltage, V <sub>CC</sub> falling		V <sub>I</sub> = V <sub>CC</sub> or GND, I <sub>O</sub> = 0	1.65V to 5.5V	0.98	1.25	1.33	V
t <sub>SU</sub>	Startup time		from V <sub>CC</sub> rising past V <sub>PORR</sub>	1.65V to 5.5V		170		μs
V <sub>PP</sub>	Programming voltage			1.65V to 5.5V	7.5		8	V
<b>Digital IO</b>								
V <sub>T+</sub>	Positive-going input threshold voltage	Logic Input with Schmitt Trigger		1.8V ± 0.15V	0.92		1.29	V
				3.3V ± 0.3V	1.55		2.17	
				5V ± 0.5V	2.21		3.19	
V <sub>T-</sub>	Negative-going input threshold voltage	Logic Input with Schmitt Trigger		1.8V ± 0.15V	0.56		0.96	V
				3.3V ± 0.3V	1.10		1.79	
				5V ± 0.5V	1.63		2.70	
V <sub>HYS</sub>	Schmitt trigger hysteresis (V <sub>T+</sub> - V <sub>T-</sub> )	Logic Input with Schmitt Trigger		1.8V ± 0.15V	0.23		0.49	V
				3.3V ± 0.3V	0.33		0.54	
				5V ± 0.5V	0.42		0.66	
V <sub>OH</sub>	High-level output voltage	Push-pull 1X or Open-drain PMOS 1X	I <sub>OH</sub> = -100μA	1.8V ± 0.15V	1.62			V
		Push-pull 2X or Open-drain PMOS 2X			1.63			
		Push-pull 1X or Open-drain PMOS 1X	I <sub>OH</sub> = -3mA	3.3V ± 0.3V	2.60			V
		Push-pull 2X or Open-drain PMOS 2X			2.75			
		Push-pull 1X or Open-drain PMOS 1X	I <sub>OH</sub> = -5mA	5V ± 0.5V	3.99			V
		Push-pull 2X or Open-drain PMOS 2X			4.16			
V <sub>OL</sub>	Low-level output voltage	Push-pull 1X	I <sub>OL</sub> = 100μA	1.8V ± 0.15V			0.01	V
		Push-pull 2X					0.01	
		Open-drain NMOS 1X					0.01	
		Open-drain NMOS 2X					0.01	
		Push-pull 1X	I <sub>OL</sub> = 3mA	3.3V ± 0.3V			0.12	V
		Push-pull 2X					0.08	
		Open-drain NMOS 1X					0.12	
		Open-drain NMOS 2X					0.08	
		Push-pull 1X	I <sub>OL</sub> = 5mA	5V ± 0.5V			0.14	V
		Push-pull 2X					0.10	
		Open-drain NMOS 1X					0.14	
		Open-drain NMOS 2X					0.10	
I <sub>I</sub>	Input leakage current	All pins	V <sub>I</sub> = V <sub>CC</sub>	1.65V to 5.5V			±1	μA
			V <sub>I</sub> = GND	1.65V to 5.5V			±1	

over operating free-air temperature range (unless otherwise noted)

PARAMETER			TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
I <sub>OZ</sub>	Off-state (high-Z state) output current	IO3	V <sub>O</sub> = 0 to 5.5V				0.06	μA
F <sub>OUT</sub>	Max output frequency <sup>(1)</sup>	Push-pull 1X or Push-pull 2X	C <sub>L</sub> = 15pF	1.8V ± 0.15V			5	MHz
				3.3V ± 0.3V			12	
				5V ± 0.5V			12	
R <sub>pu(int)</sub>	Internal pull-up resistance						1	MΩ
							100	kΩ
							10	kΩ
R <sub>pd(int)</sub>	Internal pull-down resistance						1	MΩ
							100	kΩ
							10	kΩ
R <sub>pd(int)</sub> _GPI	Internal pull-down resistance (IN0)						1	MΩ
							100	kΩ
							20	kΩ
C <sub>I</sub>	Input pin capacitance	each input pin	V <sub>I</sub> = V <sub>CC</sub> or GND	1.65V to 5.5V		3.2		pF
C <sub>IO</sub>	Input-output pin capacitance	each I/O pin	V <sub>IO</sub> = V <sub>CC</sub> or GND	1.65V to 5.5V		4.0		pF

(1) Open drain switching performance will be limited by pull-up resistors used

## 5.6 Supply Current Characteristics

$T_A = 25^\circ\text{C}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V <sub>CC</sub> = 1.8V ± 0.15V			V <sub>CC</sub> = 3.3V ± 0.3V			V <sub>CC</sub> = 5V ± 0.5V			UNIT
			MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
Standby												
I <sub>CC</sub>	Standby	Inputs = static, Outputs = open, I <sub>O</sub> = 0, OSC powered off	1.04			1.04			1.10			μA
Oscillator												
I <sub>CC</sub>	OSC0 enabled: 25kHz	Predivide = 1	6.22			8.16			13.1			μA
		Predivide = 8	6.26			8.01			13.0			
I <sub>CC</sub>	OSC0 enabled: 2MHz	Predivide = 1	59.6			69.1			88.7			μA
		Predivide = 8	47.2			56.5			76.1			

## 5.7 Switching Characteristics

over operating free-air temperature range (unless otherwise noted)

PARAMETER		FROM (INPUT)	TO (OUTPUT)	TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
Digital IO									
t <sub>pd</sub>	Delay	Digital input	Push-pull output	Rising	1.8V ± 0.15V	46.9		ns	
				Falling		39.5			
				Rising	3.3V ± 0.3V	27.3			
				Falling		26.4			
				Rising	5V ± 0.5V	22.3			
				Falling		22.5			
t <sub>pd</sub>	Delay	Digital input with Schmitt trigger	Push-pull output	Rising	1.8V ± 0.15V	50.8		ns	
				Falling		42.2			
				Rising	3.3V ± 0.3V	29.7			
				Falling		27.2			
				Rising	5V ± 0.5V	24.2			
				Falling		22.8			
t <sub>pd</sub>	Delay	Low-voltage digital input	Push-pull output	Rising	1.8V ± 0.15V	45.6		ns	
				Falling		49.5			
				Rising	3.3V ± 0.3V	25.4			
				Falling		33.0			
				Rising	5V ± 0.5V	19.6			
				Falling		31.5			
t <sub>pd</sub>	Delay	Digital input	Open-drain NMOS output	Rising	1.8V ± 0.15V			ns	
				Falling		39.3			
				Rising	3.3V ± 0.3V				
				Falling		26.2			
				Rising	5V ± 0.5V				
				Falling		22.3			

over operating free-air temperature range (unless otherwise noted)

PARAMETER			FROM (INPUT)	TO (OUTPUT)	TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
t <sub>pd</sub>	Delay	Output enable from pin	OE	Push-pull output	Hi-Z to 1	1.8V ± 0.15V	45.9		ns	
						3.3V ± 0.3V	27.3			
						5V ± 0.5V	22.4			
					Hi-Z to 0	1.8V ± 0.15V	41.1			
						3.3V ± 0.3V	24.5			
						5V ± 0.5V	19.6			
Configurable Use Logic										
t <sub>pd</sub>	Delay	2-bit LUT	IN	OUT	Rising	1.8V ± 0.15V	1.16		ns	
					Falling		1.31			
					Rising	3.3V ± 0.3V	1.16			
					Falling		1.31			
					Rising	5V ± 0.5V	1.16			
					Falling		1.31			
t <sub>pd</sub>	Delay	3-bit LUT	IN	OUT	Rising	1.8V ± 0.15V	1.04		ns	
					Falling		1.26			
					Rising	3.3V ± 0.3V	1.04			
					Falling		1.26			
					Rising	5V ± 0.5V	1.04			
					Falling		1.26			
t <sub>pd</sub>	Delay	4-bit LUT	IN	OUT	Rising	1.8V ± 0.15V	1.62		ns	
					Falling		1.99			
					Rising	3.3V ± 0.3V	1.62			
					Falling		1.99			
					Rising	5V ± 0.5V	1.62			
					Falling		1.99			
t <sub>pd</sub>	Delay	DFF/Latch	CLK	Q	Rising	1.8V ± 0.15V	1.32		ns	
					Falling		1.34			
					Rising	3.3V ± 0.3V	1.32			
					Falling		1.34			
					Rising	5V ± 0.5V	1.32			
					Falling		1.34			
t <sub>pd</sub>	Delay	DFF/Latch	nRST/nSET	Q	Rising	1.8V ± 0.15V	1.43		ns	
					Falling		1.46			
					Rising	3.3V ± 0.3V	1.43			
					Falling		1.46			
					Rising	5V ± 0.5V	1.43			
					Falling		1.46			
Counter/Delay										

over operating free-air temperature range (unless otherwise noted)

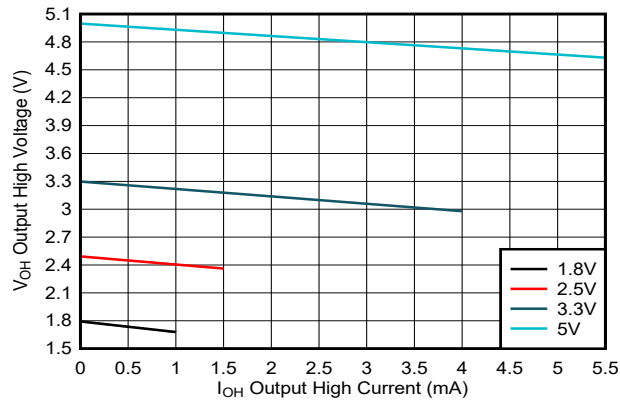
PARAMETER			FROM (INPUT)	TO (OUTPUT)	TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
t <sub>pd</sub>	Delay	Counter - Delay mode	Rising edge of IN	Rising edge of OUT	Falling edge triggered	1.8V ± 0.15V	2.61		ns	
			Falling edge of IN	Falling edge of OUT	Rising edge triggered		2.59			
			Rising edge of IN	Rising edge of OUT	Falling edge triggered	3.3V ± 0.3V	2.61			
			Falling edge of IN	Falling edge of OUT	Rising edge triggered		2.59			
			Rising edge of IN	Rising edge of OUT	Falling edge triggered	5V ± 0.5V	2.61			
			Falling edge of IN	Falling edge of OUT	Rising edge triggered		2.59			
Oscillator										
f <sub>err</sub>	Oscillator frequency error			OSC025 kHz	1.8V ± 0.15V	-5	5	%		
					3.3V ± 0.3V	-5	5			
					5V ± 0.5V	-5	5			
				OSC0 2MHz	1.8V ± 0.15V	-5	5	%		
					3.3V ± 0.3V	-5	5			
					5V ± 0.5V	-5	5			
t <sub>d_osc</sub>	Oscillator startup delay			OSC025 kHz	1.8V ± 0.15V	14.3		μs		
					3.3V ± 0.3V	14.2				
					5V ± 0.5V	14.1				
				OSC0 2MHz	1.8V ± 0.15V	6.24		μs		
					3.3V ± 0.3V	6.43				
					5V ± 0.5V	6.64				
t <sub>set_osc</sub>	Oscillator startup settling time			OSC025 kHz	1.8V ± 0.15V	1		μs		
					3.3V ± 0.3V	1				
					5V ± 0.5V	1				
				OSC0 2MHz	1.8V ± 0.15V	7		μs		
					3.3V ± 0.3V	7				
					5V ± 0.5V	7				
t <sub>d_err</sub>	Delay error			OSC (Forced power on)	1.71V to 5.5V	0	1	CLK cycle		
Programmable Filter										
t <sub>pflt_pw</sub>	Pulse width	Programmable filter - Edge detect mode	Rising edge of OUT	Falling edge of OUT	1 cell	1.8V ± 0.15V	138.0		ns	
						3.3V ± 0.3V	141.3			
						5V ± 0.5V	141.7			
					2 cells	1.8V ± 0.15V	232.6		ns	
						3.3V ± 0.3V	236.0			
						5V ± 0.5V	236.5			
					3 cells	1.8V ± 0.15V	326.8		ns	
						3.3V ± 0.3V	330.5			
						5V ± 0.5V	330.9			
					4 cells	1.8V ± 0.15V	420.9		ns	
						3.3V ± 0.3V	424.7			
						5V ± 0.5V	425.0			

over operating free-air temperature range (unless otherwise noted)

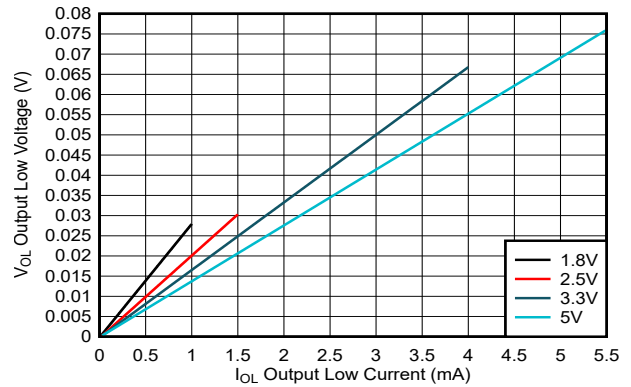
PARAMETER			FROM (INPUT)	TO (OUTPUT)	TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
t <sub>pflt_pd</sub>	Delay	Programmable filter - Edge detect mode			Any cells	1.8V ± 0.15V		24.7		ns
						3.3V ± 0.3V		21.8		
						5V ± 0.5V		21.6		
t <sub>pflt_d</sub>	Delay	Programmable filter - Both edge delay mode	Rising/Falling edge of IN	Rising/Falling edge of OUT	1 cell	1.8V ± 0.15V		208.4		ns
						3.3V ± 0.3V		191.5		
						5V ± 0.5V		186.9		
					2 cells	1.8V ± 0.15V		303.3		ns
						3.3V ± 0.3V		286.3		
						5V ± 0.5V		281.5		
					3 cells	1.8V ± 0.15V		397.7		ns
						3.3V ± 0.3V		380.6		
						5V ± 0.5V		375.9		
					4 cells	1.8V ± 0.15V		491.9		ns
						3.3V ± 0.3V		474.6		
						5V ± 0.5V		469.8		

## 5.8 Typical Characteristics

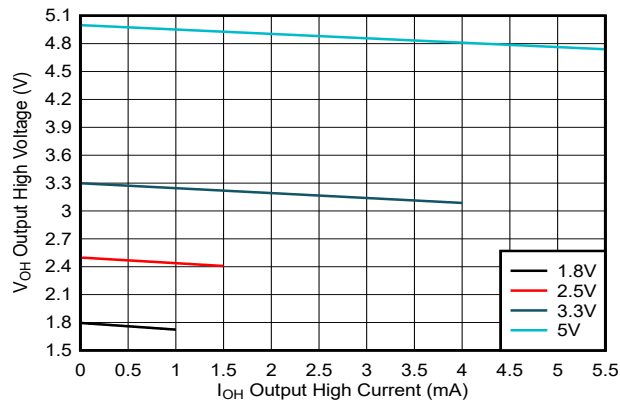
$T_A = 25^\circ\text{C}$



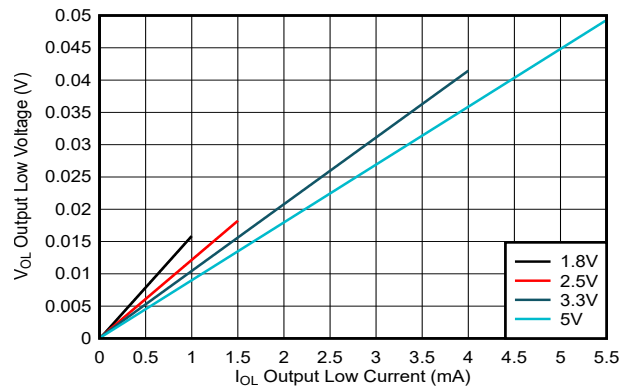
**Figure 5-1. Typical 1X Push-Pull Output Voltage in the High State ( $V_{OH}$ )**



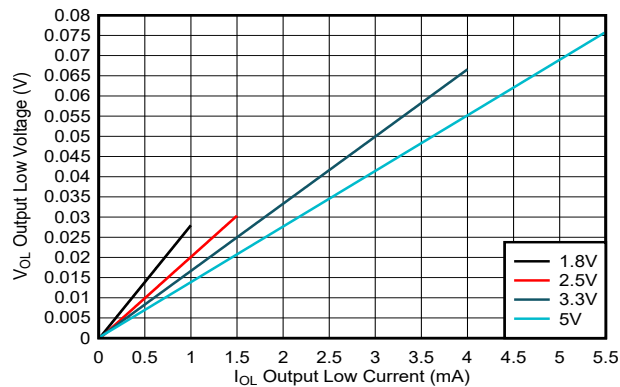
**Figure 5-2. Typical 1X Push-Pull Output Voltage in the Low State ( $V_{OL}$ )**



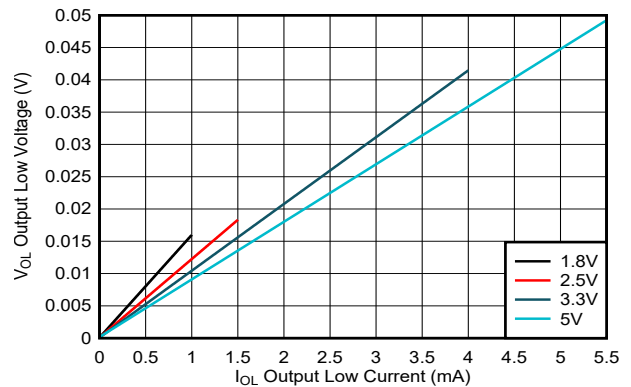
**Figure 5-3. Typical 2X Push-Pull Output Voltage in the High State ( $V_{OH}$ )**



**Figure 5-4. Typical 2X Push-Pull Output Voltage in the Low State ( $V_{OL}$ )**



**Figure 5-5. Typical 1X Open-Drain NMOS Output Voltage in the Low State ( $V_{OL}$ )**



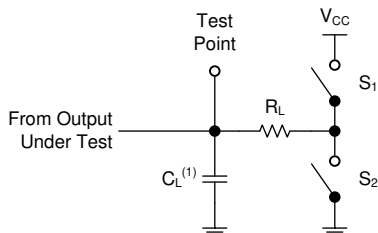
**Figure 5-6. Typical 2X Open-Drain NMOS Output Voltage in the Low State ( $V_{OL}$ )**

## 6 Parameter Measurement Information

Phase relationships between waveforms were chosen arbitrarily. All input pulses are supplied by generators having the following characteristics:  $PRR \leq 1\text{MHz}$ ,  $Z_O = 50\Omega$ ,  $t_f < 2.5\text{ns}$ .

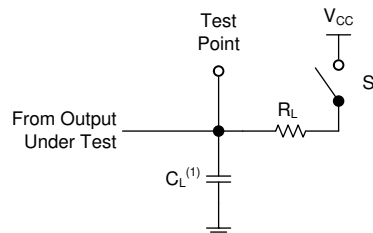
For clock inputs,  $f_{\text{max}}$  is measured when the input duty cycle is 50%.

The outputs are measured one at a time with one input transition per measurement.



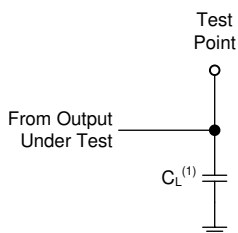
(1)  $C_L$  includes probe and test-fixture capacitance.

**Figure 6-1. Load Circuit for 3-State Outputs**



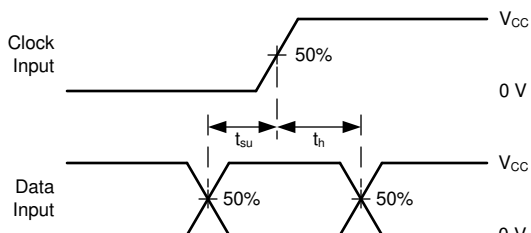
(1)  $C_L$  includes probe and test-fixture capacitance.

**Figure 6-2. Load Circuit for Open-Drain Outputs**

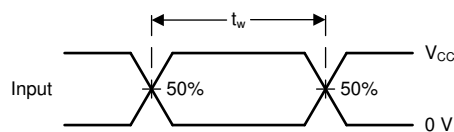


(1)  $C_L$  includes probe and test-fixture capacitance.

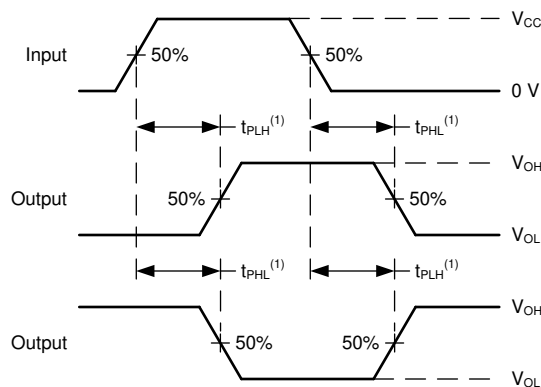
**Figure 6-3. Load Circuit for Push-Pull Outputs**



**Figure 6-5. Voltage Waveforms, Setup and Hold Times**

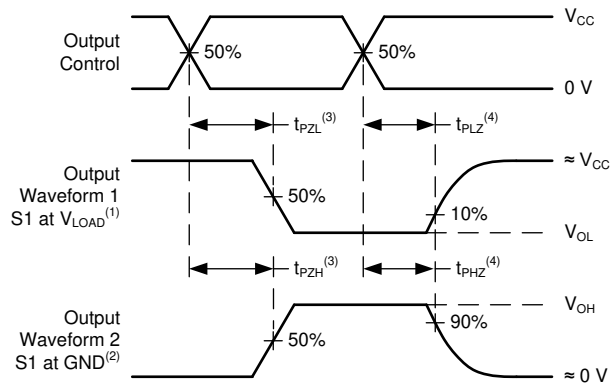


**Figure 6-4. Voltage Waveforms, Pulse Duration**

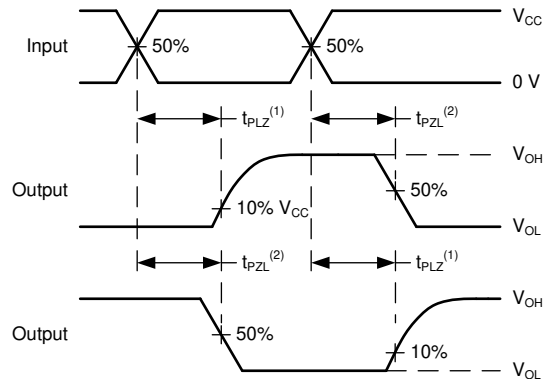


(1) The greater between  $t_{PLH}$  and  $t_{PHL}$  is the same as  $t_{pd}$ .

**Figure 6-6. Voltage Waveforms Propagation Delays**

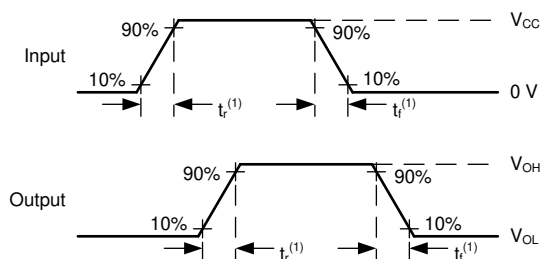


**Figure 6-7. Voltage Waveforms Propagation Delays**



(1) The greater between  $t_{PLZ}$  and  $t_{PLH}$  is the same as  $t_{pd}$ .

**Figure 6-8. Voltage Waveforms Propagation Delays**



(1) The greater between  $t_r$  and  $t_f$  is the same as  $t_t$ .

**Figure 6-9. Voltage Waveforms, Input and Output Transition Times**

## 7 Detailed Description

### 7.1 Overview

The TPLD801 is part of the TI programmable logic device (TPLD) family of devices that feature versatile programmable logic ICs with combinational logic, sequential logic, and analog blocks to provide an integrated, compact, low power solution to implement common system functions.

The TPLD801 has one GPI and five GPIOs that can be configured as a digital input, digital output, or digital input/output.

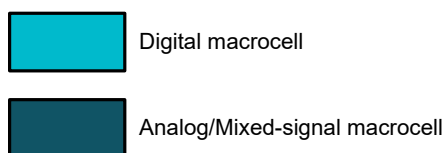
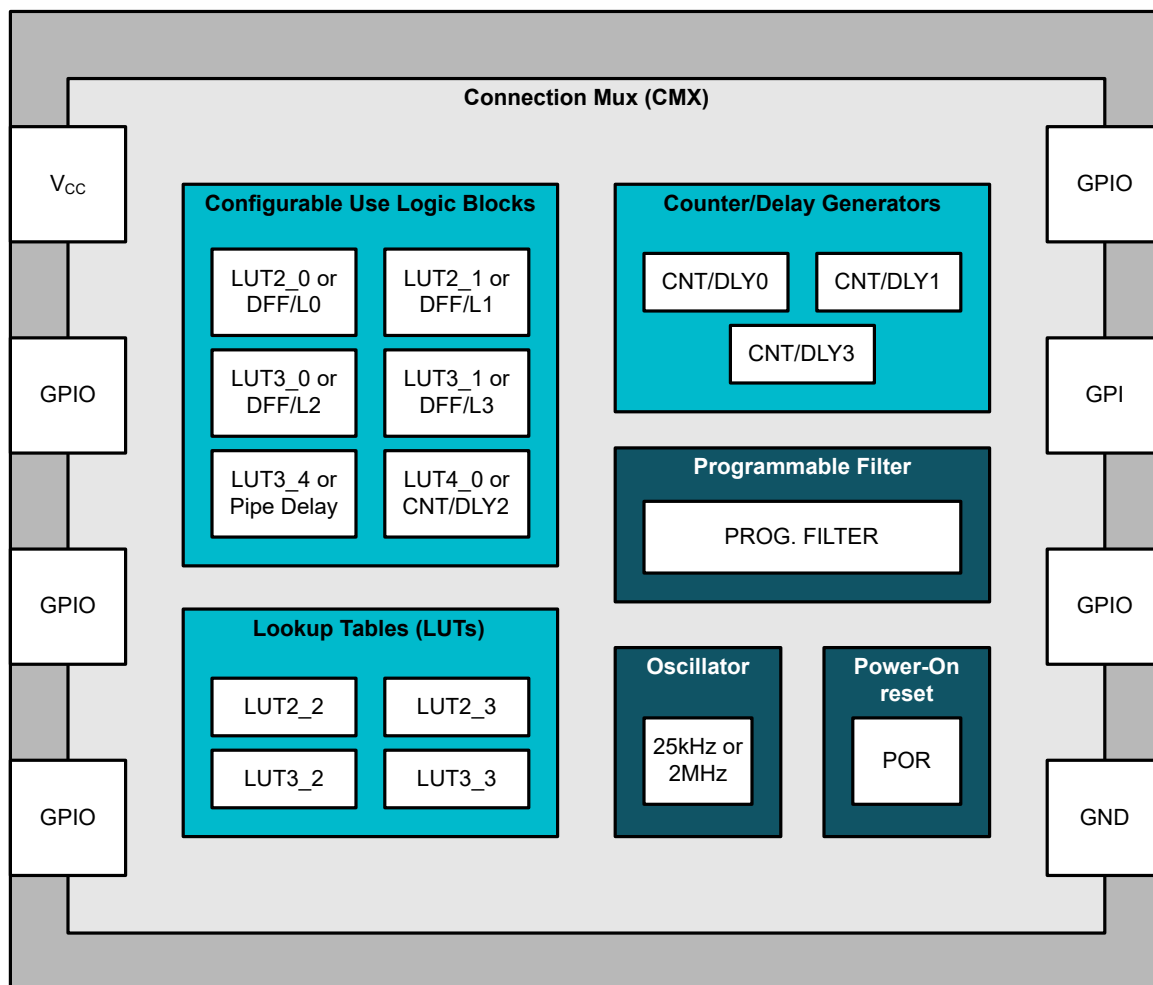
The TPLD801 has a system of interconnects, further referred to as the connection mux, to configure the routing of internal macro-cells and I/O pins. Each connection mux input is hardwired to a specific digital macro-cell output, such as digital I/O and look-up tables. The connection mux allows each of the digital inputs to only connect to one output so that bus contention does not occur.

The TPLD801 features the following macro-cells:

- Configurable use logic blocks
  - Two 2-bit look-up tables (LUT)
  - Two 3-bit LUTs
  - Two 2-bit LUTs or D-type flip-flops (DFF)/latches
  - Two 3-bit LUTs or DFF/latches with reset/set option
  - One 3-bit LUT or pipe delay
  - One 4-bit LUT or 8-bit counter (CNT) or delay generator (DLY)
- Three 8-bit CNT/DLY
- One programmable deglitch filter (PFLT) or edge detector (EDET)
- One oscillator (OSC) to generate either a 25kHz or 2MHz clock

The InterConnect Studio software environment enables a simple drag-and-drop interface to build custom circuit designs and configure the macro-cells, I/O pins, and interconnections. In addition to circuit creation, InterConnect Studio has the ability to simulate digital and analog functionality to verify designs and provide a typical power consumption estimate. Once circuit designs are finalized, InterConnect Studio can temporarily emulate the design in the non-volatile memory or permanently program the one-time programmable (OTP). The OTP can be locked to prevent readback of its contents.

## 7.2 Functional Block Diagram



**Figure 7-1. TPLD801 Functional Block Diagram**

## 7.3 Feature Description

### 7.3.1 I/O Pins

TPLD801 has one input and five multifunction I/O pins. GPIO pins can function as either a user defined input, output, or a special function.

#### 7.3.1.1 Input Modes

The following options are available when configuring pins as an input:

- Digital input without Schmitt-trigger
- Digital input with Schmitt-trigger
- Low-voltage digital input

The low-voltage digital input has lower  $V_{IH}/V_{IL}$  specifications than the digital input without Schmitt trigger. This allows for up-translation from any voltage domain lower than  $V_{CC}$  that meets the low-voltage digital input  $V_{IH}$  and  $V_{IL}$  specifications. The following pins also have the option to serve a special function:

- IO1: external clock input

#### 7.3.1.2 Output Modes

The following options are available with programmable drive strengths when configuring pins as an output:

- Push-pull output
- Open-drain NMOS output
- Open-drain PMOS output

#### 7.3.1.3 Pull-Up or Pull-Down Resistors

All I/O pins have the option of user-selectable resistors that can be connected to the pin structure. The selectable values on these resistors are 10k $\Omega$ , 100k $\Omega$  and 1M $\Omega$ . The internal resistors can be configured as either pull-up or pull-down. When designing in InterConnect Studio, any pin left unused in a design are configured with a 1M $\Omega$  pull-down by default. Furthermore, following a power-on event, all ports are in a Hi-Z state until the power-on reset sequence has completed.

**Table 7-1. Pin Configuration Options**

GPIO	IO selection	OE	IO options	Resistor	Resistor value ( $\Omega$ )
IN0	PIN not used	—	—	Pull-Down	1M
	Digital input	0	Digital in without Schmitt trigger	Floating	—
			Digital in with Schmitt trigger	Pull-Down	10k
			Low-voltage digital input		100k
					1M

NOTE: GPI/IN0 also has the option to reset the device while powered on. Unlike POR, External Reset will only reset the internal logic and routing, inputs, and outputs. The NVM retains its previous state. If GPI Reset is enabled, ensure the input mode is set to Digital Input without Schmitt trigger.

Users may select whether the External Reset is *Disabled*, *Level sensitive*, or *Edge triggered*.

When *Level sensitive* is selected, if the input is High, then the device is in reset mode where all internal devices are reset. When this pin goes Low, then the device will begin the reset power on sequence.

When *Edge triggered* is selected, the edge detector can be configured to Rising edge or Falling edge, and an edge on GPI/IN0 resets the device and begins the reset power on sequence.

**Table 7-1. Pin Configuration Options (continued)**

GPIO	IO selection	OE	IO options	Resistor	Resistor value ( $\Omega$ )
IO1, IO2, IO4, IO5	Pin not used	—	—	Pull Down	1M
	Digital input	0	Digital in without Schmitt trigger Digital in with Schmitt trigger Low-voltage digital input	Floating	—
				Pull-Up	10k
					100k
					1M
				Pull-Down	10k
					100k
					1M
	Digital output	1	Push-pull (1X, 2X)	Floating	—
			Open-drain NMOS (1X, 2X) Open-drain PMOS (1X, 2X)	Floating	—
				Pull-Up	10k
					100k
					1M
				Pull-Down	10k
					100k
					1M
	Digital input/output	1	Open-drain NMOS (1X, 2X)	Floating	—
				Pull-Up	10k
					100k
					1M
				Pull-Down	10k
					100k
					1M

**Table 7-1. Pin Configuration Options (continued)**

GPIO	IO selection	OE	IO options	Resistor	Resistor value ( $\Omega$ )
IO3	Pin not used	—	—	Pull-Down	1M
	Digital input	0	Digital in without Schmitt trigger Digital in with Schmitt trigger Low-voltage digital input	Floating	—
				Pull-Up	10k
					100k
					1M
				Pull-Down	10k
					100k
					1M
	Digital output	1/0	Push-pull (1X, 2X)	Floating	—
			Open-drain NMOS (1X, 2X) 3-state output (1X, 2X)	Floating	—
				Pull-Up	10k
					100k
					1M
				Pull-Down	10k
					100k
					1M
	Digital input/output	0	Digital in without Schmitt trigger Digital in with Schmitt trigger Low-voltage digital input)	Floating	—
				Pull-Up	10k
					100k
					1M
				Pull-Down	10k
					100k
					1M
		1	Push-pull (1X, 2X) Open-drain NMOS (1X, 2X)	Shared with above	

### 7.3.2 Connection Mux

The TPLD801 has a system of interconnects, referred to as the connection mux, to configure the routing of internal macro-cells and I/O pins. The connection mux has 32 inputs and 44 outputs. Each of the 32 inputs of the connection mux is hardwired to particular macro-cells, including I/O pins, LUTs, analog comparators, other digital resources, VCC, and GND. The input to a digital macro-cell uses a 5-bit register to select one of these 32 input lines.

### 7.3.3 Configurable Use Logic Blocks

Combinational logic is supported via lookup tables (LUTs) within the TPLD801 including two 2-bit LUTs and two 3-bit LUTs. Inputs and outputs for the combination function macro-cells are configured from the connection mux with specific logic functions being defined by the state of OTP bits.

The TPLD801 has seven combinational function blocks (macro-cells) that can serve more than one logic or timing function. In each case, they can serve as a Lookup Table (LUT), or as another logic or timing function. See the list below for the functions that can be implemented in these logic blocks:

- Two 2-bit LUTs
- Two 3-bit LUTs
- Two 2-bit LUTs or D-type flip-flops/latches
- Two 3-bit LUTs or D-type flip-flops/latches with reset/set option
- One 3-bit LUT or Pipe delay
- One 4-bit LUT or 8-bit Counter/delay generator

#### 7.3.3.1 2-Bit LUT macro-cell

When used to implement LUT functions, the 2-bit LUT takes in two input signals from the connection mux and produces a single output, which goes back into the connection mux.

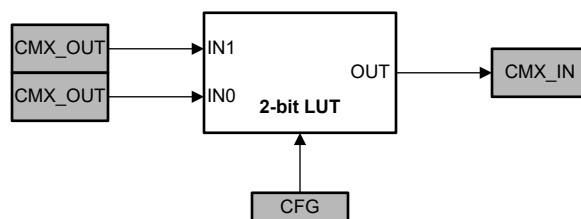


Figure 7-2. 2-bit LUT Block Diagram

These LUTs can be configured to any 2-input user defined function, including the following standard digital logic functions: AND, NAND, OR, NOR, XOR, XNOR, INV.

Table 7-2 shows the truth table for a 2-bit LUT.

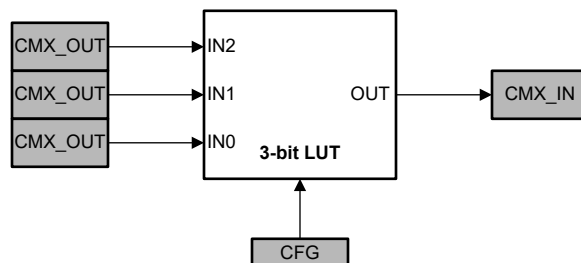
Table 7-2. 2-bit LUT Truth Table

IN1	IN0	OUT
0	0	User defined
0	1	
1	0	
1	1	

Each 2-bit LUT has 4 bits in the OTP to define their output function.

### 7.3.3.2 3-Bit LUT Macro-Cell

When used to implement LUT functions, the 3-bit LUT takes in three input signals from the connection mux and produces a single output, which goes back into the connection mux.



**Figure 7-3. 3-bit LUT Block Diagram**

These LUTs can be configured to any 3-input user defined function, including the following standard digital logic functions: AND, NAND, OR, NOR, XOR, XNOR, INV.

Table 7-3 shows the truth tables for a 3-bit LUT.

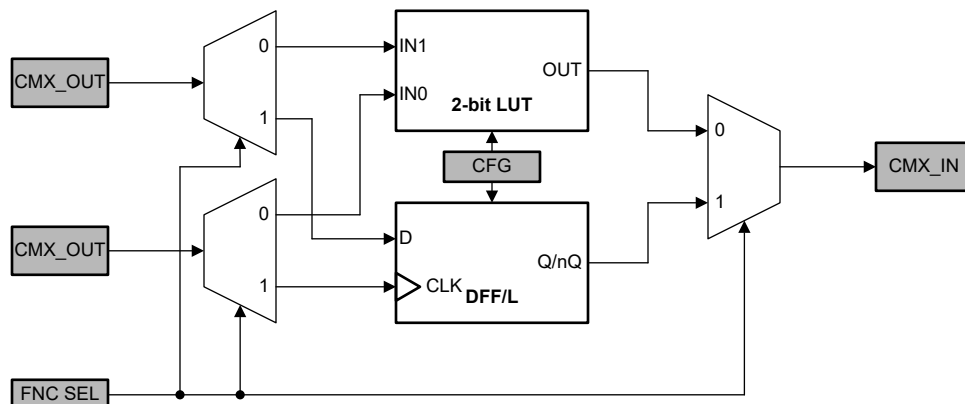
**Table 7-3. 3-bit LUT Truth Table**

IN2	IN1	IN0	OUT
0	0	0	User defined
0	0	1	
0	1	0	
0	1	1	
1	0	0	
1	0	1	
1	1	0	
1	1	1	

Each 3-bit LUT has 8 bits in the OTP to define their output function.

### 7.3.3.3 2-Bit LUT or D Flip-Flop/Latch Macro-Cell

This configurable use logic block can serve as either a 2-bit LUT, or as a D flip-flop or latch.



**Figure 7-4. 2-bit LUT or DFF/Latch Block Diagram**

When used to implement LUT functions, the 2-bit LUT takes in two input signals from the connection mux and produces a single output, which goes back into the connection mux. These LUTs can be configured to any 2-input user defined function, including the following standard digital logic functions: AND, NAND, OR, NOR, XOR, XNOR, INV.

Table 7-4 shows the truth table for a 2-bit LUT.

**Table 7-4. 2-bit LUT Truth Table**

IN1	IN0	OUT
0	0	User defined
0	1	
1	0	
1	1	

Each 2-bit LUT has 4 bits in the OTP to define their output function.

When used to implement a sequential logic element, the two input signals from the connection mux go to the data (D) and clock (CLK) inputs of the flip-flop or latch, with the output going back to the connection mux. This macro-cell has initial state parameters, as well as clock and output polarity parameters.

The operation of the D flip-flop/latch will follow the functional descriptions below:

- The clock polarity is configurable and can be set to non-inverted (CLKPOL = 0, CLK) or inverted (CLKPOL = 1, nCLK).
  - DFF with CLK: CLK is rising edge triggered, then  $Q = D$ ; otherwise  $Q$  will not change.
  - DFF with nCLK: CLK is falling edge triggered, then  $Q = D$ ; otherwise  $Q$  will not change.
  - Latch with CLK: when CLK is Low, then  $Q = D$ ; otherwise  $Q$  remains its previous value (input  $D$  has no effect on the output, when CLK is High).
  - Latch with nCLK: when CLK is High, then  $Q = D$ ; otherwise  $Q$  remains its previous value (input  $D$  has no effect on the output, when CLK is Low).
- The output polarity is configurable and can be set to non-inverted ( $Q$ ) or inverted ( $nQ$ ).

Table 7-5 and Table 7-6 show the truth tables for the D flip-flop and D latch, respectively.

**Table 7-5. D Flip-Flop Truth Table**

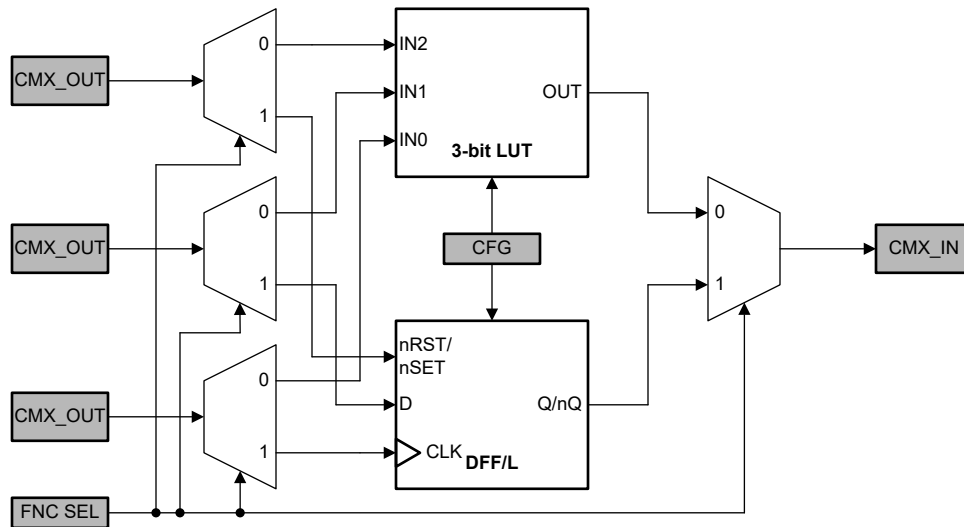
CLKPOL	CLK	D	Q	nQ
0	↓	0	$Q_0$	$nQ_0$
	↑	0	0	1
	↓	1	$Q_0$	$nQ_0$
	↑	1	1	0
1	↓	0	0	1
	↑	0	$Q_0$	$nQ_0$
	↓	1	1	0
	↑	1	$Q_0$	$nQ_0$

**Table 7-6. D Latch Truth Table**

CLKPOL	CLK	D	Q	nQ
0	0	0	0	1
	1	0	$Q_0$	$nQ_0$
	0	1	1	0
	1	1	$Q_0$	$nQ_0$
1	0	0	$Q_0$	$nQ_0$
	1	0	0	1
	0	1	$Q_0$	$nQ_0$
	1	1	1	0

### 7.3.3.4 3-Bit LUT or D Flip-Flop/Latch with Set/Reset Macro-Cell

This configurable use logic blocks can serve as either a 3-bit LUT, or as a D flip-flop or latch with a reset or set.



**Figure 7-5. 3-bit LUT or DFF/Latch with nRST/nSET Block Diagram**

When used to implement LUT functions, the 3-bit LUT takes in three input signals from the connection mux and produces a single output, which goes back into the connection mux. These LUTs can be configured to any 3-input user defined function, including the following standard digital logic functions: AND, NAND, OR, NOR, XOR, XNOR, INV.

Table 7-7 shows the truth table for a 3-bit LUT.

**Table 7-7. 3-bit LUT Truth Table**

IN2	IN1	IN0	OUT
0	0	0	User defined
0	0	1	
0	1	0	
0	1	1	
1	0	0	
1	0	1	
1	1	0	
1	1	1	

Each 3-bit LUT has 8 bits in the OTP to define their output function.

When used to implement a sequential logic element, the three input signals from the connection mux go to the data (D), clock (CLK), and reset/set (nRST/nSET) inputs for the flip-flop or latch, with the output going back to the connection mux. This macro-cell has initial state, clock polarity, reset/set polarity, and output polarity parameters.

The operation of the D flip-flop/latch will follow the function descriptions below:

- The clock polarity is configurable and can be set to non-inverted (CLKPOL = 0, CLK) or inverted (CLKPOL = 1, nCLK).
  - DFF with CLK: CLK is rising edge triggered, then  $Q = D$ ; otherwise  $Q$  will not change.
  - DFF with nCLK: CLK is falling edge triggered, then  $Q = D$ ; otherwise  $Q$  will not change.
  - Latch with CLK: when CLK is Low, then  $Q = D$ ; otherwise  $Q$  remains its previous value (input  $D$  has no effect on the output, when CLK is High).
  - Latch with nCLK: when CLK is High, then  $Q = D$ ; otherwise  $Q$  remains its previous value (input  $D$  has no effect on the output, when CLK is Low).
- These DFF/latches have an option for an active-low reset or set.
  - nRST: when the input is high, the DFF/latch is in normal operation; and when low,  $Q$  is reset to 0.
  - nSET: when the input is high, the DFF/latch is in normal operation; and when low,  $Q$  is set to 1.
- If reset/set is not desired, users may tie this input to  $V_{CC}$  or another constant high source.
- The output polarity is configurable and can be set to non-inverted ( $Q$ ) or inverted ( $nQ$ ).

Table 7-8 and Table 7-9 show the truth tables for the D flip-flop and D latch with reset/set, respectively.

**Table 7-8. D Flip-Flop with nRST/nSET Truth Table**

nRST	nSET	CLKPOL	CLK	D	Q	nQ
0	—	0	X	X	0	1
—	0		X	X	1	0
1	1		↓	0	Q <sub>0</sub>	nQ <sub>0</sub>
			↑	0	0	1
			↓	1	Q <sub>0</sub>	nQ <sub>0</sub>
			↑	1	1	0
0	—	1	X	X	0	1
—	0		X	X	1	0
1	1		↓	0	0	1
			↑	0	Q <sub>0</sub>	nQ <sub>0</sub>
			↓	1	1	0
			↑	1	Q <sub>0</sub>	nQ <sub>0</sub>

**Table 7-9. D Latch with nRST/nSET Truth Table**

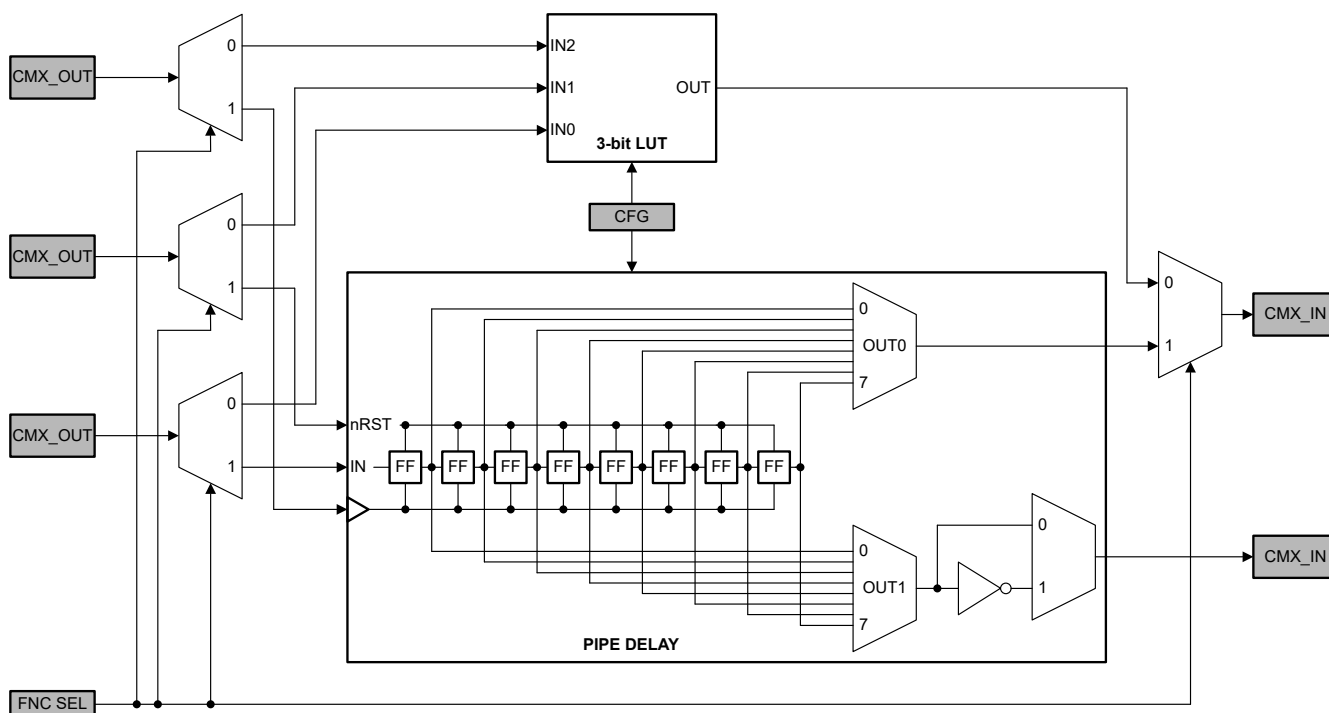
nRST	nSET	CLKPOL	CLK	D	Q	nQ
0	—	0	X	X	0	1
—	0		X	X	1	0
1	1		0	0	0	1
			1	0	Q <sub>0</sub>	nQ <sub>0</sub>
			0	1	1	0
			1	1	Q <sub>0</sub>	nQ <sub>0</sub>

**Table 7-9. D Latch with nRST/nSET Truth Table (continued)**

nRST	nSET	CLKPOL	CLK	D	Q	nQ
0	—	1	X	X	0	1
—	0		X	X	1	0
1	1		0	0	Q <sub>0</sub>	nQ <sub>0</sub>
			1	0	0	1
			0	1	Q <sub>0</sub>	nQ <sub>0</sub>
			1	1	1	0

### 7.3.3.5 3-Bit LUT or Pipe Delay Macro-Cell

This macro-cell can serve as either a 3-bit LUT or as a pipe delay.



**Figure 7-6. 3-bit LUT or Pipe delay block diagram**

When used to implement LUT functions, the 3-bit LUT takes in three input signals from the connection mux and produces a single output, which goes back into the connection mux. These LUTs can be configured to any 3-input user defined function, including the following standard digital logic functions: AND, NAND, OR, NOR, XOR, XNOR, INV.

Table 7-10 shows the truth table for a 3-bit LUT.

**Table 7-10. 3-bit LUT Truth Table**

IN2	IN1	IN0	OUT
0	0	0	User defined
0	0	1	
0	1	0	
0	1	1	
1	0	0	
1	0	1	
1	1	0	
1	1	1	

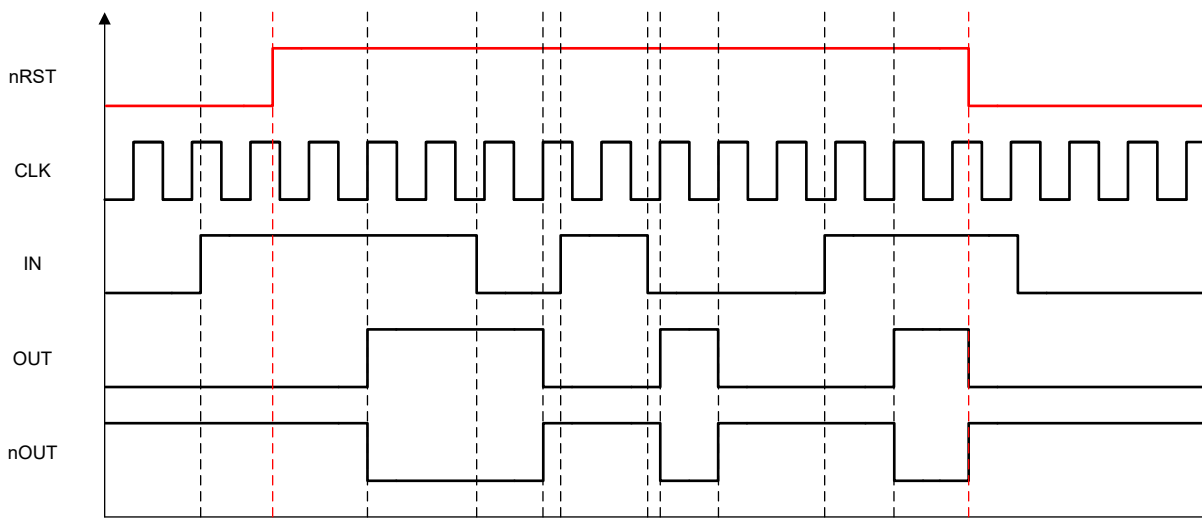
Each 3-bit LUT has 8 bits in the OTP to define their output function.

When used to implement a pipe delay, the three input signals from the connection mux go to the delay input (IN), clock (CLK), and reset (nRST) inputs for the flip-flop or latch, with two outputs going back to the connection mux. With this macro-cell, users can select the number of delay stages per output (from 1 to 8) and the output polarity for OUT1.

The pipe delay is an 8-stage delay composed of 8 DFFs. The DFF cells are tied in series where the output of each delay cell goes to the next DFF cell. There are delay output points for each set of the OUT0 and OUT1 outputs to a mux that is used to control the selection of the amount of delay for each pipe delay output.

For normal pipe delay functionality, the nRST input should be high. If nRST input is low, the pipe delay macro-cell is in a reset state and all outputs are low.

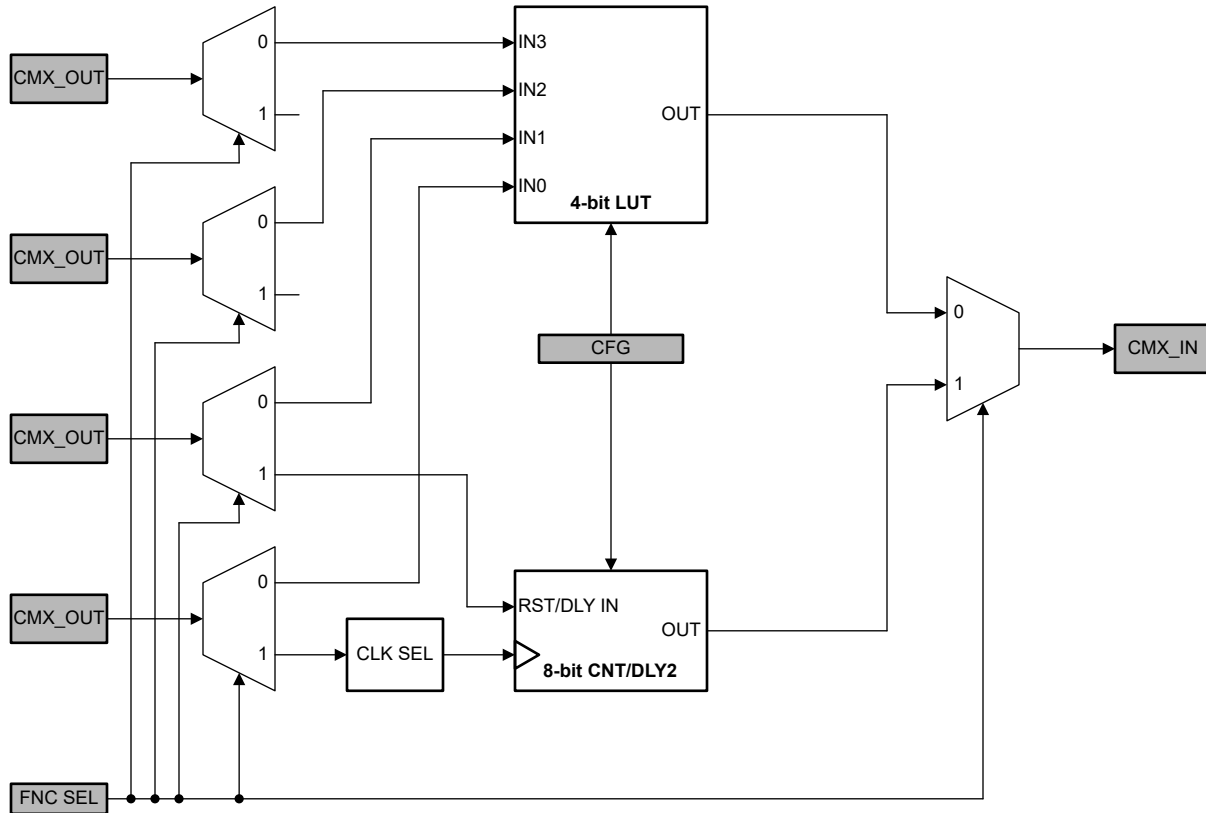
Figure 7-7 shows an example of the pipe delay macro-cell with 2 stages of delay selected.



**Figure 7-7. Pipe Delay Macro-Cell Timing Example (Delay = 2)**

### 7.3.3.6 4-Bit LUT or 8-Bit Counter/Delay Macro-Cell

This macro-cell can serve as either a 4-bit LUT or as a counter/delay generator (CNT/DLY).



**Figure 7-8. 4-bit LUT or 8-bit CNT/DLY Block Diagram**

When used to implement LUT functions, the 4-bit LUT takes in four input signals from the connection mux and produces a single output, which goes back into the connection mux. This LUT can be configured to any 4-input user defined function, including the following standard digital logic functions: AND, NAND, OR, NOR, XOR, XNOR, INV.

Table 7-11 shows the truth table for a 4-bit LUT.

**Table 7-11. 4-bit LUT Truth Table**

IN3	IN2	IN1	IN0	OUT
0	0	0	0	User defined
0	0	0	1	
0	0	1	0	
0	0	1	1	
0	1	0	0	
0	1	0	1	
0	1	1	0	
0	1	1	1	
1	0	0	0	
1	0	0	1	
1	0	1	0	
1	0	1	1	
1	1	0	0	
1	1	0	1	
1	1	1	0	
1	1	1	1	

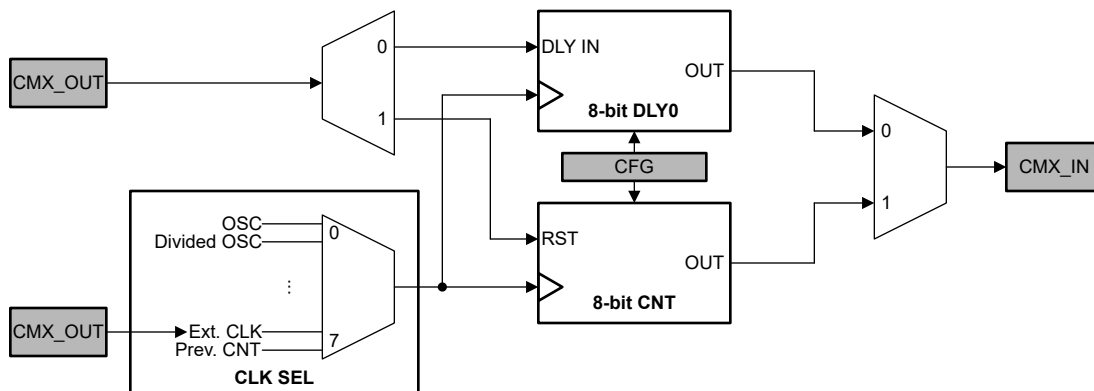
Each 4-bit LUT has 16 bits in the OTP to define their output function.

When used to implement 8-bit counter/delay function, the two input signals from the connection mux go to the clock (CLK) and reset (RST/DLY IN) for the counter/delay macro-cell, with the output going back to the connection mux. As a counter, the macro-cell counts to the given data value and generates a pulse when it reaches the set value or is reset. As a delay, it postpones rising and/or falling edges for the duration that is a function of the register value.

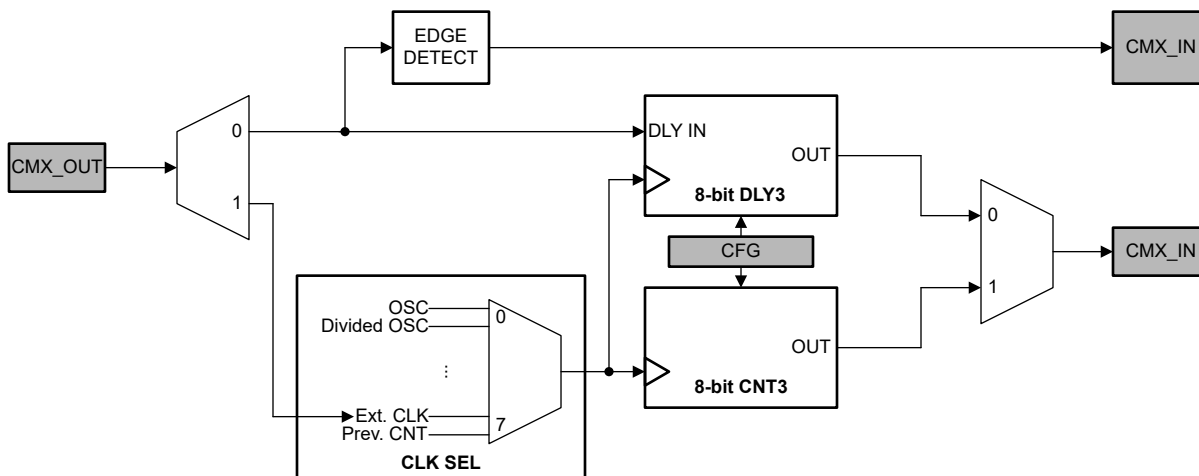
For more information on CNT/DLY macro-cell, see [Section 7.3.4](#).

### 7.3.4 8-Bit Counters and Delay Generators (CNT/DLY)

The counters/delay generators are 8-bit, supporting counter data values from 1 to 255. For flexibility, the clock source for each of these macro-cells can be configured as the internal oscillator, a divided clock derived from an oscillator (OSC/4, /12, /24, /64, /4096), or an external clock source coming from the connection mux. There is also the option to chain from the output of the previous CNT/DLY macro-cell to implement longer counter/delay circuits. Note that the counter/delay macro-cell is rising edge triggered, that is the counter will increment/decrement on rising clock edges.



**Figure 7-9. CNT/DLY Block Diagram**



**Figure 7-10. CNT/DLY3 Block Diagram**

As a counter/delay (CNT/DLY) macro-cell, users may select from the following modes: delay, counter.

CNT/DLY3, when in Delay mode, also has an optional edge detector that will generate a short pulse on the specified edge in addition to the delayed output.

### 7.3.4.1 Delay Mode

When configured as a Delay generator (DLY), this macro-cell delays the input based on counter DATA and CLK input frequency and postpones rising and/or falling edges. The initial output value of this macro-cell after device startup can also be configured to Bypass Initial, Initial Low, or Initial High. The edge on which to delay is selected by the Edge select parameter and can be configured as:

- Rising: only delay on rising edges of IN.
- Falling: only delay on falling edges of IN.
- Both: delay on both rising and falling edges of IN.

For delay applications, it is recommended to use larger counter data values for less error. If an input pulse width is shorter than the specified delay time, the pulse will be filtered out. This feature can be useful for deglitching.

If the on-chip oscillator is used, a delay error or offset is introduced depending on whether the OSC is set to "forced power on" or "auto power on". An additional 2 clock cycles are included in the delay calculation for clock synchronization with an option to bypass. Note, bypassing the clock synchronization may result in the counter resetting to an unknown value.

The delay time is calculated by  $DELAY = (DATA + (t_{d\_err} \text{ or } t_{d\_os}) + 3)/f_{CLK}$  or, if 2-DFF sync is bypassed,  $DELAY = (DATA + (t_{d\_err} \text{ or } t_{d\_os}) + 1)/f_{CLK}$ .

When the OSC is set to "auto power on" and DLY macro-cells are triggered subsequently before the previous output is present, the OSC will continue to clock and the DLY will begin on the next rising edge. Thus, the subsequent delays can be calculated as if the OSC were set to "forced power on".

Figure 7-11 shows an example of the Delay macro-cell operation set to both edge delay and data = 1.

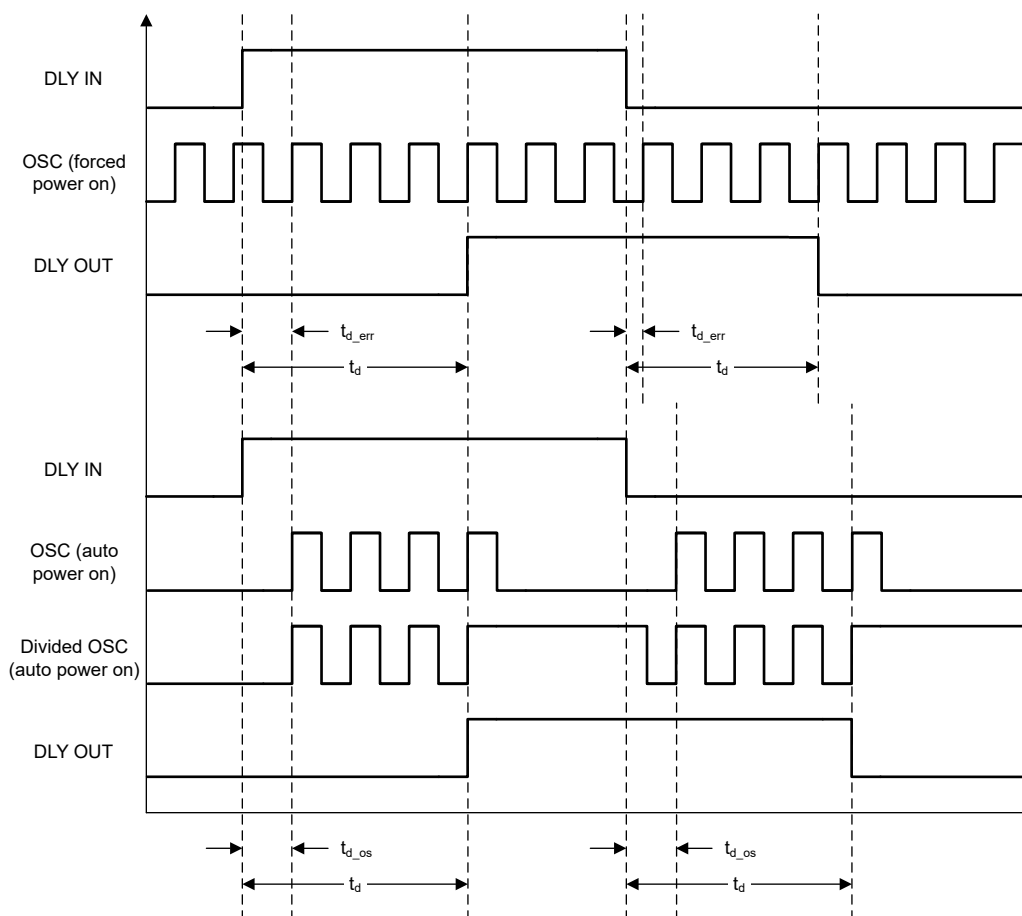
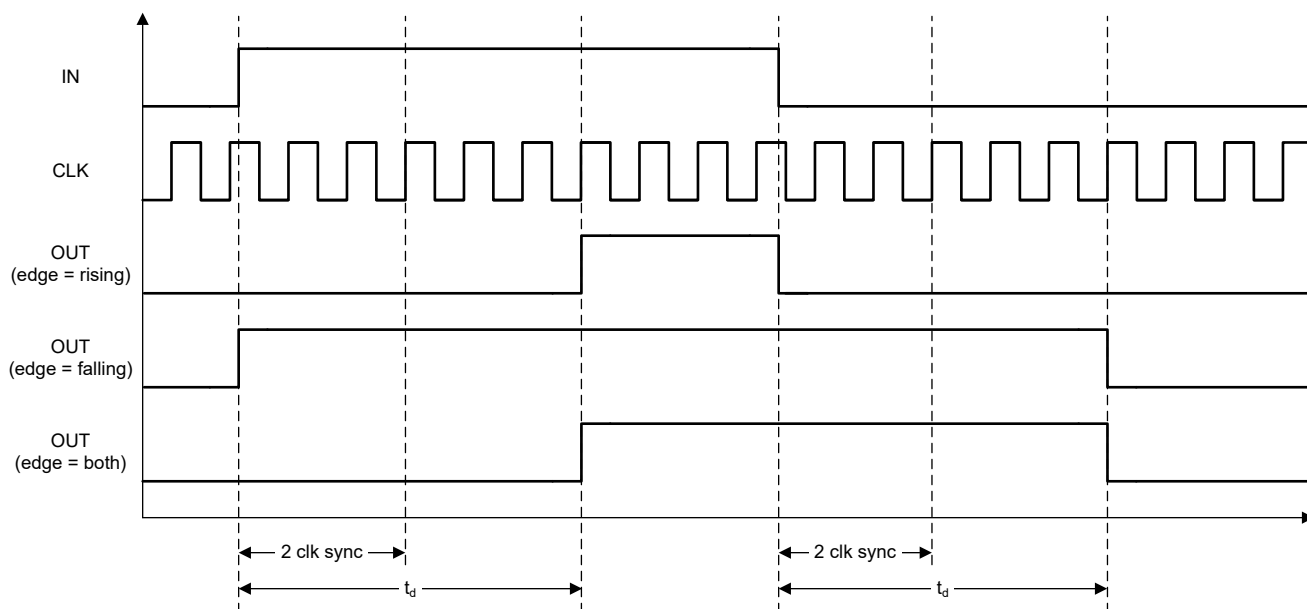


Figure 7-11. Delay Output Timing Example (Both Edge Delay and DATA = 1)

Figure 7-12 shows an example timing of Delay macro-cells with respect to the edge selected and data = 3.



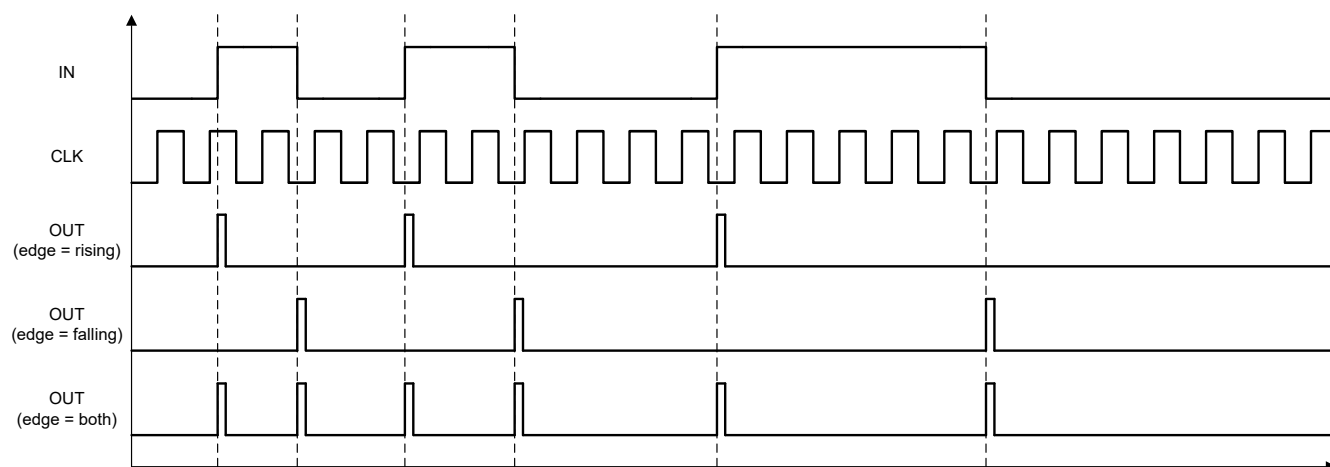
**Figure 7-12. Delay Output Timing Example (DATA = 3)**

#### 7.3.4.2 Edge Detector Mode

When CNT/DLY3 is configured as a Delay, this macro-cell has the option to generate a pulse of approximately 20ns width when a valid edge is detected. The edge on which the Edge detector generates a pulse is determined by the Edge select parameter and can be configured as:

- Rising: only rising edges of IN generate a pulse.
- Falling: only falling edges of IN generate a pulse.
- Both: both rising and falling edges of IN generate a pulse.

The image below shows an example of how the EDET option operates with respect to the Edge select parameter.



**Figure 7-13. Edge Detector Output Timing Example**

### 7.3.4.3 Reset Counter Mode

When configured as a Counter (CNT) and a valid edge appears on the IN input, this macro-cell resets the internal counter to 0 and begins counting down from DATA on the next rising clock edge. Then, the macro-cell outputs a pulse for the duration of one CLK period when the count reaches 0 and wrap around to the value in DATA. The counter will continually operate until another reset is received. The edge on which the Counter is reset is determined by the Edge select parameter and can be configured as:

- Rising: only rising edges of IN reset the counter.
- Falling: only falling edges of IN reset the counter.
- Both: both rising and falling edges of IN reset the counter.
- High Level Reset: the counter is reset to 0 whenever IN is High; after reset, the counter output stays Low until the next rising CLK edge, then operates normally.

The counter time is calculated by  $COUNT = (DATA + 1)/f_{CLK}$ . After a reset, an additional 2 clock cycles is added for clock synchronization with an option to bypass. Note, bypassing the clock synchronization may result in the counter resetting to an unknown value.

#### Note

Counters are initialized with DATA = 0 after POR.

Figure 7-14 and Figure 7-15 show examples of Counter output timing diagrams with respect to the Edge select parameter with DATA = 1 and DATA = 3, respectively.

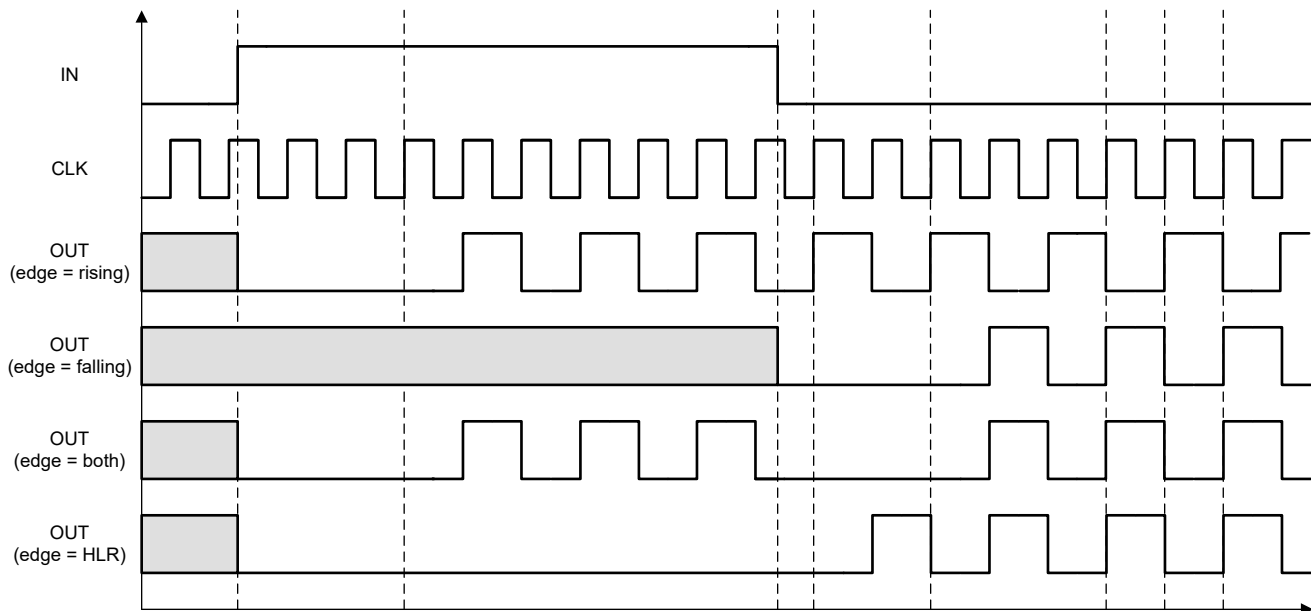
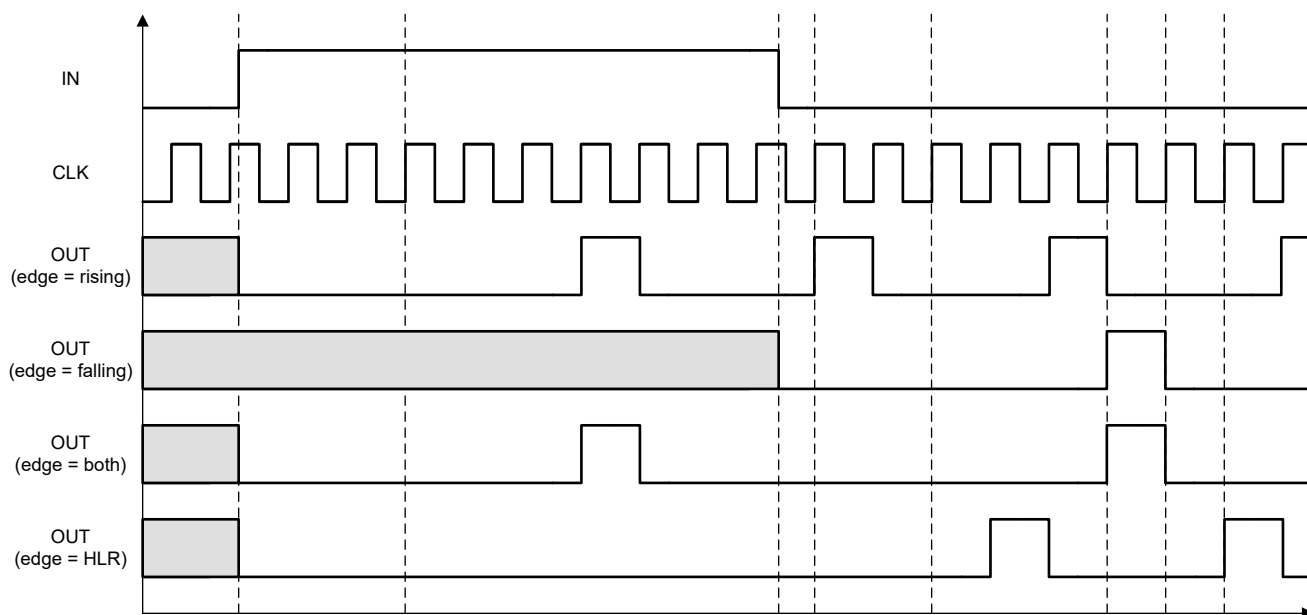
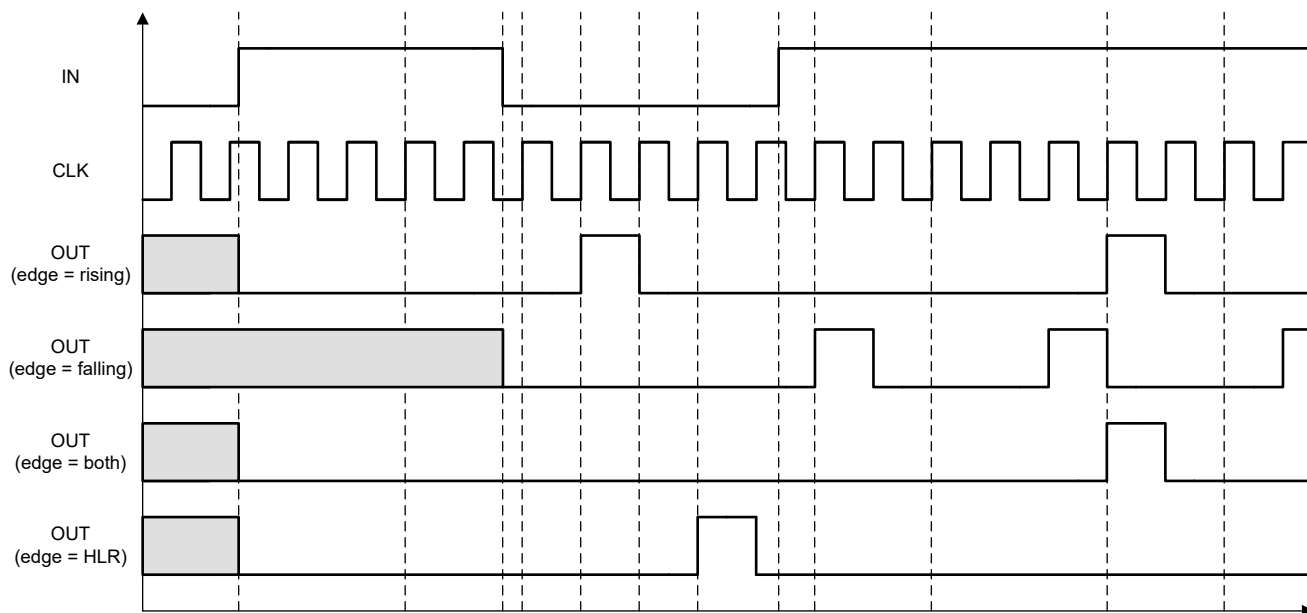


Figure 7-14. Counter Output Timing Example (DATA = 1)



**Figure 7-15. Counter Output Timing Example (DATA = 3)**

Figure 7-16 shows an example of how the Counter macro-cell operates when the IN signal is shorter than the counter length (shown when edge select parameter is set to "both").



**Figure 7-16. Counter Output Timing Example with RST < DATA (DATA = 3)**

### 7.3.5 Programmable Deglitch Filter or Edge Detector Macro-Cell

The TPLD801 has one macro-cell that can be configured as a programmable filter (PFLT) or edge detector (EDET). The PFLT macro-cell can be used to generate a delay ( $t_{pflt\_d}$ ) characterized by  $t_{pflt\_pw}$  and  $t_{pflt\_pd}$ .  $t_{pflt\_pw}$  can be set to 125ns, 250ns, 375ns, or 500ns and  $t_{pflt\_pd}$  is a fixed value. Furthermore, the output of the macro-cell can be configured to one of four options: rising edge detection, falling edge detection, both edge detection, or both edge delay. Lastly, the filter operates as a short low-pass filter and its output can be set as non-inverted or inverted.

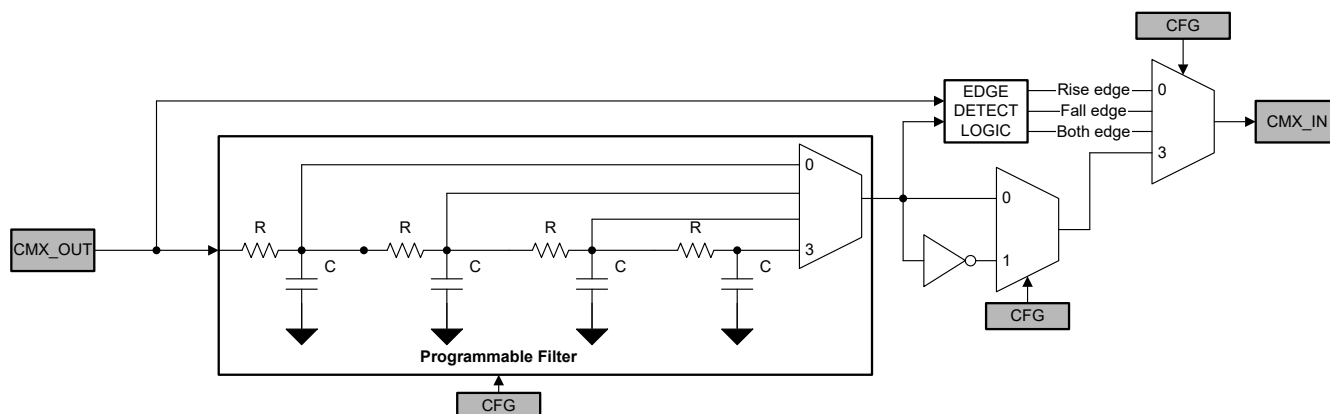


Figure 7-17. Programmable Filter and Edge Detector Block Diagram

#### Note

The input signal must be longer than  $t_{pflt\_d}$ , otherwise it will be filtered out.

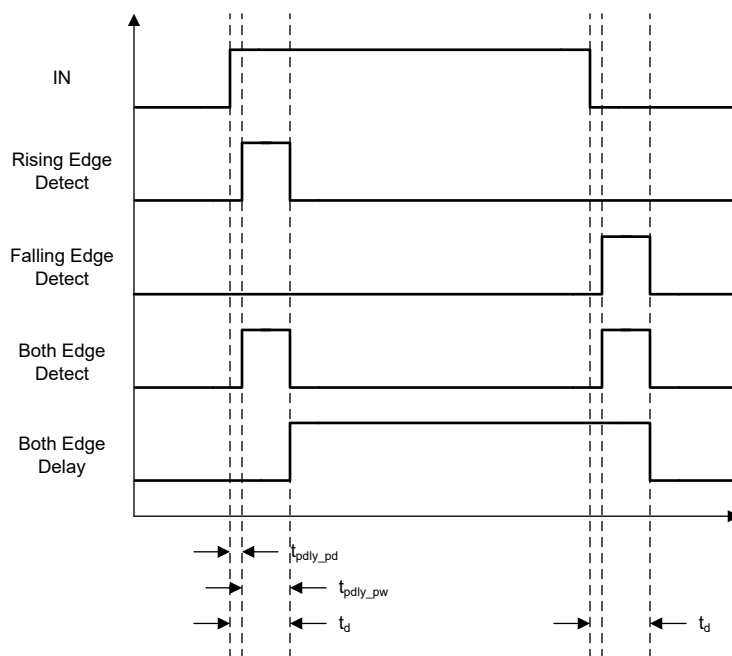
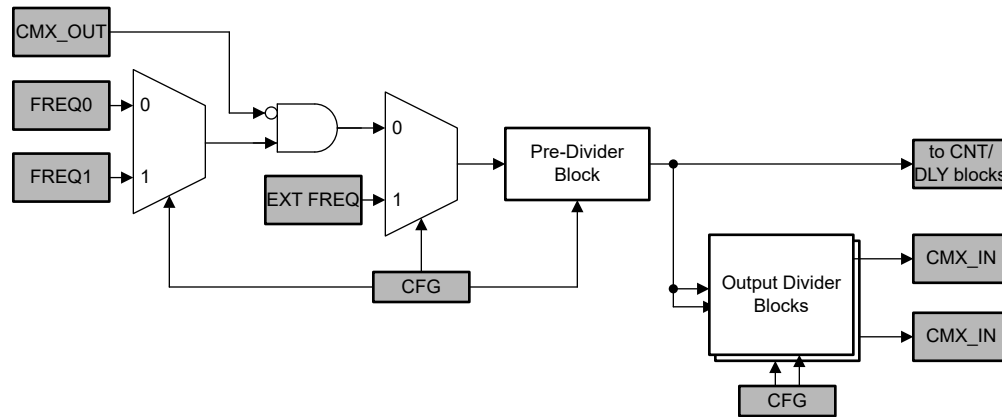


Figure 7-18. Programmable Filter and Edge Detector Output Timing Diagram Example

### 7.3.6 Selectable Frequency Oscillator

The TPLD801 has one internal oscillator, selectable to operate at 25kHz or at 2MHz. The user can select one of these operating frequencies for the OSC macro-cell, or the internal oscillator could be bypassed and the operating frequency can come from an external clock.



**Figure 7-19. Oscillator Block Diagram**

Following the operating clock input, there are two divider stages that allow users the flexibility of various clock frequencies for use throughout the device.

The first stage divider allows the selection of up to four options from the operating oscillator frequency as listed in [Oscillator Frequency Modes](#). The output of the first divider stage is routed directly to the counter/delay generator macro-cell CLK inputs, where a separate second divider stage is available.

The output of the first divider stage is also routed into a second divider stage within the oscillator macro-cell. The oscillator macro-cell has two separate second stage dividers, allowing for the output of two separate clocks (OUT0 and OUT1) into the connection mux. See [Oscillator Frequency Modes](#)

### 7.3.6.1 Oscillator Power Modes

When using the device's internal oscillator, there are two configuration settings available:

- Force power on: the internal oscillator will continuously run as long as the device is powered on.
- Auto power on: the internal oscillator will dynamically power on when any macro-cell requests the oscillator directly from the pre-divider block output and not through the connection mux, and then power off once the task is complete.
- External power on/off: the internal oscillator will be powered down when PDWN is asserted High. PDWN signal takes priority over the oscillator power modes. This is only applicable when the internal oscillator is selected and is bypassed when an external clock is used.

**Table 7-12. Frequency Options and Limits**

Frequency Option	MIN	TYP	MAX
FREQ0	23.75kHz	25kHz	26.25kHz
FREQ1	1.9MHz	2MHz	2.1MHz
EXT	-	-	-

**Table 7-13. Oscillator Pre-dividers**

Pre-Divider Option	Magnitude
P0	1
P1	2
P2	4
P3	8

**Table 7-14. Oscillator Output Dividers**

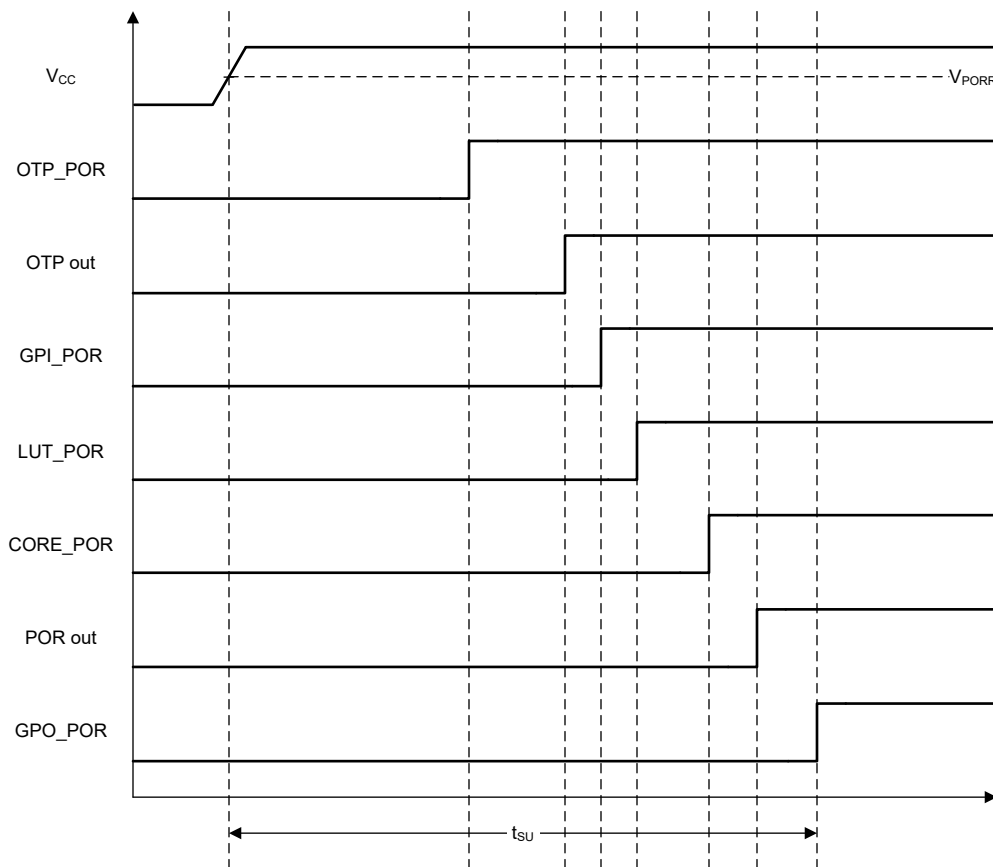
Output Divider Options	Magnitude
OD0	1
OD1	2
OD2	3
OD3	4
OD4	8
OD5	12
OD6	24
OD7	64

## 7.4 Device Functional Modes

### 7.4.1 Power-On Reset

The TPLD801 has a power-on reset (POR) macro-cell to ensure correct device initialization and operation of all macro-cells in the device. The purpose of the POR circuit is to have consistent behavior and predictable results when the  $V_{CC}$  power is first ramping to the device, and also while the  $V_{CC}$  is falling during power-down. To accomplish this goal, the POR drives a defined sequence of internal events that trigger changes to the states of different macro-cells inside the device, and finally to the state of the I/O pins.

The power-on Reset (POR) macro-cell will produce a logic High signal as an output when the device power supply ( $V_{CC}$ ) rises to approximately  $V_{PORR}$  and device completely starts up. All outputs are in high impedance state and chip starts loading data from OTP. The reset signal is released for internal macro-cells and all the registers are initialized to their default states. Figure 7-20 shows POR system generates a sequence of signals that enable certain macro-cells.



**Figure 7-20. POR Sequence**

As shown in Figure 7-20, after the  $V_{CC}$  has start ramping up and crosses the  $V_{PORR}$  threshold:

- First, the on-chip OTP memory is reset.
- Next, the device reads the data from OTP memory, and transfers this information to configure each macro-cell and the connection mux.
- The third stage resets the GPIOs that are configured as inputs and then enables them.
- After that, the LUTs are reset and become active. After LUTs, the delay cells, OSC, DFFs, latches and pipe delay are initialized.
- After all macro-cells are initialized, the internal POR signal generated by the POR macro-cell goes from low to high.
- The last portion of the device to be initialized are the output PINs, which transition from high impedance to active at this point.

Delay blocks will pass their inputs through to the output during the startup sequence without delaying the signal per the configuration, so a LUT added in front of the input of a DLY that ANDs the DLY input with POR will guarantee the input signal will not appear until the device has fully powered up.

#### 7.4.1.1 GPIO Quick Charge

There is an option to connect a 2k $\Omega$  resistor in parallel to any configured pull up/pull down resistors to help inputs get to the right voltage faster, especially if there is significant capacitance. The 10k $\Omega$ , 100k $\Omega$  and 1M $\Omega$  GPIO pull up/pull down resistors are not enabled until the POR sequence is completed.

#### 7.4.1.2 Initialization

All internal macro-cells are initialized to a low level by default. Starting from when  $V_{CC}$  exceeds  $V_{PORR}$ , macro-cells in the TPLD801 are powered on and forced into a reset state.

The POR signal going high indicates the mentioned power-up sequence is complete.

## 8 Application and Implementation

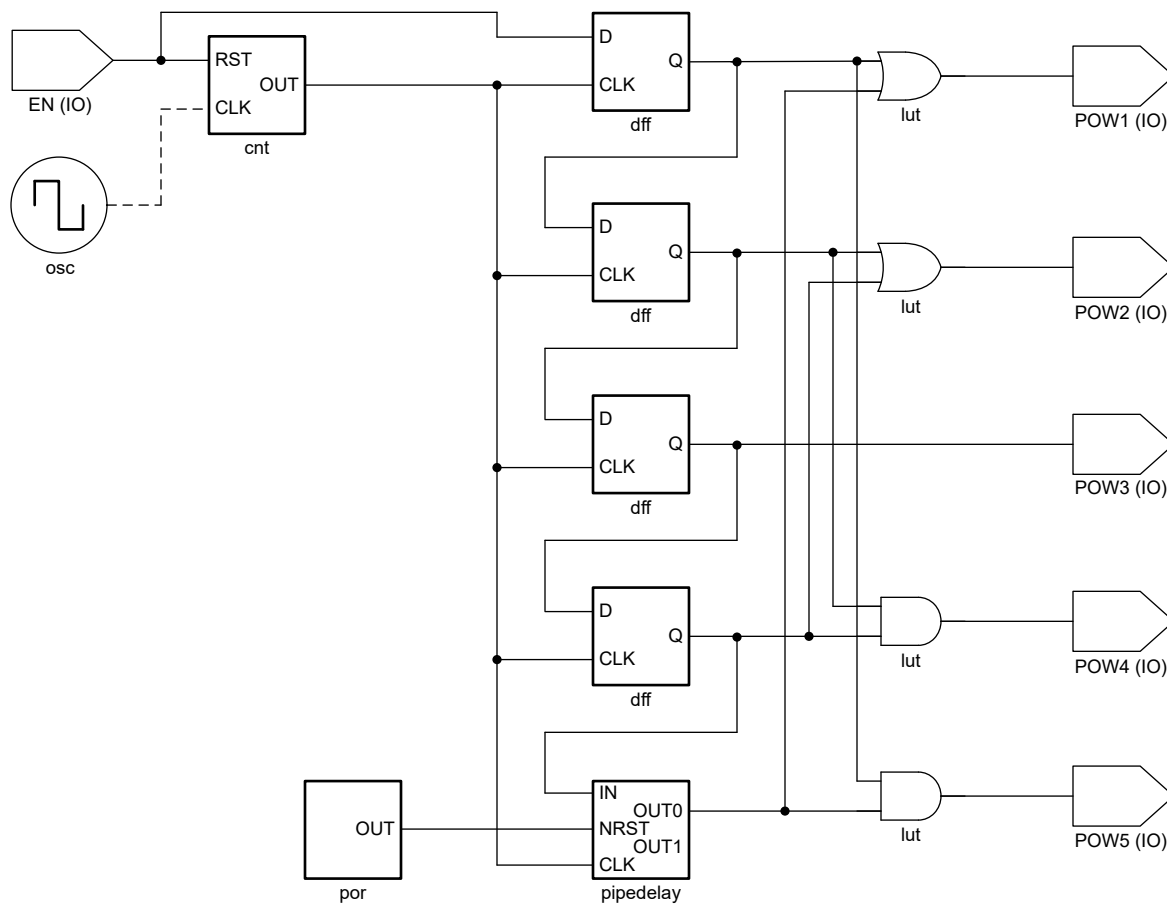
### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 8.1 Application Information

The configurable logic and timing blocks of TPLD801 allow for the device to provide symmetric power-up and power-down signals for numerous components. In this application the device is configured to output the maximum amount of power-up and power-down sequencing signals based on a counter/delay macro-cell.

### 8.2 Typical Application



**Figure 8-1. Typical Application Block Diagram**

## 8.2.1 Design Requirements

### 8.2.1.1 Power Considerations

Ensure the desired supply voltage is within the range specified in the *Recommended Operating Conditions*. The supply voltage sets the device's electrical characteristics of the device as described in the *Electrical Characteristics* section.

The positive voltage supply must be capable of sourcing current equal to the total current to be sourced by all outputs of the TPLD801 plus the maximum static supply current,  $I_{CC}$ , listed in the *Electrical Characteristics*, and any transient current required for switching. The device can only source as much current that is provided by the positive supply source. Ensure the maximum total current through  $V_{CC}$  listed in the *Absolute Maximum Ratings* is not exceeded.

The ground must be capable of sinking current equal to the total current to be sunk by all outputs of the TPLD801 plus the maximum supply current,  $I_{CC}$ , listed in the *Electrical Characteristics*, and any transient current required for switching. The logic device can only sink as much current that can be sunk into its ground connection. Ensure the maximum total current through GND listed in the *Absolute Maximum Ratings* is not exceeded.

The TPLD801 can drive a load with a total capacitance less than or equal to 15pF while still meeting all of the data sheet specifications. Larger capacitive loads can be applied; however, it is not recommended to exceed 15pF.

The TPLD801 can drive a load with total resistance described by  $R_L \geq V_O / I_O$ , with the output voltage and current defined in the *Electrical Characteristics* table with  $V_{OH}$  and  $V_{OL}$ . When outputting in the HIGH state, the output voltage in the equation is defined as the difference between the measured output voltage and the supply voltage at the  $V_{CC}$  pin.

Total power consumption can be calculated using the information provided in [CMOS Power Consumption and Cpd Calculation](#).

Thermal increase can be calculated using the information provided in [Thermal Characteristics of Standard Linear and Logic \(SLL\) Packages and Devices](#).

#### CAUTION

The maximum junction temperature,  $T_{J(max)}$  listed in the *Absolute Maximum Ratings*, is an additional limitation to prevent damage to the device. Do not violate any values listed in the *Absolute Maximum Ratings*. These limits are provided to prevent damage to the device.

### 8.2.1.2 Input Considerations

Input signals must cross  $V_{IL(max)}$  or  $V_{t-(min)}$  to be considered a logic LOW, and  $V_{IH(min)}$  or  $V_{t+(max)}$  to be considered a logic HIGH. Do not exceed the maximum input voltage range found in the *Absolute Maximum Ratings*.

Unused inputs must be terminated to either  $V_{CC}$  or ground. The unused inputs can be directly terminated if the input is completely unused, or they can be connected with a pull-up or pull-down resistor if the input will be used sometimes, but not always. A pull-up resistor is used for a default state of HIGH, and a pull-down resistor is used for a default state of LOW. The drive current of the controller, leakage current into the TPLD801 (as specified in the *Electrical Characteristics*), and the desired input transition rate limits the resistor size. A 10k $\Omega$  resistor value is often used due to these factors.

The TPLD801 has CMOS inputs and thus requires fast input transitions to operate correctly, as defined in the *Recommended Operating Conditions* table. Slow input transitions can cause oscillations, additional power consumption, and reduction in device reliability.

The TPLD801 can be used with no signal transition rate requirements because it has Schmitt-Trigger inputs.

Another benefit to having Schmitt-Trigger inputs is the ability to reject noise. Noise with a large enough amplitude can still cause issues. To know how much noise is too much, please refer to the  $\Delta V_{T(min)}$  in the *Electrical Characteristics*. This hysteresis value will provide the peak-to-peak limit.

Unlike what happens with standard CMOS inputs, Schmitt-Trigger inputs can be held at any valid value without causing huge increases in power consumption. The typical additional current caused by holding an input at a value other than  $V_{CC}$  or ground is plotted in the *Typical Characteristics*.

Refer to the *Feature Description* section for additional information regarding the inputs for this device.

### 8.2.1.3 Output Considerations

The positive supply voltage is used to produce the output HIGH voltage. Drawing current from the output will decrease the output voltage as specified by the  $V_{OH}$  specification in the *Electrical Characteristics*. The ground voltage is used to produce the output LOW voltage. Sinking current into the output will increase the output voltage as specified by the  $V_{OL}$  specification in the *Electrical Characteristics*.

Push-pull outputs that could be in opposite states, even for a very short time period, should never be connected directly together. This can cause excessive current and damage to the device.

Two channels within the same device with the same input signals can be connected in parallel for additional output drive strength.

Open-drain outputs can be connected together directly to produce a wired-AND configuration or for additional output drive strength.

Unused outputs can be left floating. Do not connect outputs directly to  $V_{CC}$  or ground.

Refer to the *Feature Description* section for additional information regarding the outputs for this device.

### 8.2.2 Detailed Design Procedure

1. Add a decoupling capacitor from  $V_{CC}$  to GND. The capacitor needs to be placed physically close to the device and electrically close to both the  $V_{CC}$  and GND pins. An example layout is shown in the *Layout* section.
2. Verify that the capacitive load at the output is  $\leq 50\text{pF}$ . This is not a hard limit; by design, however, it will optimize performance. This can be accomplished by providing short, appropriately sized traces from the TPLD801 to one or more of the receiving devices.
3. Verify that the resistive load at the output is larger than  $(V_{CC} / I_{O(max)})\Omega$ . Doing this prevents the maximum output current from the *Absolute Maximum Ratings* from being violated. Most CMOS inputs have a resistive load measured in  $M\Omega$ ; much larger than the minimum calculated previously.
4. Thermal issues are rarely a concern for logic gates; the power consumption and thermal increase, however, can be calculated using the steps provided in the [CMOS Power Consumption and Cpd Calculation application note](#).

### 8.2.3 Application Curves

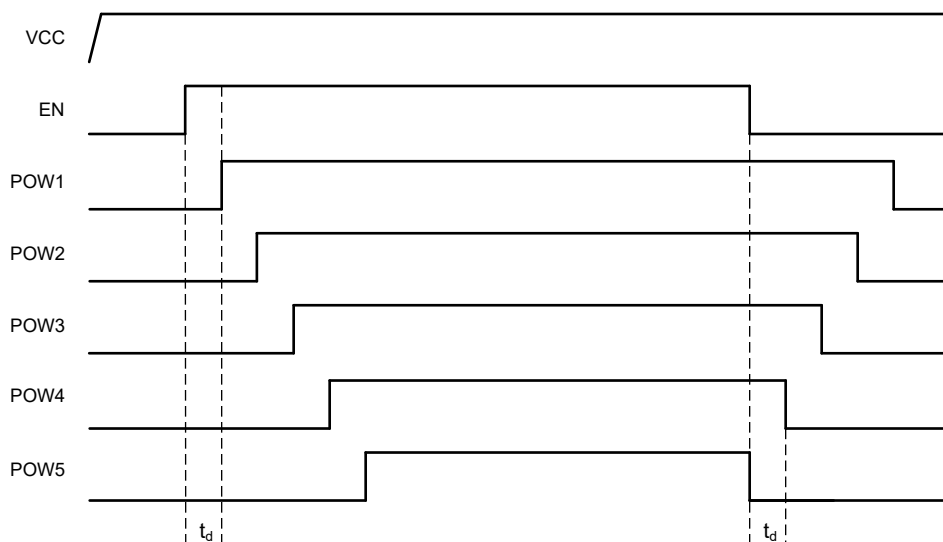


Figure 8-2. Application Timing Diagram

## 8.3 Power Supply Recommendations

The power supply can be any voltage between the minimum and maximum supply voltage rating located in the *Recommended Operating Conditions*. Each  $V_{CC}$  terminal should have a good bypass capacitor to prevent power disturbance.

A 0.1 $\mu$ F capacitor is recommended for this device. It is acceptable to parallel multiple bypass capacitors to reject different frequencies of noise. The 0.1 $\mu$ F and 1 $\mu$ F capacitors are commonly used in parallel. The bypass capacitor should be installed as close to the power terminal as possible for best results.

## 8.4 Layout

### 8.4.1 Layout Guidelines

When using multiple-input and multiple-channel logic devices, inputs must never be left floating. In many cases, functions or parts of functions of digital logic devices are unused; for example, when only two inputs of a triple-input AND gate are used or only 3 of the 4 buffer gates are used. Such unused input pins must not be left unconnected because the undefined voltages at the outside connections result in undefined operational states. All unused inputs of digital logic devices must be connected to a logic high or logic low voltage, as defined by the input voltage specifications, to prevent them from floating. The logic level that must be applied to any particular unused input depends on the function of the device. Generally, the inputs are tied to GND or  $V_{CC}$ , whichever makes more sense for the logic function or is more convenient.

## 8.4.2 Layout Example

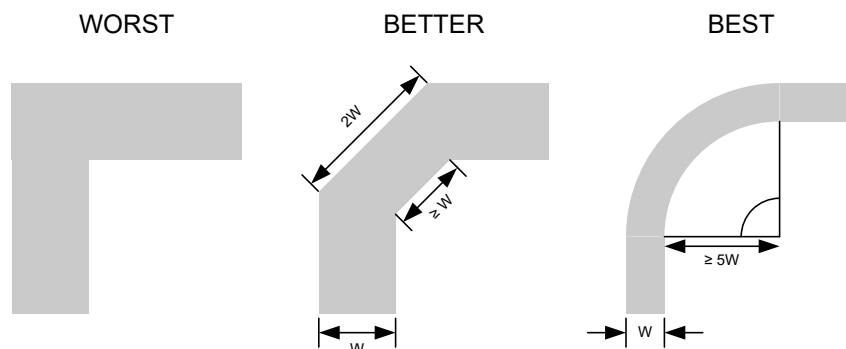


Figure 8-3. Example trace corners for improved signal integrity

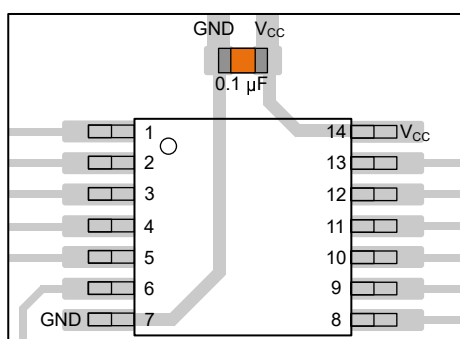


Figure 8-4. Example bypass capacitor placement for TSSOP and similar packages

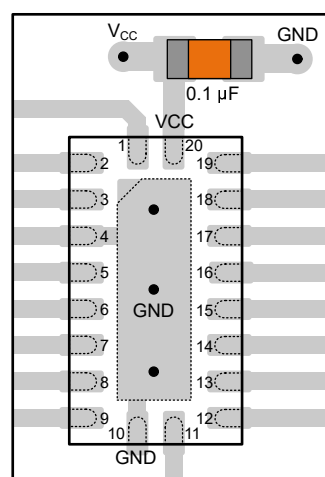


Figure 8-5. Example bypass capacitor placement for WQFN and similar packages

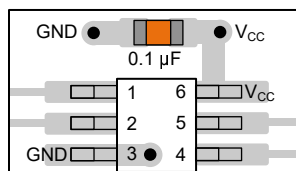


Figure 8-6. Example bypass capacitor placement for SOT, SC70 and similar packages

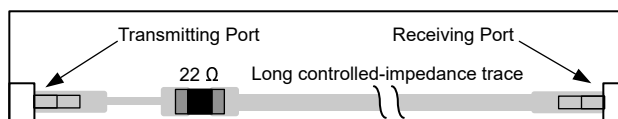


Figure 8-7. Example damping resistor placement for improved signal integrity

## 9 Device and Documentation Support

### 9.1 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on [ti.com](https://www.ti.com). Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

### 9.2 Support Resources

[TI E2E™ support forums](#) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

### 9.3 Trademarks

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### 9.4 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 9.5 Glossary

[TI Glossary](#) This glossary lists and explains terms, acronyms, and definitions.

## 10 Revision History

Changes from Revision * (September 2024) to Revision A (July 2025)	Page
• Updated document status from Advance Information to Production Data.....	<a href="#">1</a>

## 11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">TPLD801DRLR</a>	Active	Production	SOT-5X3 (DRL)   8	3000   LARGE T&R	-	Call TI	Level-1-260C-UNLIM	-40 to 125	T801

(1) **Status:** For more details on status, see our [product life cycle](#).

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

**Important Information and Disclaimer:**The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

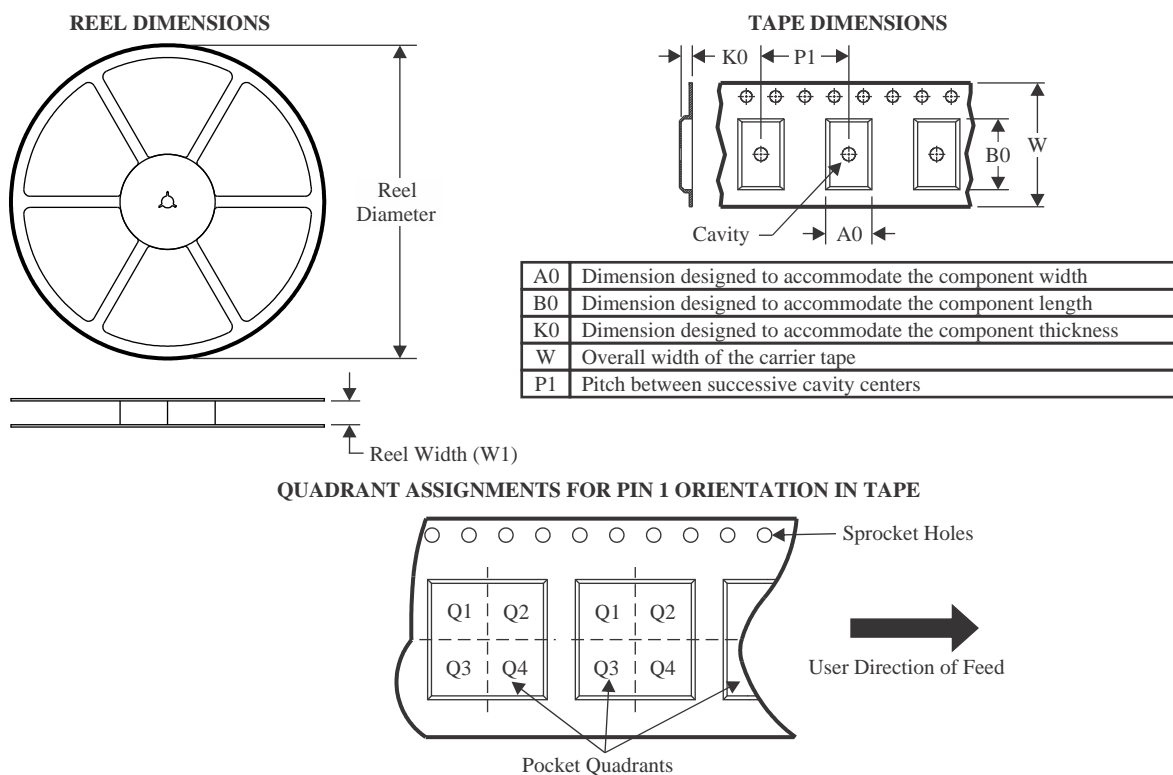
### OTHER QUALIFIED VERSIONS OF TPLD801 :

- Automotive : [TPLD801-Q1](#)

NOTE: Qualified Version Definitions:

- Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

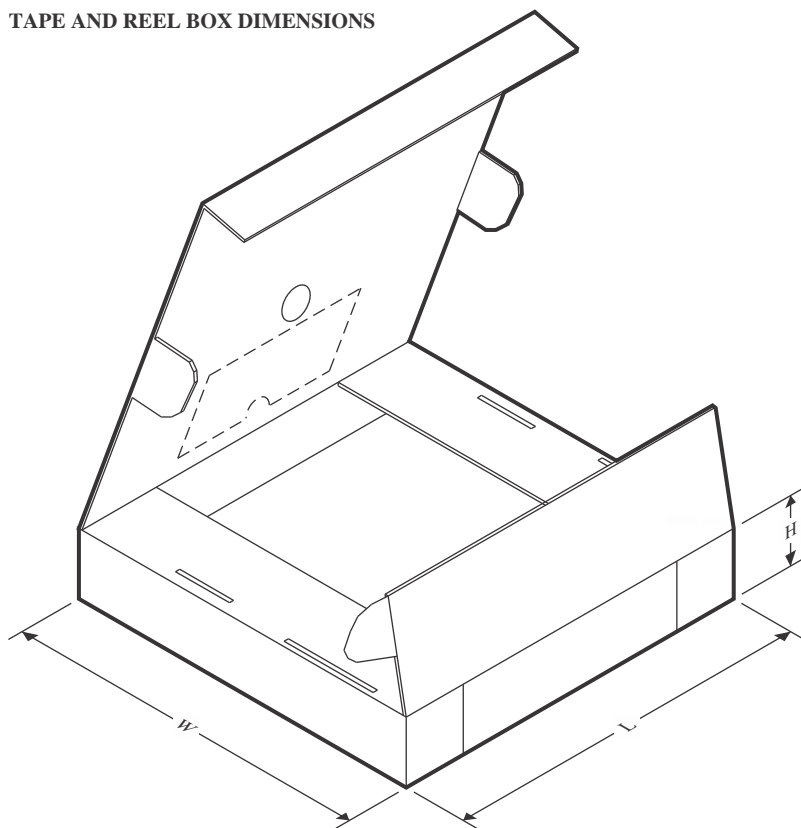
## TAPE AND REEL INFORMATION



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPLD801DRLR	SOT-5X3	DRL	8	3000	180.0	8.4	2.75	1.9	0.8	4.0	8.0	Q3

## TAPE AND REEL BOX DIMENSIONS



\*All dimensions are nominal

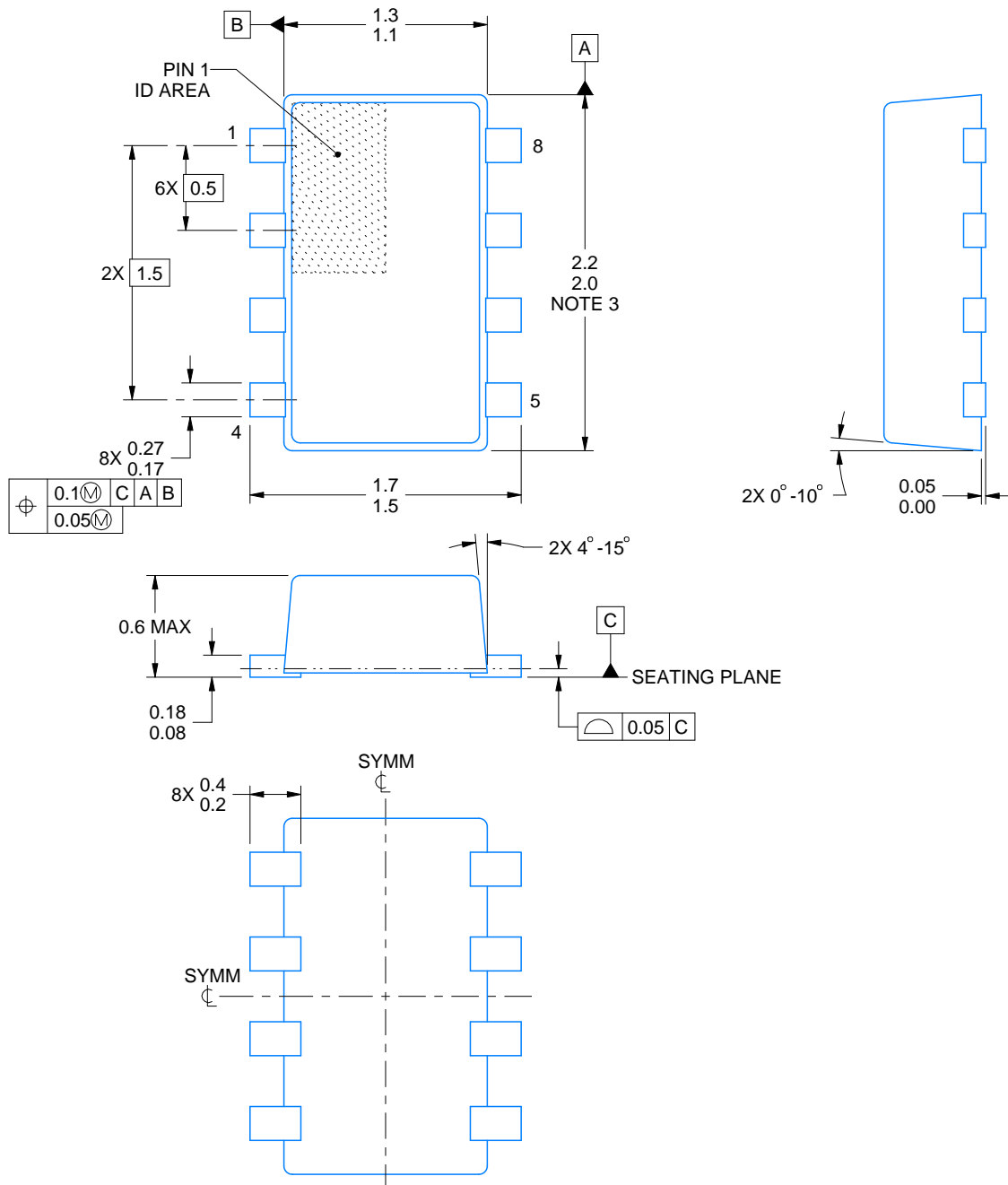
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPLD801DRLR	SOT-5X3	DRL	8	3000	210.0	185.0	35.0

**DRL0008A**

## PACKAGE OUTLINE

### SOT-5X3 - 0.6 mm max height

## PLASTIC SMALL OUTLINE



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NOTES:

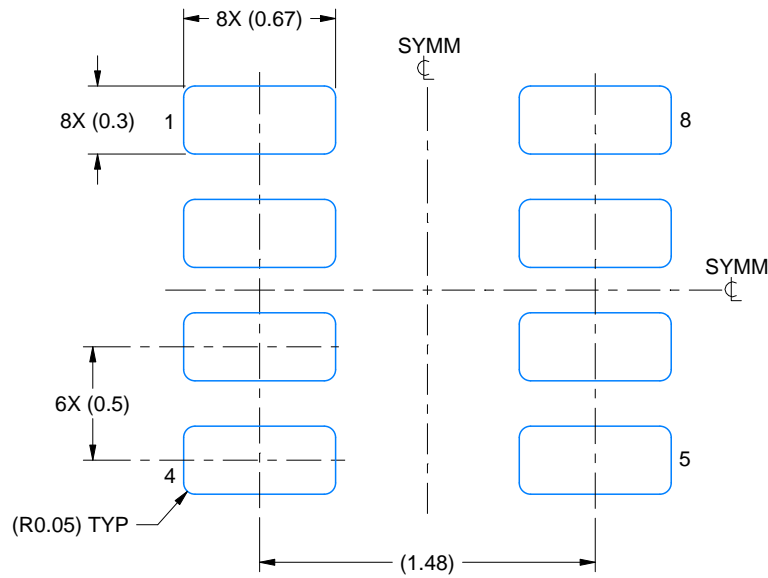
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, interlead flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
- 4.Reference JEDEC Registration MO-293, Variation UDAD

# EXAMPLE BOARD LAYOUT

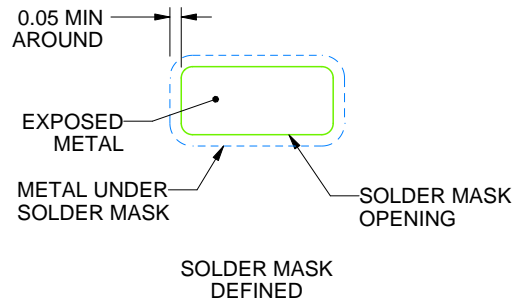
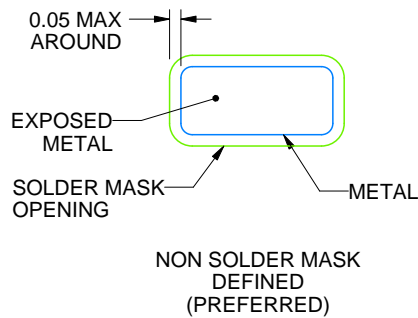
DRL0008A

SOT-5X3 - 0.6 mm max height

PLASTIC SMALL OUTLINE



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:30X



SOLDERMASK DETAILS

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NOTES: (continued)

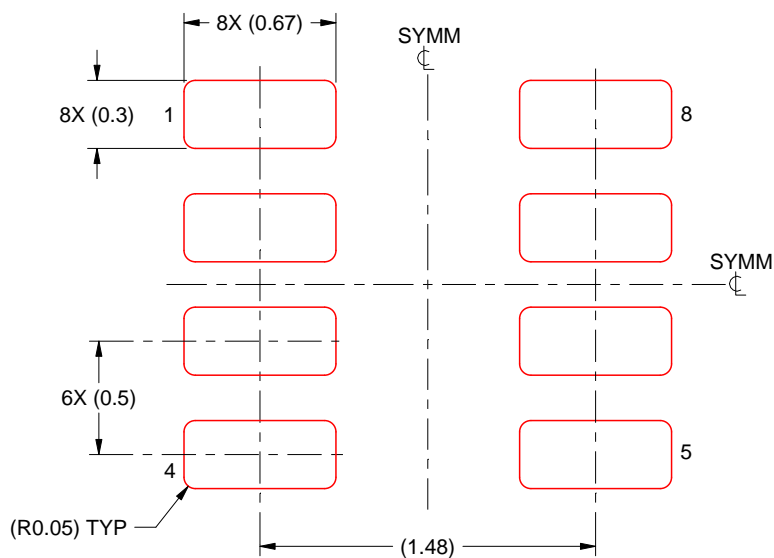
5. Publication IPC-7351 may have alternate designs.
6. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
7. Land pattern design aligns to IPC-610, Bottom Termination Component (BTC) solder joint inspection criteria.

# EXAMPLE STENCIL DESIGN

DRL0008A

SOT-5X3 - 0.6 mm max height

PLASTIC SMALL OUTLINE



SOLDER PASTE EXAMPLE  
BASED ON 0.1 mm THICK STENCIL  
SCALE:30X

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NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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