

TPS1HC08-Q1 9.8mΩ Single-Channel Automotive Smart High-Side Switch

1 Features

- Single-Channel smart high-side switch with full diagnostics
 - Control using GPIO pins
 - Open-drain status output
 - Current sense analog output: sense accuracy $<\pm 5\%$ at $\geq 2A$
- Wide operating voltage: 3V to 28V
- Low R_{ON} : 9.8mΩ typical, 16.5mΩ max at 150°C
- Ultra-low standby current: $<1.4\mu A$ at 85°C
- Adjustable current limit with and without thermal regulation
 - Current limit range: 10A to 25A
- Protection
 - Overload and short-circuit protection
 - Undervoltage lockout (UVLO)
 - Thermal shutdown and swing with self recovery
 - Integrated output clamp to demagnetize inductive loads
 - Loss-of-GND, loss-of-battery, and reverse battery protection
- Diagnostics
 - Global fault report for fast interrupt
 - Overcurrent and short-to-ground detection
 - Open-load and short-to-battery detection
- Qualified for automotive applications
 - AEC-Q100 qualified with the following results:
 - Temperature grade 1: $-40^{\circ}C$ to $125^{\circ}C$ ambient operating temperature range
 - Passed electrical transient disturbance immunity tests (ISO7637-2 and ISO16750-2)
- Small footprint: 11-pin wettable flank VQFN-HR 2.2mm x 3.6mm, 0.55mm pitch
- **Functional Safety Capable**
 - Documentation available to aid functional safety system design

2 Applications

- Zone control module
- Body control module
- Incandescent and LED lighting
- Front door module
- Seat heater

3 Description

TPS1HC08-Q1 is a single-channel, smart high-side switch, with integrated NMOS power FET and charge pump, designed for 12V automotive battery systems. The low on-resistance (9.8mΩ) minimizes device power dissipation when driving a wide range of output load current up to 10A DC.

The device integrates protection features such as thermal shutdown, output clamp, and current limit. TPS1HC08-Q1 implements an adjustable current limiting circuit that improves the reliability of the system by reducing inrush current when driving large capacitive loads and minimizing overload current. The adjustable current limit can be adjusted from (10A to 25A) using an external resistor on the ILIM pin. The device offers both thermal-regulated current limiting for capacitive loads at startup and non-regulated current limiting for motor inrush or bulb applications.

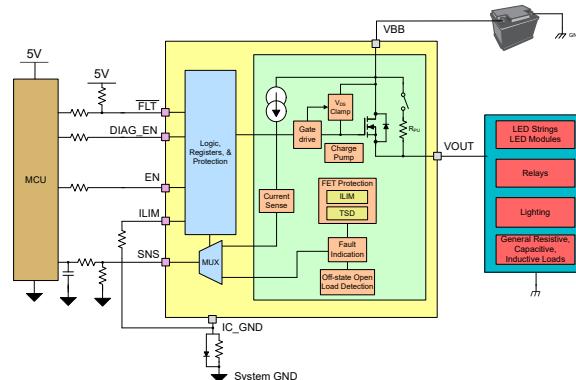
The device also provides an accurate current sense that allows for improved load diagnostics such as overload and open-load detection, enabling better predictive maintenance. TPS1HC08-Q1 is available in a 11-pin, 2.2mm x 3.6mm VQFN-HR wettable-flank package with 0.55mm pitch, minimizing the PCB footprint.

Package Information

| PART NUMBER | PACKAGE ⁽¹⁾ | PACKAGE SIZE ⁽²⁾ |
|-------------|------------------------|-----------------------------|
| TPS1HC08-Q1 | VAH (VQFN-HR, 11) | 2.2mm x 3.6mm |

(1) See the orderable addendum at the end of the data sheet.

(2) The package size is a nominal value and includes pins.



Typical Application Schematic



An IMPORTANT NOTICE at the end of this data sheet addresses availability, warranty, changes, use in safety-critical applications, intellectual property matters and other important disclaimers. PRODUCTION DATA.

Table of Contents

| | | | |
|--|-----------|--|-----------|
| 1 Features | 1 | 8.3 Feature Description..... | 18 |
| 2 Applications | 1 | 8.4 Device Functional Modes..... | 50 |
| 3 Description | 1 | 9 Application and Implementation | 52 |
| 4 Device Comparison Table | 3 | 9.1 Application Information..... | 52 |
| 5 Pin Configuration and Functions | 4 | 9.2 Typical Application..... | 52 |
| 6 Specifications | 5 | 9.3 Power Supply Recommendations..... | 57 |
| 6.1 Absolute Maximum Ratings..... | 5 | 9.4 Layout..... | 57 |
| 6.2 ESD Ratings..... | 5 | 10 Revision History | 60 |
| 6.3 Recommended Operating Conditions..... | 5 | 11 Device and Documentation Support | 61 |
| 6.4 Thermal Information..... | 6 | 11.1 Third-Party Products Disclaimer..... | 61 |
| 6.5 Electrical Characteristics..... | 6 | 11.2 Receiving Notification of Documentation Updates..... | 61 |
| 6.6 SNS Timing Characteristics..... | 9 | 11.3 Support Resources..... | 61 |
| 6.7 Switching Characteristics..... | 9 | 11.4 Trademarks..... | 61 |
| 6.8 Typical Characteristics..... | 11 | 11.5 Electrostatic Discharge Caution..... | 61 |
| 7 Parameter Measurement Information | 15 | 11.6 Glossary..... | 61 |
| 8 Detailed Description | 16 | 12 Mechanical, Packaging, and Orderable Information | 62 |
| 8.1 Overview..... | 16 | | |
| 8.2 Functional Block Diagram..... | 17 | | |

4 Device Comparison Table

TPS1HC08-Q1 is part of a high current, smart high-side switch family, which has multiple device versions. The following tables shows the details of the versions and which versions are going to be available for each device.

Table 4-1. Version Table

| VERSION ⁽²⁾ | SLEW RATE | OPEN LOAD DETECTION DELAY |
|------------------------|--------------------|---------------------------|
| P | Nominal (0.45V/μs) | 0.4ms delay |
| M ⁽¹⁾ | Nominal (0.45V/μs) | 2.4ms delay |
| D ⁽¹⁾ | Slow (0.06V/μs) | 0.4ms delay |
| B ⁽¹⁾ | Slow (0.06V/μs) | 2.4ms delay |

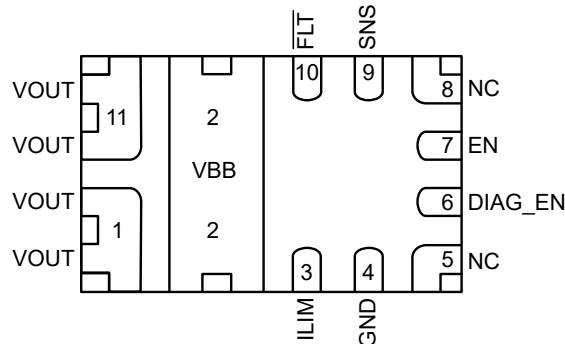
(1) Device in preview. Please contact TI for more information.

(2) All versions are GPIO controlled.

Table 4-2. Device Comparison Table

| PART NUMBER | PLANNED VERSIONS | NUMBER OF CHANNELS | ON-RESISTANCE at 25°C | ADJUSTABLE CURRENT LIMIT RANGE | OVERCURRENT BEHAVIOR |
|-------------|------------------|--------------------|-----------------------|--------------------------------|--|
| TPS2HC08-Q1 | P, D, M, B | 2 | 9.5mΩ | 7.5A - 25A | |
| TPS2HC16-Q1 | P, M | 2 | 18.7mΩ | 5A - 15A | |
| TPS1HC08-Q1 | P, D, M | 1 | 9.8mΩ | 10A - 25A | |
| TPS1HC04-Q1 | P, D | 1 | 4.9mΩ | 15A - 45A | |
| TPS1HC03-Q1 | P, D, M | 1 | 3.2mΩ | 20A - 55A | |
| TPS1HC16-Q1 | P | 1 | 16mΩ | 7A - 17A | |
| TPS2HC30-Q1 | P | 2 | 30mΩ | 3.5A - 11A | <ul style="list-style-type: none"> • Current limiting with thermal regulation when external resistor is used on ILIM pin • Current limiting with no thermal regulation when ILIM pin = GND |

5 Pin Configuration and Functions



NC – No internal connection

Figure 5-1. VAH Package TPS1HC08-Q1 Top View

Table 5-1. Pin Functions

over operating free-air temperature range (unless otherwise noted)

| PIN | | TYPE | DESCRIPTION |
|-----|---------|--------|---|
| NO. | NAME | | |
| 1 | VOUT | Power | Output of high side switch, connect to load |
| 2 | VBB | Power | Power supply |
| 3 | ILIM | Input | Adjustable current limit. Connect a resistor from the pin to GND to set the current limit. |
| 4 | GND | Power | Ground of device. Connect to resistor-diode ground network to have reverse battery protection |
| 5 | NC | N/A | No internal connection |
| 6 | DIAG_EN | Input | Enable-disable pin for diagnostics, internal pulldown |
| 7 | EN | Input | Input control for channel activation, internal pulldown |
| 8 | NC | N/A | No internal connection |
| 9 | SNS | Output | Analog current sense output corresponding to load current. Connect R_{SNS} to ground to convert to a voltage. Also shows fault status by going high |
| 10 | FLT | Output | Open drain global fault output. Referred to as FAULT, \overline{FLT} , or fault pin |
| 11 | VOUT | Power | Output of high side switch, connect to load |

6 Specifications

6.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted)⁽¹⁾

| | | MIN | MAX | UNIT |
|---|---|-------------------|-----------------|------|
| Maximum continuous supply voltage, V _{BB} | | 28 | | V |
| Load dump voltage, V _{LD} | ISO16750-2:2010(E) | 35 | | V |
| Reverse polarity voltage | Maximum duration of 3 minutes and with the application circuit | -18 | | V |
| Enable pin current, I _{EN} | Enable pin current, I _{EN} | -1 | 20 | mA |
| Enable pin voltage, V _{EN} | | -1 | 7 | V |
| Diagnostic Enable pin current, I _{DIAG_EN} | | -1 | 20 | mA |
| Diagnostic Enable pin voltage, V _{DIAG_EN} | | -1 | 7 | V |
| Sense pin current, I _{SNS} | | -150 | 10 | mA |
| FLT pin current, I _{FLT} | | -30 | 10 | mA |
| FLT pin voltage, V _{FLT} | | -0.3 | V _{BB} | V |
| ILIM pin current, I _{ILIM} | FLT pin current, I _{FLT} | -30 | 10 | mA |
| ILIM pin voltage, V _{ILIM} | FLT pin voltage, V _{FLT} | -0.3 | V _{BB} | V |
| Reverse ground current, I _{GND} | V _{BB} < 0V | | -50 | mA |
| Energy dissipation during turnoff, E _{AS} | Single pulse, V _{BB} = 13.5V, I _{OUT} = 5mH, T _{J,start} = 125°C, nominal slew rate (version P, M) | 96 ⁽²⁾ | | mJ |
| Energy dissipation during turnoff, E _{AR} | Repetitive pulse, 13.5V, I _{OUT} = 10A, T _{J,start} = 125°C, nominal slew rate (version P, M) | 13 ⁽²⁾ | | mJ |
| Maximum junction temperature, T _J | | 150 | | °C |
| Storage temperature, T _{stg} | | -65 | 150 | °C |

(1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

(2) For further details, see the section regarding switch-off of an inductive load.

6.2 ESD Ratings

| | | | VALUE | UNIT |
|--------------------|--|--|--|-------|
| V _(ESD) | Electrostatic discharge ⁽¹⁾ | Human-body model (HBM), per AEC Q100-002 Classification Level 2 ⁽²⁾ | All pins except V _{BB} and V _{OUT} | ±2000 |
| | | | V _{BB} and V _{OUT} | ±4000 |
| | | Charged-device model (CDM), per AEC Q100-011 Classification Level C5 | All pins | ±750 |

(1) All ESD strikes are with reference from the pin mentioned to GND

(2) AEC-Q100-002 indicates that HBM stressing shall be in accordance with the ANSI/ESDA/JEDEC JS-001 specifications.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

| | | MIN | MAX | UNIT |
|----------------------|---|-----|-----|------|
| V _{VBB_NOM} | Nominal supply voltage ⁽¹⁾ | 4 | 18 | V |
| V _{VBB_EXT} | Extended supply voltage ⁽²⁾ | 3 | 28 | V |
| V _{VBB_SC} | Short circuit supply voltage capability | | 24 | V |
| V _{EN} | Enable voltage | -1 | 5.5 | V |
| V _{DIAG_EN} | Diagnostic Enable voltage | -1 | 5.5 | V |
| V _{SNS} | Sense voltage | -1 | 5.5 | V |

over operating free-air temperature range (unless otherwise noted) ⁽¹⁾

| | | MIN | MAX | UNIT |
|----------------|--------------------------------|-----|-----|------|
| T _A | Operating free-air temperature | -40 | 125 | °C |

(1) All operating voltage conditions are measured with respect to device GND

(2) Device will function within extended operating range, however some timing parametric values might not apply. See the respective sections for what voltages are used. Additionally more explanation can be found in [Power Supply Recommendations](#)

6.4 Thermal Information

| THERMAL METRIC ^{(1) (2)} | | TPS1HC08-Q1 | UNIT |
|-----------------------------------|--|-------------|------|
| | | VAH | |
| | | 11 PINS | |
| R _{θJA} | Junction-to-ambient thermal resistance | 46.2 | °C/W |
| R _{θJC(top)} | Junction-to-case (top) thermal resistance | 44.0 | °C/W |
| R _{θJB} | Junction-to-board thermal resistance | 13.7 | °C/W |
| Ψ _{JT} | Junction-to-top characterization parameter | 2.4 | °C/W |
| Ψ _{JB} | Junction-to-board characterization parameter | 13.7 | °C/W |
| R _{θJC(bot)} | Junction-to-case (bottom) thermal resistance | 17.5 | °C/W |

(1) For more information about traditional and new thermal metrics, see the [SPRA953](#) application report.

(2) The thermal parameters are based on a 4-layer PCB according to the JESD51-5 and JESD51-7 standards.

6.5 Electrical Characteristics

V_{BB} = 6V to 18V, T_J = -40°C to 150°C (unless otherwise noted); Typical application is V_{BB} = 13.5V, R_{LIM} = Open (unless otherwise specified)

| PARAMETER | TEST CONDITIONS | | MIN | TYP | MAX | UNIT | |
|----------------------------------|---|--|-----------------------------------|------|------|------|---|
| INPUT VOLTAGE AND CURRENT | | | | | | | |
| V _{UVLOR} | V _{BB} undervoltage lockout | Measured with respect to device GND pin | V _{BB} rising threshold | 3.7 | 3.85 | 4.0 | V |
| V _{UVLOF} | V _{BB} undervoltage lockout | | V _{BB} falling threshold | 2.8 | 2.9 | 3.0 | V |
| V _{DET1} | V _{BB} detection 1 threshold | Active, diagnostic, or standby state | V _{BB} rising threshold | 19 | 20.5 | 22.5 | V |
| | | | V _{BB} falling threshold | 18.4 | 19.5 | 20.7 | V |
| V _{DET2} | V _{BB} detection 2 threshold | Active state | V _{BB} rising threshold | 24.5 | 26 | 28 | V |
| | | | V _{BB} falling threshold | 22.5 | 24 | 26 | V |
| V _{HV_R} | V _{BB} high voltage wake-up threshold | V _{BB} voltage to transition from sleep to standby state | V _{BB} rising threshold | 20.9 | 25 | 28.1 | V |
| V _{HV_F} | V _{BB} high voltage wake-up threshold | V _{BB} voltage to transition from standby to sleep state | V _{BB} falling threshold | 18 | | | V |
| V _{Clamp} | VDS clamp voltage | V _{BB} ≥ V _{DET1} | T _J = 25°C | 35 | 37 | | V |
| | | | T _J = -40°C to 150°C | 31 | 42 | | V |
| | | V _{BB} < V _{DET1} | T _J = -40°C to 150°C | 24 | 35 | | V |
| I _{SLEEP} | Standby current (total device leakage including MOSFET channel) | V _{EN} = V _{DIAG_EN} = 0V, V _{OUT} = 0V | T _J = 25°C | | 1.2 | μA | |
| | | | T _J = 85°C | | 1.4 | μA | |
| | | | T _J = 150°C | | 12 | μA | |
| I _{OUT(SLEEP)} | Output leakage current | V _{EN} = V _{DIAG_EN} = 0V, V _{OUT} = 0V | T _J = 25°C | 0.01 | 0.5 | μA | |
| | | | T _J = 85°C | | 0.7 | μA | |
| | | | T _J = 150°C | | 6 | μA | |

$V_{BB} = 6V$ to $18V$, $T_J = -40^{\circ}C$ to $150^{\circ}C$ (unless otherwise noted); Typical application is $V_{BB} = 13.5V$, $R_{LIM} = \text{Open}$ (unless otherwise specified)

| PARAMETER | | TEST CONDITIONS | | MIN | TYP | MAX | UNIT |
|------------|--------------------------------------|---|--|-----|-----|-----|------|
| I_{DIAG} | Diagnostic state current consumption | $V_{EN} = 0V$, $V_{DIAG_EN} = 0V$, $V_{OUT} = 0V$, $I_{SNS} = 0A$ | | | 1.2 | 2.4 | mA |
| | | $V_{EN} = 0V$, $V_{DIAG_EN} = 5V$, $V_{OUT} = 0V$, $I_{SNS} = 0A$ | | | 1.2 | 2.4 | mA |
| I_Q | Quiescent current | $V_{EN} = V_{DIAG_EN} = 5V$, $I_{OUT} = 0A$ | | | 1.4 | 2.6 | mA |
| t_{STBY} | Standby mode delay time | $V_{EN} = V_{DIAG_EN} = 0V$, $V_{BB} < V_{HV_F}$ to standby | | 15 | 20 | 23 | ms |

RON CHARACTERISTICS

| | | | | | | | |
|----------------------|---------------------------------------|--|----------------------|------|------|-----------|---|
| R_{ON} | On-resistance | $3V \leq V_{BB} \leq 28V$, $I_{OUT} = 1A$ | $T_J = 25^{\circ}C$ | 9.8 | 11 | $m\Omega$ | |
| | | | $T_J = 150^{\circ}C$ | | 16.5 | $m\Omega$ | |
| $R_{ON(\text{REV})}$ | On-resistance during reverse polarity | $-18V \leq V_{BB} \leq -6V$ | $T_J = 25^{\circ}C$ | 10 | 11.5 | $m\Omega$ | |
| | | | $T_J = 150^{\circ}C$ | | 16.8 | $m\Omega$ | |
| $I_{L\text{NOM}}$ | Continuous load current | $T_A = 85^{\circ}C$ | | 10 | | A | |
| V_F | Source-to-drain body diode voltage | $V_{EN} = 0V$ $I_{OUT} = -1A$ | | 0.15 | 0.6 | 0.8 | V |

CURRENT SENSE CHARACTERISTICS

| | | | | | | |
|-----------|--|--|-------------------|------|-----|-----|
| K_{SNS} | Current sense ratio I_{OUT} / I_{SNS} across I_{OUT} | $V_{BB} > V_{BB_ISNS}$, $V_{EN} = V_{DIAG_EN} = 5V$ | $I_{OUT} = 5A$ | 4252 | | A/A |
| | | | -5 | | 5 | % |
| | | | $I_{OUT} = 2A$ | 4256 | | A/A |
| | | | -5 | | 5 | % |
| | | | $I_{OUT} = 1A$ | 4266 | | A/A |
| | | | -5.5 | | 5.7 | % |
| | | | $I_{OUT} = 500mA$ | 4279 | | A/A |
| | | | -9 | | 9 | % |
| | | | $I_{OUT} = 200mA$ | 4323 | | A/A |
| | | | -24 | | 25 | % |
| | | | $I_{OUT} = 100mA$ | 4410 | | A/A |
| | | | -47 | | 54 | % |

SNS CHARACTERISTICS

| | | | | | | | | |
|---------------------------------------|--|----------------------------------|---------------------|-----|------|-----|-----|----|
| I_{SNSFH} | I_{SNS} fault high-level | $V_{DIAG_EN} > V_{IH,DIAG_EN}$ | | 5.5 | 7.4 | 9.5 | mA | |
| $I_{SNS\text{leak_disab}}\text{led}$ | I_{SNS} leakage (Diagnostics disabled) | $V_{DIAG_EN} = 0V$ | Force 0V on SNS Pin | | -100 | 1 | 100 | nA |

CURRENT LIMIT CHARACTERISTICS

| | | | | | | | |
|---------------------|--|--|--------------------------------------|-----|-----|-----------|---------------|
| R_{LIM} | R_{LIM} Short Circuit Detection Range | | | 20 | | $k\Omega$ | |
| R_{LIM} | R_{LIM} Open Detection Range | | | 50 | | $k\Omega$ | |
| $I_{CL_FLT_Trip}$ | Ratio of Current at which fault assertion happens to actual current limit ⁽¹⁾ | $T_J = -40^{\circ}C$ to $150^{\circ}C$ | $R_{LIM} = 20k\Omega$ to $50k\Omega$ | 74 | 80 | % | |
| K_{CL} | Current Limit Ratio ⁽¹⁾ | $T_J = -40^{\circ}C$ to $150^{\circ}C$ | $R_{LIM} = 20k\Omega$ | 405 | 500 | 635 | $A * k\Omega$ |
| | | | $R_{LIM} = 33.2k\Omega$ | 405 | 500 | 635 | $A * k\Omega$ |
| | | | $R_{LIM} = 50k\Omega$ | 405 | 500 | 635 | $A * k\Omega$ |
| I_{CL} | I_{CL} Current Limit Threshold | $T_J = -40^{\circ}C$ to $150^{\circ}C$ | $R_{LIM} = GND$ | | 25 | | A |
| | | | $R_{LIM} = OPEN$ | | 10 | | A |

V_{BB} = 6V to 18V, T_J = -40°C to 150°C (unless otherwise noted); Typical application is V_{BB} = 13.5V, R_{LIM} = Open (unless otherwise specified)

| PARAMETER | | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|----------------------|---|---------------------------------|---|------------------------|-----------------|------|
| I _{CB} | Peak current threshold when short is applied while switch enabled (2) | R _{LIM} = 20kΩ to 50kΩ | T _J = -40°C | 28 | | A |
| | | | T _J = 25°C | 27 | | A |
| | | | T _J = 150°C | 26 | | A |
| I _{CL_HV} | I _{CL} current limit derating at high voltage (2) | T _J = -40°C to 150°C | V _{BB} < V _{DET1} | I _{CL} | | A |
| | | | V _{DET1} ≤ V _{BB} < V _{DET2} | (I _{CL})/2 | | A |
| | | | V _{BB} ≥ V _{DET2} | (I _{CL})/3 | | A |
| I _{CL_LNPK} | Linear mode Peak (2) | T _J = -40°C to 150°C | R _{LIM} ≥ 30kΩ | 1.45 × I _{CL} | | A |
| | | | R _{LIM} < 30kΩ | 1.45 × I _{CL} | I _{CB} | A |

FAULT CHARACTERISTICS

| | | | | | | |
|----------------------------|---|---|-----|------|-----|----|
| V _{OL} | Open-load detection voltage (V _{BB} - V _{OUTx} voltage) | V _{EN} = 0V, V _{DIAG_EN} = 5V, diagnostic state | 1.5 | 2.2 | 2.9 | V |
| R _{PU} | Open-load (OL) detection internal pull-up resistor per channel | V _{EN} = 0V, V _{DIAG_EN} = 5V, diagnostic state, (V _{BB} - V _{OUT} = 2.7V) | | 90 | | kΩ |
| t _{OL} | Open-load (OL) detection deglitch time | V _{EN} = 0V, V _{DIAG_EN} = 5V, When V _{BB} - V _{OUT} < V _{OL} , duration longer than t _{OL} | 200 | 550 | | μs |
| t _{OL1} | OL and STB indication-time from EN falling | V _{EN} = 5V to 0V, V _{DIAG_EN} = 5V, I _{OUT} = 0mA, V _{OUT} = V _{BB} - V _{OL} | 200 | 550 | | μs |
| t _{OL2} | OL and STB indication-time from DIAG_EN rising | V _{EN} = 0V, V _{DIAG_EN} = 0V to 5V, I _{OUT} = 0mA, V _{OUT} = V _{BB} - V _{OL} | 200 | 4050 | | μs |
| T _{ABS} | Thermal shutdown (2) | | 150 | 165 | 185 | °C |
| T _{REL} | Relative thermal shutdown | | | 85 | | °C |
| T _{HYS} | Thermal shutdown hysteresis | | | 28 | | °C |
| V _{FLT} | FLT low output voltage | I _{FLT} = 2.5mA | | 0.2 | | V |
| t _{FAULT_FLT} | Fault indication-time (2) | V _{DIAG_EN} = 5V, time between fault and FLT asserting | | 20 | | μs |
| t _{FAULT_SNS} | Fault indication-time (2) | V _{DIAG_EN} = 5V, time between fault and I _{SNS} settling at I _{SNSFH} | | 30 | | μs |
| t _{RETRY_WIN_DOW} | Initial retry time window | | | 40 | | ms |
| t _{RETRY_INT} | Retry time in initial retry window | Time from thermal shutdown to switch re-enable | 100 | 160 | 300 | μs |
| t _{RETRY,EXTD} | Retry time in extended overcurrent | | 50 | 80 | 150 | ms |

EN PIN CHARACTERISTICS

| | | | | | | |
|-----------------------|------------------------------|------------------------|-----|-----|-----|----|
| V _{IL, EN} | Input voltage low-level | No GND Network | 0.8 | | V | |
| V _{IH, EN} | Input voltage high-level | | 1.5 | | V | |
| V _{IHYS, EN} | Input voltage hysteresis | | 320 | | mV | |
| R _{EN} | Internal pulldown resistor | | 150 | 200 | 500 | kΩ |
| I _{IL, EN} | Input current low-level (2) | V _{EN} = 0.8V | 1.6 | 4 | 5.5 | μA |
| I _{IH, EN} | Input current high-level (2) | V _{EN} = 5V | 19 | 25 | 35 | μA |

DIA_EN PIN CHARACTERISTICS

| | | | | | |
|----------------------------|--------------------------|----------------|-----|--|----|
| V _{IL, DIAG_EN} | Input voltage low-level | No GND Network | 0.8 | | V |
| V _{IH, DIAG_EN} | Input voltage high-level | | 1.5 | | V |
| V _{IHYS, DIAG_EN} | Input voltage hysteresis | | 320 | | mV |

$V_{BB} = 6V$ to $18V$, $T_J = -40^\circ C$ to $150^\circ C$ (unless otherwise noted); Typical application is $V_{BB} = 13.5V$, $R_{LIM} = \text{Open}$ (unless otherwise specified)

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--------------------|----------------------------|-----|-----|-----|------------------|
| R_{DIAG_EN} | Internal pulldown resistor | 100 | 200 | 500 | $\text{k}\Omega$ |
| $I_{IL, DIAG_EN}$ | $V_{DIAG_EN} = 0.8V$ | 1.6 | 4 | 5.5 | μA |
| $I_{IH, DIAG_EN}$ | $V_{DIAG_EN} = 5V$ | 19 | 25 | 35 | μA |

(1) To calculate I_{CL} from K_{CL} use equation $I_{CL} = K_{CL} / R_{LIM}$

(2) Parameter specified by design; not subject to production test.

6.6 SNS Timing Characteristics

$V_{BB} = 6V$ to $18V$, $V_{EN} = 5V$, $V_{DIAG_EN} = 5V$, $R_{SNS} = 1\text{k}\Omega$, $T_J = -40^\circ C$ to $+150^\circ C$ (unless otherwise noted)

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|-----------------------------------|--|-----|-----|-----|---------------|
| SNS TIMING - CURRENT SENSE | | | | | |
| $t_{SNSION1}$ | $V_{DIAG_EN} = 0V$ to $5V$, $I_{OUT} = 1A$ | | | 20 | μs |
| | $V_{DIAG_EN} = 0V$ to $5V$, $I_{OUT} = 50\text{mA}$ | | | 20 | μs |
| $t_{SNSION2}$ | $V_{EN} = V_{DIAG_EN} = 0V$ to $5V$, $I_{OUT} = 1A$ | | | 170 | μs |
| | $V_{EN} = V_{DIAG_EN} = 0V$ to $5V$, $I_{OUT} = 50\text{mA}$ | | | 170 | μs |
| $t_{SNSION3}$ | $V_{EN} = 0V$ to $5V$, $V_{DIAG_EN} = 5V$, $I_{OUT} = 1A$ | | | 110 | μs |
| $t_{SNSIOFF}$ | $V_{EN} = 5V$, $V_{DIAG_EN} = 5V$ to $0V$, $I_{OUT} = 1A$ | | | 20 | μs |
| $t_{SETTLEH}$ | $I_{OUT} = 50\text{mA}$ to $1A$ | | | 20 | μs |
| $t_{SETTLEL}$ | $I_{OUT} = 1A$ to 50mA | | | 20 | μs |

(1) Parameter specified by design; not subject to production test.

6.7 Switching Characteristics

$V_{BB} = 13.5V$, $R_L = 10\Omega$, $T_J = -40^\circ C$ to $+150^\circ C$ (unless otherwise noted)

| PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT | |
|-----------|-----------------------------|--|------|------|------|------------------------|
| t_{DR} | Channel Turn-on delay time | 50% of EN to 20% of VOUT from standby state | 6 | 12 | 30 | μs |
| | | 50% of EN to 20% of VOUT from sleep state | 8 | 45 | 70 | μs |
| t_{DF} | Channel Turn-off delay time | 50% of EN to 80% of VOUT | 35 | 80 | 121 | μs |
| SR_R | VOUT rising slew rate | 20% to 80% of VOUT (version = D, B) | 0.02 | 0.06 | 0.1 | $\text{V}/\mu\text{s}$ |
| | | 20% to 80% of VOUT (version = P, M) | 0.3 | 0.45 | 0.7 | $\text{V}/\mu\text{s}$ |
| SR_F | VOUT falling slew rate | 80% to 20% of VOUT (version = D, B) | 0.02 | 0.06 | 0.1 | $\text{V}/\mu\text{s}$ |
| | | 80% to 20% of VOUT (version = P, M) | 0.3 | 0.5 | 0.7 | $\text{V}/\mu\text{s}$ |
| t_{ON} | Channel Turn-on time | 50% of EN to 80% of VOUT, from standby state | 15 | 30 | 90 | μs |
| | | 50% of EN to 80% of VOUT, from sleep state | 35 | 60 | 110 | μs |
| t_{OFF} | Channel Turn-off time | 50% of EN to 20% of VOUT | 50 | 90 | 130 | μs |

$V_{BB} = 13.5V$, $R_L = 10\Omega$, $T_J = -40^\circ C$ to $+150^\circ C$ (unless otherwise noted)

| PARAMETER | | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--------------------|--|--|-----|------|---------|------|
| $t_{ON} - t_{OFF}$ | Turn-on and off matching ⁽¹⁾ | 1ms enable pulse | -75 | 40 | μs | |
| | | 200 μs enable pulse | -90 | 40 | μs | |
| Δ_{PWM} | PWM accuracy - average load current ⁽¹⁾ | 200 μs enable pulse (1ms period) | -45 | 25 | % | |
| | | $\leq 500Hz$, 50% Duty cycle | -12 | 12 | % | |
| E_{ON} | Switching energy losses during turn-on | $V_{BB} = 18V$, $R_L = 3.3\Omega$, 0% to 100% of V_{OUT} | | 0.63 | | mJ |
| | | $V_{BB} = 18V$, $R_L = 3.3\Omega$, 10% to 90% of V_{OUT} | | 0.59 | | mJ |
| E_{OFF} | Switching energy losses during turn-off | $V_{BB} = 18V$, $R_L = 3.3\Omega$, 100% to 0% of V_{OUT} | | 0.77 | | mJ |
| | | $V_{BB} = 18V$, $R_L = 3.3\Omega$, 90% to 10% of V_{OUT} | | 0.67 | | mJ |

(1) Parameter specified by design; not subject to production test.

6.8 Typical Characteristics

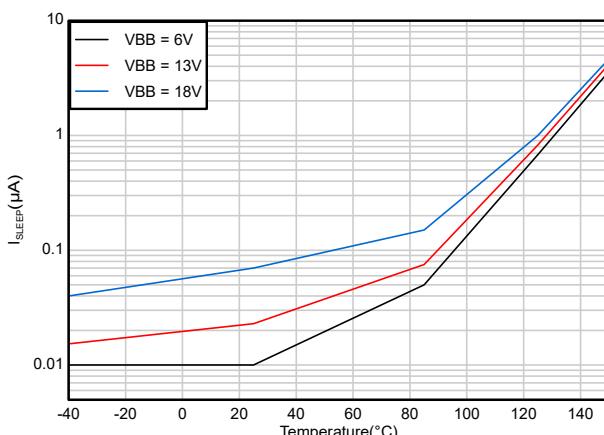


Figure 6-1. Standby Current (I_{SLEEP}) vs Temperature

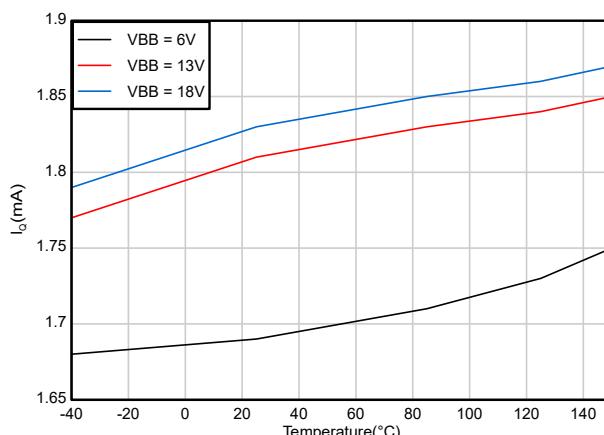


Figure 6-2. Quiescent Current (I_Q) vs Temperature

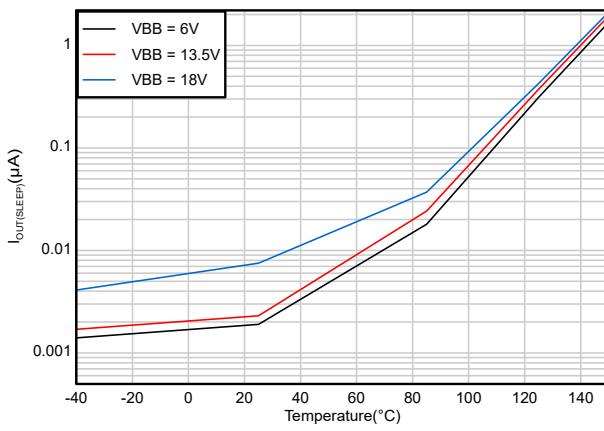


Figure 6-3. Output Leakage Current ($I_{OUT(SLEEP)}$) vs Temperature

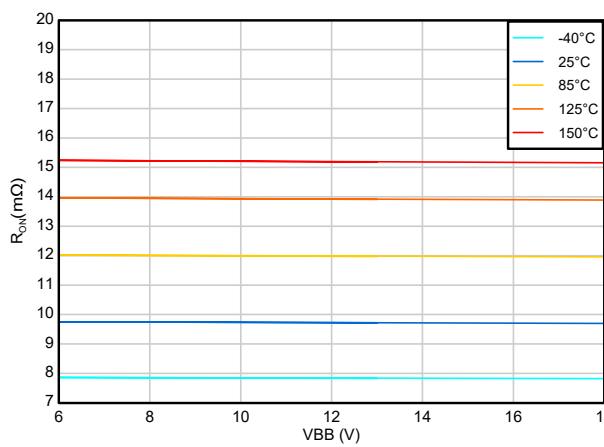


Figure 6-4. On-resistance (R_{ON}) vs VBB

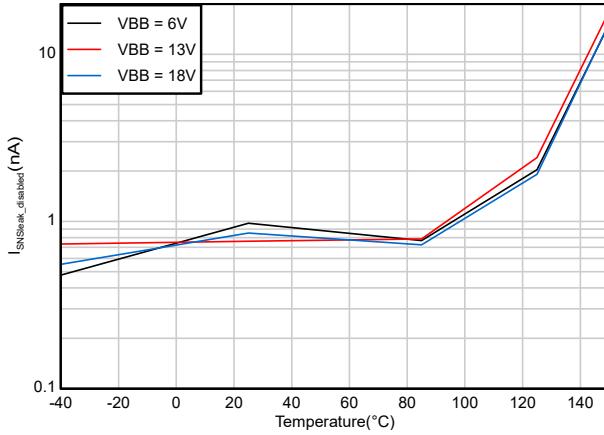


Figure 6-5. I_{SNS} leakage with Diagnostics disabled vs Temperature

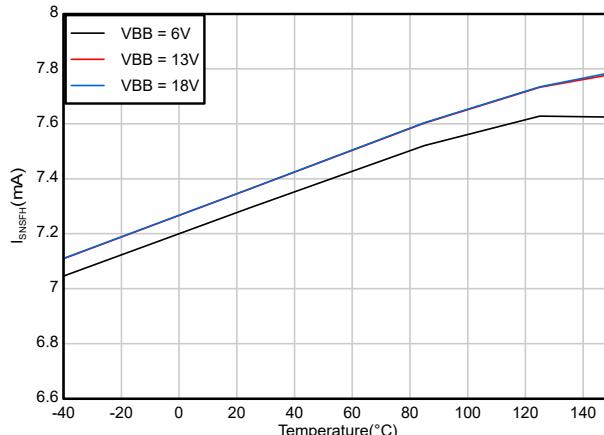


Figure 6-6. I_{SNS} fault high-level current vs Temperature

6.8 Typical Characteristics (continued)

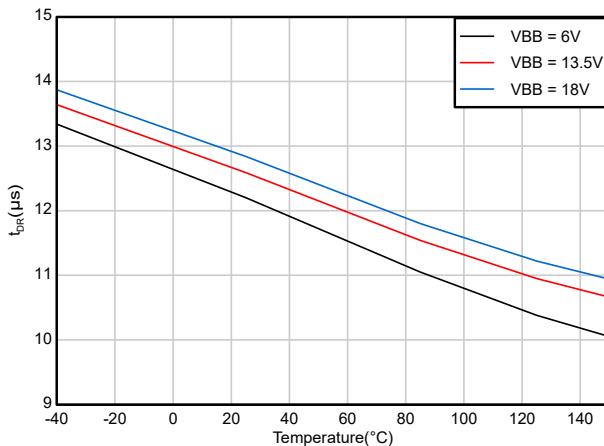


Figure 6-7. Channel Turn-on Delay Time (t_{DR}) vs Temperature

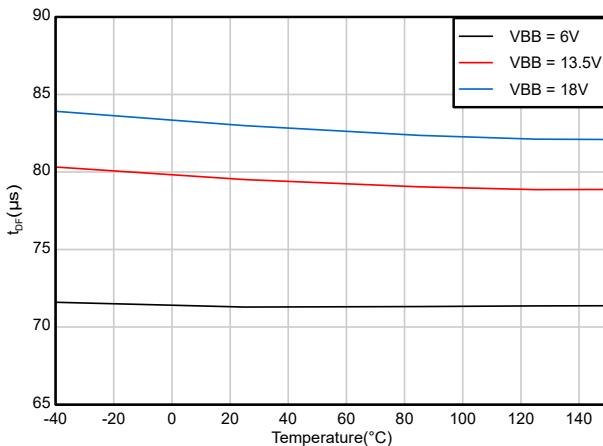


Figure 6-8. Channel Turn-off Delay Time (t_{DF}) vs Temperature

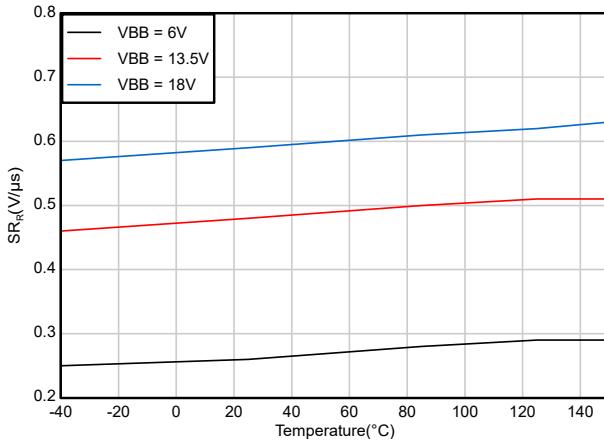


Figure 6-9. VOUT Rising Slew Rate (SR_R) vs Temperature (P, M version)

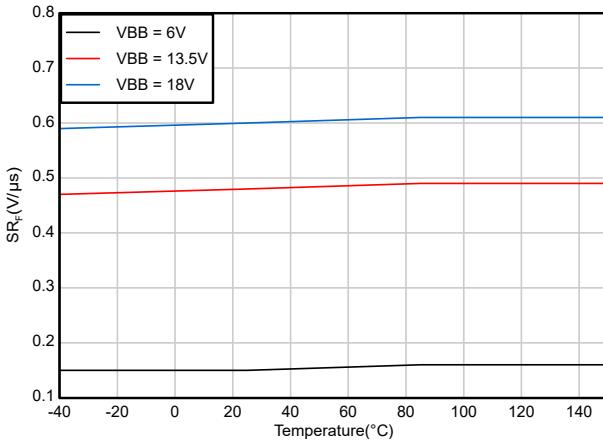


Figure 6-10. VOUT Falling Slew Rate (SR_F) vs Temperature (P, M version)

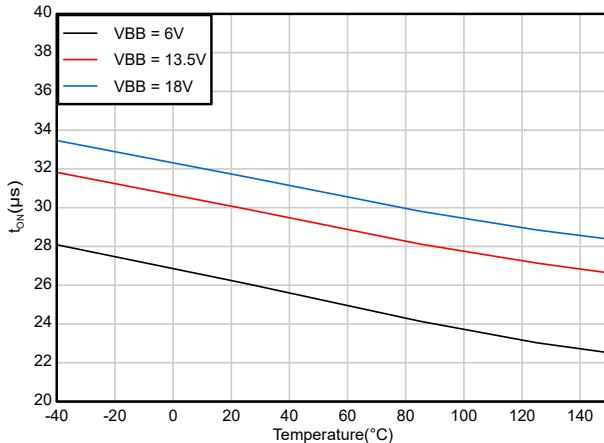


Figure 6-11. Channel Turn-on Time (t_{ON}) vs Temperature

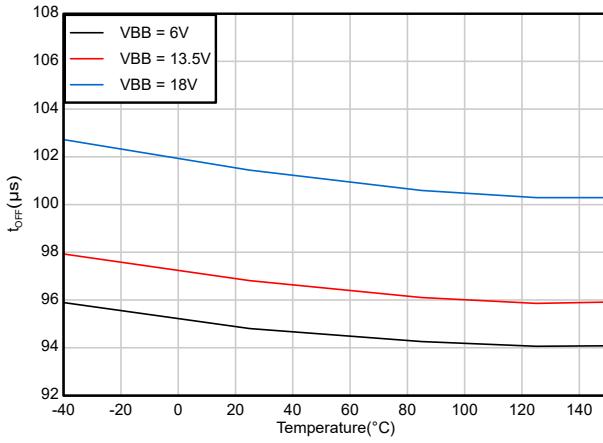


Figure 6-12. Channel Turn-off Time (t_{OFF}) vs Temperature

6.8 Typical Characteristics (continued)

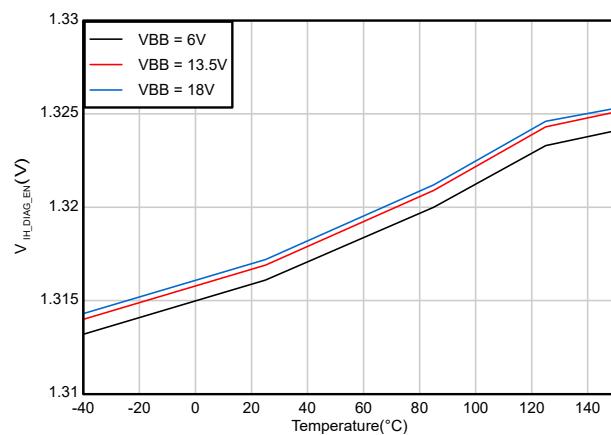


Figure 6-13. DIAG_EN Input Voltage High Level vs Temperature

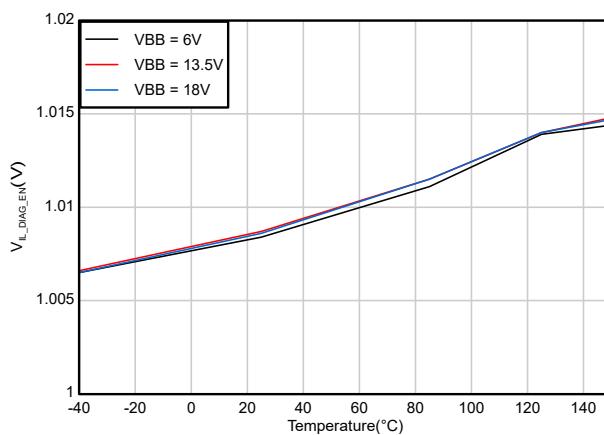


Figure 6-14. DIAG_EN Input Voltage Low Level vs Temperature

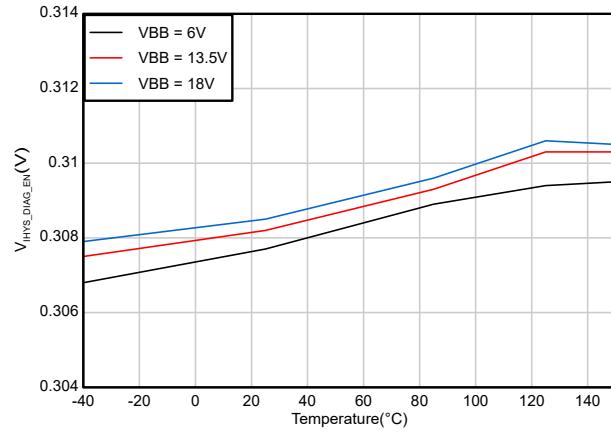


Figure 6-15. DIAG_EN Input Voltage Hysteresis vs Temperature

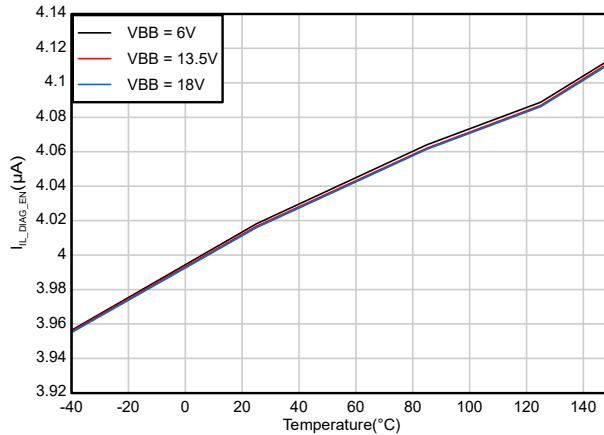


Figure 6-16. DIAG_EN Input Current Low Level vs Temperature

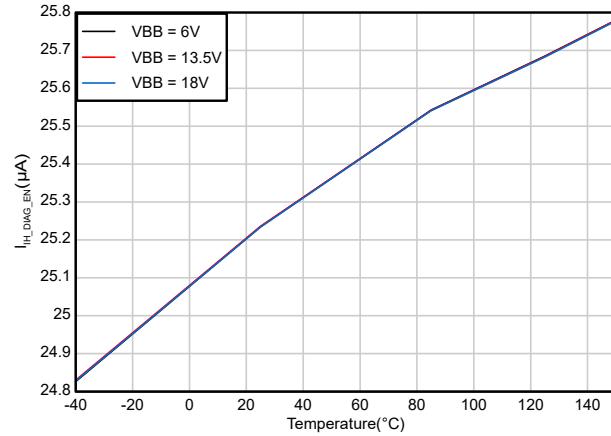


Figure 6-17. DIAG_EN Input Current High Level vs Temperature

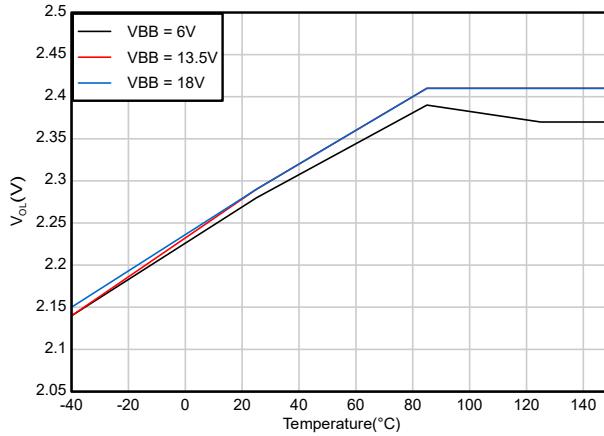


Figure 6-18. Open-Load Detection Voltage (V_{OL}) vs Temperature

6.8 Typical Characteristics (continued)

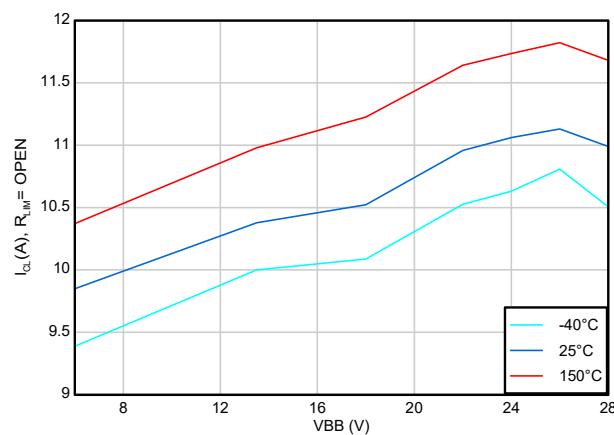


Figure 6-19. Current Limit Regulation Level (I_{CL}) vs V_{BB} , $R_{LIM} = OPEN$

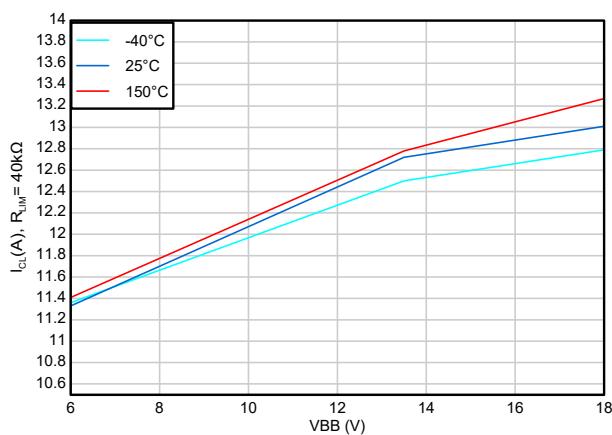


Figure 6-20. Current Limit Regulation Level (I_{CL}) vs V_{BB} , $R_{LIM} = 40k\Omega$

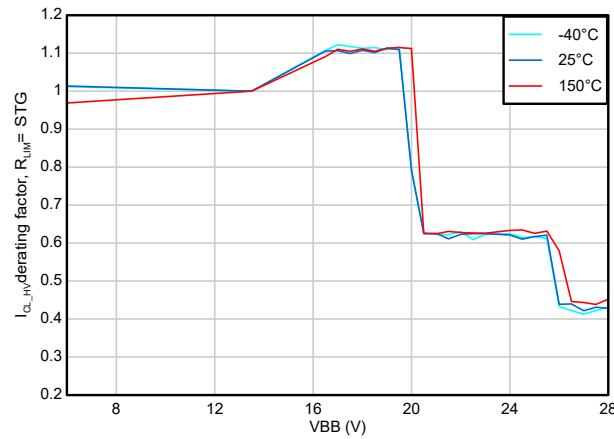


Figure 6-21. Current Limit Derating factor (I_{CL_HV}) vs V_{BB} , $R_{LIM} = STG$

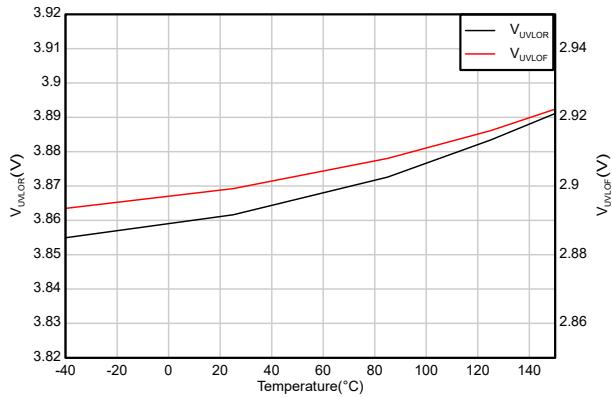


Figure 6-22. Undervoltage Lockout Thresholds (V_{UVLOR} , V_{UVLOF}) vs Temperature

7 Parameter Measurement Information

For reference purposes throughout the data sheet, current directions on the respective pins are as shown by the arrows in [Figure 7-1](#). All voltages are measured relative to the ground plane.

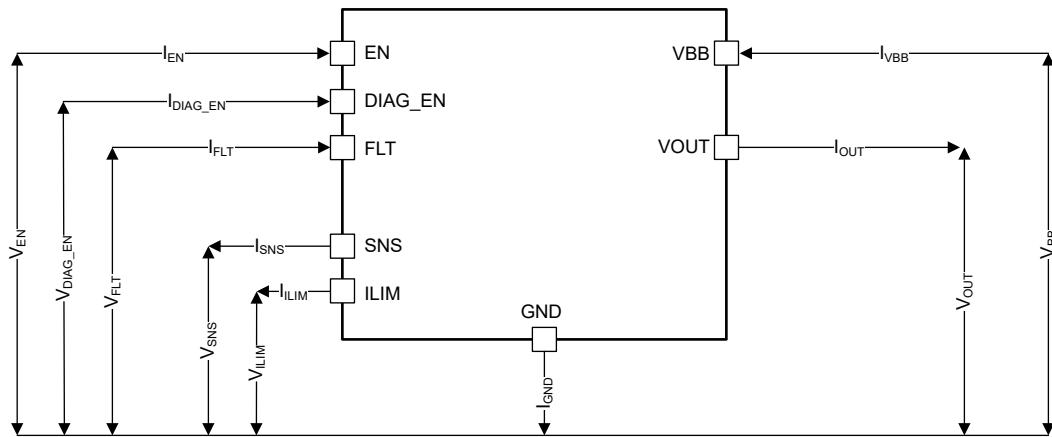
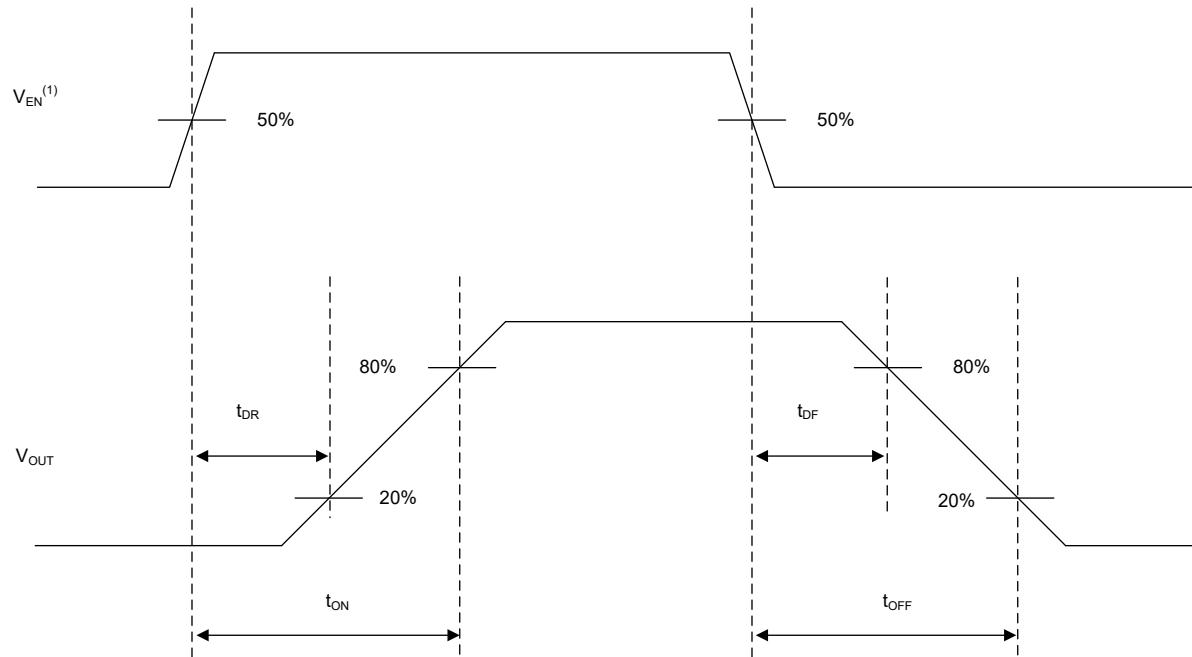


Figure 7-1. Voltage and Current Conventions



Rise and fall time of VEN is 100 ns.

Figure 7-2. Switching Characteristics Definitions

8 Detailed Description

8.1 Overview

The TPS1HC08-Q1 is a single-channel, fully-protected, high side power switch with integrated NMOS power FET and charge pump. Full diagnostics and high-accuracy current-sense features enable intelligent control of the load. The device offers two pins to support both digital status and analog current-sense output. The current-sense output can be set to high-impedance state when diagnostics are disabled, which can enable multiplexing of the MCU analog interface between multiple devices.

The device has dedicated logic pin to enable the FET and a separate DIAG_EN pin to enable the diagnostic output. With diagnostics enabled, the analog current sense is output on the SNS pin. The device also implements a global FLT pin with an open-drain structure, to be used as an interrupt to the MCU. When a fault condition occurs, the pin is pulled down to GND. An external pullup is required to match the microcontroller supply level.

High-accuracy current sensing allows for better real-time monitoring and more-accurate diagnostics without additional in-line calibration. A current mirror is used to source $1 / K_{SNS}$ of the load current, which is reflected as voltage across a resistor on the SNS pin. The SNS pin can also report a fault by sourcing a current of I_{SNSFH} out of the SNS pin. During fault the SNS pin voltage is represented by $I_{SNSFH} \times R_{SNS}$. If this voltage violates the acceptable voltage range of the MCU ADC, an external Zener diode or resistor divider on the SNS pin has to be connected.

The device also offers a programmable current-limit function which greatly improves the reliability of the whole system by clamping the inrush current effectively at start-up when charging large capacitances or during short-circuit conditions. The high-accuracy current limit of the device can be set using an external resistor between 10A to 25A. The device also offers current limit settings with and without thermal regulation. The thermal regulated current limit can be useful when charging large capacitors at startup. The current limit setting without thermal regulation is useful for loads such high motor stall currents or bulb loads.

A voltage clamp is built in to address switching off the energy of inductive loads, such as relays, solenoids, pumps, motors, and so forth. With the benefits of process technology and excellent IC layout, the TPS1HC08-Q1 device can achieve excellent power dissipation capacity, which can help save the external free-wheeling circuitry in most cases. For more details, see Inductive-Load Switching-Off Clamp.

The TPS1HC08-Q1 device can be used as a high side power switch for a wide variety of resistive, inductive, and capacitive loads, including bulbs, LEDs, relays, solenoids, and heaters.

8.2 Functional Block Diagram

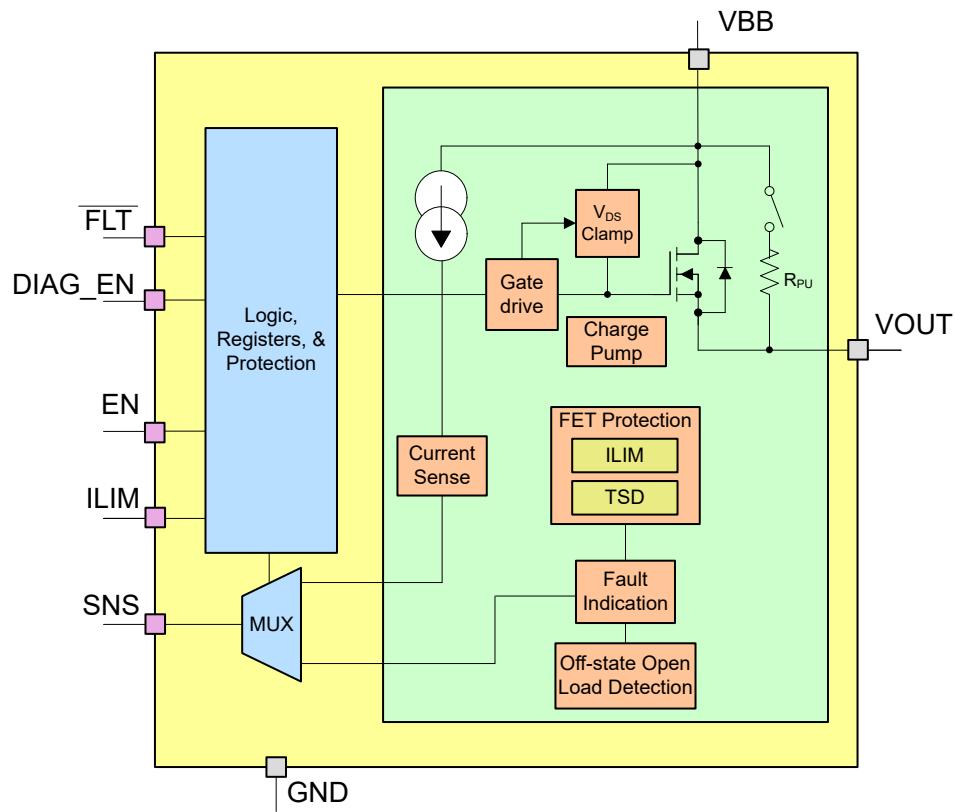


Figure 8-1. Functional Block Diagram

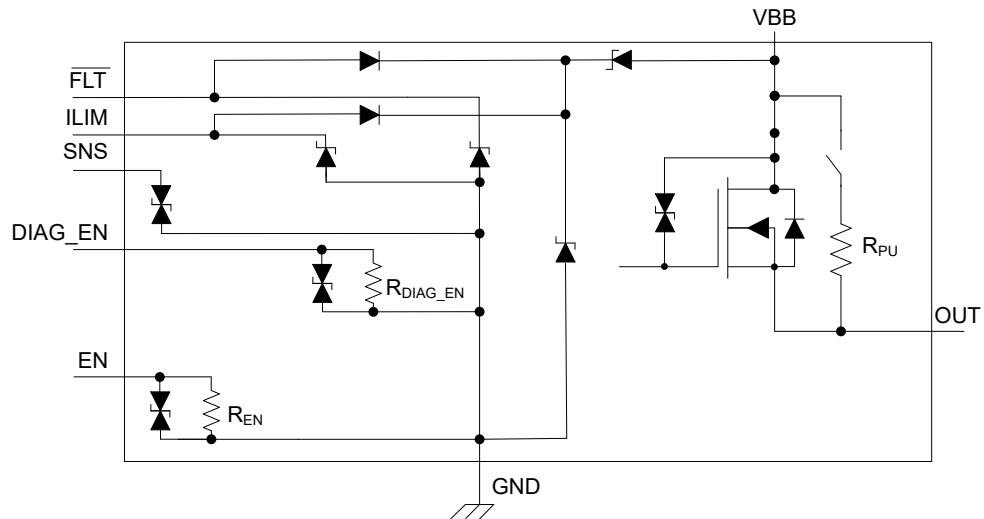


Figure 8-2. Internal Diodes Diagram

The above figure shows the internal diodes structure of the device. There are back-to-back diodes connected between GND pin and low voltage IO pins to provide voltage clamp along with the internal pulldown resistor to keep pins in known state. The **FLT** and **ILIM** pins have internal protection structure to withstand voltage up to **V_{BB}**, making it robust against adjacent pin short. A drain-to-source clamp structure, comprising back-to-back zener and diode, is also implemented across the power switch to protect against inductive energy demagnetisation.

8.3 Feature Description

8.3.1 Input Voltage Thresholds

The device has below input voltage thresholds:

- VBB undervoltage lockout thresholds (V_{UVLOR} , V_{UVLOF}) determines device turn on and off voltages.
- VBB detection 1 thresholds (V_{DET1}) determines device VDS clamp voltage (V_{clamp}) switching and I_{CL} and I_{CB} foldback across VBB.
- VBB detection 2 thresholds (V_{DET2}) determines I_{CL} and I_{CB} foldback across VBB.
- VBB high voltage wakeup thresholds (V_{HV_R} , V_{HV_F}) determines device transition from standby to sleep state. In case V_{HV_R} threshold value is higher than (V_{DET1} or V_{DET2}) rising threshold, the V_{HV_R} threshold also determines the VDS clamp voltage (V_{clamp}) switching.

8.3.2 Accurate Current Sense

The high-accuracy current-sense function allows a better real-time monitoring effect and accurate diagnostics without further calibration. A current mirror is used to source $1 / K_{SNS}$ of the load current, flowing out to the external resistor between the SNS pin and GND, and reflected as voltage on the SNS pin.

K_{SNS} is the ratio of the output current and the sense current. The accuracy values of K_{SNS} quoted in the electrical characteristics do take into consideration temperature and supply voltage. Each device is internally calibrated while in production, so post-calibration by users is not required.

The sense resistor value, R_{SNS} , can be chosen to maximize the range of currents needed to be measured by the system. The R_{SNS} value must be chosen based on application need. The minimum R_{SNS} value is bounded by the ADC minimum acceptable voltage, $V_{ADC,min}$, for the minimum load current needed to be measured by the system, $I_{LOAD,min}$. The maximum R_{SNS} value is bounded by the ADC maximum acceptable voltage, $V_{ADC,max}$, for the I_{SNSFH} (check [Electrical Characteristics](#) for the minimum specification) during fault condition. The SNS pin current during fault condition, I_{SNSFH} should be significantly higher than the SNS pin current at maximum load current ($I_{LOAD,max}$), to provide sufficient headroom voltage (V_{HR}) to determine difference between the maximum readable current and a fault condition. Use [Equation 1](#) to calculate the value of R_{SNS} without any external zener diode or resistor divider on SNS pin.

$$\frac{(V_{ADC,min} \times K_{SNS})}{I_{LOAD,min}} \leq R_{SNS} \leq \frac{V_{ADC,max}}{I_{SNSFH}} \quad (1)$$

To get better resolution in current sense voltage, an external Zener diode or resistor divider can be connected to the SNS pin to clamp the SNS pin voltage to ADC maximum acceptable voltage, $V_{ADC,max}$ during the fault condition. In this case, user needs to select R_{SNS} resistor to achieve required headroom voltage (V_{HR}) between the maximum readable current and a fault condition. Use [Equation 2](#) to calculate the value of R_{SNS} in this scenario.

$$\frac{(V_{ADC,min} \times K_{SNS})}{I_{LOAD,min}} \leq R_{SNS} \leq \frac{((V_{ADC,max} - V_{HR}) \times K_{SNS})}{I_{LOAD,max}} \quad (2)$$

In some applications, where there is a higher load current range the above applicable boundary equation can only satisfy either the lower or upper bound. In these cases, more emphasis can be put on the lower measurable current values which increases R_{SNS} . Likewise, if the higher currents are of more interest the R_{SNS} can be decreased. In case a GND network is used for reverse polarity protection, the voltage drop across the GND network has to be taken into account to ensure that the SNS pin voltage does not exceed the maximum acceptable ADC voltage.

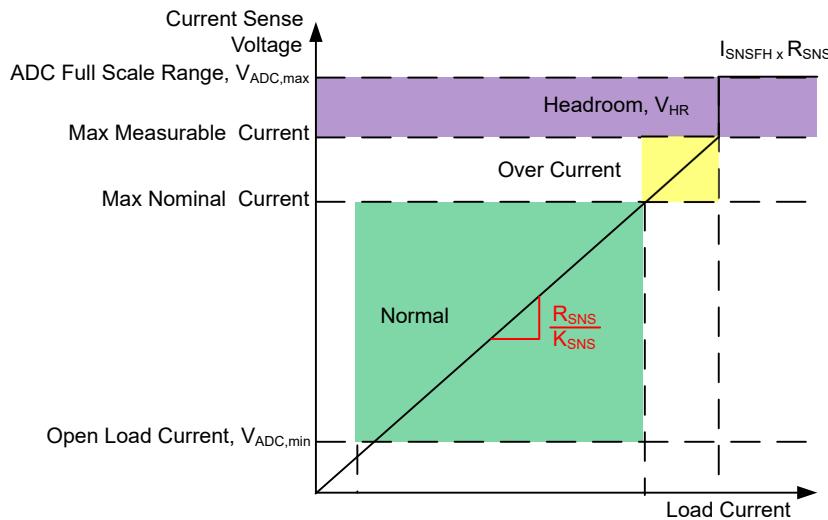


Figure 8-3. Voltage Indication on the Current-Sense Pin

The maximum current the system wants to read, $I_{LOAD,max}$, must be below the current-limit threshold because after the current-limit threshold is tripped the SNS pin current goes to I_{SNSFH} . Figure 8-4 shows the SNS pin behavior for 5A load step on the device with $1\text{k}\Omega R_{SNS}$

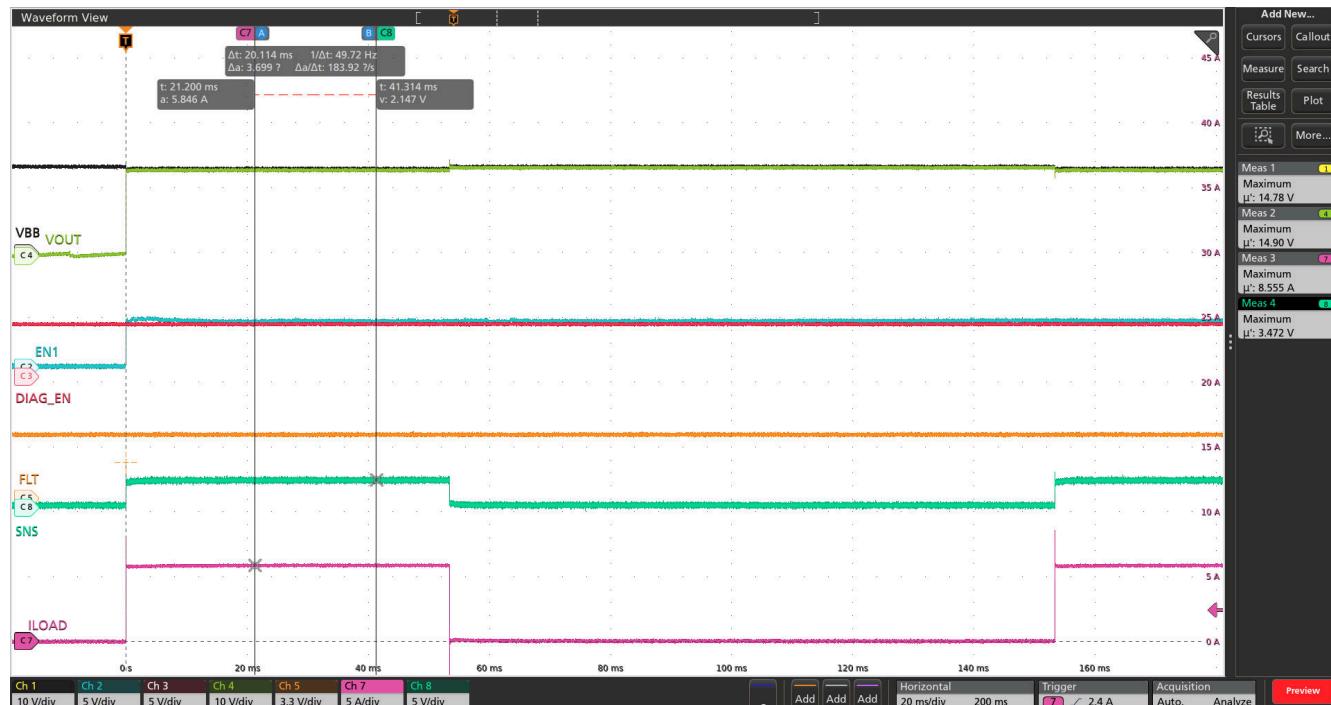


Figure 8-4. SNS Pin Voltage with Varying Load Current ($R_{SNS} = 1\text{k}\Omega$)

8.3.2.1 SNS Response Time

Some applications can operate with a high frequency, low duty cycle PWM. Such applications require fast settling of the SNS output. For example, a 250Hz, 5% duty cycle PWM has an on-time of only 200 μs . The microcontroller ADC can sample the SNS signal after the defined settling time. The following figures shows response time of SNS signal with EN and DIAG_EN being pulled high respectively. The fast response time of the device SNS signal easily allows current sense read by ADC in such applications.

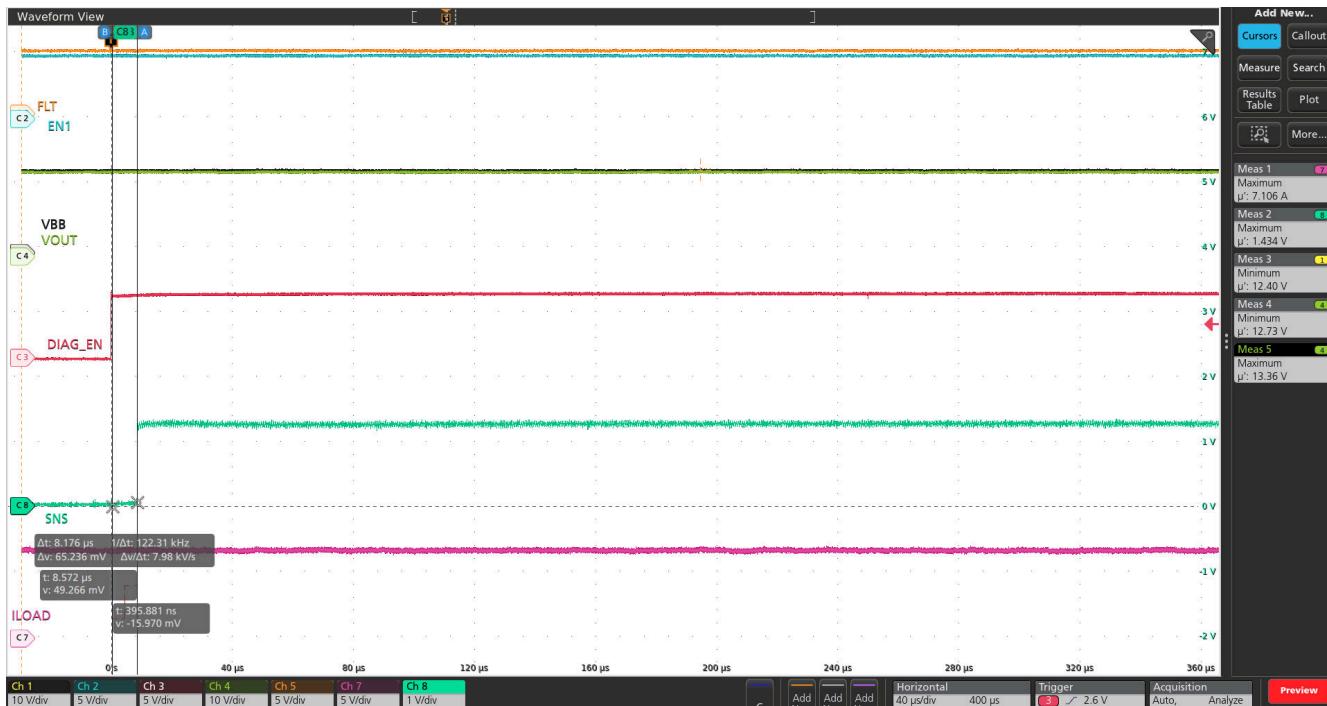


Figure 8-5. SNS Response Time with **DIAG_EN** (t_{SNSION1})



Figure 8-6. SNS Response Time with **EN** (t_{SNSION3})

Note

Rise and fall times of control signals are 100ns. Control signals include: EN and **DIAG_EN**.

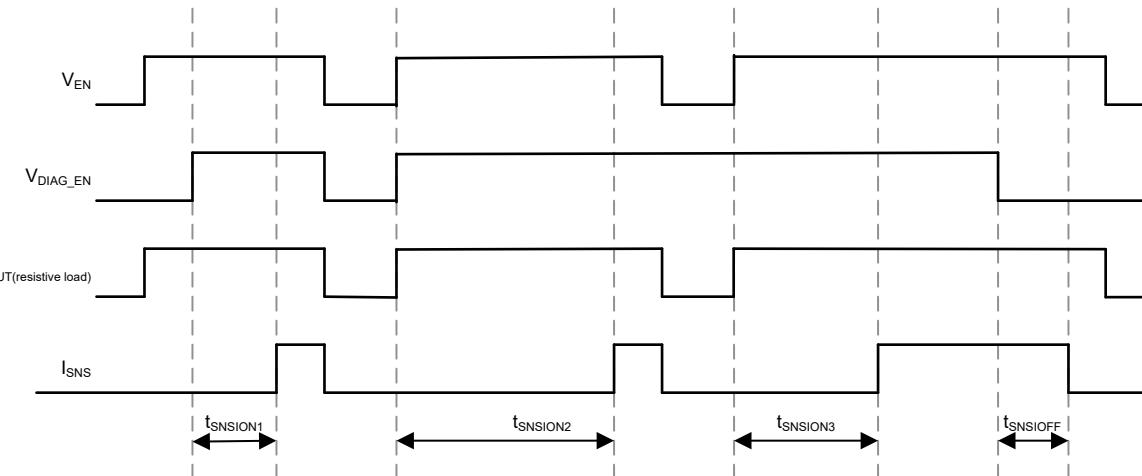


Figure 8-7. SNS Settling Time From EN or DIAG_EN

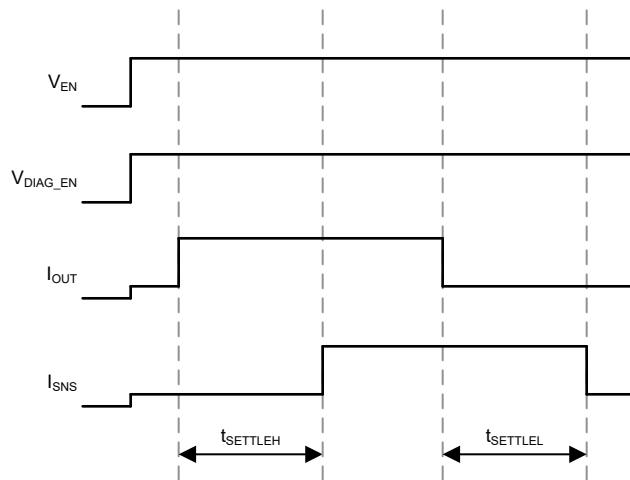


Figure 8-8. SNS Settling Time From Load step

8.3.2.2 SNS Output Filter

Due to the internal architecture, the SNS pin signal has a ripple component at a frequency of approximately 1.6MHz. Based on the R_{SNS} value, appropriate C_{SNS} can be connected on SNS pin to filter out this ripple component and reduce the peak-to-peak ripple of the SNS pin voltage. **Table 8-1** shows the typical peak-to-peak ripple voltage values with and without C_{SNS} on SNS pin. The designer can select a C_{SNS} capacitor value based on system requirements. A larger value can provide improved filtering. A smaller value can allow for faster transient response. For example, the 150pF C_{SNS} with 1k Ω R_{SNS} adds 750ns (5RC) to the settling time of SNS voltage.

Table 8-1. SNS Ripple (Typical measurement at $V_{BB} = 13.5V$, $I_{LIM} = OPEN$, $T_A = 25^\circ C$)

| R_L (Load resistor) | R_{SNS} | C_{SNS} | PEAK-TO-PEAK RIPPLE WITHOUT C_{SNS} (mV) | PEAK-TO-PEAK RIPPLE WITH C_{SNS} (mV) |
|-----------------------|-------------|-----------|--|---|
| 10 Ω | 1k Ω | 150pF | 105mV | 50mV |
| 2.2 Ω | 1k Ω | 150pF | 157mV | 55mV |

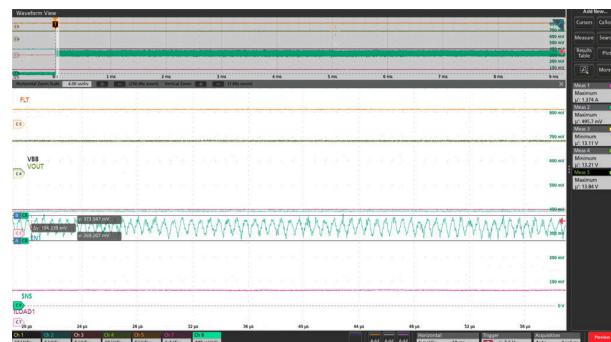


Figure 8-9. SNS Pin Ripple Without C_{SNS} at $V_{BB} = 13.5V$, $I_{LIM} = OPEN$, $R_L = 10\Omega$, $R_{SNS} = 1k\Omega$ and $T_A = 25^\circ C$



Figure 8-10. SNS Pin Ripple With $150pF C_{SNS}$ at $V_{BB} = 13.5V$, $I_{LIM} = OPEN$, $R_L = 10\Omega$, $R_{SNS} = 1k\Omega$ and $T_A = 25^\circ C$

8.3.2.3 Multiplexing of Current Sense Across Devices

Figure 8-11 shows SNS pin sharing across two devices using common R_{SNS} resistor. Similarly multiple devices can be configured to share SNS pin. When $DIAG_EN$ is set high, the selected device current sense output can be enabled using associated EN signal, and a current proportional to the load current (I_{LOAD}/K_{SNS}) flows out of the SNS pin through the external sense resistor to ground. This current is reflected as a voltage that can be measured by an MCU's ADC input. When $DIAG_EN$ is set low, the SNS pin is placed in a high-impedance (tri-state) condition. This feature allows multiple TPS1HC08-Q1 devices to share the same sense resistor and ADC input pin, as only one device can drive the SNS pin at any given time.

K_{SNS} is designed such that SNS pin current at maximum rated load current is same across the device family. This allows for devices with different current ratings to be multiplexed by having same R_{SNS} resistor and ADC full scale range.

When implementing current sense multiplexing across devices, the disabled state SNS pin leakage current ($I_{SNS,leak_disabled}$) from devices (with $DIAG_EN$ set to low) introduces measurement error when reading the current from an active device. For TPS1HC08-Q1 device, the disabled state SNS pin leakage is very low (typical few nA), allowing higher count of devices to be multiplexed.

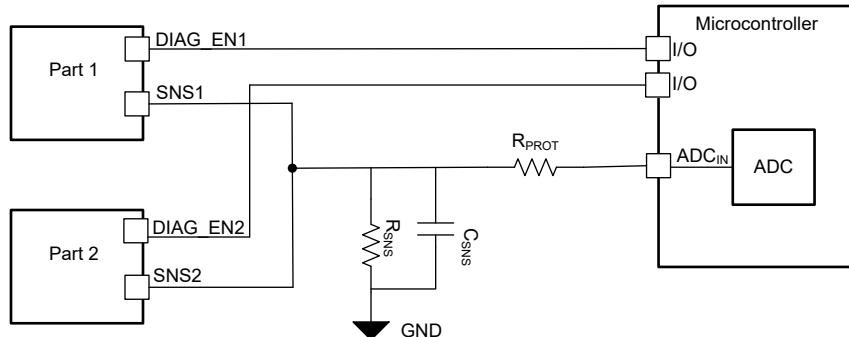


Figure 8-11. SNS Multiplexing Across Multiple Devices

8.3.3 Overcurrent Protection

The TPS1HC08-Q1 provides thermal shutdown and current limiting protection during overcurrent events to protect the internal power MOSFET. These protection functions are enabled when the device is in the active state. The current limit fault gets asserted at about 80% ($I_{CL_FLT_Trip}$) of set current limit value.

8.3.3.1 Adjustable Current Limit

The TPS1HC08-Q1 offers a high accuracy, adjustable current which enables higher reliability and provides protection to the power supply during a short circuit or power up with large capacitance. An adjustable current

limit can also save system costs by reducing PCB traces, connector size, and the capacity of the preceding power stage by setting the current limit at a lower level.

The current limit of the device can be adjusted via an external resistor on the ILIM pin. The device provides ILIM settings with a thermal regulated current limit which adjusts the current limit level based on the relative temperature of the FET and the controller. This avoids fast heating of the FET and delays the trigger of relative thermal shutdown, which enables the device to charge up large capacitors at startup. With ILIM pin shorted to GND, the device current limit can be configured without thermal regulation where the device limits the current at the set ILIM value. **Table 8-2** details the different settings that are possible based on the ILIM pin configuration.

Table 8-2. Current Limit Settings Through ILIM Pin

| R_{LIM} VALUE on ILIM pin | TYP $I_{CL} = K_{CL} / R_{LIM}$ | THERMAL REGULATION |
|---|---------------------------------|--------------------|
| ILIM = GND or $R_{LIM} < 20\text{k}\Omega$ | Maximum setting of 25A | Disabled |
| $R_{LIM} = 20\text{k}\Omega$ | 25A | Enabled |
| $20\text{k}\Omega < R_{LIM} < 50\text{k}\Omega$ | $I_{CL} = K_{CL} / R_{LIM}$ | Enabled |
| $R_{LIM} = 50\text{k}\Omega$ | 10A | Enabled |
| ILIM = Open or $R_{LIM} > 50\text{k}\Omega$ | Minimum setting of 10A | Enabled |

The device also offers a fast-trip circuit breaker function which is used when a short-circuit occurs while a channel is enabled which is also known as a hot-short. Once the I_{CB} threshold is reached, the device quickly turns off the channel to protect the internal MOSFET. Additionally, the device provides a current limit foldback function at higher voltages to help protect the internal power MOSFET during high V_{DS} events.

The different overcurrent events that can occur in a system are:

- hot-short
- enable into short
- current overload (slow creep)

A hot-short occurs when the device is enabled and a short-circuit condition is applied to the output of the device. Enabling in to short occurs when there is already a short on the output of the MOSFET and the device is enabled into the short-circuit condition. Current overload or also known as slow creep can occur if there is a slow rising overcurrent event at the output.

The following sections describe how the current limiting with thermal regulation and without thermal regulation work along with the circuit breaker and thermal shutdown functions to help protect against the various overcurrent conditions that can occur.

8.3.3.1 Current Limiting With Thermal Regulation

Based on the ILIM setting the device can be configured to limit current with thermal regulation. The thermal regulation works by monitoring the relative temperature of the MOSFET ($T_{J,FET}$) to the temperature of controller ($T_{J,CONTROLLER}$) and reducing the current limit based on the relative temperature.

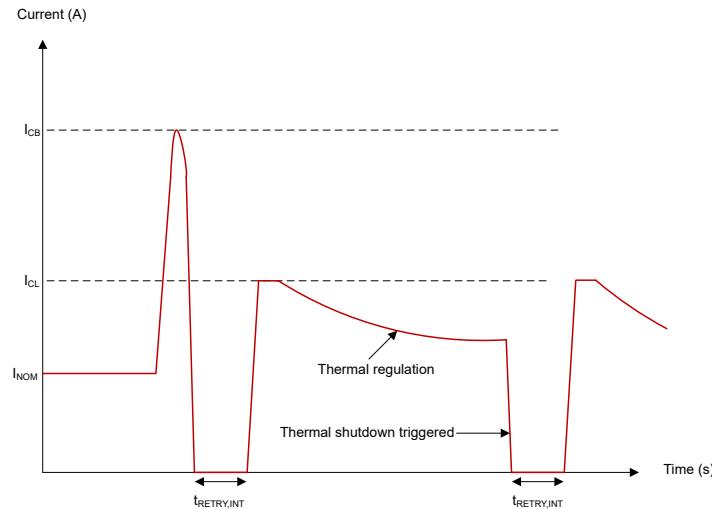


Figure 8-12. On-State Short-Circuit Behavior with Thermal Regulation

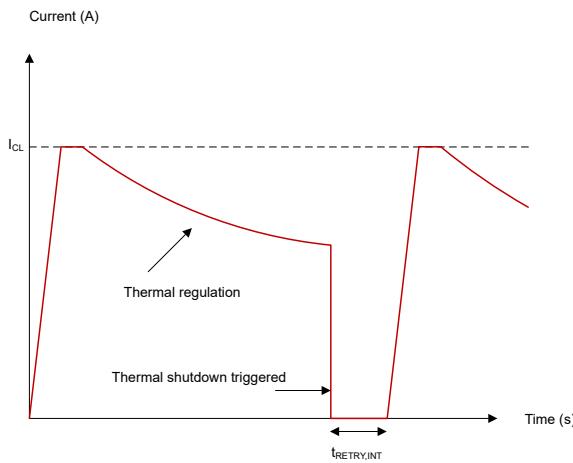


Figure 8-13. Enable Into Short with Thermal Regulation

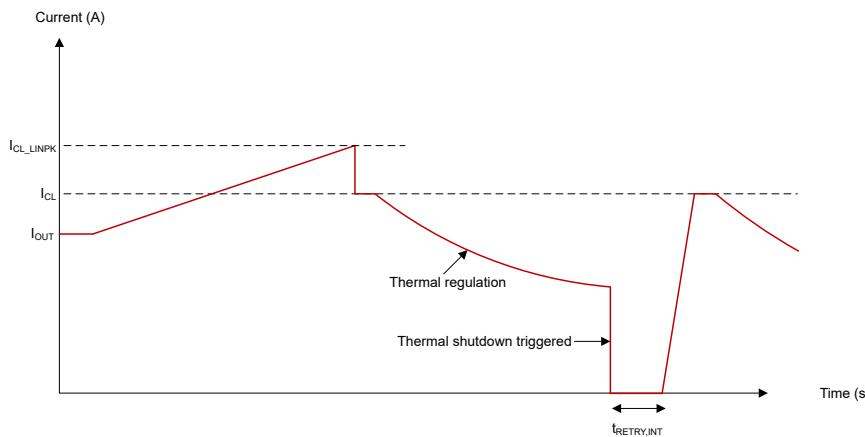


Figure 8-14. Overload Behavior (current creep) with Thermal Regulation

8.3.3.1.2 Current Limiting With No Thermal Regulation

Based on the ILIM setting, the device can be configured to limit current without thermal regulation. The device limits the current based on the setting at the ILIM pin. Applications where this can be used are bulb loads and motor loads with high inrush currents.

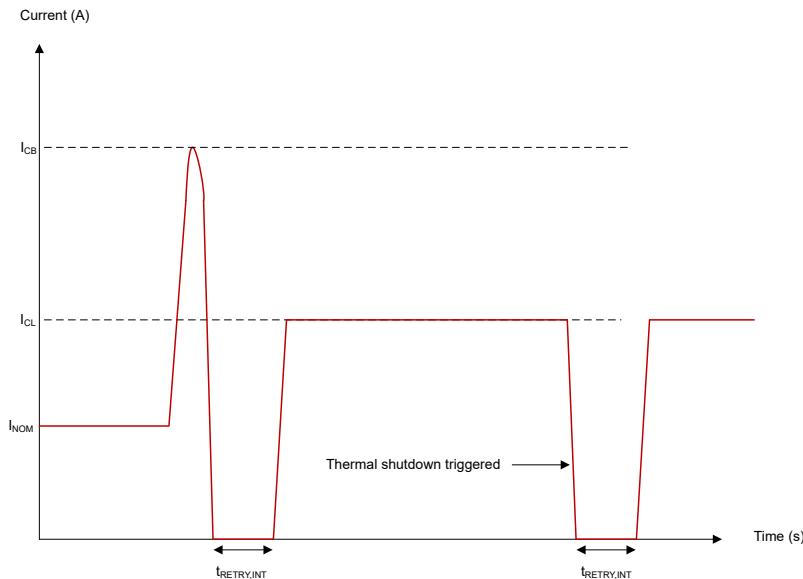


Figure 8-15. On-State Short-Circuit Behavior with No Thermal Regulation

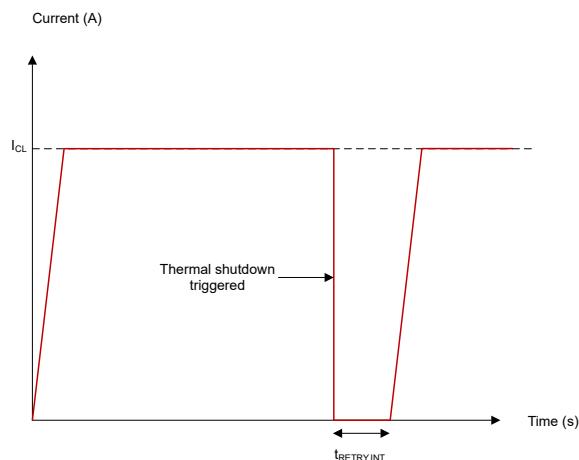


Figure 8-16. Enable Into Short with No Thermal Regulation

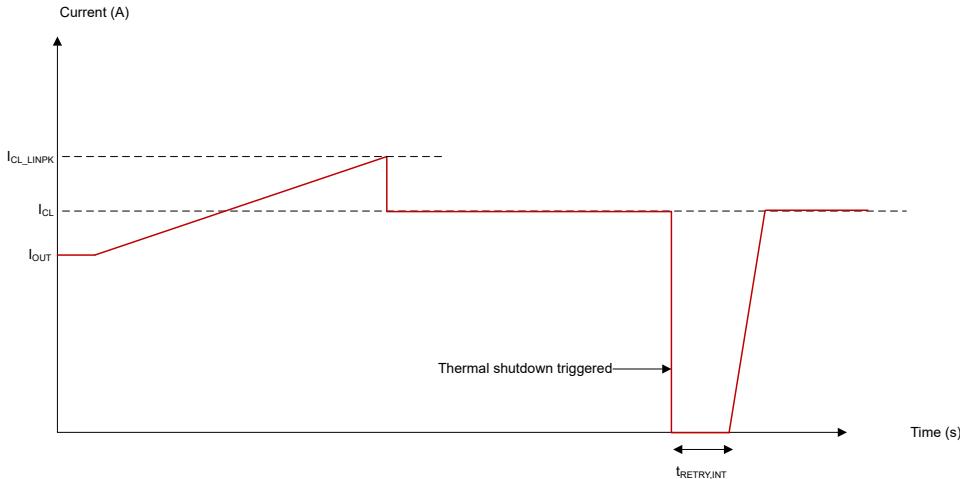


Figure 8-17. Overload Behavior (current creep) with No Thermal Regulation

8.3.3.1.3 Current Limit Foldback

To protect the MOSFET from overcurrent at high V_{DS} voltages the device offers a current limit foldback mechanism for higher current limit. If the V_{BB} voltage is greater than V_{DET1} then the current limit folds back to 1/2 of current limit setting. If the V_{BB} voltage is above V_{DET2} , the current limit folds back 1/3 of current limit setting. [Figure 6-21](#) shows device current limit foldback behavior across V_{BB} voltage.

8.3.3.1.4 Current Limit Accuracy

The adjustable current limit of the device can be set using [Equation 3](#) for valid range of R_{LIM} resistor mentioned in [Table 8-2](#).

$$R_{LIM} = K_{CL} / I_{CL} \quad (3)$$

The accuracy of current limit depends on R_{LIM} resistor tolerance and K_{CL} parameter variation (K_{CL_min} , K_{CL_max}) mentioned in [Electrical Characteristics](#). For example, for 33.2k Ω R_{LIM} resistor with 1% tolerance, the I_{CL} can be calculated as below.

$$I_{CL}(\max) = \min((K_{CL_max} / R_{LIM_min}), I_{CB})$$

$$I_{CL}(\min) = K_{CL_min} / R_{LIM_max}, \text{ where } R_{LIM_max} = 1.01 * R_{LIM}$$

For R_{LIM} GND and OPEN case, K_{CL} parameter variation contributes to I_{CL} variation.

The device current limit variation in fold-back state is same as nominal current limit variation and can be determined using above method. Device I_{CB} also folds back similar to I_{CL} across V_{BB} based on V_{DET1} and V_{DET2} thresholds.

8.3.3.2 Thermal Shutdown

The device includes a temperature sensor on the power FET and within the controller portion of the device to monitor the temperature of the FET ($T_{J,FET}$) and the temperature of the controller ($T_{J,CONTROLLER}$). There are two cases that the device considers to be a thermal shutdown fault:

- **Relative thermal shutdown (T_{REL}):** $T_{J,FET} - T_{J,CONTROLLER} > T_{REL}$
- **Absolute thermal shutdown (T_{ABS}):** $T_{J,FET} > T_{ABS}$

If either the above faults occur, the switch is turned off.

8.3.3.2.1 Relative Thermal Shutdown

A relative thermal shutdown event can occur when there is a large peak power event such as a short-to-ground event where the FET temperature ($T_{J,FET}$) quickly rises relative to the controller temperature ($T_{J,CONTROLLER}$). Once the relative temperature ($T_{J,FET} - T_{J,CONTROLLER}$) exceeds T_{REL} the channel is turned off.

8.3.3.2.2 Absolute Thermal Shutdown

An absolute thermal shutdown occurs when the FET temperature ($T_{J,FET}$) rises above T_{ABS} . This can occur when a channel is subjected to long durations of overcurrent such as a permanent short use case. Once the FET temperature ($T_{J,FET}$) exceeds T_{ABS} the channel is turned off.

8.3.4 Retry Protection Mechanism From Thermal Shutdown

When a thermal shutdown occurs, the device shuts off and implements a retry protection mechanism to improve system reliability. Figure 8-19 explains how the device responds depending on the load current and duration of the overcurrent event.

For load current lower than current limit, device enters into infinite thermal shutdown retry cycles phase until the device recovers from the thermal shutdown fault. In this case, the device turn off time depends on cooling time needed with inherent 200 μ s delay.

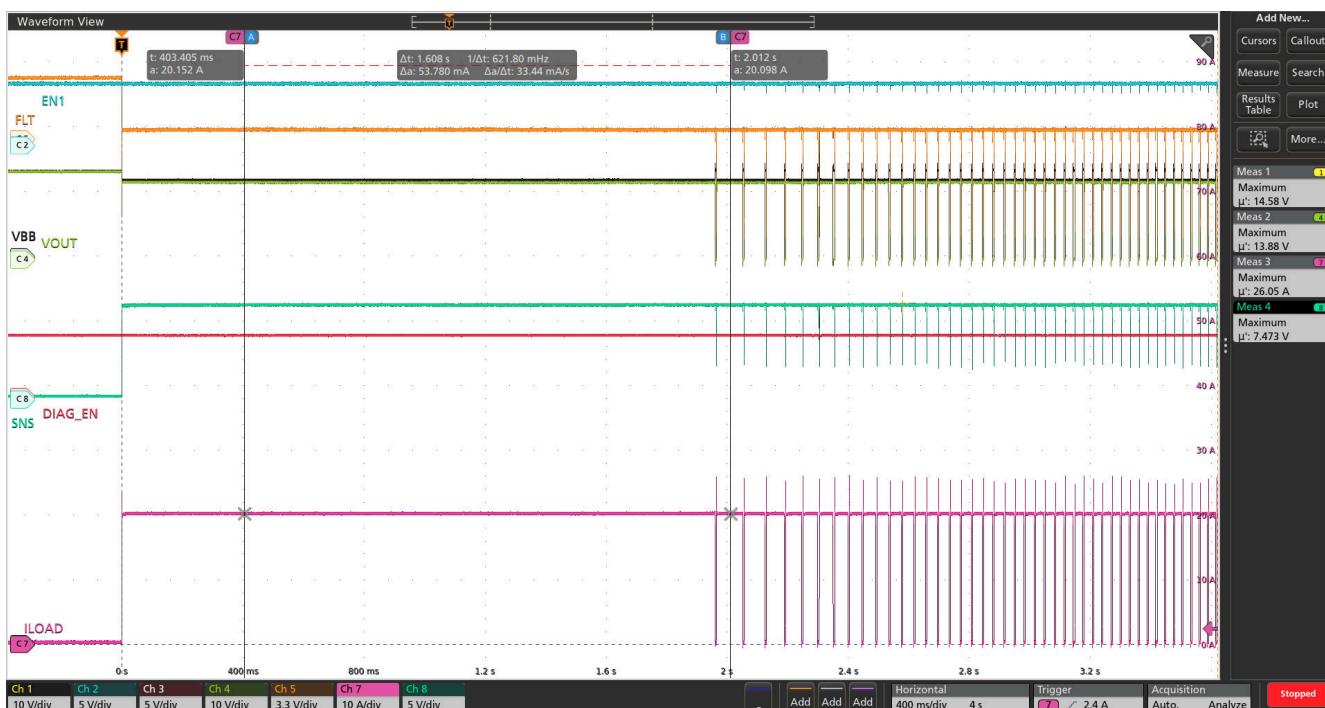


Figure 8-18. Device Enters Into Infinite Thermal Shutdown Retry Phase For Load Current (20A electronic load) Less Than Current Limit (ILIM = GND)

For load current higher than current limit, device implements a finite retry cycles phase protection mechanism based on the duration of the overcurrent event, that can trigger when either of the below fault conditions occur:

1. **Absolute thermal shutdown (T_{ABS}):** $T_{J,FET} > T_{ABS}$
2. **Relative thermal shutdown (T_{REL}):** $T_{J,FET} - T_{J,CONTROLLER} > T_{REL}$
3. **Circuit Breaker (I_{CB}):** A fast-trip protection that triggers when current exceeds the I_{CB} threshold during a hot-short condition. This quickly turns off the channel to protect the internal MOSFET.

The finite retry cycles phase protection mechanism has below durations:

1. **Initial Retry Window ($t < t_{RETRY_WINDOW}$):**
 - After I_{CB} or thermal shutdown triggers.
 - Retry attempts occur every t_{RETRY_INT} minimum duration.
 - Each retry can start with I_{CB} peak followed by current limit (I_{CL}) peaks.
2. **Extended Overcurrent Window ($t > t_{RETRY_WINDOW}$):**

- Limited to 6 retry attempts.
- First retry cycle happens with minimum $t_{RETRY, EXTD}/2$ duration.
- Successive 5 retry cycles happen with minimum $t_{RETRY, EXTD}$ duration.
- Current peaks are typically limited to I_{CL} .

3. Latch-off Condition:

- After 6 unsuccessful retry attempts.

Table 8-3. Response To Thermal Shutdown

| LOAD CURRENT | CONDITIONS | | MINIMUM RETRY TIME |
|---------------------|-------------------------|-----------------------|--|
| $I_{LOAD} < I_{CL}$ | - | | Infinite retry |
| $I_{LOAD} > I_{CL}$ | $t < t_{RETRY_WINDOW}$ | | $t_{RETRY, INT} = 160\mu s$ (typical) |
| | $t > t_{RETRY_WINDOW}$ | $n_{RETRY, EXTD} < 6$ | $t_{RETRY, EXTD} = 80ms$ (typical) |
| | | $n_{RETRY, EXTD} > 6$ | Latch-off |

In any of the above retry cases the relevant channel restarts when below "restart" conditions are fulfilled.

1. **Temperature Recovery:** the T_{ABS} or T_{REL} to recover below the T_{HYS} level to restart the device.
2. **Retry Window:** For $I_{LOAD} > I_{CL}$, appropriate t_{RETRY_WINDOW} interval must elapse.

In case of $I_{LOAD} > I_{CL}$, if the retry timer has expired and the temperature of T_{ABS} or T_{REL} has not recovered below the T_{HYS} level, the channel does not retry until the temperature falls below the T_{HYS} level. Once a channel latches off due to an extended overcurrent event, the EN pin can be brought from high to low (with minimum pulse duration of about 20us) to reset the FLT and SNS signal. The output of the channel then follows the EN pin after the initial toggle from high to low.

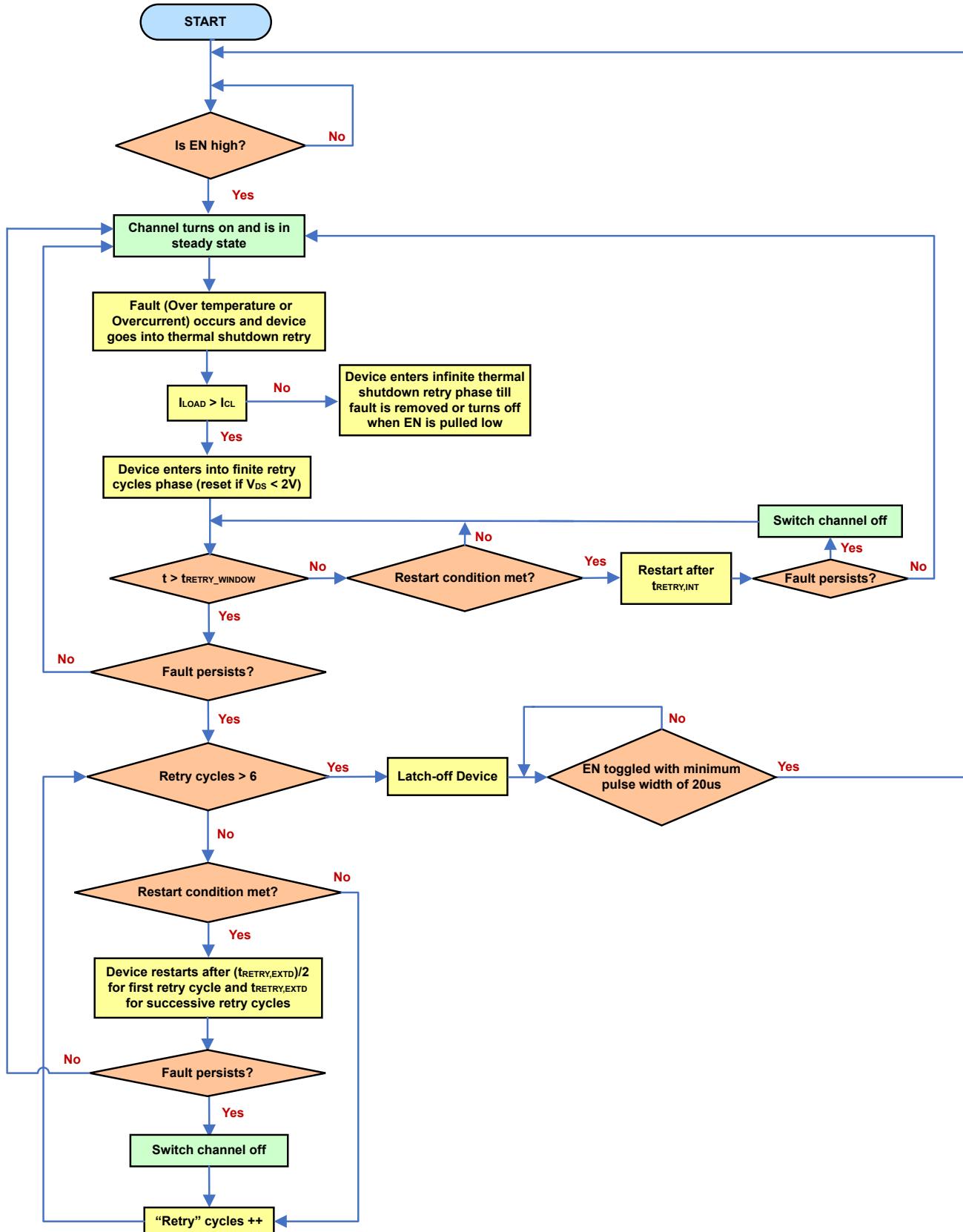


Figure 8-19. Retry Protection Mechanism

The following figures show how the device retries after a hot-short with and without thermal regulation, respectively. When the device experiences a thermal fault and enters the retry cycle, the first current peak in initial retry window reaches I_{CB} threshold, triggering fast trip circuit breaker. Successive current peaks are lower and correspond to set current limit (I_{CL}) value.

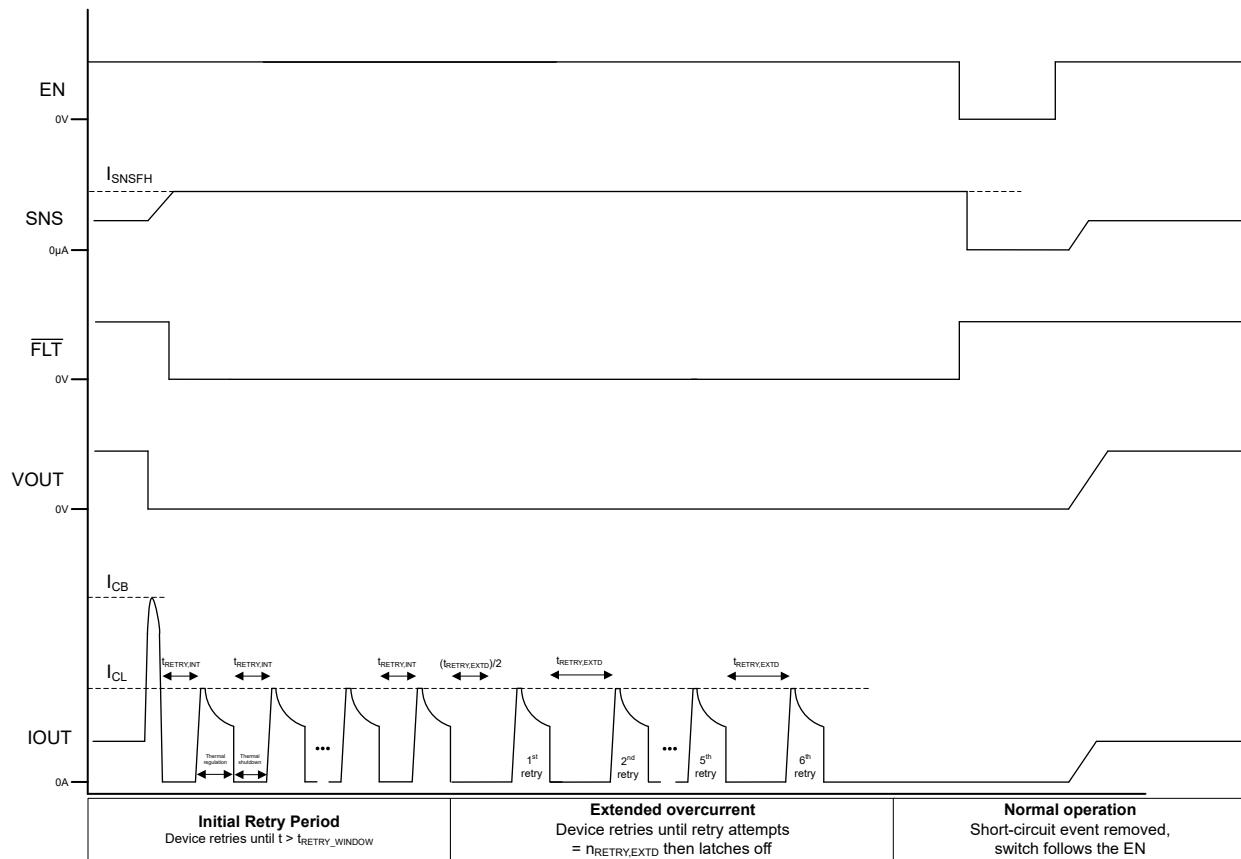


Figure 8-20. Retry Behavior After Hot-Short with Thermal Regulation

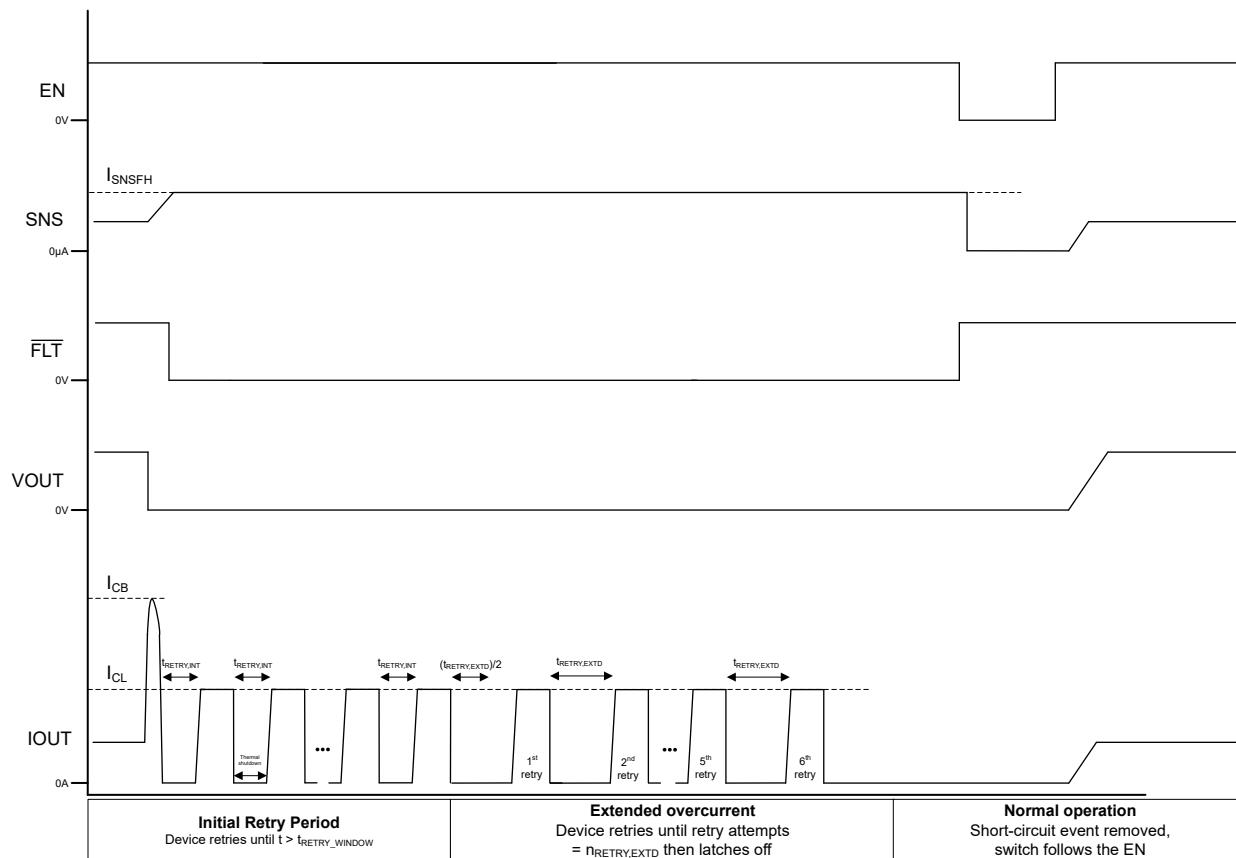


Figure 8-21. Retry Behavior After Hot-Short with No Thermal Regulation

In case the device enters finite retry cycles phase protection mechanism due to overcurrent fault without thermal shutdown fault, the device can stay in thermal regulation in initial retry window and directly enter thermal shutdown retry behavior in extended retry window.

8.3.5 Inductive-Load Switching-Off Clamp

When switching an inductive load off, the inductive reactance tends to pull the output voltage negative. Excessive negative voltage can cause the power FET to break down. To protect the power FET, an internal clamp between drain and source is implemented, namely $V_{DS(\text{clamp})}$.

$$V_{DS(\text{clamp})} = V_{VS} - V_{OUT} \quad (4)$$

During the period of demagnetization (t_{decay}), the power FET is turned on for inductance-energy dissipation. The total energy is dissipated in the high-side switch. Total energy includes the energy of the power supply ($E_{(VS)}$) and the energy of the load ($E_{(load)}$). If resistance is in series with inductance, some of the load energy is dissipated on the resistance.

$$E_{(HSS)} = E_{(VS)} + E_{(load)} = E_{(VS)} + E_{(L)} - E_{(R)} \quad (5)$$

When an inductive load switches off, $E_{(HSS)}$ causes high thermal stressing on the device. The upper limit of the power dissipation depends on the device intrinsic capacity, ambient temperature, and board dissipation condition.

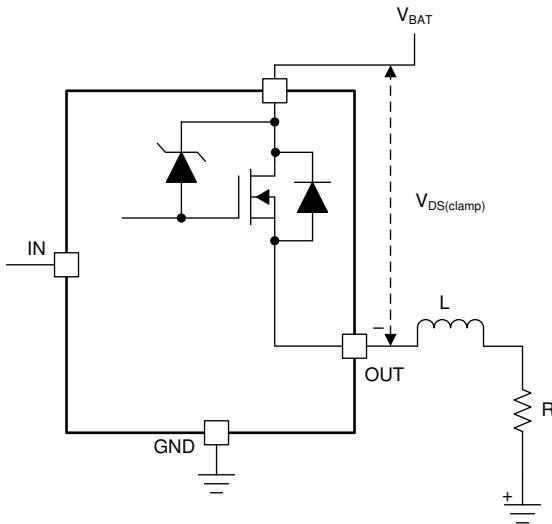


Figure 8-22. Drain-to-Source Clamping Structure

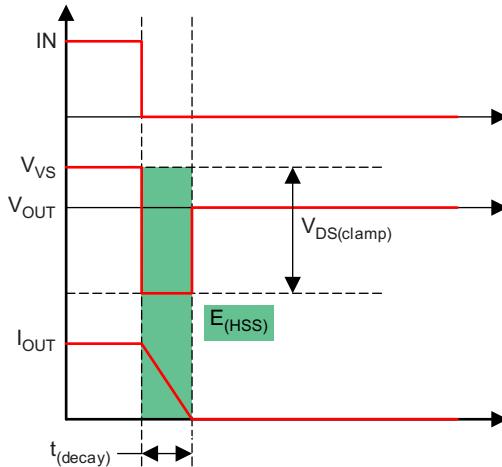


Figure 8-23. Inductive Load Switching-Off Diagram

From the perspective of the high-side switch, $E_{(HSS)}$ equals the integration value during the demagnetization period.

$$\begin{aligned}
 E_{(HSS)} &= \int_0^{t_{(decay)}} V_{DS(\text{clamp})} \times I_{OUT}(t) dt \\
 t_{(decay)} &= \frac{L}{R} \times \ln \left(\frac{R \times I_{OUT(\text{max})} + |V_{OUT}|}{|V_{OUT}|} \right) \\
 E_{(HSS)} &= L \times \frac{V_{VS} + |V_{OUT}|}{R^2} \times \left[R \times I_{OUT(\text{max})} - |V_{OUT}| \ln \left(\frac{R \times I_{OUT(\text{max})} + |V_{OUT}|}{|V_{OUT}|} \right) \right]
 \end{aligned} \tag{6}$$

When R approximately equals 0, $E_{(HSS)}$ can be given simply as:

$$E_{(HSS)} = \frac{1}{2} \times L \times I_{OUT(\text{max})}^2 \frac{V_{VS} + |V_{OUT}|}{|V_{OUT}|} \tag{7}$$

Note that for PWM-controlled inductive loads, adding the external freewheeling circuitry as shown in [Figure 8-24](#) is recommended to protect the device from repetitive power stressing. TVS is used to achieve the fast decay. See [Figure 8-24](#) for more details.

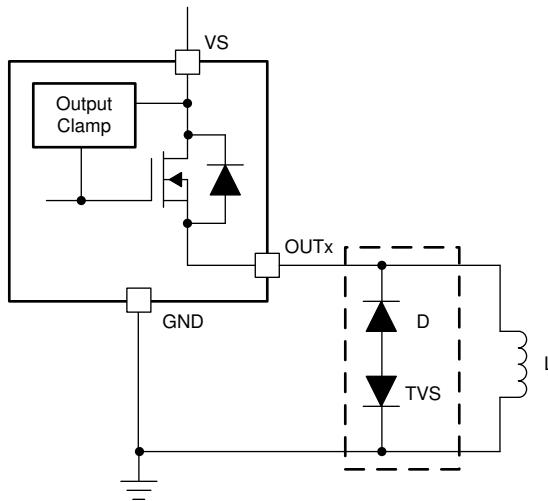


Figure 8-24. Protection with External Circuitry

[Figure 8-25](#) shows the VDS clamp engaging during 5mH inductive load discharge. [Figure 8-26](#) and [Figure 8-27](#) shows maximum energy dissipation capability of the device during inductive load turn off.



Figure 8-25. 5mH Inductive Load Driving (VBB = 13.5V, T_{AMB} = 125°C)

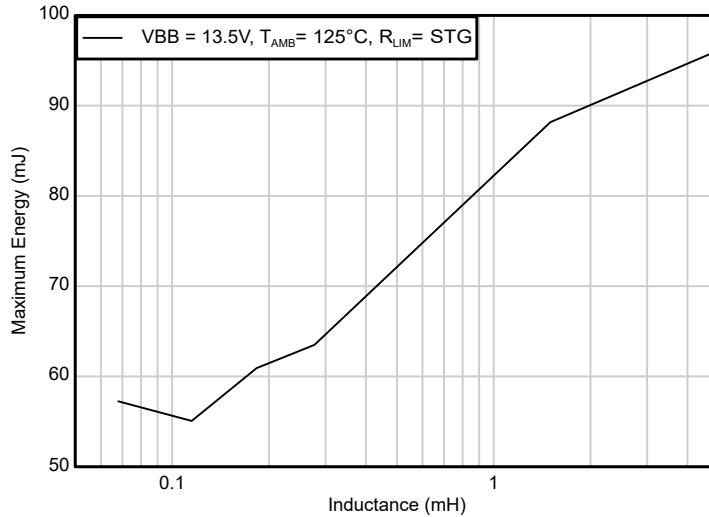


Figure 8-26. Maximum Energy Dissipation for Inductive Switch OFF vs Inductance (single pulse, VBB = 13.5V, T_{AMB} = 125°C)

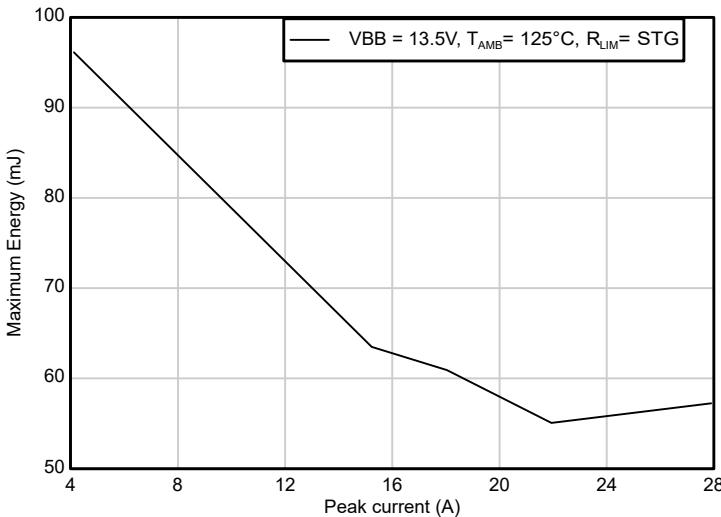


Figure 8-27. Maximum Energy Dissipation for Inductive Switch OFF vs Peak Current (single pulse, VBB = 13.5V, T_{AMB} = 125°C)

8.3.6 Slower Slew Rate Option

The TPS1HC08-Q1 offers device versions (D, B) with slower rising and falling slew rate for automotive seat heater applications. Such applications require that 10%-90% rise and fall times of the PWM currents must stay at or below 80A/msec. The slower slew rate helps reduce electromagnetic interference in the vehicle's electrical system. Without proper slew rate control, the fast switching of current in the seat heater application can cause EMC issues in the system.

8.3.7 Capacitive Load Charging

The TPS1HC08-Q1 incorporates an advanced adjustable current limiting circuit with thermal regulation that significantly improves system reliability by effectively managing inrush currents when charging large capacitive loads. The device also provides protection against current limit and overcurrent faults by turning off the smart high side switch. With no protection, charging a large capacitive load can lead to high inrush currents that pull a supply down, however by using the low thermal regulated current limit device options the capacitive load can be safely charged.

8.3.7.1 Adjustable Current Limiting for Inrush Control

Adjustable current limit feature of the device allows precise control of inrush current during capacitive load charging. By selecting an appropriate external resistor value on the ILIM pin, designers can:

- Tailor the maximum charging current to match specific capacitive load requirements.
- Protect upstream power supplies from excessive current draw during startup.
- Reduce PCB trace width requirements and connector sizing by limiting peak currents.
- Minimize voltage droop on the supply rail during capacitive charging.
- Enable the use of smaller, more cost-effective components throughout the system.

Figure 8-28 and **Figure 8-29** compares the 1mF capacitive load charging at same conditions with device configured to maximum (ILIM pin shorted to ground (STG)) and minimum (ILIM pin OPEN) current limit setting. The lower current limit limits the inrush current while charging the capacitive load and provides clean startup without triggering thermal shutdown.

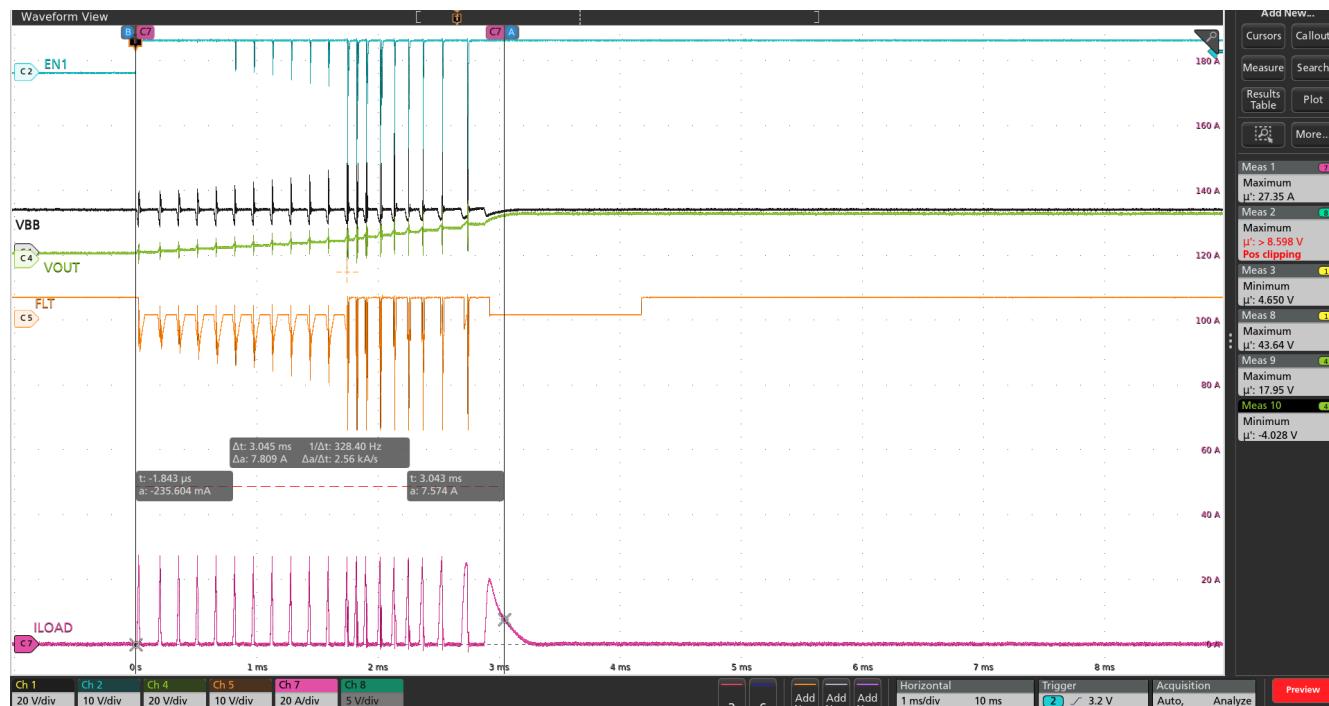


Figure 8-28. 1mF Capacitive Load Charging with TPS1HC08-Q1 Device at 13.5V VBB, ILIM Pin shorted to ground and 125°C Ambient Temperature



Figure 8-29. 1mF Capacitive Load Charging with TPS1HC08-Q1 Device at 13.5V VBB, ILIM Pin OPEN and 125°C Ambient Temperature

8.3.7.2 Current Limit with Thermal Regulation for Capacitive Loads

When configured with an external resistor on the ILIM pin, the TPS1HC08-Q1 enables thermal-regulated current limiting. The thermal regulation works through a negative feedback mechanism by continuously monitoring the relative temperature of the power FET ($T_{J,FET}$) compared to the controller temperature ($T_{J,CONTROLLER}$). As the temperature difference increases during high-current events, the device automatically reduces the current limit to maintain safe operation while allowing maximum charging current. This feature provides below advantages for capacitive load charging:

- **Expanded Capacitive Load Range:** The thermal-regulated current limiting significantly expands the range of capacitive loads that can be safely charged without triggering thermal shutdown. By dynamically adjusting current based on thermal conditions, the device can handle much larger capacitances than traditional high-side switches.
- **Elimination of Manual Pulsing:** Previously, without thermal regulation of current limit, customers often resorted to manually pulsing switches on and off to charge large capacitive loads. This approach introduced significant noise and EMI concerns into the system. The device thermal regulation eliminates the need for this practice.
- **Prevention of Thermal Runaway:** The thermal regulation implements a negative feedback loop that stabilizes the system during capacitive charging. As temperature rises, current is automatically reduced, preventing the uncontrolled thermal escalation seen in conventional switches.

8.3.7.3 Retry Thermal Shutdown Behavior for Capacitive Loads

For large capacitive loads, device can trigger thermal shutdown fault and enter into retry thermal shutdown flow. In this case, the retry protection mechanism (Section 8.3.4) of the device allows load to turn on reliably with multiple retry cycles. For most properly sized capacitive loads, the thermal regulation can prevent reaching thermal shutdown conditions, resulting in smooth capacitive charging without interruption. Figure 8-28 shows capacitive load charging with multiple thermal shutdown retry cycles. This behavior can be acceptable in applications where capacitive load has high enough load impedance connected in parallel, hence not discharging the capacitor significantly when the device is off during thermal shutdown.

8.3.7.4 Impact of DC Load on Capacitive Charging Capability

When designing systems with both capacitive and DC loads on the same channel, it's important to consider the combined thermal impact:

- **Thermal Budget Consumption:** Any DC load connected in parallel with a capacitive load consumes part of the device's thermal budget. The power dissipation from the DC load (I^2R) generates heat that raises the baseline temperature of the power FET.
- **Reduced Capacitive Charging Capability:** With a power dissipation across FET to DC load, the margin between operating temperature and thermal shutdown threshold is reduced. This effectively decreases the maximum capacitance that can be safely charged without triggering thermal shutdown.
- **Accelerated Thermal Shutdown:** The combined heating effect of DC load current and capacitive charging current can accelerate the onset of thermal shutdown. This can cause the device to enter the retry mechanism earlier and more frequently during capacitive charging.
- **Design Considerations:** When both load types must be supported simultaneously:
 - Select a more conservative (higher) R_{LIM} value to reduce the current limit.
 - Provide adequate PCB copper area for improved thermal dissipation.
 - For critical applications, consider using separate channels for DC and capacitive loads.

For more information on driving inductive or capacitive loads, reference TI's [How To Drive Inductive, Capacitive, and Lighting Loads with Smart High Side Switch](#) application report.

8.3.7.5 Device Capability

The table below shows some data for capacitive load charging across device family at $V_{BB} = 18V$, $T_A = 125^\circ C$. Only single channel is enabled for TPS2HC08-Q1 and TPS2HC16-Q1 devices.

Table 8-4. Capacitive Load Charging Results Across Device Family

| PART NUMBER | ILIM | CAPACITIVE LOAD | CHARGING TIME (typical) | THERMAL SHUTDOWN TRIGGERED |
|-------------|------|-----------------|----------------------------|-------------------------------|
| TPS2HC08-Q1 | OPEN | 2mF | >10ms | No |
| | GND | 1mF | <10ms | Yes |
| TPS2HC16-Q1 | OPEN | 47uF | <10ms | No |
| | GND | 220uF | <10ms | Yes |
| TPS1HC08-Q1 | OPEN | 470uF | <10ms | No |
| | GND | 1mF | <10ms | Yes |
| TPS1HC04-Q1 | OPEN | 680uF | <10ms | No |
| | GND | 470uF | <10ms | Yes |
| TPS1HC03-Q1 | OPEN | 680uF | <10ms | No |
| | OPEN | 1mF | <10ms | Yes |

8.3.8 Bulb Charging

Figure 8-30 shows a simple bulb model as a combination of capacitive and resistive elements that define the startup and steady-state characteristics:

- R_{inrush} : The initial cold filament resistance that limits peak inrush current at startup.
- C_{inrush} : Represents the energy storage required for the filament to generate sufficient heat for proper illumination.
- R_{dc} : The steady-state hot filament resistance that determines normal operating current ($V_{battery} / R_{dc}$).

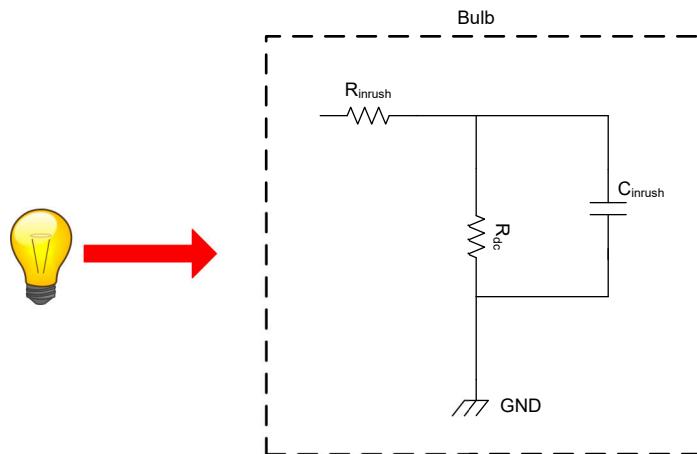


Figure 8-30. Simple Bulb Model

During cold startup, the filament resistance (R_{inrush}) can be 7-10 times lower than the steady-state value (R_{dc}), resulting in substantial inrush currents and need of low R_{ON} (on-resistance) switch.

In real environment, a bulb is introduced to many inductances and resistances when placed in a vehicle. Figure 8-31 shows simplified vehicle architecture model in real environment consisting of below complex electrical network that significantly affects the bulb turn-on behavior and peak current.

- **$R_{vehicle}$** : The total wire harness and connector resistance in the path from battery to chassis ground excluding $R_{ds,ON}$ switch (R_{ON} of the switch) typically ranges from $45m\Omega$ to $130m\Omega$ in production vehicles. The short and long cable harness length typically makes $50m\Omega$ and $100m\Omega$ of $R_{vehicle}$ respectively.
- **$L_{vehicle}$** : Wire harness inductance affects current slew rate and turn-on timing.
- **System resistances**: Connector contact resistance and ground path resistance contribute to the overall circuit behavior.

The three primary components that determine peak inrush current during bulb charging are:

- **$R_{vehicle}$** : Higher vehicle resistance reduces peak current.
- **$R_{ds,ON}$ switch** : The switch's on-resistance (R_{ON}) contributes to current limiting.
- **R_{inrush}** : The cold filament resistance of the specific bulb.

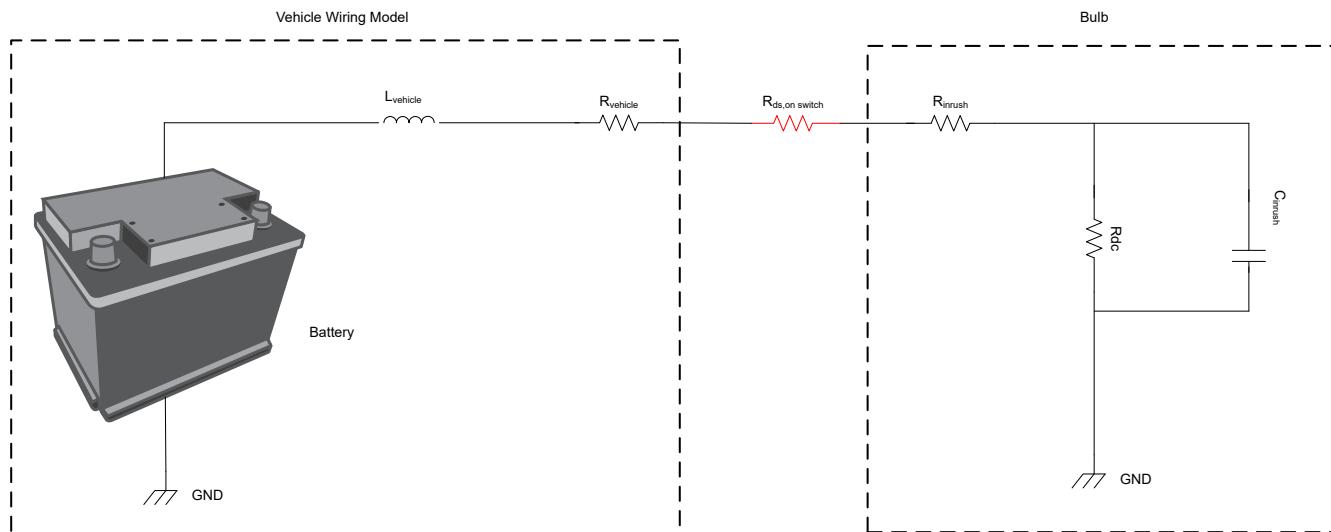


Figure 8-31. Simplified Vehicle Architecture Model

8.3.8.1 Non-Thermal Regulated Mode for Bulb Loads

For bulb loads with high inrush currents, the TPS1HC08-Q1 offers a specialized non-thermal regulated current limit mode that can be enabled by connecting the ILIM pin directly to GND. This mode provides consistent and predictable current limiting behavior regardless of temperature conditions with below device features.

- Maintains a fixed current limit of 25A regardless of temperature.
- Allows the device to handle the high initial current demand.

8.3.8.2 Thermal Management During Bulb Inrush

For high wattage bulb loads or at cold temperature startup or high VBB voltage, with high inrush current demand, the device employs sophisticated thermal protection mechanisms:

- **Relative Thermal Shutdown**

During high-inrush events, toggling of the switch output can be observed due to the FET heating up rapidly.

When this occurs, the device enters a relative thermal shutdown ($T_{J,FET} - T_{J,CONTROLLER} > T_{REL}$) state and auto-recovers from this event within t_{RETRY_INT} . This rapid recovery allows the bulb to continue charging while preventing excessive thermal stress on the device.

- **Absolute Thermal Shutdown**

If the junction temperature continues to rise despite relative thermal protection, an absolute thermal shutdown event occurs when the FET temperature exceeds T_{ABS} . In this case, the switch turns off to protect the device and auto-recovers from this event within t_{RETRY_EXT} once the temperature decreases sufficiently, resuming bulb charging.

8.3.8.3 Device Capability

The table below shows some data for bulb load charging across device family at $V_{BB} = 13.5V$, $T_A = -40^\circ C$. Only single channel is enabled for TPS2HC08-Q1 and TPS2HC16-Q1 devices.

Table 8-5. Bulb Load Charging Results Across Device Family (with short cable length, $R_{vehicle} = 50\text{mohm}$)

| PART NUMBER | ILIM | BULB LOAD | CHARGING TIME (typical) | THERMAL SHUTDOWN TRIGGERED |
|-------------|------|--|-------------------------|----------------------------|
| TPS2HC08-Q1 | GND | 35W | <10ms | Yes |
| TPS2HC16-Q1 | GND | 27W | >10ms | Yes |
| TPS1HC04-Q1 | GND | 35W | <10ms | No |
| | GND | 60W | <10ms | Yes |
| | GND | 100W | >10ms | Yes |
| TPS1HC03-Q1 | GND | 4 x 27W (with long cable harness length) | >10ms | Yes |
| | GND | 2 x 27W | <10ms | Yes |
| | GND | 35W | <10ms | No |

8.3.9 Fault Detection and Reporting

8.3.9.1 Diagnostic Enable Function

The DIAG_EN pin enables or disables the diagnostic functions. If multiple devices are used, but the ADC resource is limited in the microcontroller, the MCU can use GPIOs to set DIAG_EN high to enable the diagnostics of one device while disabling the diagnostics of the other devices by setting DIAG_EN low. In addition, the device can keep the power consumption to a minimum by setting DIAG_EN and EN low.

Table 8-6. Diagnosis Configuration Table

| DIAG_EN | EN | SNS | FLT | PROTECTIONS AND DIAGNOSTICS |
|---------|----|----------------|----------------|--|
| L | H | High Impedance | See Table 8-8 | SNS disabled, FLT reporting, full protection |
| | L | | High Impedance | Diagnostics disabled, no protection |

Table 8-6. Diagnosis Configuration Table (continued)

| DIAG_EN | EN | SNS | FLT | PROTECTIONS AND DIAGNOSTICS |
|---------|----|---------------|---------------|-----------------------------|
| H | - | See Table 8-8 | See Table 8-8 | See Table 8-8 |

8.3.9.2 FLT Reporting

In active state with EN high, the $\overline{\text{FLT}}$ pin is used to monitor the fault condition for the device regardless of DIAG_EN status. In case of off state diagnostics with EN low, the $\overline{\text{FLT}}$ pin monitors the fault condition when DIAG_EN is high. When a fault condition occurs on the device, the $\overline{\text{FLT}}$ pin is pulled down to GND. A 3.3V or 5V external pullup is required to match the supply level of the microcontroller.

8.3.9.3 FLT Timings

The below table shows the $\overline{\text{FLT}}$ pin timings.

Table 8-7. FLT Timings

| CONDITION | TIMING |
|--|---|
| Open load or STB fault to $\overline{\text{FLT}}$ assertion in DIAGNOSTIC state. | See Section 8.3.10.1.2 (t_{OL} , t_{OL1} , t_{OL2}) |
| Any other fault occurrence to $\overline{\text{FLT}}$ assertion | See t_{FAULT_FLT} |
| Fault clearance to $\overline{\text{FLT}}$ reset | The internal design architecture causes maximum 1ms delay for $\overline{\text{FLT}}$ signal to reset from the fault clearance event. |

8.3.9.4 Fault Table

The below table shows the response of the FLT (regardless of DIAG_EN being high) and SNS (with DIAG_EN being high) pins during different conditions.

Table 8-8. Fault Table

| CONDITIONS | EN | OUT | CRITERION | SNS (with DIAG_EN high) | FLT (with external pull-up) | BEHAVIOR | FAULT RECOVERY |
|-----------------------------|--------|-----------------------------------|--------------------------|-------------------------|-----------------------------|--|--|
| Normal | L | L | — | High Impedance | H | Normal | — |
| | H | $V_{BB} - I_{LOAD} \times R_{ON}$ | — | I_{LOAD} / K_{SNS} | H | Normal | — |
| Overcurrent | H | $V_{BB} - I_{CL} \times R_{ON}$ | Current limit triggered | I_{SNSFH} | L | Holds the current at the current limit until thermal shutdown or when the overcurrent event is removed | Auto-retry or latch, see Section 8.3.4 |
| Hot short | H | L | output shorted to ground | I_{SNSFH} | L | Device will immediately shutdown, and reenable into current limit. | Auto-retry or latch, see Section 8.3.4 |
| Enable into permanent short | L to H | L | output shorted to ground | I_{SNSFH} | L | Device will enable into current limit until thermal shutdown. | Auto-retry or latch, see Section 8.3.4 |

Table 8-8. Fault Table (continued)

| CONDITIONS | EN | OUT | CRITERION | SNS (with DIAG_EN high) | FLT (with external pull-up) | BEHAVIOR | FAULT RECOVERY |
|---|----|-----|-----------------------------|-------------------------|-----------------------------|---|--|
| Open load, short to battery (STB) | L | H | $V_{BB} - V_{OUT} < V_{OL}$ | I_{SNSFH} | L (when DIAG_EN is high) | Internal pull-up resistor is active to detect open load fault. | Auto |
| | H | H | | I_{LOAD}/K_{SNS} | H | Normal behavior. User can make judgement based on SNS pin output. | — |
| Absolute Thermal shutdown | H | — | T_{ABS} triggered | I_{SNSFH} | L | Shuts down when devices hits absolute thermal shutdown. | Auto-retry or latch, see Section 8.3.4 |
| Relative Thermal Shutdown | H | — | T_{REL} triggered | I_{SNSFH} | L | Shuts down when devices hits relative thermal shutdown. | Auto-retry or latch, see Section 8.3.4 |

8.3.10 Full Diagnostics

8.3.10.1 Open-Load Detection

8.3.10.1.1 Channel On

If a channel is on and the DIAG_EN = Logic High, then the high accuracy current sense of the device can be used to detect open-loads in the on state through an external ADC. Please note there is no detection reported on the \overline{FLT} pin. Determination of an open-load while a channel is on must be made by the user or system.

8.3.10.1.2 Channel Off

Open load detection is available in the off state if DIAG_EN = Logic High. If the channel is off and a load is connected, the output voltage is pulled to $\approx 0V$ by the load. In the case of an open load, the output voltage is close to the supply voltage, $V_{BB} - V_{OUT} < V_{OL}$. The FLT pin goes low to indicate the fault to the MCU, and the SNS pin outputs I_{SNSFH} fault current. There is always a leakage current $I_{OL,OFF}$ present on the output, due to the internal logic control path or external humidity, corrosion, and so forth. Thus, the device implements an internal pullup resistor (R_{PU}) to offset the leakage current. This pullup current must be less than the output load current to avoid false detection in the normal operation mode. To reduce the standby current, the device implements a switch and pullup resistor which is controlled by the DIAG_EN and the EN pin.

There are two settings for the open-load detection delay - 0.4ms (for P and D variants) and 2.4ms (for M and B variants). The 2.4ms open load detection delay represents the delay for the internal pullup (R_{PU}) resistor to engage between V_{BB} and V_{OUT} pins. This allows user to do fast DIAG_EN sequencing (DIAG_EN high pulse $< 2.4ms$) when SNS pins of multiple devices are tied to common R_{SNS} for MCU current sense reading. In this case, the open load fault will not engage for disabled devices during current sense read.

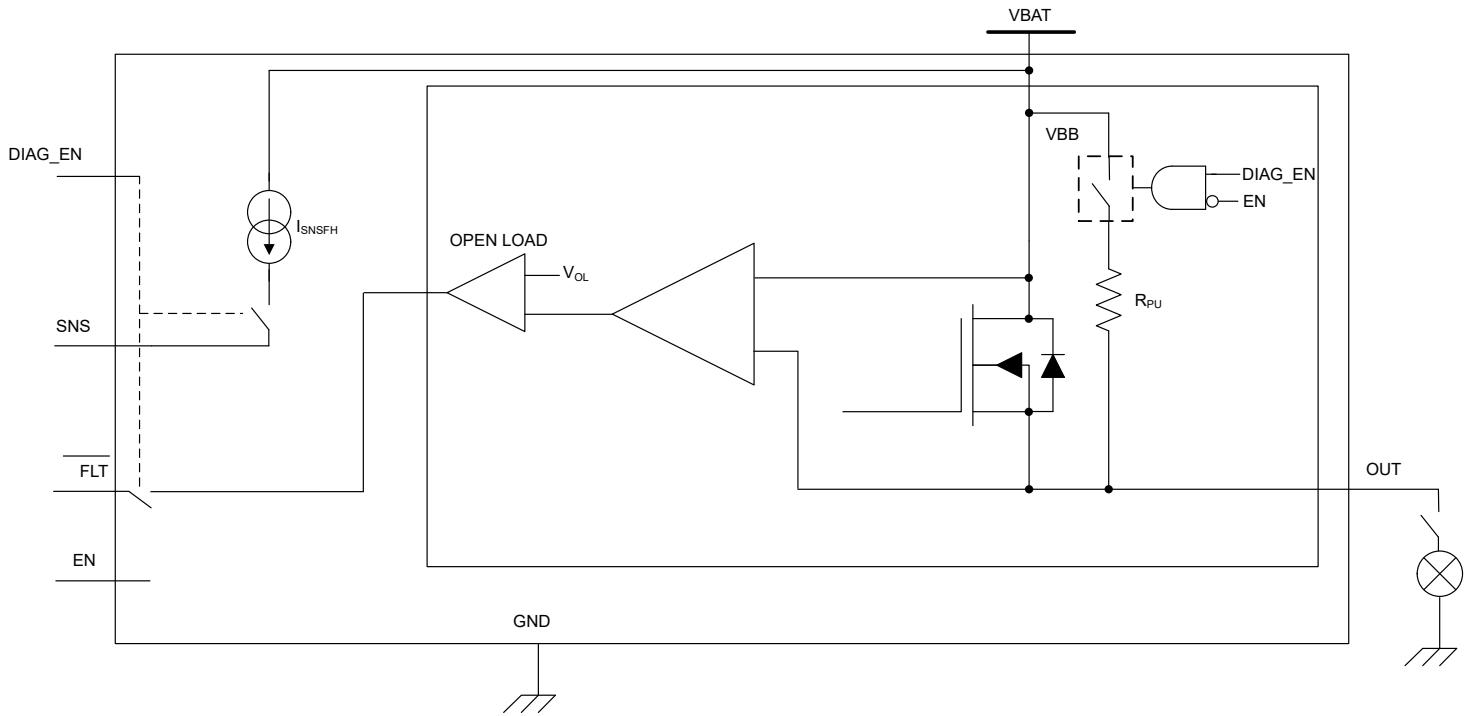
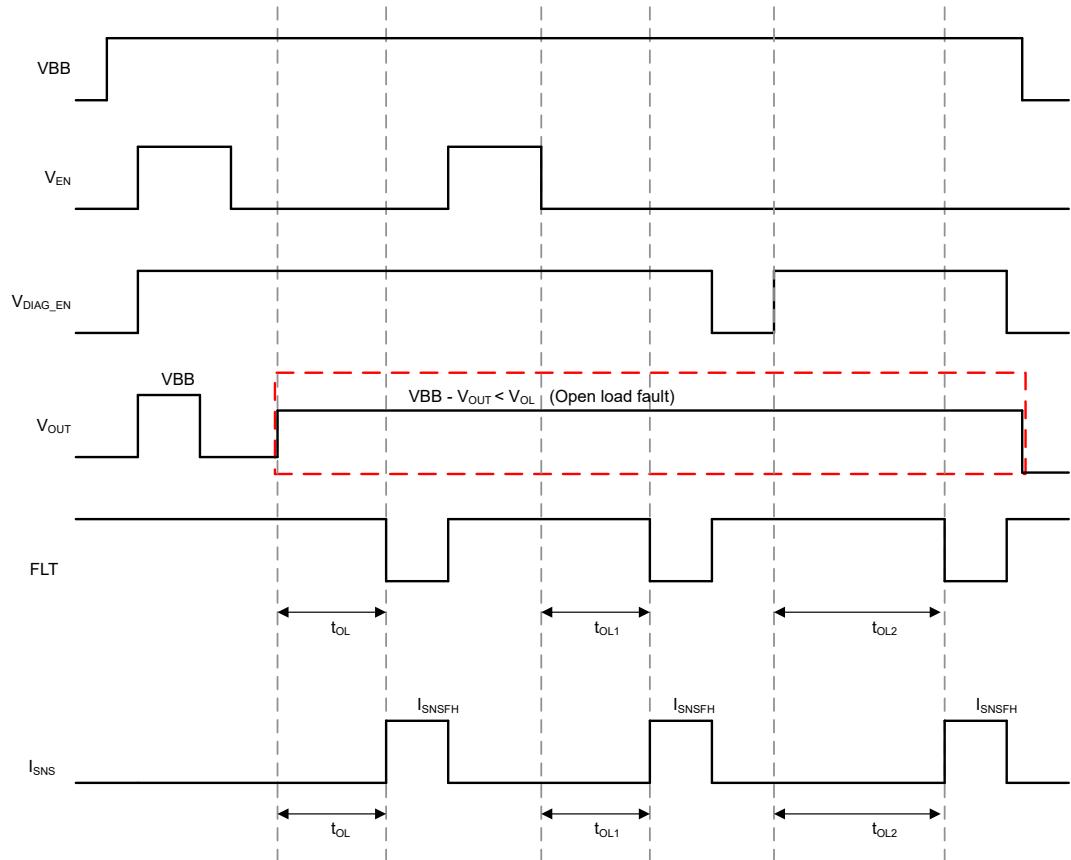


Figure 8-32. Open-Load Detection in Off-State



Note

Rise and fall times of control signals are 100ns. Control signals include: EN and DIAG_EN.

Figure 8-33. Open-load Detection Timing Characteristics

8.3.10.2 Short-to-Battery Detection

Short-to-battery detection has the same detection mechanism and behavior as open-load detection, both in the on-state and off-state. See [Table 8-8](#) for more details.

8.3.10.3 Reverse-Polarity and Battery Protection

Reverse-polarity, commonly referred to as reverse battery, occurs when the ground of the device goes to the battery potential, $V_{GND} = V_{BAT}$, and the supply pin goes to ground, $V_{BB} = 0V$. In this case, if the EN pin has a path to the *ground* plane, then the FET turns on to lower the power dissipation through the main channel and prevent current flow through the body diode. Note that the resistor/diode ground network (if there is not a central blocking diode on the supply) must be present for the device to protect the device during a reverse battery event. The ground protection network will cause the device ground to be at a higher potential than the module ground (and microcontroller ground). This offset needs to be accounted for in logic pins interface between the device and the microcontroller.

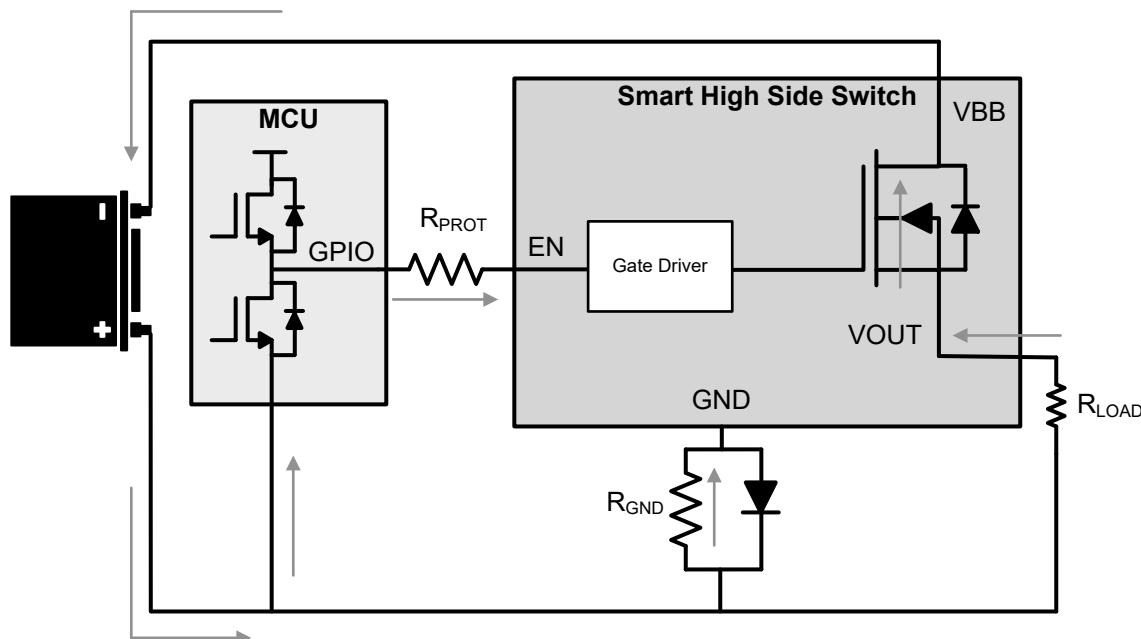


Figure 8-34. Reverse Battery Circuit

For more external protection circuitry information, see [Reverse Current Protection](#).

8.3.11 Full Protections

8.3.11.1 UVLO Protection

The device monitors the supply voltage V_{BB} , to prevent unpredicted behaviors when V_{BB} is too low. When V_{BB} falls down to V_{UVLOF} , the device shuts down. When V_{BB} rises up to V_{UVLOR} , the device turns on.

8.3.11.2 Loss of GND Protection

When loss of GND occurs, output is turned off regardless of whether the enable signal is high or low.

Case 1 (loss of device GND): loss of GND protection is active when the thermal pad (Tab), IC_GND, and current limit ground are one trace connected to the system ground, as shown in [Figure 8-35](#).

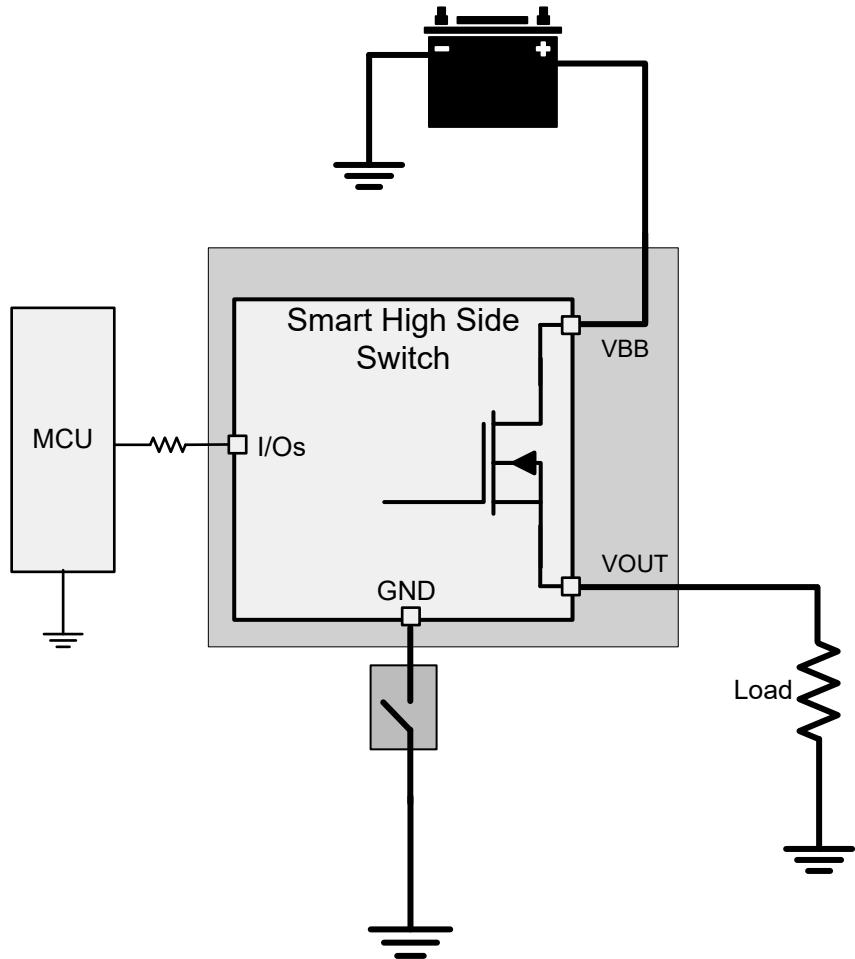


Figure 8-35. Loss of Device GND

Case 2 (loss of module GND): when the whole ECU module GND is lost, protections are also active. At this condition, the load GND remains connected.

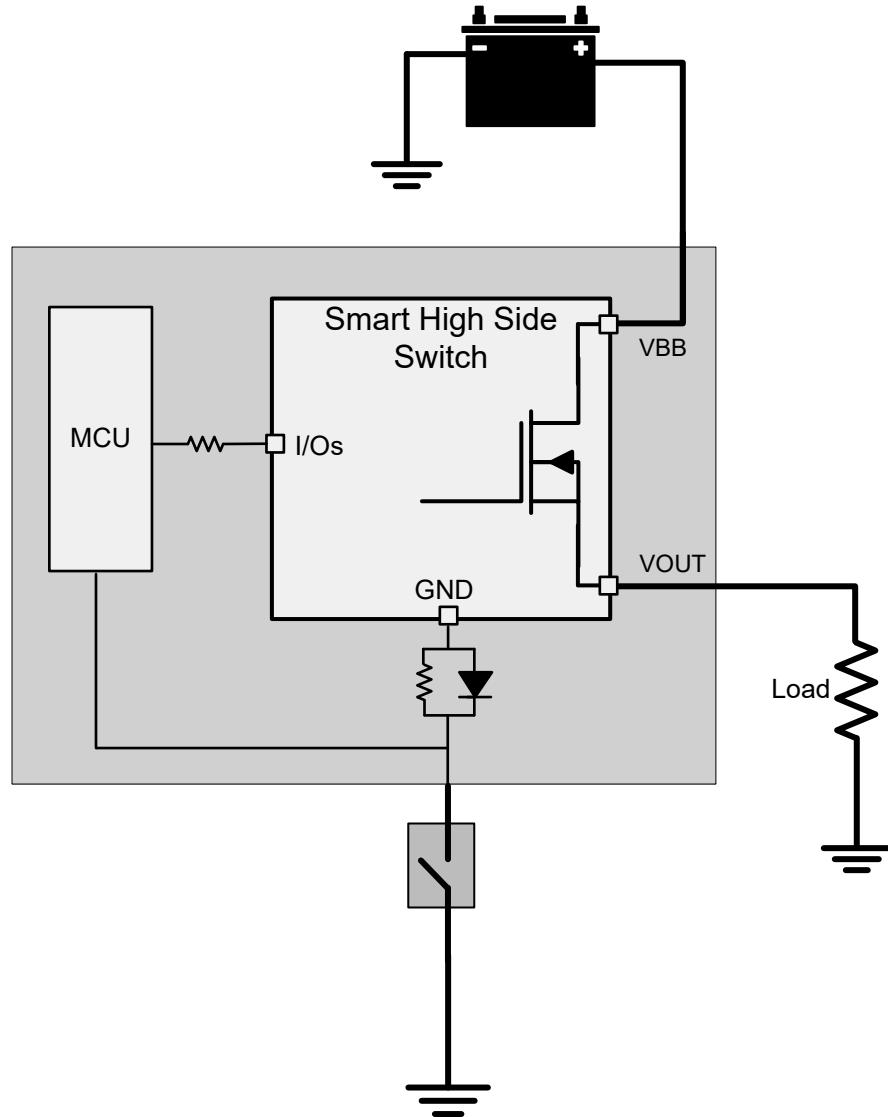


Figure 8-36. Loss of Module GND

8.3.11.3 Loss of Power Supply Protection

When loss of supply occurs, output is turned off regardless of whether the input is high or low. For a resistive or capacitive load, loss of supply protection is easy to achieve due to no more power. The worst case is a charged inductive load. In this case, the current is driven from all of the IOs to maintain the inductance output loop. TI recommends either the MCU serial resistor plus the GND network (diode and resistor in parallel) or external free-wheeling circuitry.

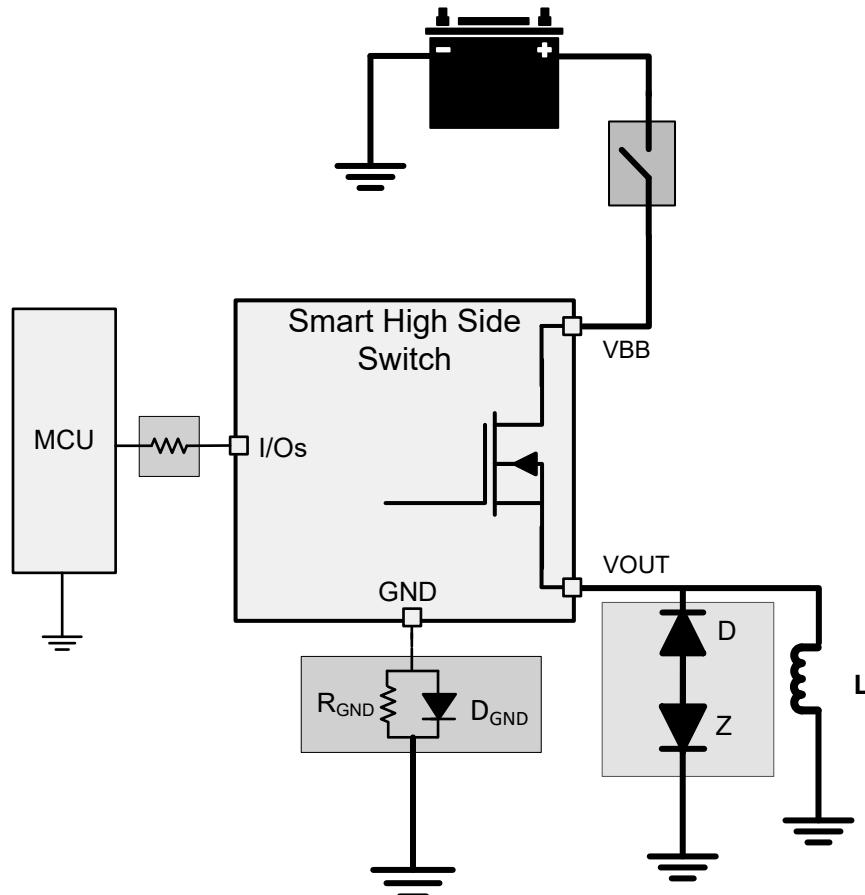


Figure 8-37. Loss of Battery

8.3.11.4 Reverse Current Protection

Method 1: block diode connected with VBB. Both the device and load are protected when in reverse polarity. The blocking diode does not allow any of the current to flow during reverse battery condition.

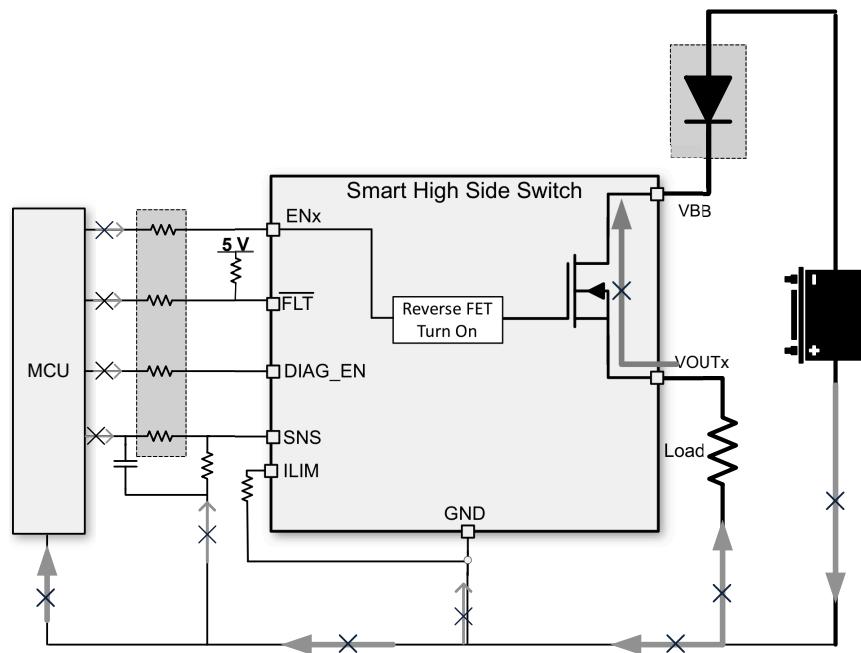


Figure 8-38. Reverse Protection with Block Diode

Method 2 (GND network protection): only the high-side device is protected under this connection. The load reverse current is limited by the impedance of the load. When reverse polarity happens, the continuous reverse current through the power FET must not make the heat build up be greater than the absolute maximum junction temperature. This can be calculated using the $R_{ON(REV)}$ value and the $R_{θJA}$ specification. In the reverse battery condition, the FET must come on to lower the power dissipation. This action is achieved through the path from EN to system ground where the positive voltage is being applied. No matter what types of connection are between the device GND and the board GND, if a GND voltage shift happens, verify that the following proper connections for the normal operation:

- Connect the current limit programmable resistor to the device GND.

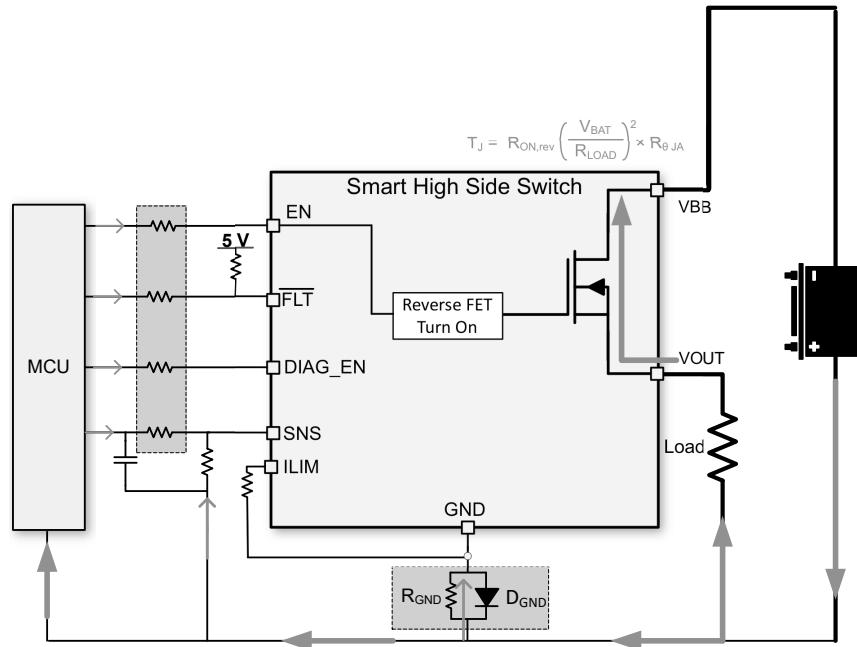


Figure 8-39. Reverse Protection with GND Network

- **Recommendation – resistor and diode in parallel:** a peak negative spike can occur when the inductive load is switching off, which can damage the HSS or the diode. So, TI recommends a resistor in parallel with the diode when driving an inductive load. The recommended selection are a $4.7k\Omega$ resistor in parallel with an $I_F > 100mA$ diode. If multiple high-side switches are used, the resistor and diode can be shared among devices.
- **Ground Resistor:** The higher resistor value contributes to a better current limit effect when the reverse battery or negative ISO pulses.

$$R_{GND} \geq \frac{(-V_{CC})}{(-I_{GND})} \quad (8)$$

where

- $-V_{CC}$ is the maximum reverse battery voltage (typically $-16V$).
- $-I_{GND}$ is the maximum reverse current the ground pin can withstand, which is available in the [Absolute Maximum Ratings](#).
- **Ground Diode:** A diode is needed to block the reverse voltage, which also brings a ground shift ($\approx 600mV$). Additionally, the diode must be $\approx 200V$ reverse voltage for the ISO 7637 pulse 1 testing so that the diode does not get biased.

8.3.11.5 Protection for MCU I/Os

In many conditions, such as the negative ISO pulse, or the loss of battery with an inductive load, a negative potential on the device GND pin can damage the MCU I/O pins (more likely, the internal circuitry connected to the pins). Therefore, the serial resistors between MCU and HSS are required.

Also, for proper protection against loss of GND, TI recommends 10k Ω resistance for the R_{PROT} resistors.

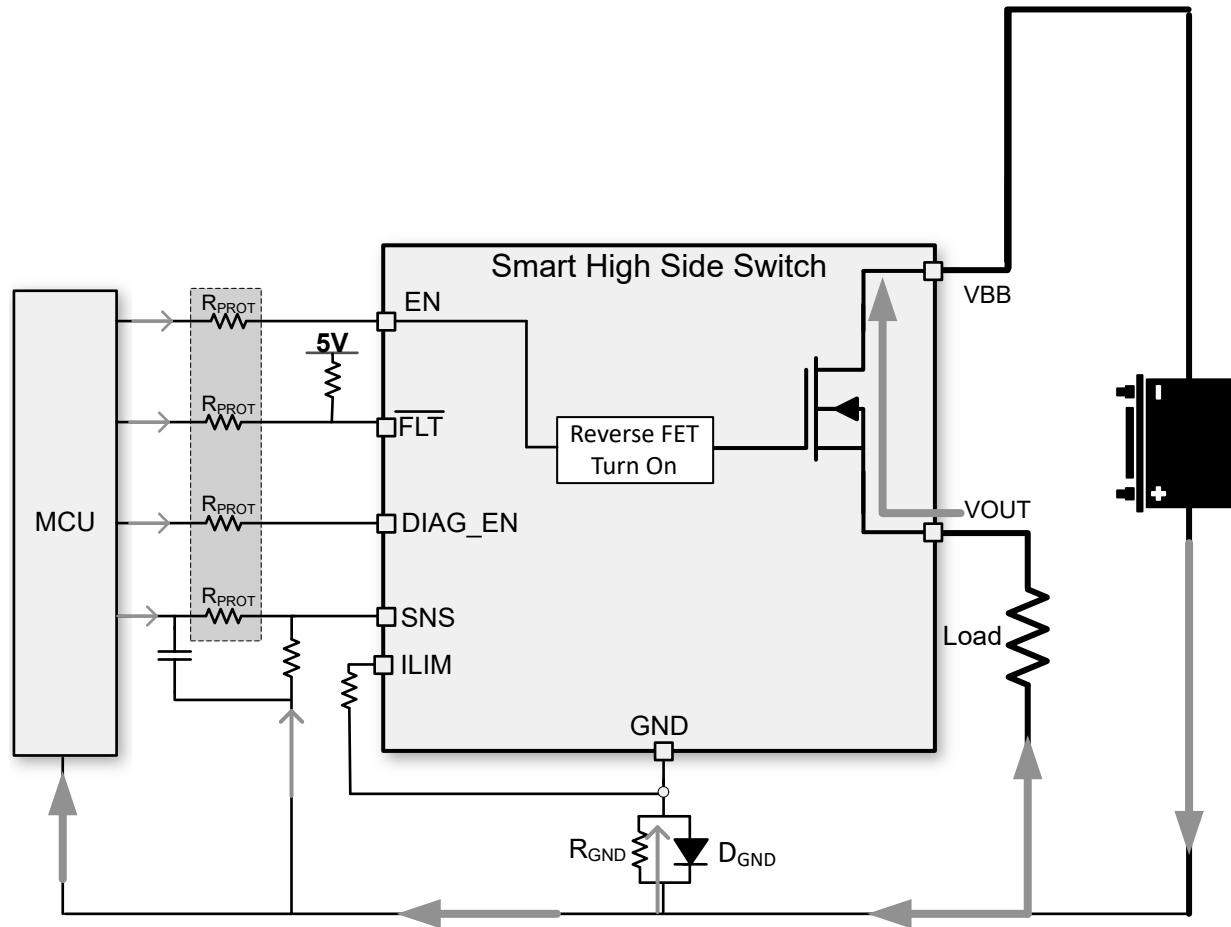


Figure 8-40. MCU I/O Protections

8.4 Device Functional Modes

The device has several states to transition into based on the EN pin, DIAG_EN pin, and VBB voltage. The different states are referenced throughout the data sheet.

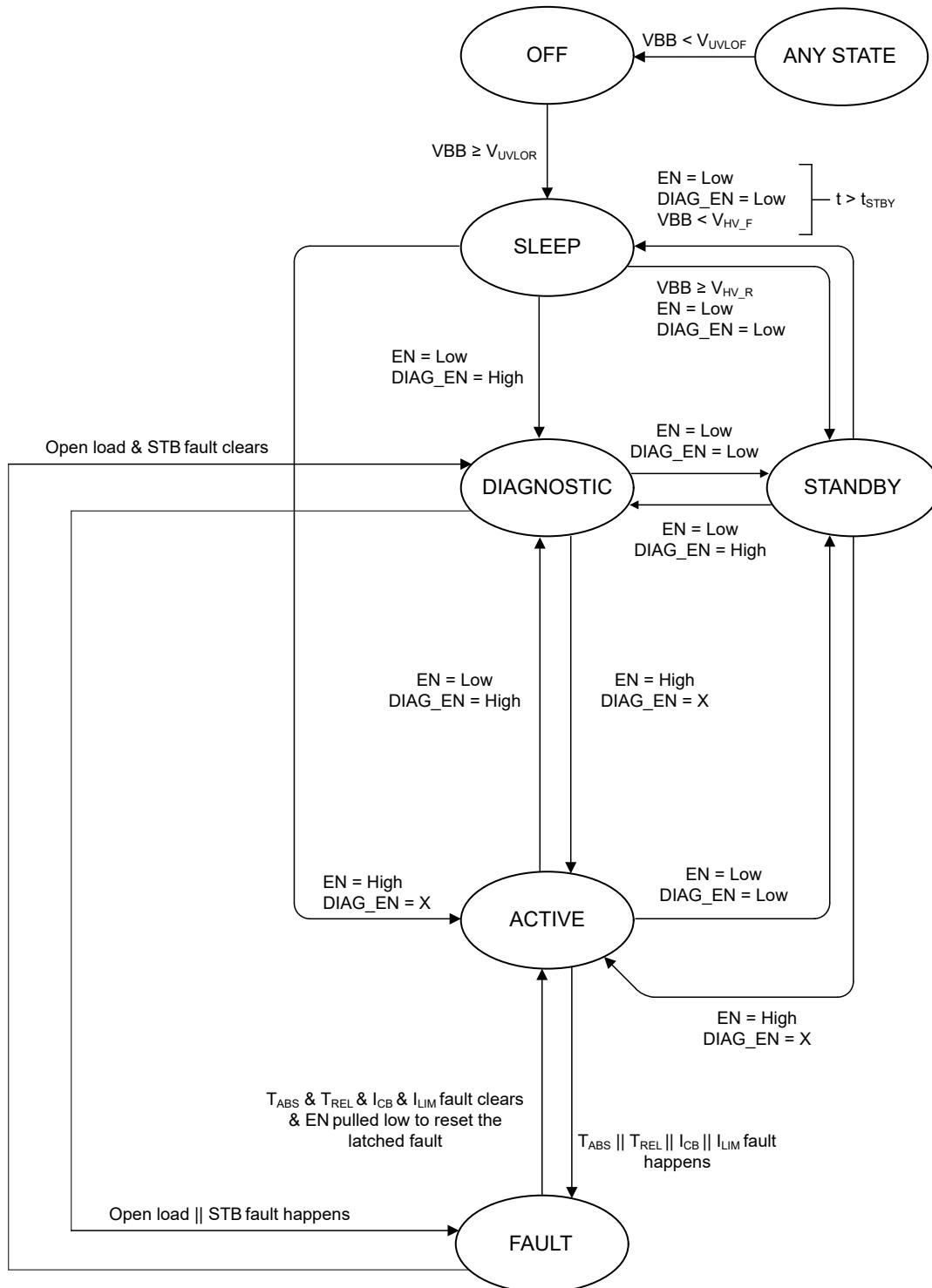


Figure 8-41. State Diagram

OFF

Device OFF state and occurs when the VBB voltage of the device is below the V_{UVLOF} .

SLEEP

This device state is entered from STANDBY state when the EN pin is pulled low for duration more than t_{STBY} amount of time and VBB is lower than V_{HV_F} . Output is turned off. In the SLEEP state, all blocks inside the device are turned off and the current into the VBB is I_{SLEEP} . From SLEEP, the device can transfer into the ACTIVE state if the EN pin is pulled high, the DIAGNOSTIC state if the DIAG_EN pin, without the EN pin, goes high, or the STANDBY state if VBB is greater than V_{HV_R} .

STANDBY

The device STANDBY state is entered when the EN pin is low. Output is turned off and the DIAG_EN pin is also low but there has not yet been t_{STBY} amount of time. This state is included so that the device output can be modulated using PWM without any of the internal rails being cut off and put to SLEEP state. Once the device has waited t_{STBY} and VBB is less than V_{HV_F} , the device completely shuts down and transitions into SLEEP state. However, if the time is less than t_{STBY} and the EN pin was to go high, the device transitions into ACTIVE state. Similarly if the DIAG_EN goes high, the device transitions into DIAGNOSTIC state.

DIAGNOSTIC

The device DIAGNOSTIC state is entered when EN is low and the DIAG_EN pin is high. Open-load or short-to-battery can be diagnosed in this state. The device signals a \overline{FLT} and the SNS pin outputs I_{SNSFH} current in either an open-load or short-to-battery fault condition.

ACTIVE

The device enters ACTIVE state when the output is on by pulling the EN pin high. In the ACTIVE state, the current limit value is set by the external resistor on the ILIM pin. If the DIAG_EN pin is pulled high while in the ACTIVE state, the SNS pin outputs a proportional current to the load current. Additionally the \overline{FLT} pin reports if there is a fault occurring on any channel. The device can transition out of the ACTIVE state by turning off all of the channels while DIAG_EN is high or low. If the device turns off and DIAG_EN is high, the device transitions into the DIAGNOSTIC state. If the device turns off and the DIAG_EN pin is low, then the device transitions into the STANDBY state.

FAULT

The device FAULT state occurs when the EN pin is high but some event has caused the device to behave differently from normal operation. These fault events include: absolute thermal shutdown, relative thermal shutdown, current limit, open load and short to battery faults. Each of these fault events either directly or eventually shut off the FET to protect the device and system.

9 Application and Implementation

Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

9.1 Application Information

The TPS1HC08-Q1 device is capable of driving a wide variety of resistive, inductive, and capacitive loads, including bulbs, LEDs, relays, solenoids, heaters, and sub-modules. Full diagnostics and high-accuracy current-sense features enable intelligent control of the load. An external adjustable current limit improves the reliability of the whole system by clamping the inrush or overload current.

9.2 Typical Application

The following figure shows an example of the external circuitry connections for TPS1HC08-Q1.

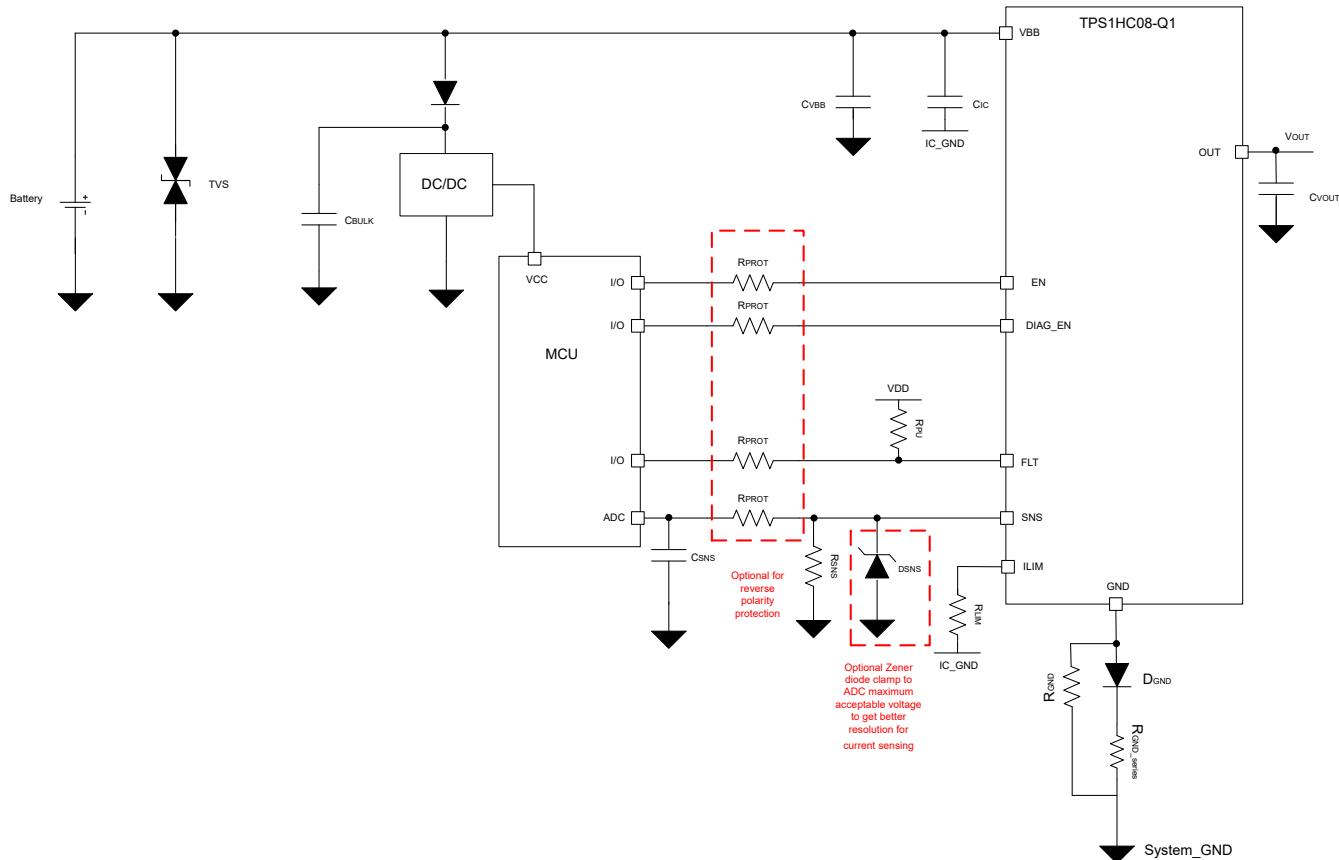


Figure 9-1. Typical Application Diagram

9.2.1 Design Requirements

Table 9-1. Recommended Component Values

| COMPONENT | DESCRIPTION | PURPOSE |
|------------------|-------------|---|
| TVS | SMBJ39CA | Filter voltage transients coming from battery (ISO7637-2) |
| C _{VBB} | 220nF | Better EMI performance |
| C _{IC} | 100nF | Minimal amount of capacitance on input for EMI mitigation |

Table 9-1. Recommended Component Values (continued)

| COMPONENT | DESCRIPTION | PURPOSE |
|-------------------|--|--|
| C_{BULK} | 10 μ F | Help filter voltage transients on the supply rail |
| R_{PROT} | 10k Ω | Protection resistor for microcontroller and device I/O pins |
| R_{LIM} | Values listed in Section 6.5 | Set current limit threshold |
| R_{SNS} | 1k Ω | Translate the sense current into sense voltage |
| D_{SNS} | SMBJ50A | Clamp SNS pin voltage to ADC maximum acceptable voltage to have improved current sense resolution. |
| C_{FILTER} | 100nF | Coupled with R _{PROT} on the SNS line creates a low pass filter to filter out noise going into the ADC of the MCU |
| C_{VOUT} | 22nF | Improves EMI performance, filtering of voltage transients |
| R_{PULLUP} | 4.7k Ω | Pull up resistor for open-drain pins (FLT and LPM) |
| R_{GND} | 4.7k Ω | Stabilize GND potential during turn-off of inductive load |
| D_{GND} | BAS21 Diode | Keeps GND close to system ground during normal operation |
| R_{GND_series} | 1 Ω | Resistor in series to D _{GND} for hot short robustness. |

9.2.2 Detailed Design Procedure

The R_{SNS} resistor value can be calculated using [Equation 1](#) in case of no external component connected on SNS pin and [Equation 2](#) when an external zener diode or resistor divider is connected on SNS pin to clamp SNS pin voltage to ADC maximum acceptable voltage, $V_{ADC,max}$ for better current sense resolution. To achieve better current-sense accuracy, a 1% tolerance or better resistor is preferred.

Table 9-2. Typical Application

| PARAMETER | VALUE (no external component connected on SNS pin) | VALUE (external zener diode or resistor divider is connected on SNS) |
|---|---|---|
| $I_{LOAD,max}$ | N/A | N/A |
| $I_{LOAD,min}$ | 100mA | 100mA |
| $V_{ADC,max}$ | 5V | 5V |
| $V_{ADC,min}$ | 5mV | 5mV |
| V_{HR} (needed) | 1V | 1V |
| K_{SNS} | 3000 | 3000 |
| K_{CL} | 500 | 500 |
| I_{SNSFH} | 7.5mA | 7.5mA |
| V_{HR} (calculated with maximum R_{SNS}) | 3.33V | - |
| R_{SNS} (minimum) | 150 Ω | 150 Ω |
| R_{SNS} (maximum) | 667 Ω | 1600 Ω |

For this application with a zener diode (D_{SNS}) connected on SNS pin, a R_{SNS} value of 1000 Ω can be chosen to satisfy the [Equation 2](#) requirements.

In other applications with a higher dynamic current range, either more emphasis can be put on the lower end measurable values which increases R_{SNS}. Likewise, if the higher currents are of more interest the R_{SNS} can be decreased.

To set the adjustable current limit value I_{CL}, use [Equation 9](#) to select the R_{LIM} value.

$$R_{LIM} = K_{CL} / I_{CL} \quad (9)$$

TI recommends R_{PROT} = 10k Ω for 5V MCU IO connections.

9.2.2.1 EMC Transient Disturbances Test

Due to the severe electrical conditions in the automotive environment, immunity capacity against electrical transient disturbances is required, especially for a high side power switch, which is connected directly to the battery. Detailed test requirements are in accordance with the ISO 7637-2:2011 and ISO 16750-2:2010 standards.

Table 9-3. ISO 7637-2:2011(E) in 12V System

| TEST ITEM | TEST PULSE SEVERITY LEVEL AND Vs ACCORDINGLY ^{(1) (2)} | | PULSE DURATION (t _d) | MINIMUM NUMBER OF PULSES OR TEST TIME | BURST-CYCLE PULSE-REPETITION TIME | | INPUT RESISTANCE (Ω) ⁽³⁾ | FUNCTION PERFORMANCE STATUS CLASSIFICATION ⁽⁴⁾ |
|-----------|---|------|----------------------------------|---------------------------------------|-----------------------------------|-------|-------------------------------------|---|
| | LEVEL | Vs/V | | | MIN | MAX | | |
| 1 | III | -112 | 2ms | 500 pulses | 0.5s | — | 10 | Status II |
| 2a | III | 55 | 50μs | 500 pulses | 0.2s | 5s | 2 | Status II |
| 2b | IV | 10 | 0.2s to 2s | 10 pulses | 0.5s | 5s | 0 to 0.05 | Status II |
| 3a | IV | -220 | 0.1μs | 1h | 90ms | 100ms | 50 | Status II |
| 3b | IV | 150 | 0.1μs | 1h | 90ms | 100ms | 50 | Status II |

(1) Tested both under input low condition and high condition.

(2) The pulse 2A voltage is 54V maximum from VBB with respect to ground. A voltage suppressing mechanism must be used to pass Level III. This test was run with an 1μF capacitor from VBB to system ground.

(3) GND pin network is a 4.7kΩ resistor in parallel with a diode BAS21-7-F.

(4) Status II: The function does not perform as designed during the test, but returns automatically to normal operation after the test.

Table 9-4. ISO 16750-2:2010(E) Load Dump Test B in 12V System

| TEST ITEM | TEST PULSE SEVERITY LEVEL AND Vs ACCORDINGLY ^{(1) (2)} | | PULSE DURATION (t _d) | MINIMUM NUMBER OF PULSES OR TEST TIME | BURST-CYCLE PULSE-REPETITION TIME | | INPUT RESISTANCE (Ω) ⁽³⁾ | FUNCTION PERFORMANCE STATUS CLASSIFICATION ^{(4) (5)} |
|-----------|---|------|----------------------------------|---------------------------------------|-----------------------------------|-----|-------------------------------------|---|
| | LEVEL | Vs/V | | | MIN | MAX | | |
| Test B | | 35 | 40ms to 400ms | 5 pulses | 60s | | 0.5 to 4 | Status II |

(1) Tested both under input low condition and high condition (DIAG_EN, EN, and VBB are all classified as inputs).

(2) Considering the worst test condition, the device is tested without any filter capacitors on VBB and VOUT.

(3) The GND pin network is a 4.7kΩ resistor in parallel with a diode BAS21-7-F.

(4) Status II: The function does not perform as designed during the test, but returns automatically to normal operation after the test.

(5) Select a 36V external suppressor.

9.2.3 Transient Thermal Performance

The TPS1HC08-Q1 device can experience different transient conditions that cause large currents to flow for a short duration of time. These may include:

- Inrush current during high capacitive or bulb load charging.
- Fault conditions such as output shorted to ground, triggering overcurrent protection.
- Briefly energizing an inductive load such as motor or solenoid for a limited time, then de-energizing.

In these transient cases, the thermal impedance parameter Z_{eJA} denotes the junction-to-ambient thermal performance. The below figure shows the simulated thermal impedance for EVM under natural convection conditions using an FR4 2s2p board. The device (chip + package) was modeled on a 76.2 × 114.3 × 1.5mm board featuring two inner copper layers (two at 70μm Cu thickness and two at 35μm Cu thickness). Five thermal vias positioned beneath the exposed pad established contact with the first inner copper layer (12mm x 12mm). All simulations were performed at an ambient temperature of 25°C with power dissipation set at 1 W for the channel.

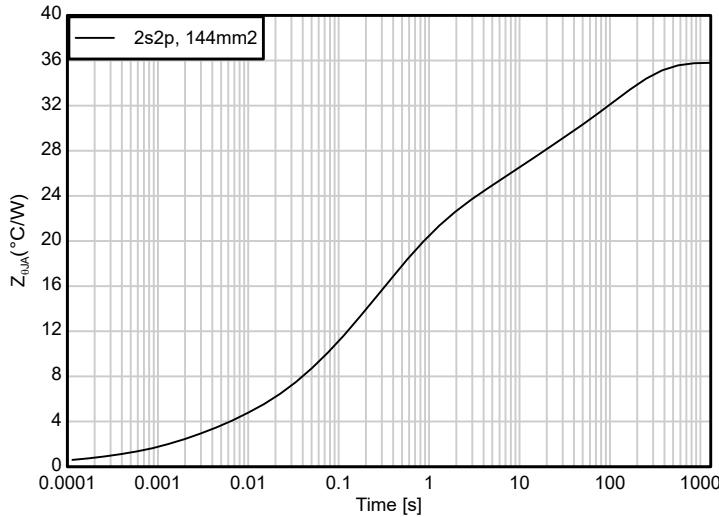


Figure 9-2. $Z_{\theta JA}$ (transient thermal impedance) with EVM 2s2p PCB Layout, 5 Thermal Vias Below Exposed Pad

9.2.4 Application Curves

The subscript "1" is sometimes used to refer the device channel in few images below.

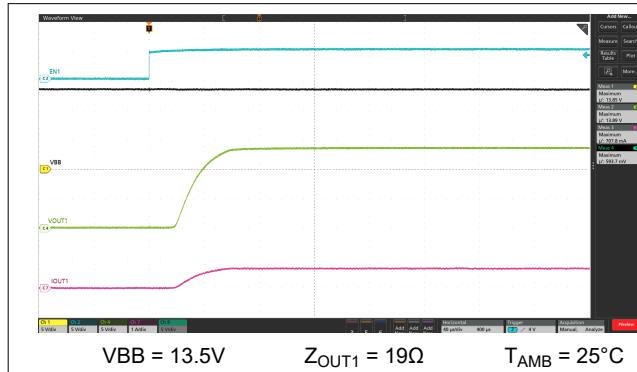


Figure 9-3. Turn-on with Resistive Load

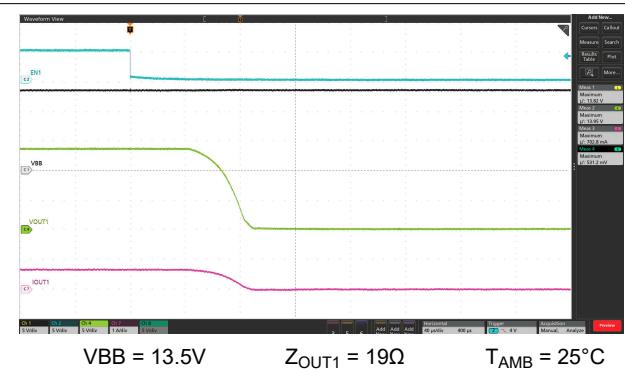


Figure 9-4. Turn-off with Resistive Load

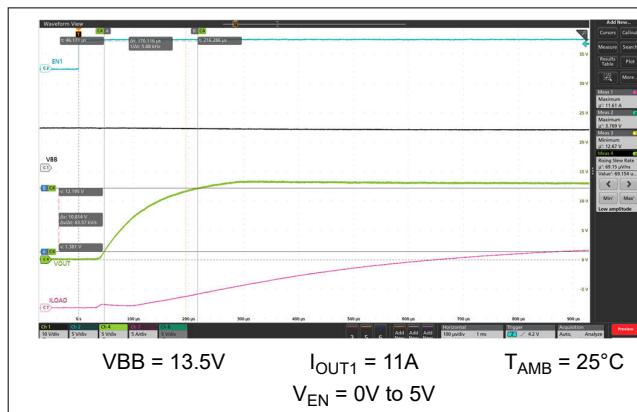


Figure 9-5. Rising Slew Rate (D, B version)

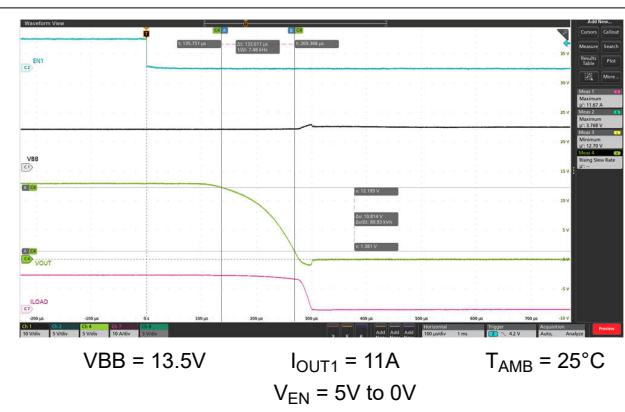
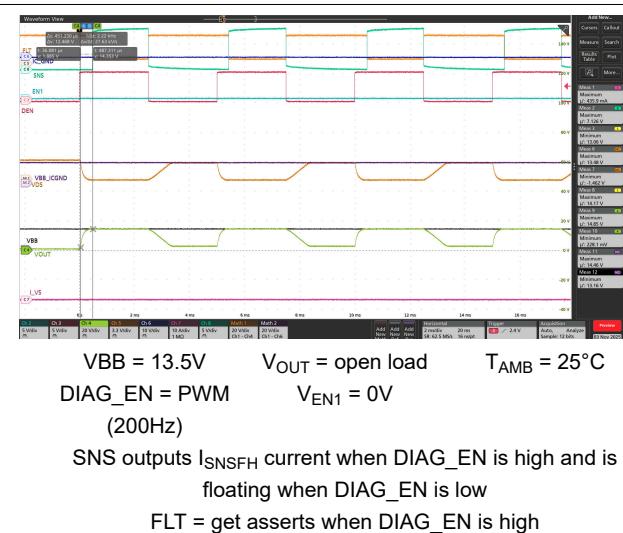
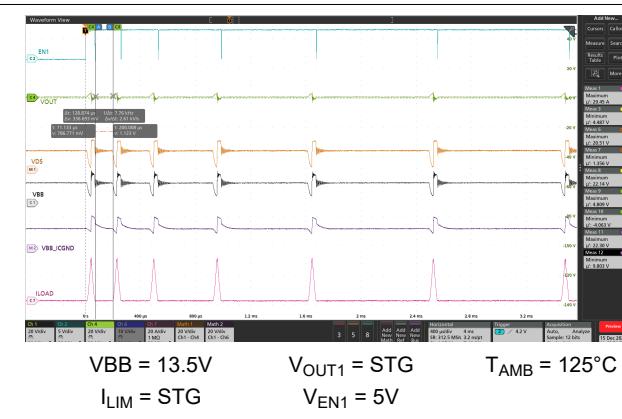
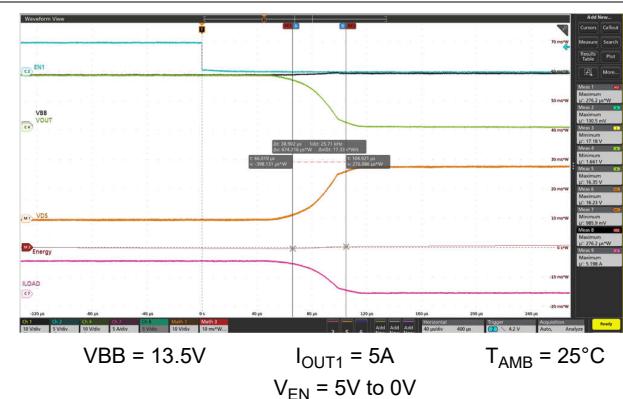
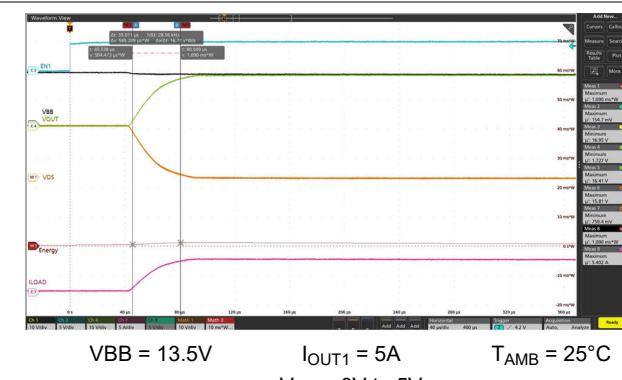


Figure 9-6. Falling Slew Rate (D, B version)



9.3 Power Supply Recommendations

The device is qualified for both automotive and industrial applications. The normal power supply connection is a 12V automotive system. The supply voltage must be within the range specified in the [Recommended Operating Conditions](#).

Table 9-5. Voltage Operating Ranges

| VBB VOLTAGE RANGE | NOTE |
|-------------------|---|
| 3V to 6V | Extended lower 12V automotive battery operation such as cold crank and start-stop. The device is fully functional and protected but some parametrics such as R_{ON} , current sense accuracy, current limit accuracy and timing parameters can deviate from specifications. Check the individual specifications in the <i>Electrical Characteristics</i> to confirm the voltage range. |
| 6V to 18V | Nominal 12V automotive battery voltage range. All parametric specifications apply and the device is fully functional and protected. |
| 18V to 28V | Extended upper 12V automotive battery operation such as double battery. The device is fully functional and protected (short-circuit protection up to 24V) but some parametrics such as R_{ON} , current sense accuracy, current limit accuracy, and timing parameters can deviate from specifications. Check the individual specifications in the <i>Electrical Characteristics</i> to confirm the voltage range. |
| 35V | Load dump voltage. Device is operational and lets the pulse pass through without being damaged but does not protect against short circuits. |

9.4 Layout

9.4.1 Layout Guidelines

To achieve good thermal performance, connect the VBB pad to a large copper pour. On the top PCB layer, the pour can extend beyond the package dimensions as shown in the layout examples below. In addition to this, having a VBB plane on one or more internal PCB layers and/or on the bottom layer is recommended. Vias must connect these planes to the top VBB pour. Connecting the VOUT pad to large copper pours on the board can also help to achieve better thermal performance as the heat can transfer through the internal copper pillars to the large copper pours on the board.

TI recommends that the IO signals that connect to the microcontroller be routed to a via and then through an internal PCB layer.

If used in the design, the C_{IC} capacitor, must be placed as close as possible to the VBB and GND pin of the device. If a ground network is used for reverse battery protection, the C_{IC} capacitor must be connected from the VBB net to the IC_GND net. The C_{VBB} capacitor must be placed close to the VBB pin and connected to system ground to allow for best performance.

The R_{LIM} component must be placed close to the ILIM and GND pin of the device. If a ground network is used for reverse battery protection, the R_{LIM} must be connected from the ILIM pin to the IC_GND net for expected current limit performance.

The FLT and SNS pin traces must be routed far apart (orthogonal or in different layers) to avoid any coupling between the two signals.

The TPS1HC03-Q1 device footprint is compatible with all other devices in the family and can be used for common board design.

9.4.2 Layout Examples

9.4.2.1 Without a GND Network

The below figure shows an example PCB layout without a GND network. TI recommends that the IO signals that connect to the microcontroller be routed to a via and then through an internal PCB layer.

LEGEND

■ = Module GND

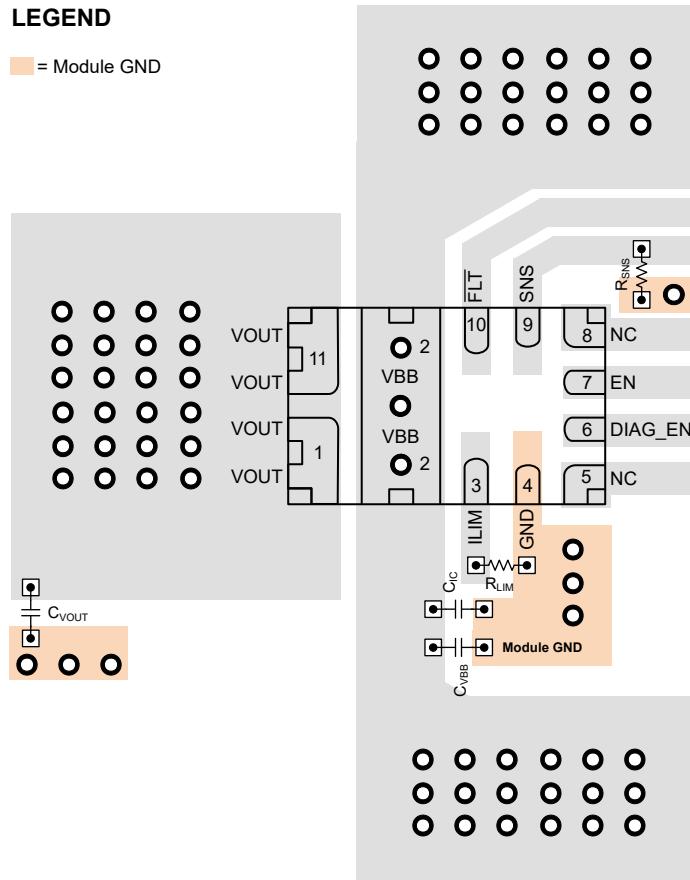


Figure 9-12. Layout Example without a GND Network

9.4.2.2 With a GND Network

The below figure shows an example PCB layout with a GND network. TI recommends that the IO signals that connect to the microcontroller be routed to a via and then through an internal PCB layer.

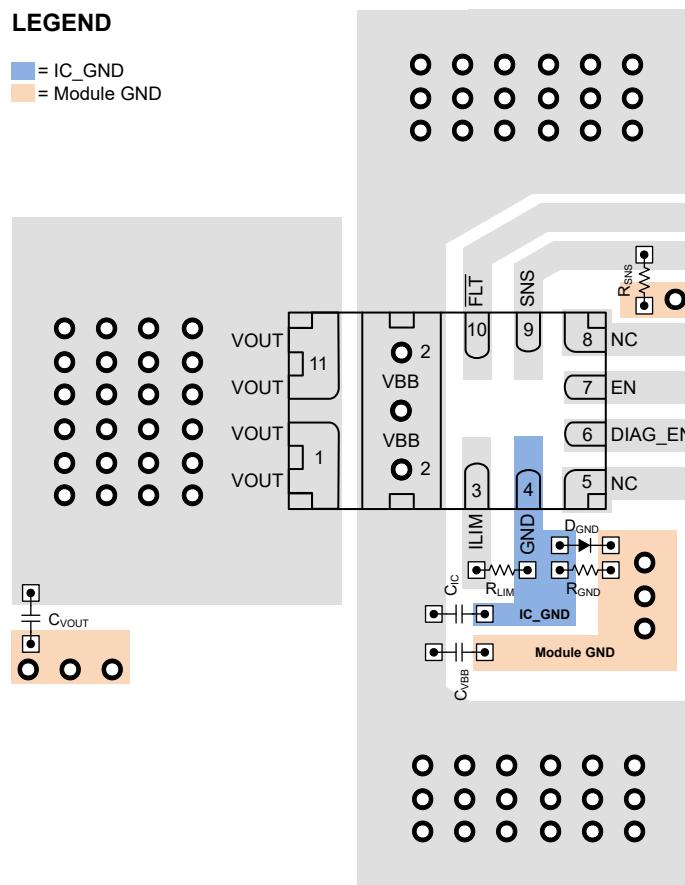


Figure 9-13. Layout Example with a GND Network

9.4.3 Wettable Flank Package

In traditional QFN packages, confirming proper solder connections to PCBs via Automatic Optical Inspection (AOI) is challenging. Exposed copper edges after package sawing are prone to oxidation, making reliable solder wetting difficult. Without a consistent solder fillet, proper solder connections cannot be visually confirmed during inspection.

To mitigate above challenge, wettable flank process employs mechanical and metallurgy-based techniques that enable the sidewall of QFN packages to be wettable to a specified height. This creates an inspectable solder fillet, providing visual confirmation of proper connection and meeting inspection requirements.

Wettable flank can be of three types – Dimple cut, Step cut and Immersion Tin. Dimple cut or step cut options feature visible grooves on package sidewalls, whereas the Immersion Sn approach uses tin plating on the sidewall without requiring physical grooves.

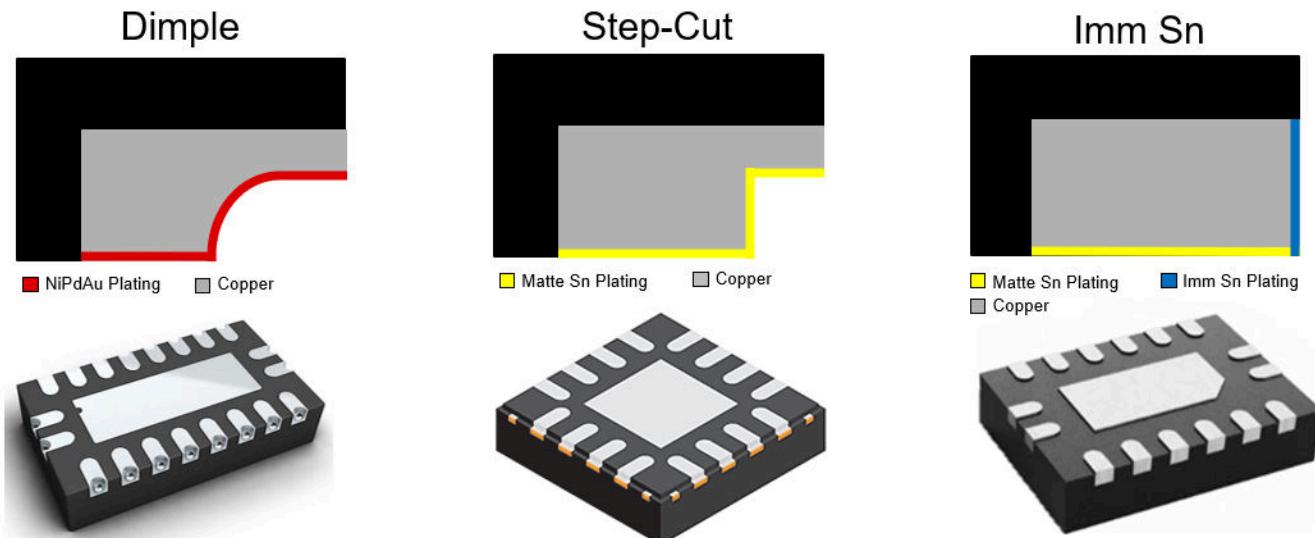


Figure 9-14. Types of Wettable Flank Packages

The VAH package of the TPS1HC08-Q1 uses the Immersion Sn plating option. This implementation meets industry requirements for minimum 100µm side-wetting of solder material, making sure reliable connections while allowing for automated optical inspection.

10 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

| DATE | REVISION | NOTES |
|---------------|----------|-----------------|
| December 2025 | * | Initial Release |

11 Device and Documentation Support

11.1 Third-Party Products Disclaimer

TI'S PUBLICATION OF INFORMATION REGARDING THIRD-PARTY PRODUCTS OR SERVICES DOES NOT CONSTITUTE AN ENDORSEMENT REGARDING THE SUITABILITY OF SUCH PRODUCTS OR SERVICES OR A WARRANTY, REPRESENTATION OR ENDORSEMENT OF SUCH PRODUCTS OR SERVICES, EITHER ALONE OR IN COMBINATION WITH ANY TI PRODUCT OR SERVICE.

11.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

11.3 Support Resources

[TI E2E™ support forums](#) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

11.4 Trademarks

TI E2E™ is a trademark of Texas Instruments.

All trademarks are the property of their respective owners.

11.5 Electrostatic Discharge Caution

 This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

11.6 Glossary

[TI Glossary](#) This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most-current data available for the designated device. This data is subject to change without notice and without revision of this document. For browser-based versions of this data sheet, see the left-hand navigation pane.

PACKAGING INFORMATION

| Orderable part number | Status (1) | Material type (2) | Package Pins | Package qty Carrier | RoHS (3) | Lead finish/ Ball material (4) | MSL rating/ Peak reflow (5) | Op temp (°C) | Part marking (6) |
|-----------------------|---------------|----------------------|--------------------|-----------------------|-------------|--------------------------------------|-----------------------------------|--------------|---------------------|
| TPS1HC08PQVAHRQ1 | Active | Production | VQFN-HR (VAH) 11 | 3000 LARGE T&R | - | Call TI | Level-2-260C-1 YEAR | -40 to 125 | 1HC08P |

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

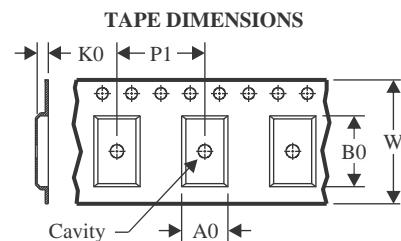
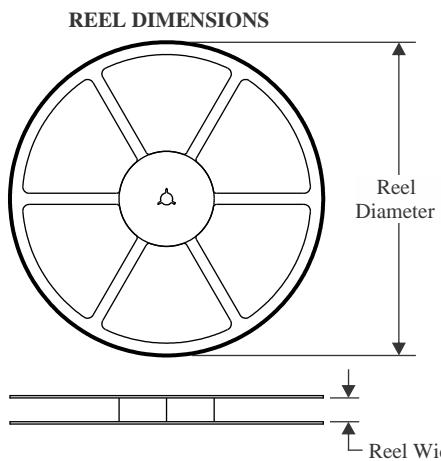
⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

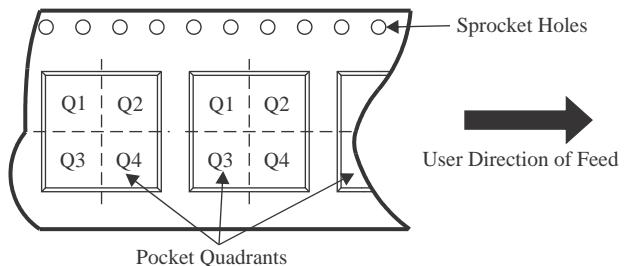
Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

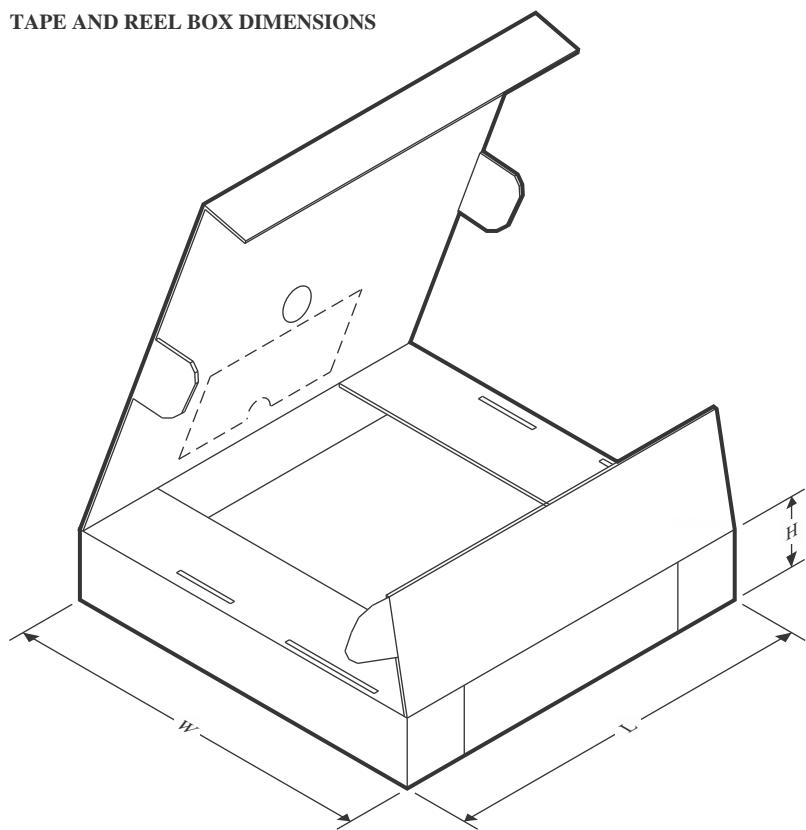
TAPE AND REEL INFORMATION


| | |
|----|---|
| A0 | Dimension designed to accommodate the component width |
| B0 | Dimension designed to accommodate the component length |
| K0 | Dimension designed to accommodate the component thickness |
| W | Overall width of the carrier tape |
| P1 | Pitch between successive cavity centers |

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE


*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|------------------|--------------|-----------------|------|------|--------------------|--------------------|---------|---------|---------|---------|--------|---------------|
| TPS1HC08PQVAHRQ1 | VQFN-HR | VAH | 11 | 3000 | 180.0 | 12.4 | 2.5 | 3.9 | 1.2 | 4.0 | 12.0 | Q1 |

TAPE AND REEL BOX DIMENSIONS


*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
|------------------|--------------|-----------------|------|------|-------------|------------|-------------|
| TPS1HC08PQVAHRQ1 | VQFN-HR | VAH | 11 | 3000 | 210.0 | 185.0 | 35.0 |

GENERIC PACKAGE VIEW

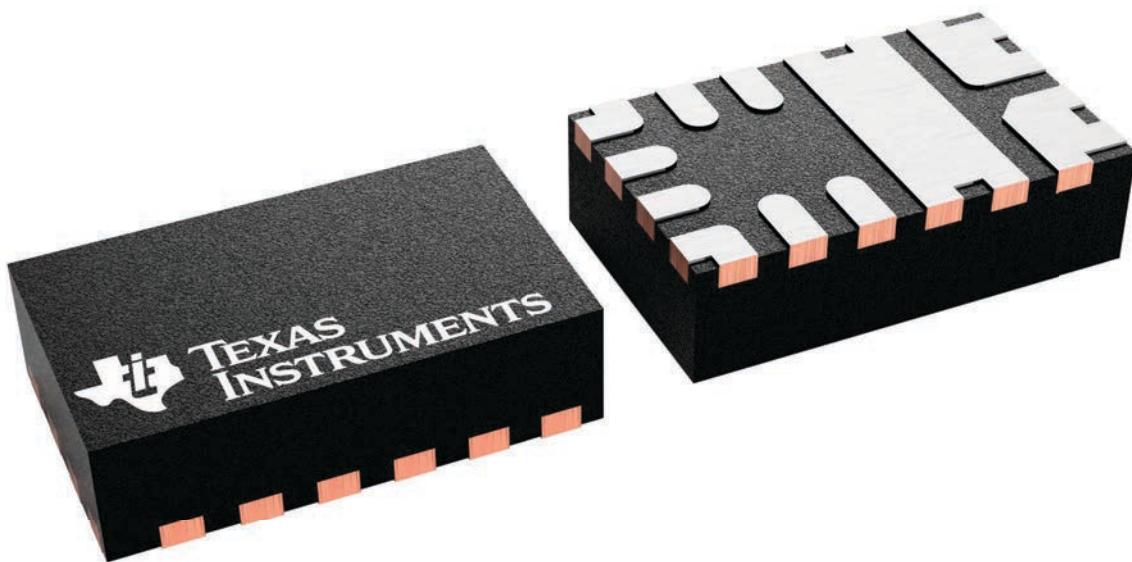
VAH 11

2.2 x 3.6, 0.5 mm pitch

VQFN-HR - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD

This image is a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.



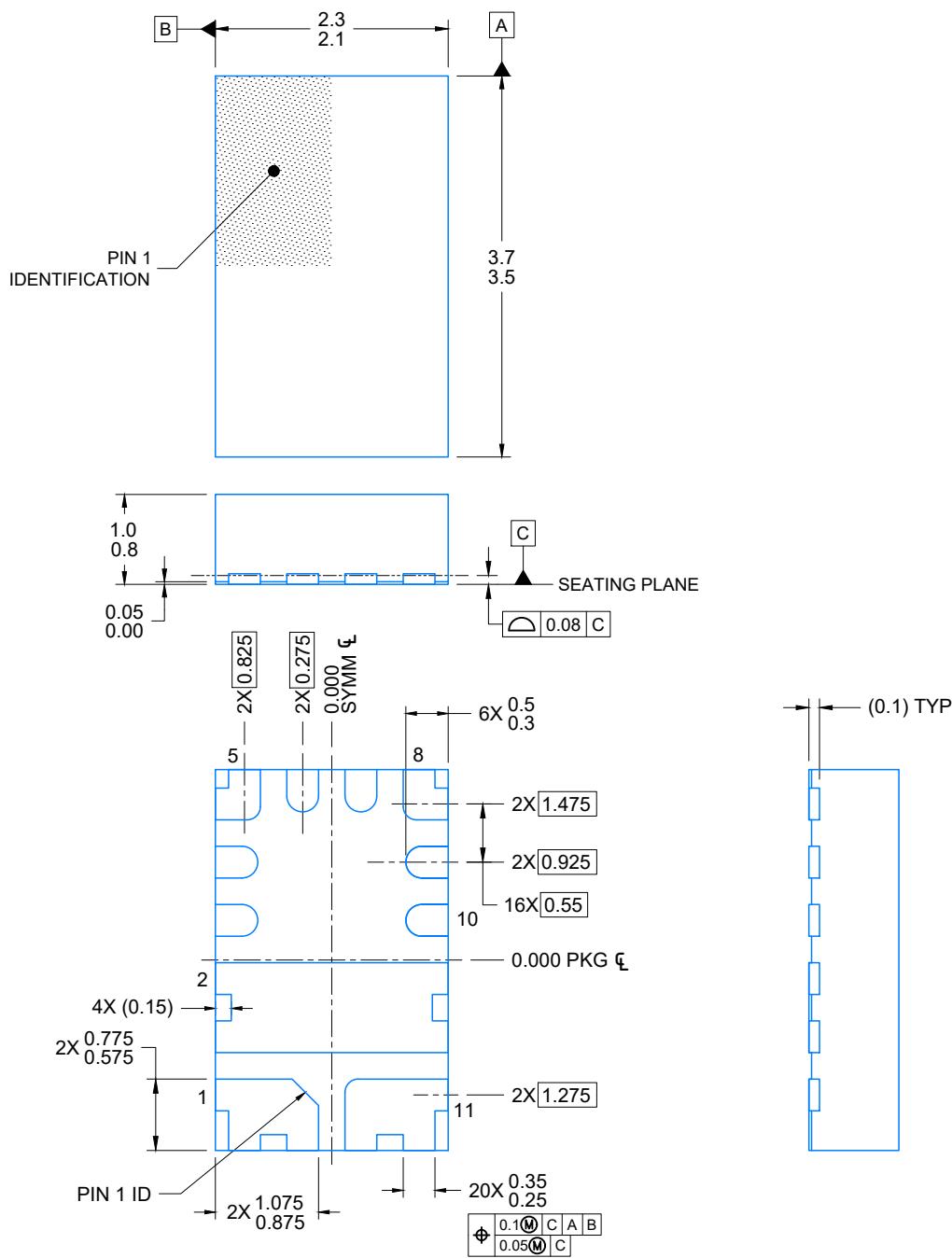
4230955/A

PACKAGE OUTLINE

VAH0011B

VQFN-HR - 1 mm max height

PLASTIC QUAD FLATPACK-NO LEAD



4230593/A 03/2024

NOTES:

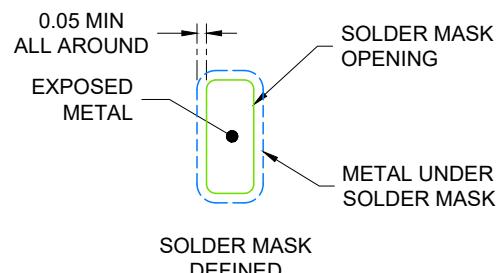
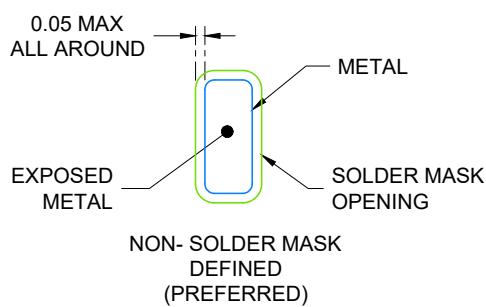
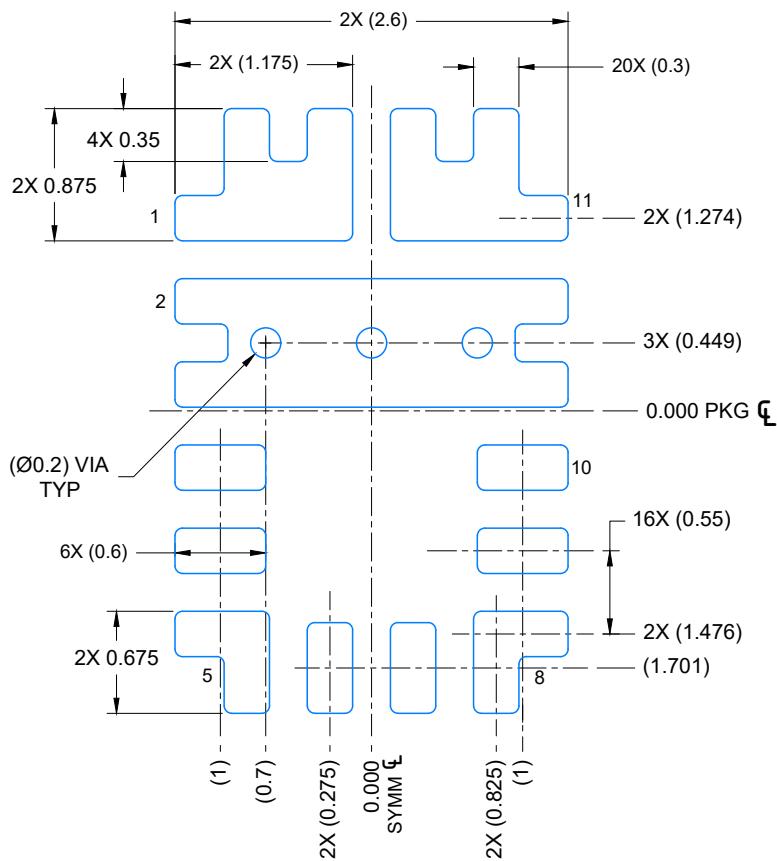
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.

EXAMPLE BOARD LAYOUT

VAH0011B

VQFN-HR - 1 mm max height

PLASTIC QUAD FLATPACK-NO LEAD



SOLDER MASK DETAILS
NOT TO SCALE

4230593/A 03/2024

NOTES: (continued)

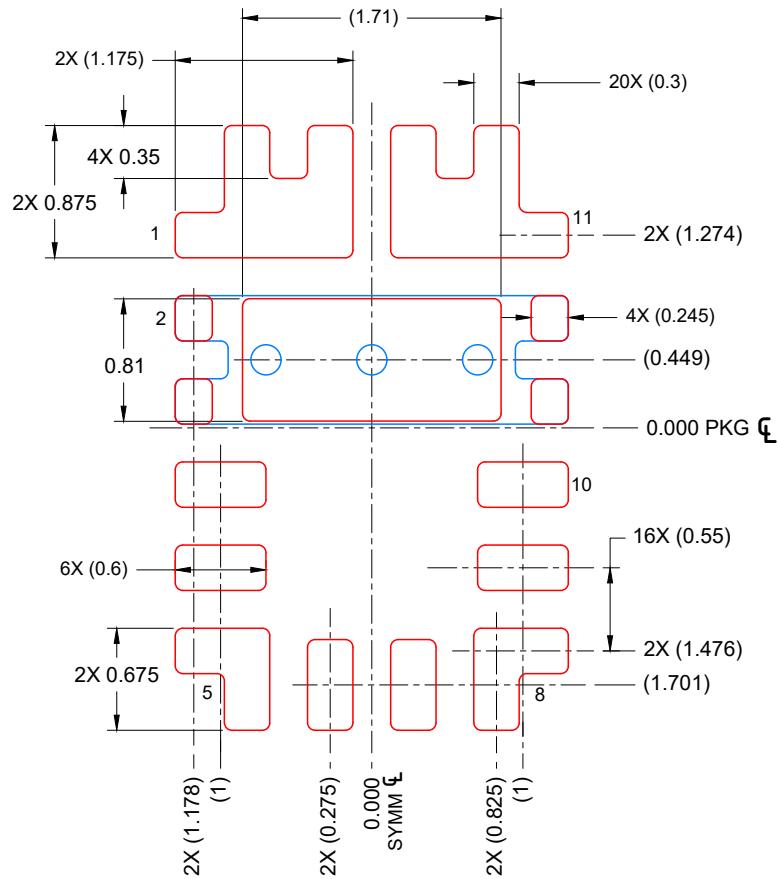
3. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
4. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

VAH0011B

VQFN-HR - 1 mm max height

PLASTIC QUAD FLATPACK-NO LEAD



**SOLDER PASTE EXAMPLE
BASED ON 0.1 mm THICK STENCIL
SCALE: 20X**

4230593/A 03/2024

NOTES: (continued)

5. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATASHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you fully indemnify TI and its representatives against any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to [TI's Terms of Sale](#), [TI's General Quality Guidelines](#), or other applicable terms available either on [ti.com](#) or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products. Unless TI explicitly designates a product as custom or customer-specified, TI products are standard, catalog, general purpose devices.

TI objects to and rejects any additional or different terms you may propose.

Copyright © 2026, Texas Instruments Incorporated

Last updated 10/2025