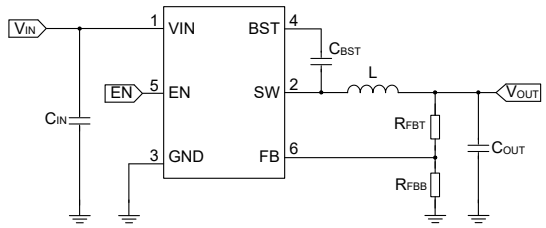
TPS56x24x 3V to 17V Input, 2A/3A, Synchronous Buck Converters in SOT-563 Package

1 Features

- Configured for a wide range of applications
  - 3V to 17V input voltage range
  - 0.6V to 10V output voltage range
  - 0.6V reference voltage
  - ±1% reference accuracy at 25°C
  - ±1.5% reference accuracy at –40°C to 125°C
  - Integrated 55.0mΩ and 24.3mΩ MOSFETs
  - 100µA low quiescent current
  - 1.2MHz switching frequency
  - Maximum 95% large duty cycle operation
  - Precision EN threshold voltage
  - 1.6ms fixed typical soft-start time
- Ease of use and small design size
  - TPS562242B, TPS563242 Eco-mode, TPS563247 FCCM mode at light loading
  - D-CAP3™ control mode
  - Easy layout with integrated bootstrap capacitor
  - Supports start-up with prebiased output
  - Non-latch for OV, OT, and UVLO protection
  - Hiccup mode for UV protection
  - Cycle-by-cycle OC and NOC protection
  - 1.6mm × 1.6mm SOT-563 package
- Create a custom design using the TPS56x24x with the WEBENCH® Power Designer

2 Applications

- WLAN/Wi-Fi access point, switch, router
- Appliances, video recorder
- Pro-audio, surveillance, drone
- TV, STB and DVR, smart speaker



Simplified Application

3 Description

The TPS56x24x is a simple, easy-to-use, high efficiency, high power density, synchronous buck converter with input voltage ranging from 3V to 17V and supports up to 2A (TPS562242B), 3A (TPS563242, TPS563247) continuous current at output voltages between 0.6V and 10V.

The TPS56x24x employs D-CAP3 control mode to provide a fast transient response and to support low-ESR output capacitors with no requirement for external compensation. The device can support up to 95% duty cycle operation.

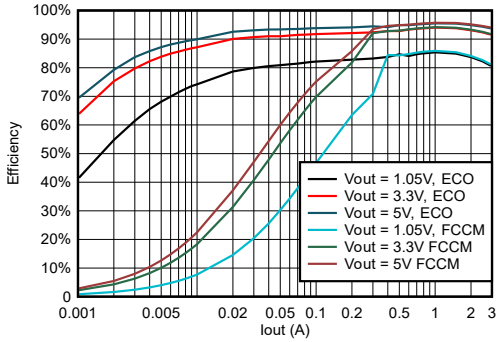
The TPS562242B and TPS563242 operate in Eco-mode, which maintains high efficiency during light loading. The TPS563247 operates in FCCM mode, which keeps the same frequency and lower output ripple during all load conditions. The devices integrate complete protection through OVP, OCP, UVLO, OTP, and UVP with hiccup.

The device is available in 1.6mm × 1.6mm SOT-563 package. The junction temperature is specified from –40°C to 125°C.

Device Information

PART NUMBER	MODE	PACKAGE(1)
TPS562242B	ECO	DRL (SOT-563, 6)
TPS563242	ECO	
TPS563247	FCCM	

(1) For more information, see Section 10.



TPS56324x Efficiency at V_{IN} = 12V

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4 Pin Configuration and Functions

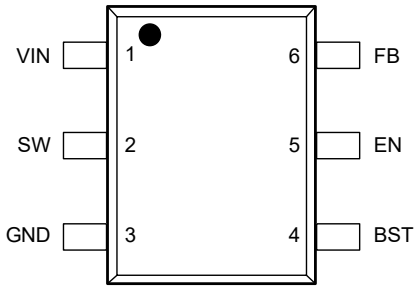


Figure 4-1. 6-Pin SOT563 DRL Package (Top View)

Table 4-1. Pin Functions

PIN		TYPE(1)	DESCRIPTION
NAME	NO.		
VIN	1	P	Input voltage supply pin. Connect the input decoupling capacitors between VIN and GND.
SW	2	P	Switch node pin. Connect the output inductor to this pin.
GND	3	G	GND pin for the controller circuit and the internal circuitry.
BST	4	P	Connect a 100nF ceramic capacitor from this pin to the SW pin or leave the pin floating.
EN	5	A	Enable control input. Driving EN high enables the converter.
FB	6	A	Converter feedback input. Connect to output voltage with a feedback resistor divider.

(1) A = Analog, P = Power, G = Ground

5 Specifications

5.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)(1)

		MIN	MAX	UNIT
Pin voltage(2)	VIN	–0.3	18	V
	FB, EN	–0.3	6	V
	GND	–0.3	0.3	V
	SW	–2	18	V
	SW (transient < 20ns)	–5.5	20	V
	BST	–2	18	V
	BST (transient < 20ns)	–5.5	20	V
Operating junction temperature, T_J		–40	150	°C
Storage temperature, T_{stg}		–55	150	°C

(1) Operation outside the *Absolute Maximum Ratings* may cause permanent device damage. *Absolute Maximum Ratings* do not imply functional operation of the device at these or any other conditions beyond those listed under *Recommended Operating Conditions*. If used outside the *Recommended Operating Conditions* but within the *Absolute Maximum Ratings*, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.
(2) All voltage values are with respect to the network ground pin.

5.2 ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001(1), all pins	±2000	V
		Charged-device model (CDM), per ANSI/ESDA/JEDEC JS-002(2)	±500	

(1) JEDEC document JEP155 states that 500V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 250V CDM allows safe manufacturing with a standard ESD control process.

5.3 Recommended Operating Conditions

Over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
Pin voltage	VIN	3		17	V
	FB, EN	–0.1		5.5	
	GND	–0.1		0.1	
	SW	–1		17	
	SW (transient < 20ns)	–5		18	
	BST	–1		17	
	BST (transient < 20ns)	–5		18	
Output current	I_{OUT}	0		2 (TPS562242B) 3 (TPS563242, TPS563247)	A
Temperature	Operating junction temperature, T_J	–40		125	°C
	Storage temperature, T_{stg}	–40		150	

5.4 Thermal Information

THERMAL METRIC(1)		DRL (SOT-563)	UNIT
		6 PINS	
$R_{\theta JA}$ (2)	Junction-to-ambient thermal resistance	137.4	°C/W
$R_{\theta JA\_effective}$ (3)	Junction-to-ambient thermal resistance on EVM board	74	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	58.8	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	29.8	°C/W
ψ_{JT}	Junction-to-top characterization parameter	1.3	°C/W
ψ_{JB}	Junction-to-board characterization parameter	29.4	°C/W

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application note.
(2) The value of $R_{\theta JA}$ given in this table is only valid for comparison with other packages and cannot be used for design purposes. These values are simulated on a standard JEDEC board. These values do not represent the performance obtained in an actual application.
(3) This $R_{\theta JA\_effective}$ is tested on TPS563242EVM board (2 layer, copper thickness is 2oz) at V_{IN} = 12V, V_{OUT} = 5V, I_{OUT} = 3A, T_A = 25°C.

5.5 Electrical Characteristics

T_J = –40°C to 125°C, V_{IN} = 12V (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
INPUT SUPPLY VOLTAGE						
V_{IN}	Input voltage range	V_{IN}	3		17	V
I_{VIN}	VIN supply current	No load, V_{EN} = 5V, V_{FB} = 0.65V, non-switching, ECO version		100		µA
		No load, V_{EN} = 5V, V_{FB} = 0.65V, non-switching, FCCM version		370		µA
I_{INSDN}	VIN shutdown current	No load, V_{EN} = 0V		2		µA
UVLO						
V_{IN_UVLO}	Input undervoltage lockout threshold	Rising threshold	2.80	2.92	3.00	V
		Falling threshold	2.60	2.72	2.80	V
		Hysteresis		200		mV
FEEDBACK VOLTAGE						
V_{REF}	FB voltage	T_J = 25°C	594	600	606	mV
		T_J = –40°C to 125°C	591	600	609	mV
INTEGRATED POWER MOSFETS						
R_{DSON_HS}	High-side MOSFET on-resistance	T_J = 25°C, V_{IN} ≥ 5V		55.0		mΩ
		T_J = 25°C, V_{IN} = 3V (1)		67.5		mΩ
R_{DSON_LS}	Low-side MOSFET on-resistance	T_J = 25°C, V_{IN} ≥ 5V		24.3		mΩ
		T_J = 25°C, V_{IN} = 3V		30.2		mΩ
SWITCHING FREQUENCY						
f_{sw}	Switching frequency	T_J = 25°C, V_{OUT} = 3.3V		1.2		MHz
$t_{ON(MIN)}$ (1)	Minimum on time			60		ns
$t_{OFF(MIN)}$ (1)	Minimum off time	V_{FB} = 0.5V		110		ns
LOGIC THRESHOLD						
V_{ENH}	EN threshold high level	Rising enable threshold	1.15	1.19	1.25	V
V_{ENL}	EN threshold low level	Falling disable threshold	0.90	1.00	1.10	V
V_{ENHYS}	EN hysteresis	Hysteresis		190		mV
R_{EN}	EN pulldown resistor			2		MΩ

5.5 Electrical Characteristics (continued)

T_J = –40°C to 125°C, V_{IN} = 12V (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
CURRENT LIMIT						
I_{OCL_LS}	Overcurrent threshold	Valley current set point (TPS562242B)	2.3	3.0	3.6	A
I_{OCL_LS}	Overcurrent threshold	Valley current set point (TPS563242, TPS563247)	3.1	4.1	5.0	A
I_{NOC}	Negative overcurrent threshold	(TPS563247)	1.5	2.1	2.5	A
SOFT START						
t_{SS}	Internal soft-start time			1.6		ms
OUTPUT OVERVOLTAGE AND UNDERVOLTAGE PROTECTION						
V_{OVP}	OVP trip threshold	V_{FB} rising	110%	115%	120%	
t_{OVPDLY}	OVP prop deglitch			24		µs
V_{UVP}	UVP trip threshold	V_{FB} falling	55%	60%	65%	
t_{UVPDLY}	UVP prop deglitch			220		µs
t_{UVPEN}	Hiccup enable delay time	UVP detect		14		ms
THERMAL SHUTDOWN						
T_{SDN} (1)	Thermal shutdown threshold	Shutdown temperature		155		°C
T_{OTPHSY} (1)		Hysteresis		20		

(1) Specified by design

5.6 Typical Characteristics

T_J = –40°C to 125°C, V_{IN} = 12V (unless otherwise noted)

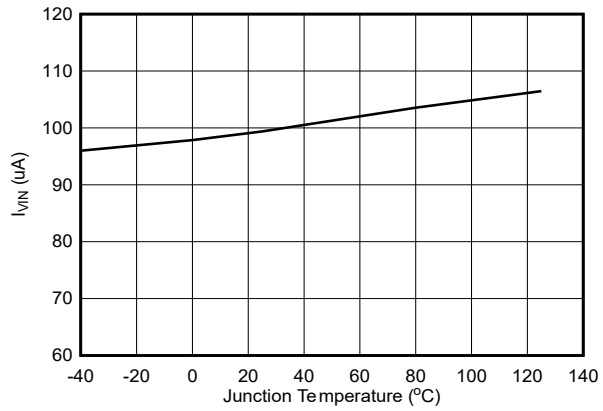


Figure 5-1. TPS562242B, TPS563242 Quiescent Current

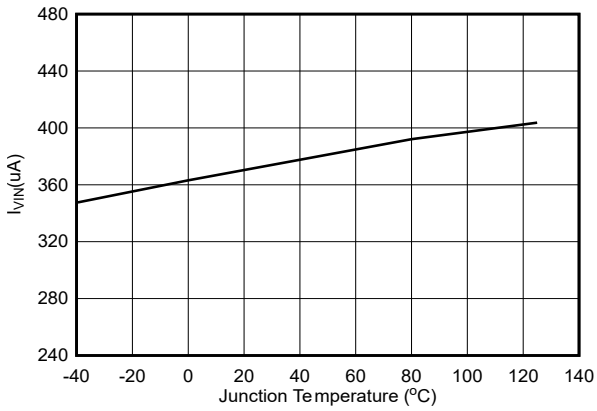


Figure 5-2. TPS563247 Quiescent Current

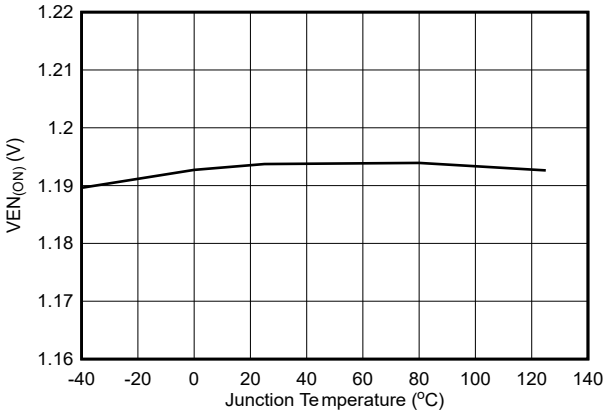


Figure 5-3. Enable On Threshold Voltage

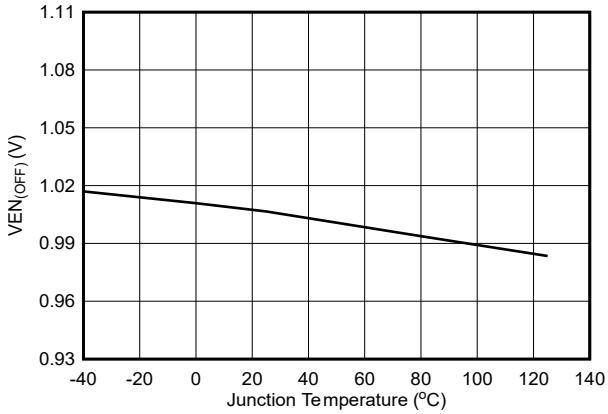


Figure 5-4. Enable Off Threshold Voltage

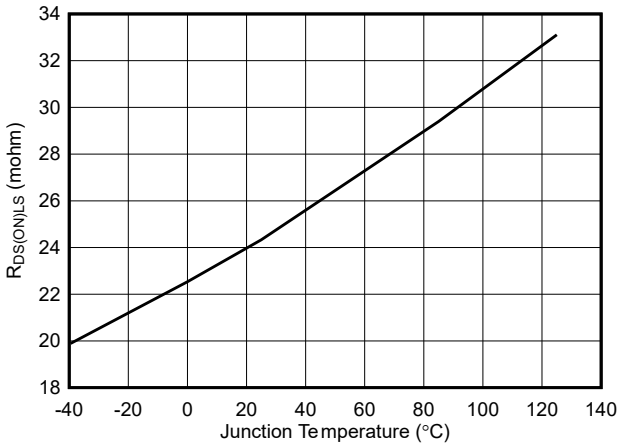


Figure 5-5. Low-Side $R_{DS(ON)}$

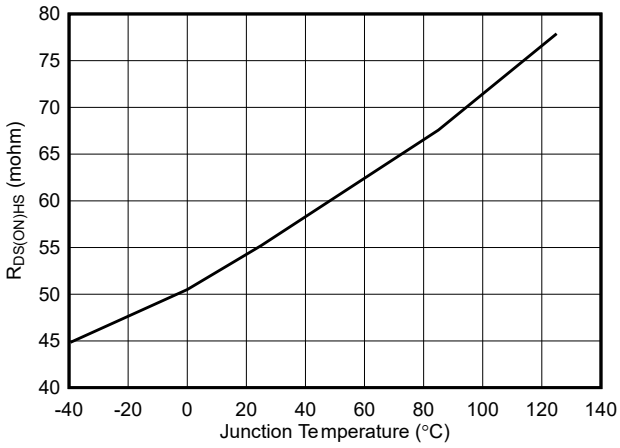


Figure 5-6. High-Side $R_{DS(ON)}$

5.6 Typical Characteristics (continued)

T_J = –40°C to 125°C, V_{IN} = 12V (unless otherwise noted)

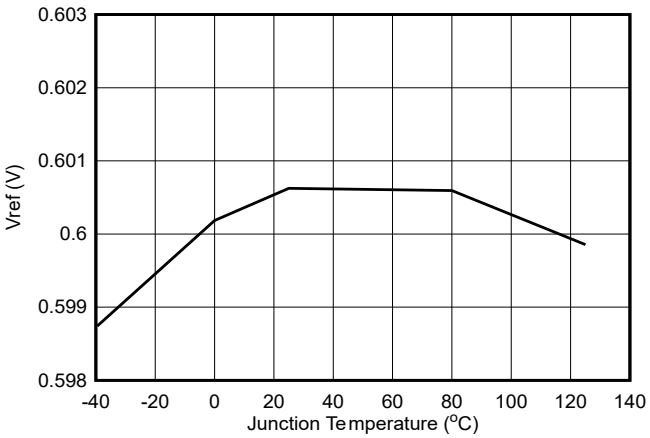


Figure 5-7. VREF Voltage

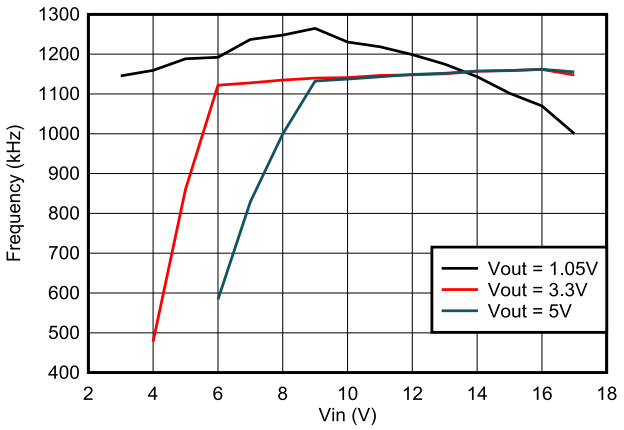


Figure 5-8. Frequency vs Input Voltage, I_{OUT} = 3A

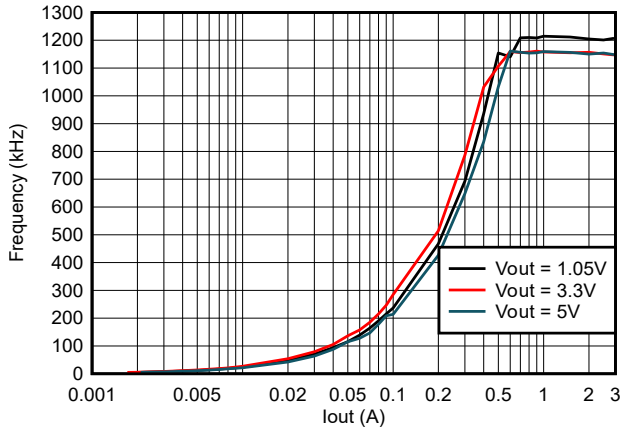


Figure 5-9. TPS563242 Frequency vs Loading, V_{IN} = 12V

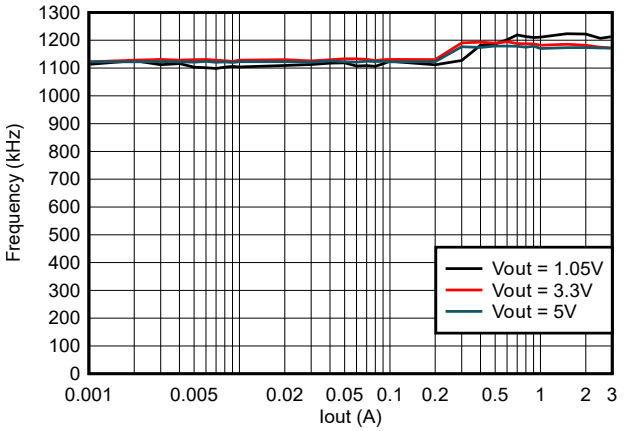


Figure 5-10. TPS563247 Frequency vs Loading, V_{IN} = 12V

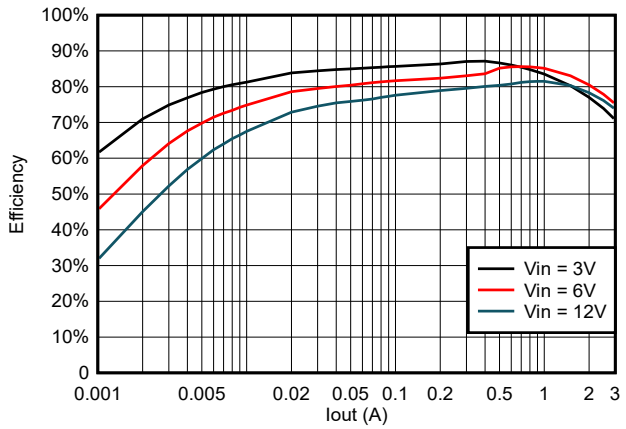


Figure 5-11. TPS563242 Efficiency at 0.6 V_{OUT} With a 0.68µH Inductor

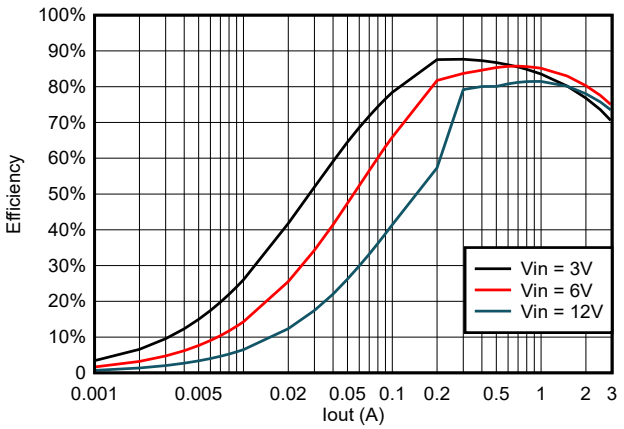


Figure 5-12. TPS563247 Efficiency at 0.6 V_{OUT} With a 0.68µH Inductor

5.6 Typical Characteristics (continued)

T_J = –40°C to 125°C, V_{IN} = 12V (unless otherwise noted)

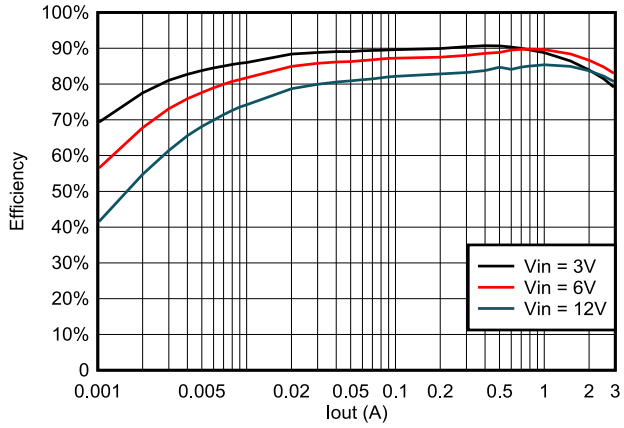


Figure 5-13. TPS563242 Efficiency at 1.05 V_{OUT} With a 0.82µH Inductor

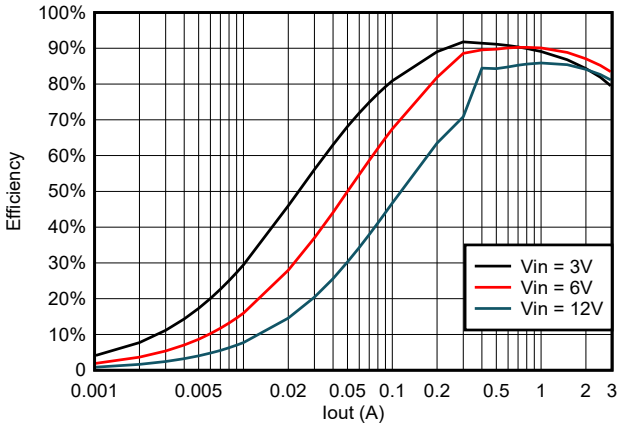


Figure 5-14. TPS563247 Efficiency at 1.05 V_{OUT} With a 0.82µH Inductor

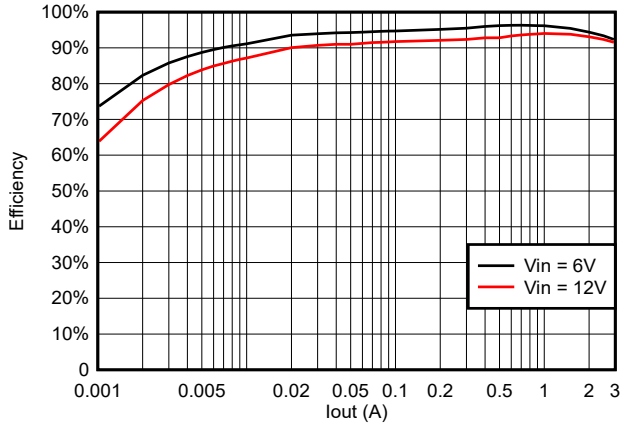


Figure 5-15. TPS563242 Efficiency at 3.3 V_{OUT} With a 2.2µH Inductor

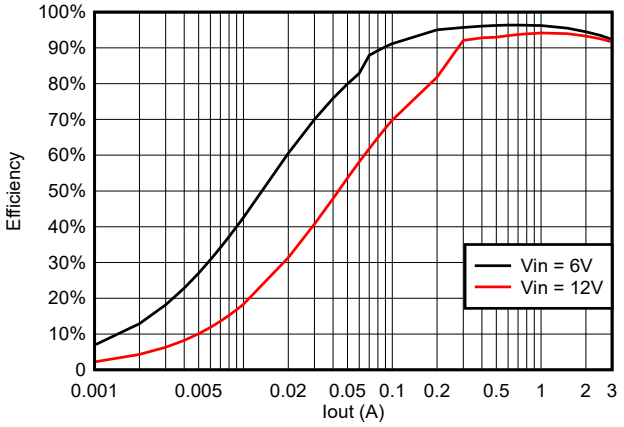


Figure 5-16. TPS563247 Efficiency at 3.3 V_{OUT} With a 2.2µH Inductor

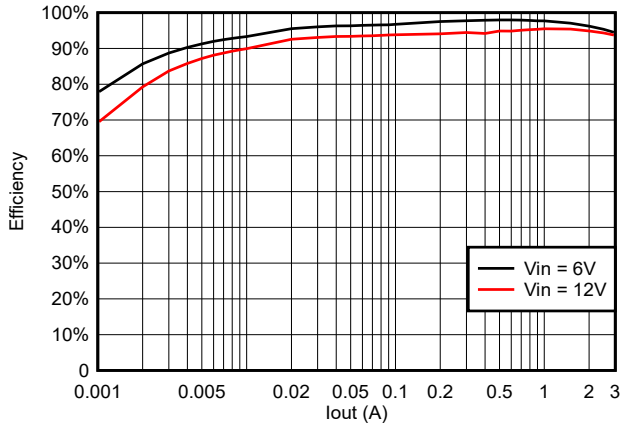


Figure 5-17. TPS563242 Efficiency at 5 V_{OUT} With a 2.2µH Inductor

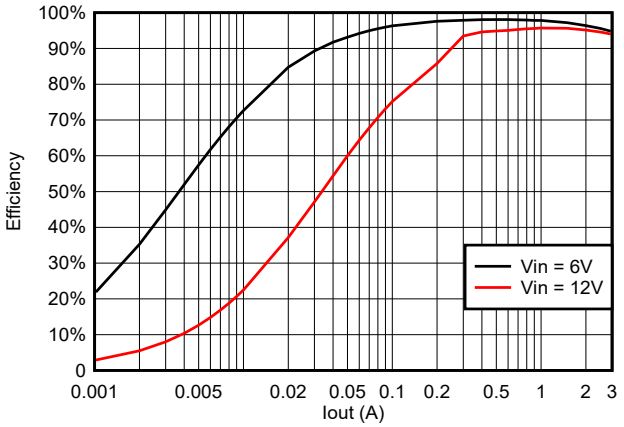


Figure 5-18. TPS563247 Efficiency at 5 V_{OUT} With a 2.2µH Inductor

5.6 Typical Characteristics (continued)

T_J = –40°C to 125°C, V_{IN} = 12V (unless otherwise noted)

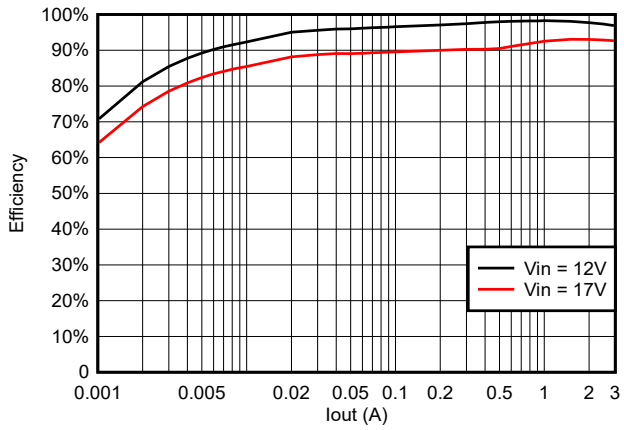


Figure 5-19. TPS563242 Efficiency at 10 V_{OUT} With a 4.7µH Inductor

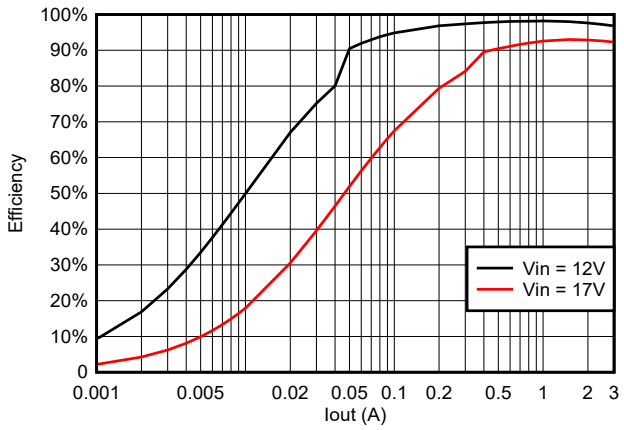


Figure 5-20. TPS563247 Efficiency at 10 V_{OUT} With a 4.7µH Inductor

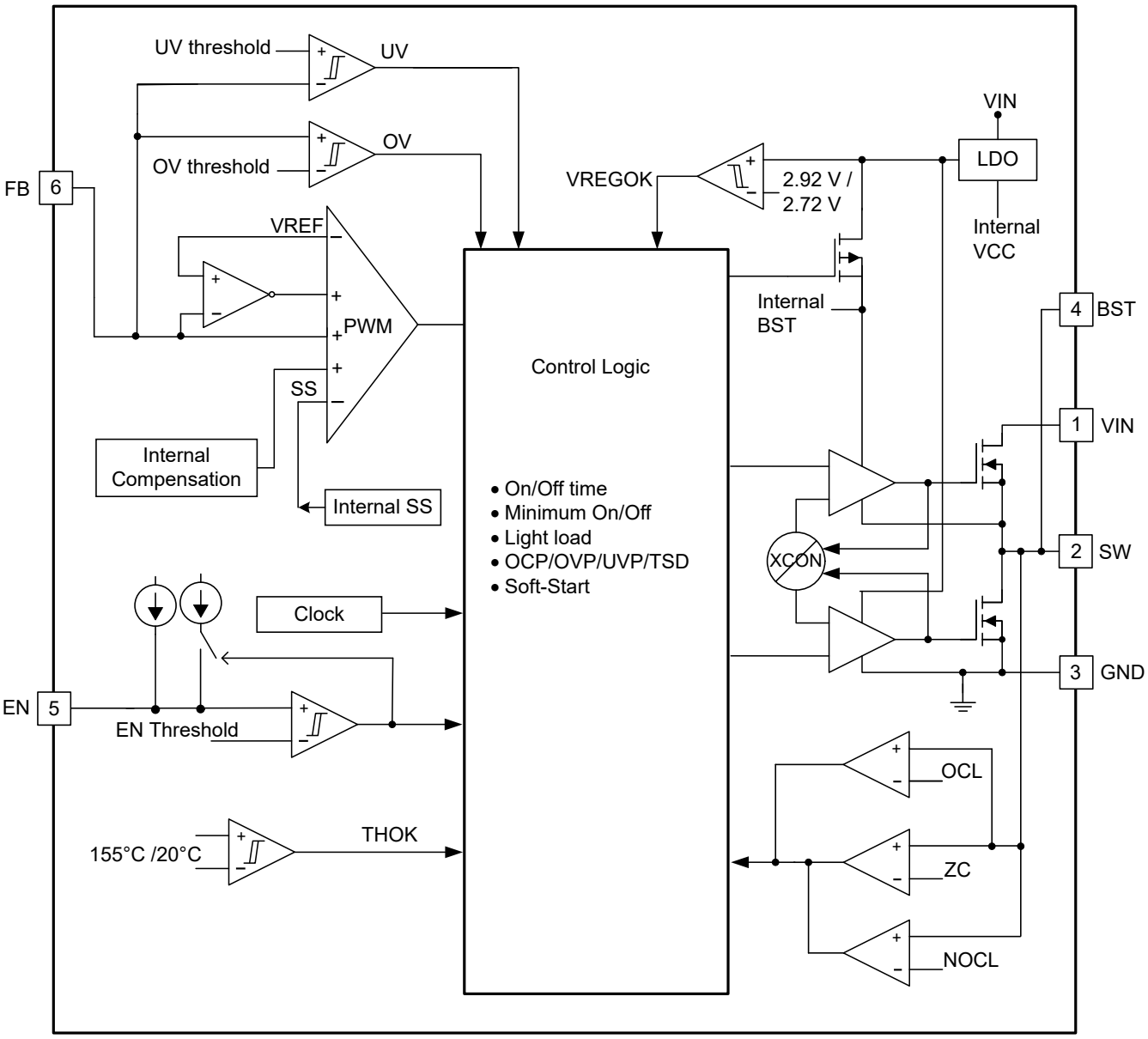
6 Detailed Description

6.1 Overview

The TPS56x24x is a 2A and 3A integrated FET synchronous buck converter that operates from 3V to 17V input voltage and 0.6V to 10V output voltage. The device employs a D-CAP3 control mode that provides fast transient response with no external compensation components and an accurate feedback voltage. The proprietary D-CAP3 control mode enables low external component count, ease of design, and optimization of the power design for cost, size, and efficiency. The topology provides a seamless transition between CCM operating mode at higher load condition and DCM operation mode at lighter load condition.

The Eco-mode version allows the TPS562242B and TPS563242 to maintain high efficiency at light load. The FCCM version allows the TPS563247 to maintain a fixed switching frequency and lower voltage output ripple. The TPS56x24x is able to adapt to both low equivalent series resistance (ESR) output capacitors such as POSCAP or SP-CAP, and ultra-low ESR ceramic capacitors.

6.2 Functional Block Diagram



6.3 Feature Description

6.3.1 PWM Operation and D-CAP3™ Control Mode

The main control loop of the buck is an adaptive on-time pulse width modulation (PWM) controller that supports a proprietary D-CAP3 control mode. The D-CAP3 control mode combines adaptive on-time control with an internal compensation circuit for pseudo-fixed frequency and low external component count configuration with both low-ESR and ceramic output capacitors. The device is stable even with virtually no ripple at the output. The TPS56x24x also includes an error amplifier that makes the output voltage very accurate.

At the beginning of each cycle, the high-side MOSFET is turned on. This MOSFET is turned off after an internal one-shot timer expires. This one-shot duration is set proportional to the output voltage, V_{OUT}, and is inversely proportional to the converter input voltage, V_{IN}, to maintain a pseudo-fixed frequency over the input voltage range, therefore called adaptive on-time control. The one-shot timer is reset and the high-side MOSFET is

turned on again when the feedback voltage falls below the reference voltage. An internal ripple generation circuit is added to reference voltage to emulate the output ripple, enabling the use of very low-ESR output capacitors such as multi-layered ceramic caps (MLCC). No external current sense network or loop compensation is required for D-CAP3 control mode.

6.3.2 Eco-mode Control

The TPS562242B, and TPS563242 are designed with advanced Eco-mode to maintain high light-load efficiency. As the output current decreases from heavy load condition, the inductor current is also reduced and eventually comes to point that the ripple valley touches zero level, which is the boundary between continuous conduction and discontinuous conduction mode. The rectifying MOSFET is turned off when the zero inductor current is detected. As the load current further decreases, the converter runs into discontinuous conduction mode. The on time is kept almost the same as in continuous conduction mode so that discharging the output capacitor with smaller load current to the level of the reference voltage takes longer time. This action makes the switching frequency lower, proportional to the load current, and keeps the light load efficiency high. Use the following equation to calculate the transition point to the light load operation $I_{OUT(LL)}$ current.

$$I_{OUT(LL)} = \frac{1}{2 \times L \times f_{SW}} \times \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{V_{IN}} \quad (1)$$

6.3.3 Soft Start and Prebiased Soft Start

The TPS56x24x has an internal fixed 1.6ms soft-start time. The EN default status is low. When the EN pin becomes high, the internal soft-start function begins ramping up the reference voltage to the PWM comparator.

If the output capacitor is prebiased at start-up, the devices initiate switching and start ramping up only after the internal reference voltage becomes higher than the feedback voltage, V_{FB}. This scheme makes sure that the converter ramps up smoothly into the regulation point.

6.3.4 Overvoltage Protection

The TPS56x24x has the overvoltage protection feature. When the output voltage becomes higher than the OVP threshold, the OVP is triggered with a 24µs deglitch time. Both the high-side MOSFET and the low-side MOSFET drivers are turned off. When the overvoltage condition is removed, the device returns to switching.

6.3.5 Large Duty Operation

The TPS56x24x can support large duty operations up to 95% by smoothly dropping down the switching frequency. When V_{IN} / V_{OUT} < 1.6 and V_{FB} is lower than internal V_{REF}, the switching frequency is allowed to smoothly drop to make t_{ON} extended to implement the large duty operation and improve the performance of the load transient. Please refer to the frequency test waveform in Figure 5-8. The minimum switching frequency is limited to approximately 450kHz.

6.3.6 Current Protection and Undervoltage Protection

The output overcurrent limit (OCL) is implemented using a cycle-by-cycle valley detect control circuit. The switch current is monitored during the off state by measuring the low-side FET drain-to-source voltage. This voltage is proportional to the switch current. To improve accuracy, the voltage sensing is temperature compensated.

During the on time of the high-side FET switch, the switch current increases at a linear rate determined by the following:

- V_{IN}
- V_{OUT}
- On-time
- Output inductor value

During the on time of the low-side FET switch, this current decreases linearly. The average value of the switch current is the load current, I_{OUT}. If the monitored valley current is above the OCL level, the converter maintains a low-side FET on and delays the creation of a new set pulse, even the voltage feedback loop requires one, until

the current level becomes OCL level or lower. In subsequent switching cycles, the on time is set to a fixed value and the current is monitored in the same manner.

There are some important considerations for this type of overcurrent protection. The load current is higher than the overcurrent threshold by one half of the peak-to-peak inductor ripple current. Also, when the current is being limited, the output voltage tends to fall as the demanded load current can be higher than the current available from the converter, which can cause the output voltage to fall. When the FB voltage falls below the UVP threshold voltage, the UVP comparator detects this fall and the device shuts down after the UVP delay time (typically 220µs) and restarts after the hiccup wait time (typically 14ms). After the device enters the hiccup cycling, the hiccup on time is typically 2.2ms.

When the overcurrent condition is removed, the output voltage returns to the regulated value.

The TPS563247 is a FCCM mode part. In this mode, the device has negative inductor current at light loading. The device has NOC (negative overcurrent) protection to avoid too large negative current. NOC protection detects the valley of inductor current. When the valley value of inductor current exceeds the NOC threshold, the device turns off the low-side FET then turns on the high-side FET. When the NOC condition is removed, the device returns to normal switching.

Because the TPS563247 is an FCCM mode port, if the inductance is so small that the device triggers NOC, this action causes the output voltage to be higher than target value. The minimum inductance is identified as Equation 2.

$$L = \frac{V_{OUT} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)}{2 \times \text{Frequency} \times NOC_{(min)}} \quad (2)$$

6.3.7 Undervoltage Lockout (UVLO) Protection

UVLO protection monitors the internal regulator voltage. When the voltage is lower than UVLO threshold voltage, the device is shut off. This protection is a non-latch protection.

6.3.8 Thermal Shutdown

The device monitors the temperature of the device. If the temperature exceeds the threshold value, the device is shut off. This protection is a non-latch protection.

6.4 Device Functional Modes

6.4.1 Eco-mode Operation

The TPS562242B and TPS563242 operate in Eco-mode, which maintains high efficiency at light loading. As the output current decreases from heavy load conditions, the inductor current is also reduced and eventually comes to a point where the rippled valley touches zero level, which is the boundary between continuous conduction and discontinuous conduction mode. The rectifying MOSFET is turned off when the zero inductor current is detected. As the load current further decreases, the converter runs into discontinuous conduction mode. The on time is kept almost the same as in continuous conduction mode so that discharging the output capacitor with smaller load current to the level of the reference voltage takes longer time. This action makes the switching frequency lower, proportional to the load current, and keeps the light load efficiency high.

6.4.2 FCCM Mode Operation

The TPS563247 operates in forced CCM (FCCM) mode, which keeps the converter operating in continuous current mode during light load conditions and allows the inductor current to become negative. During FCCM mode, the switching frequency is maintained at an almost constant level over the entire load range, which is designed for applications requiring tight control of the switching frequency and output voltage ripple at the cost of lower efficiency under light load.

7 Application and Implementation

Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

7.1 Application Information

The device is a typical buck DC/DC converter that is typically used to convert a higher DC voltage to a lower DC voltage with a maximum available output current of 2A and 3A. The following design procedure can be used to select component values for TPS56x24x. Alternately, the WEBENCH Power Designer software can be used to generate a complete design. The WEBENCH Power Designer software uses an iterative design procedure and accesses a comprehensive database of components when generating a design. This section presents a simplified discussion of the design process.

7.2 Typical Application

The following application schematic in is developed to meet the requirements in Table 7-1. This circuit is available as the evaluation module (EVM). The sections provide the design procedure.

The following figure shows the TPS56x24x 5V to 17V input, 1.05V output converter schematic.

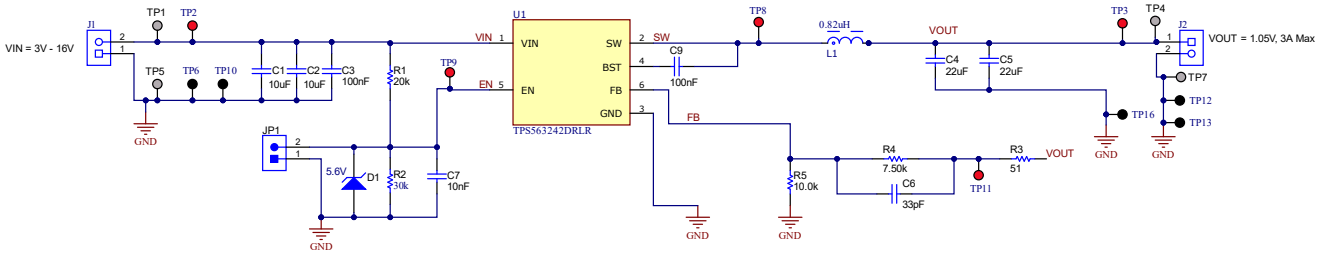


Figure 7-1. Schematic

7.2.1 Design Requirements

Table 7-1 shows the design parameters for this application.

Table 7-1. Design Parameters

PARAMETER		CONDITIONS	MIN	TYP	MAX	UNIT
V_{OUT}	Output voltage			1.05		V
I_{OUT}	Output current			3		A
ΔV_{OUT}	Transient response	0.3A – 2.7A load step, 0.8A/µs slew rate		±3% × V_{OUT}		V
V_{IN}	Input voltage		5	12	17	V
$V_{OUT(ripple)}$	Output voltage ripple	CCM condition		10		mV
F_{SW}	Switching frequency			1.2		MHz
T_A	Ambient temperature			25		°C

7.2.2 Detailed Design Procedure

7.2.2.1 Custom Design With WEBENCH® Tools

Click here to create a custom design using the TPS562242B device with the WEBENCH® Power Designer.

Click here to create a custom design using the TPS563242 device with the WEBENCH® Power Designer.

Click here to create a custom design using the TPS563247 device with the WEBENCH® Power Designer.

1. Start by entering the input voltage (V_{IN}), output voltage (V_{OUT}), and output current (I_{OUT}) requirements.
2. Optimize the design for key parameters such as efficiency, footprint, and cost using the optimizer dial.
3. Compare the generated design with other possible solutions from Texas Instruments.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Run thermal simulations to understand board thermal performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at www.ti.com/WEBENCH.

7.2.2.2 Output Voltage Resistors Selection

The output voltage is set with a resistor divider from the output node to the FB pin. TI recommends using 1% tolerance or better divider resistors. Start by using Equation 3 to calculate V_{OUT}.

To improve efficiency at very light loads, consider using larger value resistors. If the values are too high, the regulator is more susceptible to noise and voltage errors from the FB input current are noticeable. Use a 10kΩ resistor for R_5 to start the design.

$$V_{OUT} = 0.6 \times \left(1 + \frac{R_4}{R_5}\right) \tag{3}$$

7.2.2.3 Output Filter Selection

The LC filter used as the output filter has a double pole at Equation 4. In this equation, C_{OUT} uses the effective value after derating, not the nominal value.

$$f_P = \frac{1}{2\pi\sqrt{L_{OUT} \times C_{OUT}}} \tag{4}$$

For any control topology that is compensated internally, there is a range of the output filter the control topology can support. At low frequency, the overall loop gain is set by the output set-point resistor divider network and the internal gain of the device. The low frequency phase is 180°. At the output filter pole frequency, the gain rolls off at a –40dB per decade rate and the phase drops has a 180 degree drop. The internal ripple generation network introduces a high-frequency zero that reduces the gain roll off from –40dB to –20dB per decade and leads the 90 degree phase boost. The internal ripple injection high-frequency zero is about 156kHz. TI recommends the inductor and capacitor selected for the output filter such that the double pole is located approximately 40kHz, so that the phase boost provided by this high-frequency zero provides adequate phase margin for the stability requirement. The crossover frequency of the overall system is typically targeted to be less than one-third of the switching frequency (f_{SW}). For high output voltage condition, TI recommends to use 10-100pF feedforward capacitor for enough phase margin.

Table 7-2. Recommended Component Values for TPS562242B

OUTPUT VOLTAGE (V)	R4 (kΩ)	R5 (kΩ)	TYPICAL L1 (µH)	TYPICAL C_{OUT} (µF)	TYPICAL C_{OUT} (µF) NOMINAL VALUE RANGE	TYPICAL C_{OUT} CATEGORY	TYPICAL C6 (pF)
0.6	0	10.0	0.82	44	44-88	MLCC, 0805, 10V	—
1.05	7.5	10.0	1.2	22	22-66	MLCC, 0805, 10V	—
3.3	135.0	30.0	2.2	22	22-88	MLCC, 0805, 10V	33
5	220.0	30.0	3.3	22	22-88	MLCC, 0805, 10V	33
10	470.0	30.0	4.7	44	44-88	MLCC, 0805, 16V	47

Table 7-3. Recommended Component Values for TPS563242, TPS563247

OUTPUT VOLTAGE (V)	R4 (kΩ)	R5 (kΩ)	TYPICAL L1 (µH)	TYPICAL C_{OUT} (µF)	TYPICAL C_{OUT} (µF) NOMINAL VALUE RANGE	TYPICAL C_{OUT} CATEGORY	TYPICAL C6 (pF)
0.6	0	10.0	0.68	44	44-88	MLCC, 0805, 10V	—
1.05	7.5	10.0	0.82	22	22-44	MLCC, 0805, 10V	—
3.3	135.0	30.0	2.2	22	22-88	MLCC, 0805, 10V	33
5	220.0	30.0	2.2	22	22-88	MLCC, 0805, 10V	22
10	470.0	30.0	4.7	44	44-88	MLCC, 0805, 16V	47

The inductor peak-to-peak ripple current, peak current, and RMS current are calculated using Equation 5, Equation 6, and Equation 7. Generally, TI recommends the peak-to-peak ripple current to be 20% – 50% of output average current for a comprehensive benefit of efficiency and inductor volume. The inductor saturation current rating must be greater than the calculated peak current and the RMS or heating current rating must be greater than the calculated RMS current.

$$II_{P-P} = \frac{V_{OUT}}{V_{IN(MAX)}} \times \frac{V_{IN(MAX)} - V_{OUT}}{L_O \times f_{SW}} \quad (5)$$

$$II_{PEAK} = I_O + \frac{II_{P-P}}{2} \quad (6)$$

$$I_{LO(RMS)} = \sqrt{I_O^2 + \frac{1}{12} II_{P-P}^2} \quad (7)$$

For this design example, the calculated peak current is 3.4A and the calculated RMS current is 3.01A. The inductor used is 744383660082 with 8.8A rated current and 11A saturation current.

The capacitor value and ESR determines the amount of output voltage ripple. The TPS56x24x are intended for use with ceramic or other low-ESR capacitors. Use Equation 8 to determine the required RMS current rating for the output capacitor.

$$I_{CO(RMS)} = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{\sqrt{12} \times V_{IN} \times L_O \times f_{SW}} \quad (8)$$

For this design, one MuRata GRM21BR61A226ME44L 22µF output capacitors are used. The typical ESR is 2mΩ each. The calculated RMS current is 0.25A and each output capacitor is rated for 4A.

7.2.2.4 Input Capacitor Selection

The TPS56x24x requires an input decoupling capacitor and a bulk capacitor is needed depending on the application. TI recommends a ceramic capacitor over 10µF for the decoupling capacitor. TI recommends an additional 0.1µF capacitor from the VIN pin to ground to provide high frequency filtering. The capacitor voltage rating must be greater than the maximum input voltage.

7.2.3 Application Curves

The following data is tested With V_{IN} = 12V, V_{OUT} = 1.05V, T_A = 25°C, unless otherwise specified.

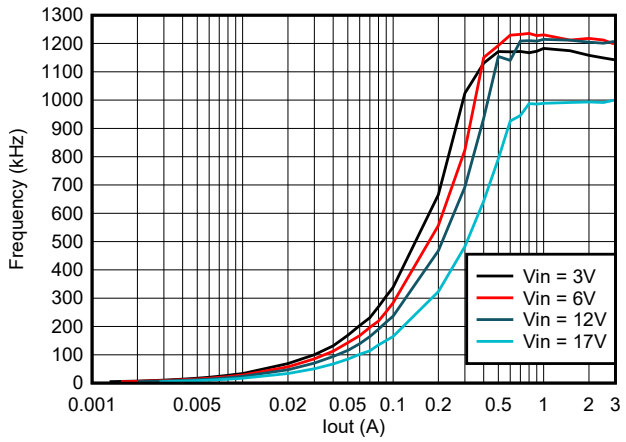


Figure 7-2. TPS563242 Frequency vs Loading

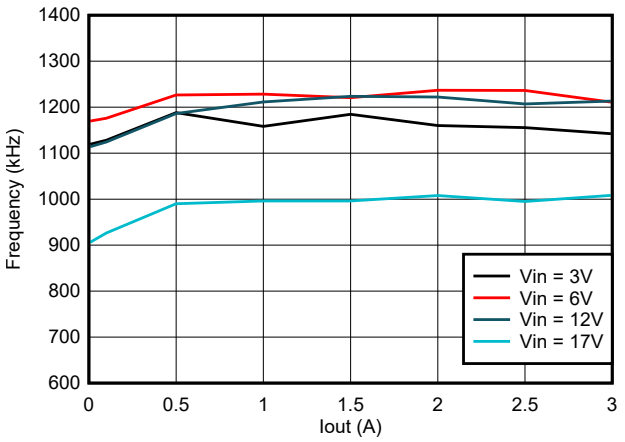


Figure 7-3. TPS563247 Frequency vs Loading

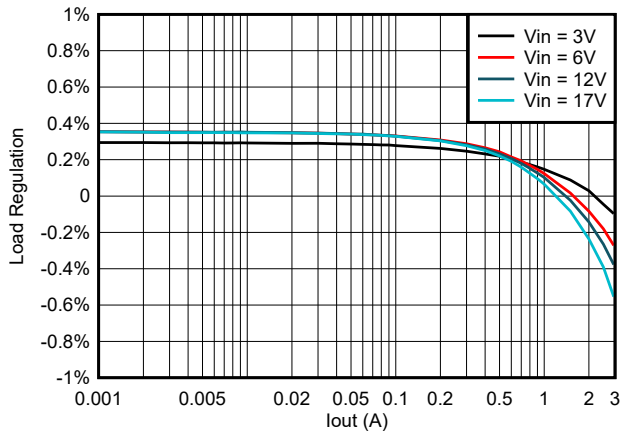


Figure 7-4. TPS563242 Load Regulation vs Loading

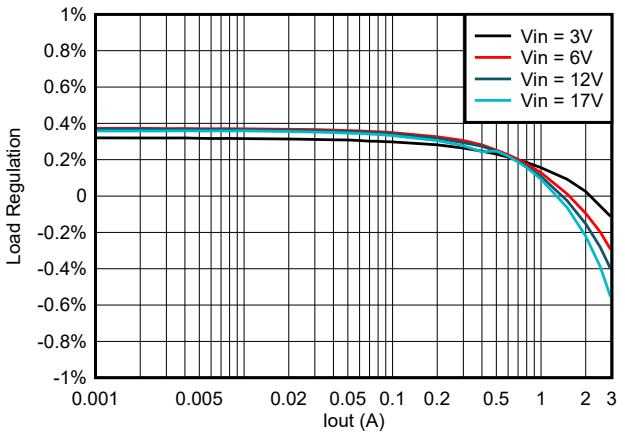


Figure 7-5. TPS563247 Load Regulation vs Loading

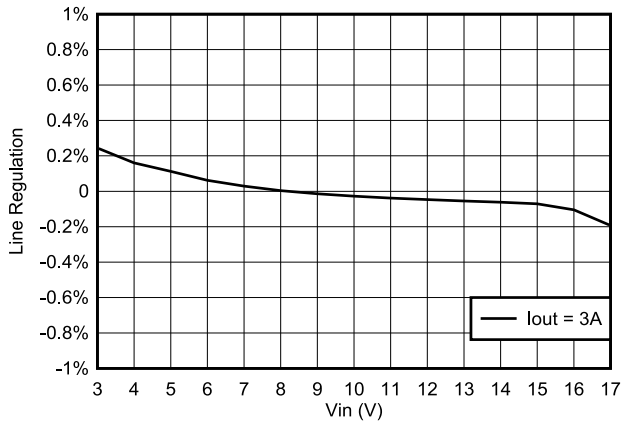


Figure 7-6. TPS563242 Line Regulation vs V_{IN}

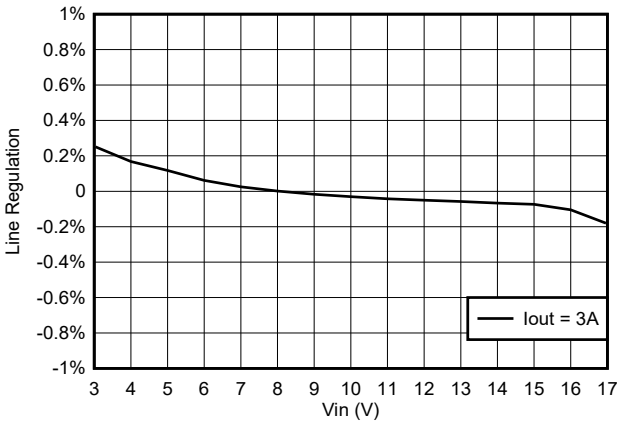


Figure 7-7. TPS563247 Line Regulation vs V_{IN}

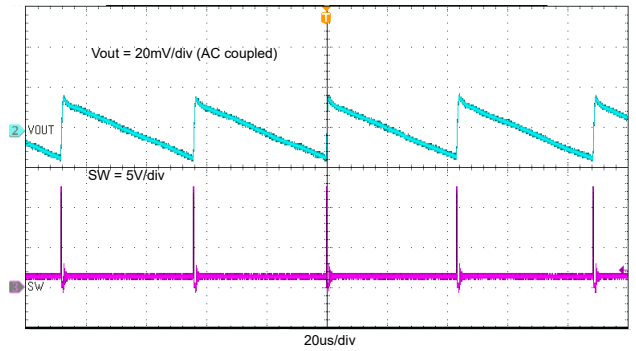


Figure 7-8. TPS563242 Output Voltage Ripple With 0.01A Loading

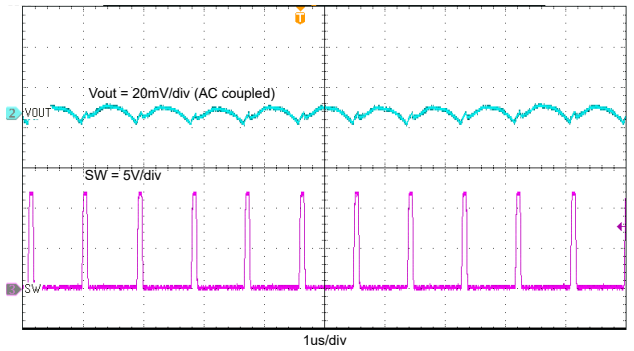


Figure 7-9. TPS563247 Output Voltage Ripple With 0.01A Loading

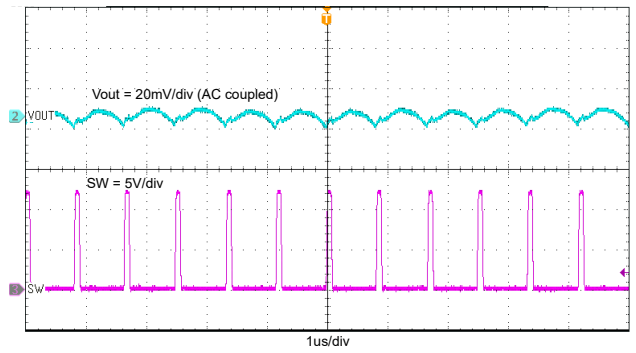


Figure 7-10. Output Voltage Ripple With 3A Loading

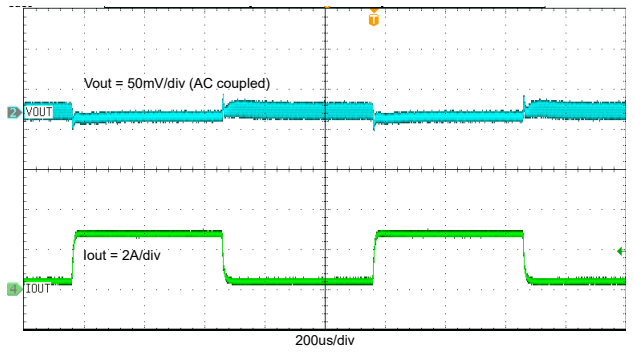


Figure 7-11. TPS563242 Transient Response With 0.3A to 2.7A

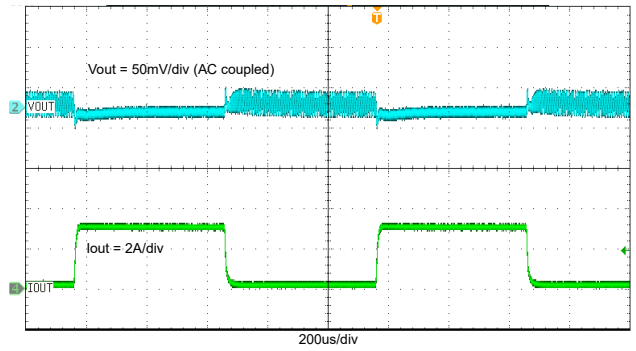


Figure 7-12. TPS563242 Transient Response With 0.1A to 3A

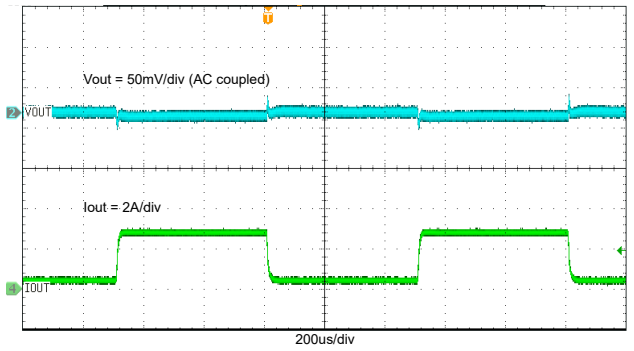


Figure 7-13. TPS563247 Transient Response With 0.3A to 2.7A

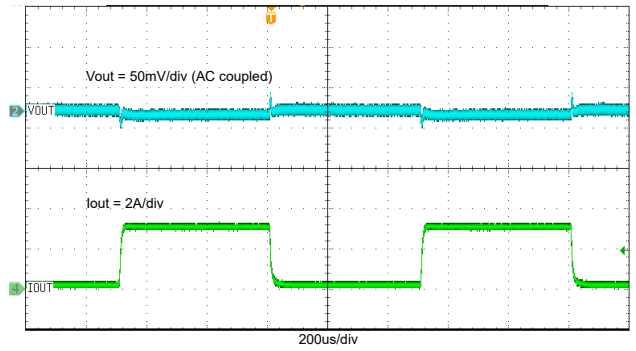


Figure 7-14. TPS563247 Transient Response With 0.1A to 3A

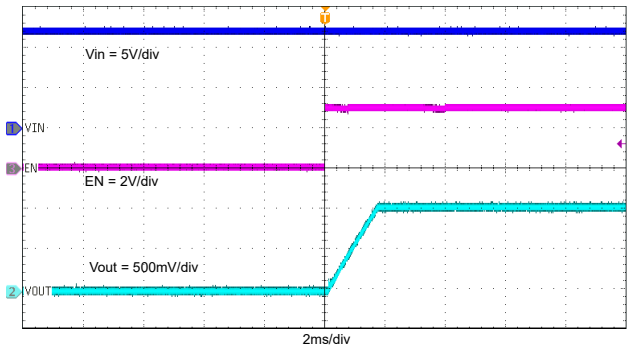


Figure 7-15. Start-up Through EN, I_{OUT} = 3A

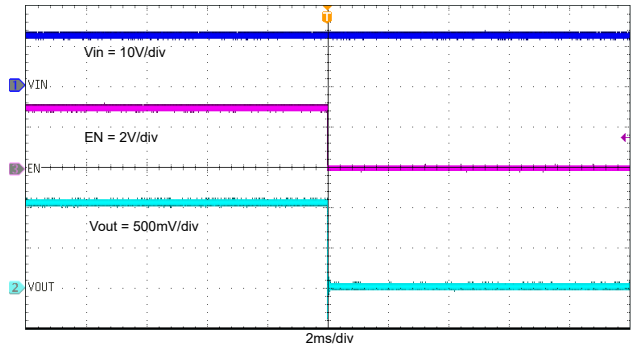


Figure 7-16. Shutdown Through EN, I_{OUT} = 3A

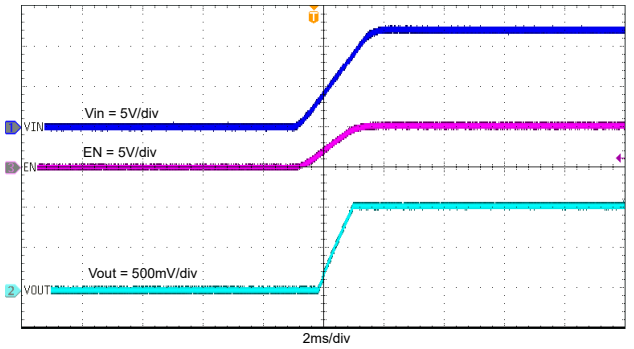


Figure 7-17. Start-up With V_{IN} Rising, I_{OUT} = 3A

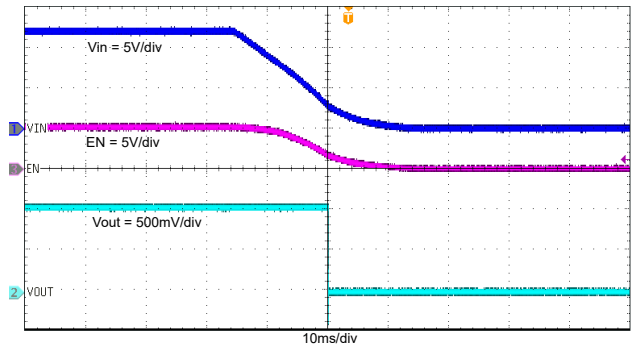


Figure 7-18. Shutdown With V_{IN} Falling, I_{OUT} = 3A

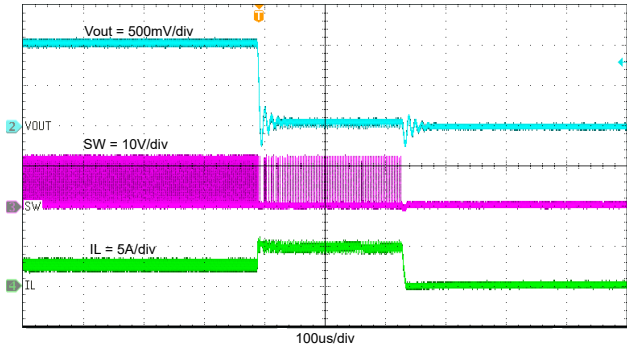


Figure 7-19. TPS563242 Normal Operation to Output Hard Short

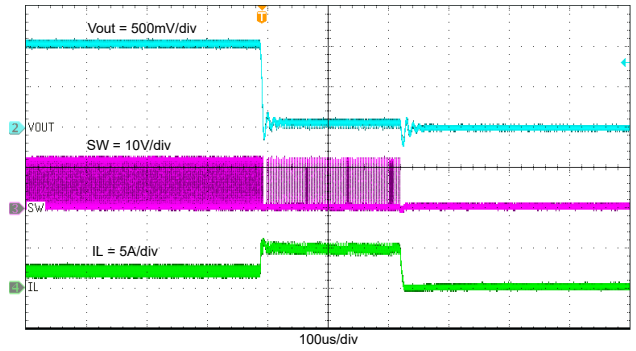


Figure 7-20. TPS563247 Normal Operation to Output Hard Short

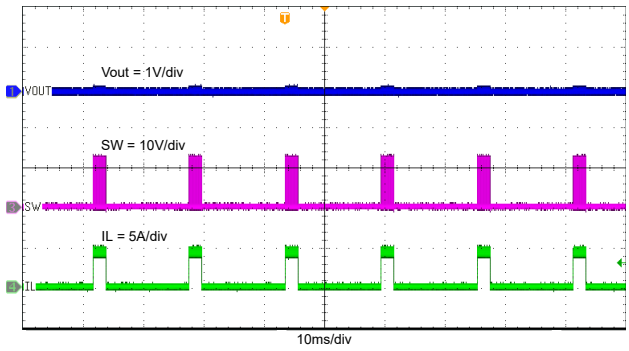


Figure 7-21. Output Hard Short Hiccup

7.3 Power Supply Recommendations

The TPS56x24x are designed to operate from input supply voltages in the range of 3V to 17V. Buck converters require the input voltage to be higher than the output voltage for proper operation.

7.4 Layout

7.4.1 Layout Guidelines

- Keep VIN and GND traces as wide as possible to reduce trace impedance. The wide areas are also an advantage from the view point of heat dissipation.
- Place the input capacitor and output capacitor as close to the device as possible to minimize trace impedance.
- Provide sufficient vias for the input capacitor and output capacitor.
- Keep the SW trace as physically short and wide as practical to minimize radiated emissions.
- Do not allow switching current to flow under the device.
- Connect a separate VOUT path to the upper feedback resistor.
- Make a Kelvin connection to the GND pin for the feedback path.
- Place a voltage feedback loop away from the high-voltage switching trace, and preferably has ground shield.
- Make the trace of the FB node as small as possible to avoid noise coupling.
- Make the GND trace between the output capacitor and the GND pin as wide as possible to minimize the trace impedance.

7.4.2 Layout Example

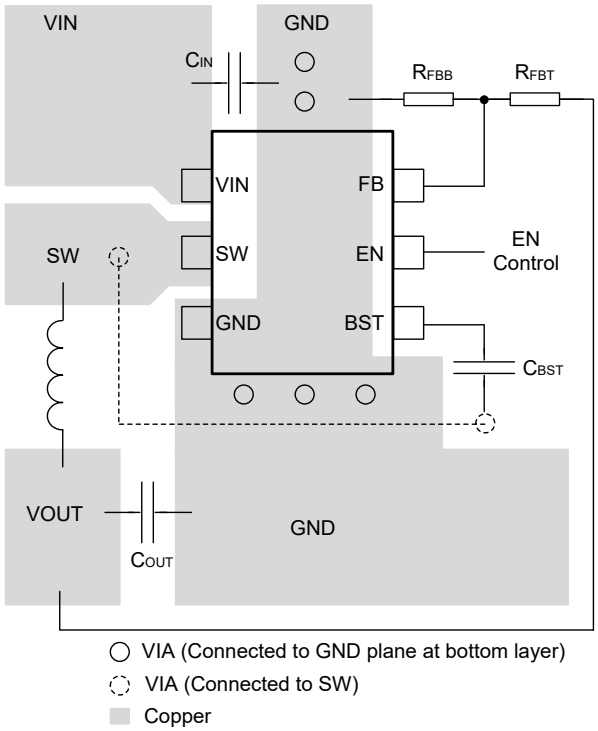


Figure 7-22. Suggested Layout

8 Device and Documentation Support

8.1 Device Support

8.1.1 Development Support

8.1.1.1 Custom Design With WEBENCH® Tools

Click here to create a custom design using the TPS562242B device with the WEBENCH® Power Designer.

Click here to create a custom design using the TPS563242 device with the WEBENCH® Power Designer.

Click here to create a custom design using the TPS563247 device with the WEBENCH® Power Designer.

1. Start by entering the input voltage (V_{IN}), output voltage (V_{OUT}), and output current (I_{OUT}) requirements.
2. Optimize the design for key parameters such as efficiency, footprint, and cost using the optimizer dial.
3. Compare the generated design with other possible solutions from Texas Instruments.

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In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Run thermal simulations to understand board thermal performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at www.ti.com/WEBENCH.

8.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

8.3 Support Resources

TI E2E™ support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

8.4 Trademarks

D-CAP3™ and TI E2E™ are trademarks of Texas Instruments.
WEBENCH® is a registered trademark of Texas Instruments.
All trademarks are the property of their respective owners.

8.5 Electrostatic Discharge Caution

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

8.6 Glossary

TI Glossary	This glossary lists and explains terms, acronyms, and definitions.

9 Revision History

DATE	REVISION	NOTES
February 2026	*	Initial Release

10 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package | Pins	Package qty | Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
TPS562242BDRLR	Active	Production	SOT-5X3 (DRL) | 6	4000 | LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	242B
TPS563247DRLR	Active	Production	SOT-5X3 (DRL) | 6	4000 | LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	3247

(1) **Status:** For more details on status, see our product life cycle.

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

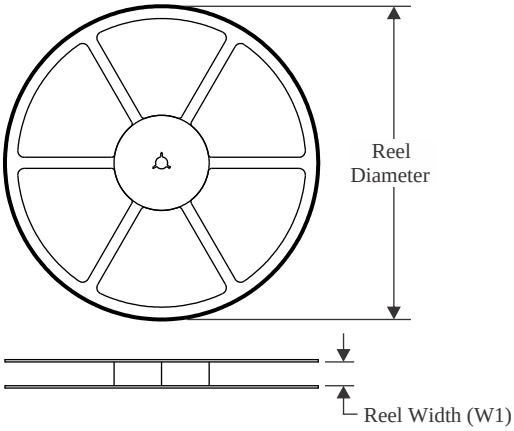
(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

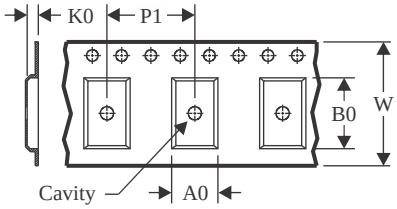
Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

TAPE AND REEL INFORMATION

REEL DIMENSIONS

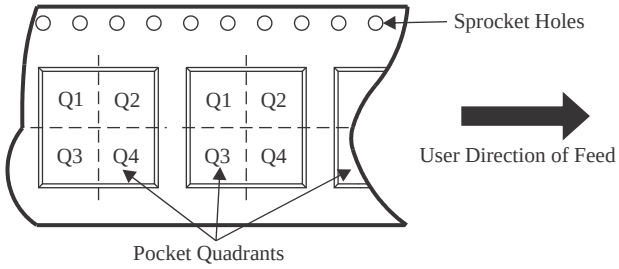


TAPE DIMENSIONS



A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

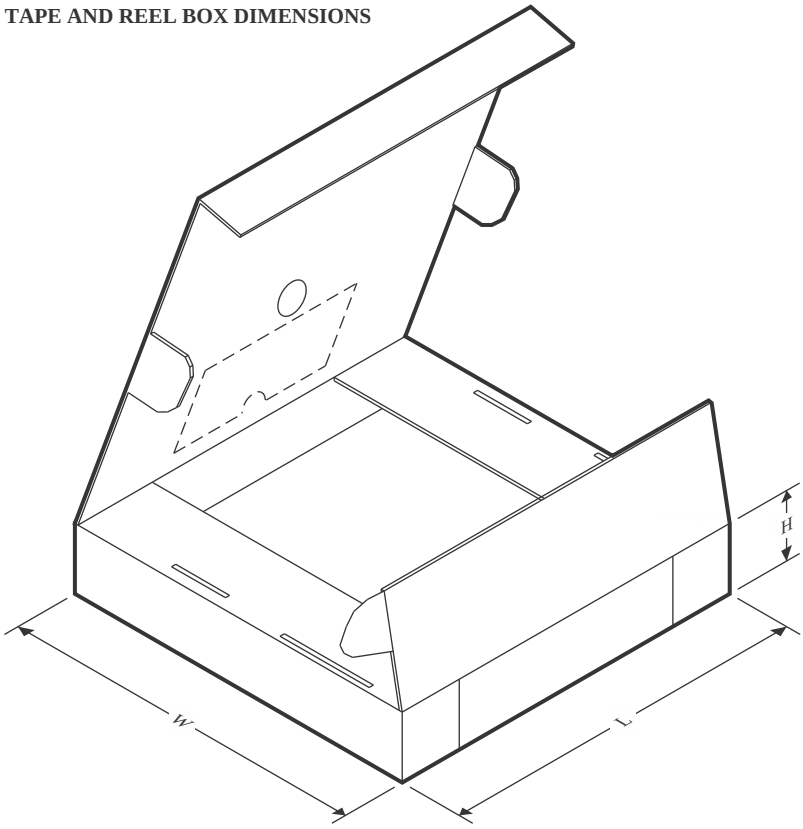
QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS562242BDRLR	SOT-5X3	DRL	6	4000	180.0	8.4	1.8	1.8	0.75	4.0	8.0	Q3
TPS563247DRLR	SOT-5X3	DRL	6	4000	180.0	8.4	1.8	1.8	0.75	4.0	8.0	Q3

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

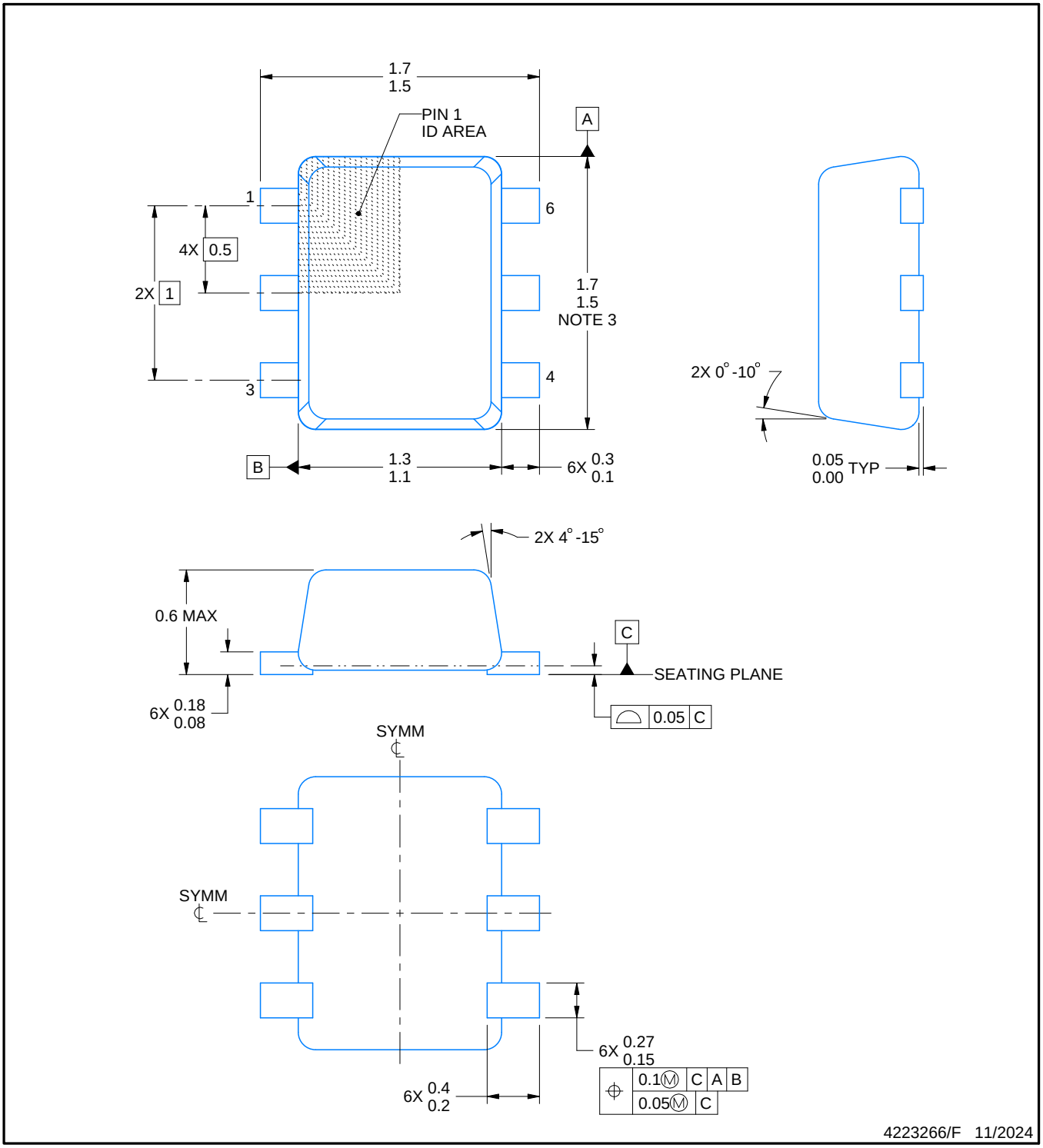
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS562242BDRLR	SOT-5X3	DRL	6	4000	210.0	185.0	35.0
TPS563247DRLR	SOT-5X3	DRL	6	4000	210.0	185.0	35.0

PACKAGE OUTLINE

DRL0006A

SOT - 0.6 mm max height

PLASTIC SMALL OUTLINE



NOTES:

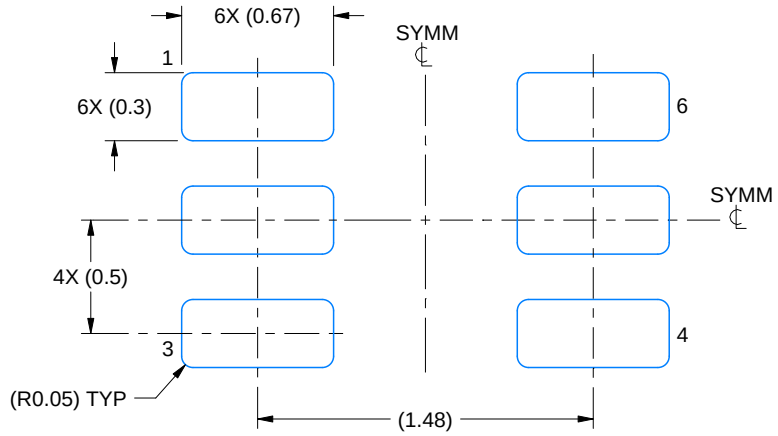
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. Reference JEDEC registration MO-293 Variation UAAD

EXAMPLE BOARD LAYOUT

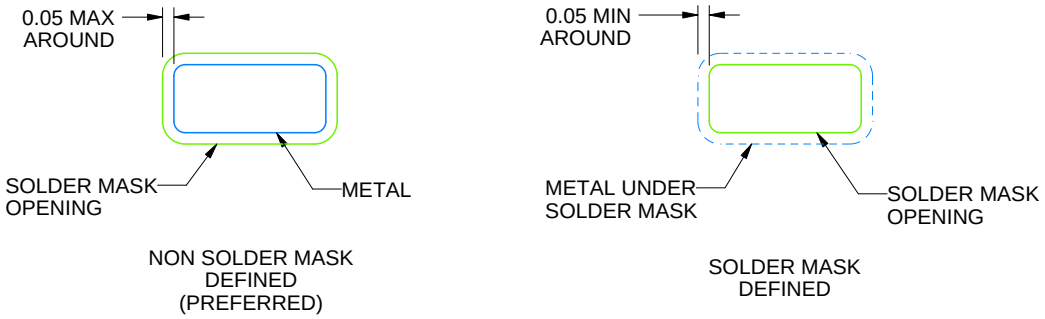
DRL0006A

SOT - 0.6 mm max height

PLASTIC SMALL OUTLINE



LAND PATTERN EXAMPLE
SCALE:30X



SOLDERMASK DETAILS

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NOTES: (continued)

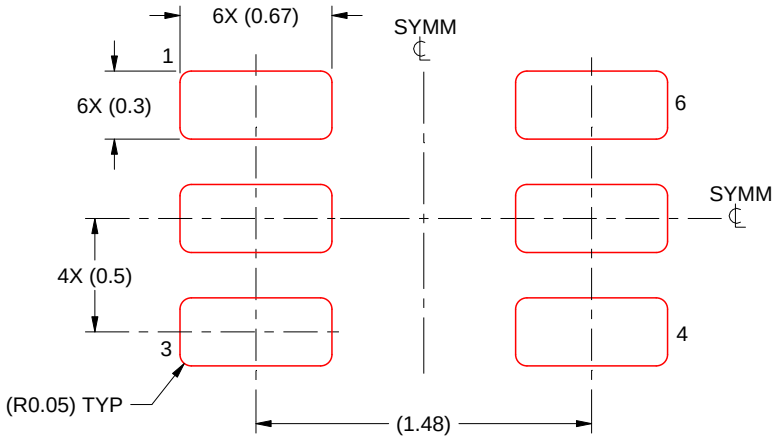
5. Publication IPC-7351 may have alternate designs.
6. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
7. Land pattern design aligns to IPC-610, Bottom Termination Component (BTC) solder joint inspection criteria.

EXAMPLE STENCIL DESIGN

DRL0006A

SOT - 0.6 mm max height

PLASTIC SMALL OUTLINE



SOLDER PASTE EXAMPLE
BASED ON 0.1 mm THICK STENCIL
SCALE:30X

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NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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