

Implementing Reverse Current Operation in the LM51772 Using MODE Function



Hassan Jamal

Introduction

The [LM51772](#) is a four-switch buck-boost controller designed to support reverse current operation (RCO) through the MODE function. This capability allows the converter to store excess energy at the output, making this highly valuable in applications where energy recovery or backup power is required. Typical use cases include regenerative energy capture during motor braking, battery backup systems during a main power outage, and so on.

This application brief describes the implementation of MODE pin control used to enable RCO operation in the LM51772. In this brief, the MODE pin is driven by a hysteresis controller implemented with a simple comparator circuit. The controller activates RCO when the output voltage exceeds the defined threshold. For the LM51772 specifically, RCO is automatically disabled when the feedback (FB) voltage falls below the device reference voltage (V_{ref}), meaning hysteresis control is not strictly required for proper operation. However, a hysteresis controller is included in this implementation to maintain design compatibility with LM5177 and LM51770 devices, which require hysteretic MODE control to make sure RCO operation is stable.

The LM51772 device allows RCO configuration through either the R2D interface or the I²C interface. While detailed configuration options for RCO are discussed in [Battery or Capacitor Backup Operation with the LM51772](#), this brief focuses on configuring RCO using the I²C interface.

MODE Function

The LM51772 device operates in two primary modes: Power-Save Mode (PSM) and Forced PWM (FPWM) mode. The detail about these modes is well explained in [LM51772 55V 4-Switch Buck-Boost Controller with I2C Interface](#). Reverse current operation is only supported when the device is configured in FPWM mode. These mode selection is controlled by the MODE pin. When the MODE pin voltage rises above the positive-going threshold (V_{T+MODE}), the device transitions from PSM to FPWM mode, enabling RCO.

To initiate RCO, the configuration settings listed in the [Table 1](#) must be properly applied, as described in detail in [Battery or Capacitor Backup Operation with the LM51772](#). The corresponding pin connections are illustrated in [Figure 1](#). When the output supply or energy source increases the feedback (FB) voltage beyond the reference threshold (V_{REF}), the MODE pin control detects the rise in output voltage and drives the MODE pin high, above the V_{T+MODE} threshold. This action enables the LM51772 device to transfer excess output energy to the storage element connected at the input of the converter.

Table 1. Pin Configuration for LM51772 Device

MODE Pin	Above V_{T+MODE} threshold
Feedback Pin (FB)	Above V_{ref} threshold
nRST Pin	Above $V_{T+(nRST)}$ threshold
UVLO Pin	Connect to output or external supply
BIAS Pin	Connect to output or external supply
VDETs	Turn off (if the voltage of the input storage element is below V_{DET} positive-going threshold)

However, other devices such as LM5177 and LM51770 require hysteresis on the MODE pin to verify proper RCO operation. To support these devices, a hysteresis controller is implemented in this design. The controller uses an open-drain comparator (TLV3401) with a positive-feedback resistor network to generate the required hysteresis. Figure 2 shows the schematic of the implemented hysteresis controller.

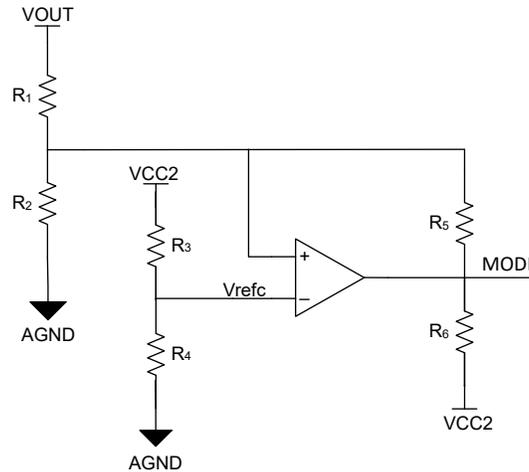


Figure 2. Hysteresis Controller

The controller compares the signal at the non-inverting input with the reference voltage (V_{refc}) applied to the inverting input of the comparator. When the non-inverting input voltage exceeds the inverting input voltage, the comparator output transitions high; otherwise, the input voltage remains low. The signal applied to the non-inverting input consists of two components: a positive-feedback signal defined by resistor R5, which sets the hysteresis magnitude, and a scaled version of the output voltage determined by the resistor divider formed by R1 and R2. Equation 1 is used to calculate the desired V_{refc} value, while Equation 2 and Equation 3 determine the upper and lower hysteresis thresholds, $V_{OUT(H)}$ and $V_{OUT(L)}$, respectively, relative to VOUT.

$$V_{refc} = \frac{R_4}{R_4 + R_3} * V_{CC2} \quad (1)$$

$$V_{out(H)} = \frac{V_{refc} * (R_2 R_5 + R_1 * (R_5 + R_2))}{R_2 R_5} \quad (2)$$

$$V_{out(L)} = \frac{R_1 * (V_{refc} * (R_6 + R_5) - R_2 * (V_{CC2} - V_{refc}))}{R_2 * (R_6 + R_5)} + V_{refc} \quad (3)$$

In this design, the V_{OUT} is set to 21.75V, with a hysteresis of 250mV applied to define the upper and lower thresholds. This results in $V_{OUT(H)} = 22.25V$ and $V_{OUT(L)} = 21.75V$. The reference voltage, V_{refc} , is set to 2.5V, and the supply voltage, V_{CC} , is 5V. Based on these parameters, the calculated values for resistors R1 through R6 are as follows: R1 = 102k Ω , R2 = 13k Ω , R3 = 102k Ω , R4 = 102k Ω , R5 = 1.07M Ω , and R6 = 20k Ω .

Results

Figure 3 shows that RCO is initiated when the output voltage exceeds the $V_{OUT(H)}$ threshold. At this point, the comparator drives the MODE pin above the V_{T+MODE} threshold, thereby enabling RCO. The storage element, implemented with capacitors, is charged by a constant current until the voltage reaches the input voltage regulation (IVR) threshold, after which it is regulated to 12V. Figure 4 demonstrates that RCO operation remains unchanged even if the MODE pin falls below the V_{T-MODE} threshold. Figure 5 indicates that RCO is disabled when the feedback signal drops below the V_{ref} threshold while the MODE pin remains above the V_{T+MODE} threshold. Figure 6 illustrates that a drop in the feedback signal below the V_{ref} threshold causes the MODE pin to fall below the V_{T-MODE} threshold, as $V_{out(L)}$ is equal to the set output voltage.

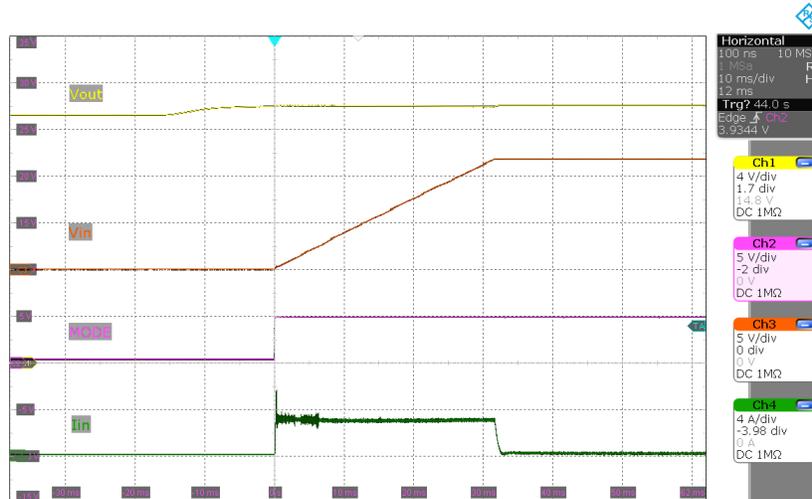


Figure 3. MODE Pin Above V_{T+MODE} Threshold

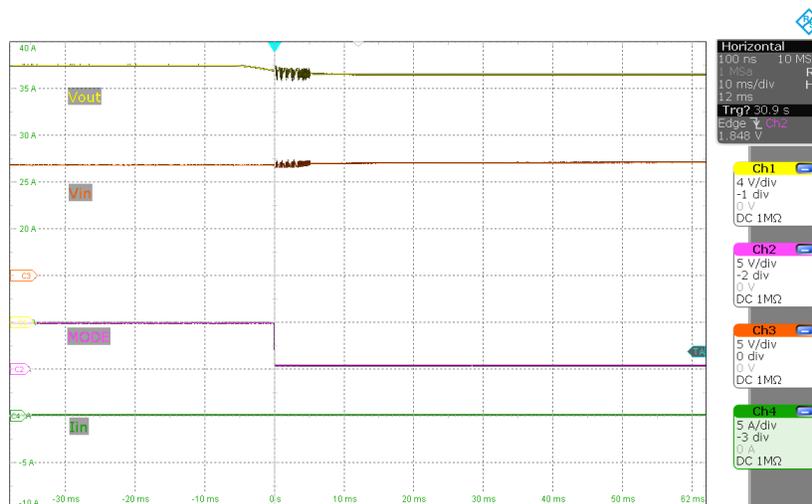


Figure 4. MODE Pin Below V_{T-MODE} Threshold During RCO

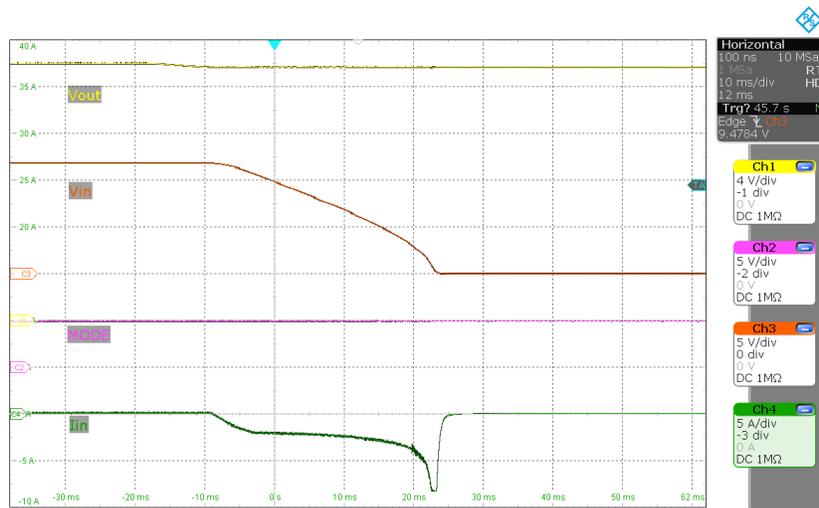


Figure 5. Feedback Signal Below V_{ref} Signal ($V_{out} < V_{out(L)}$)

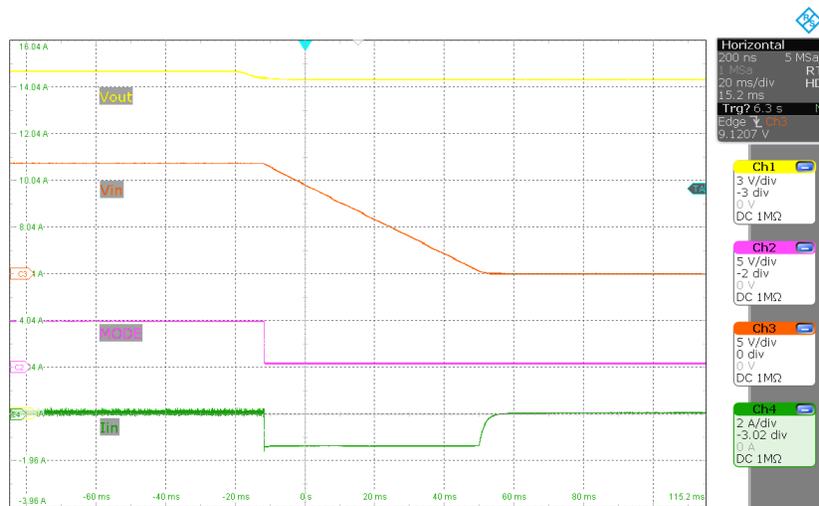


Figure 6. MODE Pin Below V_{T-MODE} Threshold and V_{out} Signal Below $V_{out(L)}$ Threshold

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATASHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you fully indemnify TI and its representatives against any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to [TI's Terms of Sale](#), [TI's General Quality Guidelines](#), or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products. Unless TI explicitly designates a product as custom or customer-specified, TI products are standard, catalog, general purpose devices.

TI objects to and rejects any additional or different terms you may propose.

Copyright © 2026, Texas Instruments Incorporated

Last updated 10/2025